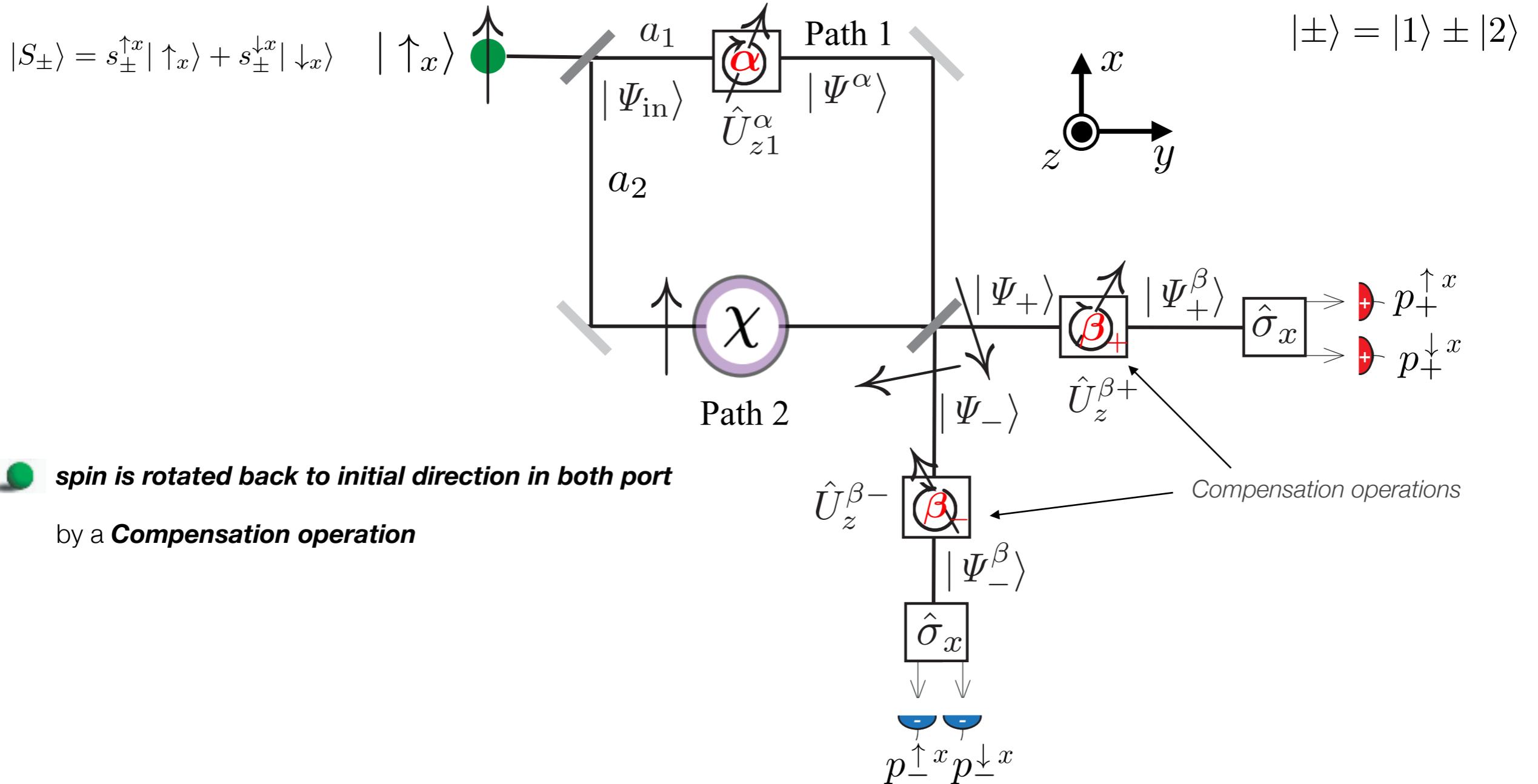


Interference VS Which-Way Measurements: **path presence**

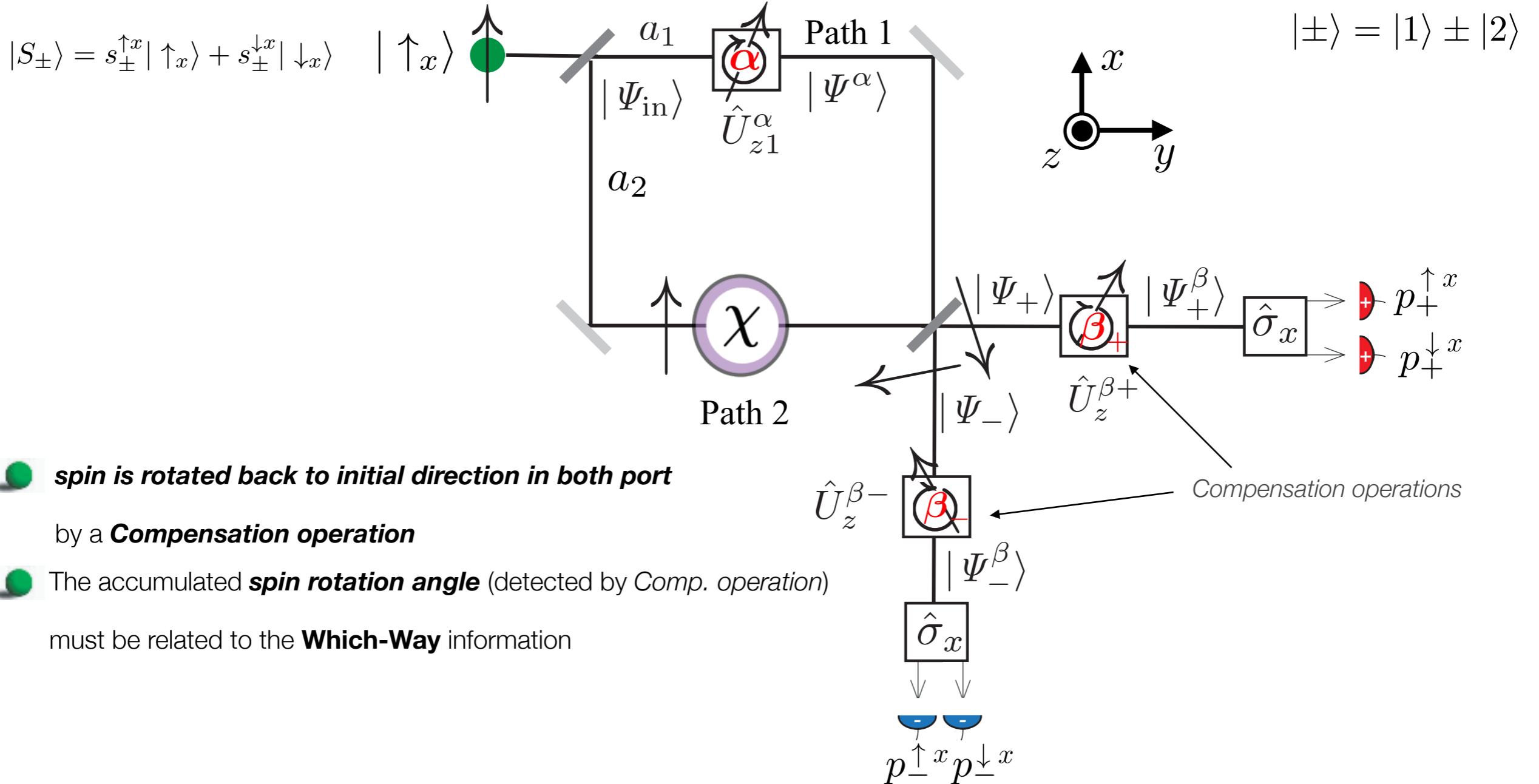
$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$



spin is rotated back to initial direction in both port
by a **Compensation operation**

Interference VS Which-Way Measurements: path presence

$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$



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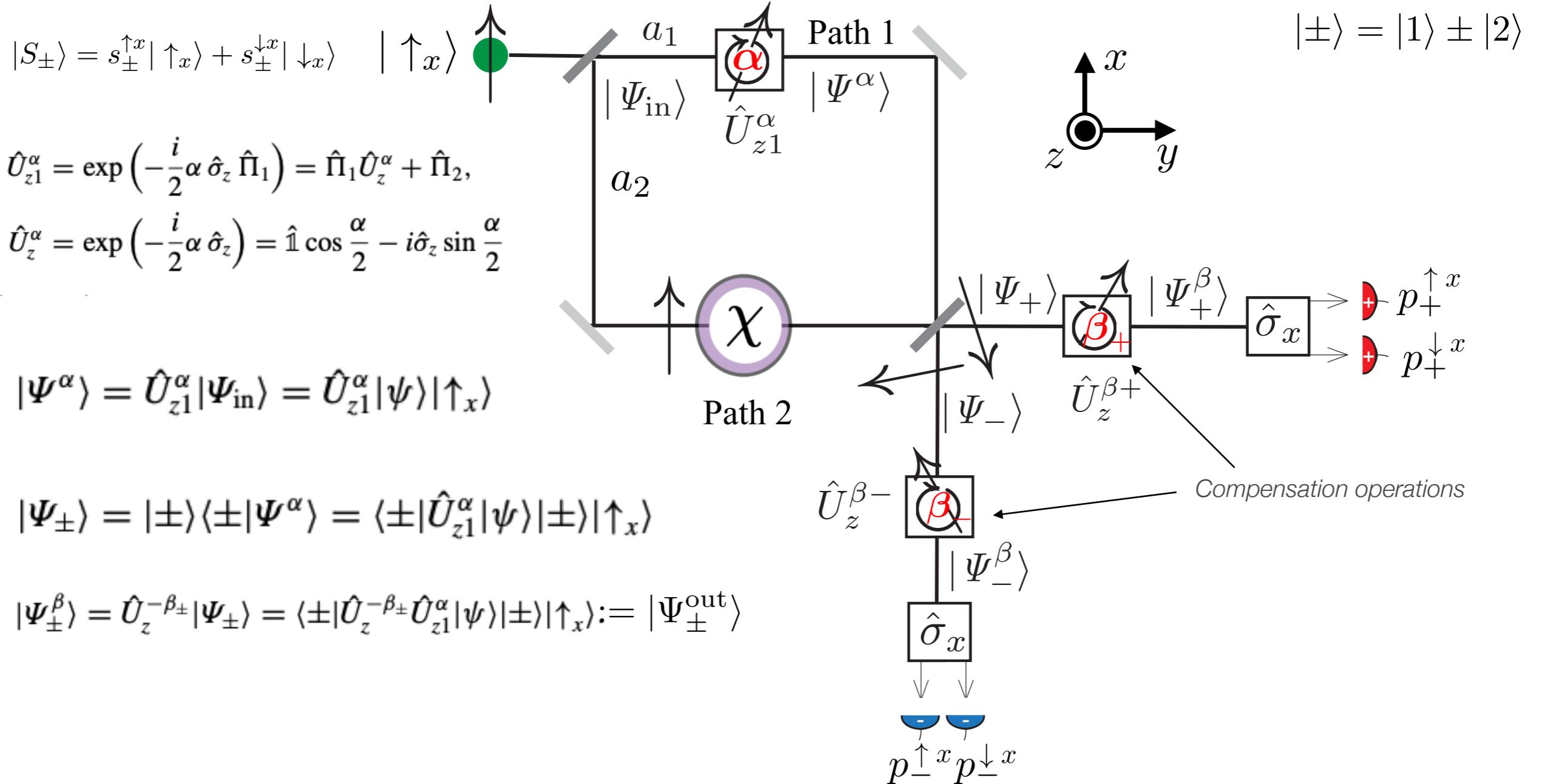
The accumulated **spin rotation angle** (detected by Comp. operation)

must be related to the **Which-Way** information

H. Lemmel, N. Geerits, A. Danner, H. F. Hofmann, and S. Sponar, *Physical Review Research* **4**, 023075 (2022)

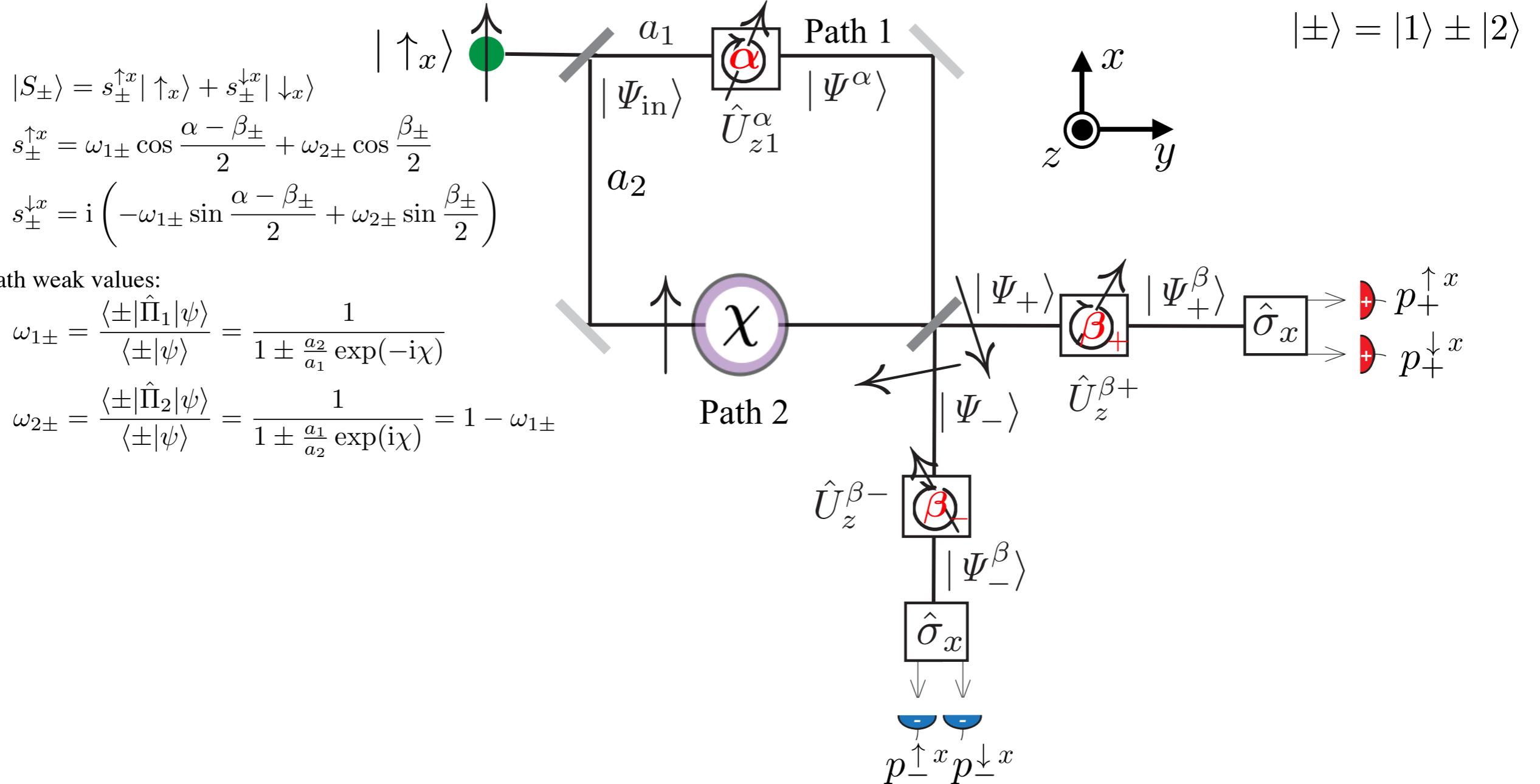
Interference VS Which-Way Measurements: **path presence**

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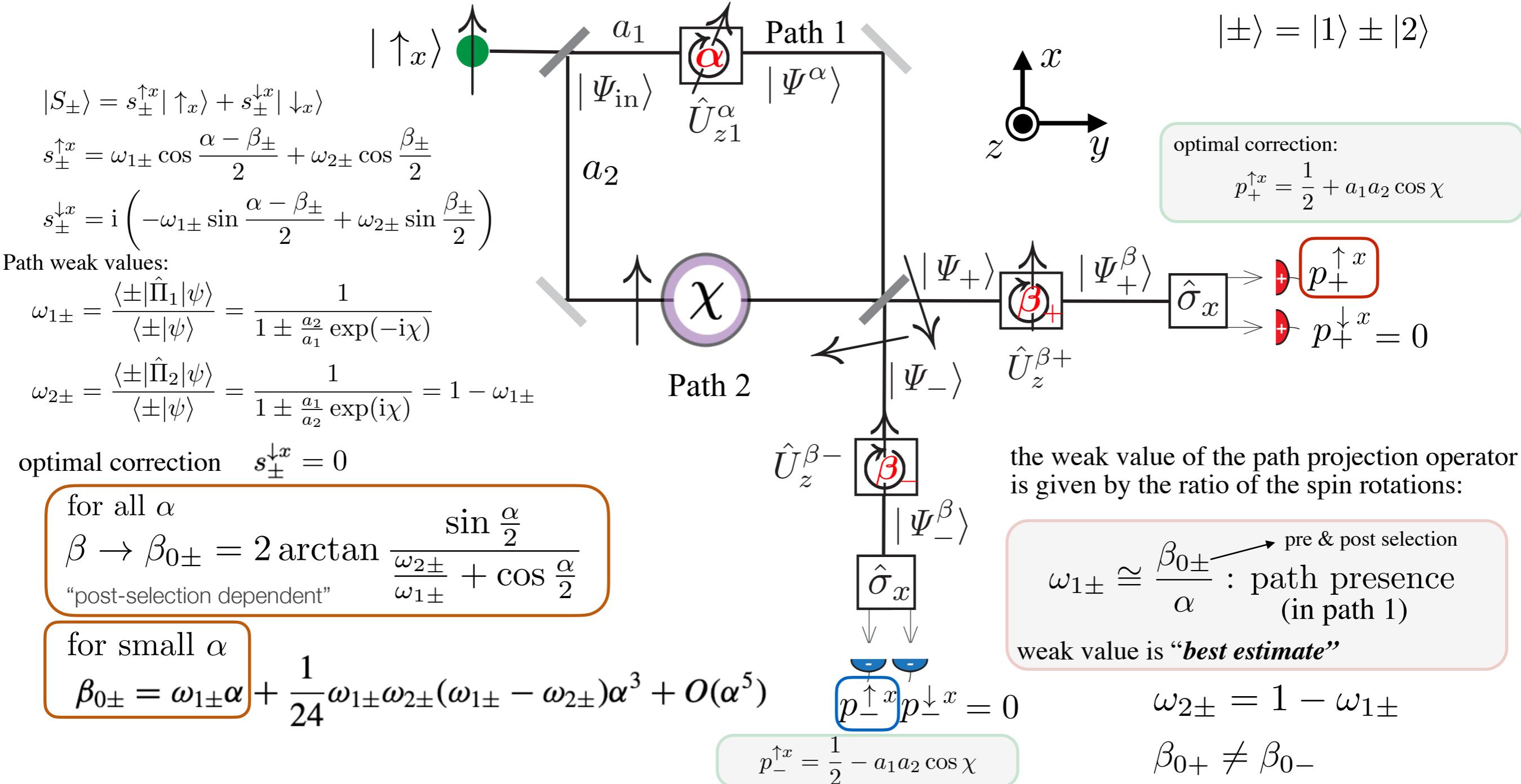
Interference VS Which-Way Measurements

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Interference VS Which-Way Measurements

$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$



Interference VS Which-Way Measurements

$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_z\rangle \quad |\Psi^{\text{out}}\rangle = \langle +|\psi\rangle |\pm\rangle |S_z\rangle$$



“Quantum -
Processing ”
Workflow

PHYSICAL REVIEW RESEARCH 3, L012011 (2021)

Letter

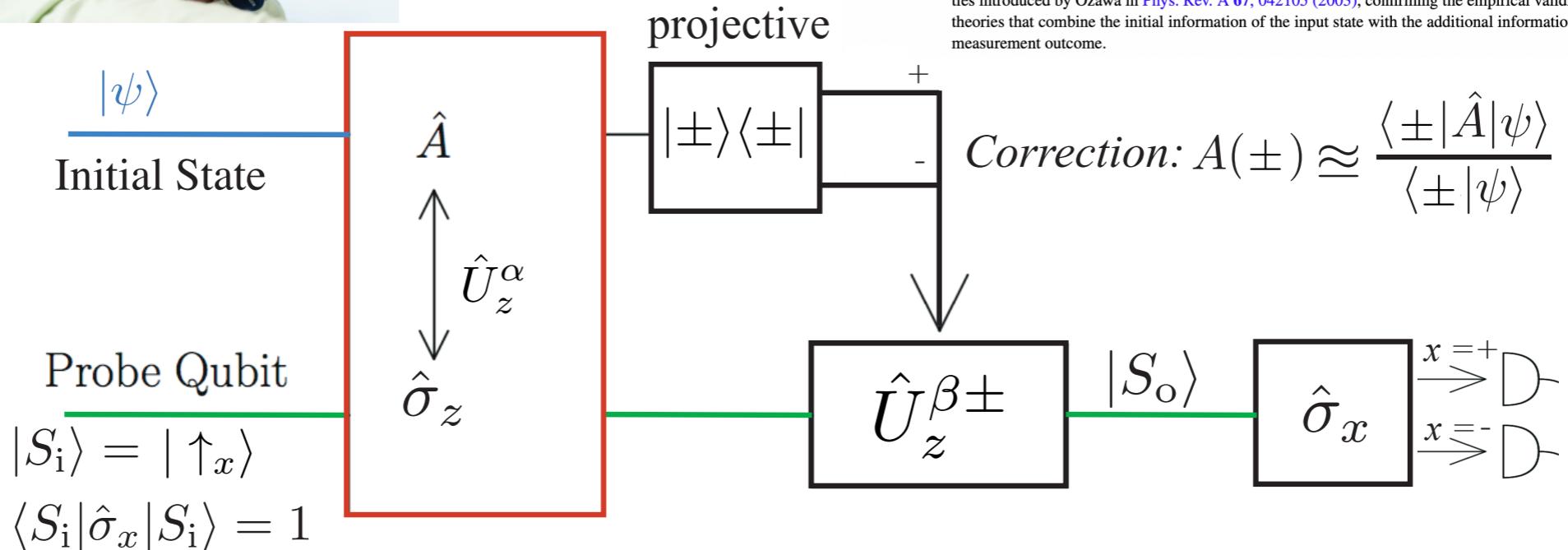
Direct evaluation of measurement uncertainties by feedback compensation of decoherence

Holger F. Hofmann*

Graduate School of Advanced Science and Engineering, Hiroshima University, Kagamiyama 1-3-1, Higashi Hiroshima 739-8530, Japan

(Received 23 June 2020; revised 15 November 2020; accepted 25 January 2021; published 3 February 2021)

It is shown that measurement uncertainties can be observed directly by evaluating the feedback compensation of the decoherence induced by the measured system on a probe qubit in a weak interaction occurring between state preparation and measurement. The uncompensated decoherence is described by the measurement uncertainties introduced by Ozawa in *Phys. Rev. A* **67**, 042105 (2003), confirming the empirical validity of measurement theories that combine the initial information of the input state with the additional information provided by each measurement outcome.



