

The InSAR Course

Synthetic Aperture Radar (SAR)

Part 2: Azimuth Resolution

Prepared by DLR-HR's Pol-InSAR Team

German Aerospace Center (DLR), Microwaves & Radar Institute (HR), Pol-InSAR Research Group

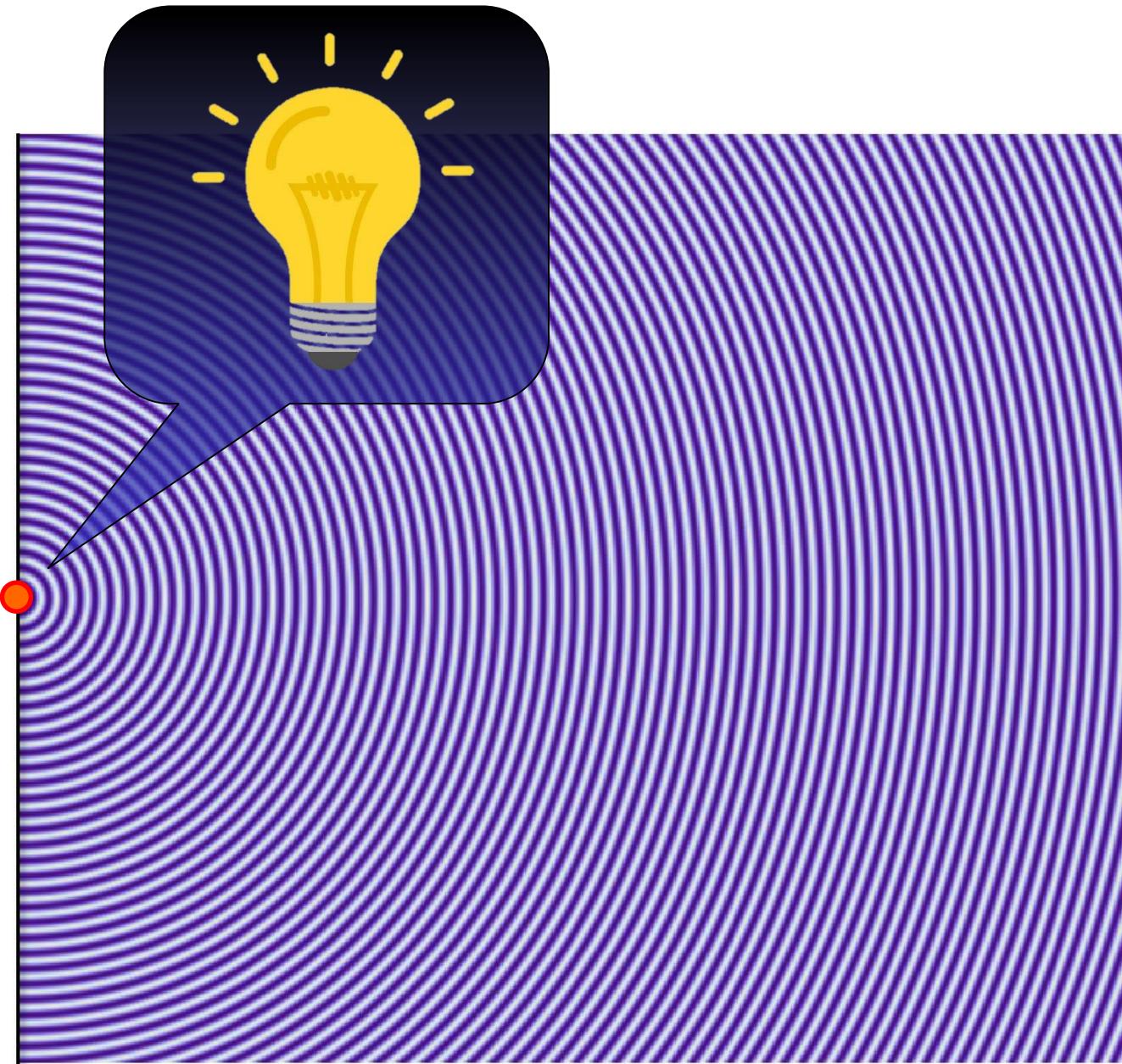
Email: kostas.papathanassiou@dlr.de, matteo.pardini@dlr.de, islam.mansour@dlr.de

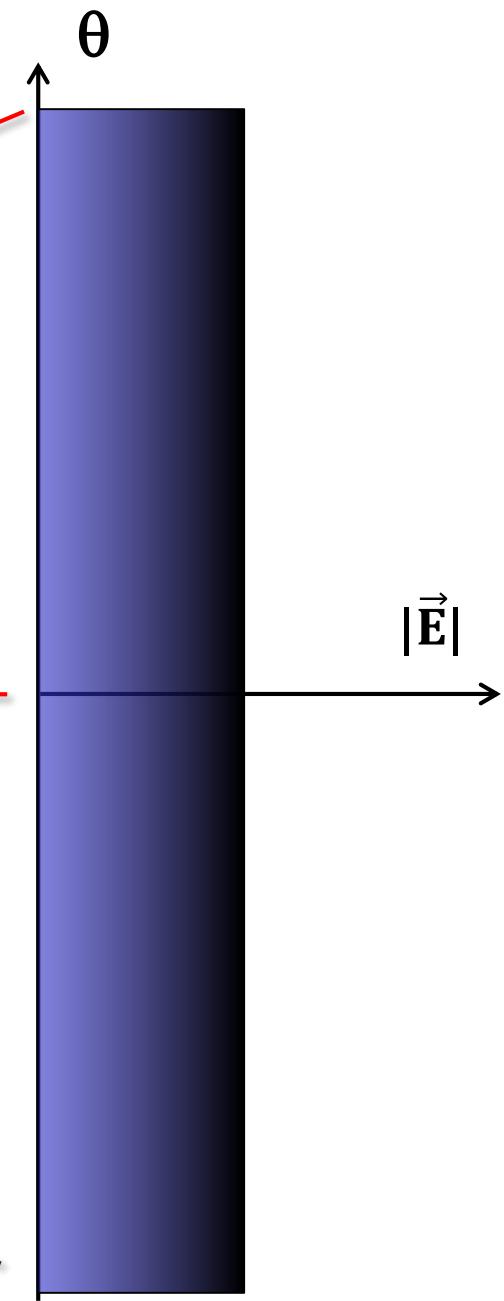
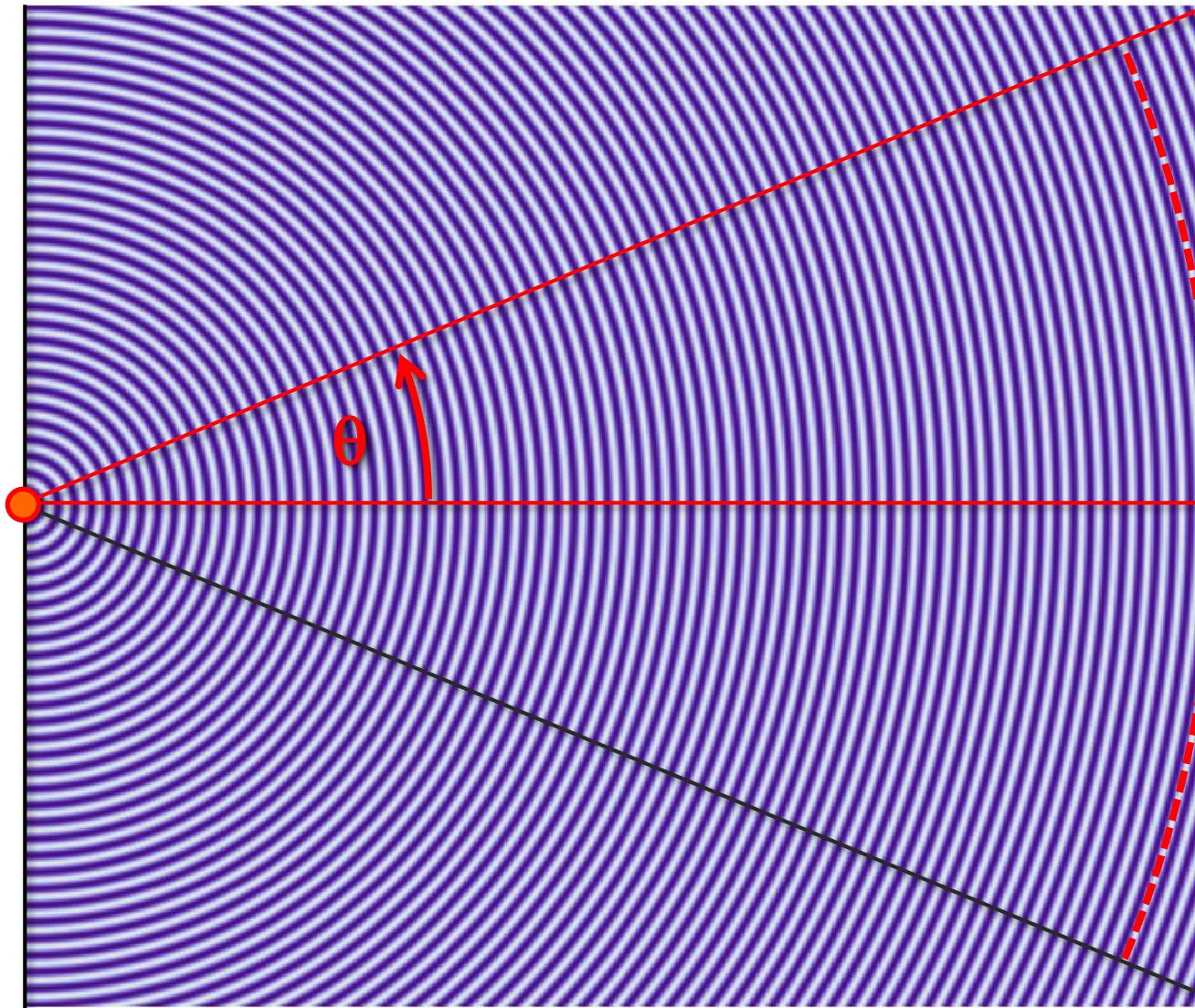


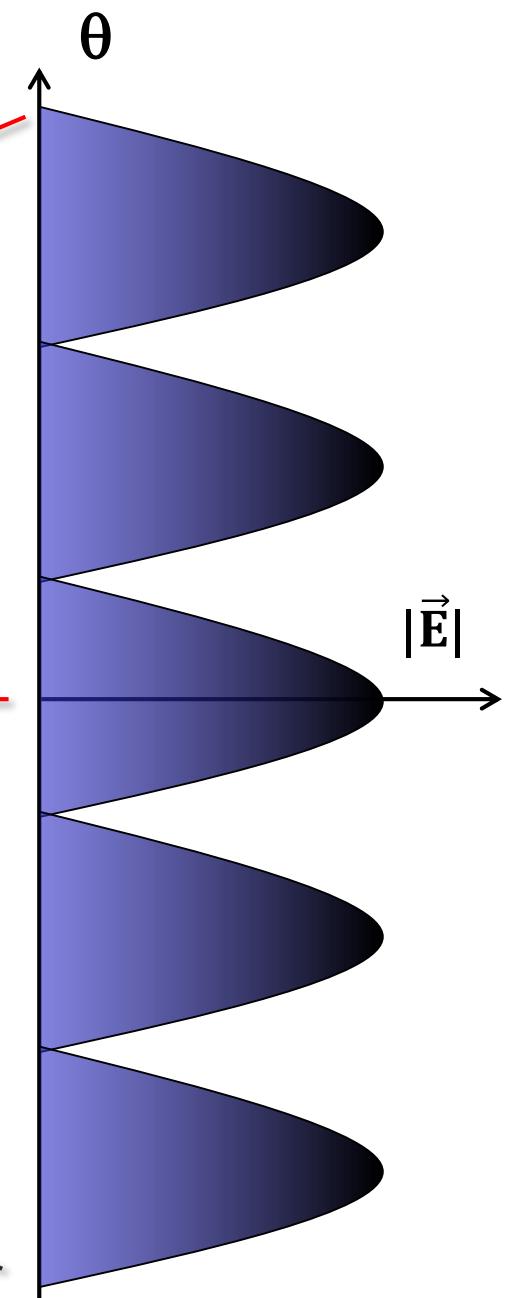
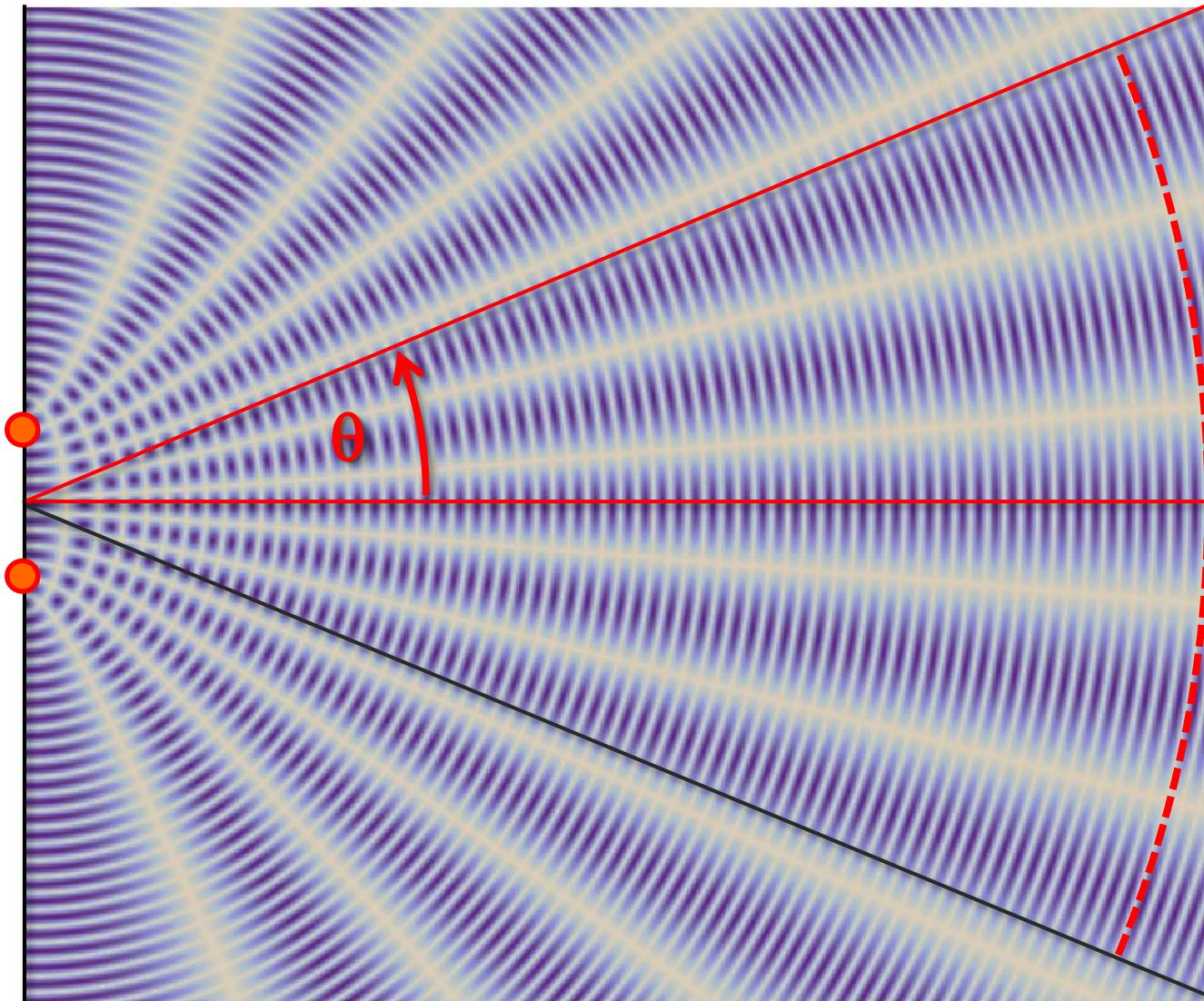
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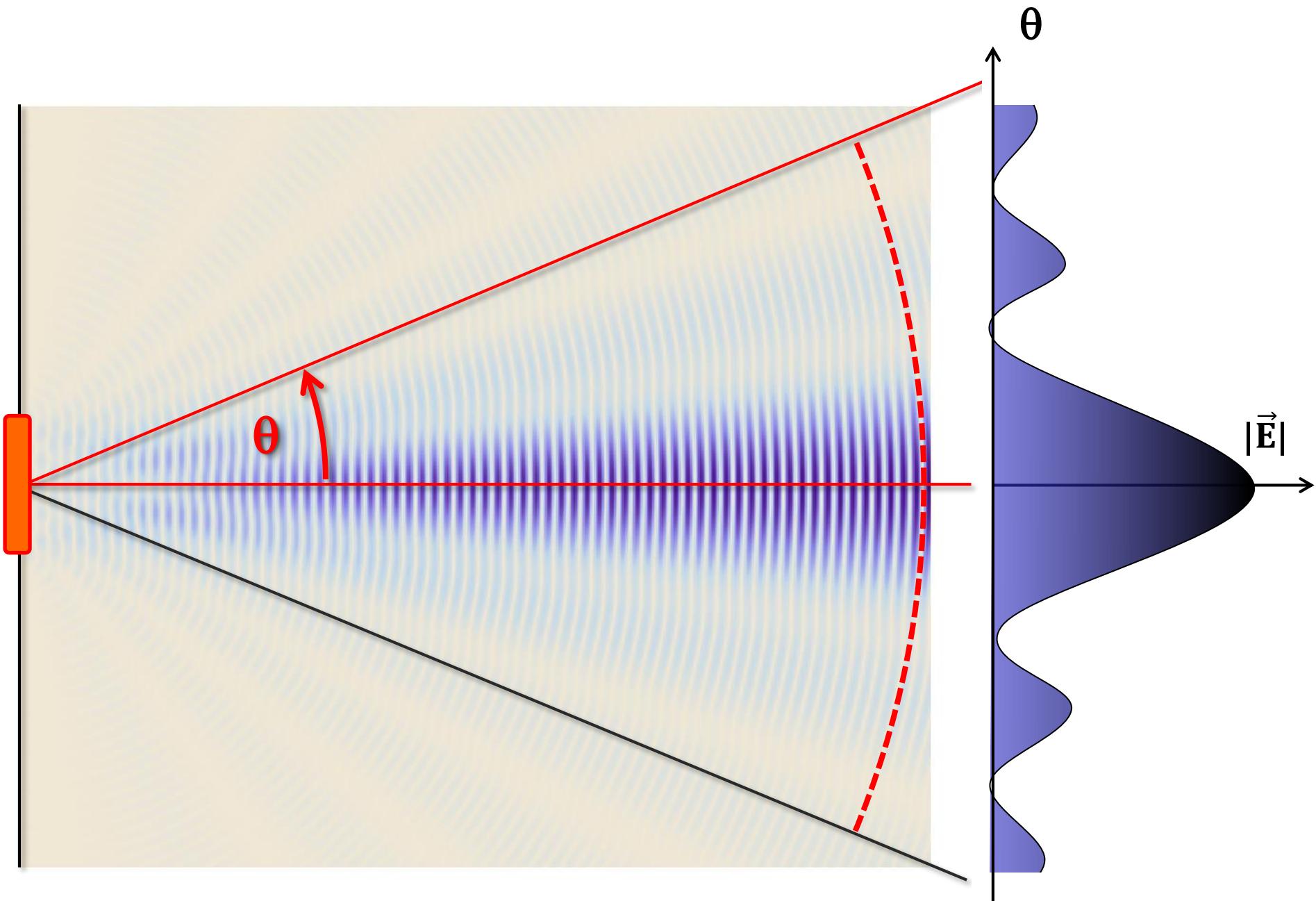