H. F. Hofmann, *Phys. Rev. Research* **3**, L012011 (2021)

$$|S_\pm\rangle = s_\pm^{\uparrow x} |\uparrow_x\rangle + s_\pm^{\downarrow x} |\downarrow_x\rangle$$

$$s_\pm^{\uparrow x} = \omega_{1\pm} \cos \frac{\alpha}{2}$$

$$s_\pm^{\downarrow x} = i \left(-\omega_{1\pm} \sin \frac{\alpha}{2} \right)$$

weak values:

$$\omega_{1\pm} = \frac{\langle \pm | \hat{\Pi}_1 | \psi \rangle}{\langle \pm | \psi \rangle}$$

$$\omega_{2\pm} = \frac{\langle \pm | \hat{\Pi}_2 | \psi \rangle}{\langle \pm | \psi \rangle}$$

optimal correction

for all α
 $\beta \rightarrow \beta_{0\pm}$
 “post-selection”

for small α

$$\beta_{0\pm} = \omega_{1\pm}\alpha + \frac{1}{24}\omega_{1\pm}\omega_{2\pm}(\omega_{1\pm} - \omega_{2\pm})\alpha^2 + O(\alpha^3)$$

$$p_-^{\uparrow x} p_-^{\downarrow x} = 0$$

$$\omega_{2\pm} = 1 - \omega_{1\pm}$$

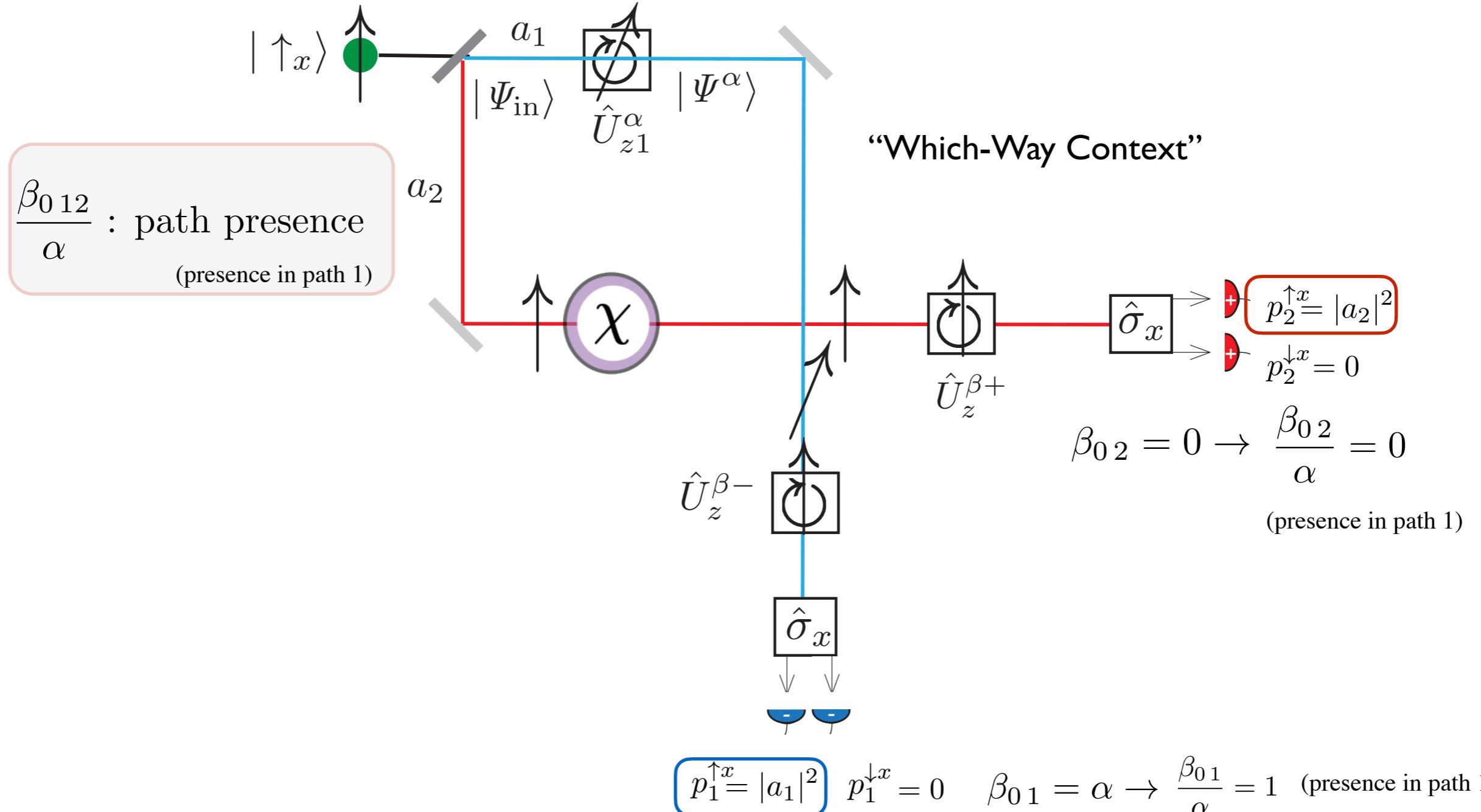
$$p_-^{\uparrow x} = \frac{1}{2} - a_1 a_2 \cos \chi$$

$$\beta_{0+} \neq \beta_{0-}$$

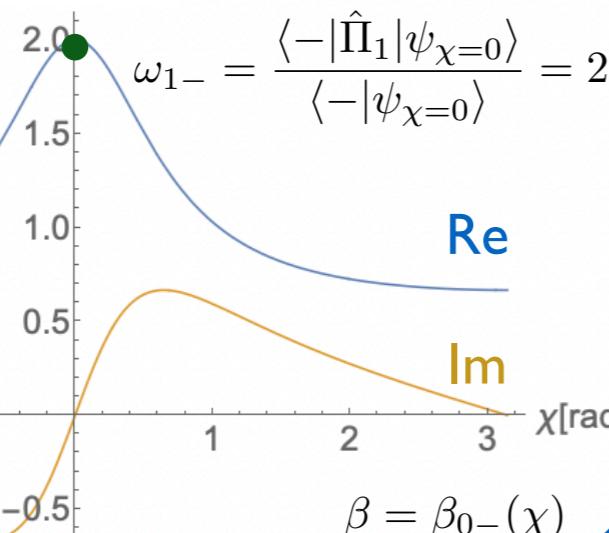
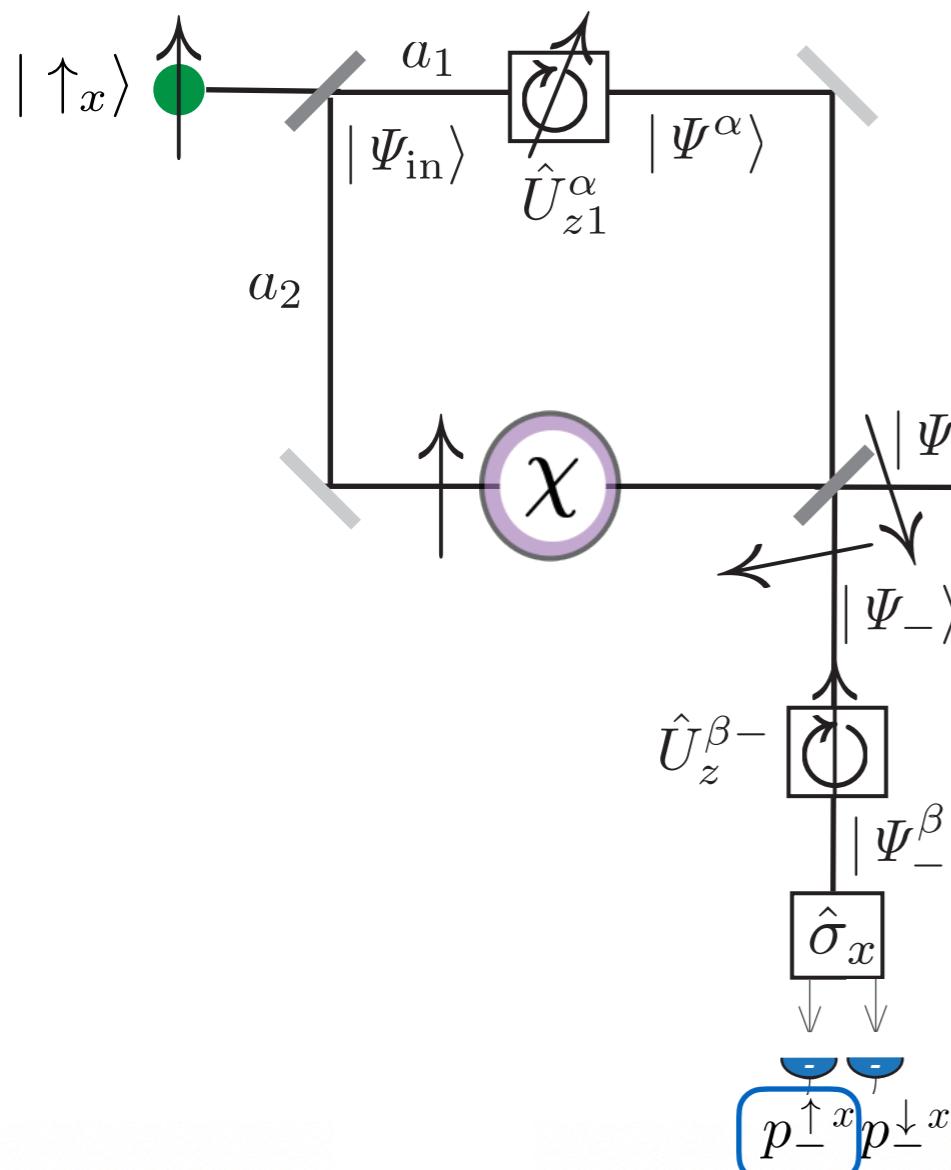
H. Lemmel, N. Geerits, A. Danner, H. F. Hofmann, and S. Sponar, *Physical Review Research* **4**, 023075 (2022)

Interference VS Which-Way Measurements

$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$

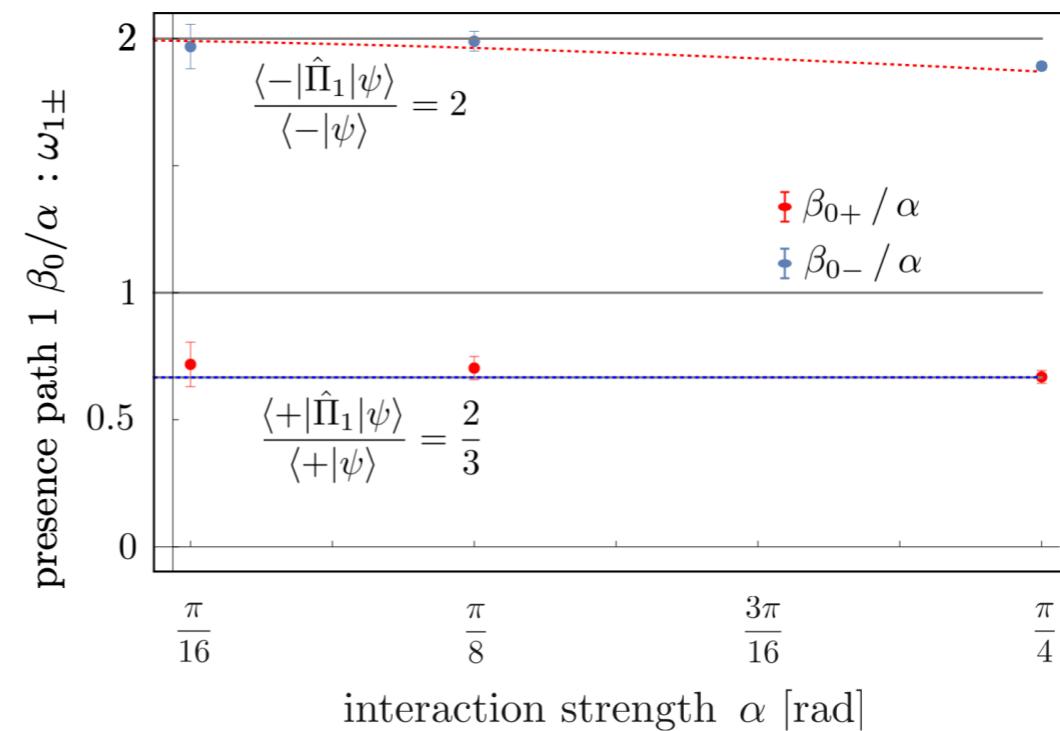
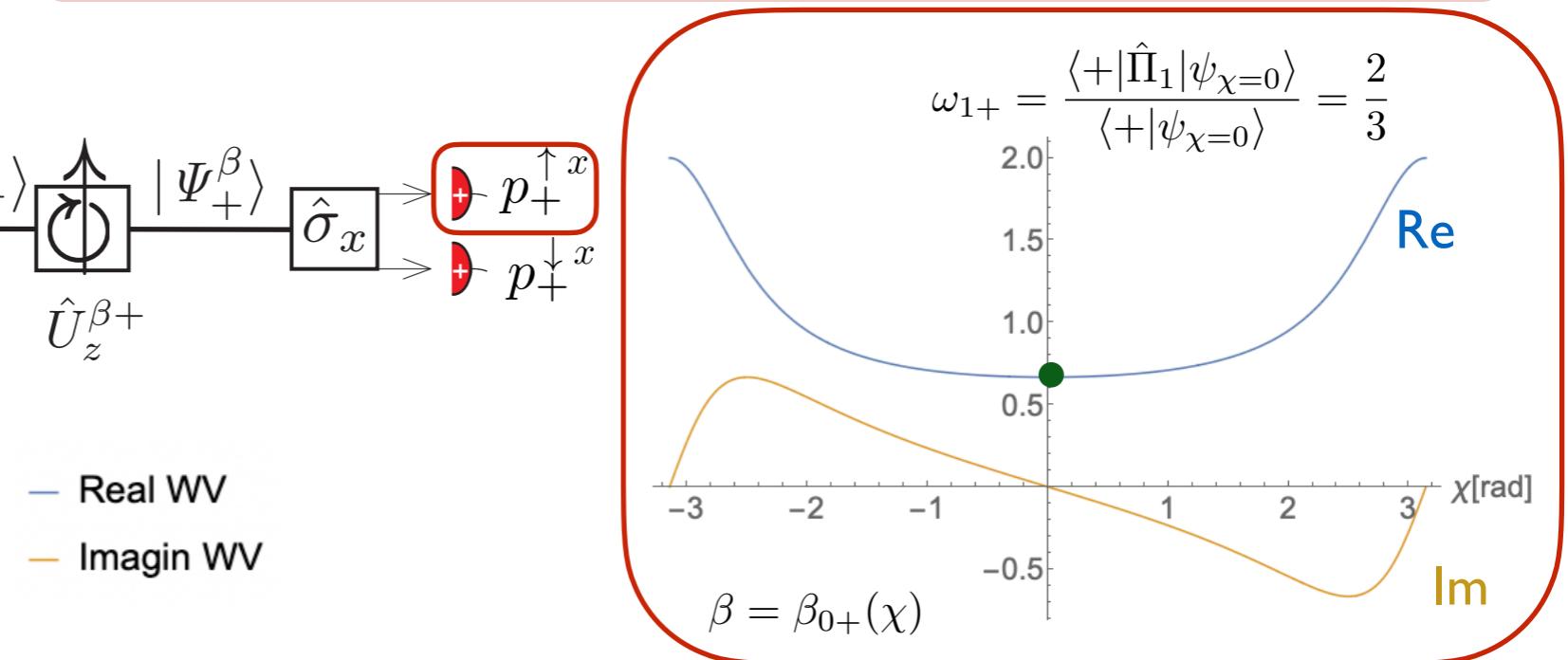


We have already measured ...



$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle$$

$$\rightarrow a_1 = \frac{2}{\sqrt{5}}, a_2 = \frac{1}{\sqrt{5}}$$

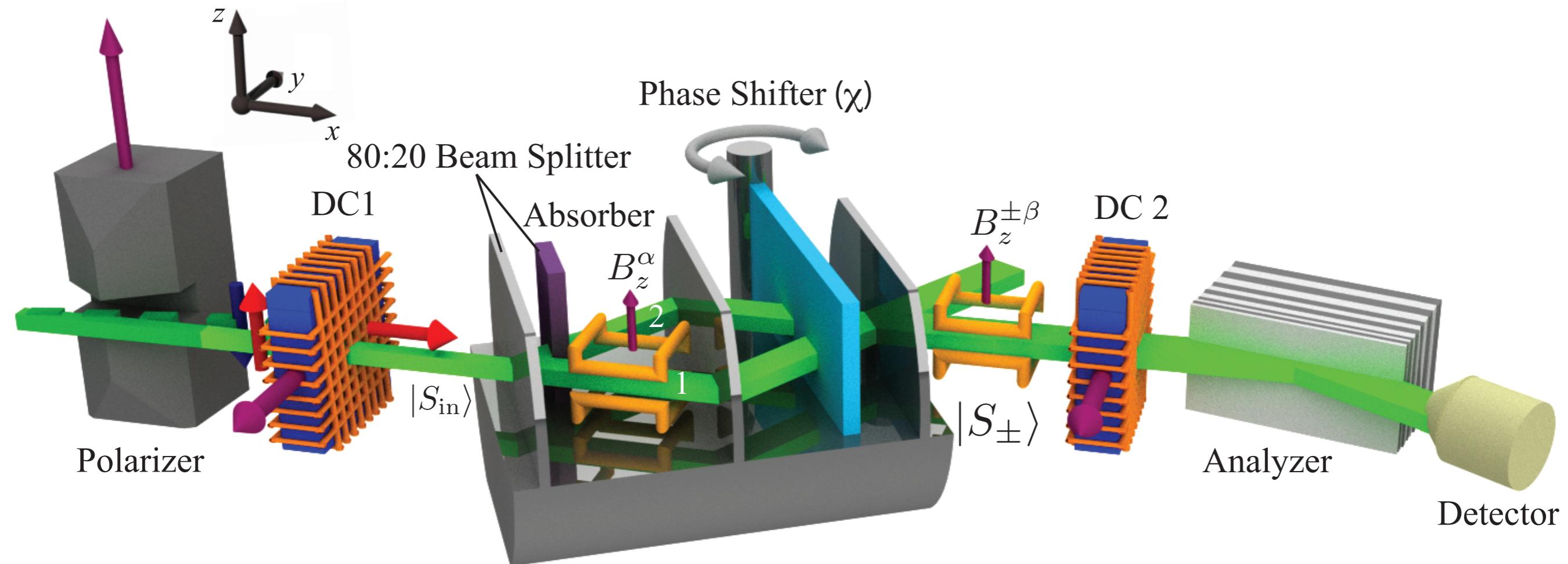


$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle := (a_1|1\rangle + a_2|2\rangle)|\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$

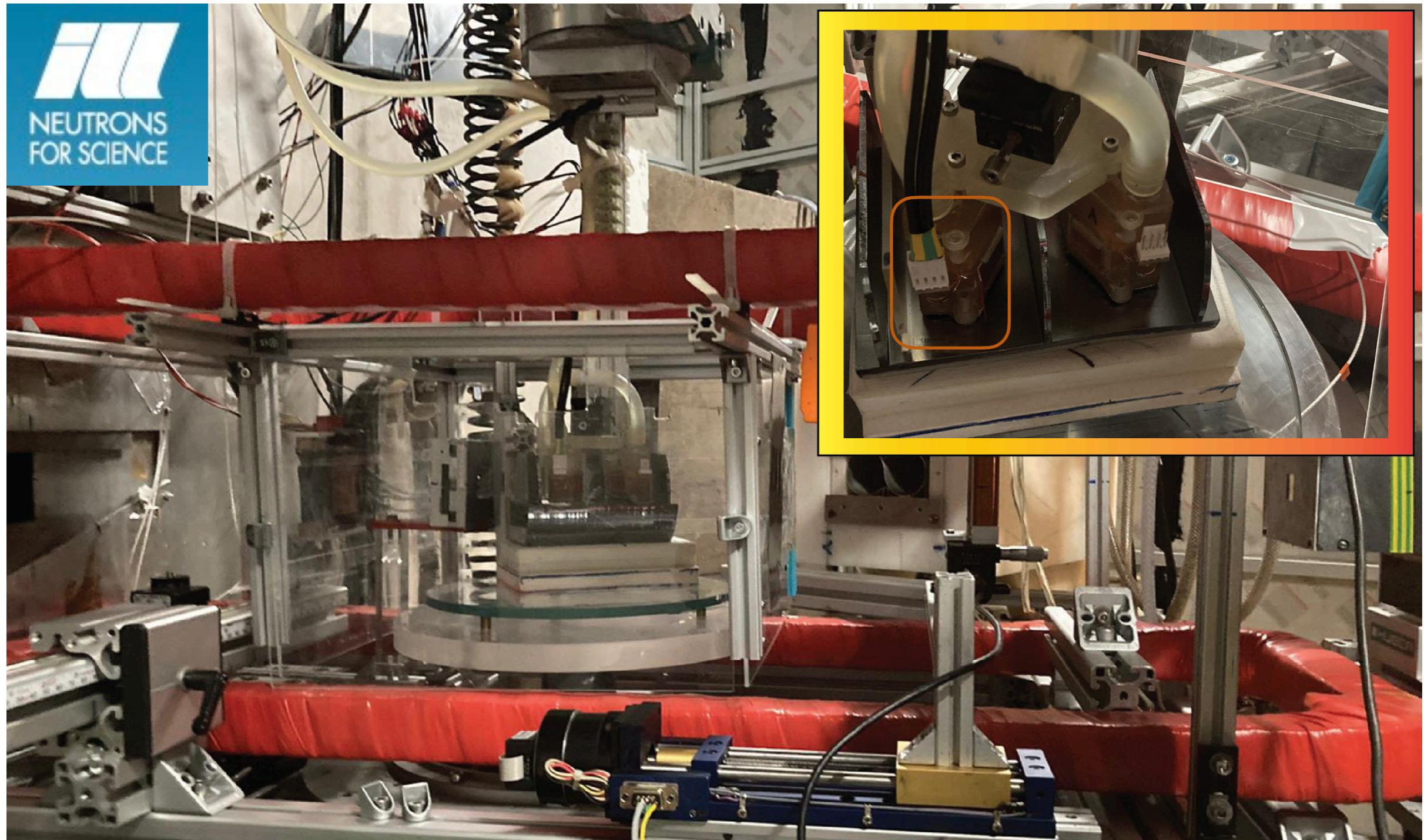
$$\rightarrow a_1 = \frac{2}{\sqrt{5}}, a_2 = \frac{1}{\sqrt{5}}$$

$$|\pm\rangle = |1\rangle + e^{i\chi_{\pm}}|2\rangle$$

$$\chi_+ = 0, \chi_- = \pi$$



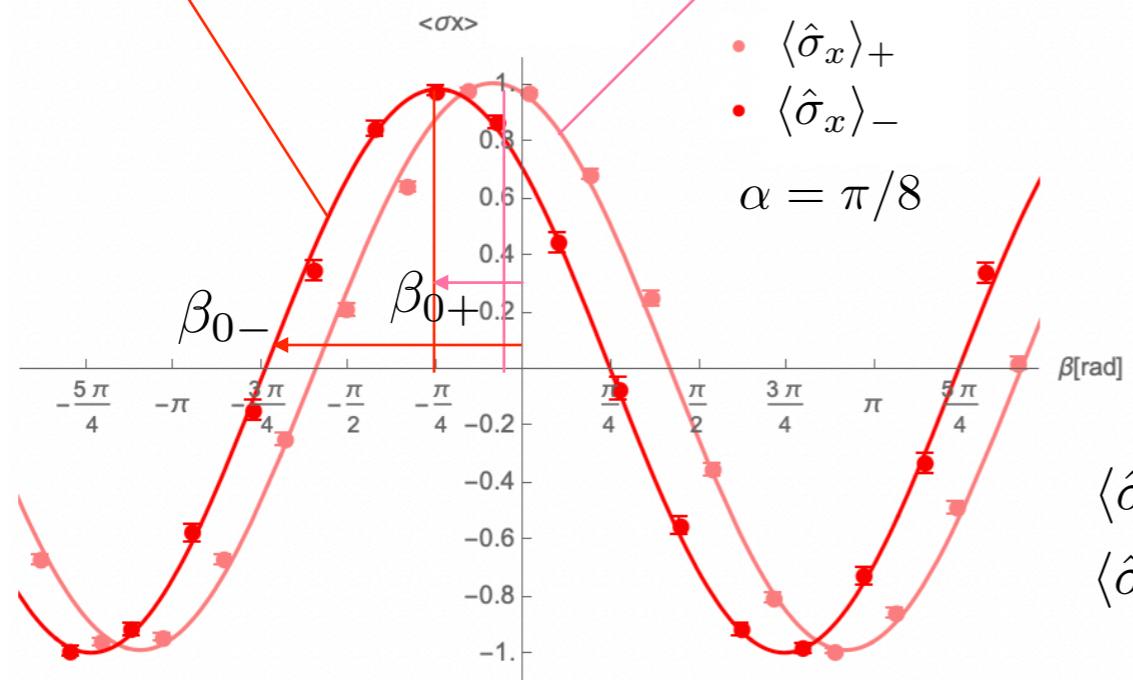
Experimental Setup @ S18, ILL Grenoble



H. Lemmel, N. Geerits, A. Danner, H. F. Hofmann, and S. Sponar, *Physical Review Research* **4**, 023075 (2022)

Additional Notes on Ozawa-Hall Error: i) Values of Errors

$$\langle \hat{\sigma}_x \rangle_- = \frac{I_{\chi=\pi}^{\uparrow x} - I_{\chi=\pi}^{\downarrow x}}{I_{\chi=\pi}^{\uparrow x} + I_{\chi=\pi}^{\downarrow x}} \cdot C_{\text{Corr}} \quad \langle \hat{\sigma}_x \rangle_+ = \frac{I_{\chi=0}^{\uparrow x} - I_{\chi=0}^{\downarrow x}}{I_{\chi=0}^{\uparrow x} + I_{\chi=0}^{\downarrow x}} \cdot C_{\text{Corr}}$$



$$\begin{aligned}\langle \hat{\sigma}_x \rangle_+ &= \cos(\beta_+ - \omega_{1+} \alpha) \\ \langle \hat{\sigma}_x \rangle_- &= \cos(\beta_- - \omega_{1-} \alpha)\end{aligned}$$