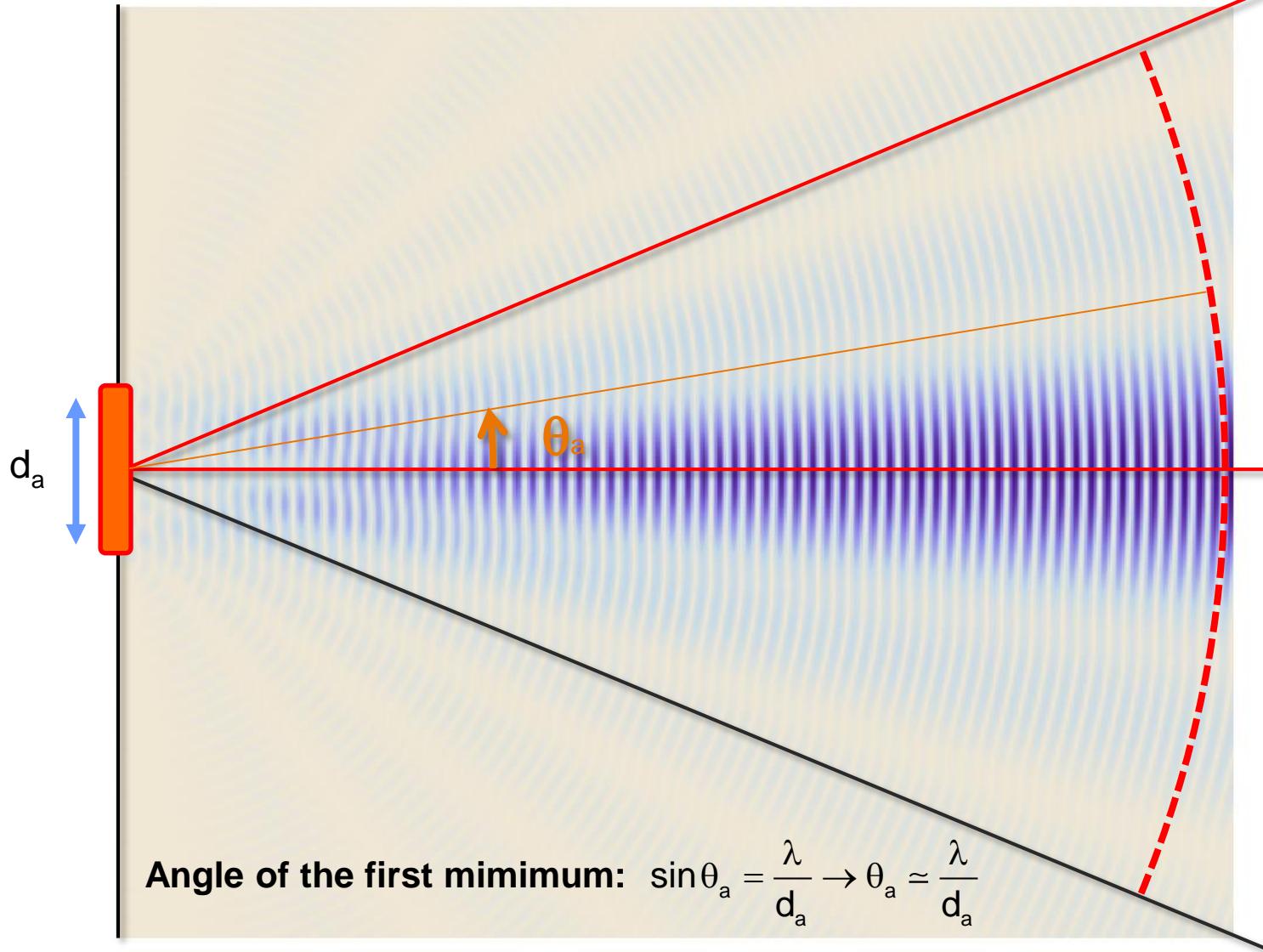
Azimuth Resolution





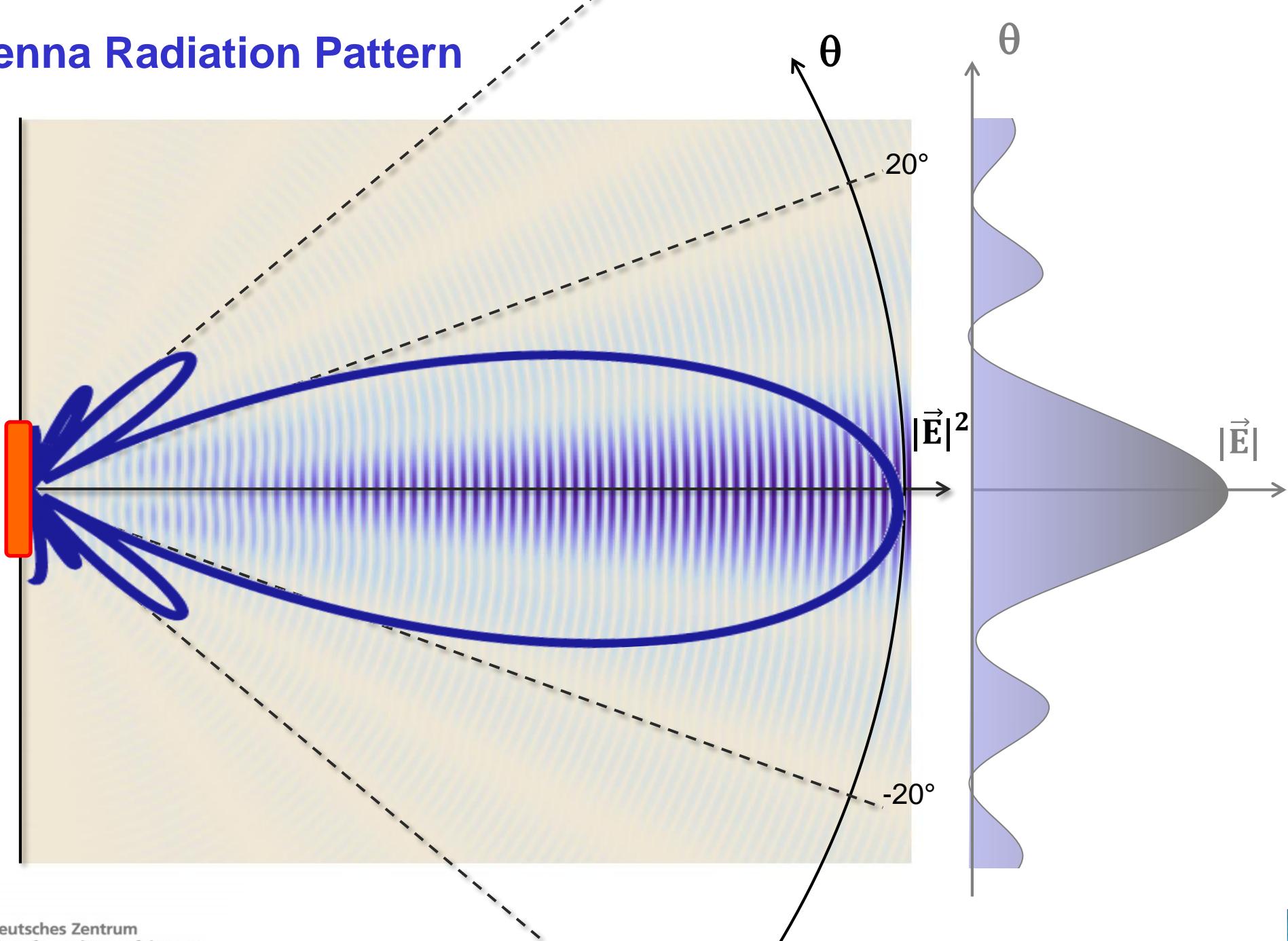






d_a is the aperture's length, λ the wavelength, θ the angle relative to the "original" direction of wave propagation.

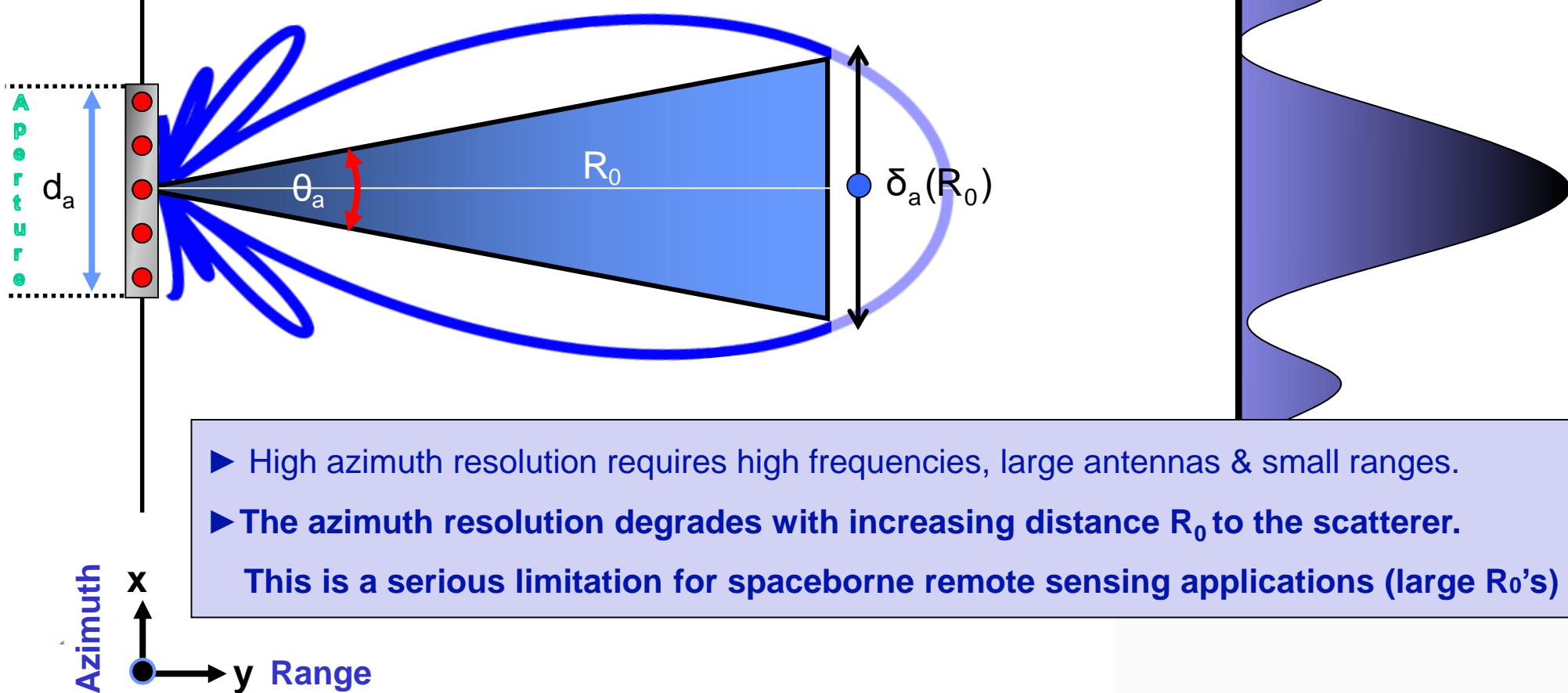
Antenna Radiation Pattern



Real Aperture Radar

Angular resolution: $\theta_a \approx \frac{\lambda}{d_a} = \frac{\text{Wavelength}}{\text{(Real) Antenna Aperture}}$