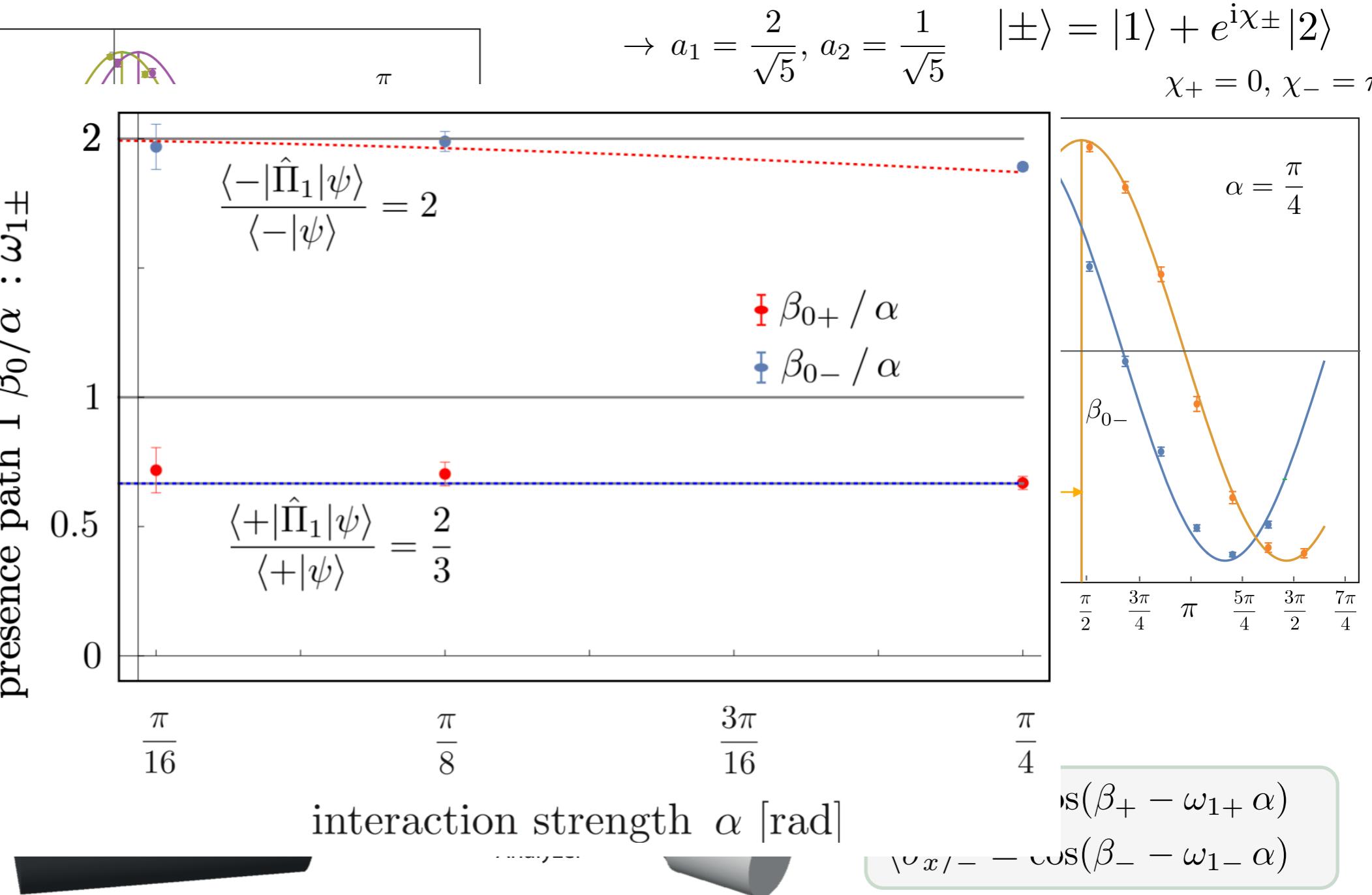
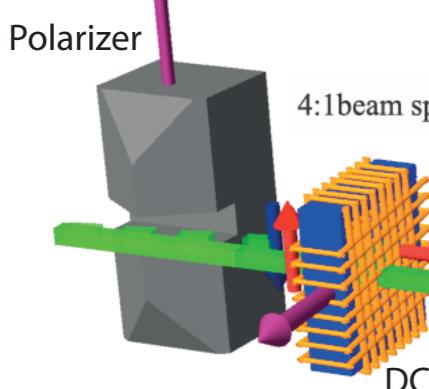
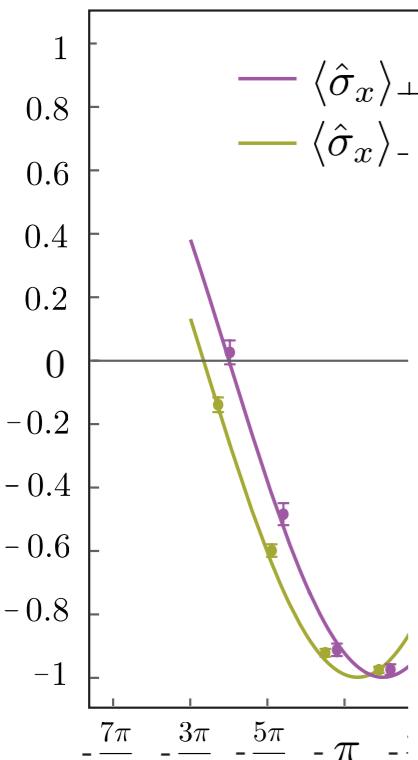
best estimates(@ $\alpha = \pi/8$) :

$$\frac{\beta_{0+}}{\alpha} = 0.703(45) \quad [\text{Theory: 2/3}]$$

$$\frac{\beta_{0-}}{\alpha} = 1.989(38) \quad [\text{Theory: 2}]$$

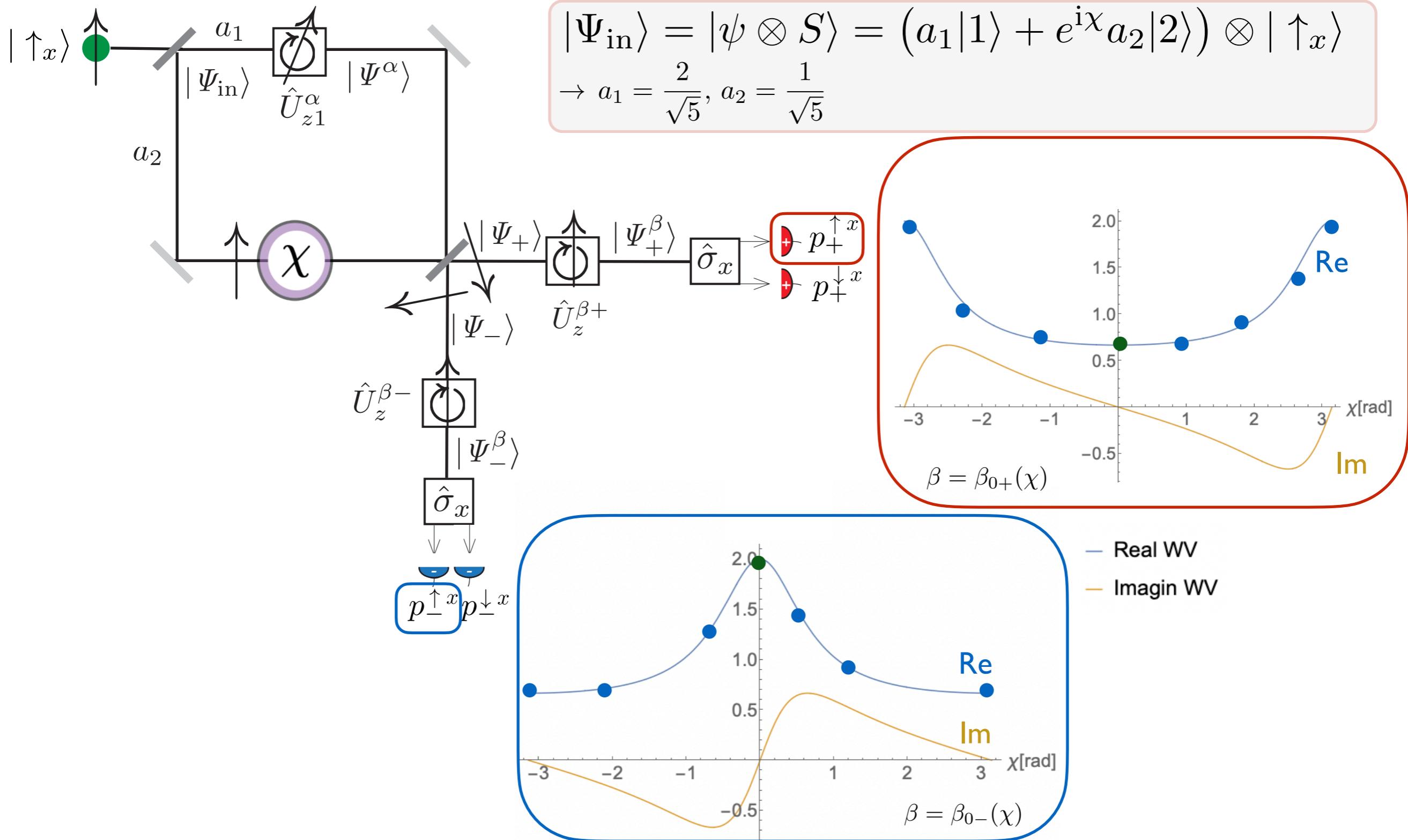
Interference Measurements

$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + a_2|2\rangle) \otimes |\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$

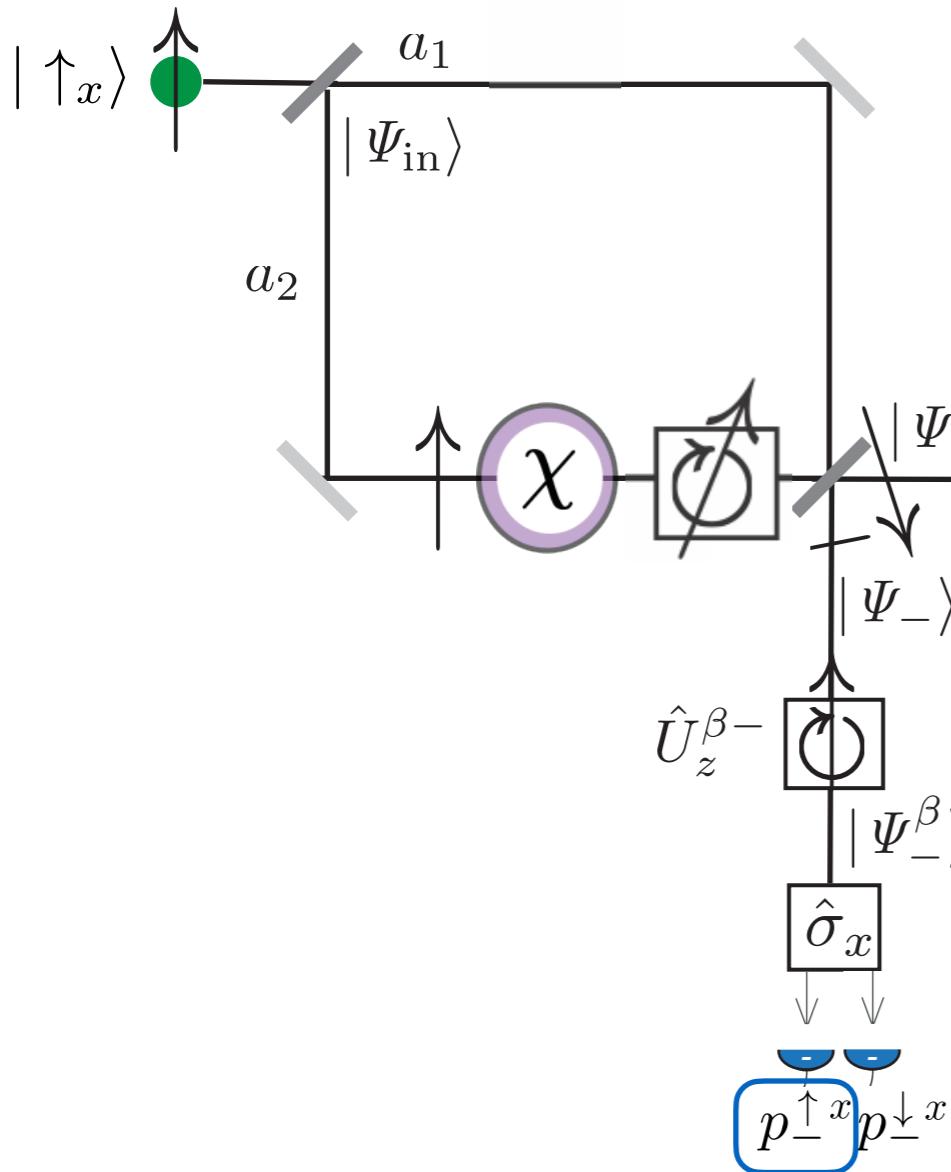


H. Lemmel, N. Geerits, A. Danner, H. F. Hofmann, and S. Sponar, *Physical Review Research* **4**, 023075 (2022)

We shall measure ...

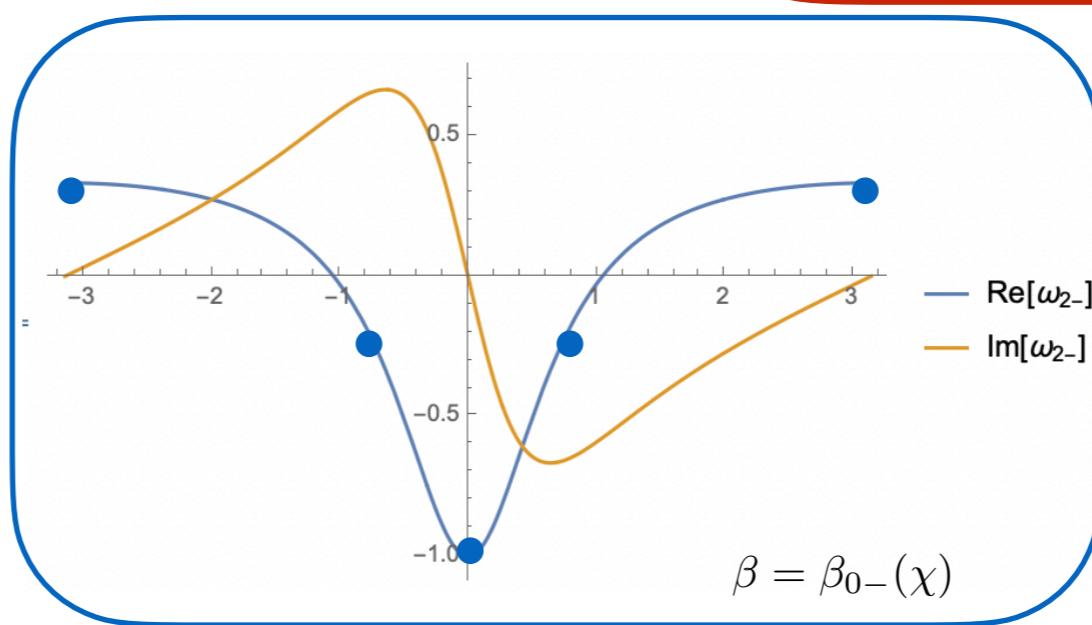
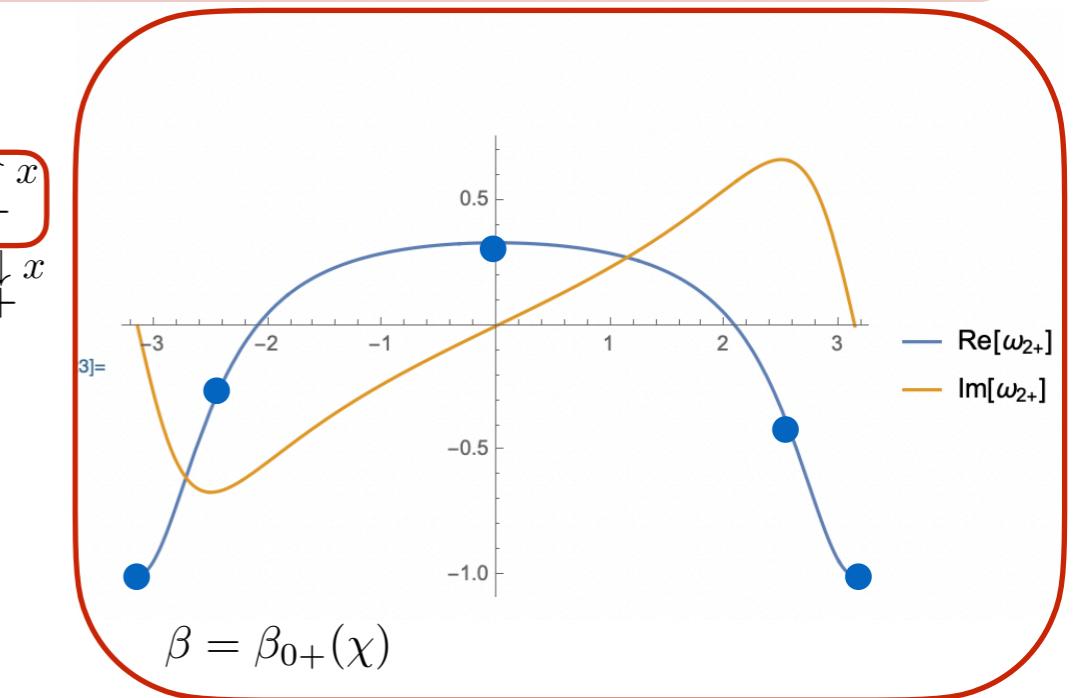


Additional Notes on Ozawa-Hall Error iii) Variation of initial state



$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle$$

$$\rightarrow a_1 = \frac{2}{\sqrt{5}}, a_2 = \frac{1}{\sqrt{5}}$$

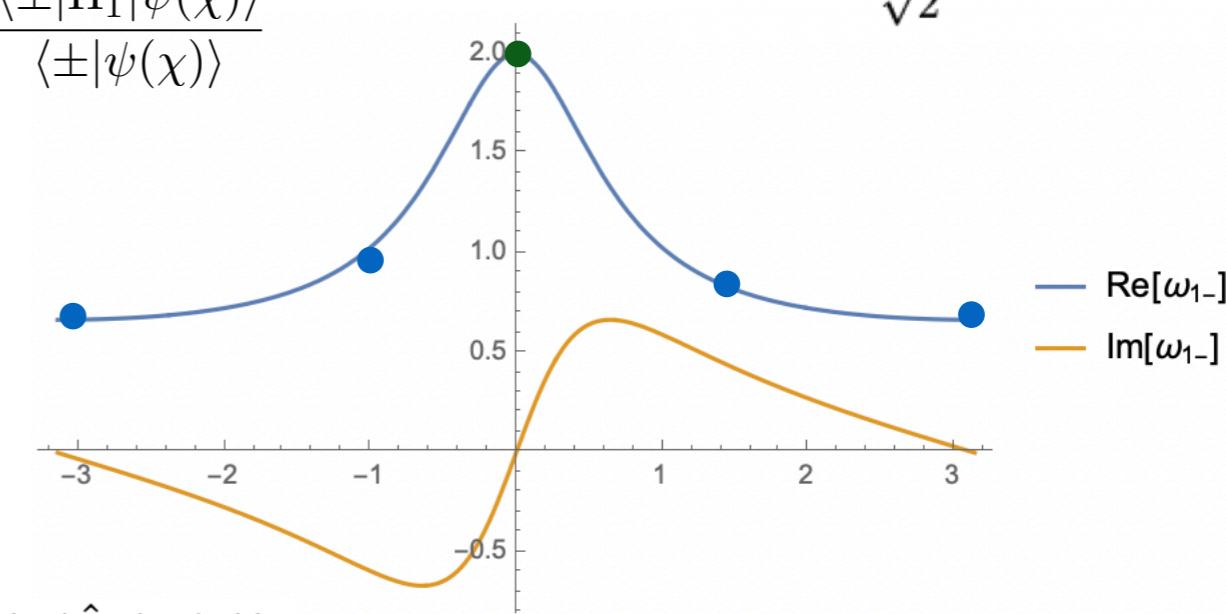
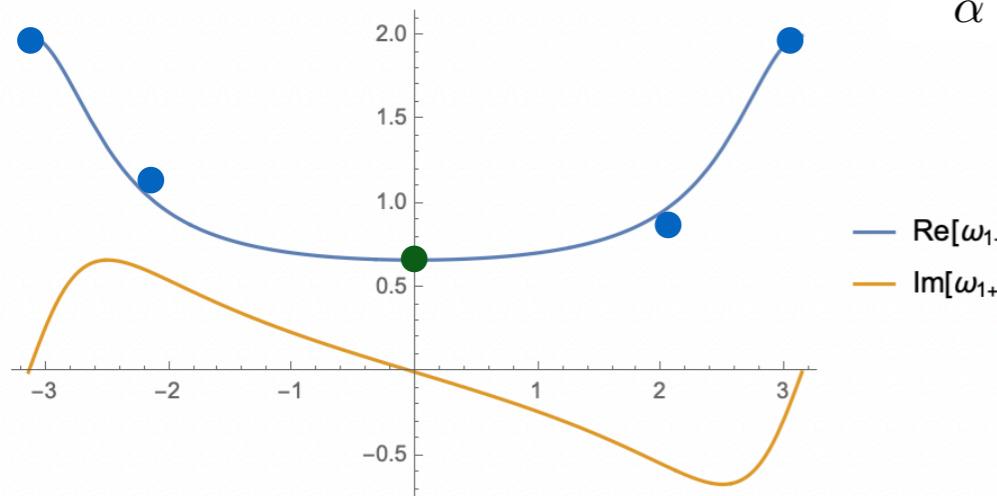


Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

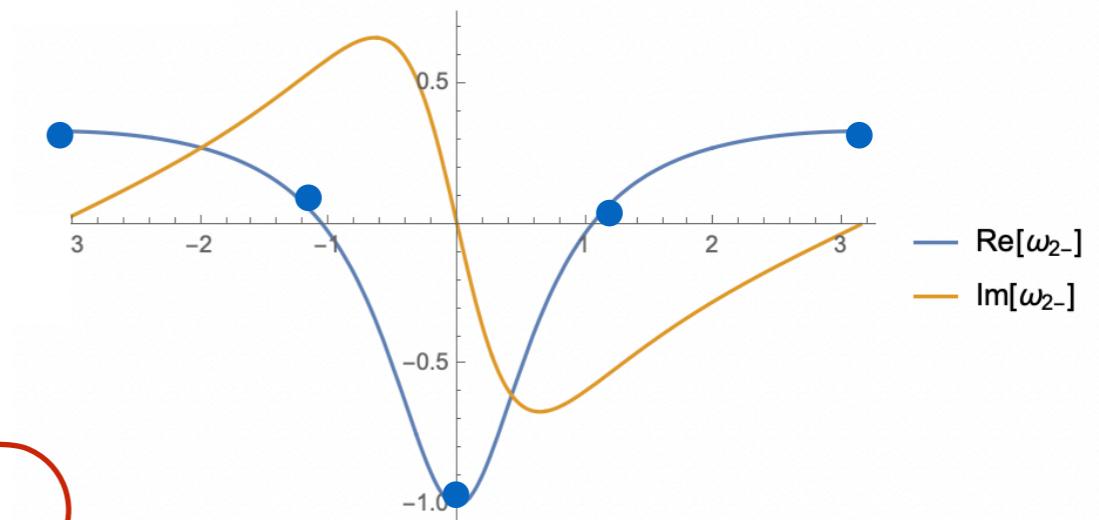
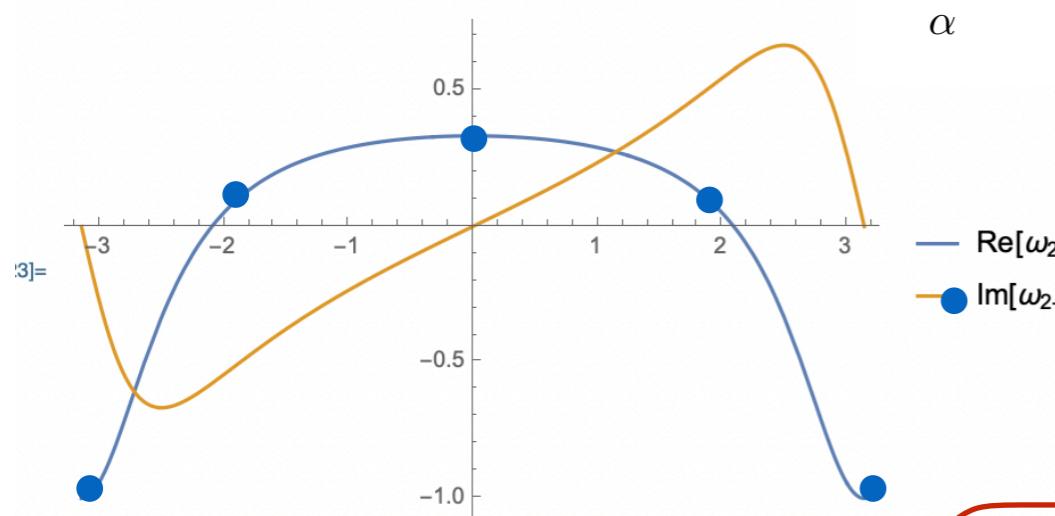
● path presence for

$$|\psi\rangle := |\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle$$

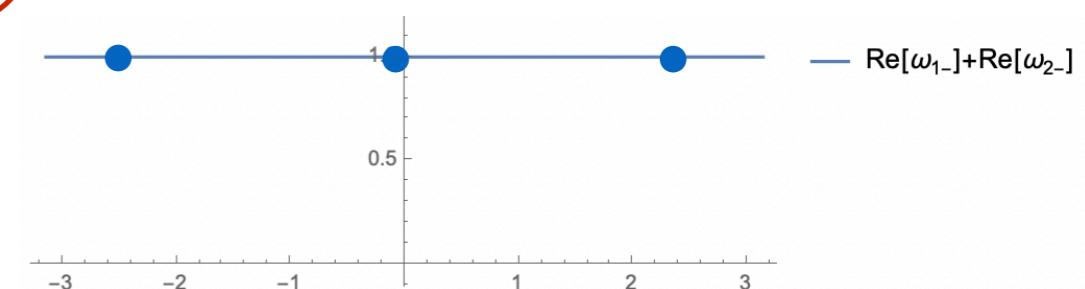
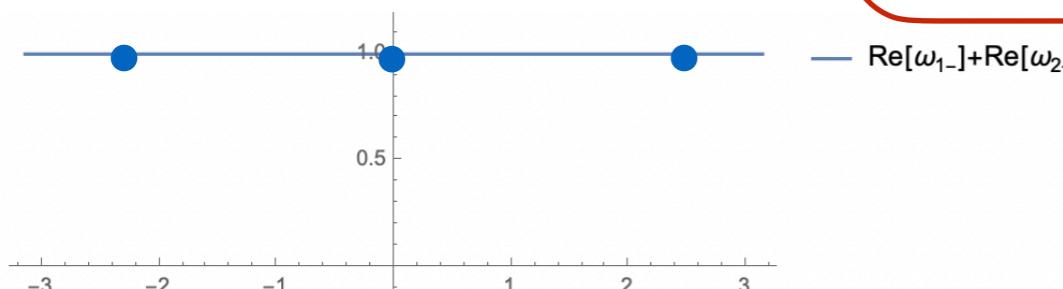
$$\frac{\beta_{0\pm}^{(1)}(\chi)}{\alpha} = \omega_{1\pm}(\chi) \cong \Re \frac{\langle \pm | \hat{\Pi}_1 | \psi(\chi) \rangle}{\langle \pm | \psi(\chi) \rangle}$$



$$\frac{\beta_{0\pm}^{(2)}(\chi)}{\alpha} = \omega_{2\pm}(\chi) \cong \Re \frac{\langle \pm | \hat{\Pi}_2 | \psi(\chi) \rangle}{\langle \pm | \psi(\chi) \rangle}$$



$$\omega_{1\pm} + \omega_{2\pm} = 1$$



PHYSICAL REVIEW A **67**, 042105 (2003)

Universally valid reformulation of the Heisenberg uncertainty principle on noise and disturbance in measurement



Masanao Ozawa

Graduate School of Information Sciences, Tôhoku University, Aoba-ku, Sendai, 980-8579, Japan

(Received 9 October 2002; published 11 April 2003)

The Heisenberg uncertainty principle states that the product of the noise in a position measurement and the momentum disturbance caused by that measurement should be no less than the limit set by Planck's constant $\hbar/2$ as demonstrated by Heisenberg's thought experiment using a γ -ray microscope. Here it is shown that this common assumption is not universally true: a universally valid trade-off relation between the noise and the disturbance has an additional correlation term, which is redundant when the intervention brought by the measurement is independent of the measured object, but which allows the noise-disturbance product much

Measurement Uncertainty:

$$\epsilon(A)\eta(B) + \epsilon(A)\Delta B + \eta(B)\Delta A \geq \frac{1}{2} |\langle \psi | [A, B] | \psi \rangle|$$

- Definitions of ERROR $\epsilon(A)$ & DISTURBANCE $\eta(B)$

describing accuracy of quantum measuring process

effect on another measurement incompatible (non-commuting) observable

Ozawa's **operator-based** Definitions of Error & Disturbance

Indirect Measurement Model:

$\hat{A}, \hat{B}, |\psi\rangle \in \mathcal{H}$, Hilbert space of *object* system
 $\hat{M}_A, |\xi\rangle \in \mathcal{K}$, Hilbert space of *probe* system

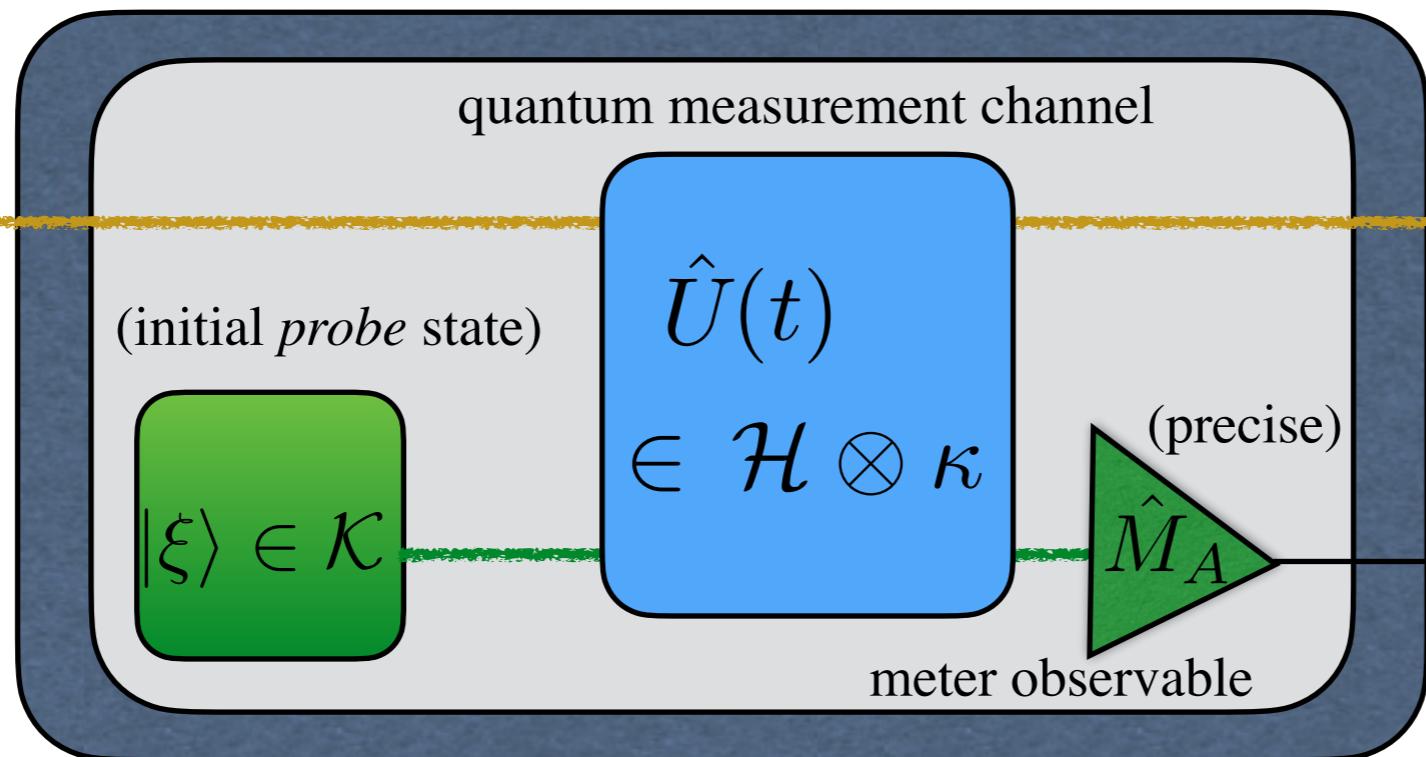
$$\varepsilon(\hat{A}) = \langle \psi \otimes \xi | (\hat{U}(t)^\dagger (I \otimes \hat{M}_A) \hat{U}(t) - \hat{A} \otimes I)^2 |\xi \otimes \psi \rangle^{1/2}$$

quantum input

$|\psi\rangle \in \mathcal{H}$

(initial *object* state)

quantum measurement channel



quantum output

$X(|\psi\rangle)$

$X(\hat{A})$ with error $\varepsilon(\hat{A})$

classical output

(Pointer)

approximate \hat{A} - measurement

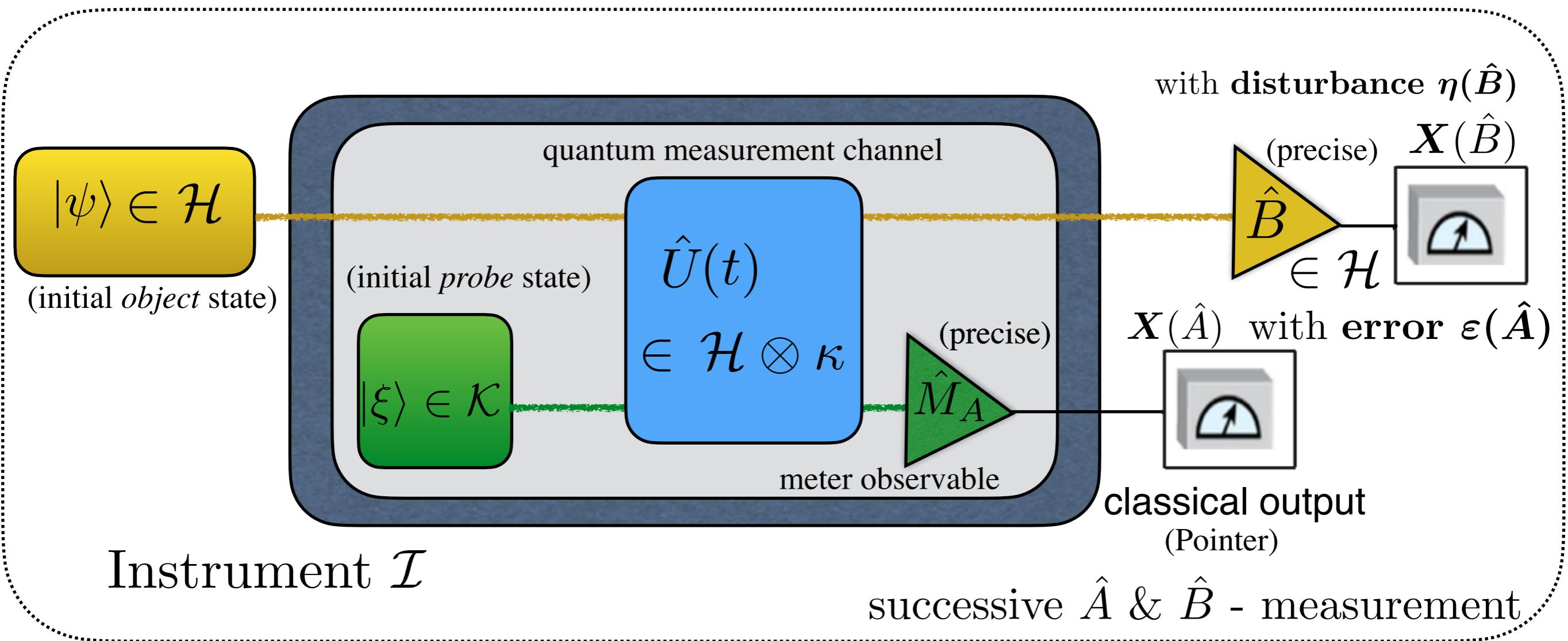
— quantum channel — classical channel

Instrument \mathcal{I}

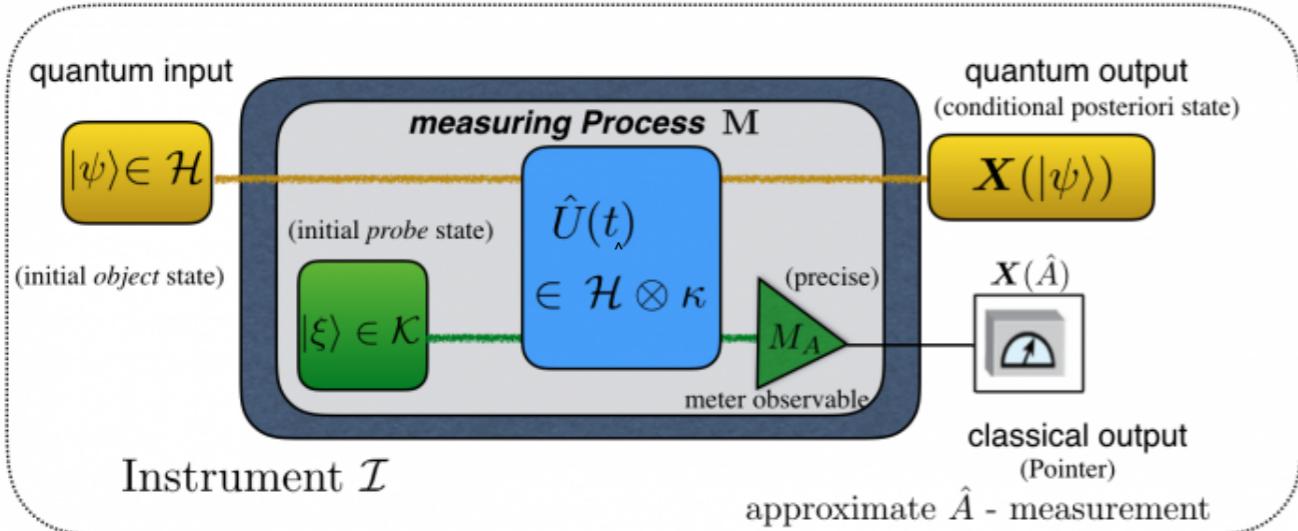
Ozawa's **operator-based** Definitions of Error & Disturbance

Indirect Measurement Model:

$\hat{A}, \hat{B}, |\psi\rangle \in \mathcal{H}$, Hilbert space of *object* system
 $\hat{M}_A, |\xi\rangle \in \mathcal{K}$, Hilbert space of *probe* system



Ozawa Error



$$\varepsilon(\hat{A}) = \langle \psi \otimes \xi | (\hat{U}(t)^\dagger (I \otimes \hat{M}_A) \hat{U}(t) - \hat{A} \otimes I)^2 | \xi \otimes \psi \rangle^{1/2}$$

family of projection **operators**: $\{\hat{O}_\lambda\}$

$$\hat{O}_\lambda = \hat{O}_\lambda^\dagger \hat{O}_\lambda = \langle \xi | \hat{U}^\dagger(t) \hat{P}_\lambda^M \hat{U}(t) | \xi \rangle$$

POVM

$$\epsilon^2(A) = \sum_\lambda ||O_\lambda(\lambda - A)|\psi\rangle||^2$$

local proj. meas:

- $\hat{P}_\lambda^M = (\hat{I} \otimes \underbrace{\sum_\lambda \lambda |\lambda\rangle\langle\lambda|}_{\hat{M}_A})$

acting on object-space \mathcal{H}^{obj} (U on $\mathcal{H}^{\text{obj}} \otimes \mathcal{H}^{\text{app}}$)

$$||...|| = ||X|\psi\rangle|| = \langle \psi | X^\dagger X | \psi \rangle^{\frac{1}{2}}$$

If the O_λ are mutually orthogonal **projection operators** sum and norm can be exchanged

$$\epsilon^2(A) = \left\| \left(\sum_\lambda \lambda O_\lambda - A \right) |\psi\rangle \right\|^2$$

output operator: $O_A = \sum_\lambda \lambda O_\lambda$
“Approximator of operator A”

$$\epsilon(A) = \|(O_A - A)|\psi\rangle\| \leftrightarrow \epsilon(A) = \sqrt{\langle \psi | (O_A - A)^2 | \psi \rangle}$$

M. Ozawa, *Phys. Rev. A* **67**, 042105 (2003).

Error and Disturbance for Spin 1/2 Measurements

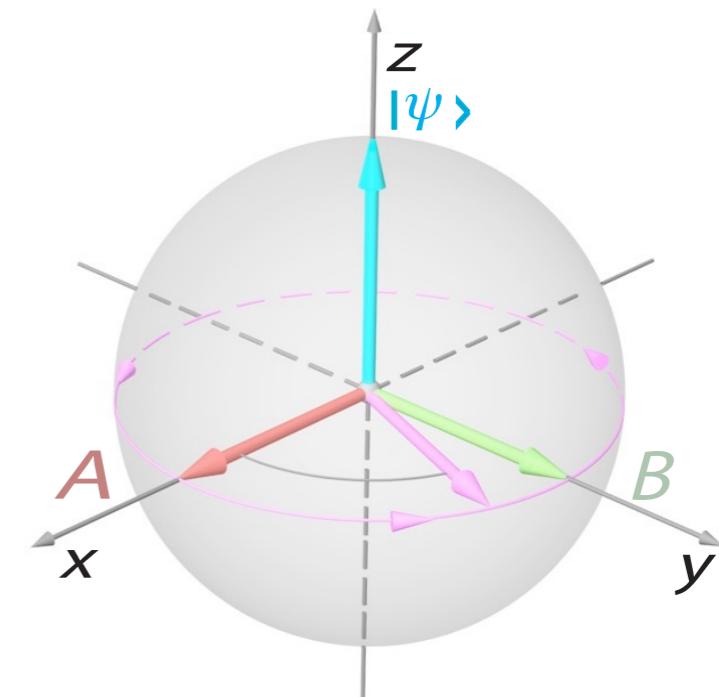
- set of observables and initial state

$$A = \sigma_x$$

$$B = \sigma_y$$

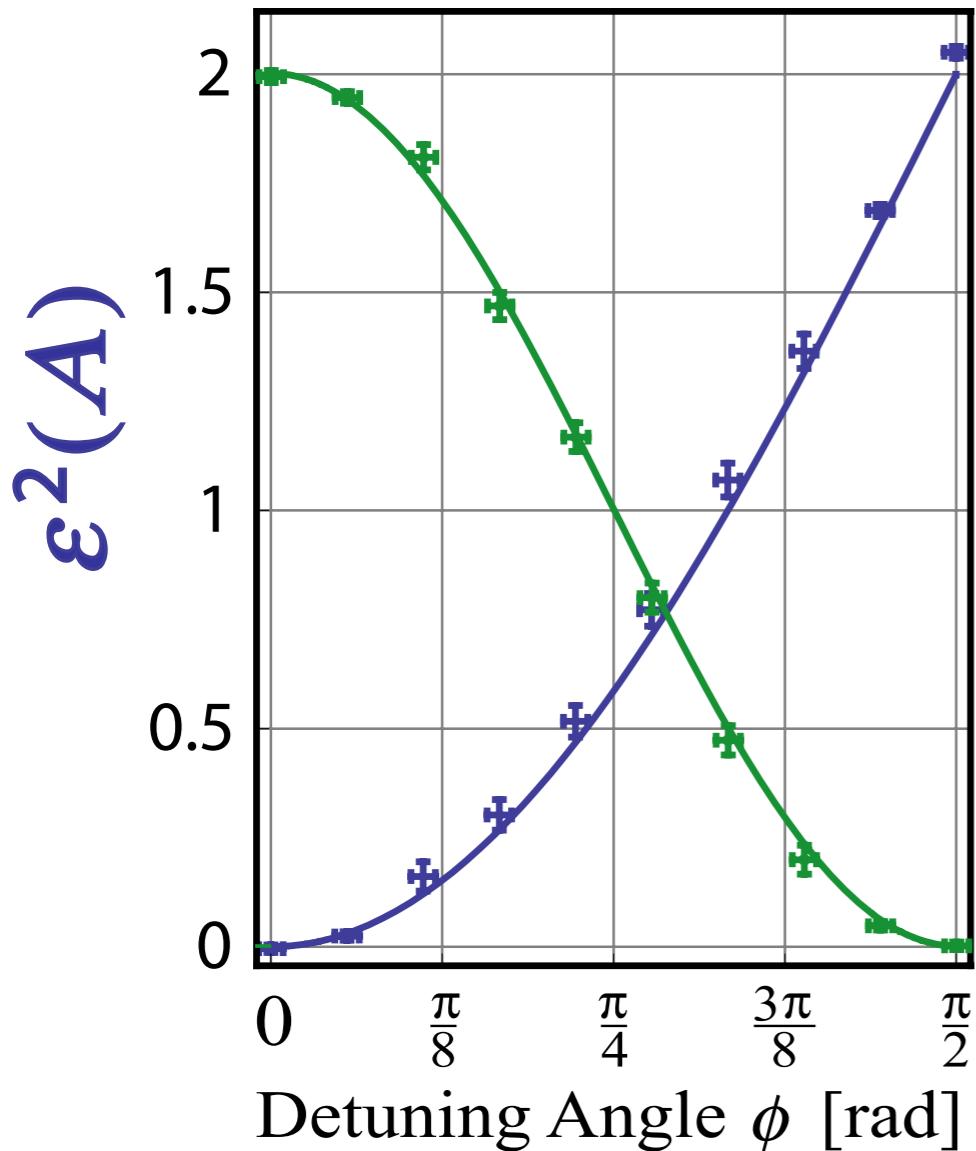
$$O_A = \sigma_\phi = \sigma_x \sin \phi + \sigma_y \cos \phi$$

$$|\psi\rangle = |+z\rangle$$



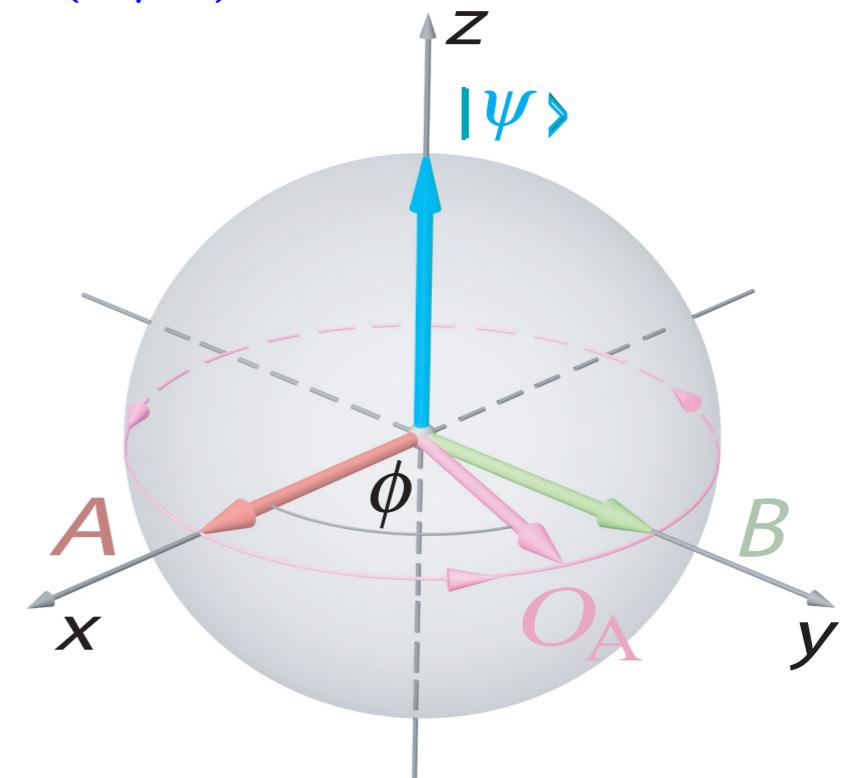
First Experimental Results of Ozawa's Error and Disturbance

● error, disturbance: trade - off



$$\epsilon(A) = \sqrt{\langle \psi | (O_A - A)^2 | \psi \rangle}$$

$$\epsilon(A)^2 = 4 \sin^2(\phi/2)$$



$$\eta(B)^2 = 2 \cos^2 \phi$$

nature
physics

LETTERS

PUBLISHED ONLINE: 15 JANUARY 2012 | DOI:10.1038/NPHYS2194

Jacqueline Erhart¹, Stephan Sponar¹, Georg Sulyok¹, Gerald Badurek¹, Masanao Ozawa²
and Yuji Hasegawa^{1*} NATURE PHYSICS VOL 8, 185, MARCH 2012.