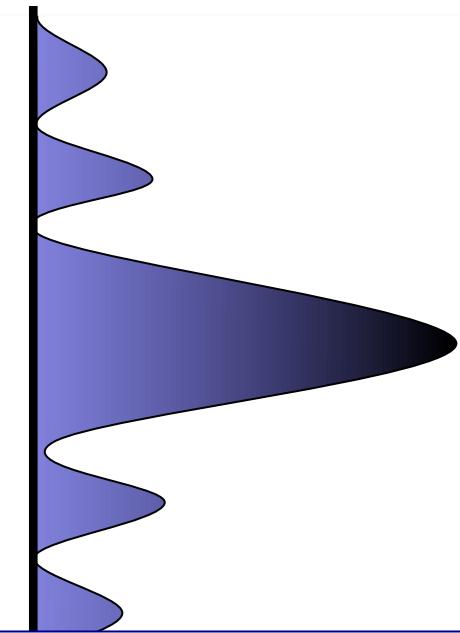
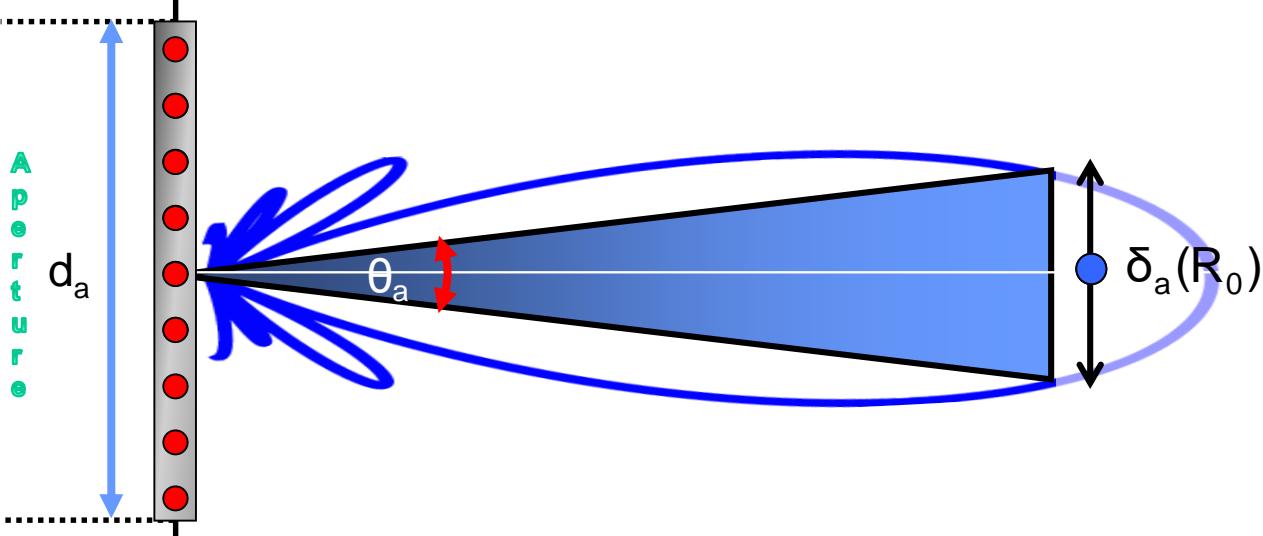
Spatial resolution (Az): $\delta_a = \theta_a R_0 \approx \frac{\lambda}{d_a} R_0$ where R_0 is the (closest) distance to the scatterer



Real Aperture Radar: Increasing the Antenna

Angular resolution: $\theta_a \approx \frac{\lambda}{d_a} = \frac{\text{Wavelength}}{\text{(Real) Antenna Aperture}}$

Spatial resolution (Az): $\delta_a = \theta_a R_0 \approx \frac{\lambda}{d_a} R_0$ where R_0 is the (closest) distance to the scatterer



Example 1: X-Band Airborne system, 50MHz bandwidth, 3m antenna, 3000m range

$$\delta_r = 3 \text{ m}$$

$$\delta_a = 30 \text{ m}$$

Example 2: X-Band Satellite system, 50MHz bandwidth, 12m antenna, 800km range

$$\delta_r = 3 \text{ m}$$

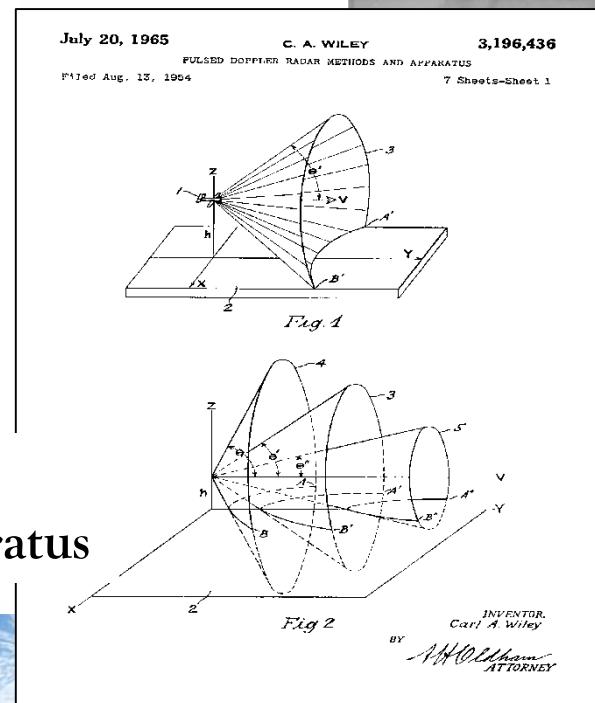
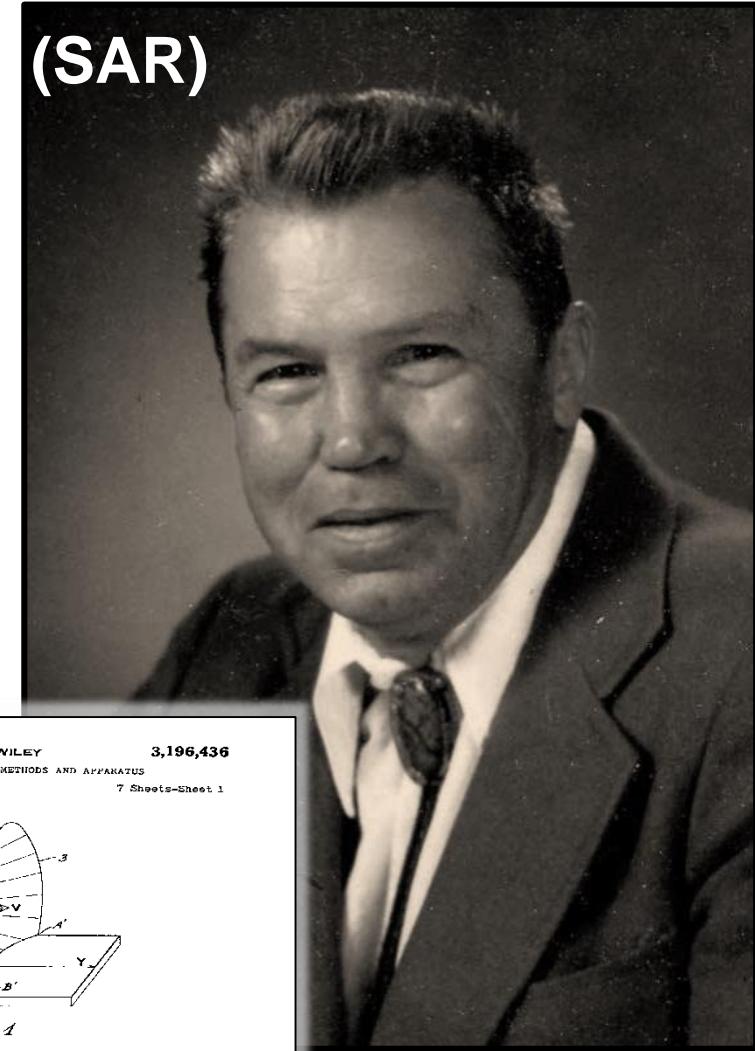
$$\delta_a = 2000 \text{ m !}$$

The Solution: Synthetic Aperture Radar

(SAR)

Carl A. Wiley, 1951:

- A large antenna - required for achieving a high spatial resolution in azimuth - is “synthesised” using an array of small antennas working together.
- This array of small antennas is formed by using a real aperture antenna
 - mounted on a moving (with velocity v_p) platform
 - operated in a pulsed mode (with a Pulse Repetition Frequency given by PRF).



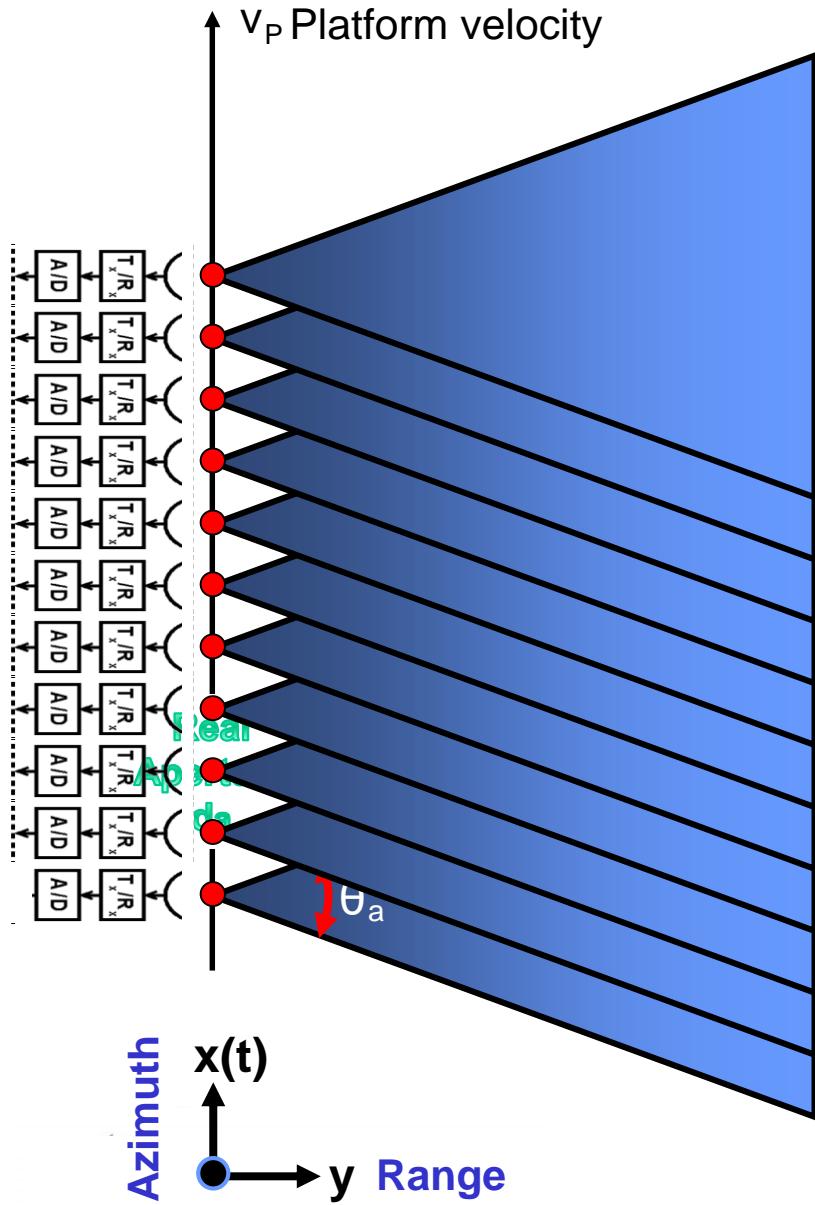
C.A. Wiley / US Patent 3,196,436 / 1951
Pulsed Doppler Radar Methods and Apparatus



Deutsches Zentrum
für Luft- und Raumfahrt e.V.
in der Helmholtz-Gemeinschaft



SAR Azimuth Resolution

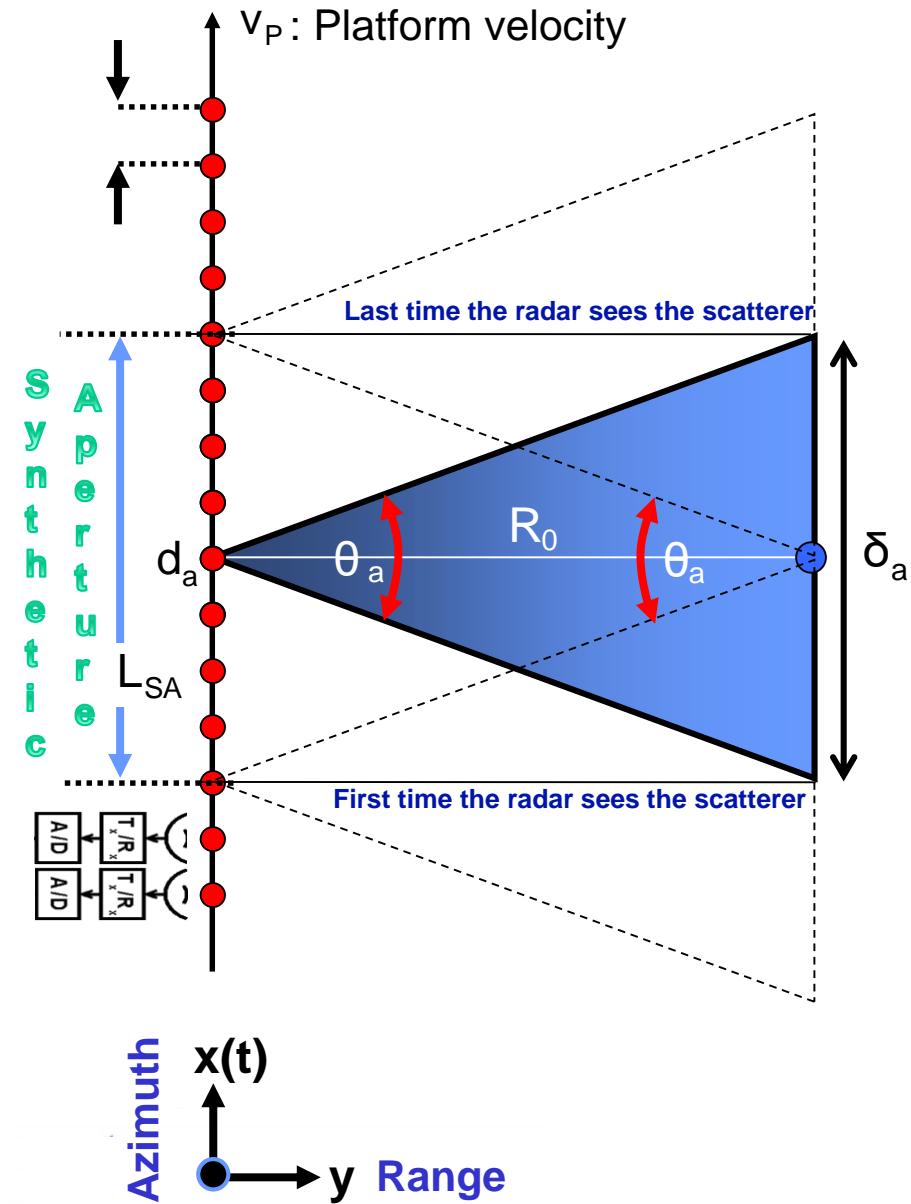


The real aperture antenna is moving forward with velocity v_p and operates in a pulsed mode

Azimuth resolution of the real aperture

$$\text{at distance } R_0: \delta_a = \theta_a R_0 = \frac{\lambda}{d_a} R_0$$

SAR Azimuth Resolution



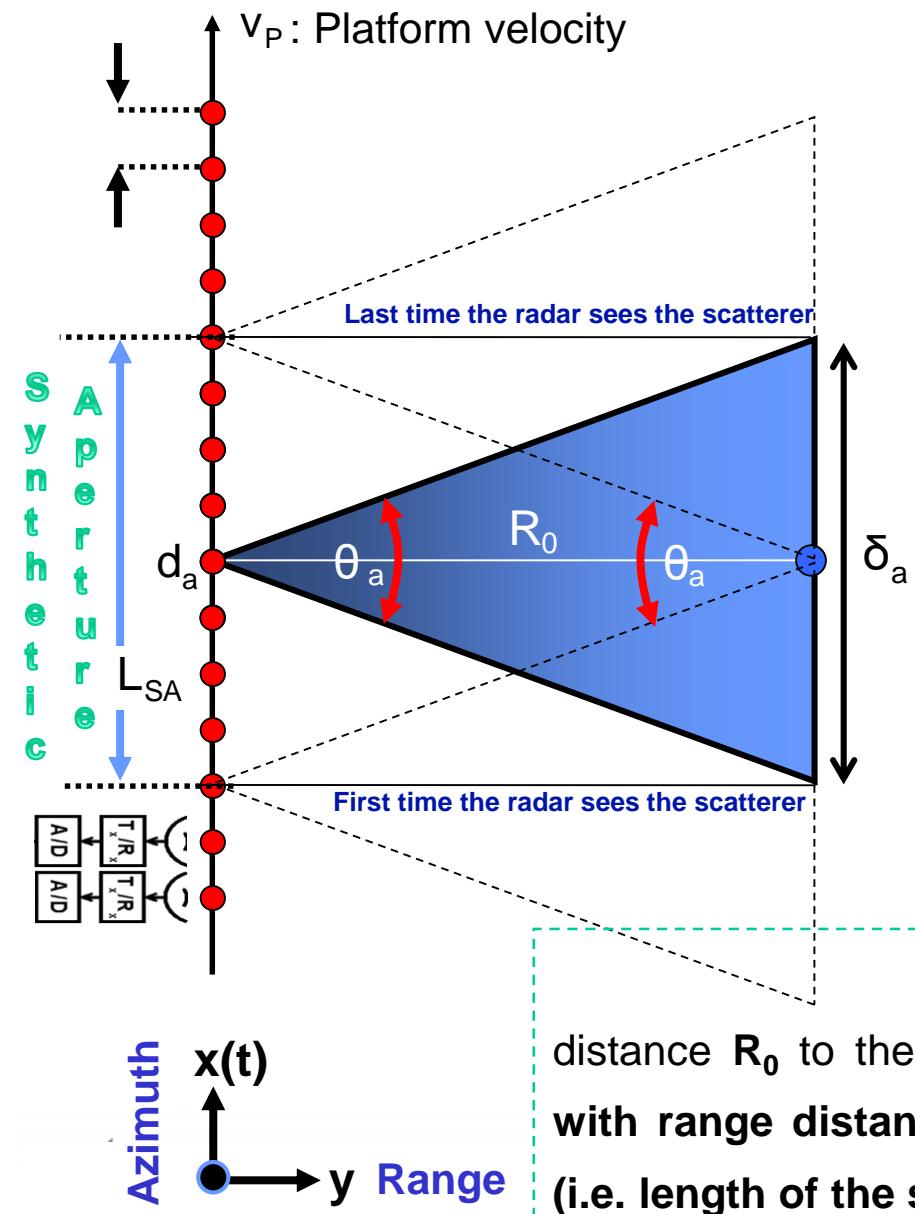
Looking on a scatterer at distance R_0

All echoes received from the scatterer between the first and last echo can be coherently combined to "synthesise" a Synthetic Aperture

Azimuth resolution of the real aperture

$$\text{at distance } R_0: \delta_a = \theta_a R_0 = \frac{\lambda}{d_a} R_0$$

SAR Azimuth Resolution



- Angular resolution of synthetic antenna:

$$\theta_{SA} = \frac{\lambda}{2L_{SA}} = \frac{d_a}{2R_0}$$

decreases with distance R_0

- Length of the synthetic aperture (at distance R_0):

$$L_{SA} = \delta_a = \theta_a R_0 = \frac{\lambda}{d_a} R_0$$

increases with R_0

- Illumination time of an scatterer at distance R_0 :

$$t_{SA} = \frac{L_{SA}}{v_p} = \frac{\lambda}{d_a} \frac{R_0}{v_p}$$

- Azimuth resolution: δ_a

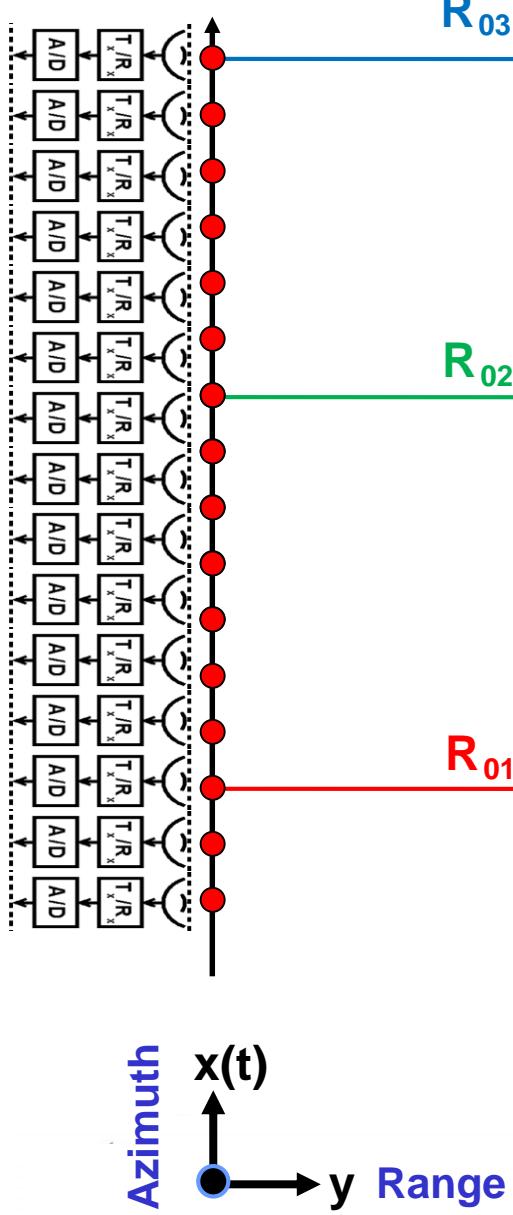
$$\delta_{SA} = \theta_{SA} R_0 = \frac{d_a}{2}$$

v_p : velocity of the platform
= Half (Real) Antenna Length!

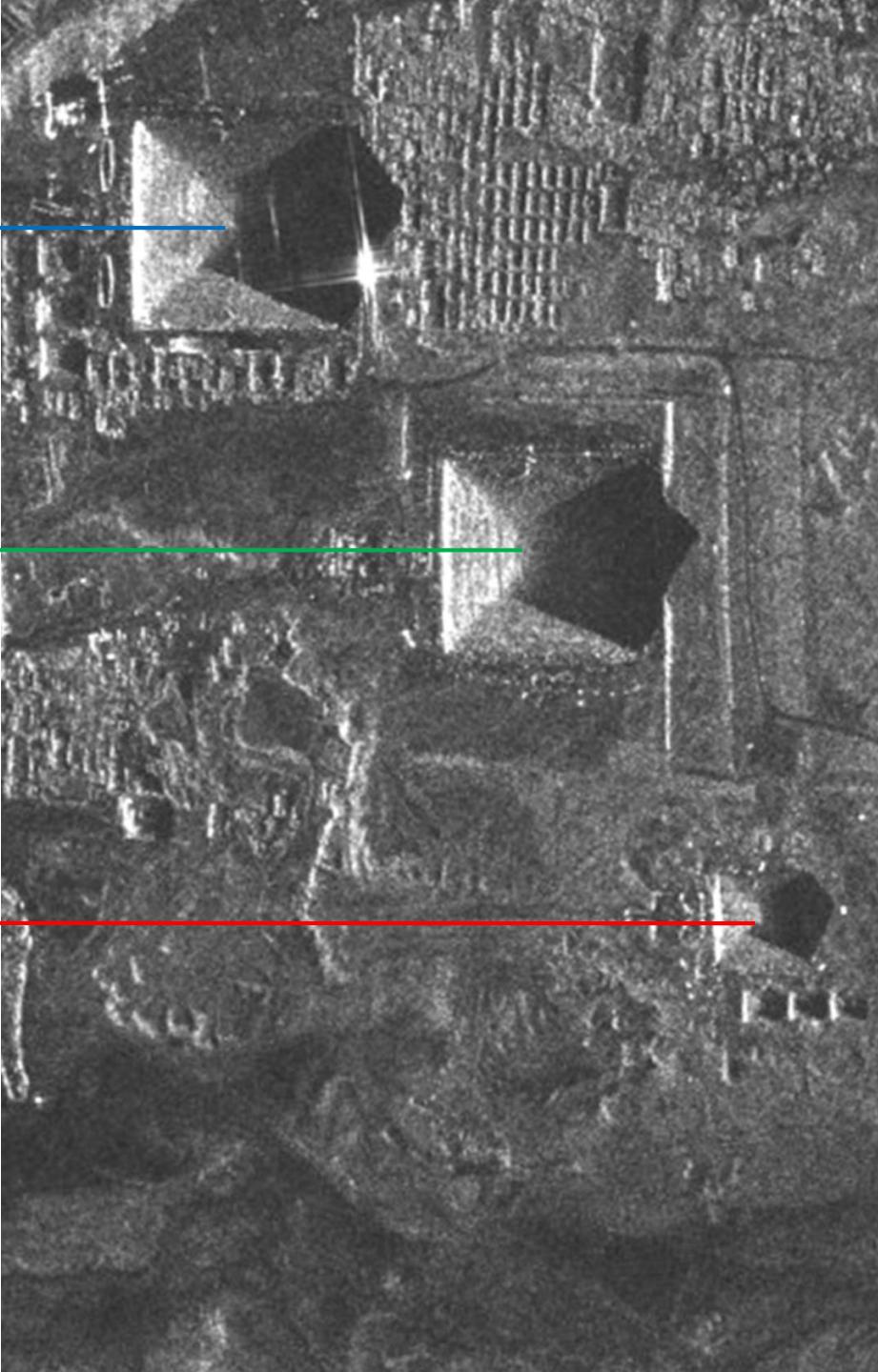
The azimuth resolution is independent on range (i.e. the

distance R_0 to the scatterer): **The (linear) decrease of spatial resolution with range distance R_0 is compensated by the longer illumination time (i.e. length of the synthetic aperture) which increases (linear) with R_0 .**

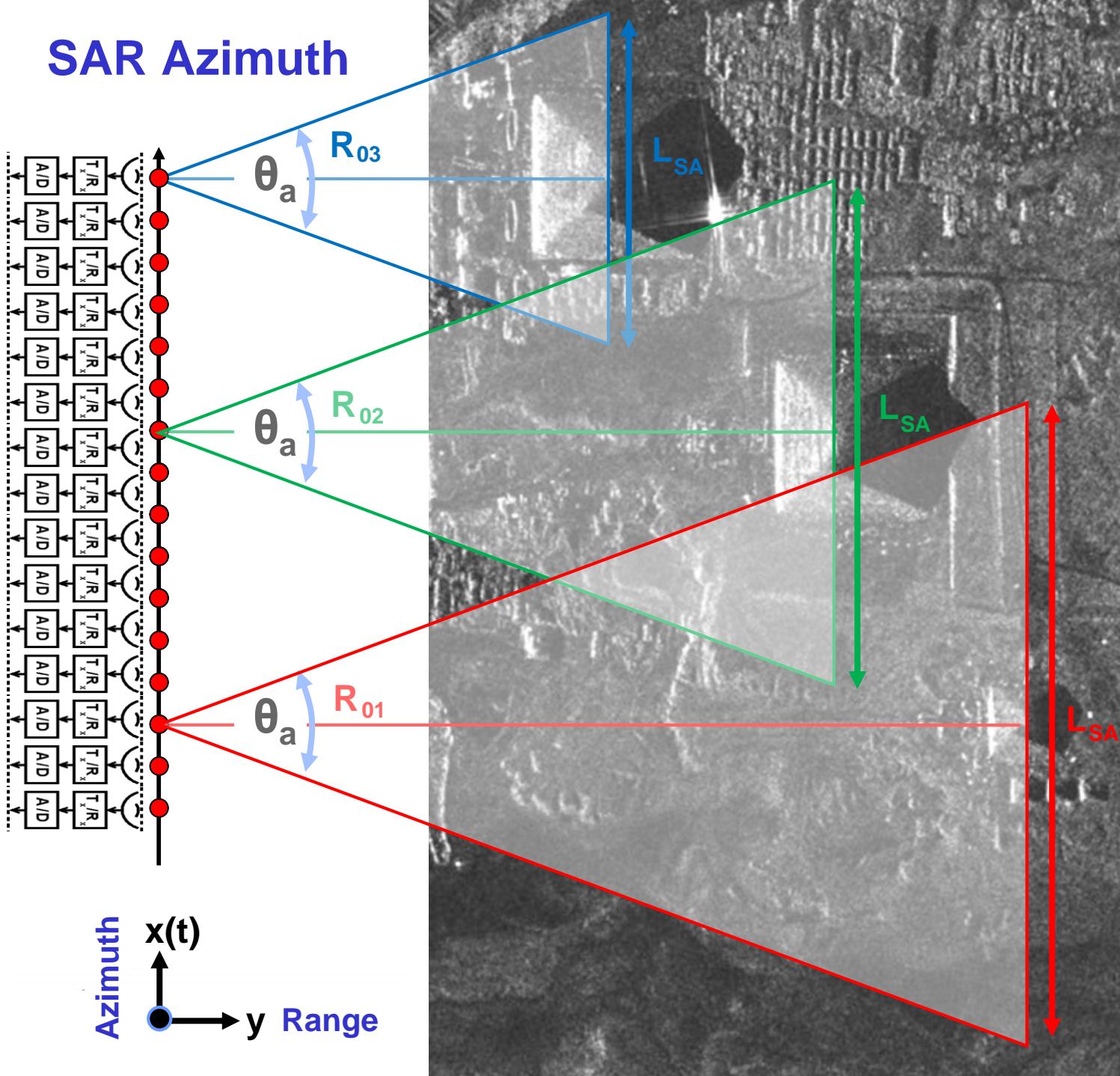
SAR Azimuth



Resolution



SAR Azimuth



Resolution

The deterioration of spatial resolution δ_{SA} with increasing range distance R_0