Ozawa Error

$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + a_2|2\rangle) \otimes |\uparrow_x\rangle \quad |\Psi_{\pm}^{\text{out}}\rangle = \langle \pm|\psi\rangle |\pm\rangle |S_{\pm}\rangle$$

$$\epsilon(A) = \sqrt{\langle\psi|(O_A - A)^2|\psi\rangle}$$

$$\frac{A}{\varepsilon^2(\hat{\Pi}_1)} = \langle\psi| \left(\sum_{\pm} \frac{\beta_{\pm}}{\alpha} |\pm\rangle\langle\pm| - \hat{\Pi}_1 \right)^2 |\psi\rangle$$

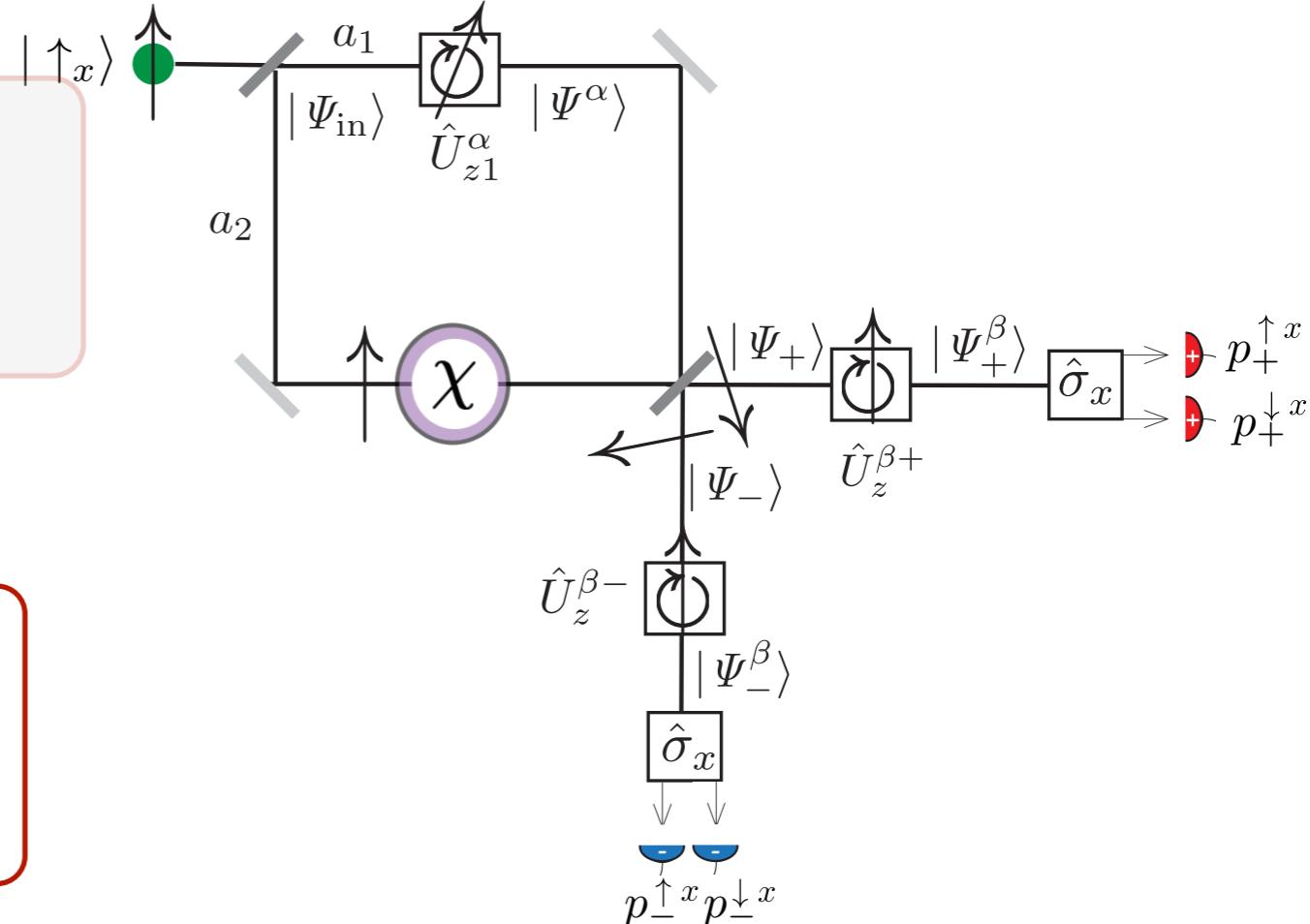
$$\varepsilon^2(\hat{\Pi}_1) = \sum_{\pm} \langle\psi| \left(\hat{\Pi}_1^{\dagger} - \frac{\beta_{\pm}}{\alpha} \right) |\pm\rangle\langle\pm| \left(\hat{\Pi}_1 - \frac{\beta_{\pm}}{\alpha} \right) |\psi\rangle$$

$$= \sum_{\pm} [p_{\pm}] \left| \langle \hat{\Pi}_1 \rangle_{\text{w}}^{\pm, \psi(\chi)} - \frac{\beta_{\pm}}{\alpha} \right|^2$$

exp. data

$$p_{\pm} = |\langle \pm | \psi \rangle|^2 = \frac{1}{2} \pm a_1 a_2 \cos \chi$$

$$\langle \hat{\Pi}_1 \rangle_{\text{w}}^{\pm, \psi(\chi)} = \frac{\langle \pm | \hat{\Pi}_1 | \psi(\chi) \rangle}{\langle \pm | \psi(\chi) \rangle}$$



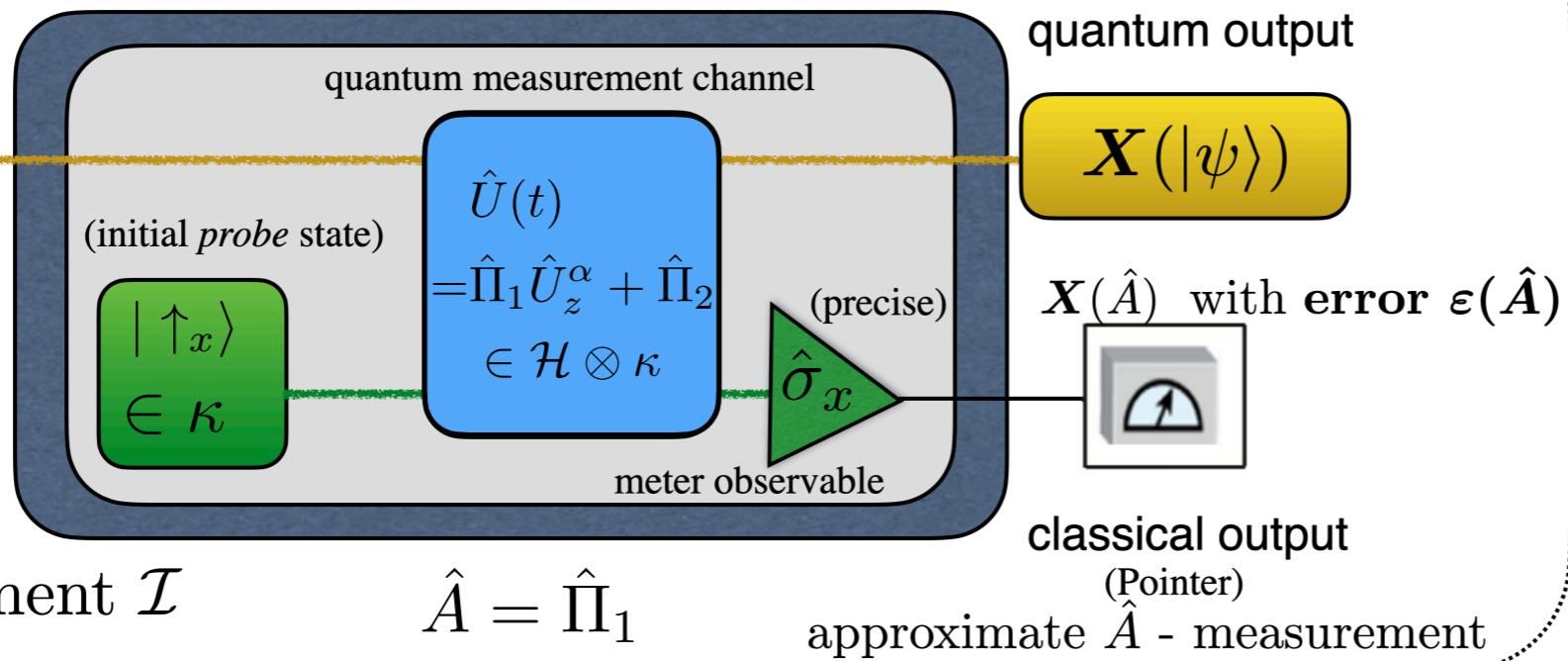
Ozawa's **operator-based** Definitions of Error & Disturbance

$$\varepsilon(\hat{A}) = \langle \psi \otimes \xi | (\hat{U}(t)^\dagger (I \otimes \hat{M}_A) \hat{U}(t) - \hat{A} \otimes I)^2 | \xi \otimes \psi \rangle^{1/2}$$

quantum input

$$|\psi(\chi)\rangle \in \mathcal{H}$$

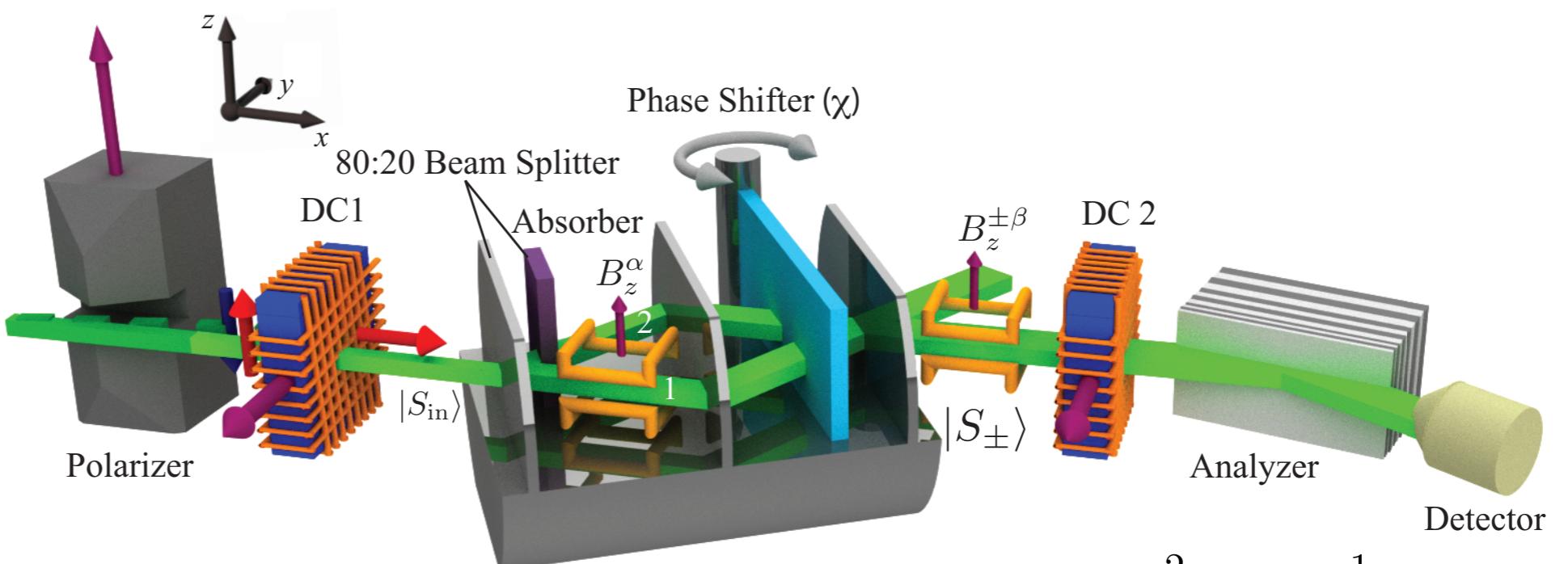
(initial object state)



Instrument \mathcal{I}

$$\hat{A} = \hat{\Pi}_1$$

approximate \hat{A} - measurement



$$|\Psi_{in}\rangle = |\psi(\chi) \otimes S\rangle = (a_1|1\rangle + a_2|2\rangle)|\uparrow_x\rangle \rightarrow a_1 = \frac{2}{\sqrt{5}}, a_2 = \frac{1}{\sqrt{5}}$$

Additional Notes on Ozawa-Hall Error: i) Values of Errors

The same conclusion can be drawn using the Ozawa-Hall theory. Ozawa [12] introduced a general concept of measurement errors and it was shown by Hall that these errors correspond to the uncertainty of an estimate of a physical property based on the outcome of an arbitrary measurement [13]. This uncertainty is given by the statistical deviation between the operator of interest and the estimated value of that operator. In our case, it reads

$$\varepsilon^2(\hat{\Pi}_1) = \langle \psi | \left[\hat{\Pi}_1 - \sum_{\pm} \frac{\beta_{\pm}}{\alpha} |\pm\rangle\langle\pm| \right]^2 | \psi \rangle, \quad (23)$$

$$\begin{aligned} \varepsilon^2(\hat{\Pi}_1) &= \sum_{\pm} \langle \psi | \left(\hat{\Pi}_1^\dagger - \frac{\beta_{\pm}}{\alpha} \right) | \pm \rangle \langle \pm | \left(\hat{\Pi}_1 - \frac{\beta_{\pm}}{\alpha} \right) | \psi \rangle \\ &= \sum_{\pm} p_{\pm} \left| \langle \hat{\Pi}_1 \rangle_w^{\pm, \psi(\chi)} - \frac{\beta_{\pm}}{\alpha} \right|^2 \end{aligned} \quad (25)$$

exp. data

where p_{\pm} denotes the statistical probability in the undisturbed system of finding the neutron in the final state $|\pm\rangle$:

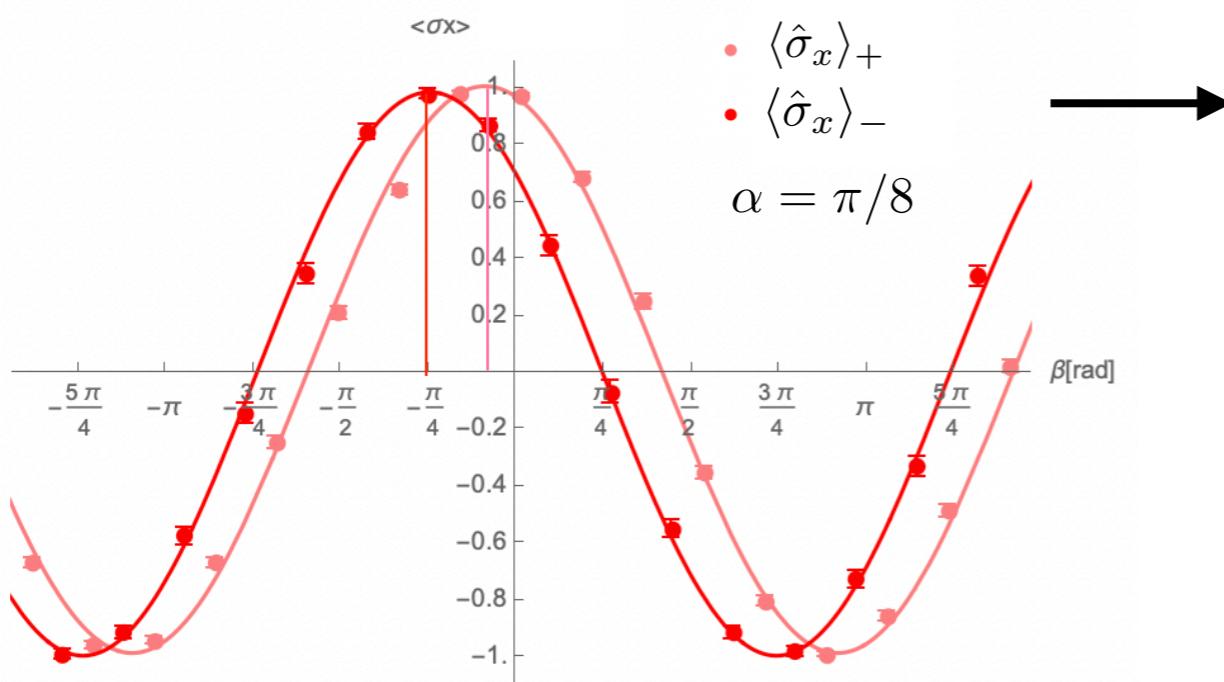
$$p_{\pm} = |\langle \pm | \psi \rangle|^2 = \frac{1}{2} \pm a_1 a_2 \cos \chi. \quad (26)$$

Interference Context: **individual “postselection-based” feedback comp:**

best estimates (@ $\alpha = \pi/8$) :

$$\frac{\beta_{0+}}{\alpha} = 0.703(45) \quad [\text{Theory: } 2/3]$$

$$\frac{\beta_{0-}}{\alpha} = 1.989(38) \quad [\text{Theory: } 2]$$



(not shown in paper; only $\alpha = \pi/16$ & $\pi/4$)

Additional Notes on Ozawa-Hall Error i) Values of Errors

The same conclusion can be drawn using the Ozawa-Hall theory. Ozawa [12] introduced a general concept of measurement errors and it was shown by Hall that these errors correspond to the uncertainty of an estimate of a physical property based on the outcome of an arbitrary measurement [13]. This uncertainty is given by the statistical deviation between the operator of interest and the estimated value of that operator. In our case, it reads

$$\varepsilon^2(\hat{\Pi}_1) = \langle \psi | \left[\hat{\Pi}_1 - \sum_{\pm} \frac{\beta_{\pm}}{\alpha} |\pm\rangle\langle\pm| \right]^2 | \psi \rangle, \quad (23)$$

$$\begin{aligned} \varepsilon^2(\hat{\Pi}_1) &= \sum_{\pm} \langle \psi | \left(\hat{\Pi}_1^\dagger - \frac{\beta_{\pm}}{\alpha} \right) | \pm \rangle \langle \pm | \left(\hat{\Pi}_1 - \frac{\beta_{\pm}}{\alpha} \right) | \psi \rangle \\ &= \sum_{\pm} p_{\pm} \left| \langle \hat{\Pi}_1 \rangle_w^{\pm, \psi(\chi)} - \frac{\beta_{\pm}}{\alpha} \right|^2 \end{aligned} \quad (25)$$

exp. data

where p_{\pm} denotes the statistical probability in the undisturbed system of finding the neutron in the final state $|\pm\rangle$:

$$p_{\pm} = |\langle \pm | \psi \rangle|^2 = \frac{1}{2} \pm a_1 a_2 \cos \chi. \quad (26)$$

Interference Context: **individual “postselection-based” feedback comp:**

best estimates (@ $\alpha = \pi/8$) :