$$\delta_{SA} = \theta_{SA} R_0 = \frac{\lambda}{2 L_{SA}} R_0$$

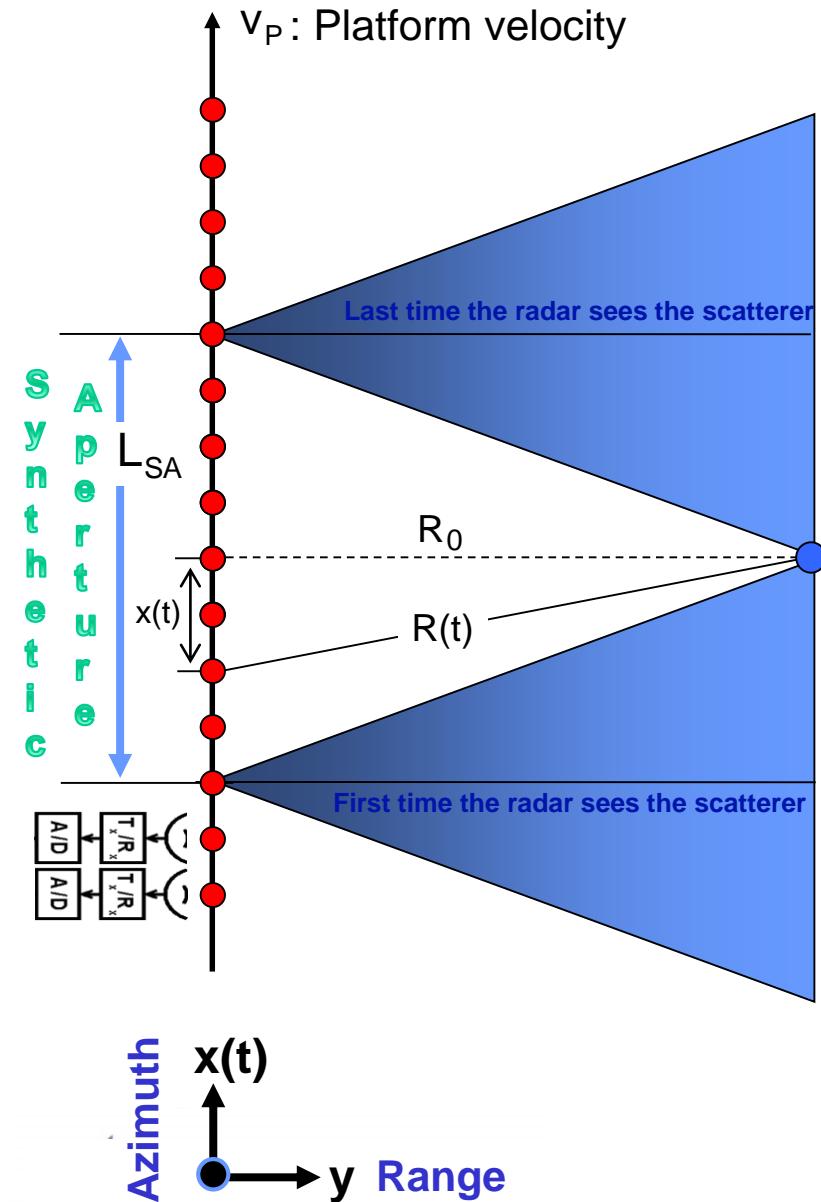
is compensated with the increase of the synthetic aperture L_{SA}

$$L_{SA} = \frac{\lambda}{d_a} R_0$$

with the increase of the time t_{SA} the scatterer is seen by the SAR):

$$t_{SA} = \frac{L_{SA}}{v_p} = \frac{\lambda}{d_a v_p} R_0$$

SAR Azimuth Signal Reconstruction



- Radar-Scatterer distance variation along the aperture:

$$R(t) = \sqrt{R_0^2 + x(t)^2}$$

$$= R_0 \sqrt{1 + \frac{x(t)^2}{R_0^2}} \approx R_0 \left(1 + \frac{x(t)^2}{2R_0^2} \right) = R_0 + \frac{x(t)^2}{2R_0}$$

$$R(t) = R_0 + \frac{v_p^2 t^2}{2R_0} \quad \text{with} \quad x(t) = v_p t$$

- Phase variation along the aperture:

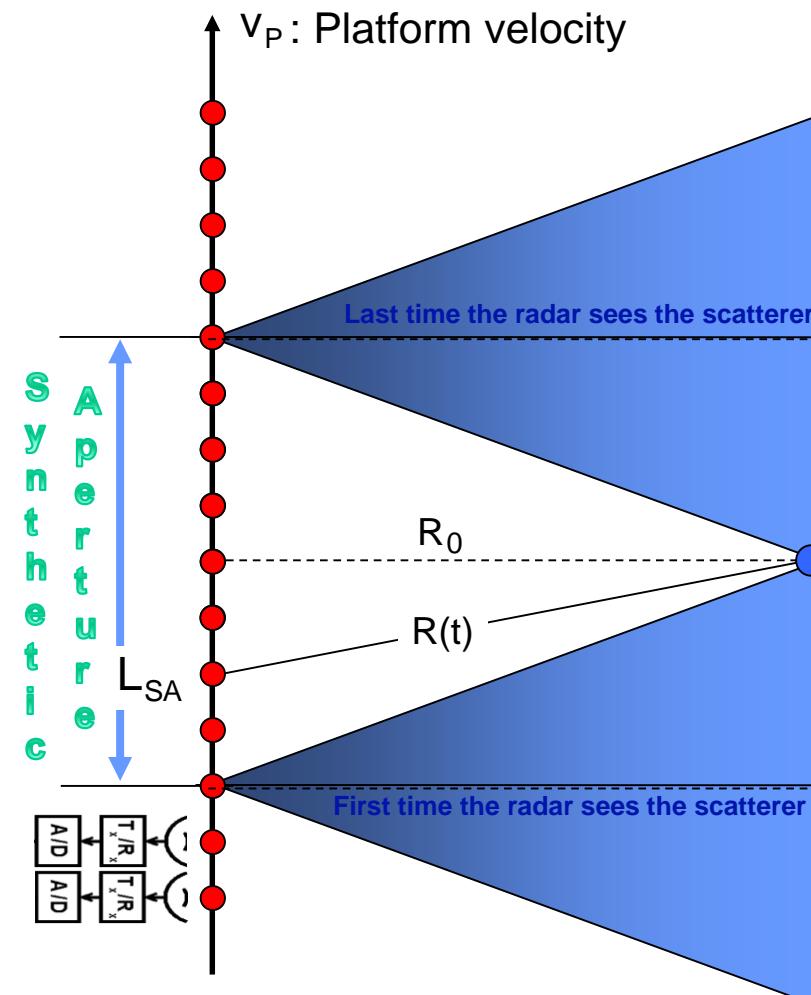
$$\varphi(t) = -2 \frac{2\pi}{\lambda} R(t) = -\frac{4\pi}{\lambda} R_0 - \frac{4\pi}{\lambda} \frac{v_p^2 t^2}{2R_0}$$

- Frequency variation along the aperture:

$$f(t) = \frac{1}{2\pi} \frac{d\varphi}{dx} = -\frac{2}{\lambda} \frac{v_p^2 t}{R_0}$$

SAR Azimuth Signal Reconstruction

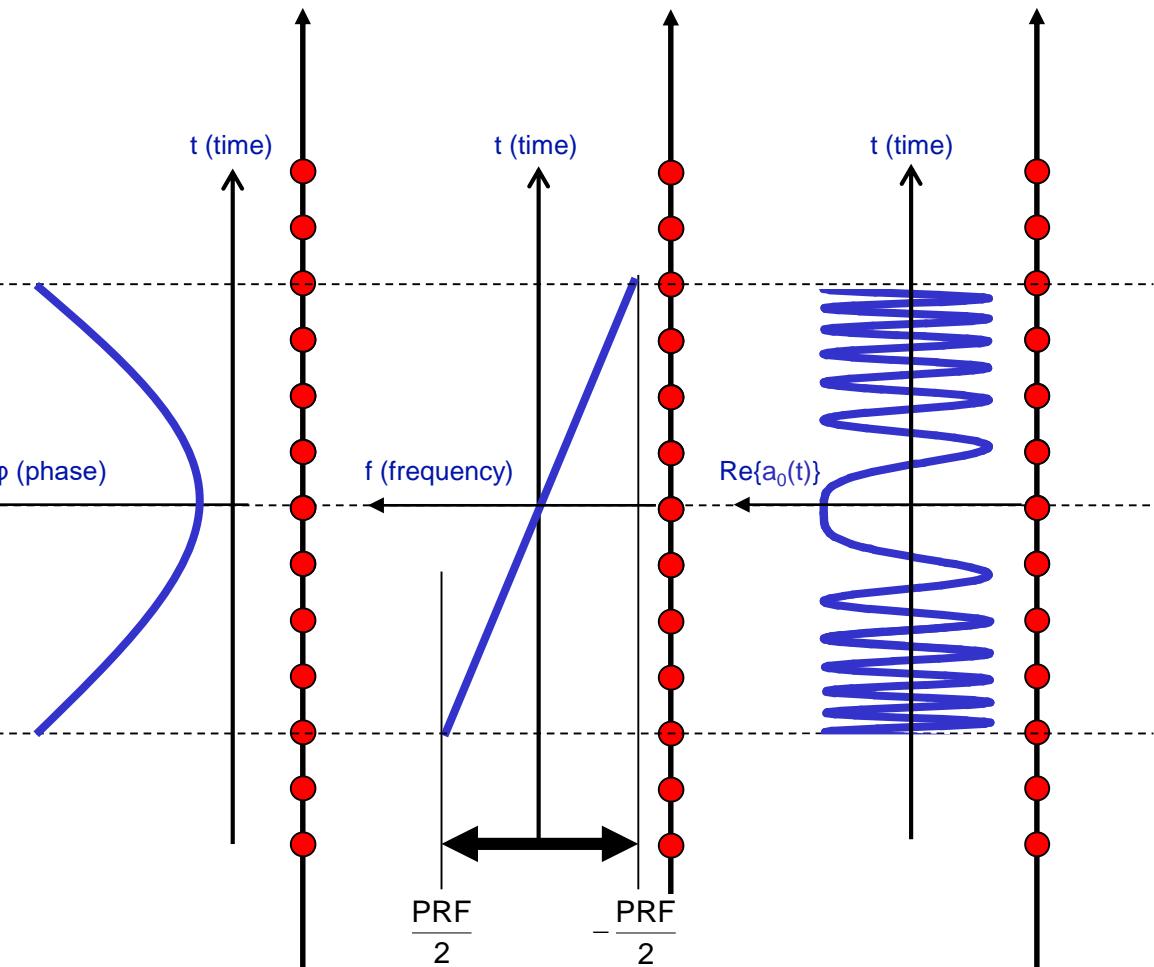
$$a_0(t) = A \exp(i\varphi(t)) \operatorname{rect}\left(\frac{t}{t_{SA}}\right)$$



Phase History
(Quadratic)

Frequency Variation
(Linear)

Received Signal
(Real Part $\operatorname{Re}\{a_0(t)\}$)

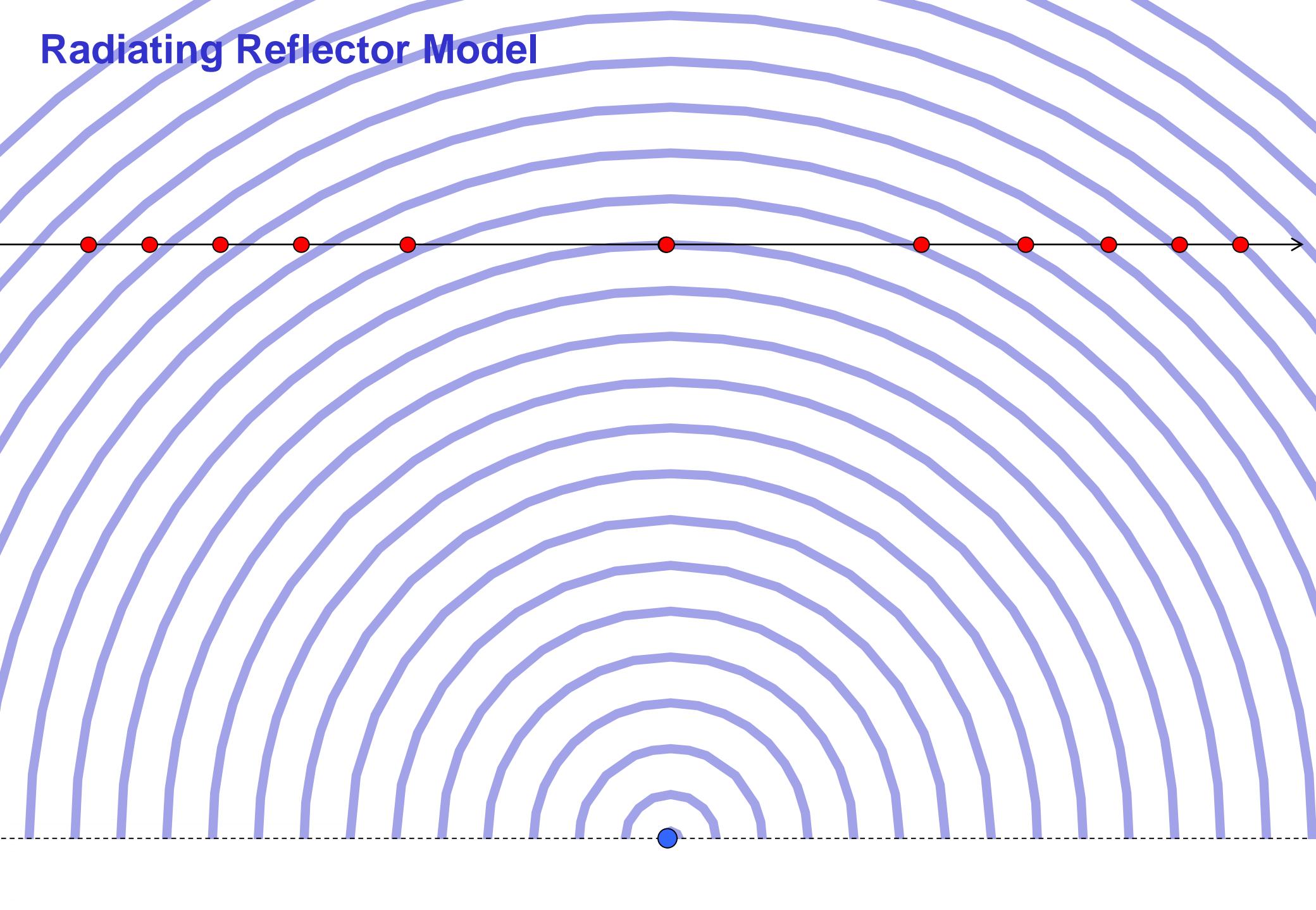


Azimuth
x(t)
y Range

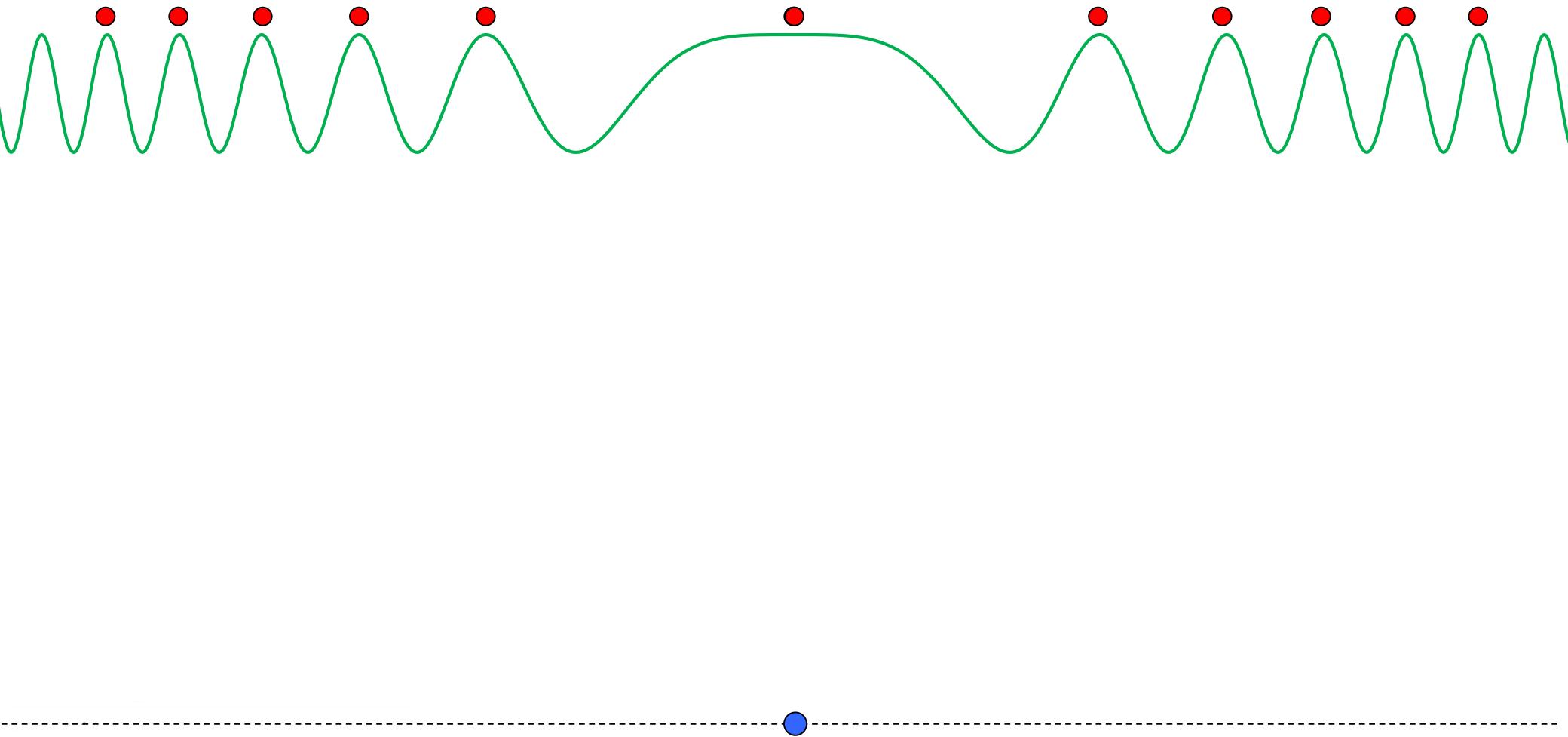
$$t_{SA} \text{ illumination time} = \text{time the scatterer is seen by the radar} \quad t_{SA} = \frac{L_{SA}}{v_p}$$

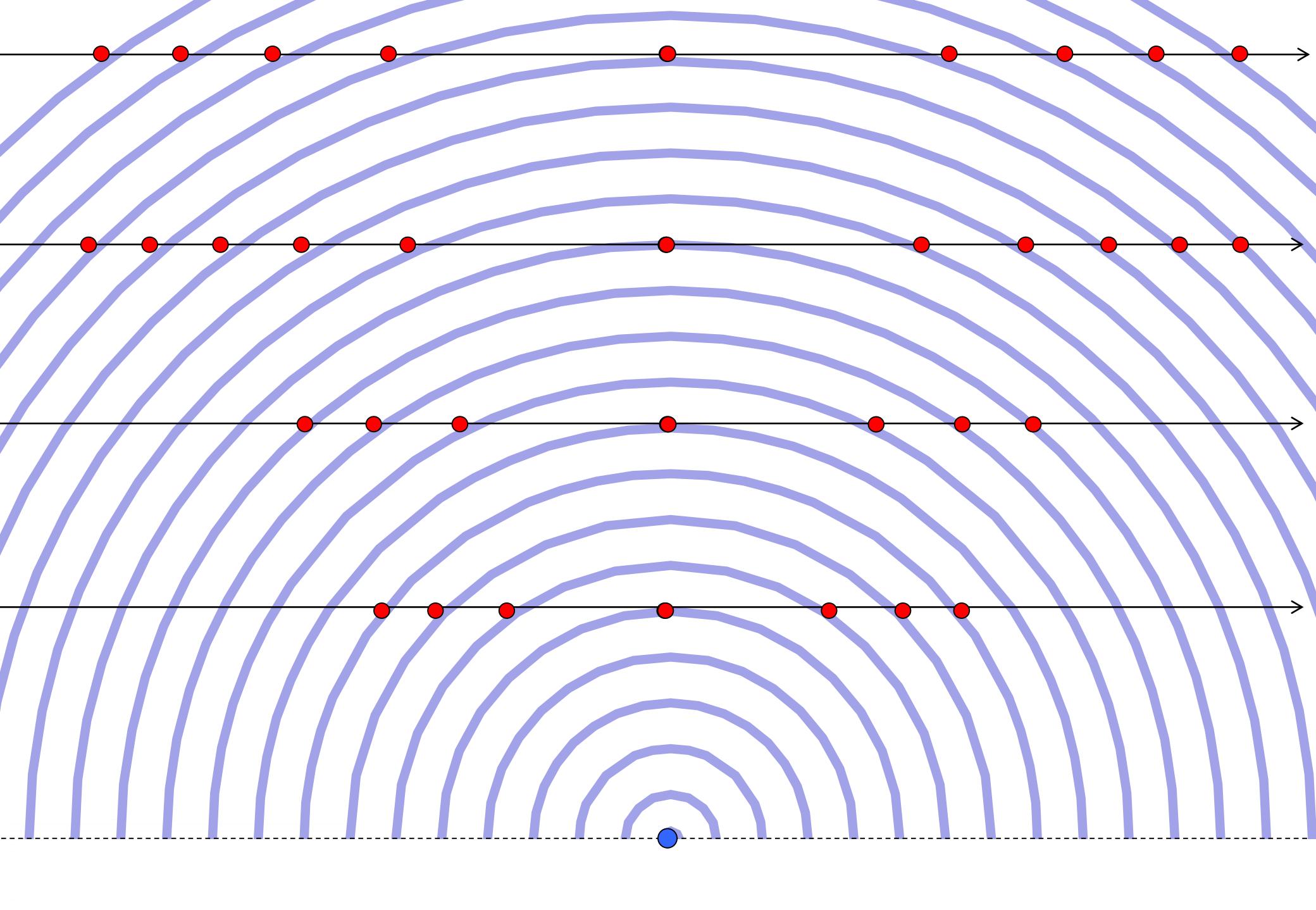
$$\varphi(t) = -\frac{4\pi}{\lambda} R_0 - \frac{4\pi v_p^2 t^2}{\lambda} \frac{2R_0}{2}$$

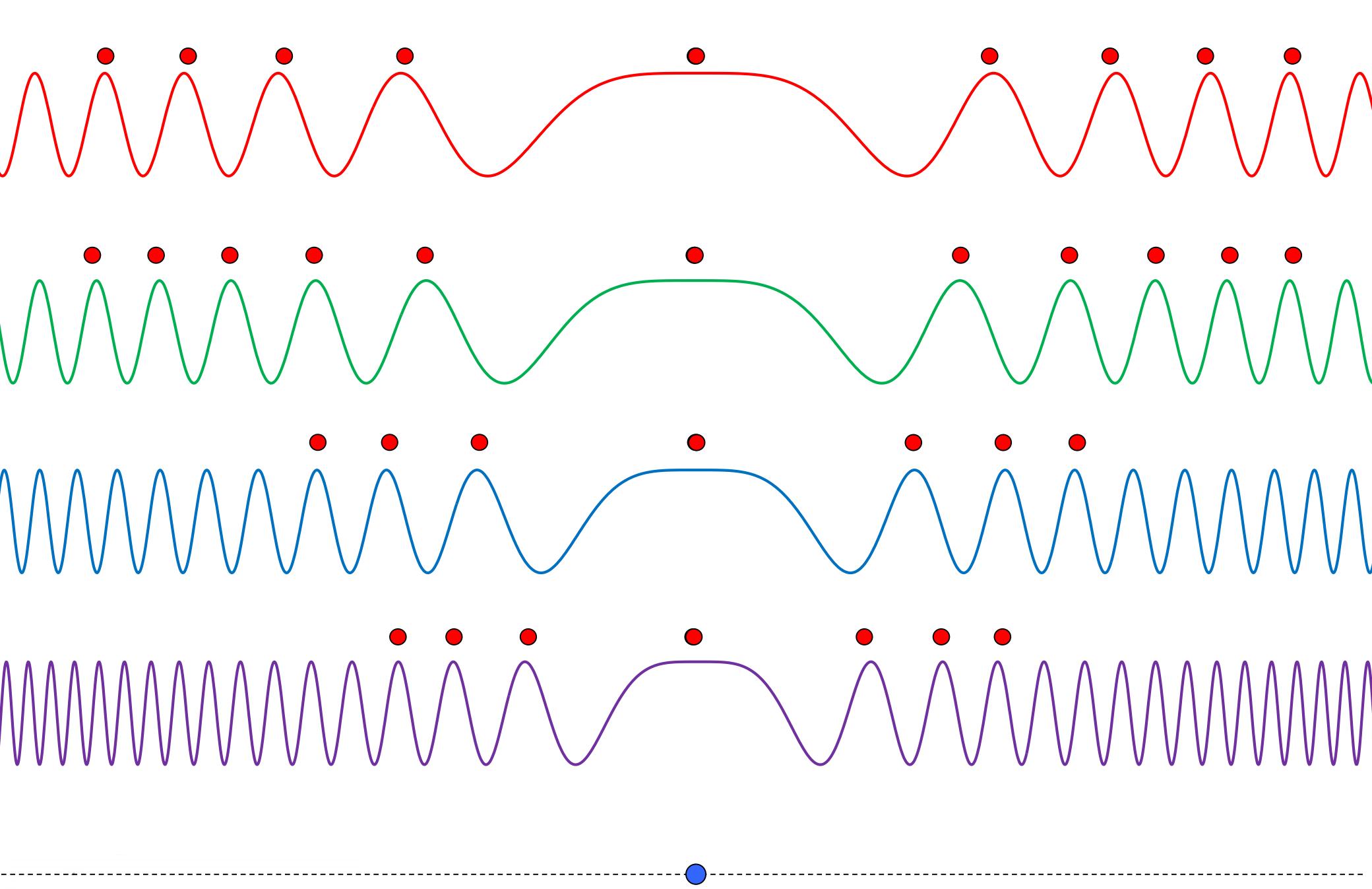
Radiating Reflector Model



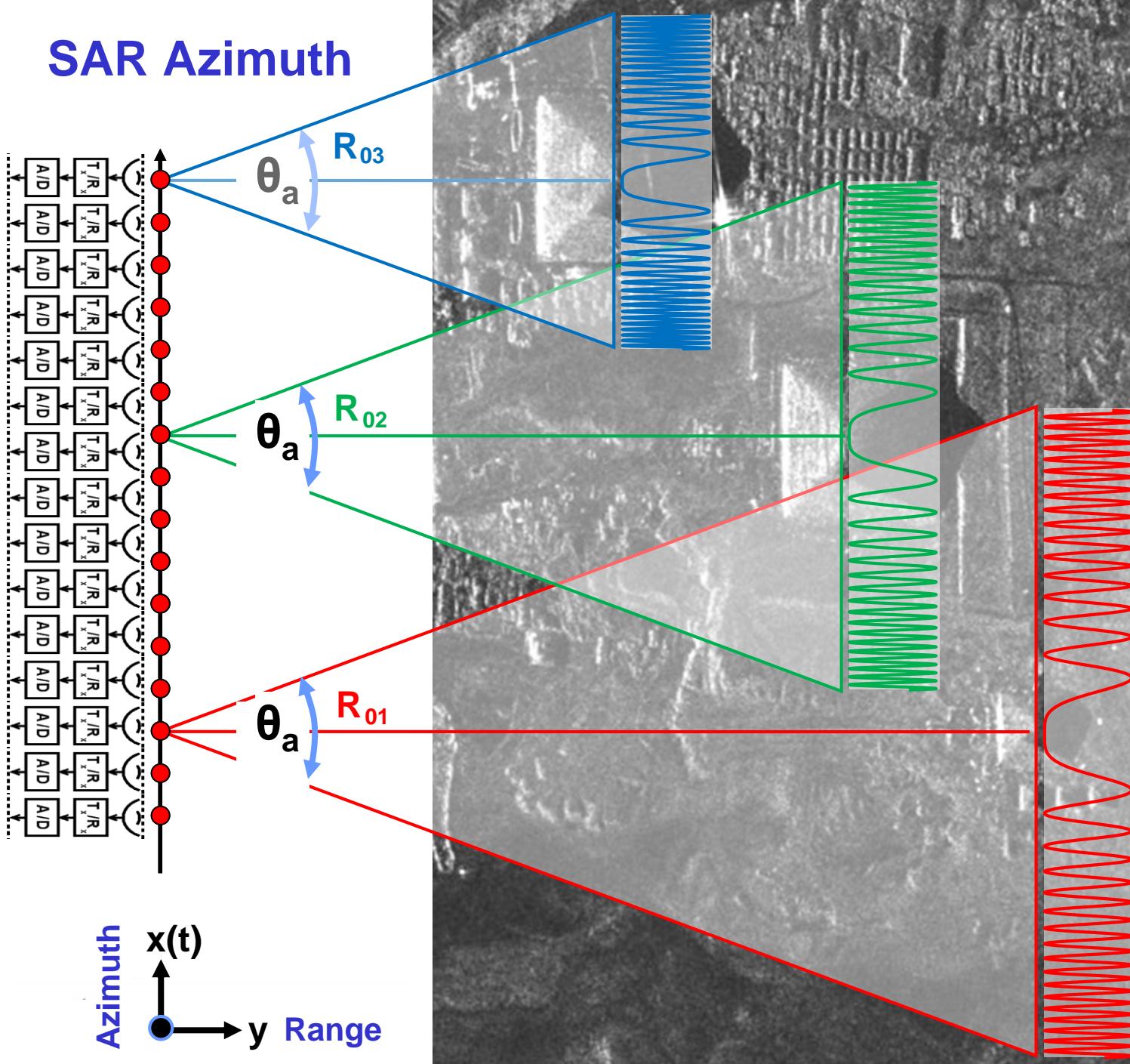
Radiating Reflector Model







SAR Azimuth



Resolution

The deterioration of spatial resolution δ_{SA} with increasing range distance R_0