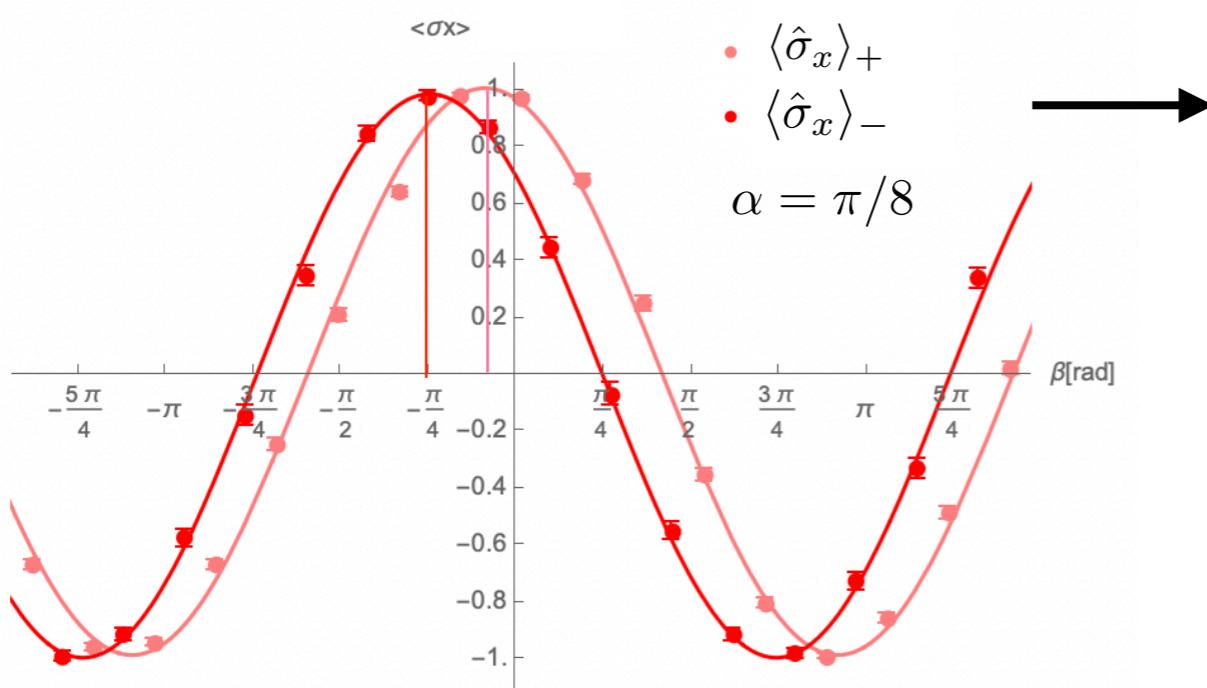
$$\frac{\beta_{0+}}{\alpha} = 0.703(45) \quad [\text{Theory: 2/3}]$$

$$\frac{\beta_{0-}}{\alpha} = 1.989(38) \quad [\text{Theory: 2}]$$

$$\varepsilon^2(\hat{\Pi}_1) = 0.0012(29)$$

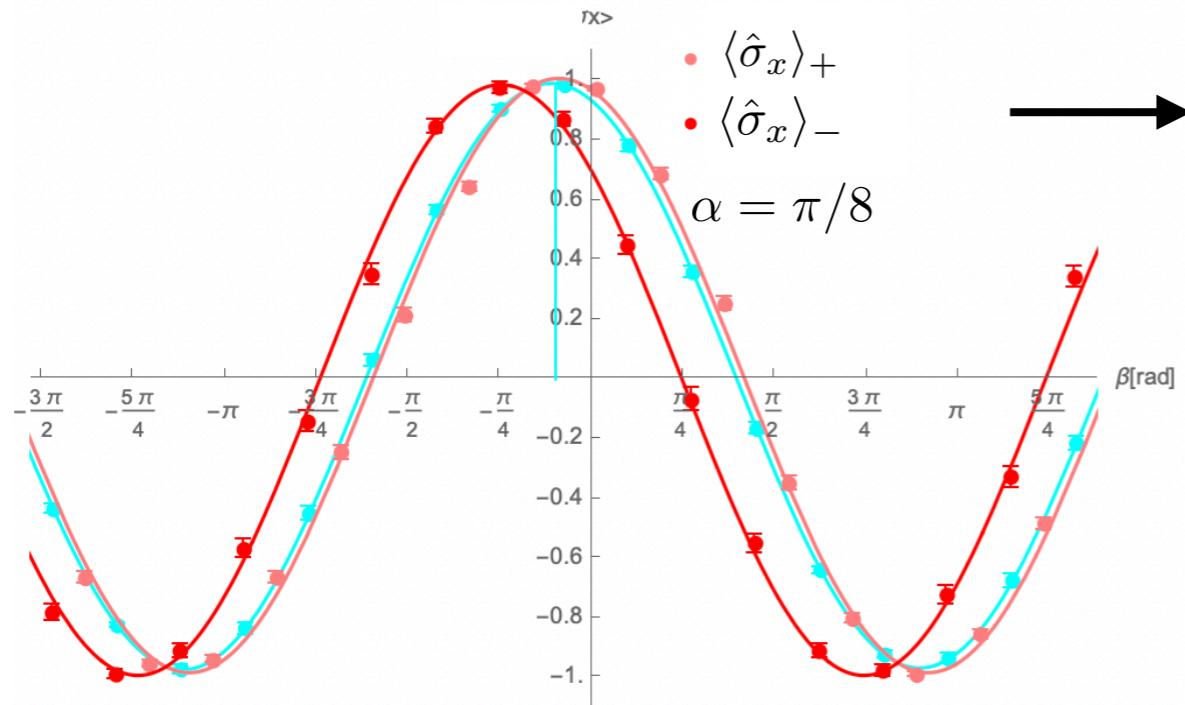
$$\varepsilon(\hat{\Pi}_1) = 0.034(42)$$

[Theory: 0]



(not shown in paper; only $\alpha = \pi/16$ & $\pi/4$)

Interference Context: **common “postselection-based” feedback comp:**



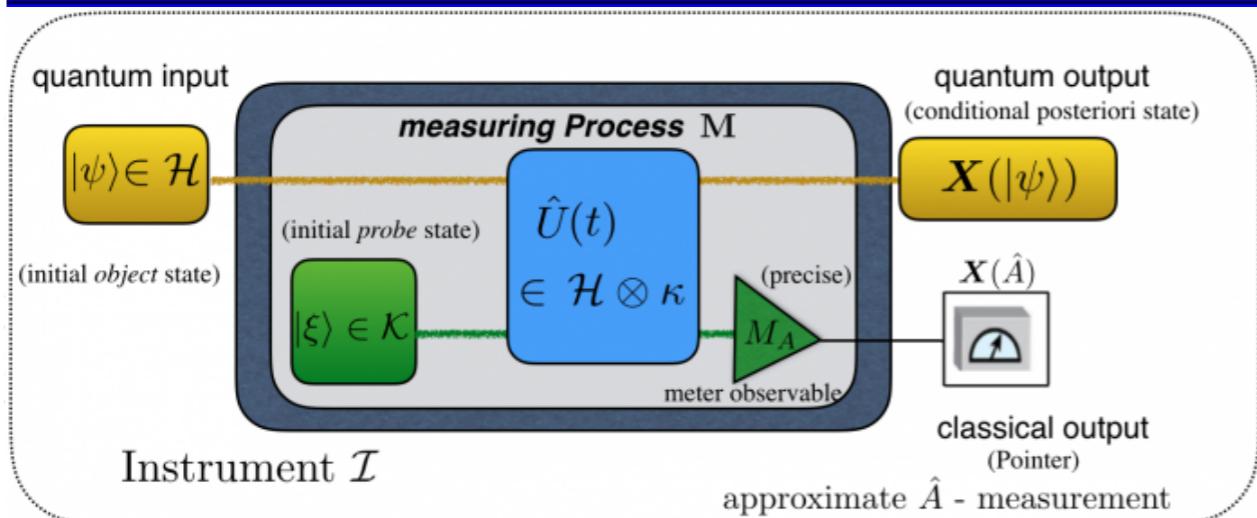
best estimates(@ $\alpha = \pi/8$) :

$$\frac{\bar{\beta}_0}{\alpha} = 0.831(41) \quad [\text{Theory: } 4/5]$$

(not shown in paper; only $\alpha = \pi/16$ & $\pi/4$)

$$\overline{\langle \hat{\sigma}_x \rangle}_{\pm} = p_+ \langle \hat{\sigma}_x \rangle_+ + p_- \langle \hat{\sigma}_x \rangle_-$$

Averages ...



$$\varepsilon^2(\hat{\Pi}_1) = \langle \psi | \left[\hat{\Pi}_1 - \sum_{\pm} \frac{\beta_{\pm}}{\alpha} |\pm\rangle\langle\pm| \right]^2 | \psi \rangle, \quad (23)$$

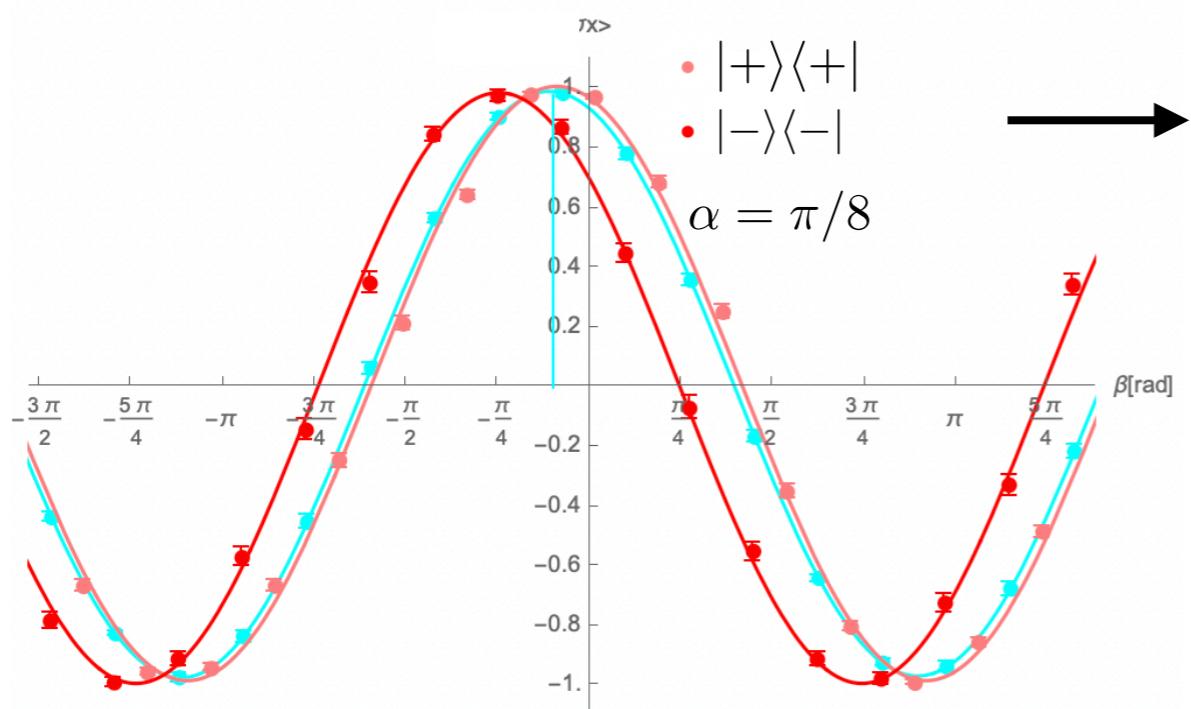
'postselection-based' feedback comp:

$$\begin{aligned} \varepsilon^2(\hat{\Pi}_1) &= \sum_{\pm} \langle \psi | \left(\hat{\Pi}_1^\dagger - \frac{\beta_{\pm}}{\alpha} \right) | \pm \rangle \langle \pm | \left(\hat{\Pi}_1 - \frac{\beta_{\pm}}{\alpha} \right) | \psi \rangle \\ &= \sum_{\pm} p_{\pm} \left| w_{1\pm} - \frac{\beta_{\pm}}{\alpha} \right|^2, \end{aligned} \quad (25)$$

where p_{\pm} denotes the statistical probability in the undisturbed system of finding the neutron in the final state $|\pm\rangle$:

$$p_{\pm} = |\langle \pm | \psi \rangle|^2 = \frac{1}{2} \pm a_1 a_2 \cos \chi. \quad (26)$$

Interference Context: common "postselection-based" feedback comp:



(not shown in paper; only $\alpha = \pi/16$ & $\pi/4$)

best estimates (@ $\alpha = \pi/8$):

$$\frac{\bar{\beta}_0}{\alpha} = 0.831(41) \quad [\text{Theory: } 4/5]$$

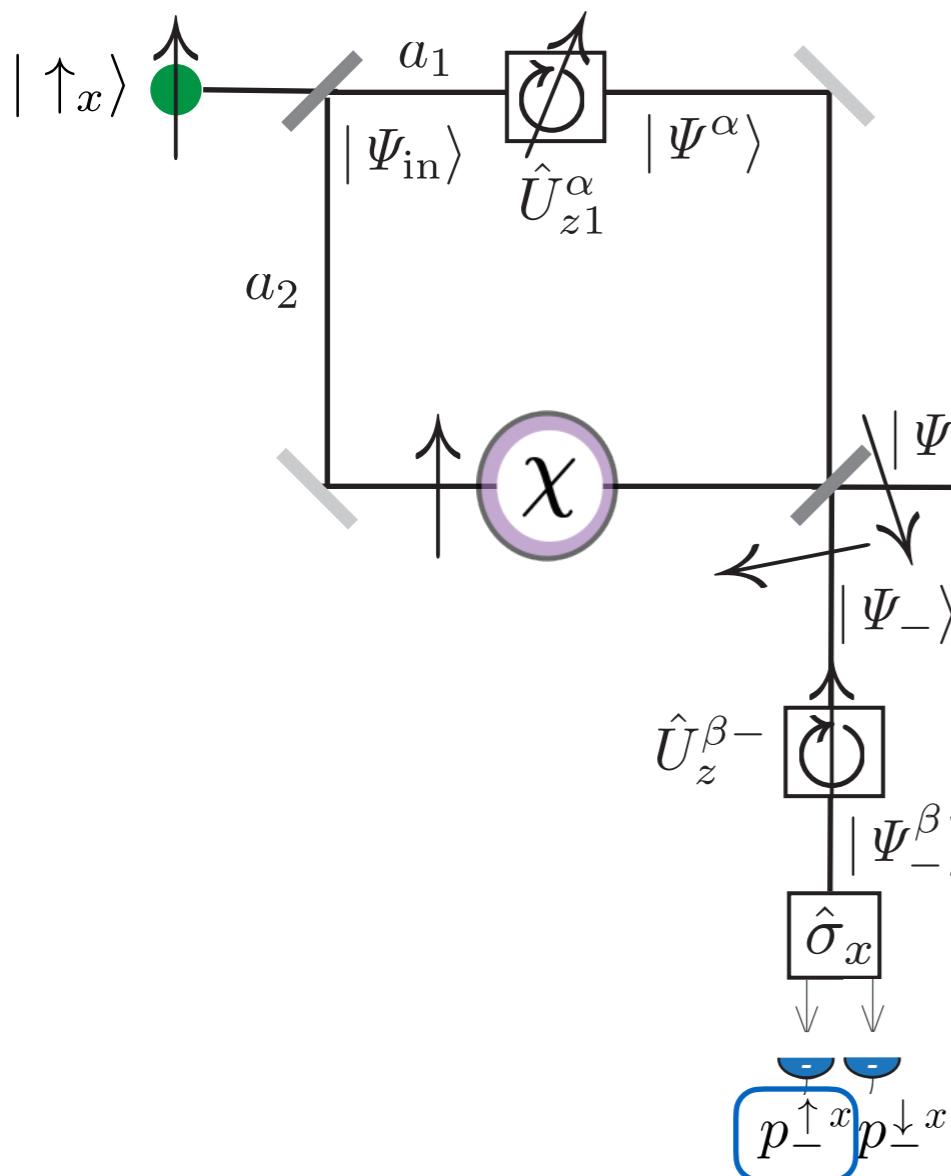


$$\varepsilon^2(\hat{\Pi}_1) = 0.161(13) \quad [\text{Theory: } 0.16]$$

$$\varepsilon(\hat{\Pi}_1) = 0.401(3) \quad [\text{Theory: } 0.4]$$

$$\text{Variance} \quad \Delta(\bar{\omega}_1) = \frac{2}{5}$$

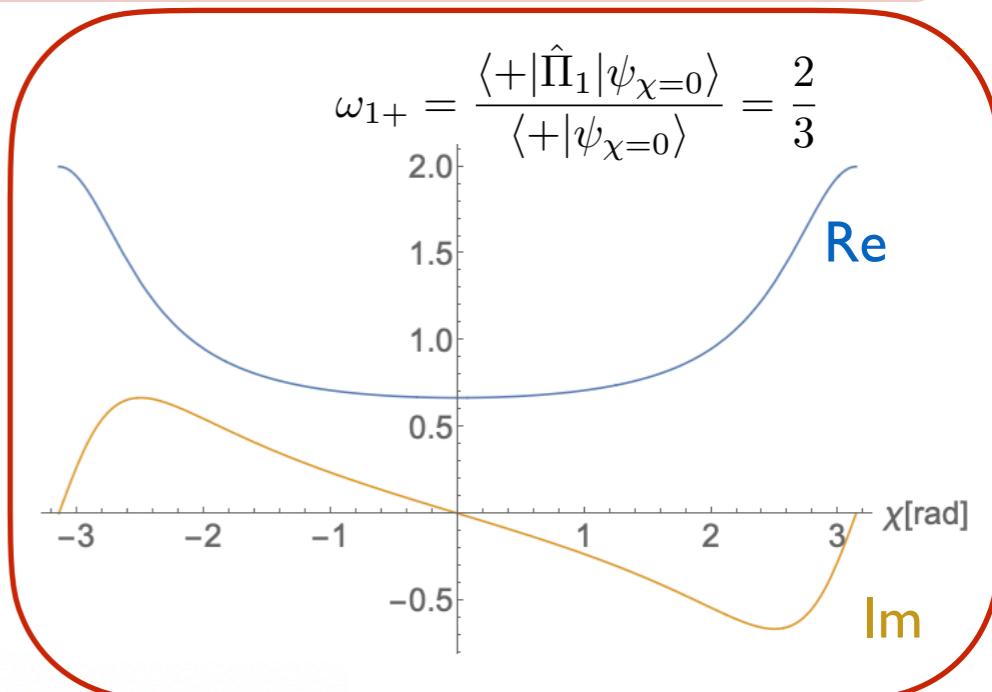
Additional Notes on Ozawa-Hall Error iii) Variation of initial state



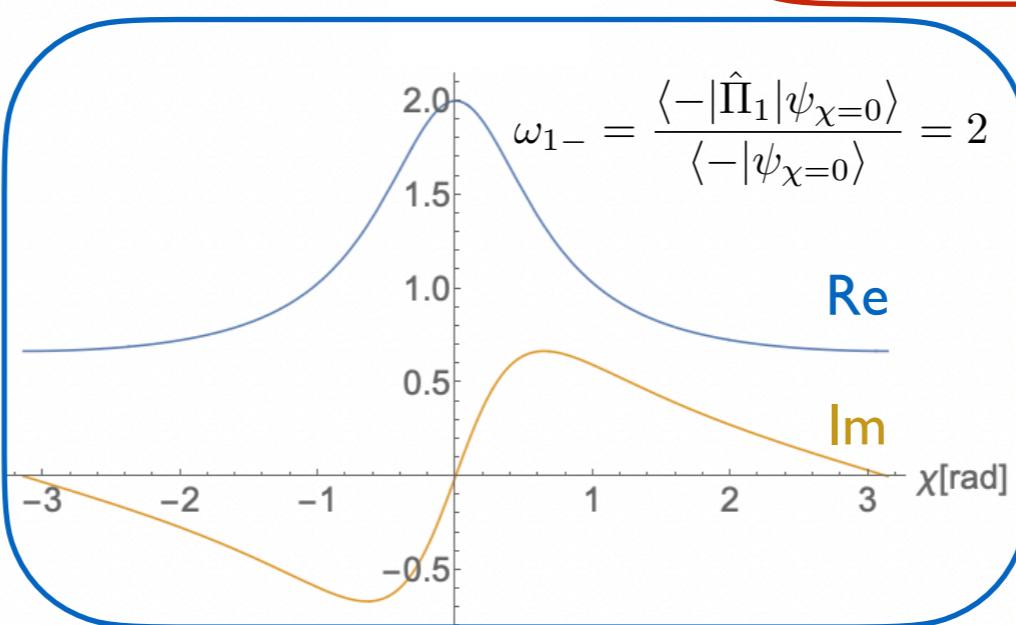
$$|\Psi_{\text{in}}\rangle = |\psi \otimes S\rangle = (a_1|1\rangle + e^{i\chi}a_2|2\rangle) \otimes |\uparrow_x\rangle$$

$$\rightarrow a_1 = \frac{2}{\sqrt{5}}, a_2 = \frac{1}{\sqrt{5}}$$

$$\omega_{1+} = \frac{\langle +|\hat{\Pi}_1|\psi_{\chi=0}\rangle}{\langle +|\psi_{\chi=0}\rangle} = \frac{2}{3}$$



— Real WV
— Imagin WV



Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\eta(B) + \epsilon(A)\Delta B + \eta(B)\Delta A \geq \frac{1}{2}|\langle\psi|[A, B]|\psi\rangle|$$

$$|\psi\rangle := |\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle \quad \hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1| \quad \hat{B} = |+\rangle\langle +| - |-\rangle\langle -| := \hat{X} \text{ (or } \hat{\sigma}_x^p\text{)} \\ |\pm\rangle = |1\rangle \pm |2\rangle$$

● simultaneous measurement:

$$\eta(B) \rightarrow \varepsilon(B)$$

Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\eta(B) + \boxed{\epsilon(A)\Delta B + \eta(B)\Delta A} \geq \frac{1}{2}|\langle\psi|[A, B]|\psi\rangle|$$

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle \quad \begin{aligned} &:= c_1 \\ &:= c_2 \end{aligned}$$

$$\hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1| \quad \hat{B} = |+\rangle\langle +| - |-\rangle\langle -| := \hat{X}$$

$$|\pm\rangle = |1\rangle \pm |2\rangle$$

● **Error:** $\varepsilon^2(\hat{\Pi}_1) = \langle\psi(\chi)| \left[\hat{\Pi}_1 - \sum_{\pm} \frac{\beta_{\pm}}{\alpha}(\chi) |\pm\rangle\langle\pm| \right]^2 |\psi(\chi)\rangle \quad (23)$

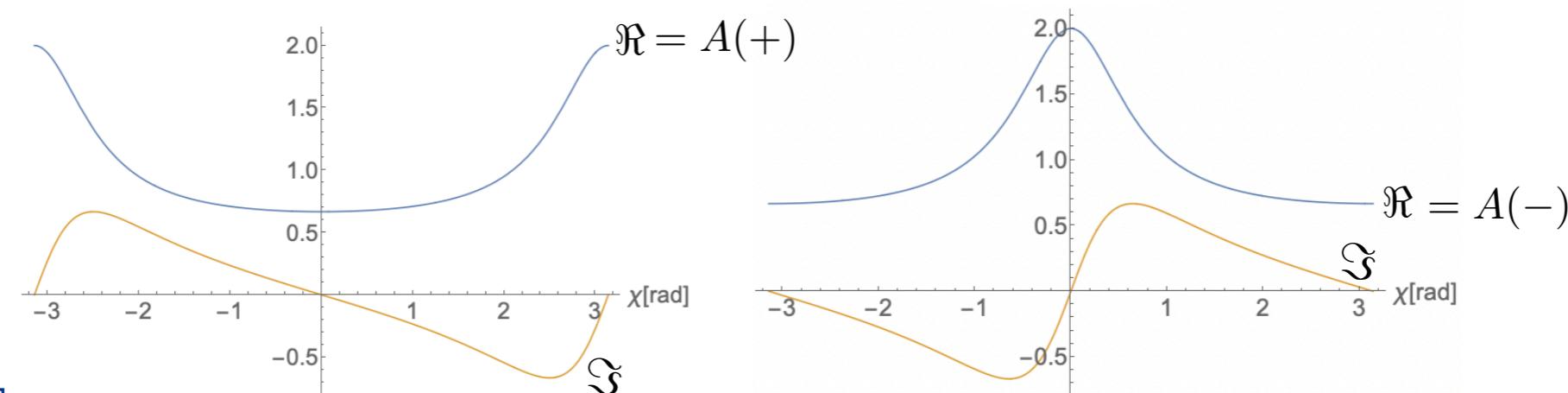
best estimate weak value path projector :

$$\frac{\beta_{\pm}}{\alpha}(\chi) = \omega_{1\pm}(\chi) \cong \Re \frac{\langle \pm | \hat{\Pi}_1 | \psi(\chi) \rangle}{\lim_{\alpha \rightarrow 0} \langle \pm | \psi(\chi) \rangle}$$

The optimal estimates after the interference measurements are given by

$$\frac{\beta_+(\chi)}{\alpha} = A(+) = c_1^2 - \frac{c_1 c_2 \cos(\chi)}{1 + 2c_1 c_2 \cos(\chi)} (c_1^2 - c_2^2)$$

$$\frac{\beta_-(\chi)}{\alpha} = A(-) = c_1^2 + \frac{c_1 c_2 \cos(\chi)}{1 - 2c_1 c_2 \cos(\chi)} (c_1^2 - c_2^2)$$



Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\eta(B) + \boxed{\epsilon(A)\Delta B + \eta(B)\Delta A} \geq \frac{1}{2}|\langle\psi|[A, B]|\psi\rangle|$$