$$\delta_{SA} = \theta_{SA} R_0 = \frac{\lambda}{2 L_{SA}} R_0$$

is compensated with the increase of the synthetic aperture L_{SA}

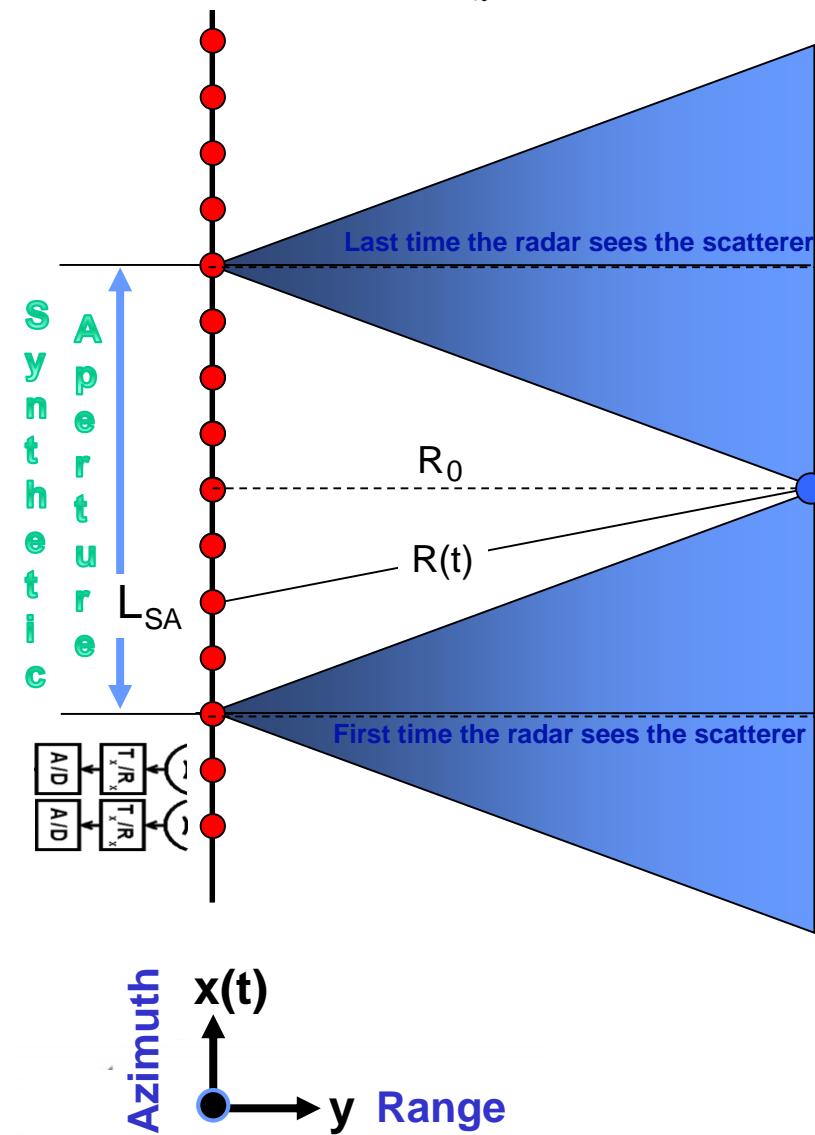
$$L_{SA} = \frac{\lambda}{d_a} R_0$$

with the increase of the time t_{SA} the scatterer is seen by the SAR):

$$t_{SA} = \frac{L_{SA}}{v_p} = \frac{\lambda}{d_a v_p} R_0$$

Matched Filter:

$$u_0(t) = s_0(t) \otimes h_0(t) = \int_{-\infty}^{\infty} s_0(T) \cdot h_0(t-T) dT$$



SAR Azimuth Compression

Phase History
(Quadratic)

Reference Signal

$$h_0(t) = x_0^*(-t)$$

Received Signal
(Real Part Re{...})

$$s_0(t) = a_0(t) + n(t)$$

t (time)

ϕ

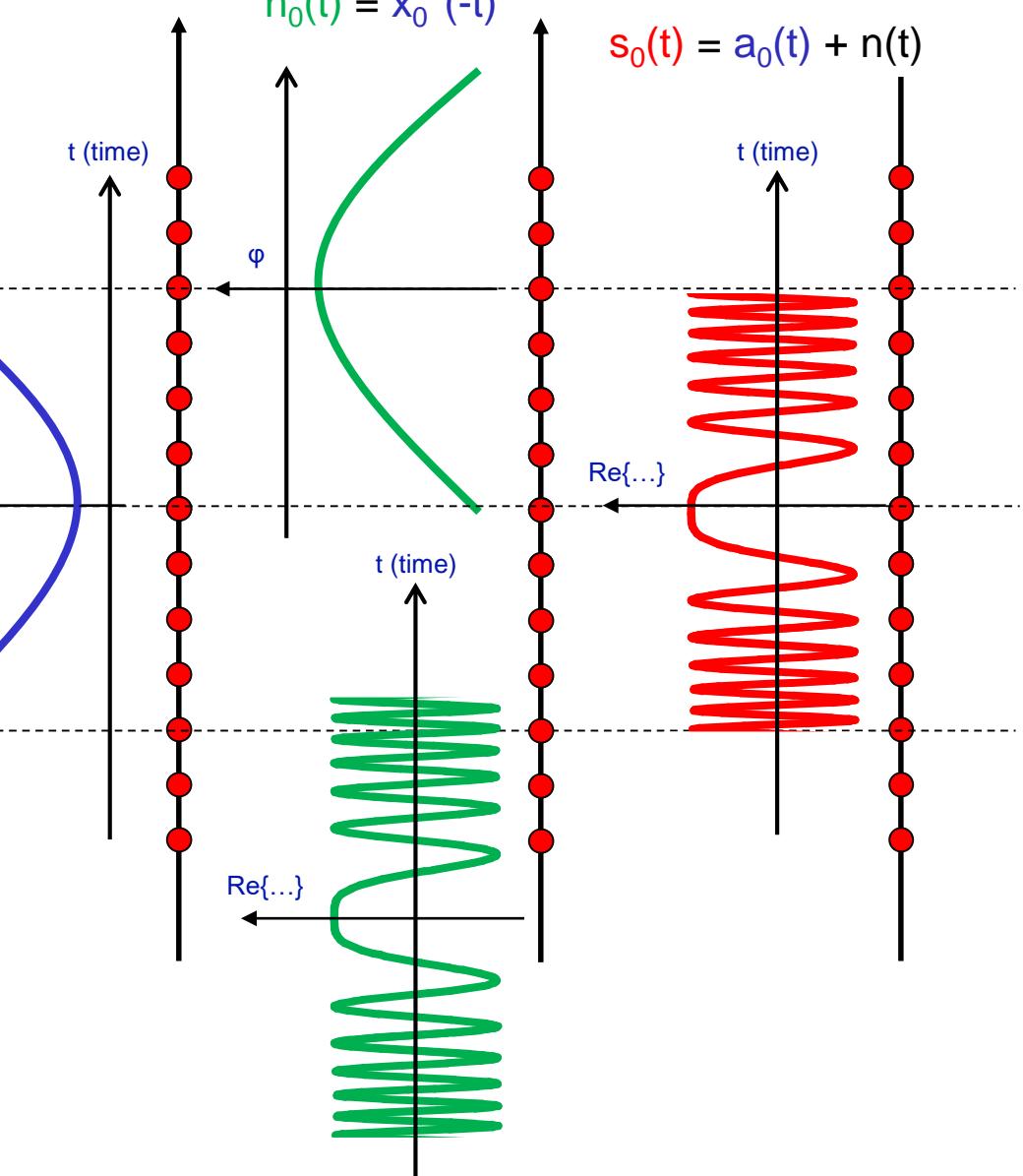
t (time)

Re{...}

t (time)

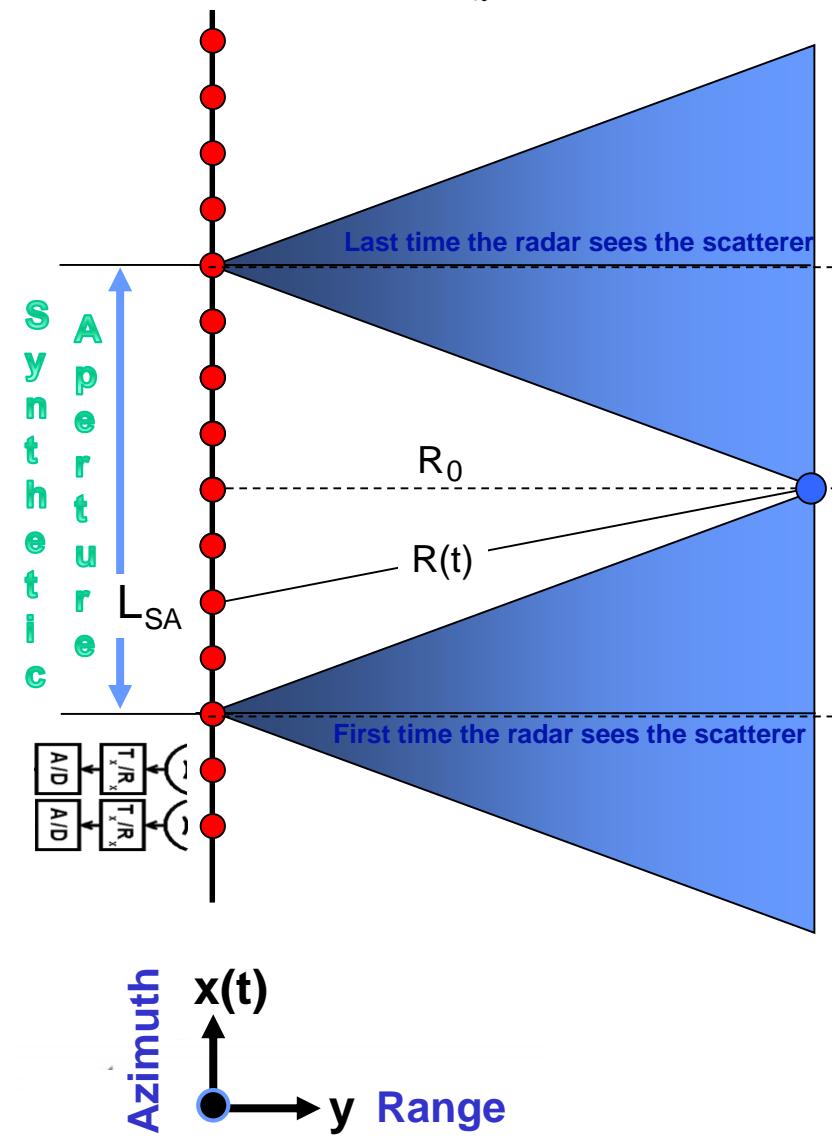
ϕ

Re{...}



Matched Filter:

$$u_0(t) = s_0(t) \otimes h_0(t) = \int_{-\infty}^{\infty} s_0(T) \cdot h_0(t-T) dT$$



SAR Azimuth Compression

Azimuth Impulse Response $u_0(t)$

Reference Signal

$$h_0(t) = x_0^*(-t)$$

Received Signal (Real Part $\text{Re}\{s_0(t)\}$)

$$s_0(t) = x_0(t) + n(t)$$

t (time)

φ

t (time)

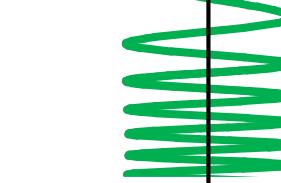
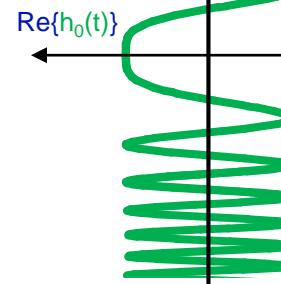
t (time)

t (time)

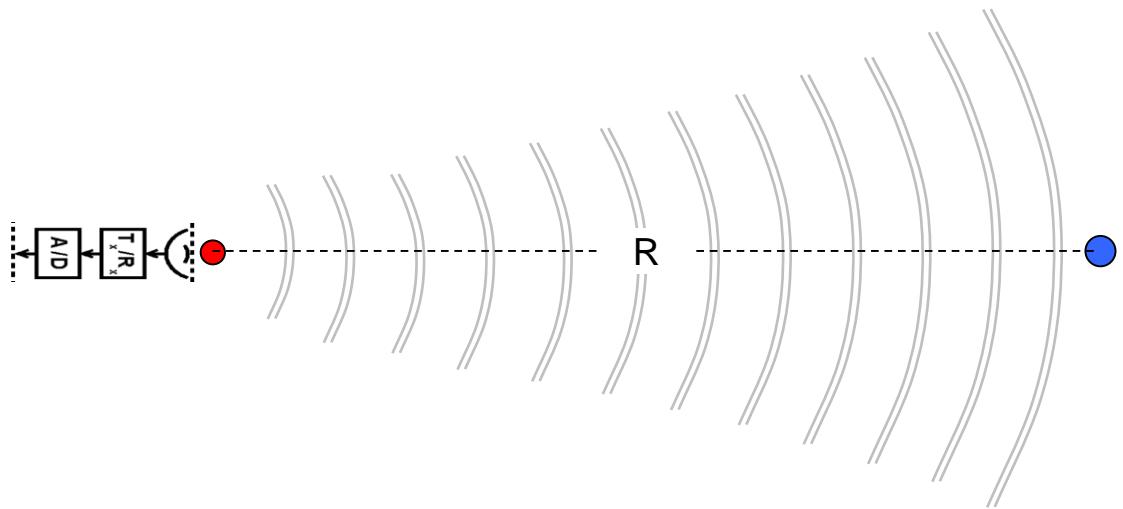
\otimes

\otimes

t (time)



SAR Azimuth Signal Reconstruction

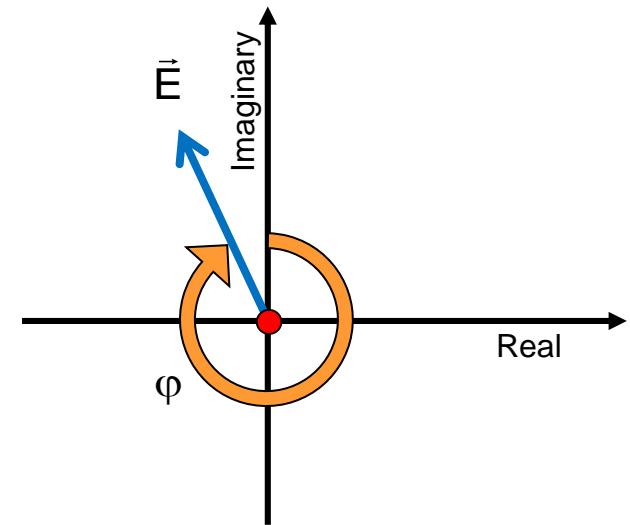
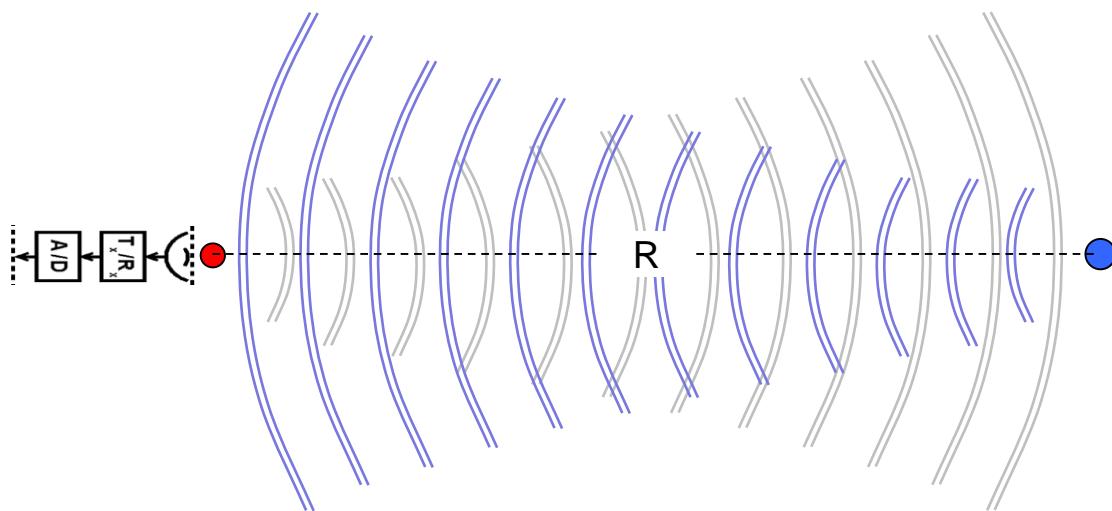


SAR Azimuth Signal Reconstruction

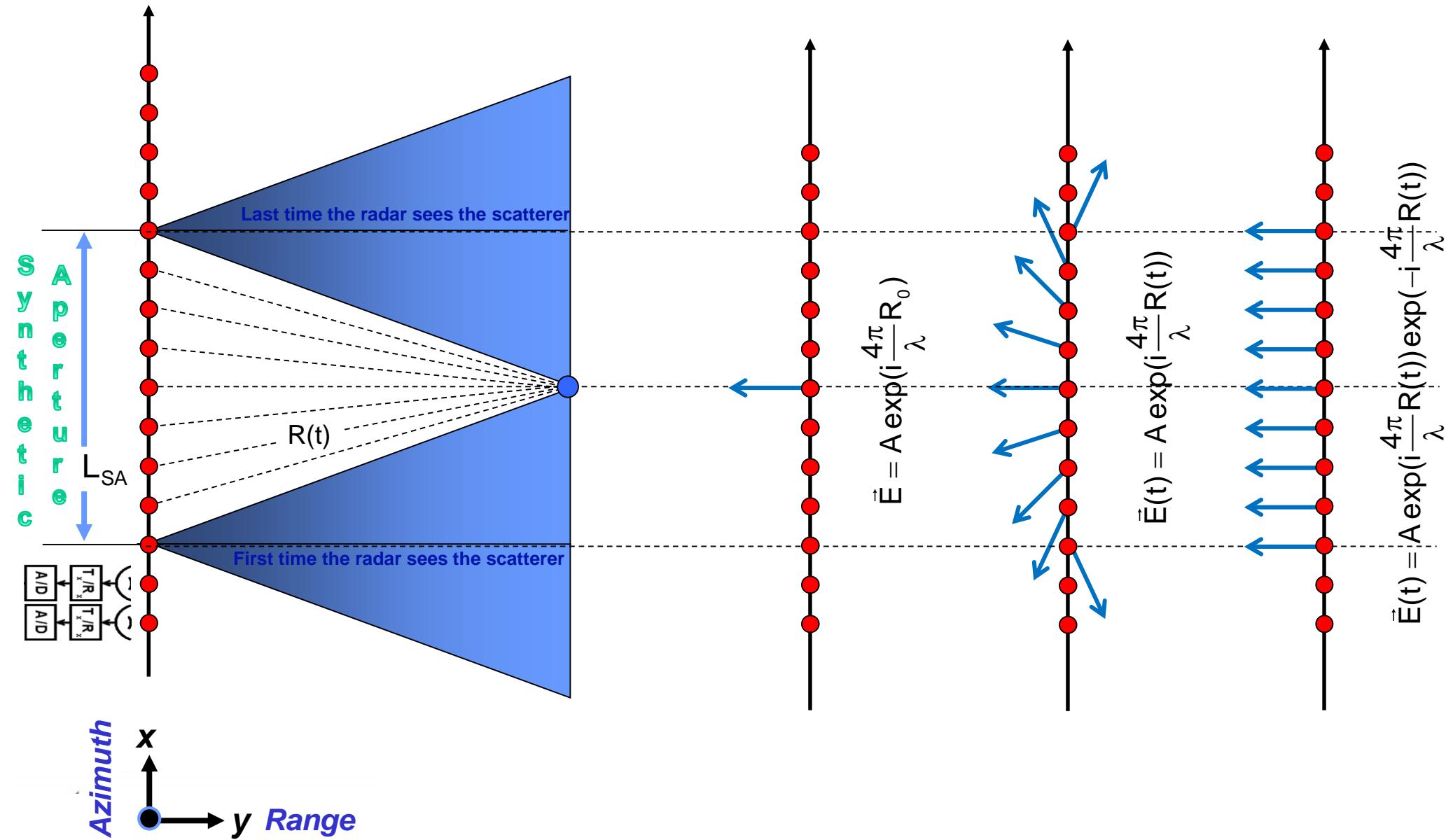
Received Electric Field: $\vec{E} = A \exp(i\varphi)$

(Scattering) Amplitude: $|\vec{E}| = A$

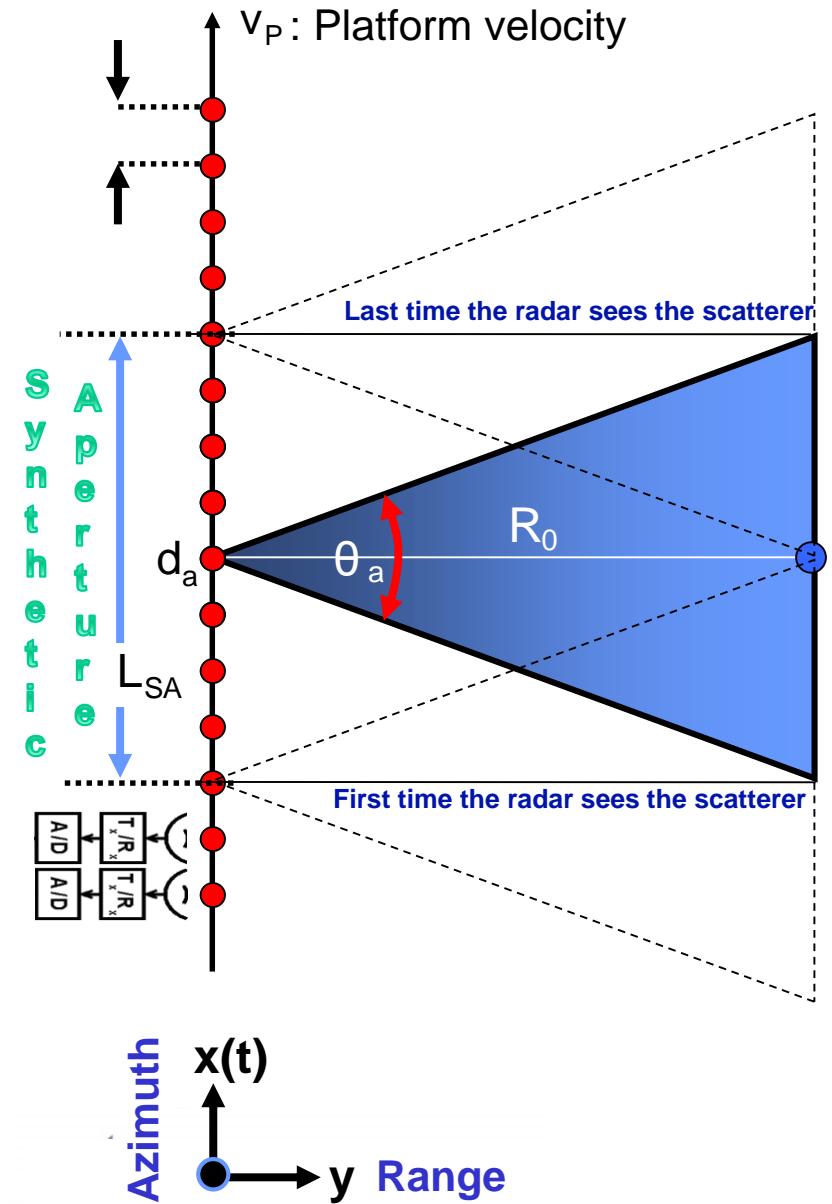
Phase: $\varphi := 2 \frac{2\pi}{\lambda} R$



SAR Azimuth Signal Reconstruction



SAR Azimuth Resolution: An example



Antenna length: $d_a = 3 \text{ m}$

Platform velocity: $v_p = 100 \text{ m/s}$

Scatterer distance: $R_0 = 8570 \text{ m}$

Wavelength P-band: $\lambda = 0.7 \text{ m}$ (P-band)

Max azimuth resolution: $\delta_{SA} = \frac{d_a}{2}$

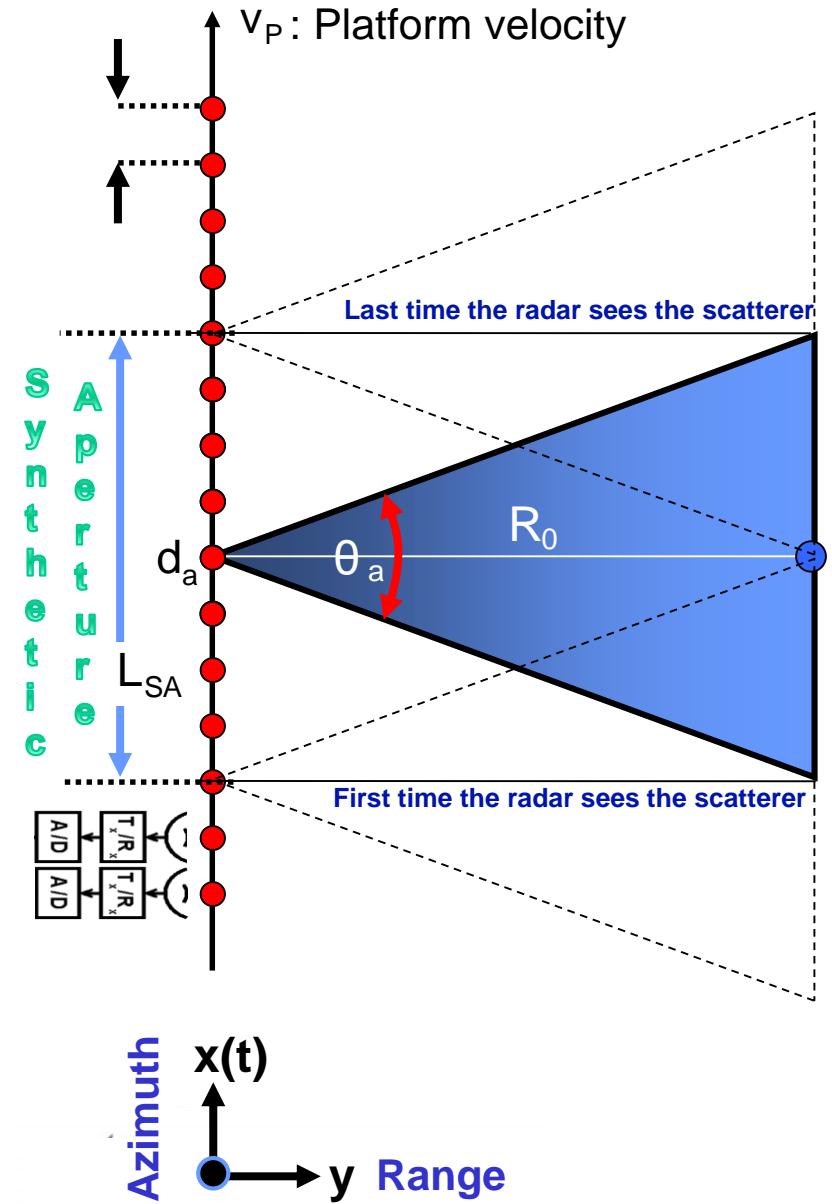
Synthetic aperture length: $L_{SA} = \frac{\lambda}{d_a} R_0$

Illumination time: $t_{SA} = \frac{L_{SA}}{v_p} = \frac{\lambda}{d_a v_p} R_0$

Azimuth Signal: $a_0(t) = A \exp(i\varphi(t)) \operatorname{rect}\left(\frac{t}{t_{SA}}\right)$

with: $\varphi(t) = -\frac{4\pi}{\lambda} R_0 - \frac{4\pi}{\lambda} \frac{v_p^2 t^2}{2R_0}$

SAR Azimuth Resolution: An example



Antenna length: $d_a = 3 \text{ m}$

Platform velocity: $v_p = 100 \text{ m/s}$

Scatterer distance: $R_0 = 8570 \text{ m}$

Wavelength P-band: $\lambda = 0.7 \text{ m}$ (P-band)

Azimuth resolution: $\delta_{SA} = 5 \text{ m}$

Equiv. real aperture: $\delta_{SA'} = \frac{d_{a'}}{2} \rightarrow d_{a'} = 2\delta_{SA}$

Synthetic aperture length: $L_{SA} = \frac{\lambda}{d_{a'}} R_0$

Illumination time: $t_{SA} = \frac{L_{SA}}{v_p} = \frac{\lambda}{d_{a'}} \frac{R_0}{v_p}$

Azimuth Signal: $a_0(t) = A \exp(i\varphi(t)) \operatorname{rect}\left(\frac{t}{t_{SA}}\right)$

with: $\varphi(t) = -\frac{4\pi}{\lambda} R_0 - \frac{4\pi v_p^2 t^2}{\lambda 2R_0}$

The InSAR Course

Synthetic Aperture Radar (SAR)

Part 2: Azimuth Resolution

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