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle$$

$$:= c_1 \quad \quad \quad := c_2$$

$$\hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1| \quad \hat{B} = |+\rangle\langle +| - |-\rangle\langle -| := \hat{X}$$

$$|\pm\rangle = |1\rangle \pm |2\rangle$$

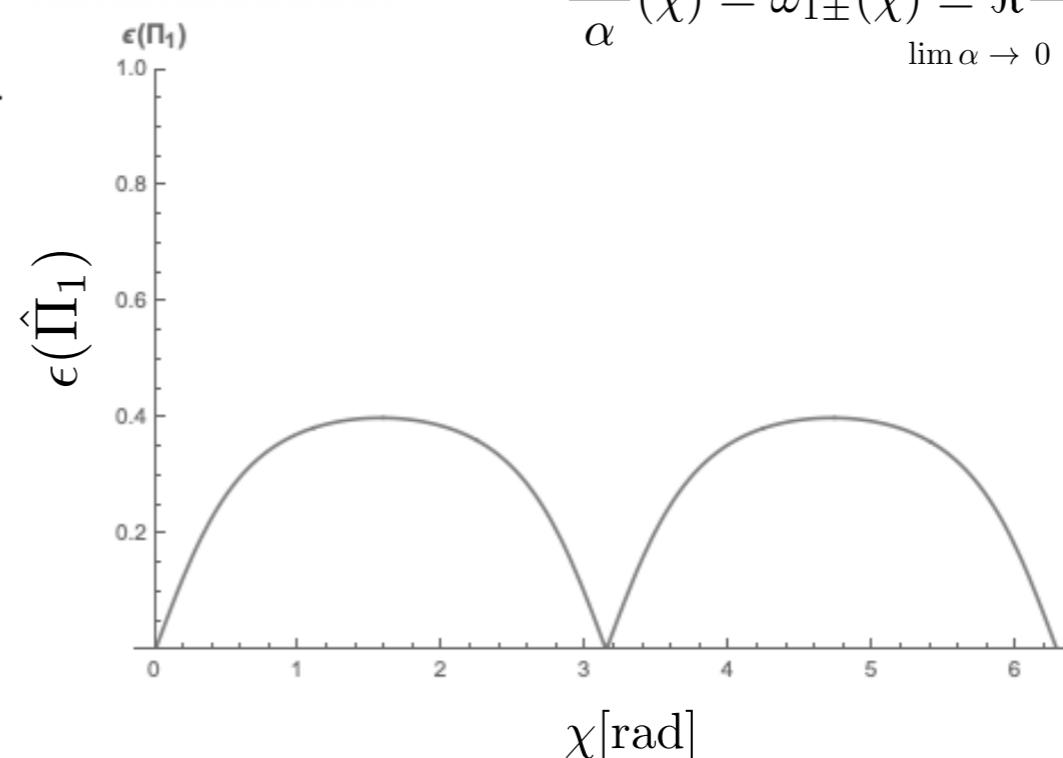
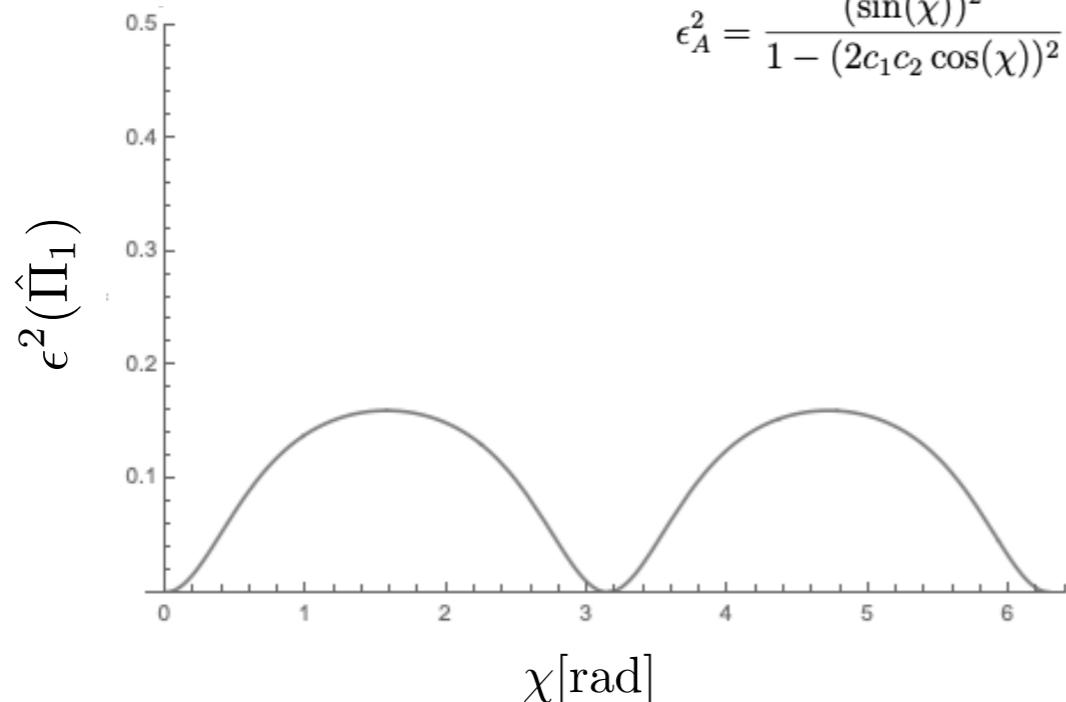
● **Error:** $\varepsilon^2(\hat{\Pi}_1) = \langle\psi(\chi)| \left[\hat{\Pi}_1 - \sum \frac{\beta_\pm}{\alpha}(\chi) |\pm\rangle\langle\pm| \right]^2 |\psi(\chi)\rangle$ (23)

best estimate weak value path projector :

$$\frac{\beta_\pm}{\alpha}(\chi) = \omega_{1\pm}(\chi) \cong \Re \frac{\langle \pm|\hat{\Pi}_1|\psi(\chi)\rangle}{\lim_{\alpha \rightarrow 0} \langle \pm|\psi(\chi)\rangle}$$

Theory: The predicted result for the interference fringes is

$$\varepsilon_A^2 = \frac{(\sin(\chi))^2}{1 - (2c_1c_2 \cos(\chi))^2} (c_1c_2)^2.$$



Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\eta(B) + \boxed{\epsilon(A)\Delta B + \eta(B)\Delta A} \geq \frac{1}{2}|\langle\psi|[A, B]|\psi\rangle|$$

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle$$

$$:= c_1 \quad \quad \quad := c_2$$

$$\hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1| \quad \hat{B} = |+\rangle\langle +| - |-\rangle\langle -| := \hat{X}$$

$$|\pm\rangle = |1\rangle \pm |2\rangle$$

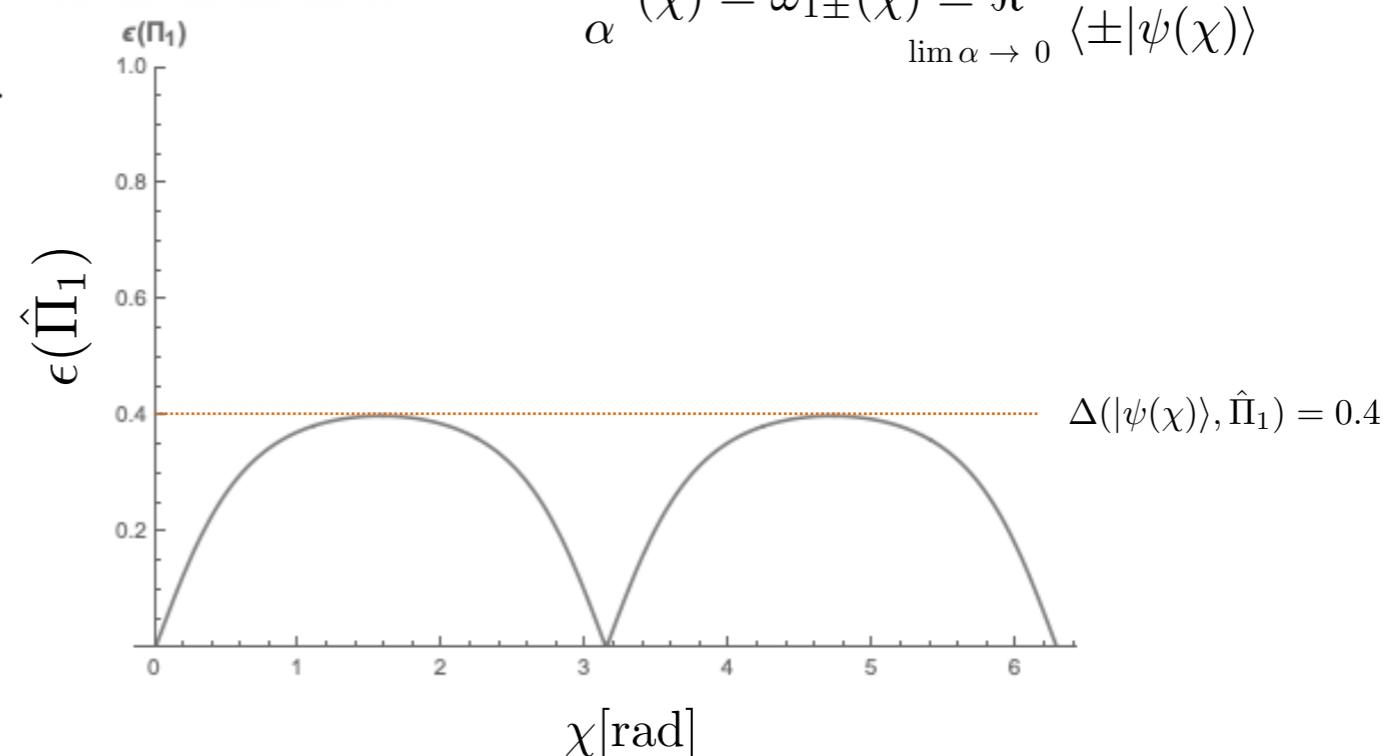
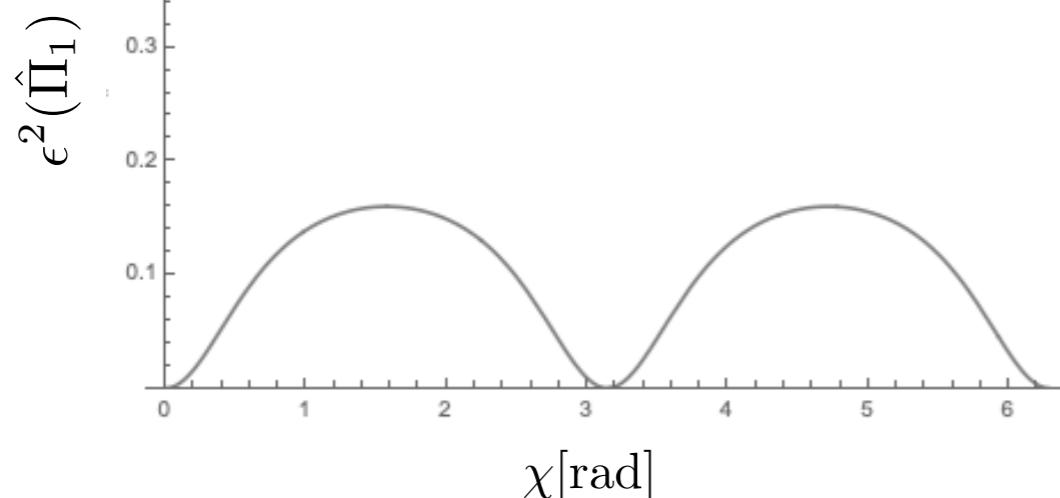
● **Error:** $\varepsilon^2(\hat{\Pi}_1) = \langle\psi(\chi)| \left[\hat{\Pi}_1 - \sum \frac{\beta_\pm}{\alpha}(\chi) |\pm\rangle\langle\pm| \right]^2 |\psi(\chi)\rangle$ (23)

best estimate weak value path projector :

$$\frac{\beta_\pm}{\alpha}(\chi) = \omega_{1\pm}(\chi) \cong \Re \frac{\langle \pm | \hat{\Pi}_1 | \psi(\chi) \rangle}{\lim_{\alpha \rightarrow 0} \langle \pm | \psi(\chi) \rangle}$$

Theory: The predicted result for the interference fringes is

$$\varepsilon_A^2 = \frac{(\sin(\chi))^2}{1 - (2c_1c_2 \cos(\chi))^2} (c_1c_2)^2.$$



Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle$$

$$\hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1|$$

Theory: $c_1 := c_1$ $c_2 := c_2$

 **Error:** $\varepsilon^2(\hat{\Pi}_1) = \langle\psi(\chi)|\left[\hat{\Pi}_1 - \sum_{\pm} \frac{\beta_{\pm}}{\alpha}(\chi)|\pm\rangle\langle\pm|\right]^2|\psi(\chi)\rangle \quad (23)$

$$\varepsilon^2(\hat{\Pi}_1) = \sum_{\pm} \langle\psi| \left(\hat{\Pi}_1^\dagger - \frac{\beta_{\pm}}{\alpha} \right) |\pm\rangle\langle\pm| \left(\hat{\Pi}_1 - \frac{\beta_{\pm}}{\alpha} \right) |\psi\rangle$$

Measurement:

$$= \sum_{\pm} p_{\pm} \left| \langle \hat{\Pi}_1 \rangle_w^{\pm, \psi(\chi)} - \frac{\beta_{\pm}}{\alpha} \right|^2$$

exp. data

$$p_{\pm} = |\langle \pm | \psi \rangle|^2 = \frac{1}{2} \pm a_1 a_2 \cos \chi$$

$$\langle \hat{\Pi}_1 \rangle_w^{\pm, \psi(\chi)} = \frac{\langle \pm | \hat{\Pi}_1 | \psi(\chi) \rangle}{\langle \pm | \psi(\chi) \rangle}$$

Theory:

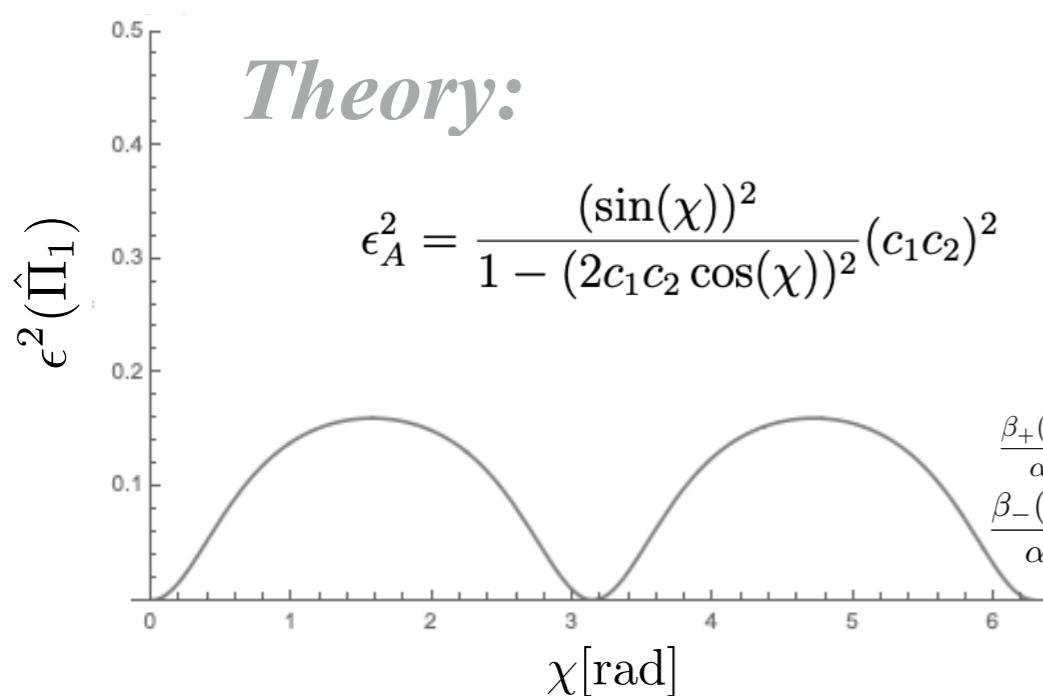
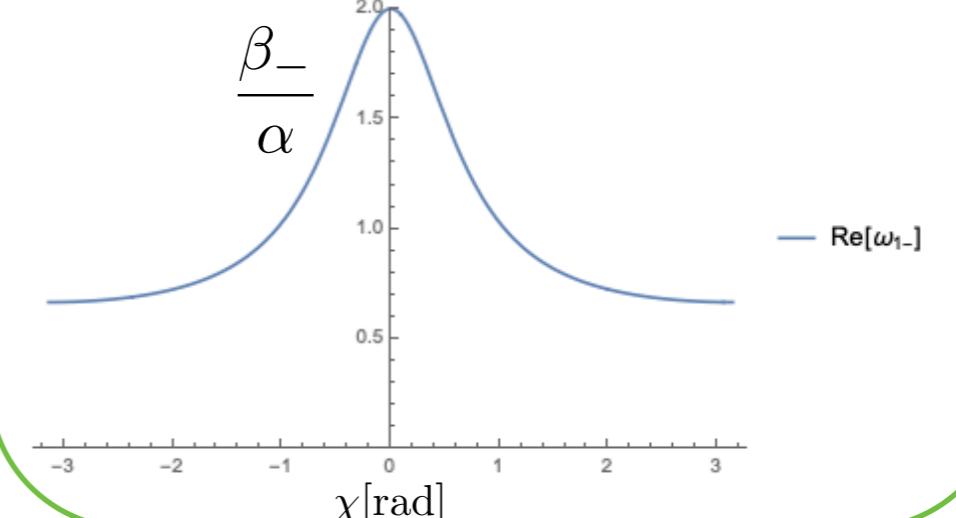
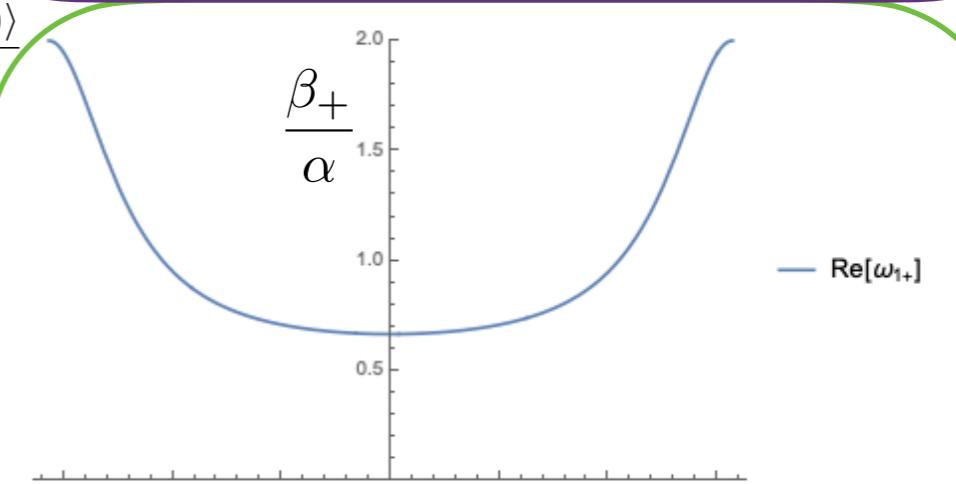
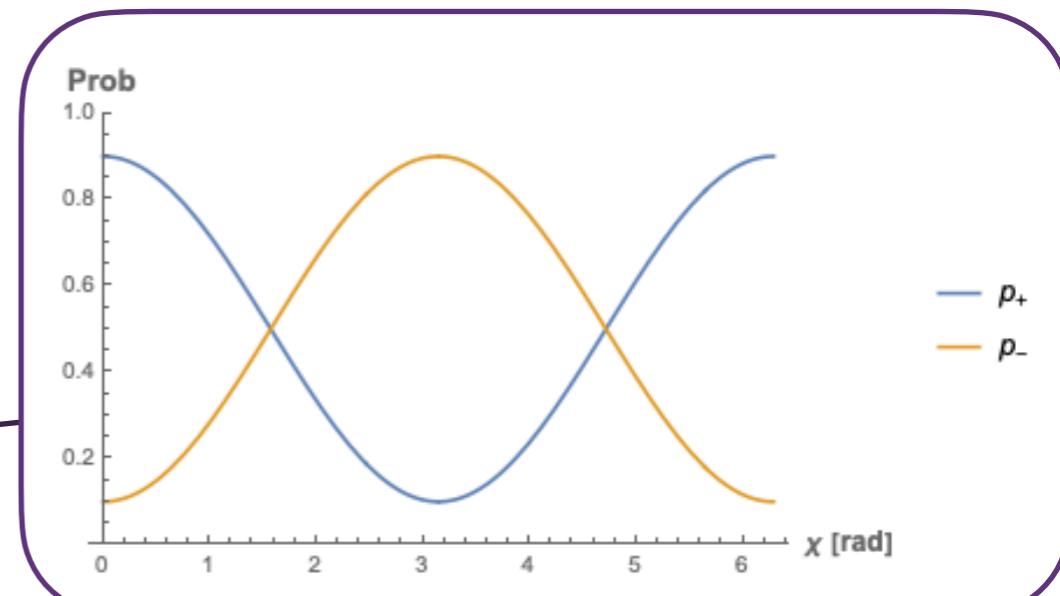
$$\epsilon_A^2 = \frac{(\sin(\chi))^2}{1 - (2c_1 c_2 \cos(\chi))^2} (c_1 c_2)^2$$

$$p_+ = \frac{1}{2} + c_1 c_2 \cos(\chi)$$

$$p_- = \frac{1}{2} - c_1 c_2 \cos(\chi).$$

$$\begin{aligned} \frac{\beta_+(\chi)}{\alpha} &= A(+) = c_1^2 - \frac{c_1 c_2 \cos(\chi)}{1 + 2c_1 c_2 \cos(\chi)} (c_1^2 - c_2^2) \\ \frac{\beta_-(\chi)}{\alpha} &= A(-) = c_1^2 + \frac{c_1 c_2 \cos(\chi)}{1 - 2c_1 c_2 \cos(\chi)} (c_1^2 - c_2^2) \end{aligned}$$

Measurement:

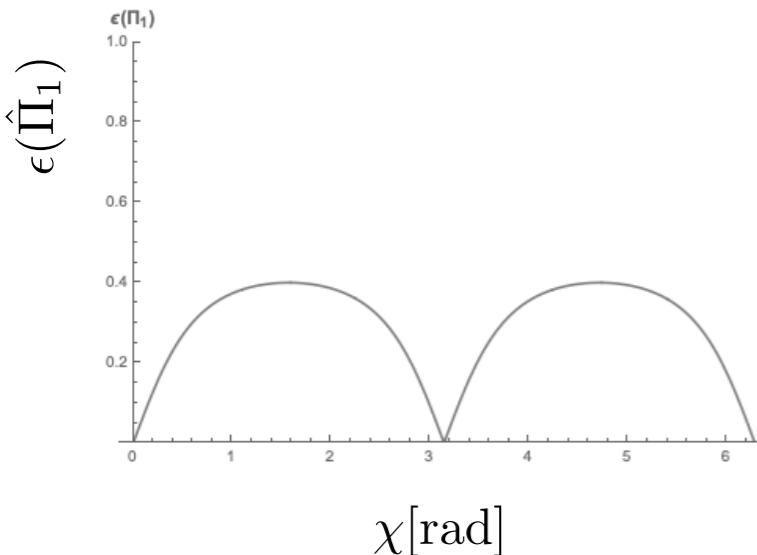


Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

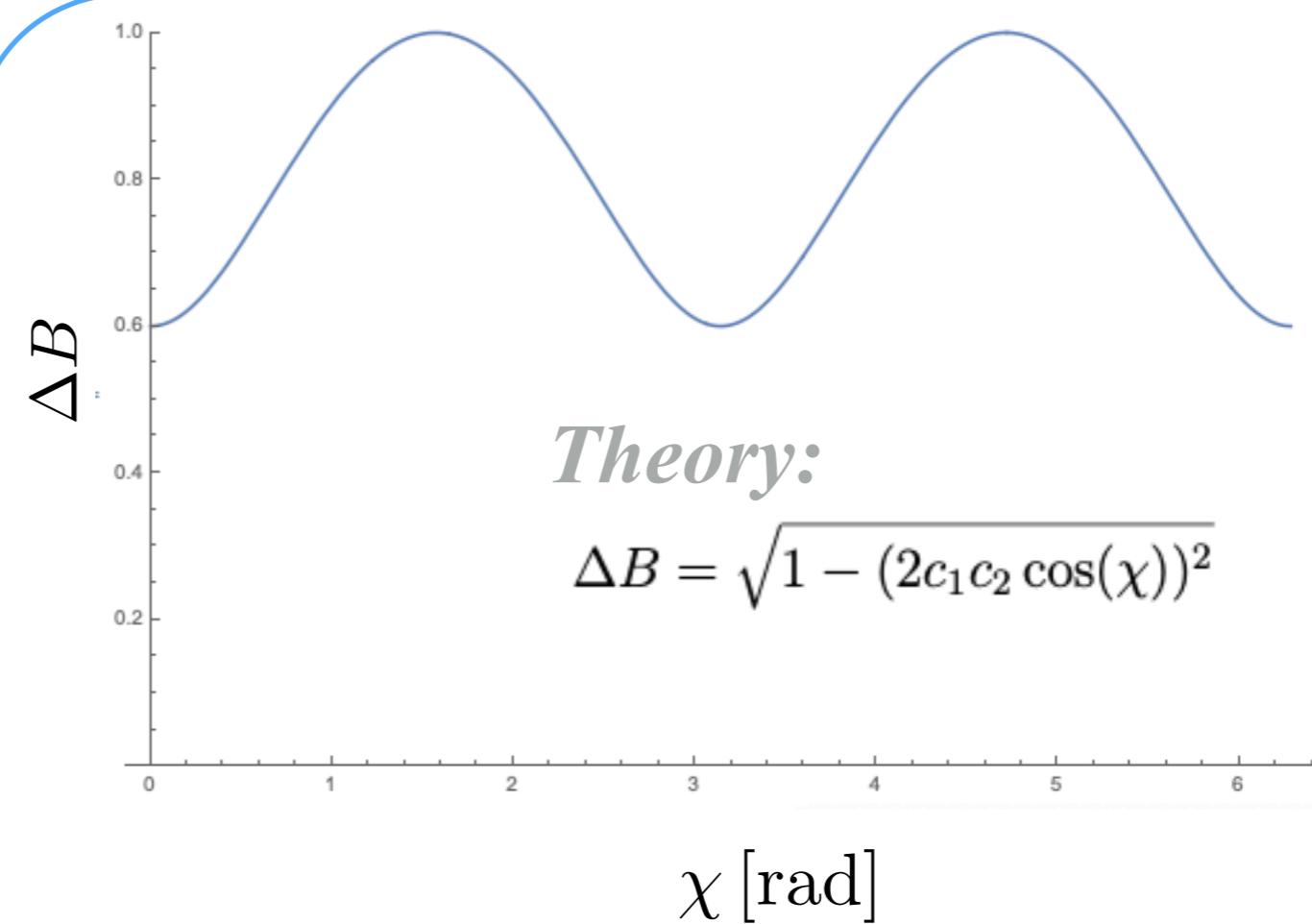
Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\eta(B) + \boxed{\epsilon(A)}\boxed{\Delta B} + \eta(B)\Delta A \geq \frac{1}{2}|\langle\psi|[A, B]|\psi\rangle|$$

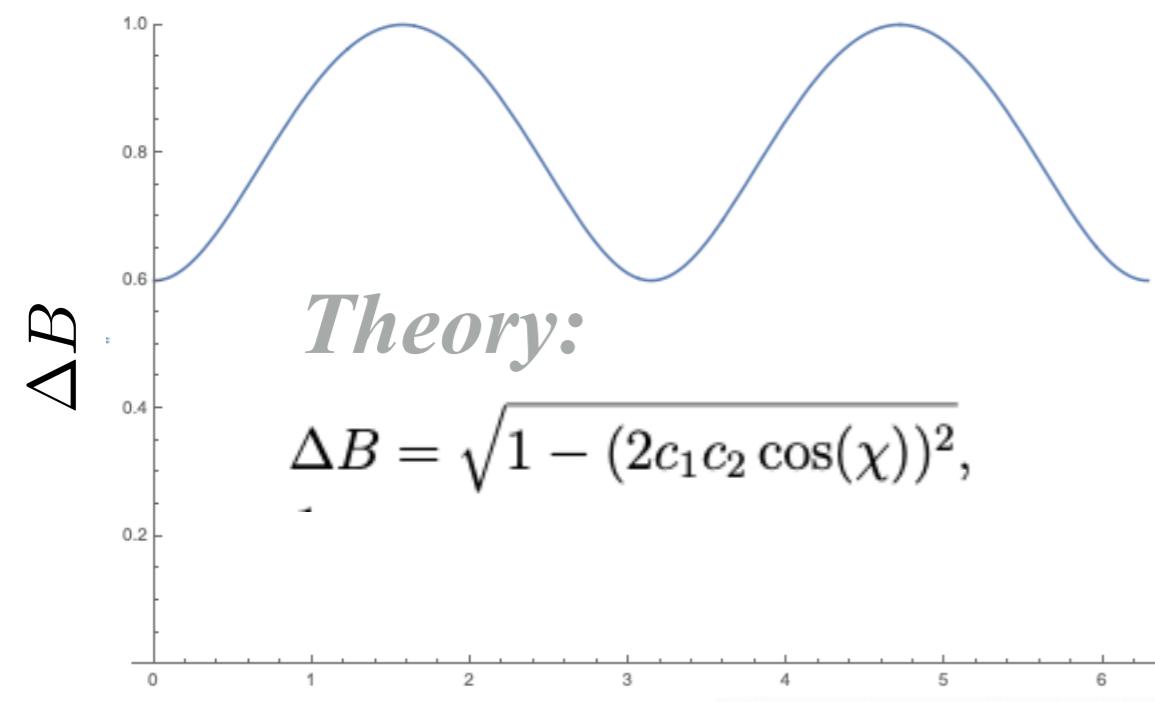
$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle \\ := c_1 \quad \quad \quad := c_2$$



$$\hat{A} = \hat{\Pi}_1 \quad \hat{B} = |+\rangle\langle+| - |-\rangle\langle-| = \hat{X} = \hat{\sigma}_x \\ |\pm\rangle = |1\rangle \pm |2\rangle$$



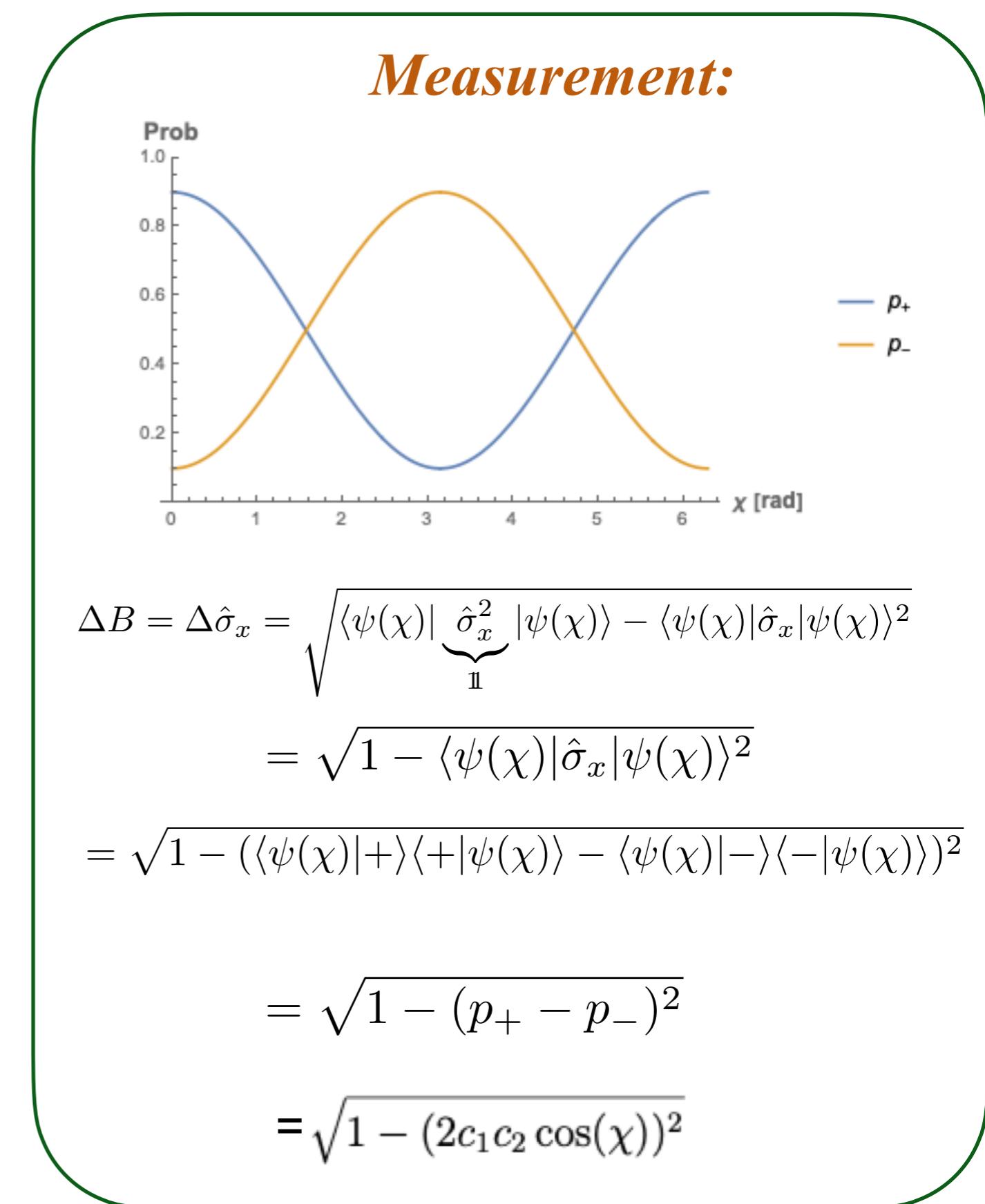
Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario



χ [rad]

$$p_+ = \frac{1}{2} + c_1 c_2 \cos(\chi)$$

$$p_- = \frac{1}{2} - c_1 c_2 \cos(\chi).$$



Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\cancel{\epsilon(A)\eta(B)} + \epsilon(A)\Delta B + \cancel{\eta(B)\Delta A} \geq \frac{1}{2} |\langle \psi | [A, B] | \psi \rangle|$$

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle$$

$$\hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1|$$

$$\hat{B} = |+\rangle\langle +| - |-\rangle\langle -| := \hat{X} = \hat{\sigma}_x$$

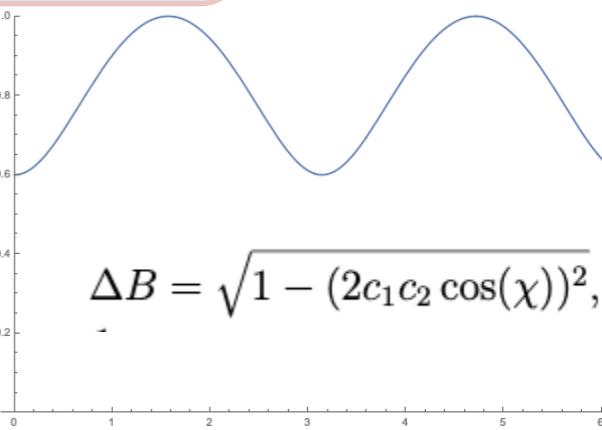
$$|\pm\rangle = |1\rangle \pm |2\rangle$$

$$\varepsilon^2(A) = \left\| \left(A - \sum_{\lambda} \lambda O_{\lambda} \right) \psi(\chi) \right\|^2$$

$$O_{\lambda} = |\pm\rangle\langle\pm|$$

$$\varepsilon^2(\hat{\Pi}_1) = \langle \psi(\chi) | \left[\hat{\Pi}_1 - \sum_{\pm} \frac{\beta_{\pm}}{\alpha}(\chi) |\pm\rangle\langle\pm| \right]^2 | \psi(\chi) \rangle \quad (23)$$

● **Error:**

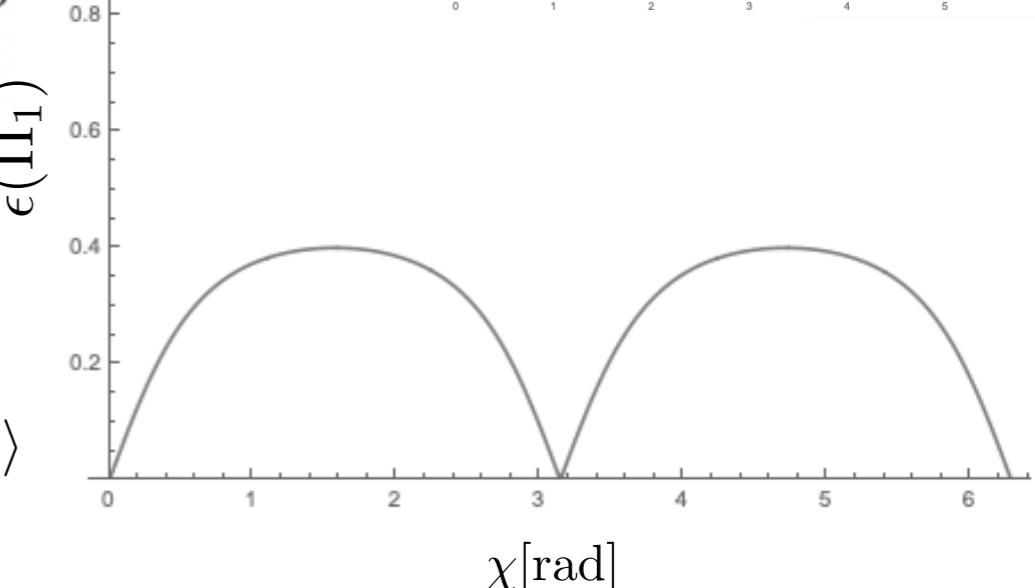


● **Disturbance:**

$$\begin{aligned} \eta^2(B) &= \sum_{\lambda} \langle \psi(\chi) | [O_{\lambda}, B]^{\dagger} [O_{\lambda}, B] | \psi(\chi) \rangle \\ &= \sum_{\lambda} \| [O_{\lambda}, B] | \psi(\chi) \rangle \|^2 = 0 \quad \forall |\psi(\chi)\rangle \end{aligned}$$

$$\updownarrow$$

$$[|\pm\rangle\langle\pm|, B] = 0$$



Eigenvectors of B are *Approximators* of A

Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\eta(B) + \epsilon(A)\Delta B + \eta(B)\Delta A \geq \frac{1}{2}|\langle\psi|[A,B]|\psi\rangle|$$

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi}\frac{1}{\sqrt{5}}|2\rangle \quad \hat{A} = \hat{\Pi}_1 = |1\rangle\langle 1| \quad \hat{B} = |+\rangle\langle +| - |-\rangle\langle -| := \hat{X} = \hat{\sigma}_x$$

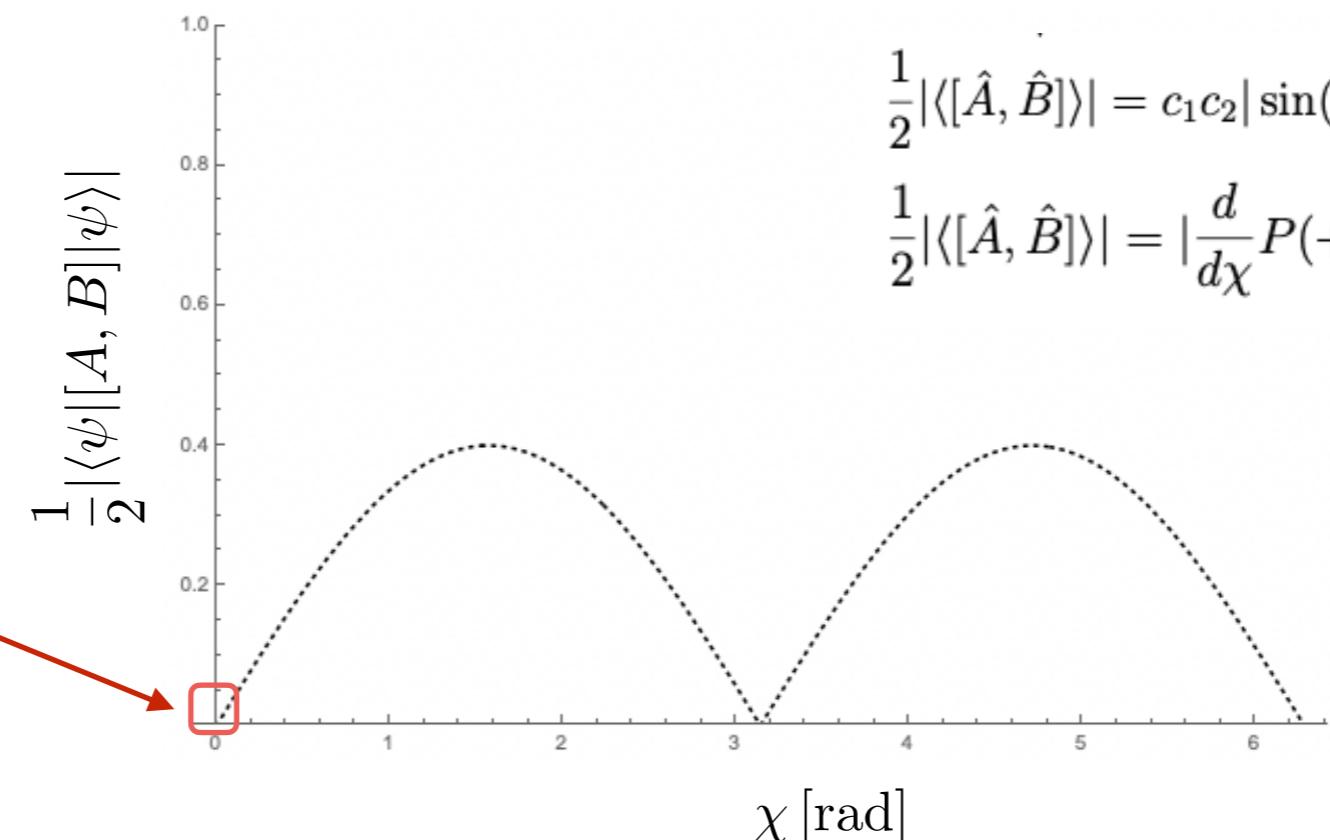
$$:= c_1 \qquad \qquad := c_2 \qquad \qquad \qquad |\pm\rangle = |1\rangle \pm |2\rangle$$

limit:

$$[A, B] = c_1 c_2 e^{i\chi} - c_1 c_2 e^{-i\chi} = 2c_1 c_2 \sin(\chi)$$

$$\frac{1}{2}|\langle [\hat{A}, \hat{B}] \rangle| = c_1 c_2 |\sin(\chi)|$$

$$\frac{1}{2}|\langle [\hat{A}, \hat{B}] \rangle| = \left| \frac{d}{d\chi} P(+) \right|$$



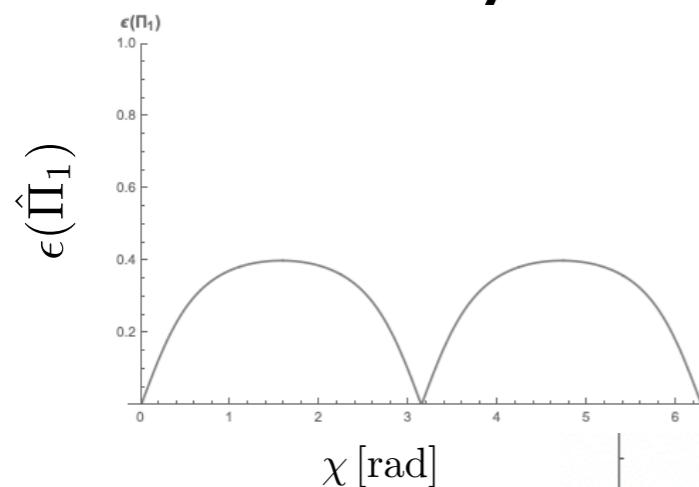
$$\frac{1}{2} |\langle \psi(\chi = 0) | [\hat{\Pi}_1, \hat{X}] | \psi(\chi = 0) \rangle| = 0$$

Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

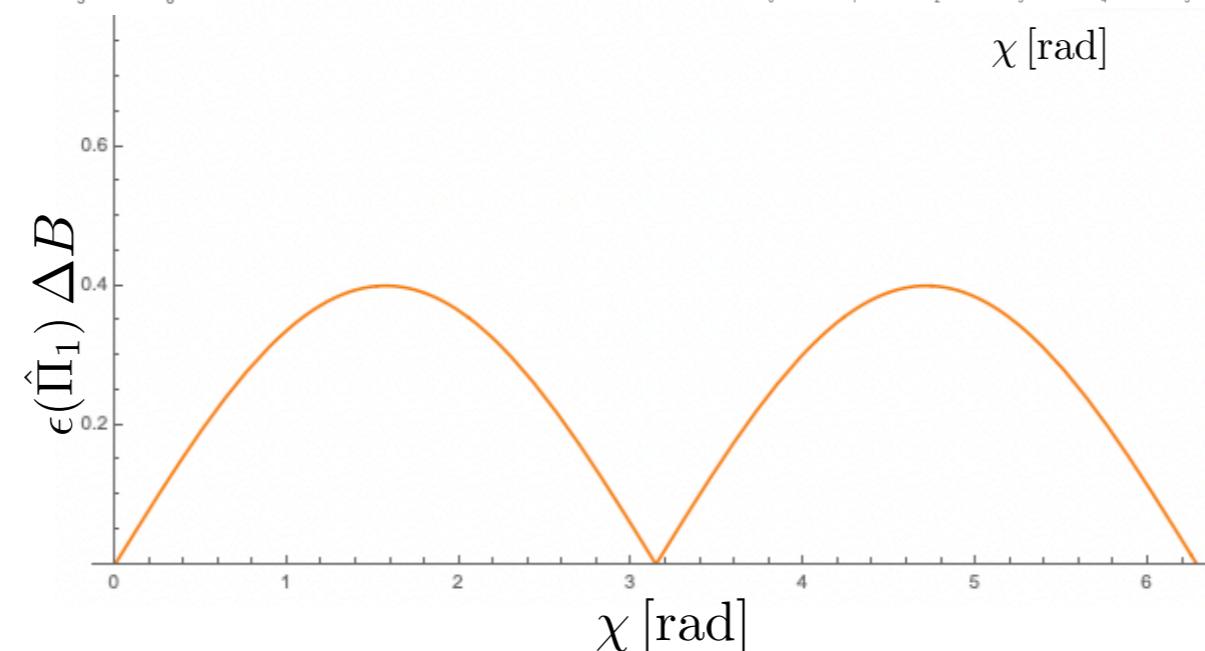
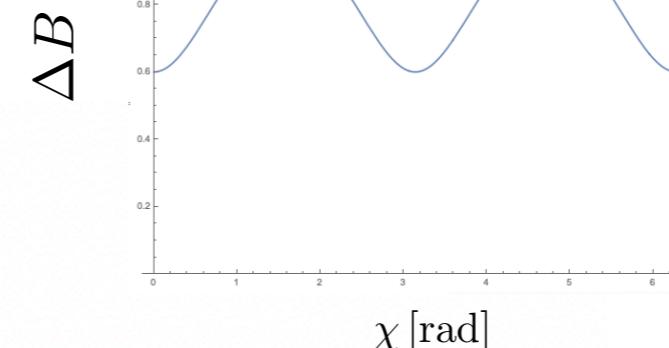
$$\cancel{\epsilon(A)\eta(B)} + \epsilon(A)\Delta B + \cancel{\eta(B)\Delta A} \geq \frac{1}{2} |\langle \psi | [A, B] | \psi \rangle|$$

$$|\psi(\chi)\rangle = \frac{2}{\sqrt{5}}|1\rangle + e^{i\chi} \frac{1}{\sqrt{5}}|2\rangle$$



$$\hat{A} = \hat{\Pi}_1 \quad \hat{B} = |+\rangle\langle+| - |-\rangle\langle-| := \hat{X} = \hat{\sigma}_x$$

$$|\pm\rangle = |1\rangle \pm |2\rangle$$



Additional Notes on Ozawa-Hall Error iii) Error - Disturbance Scenario

Ozawa's universally valid measurement uncertainty relation

$$\epsilon(A)\cancel{\eta(B)} + \epsilon(A)\Delta B + \cancel{\eta(B)\Delta A} \geq \frac{1}{2}|\langle\psi|[A, B]|\psi\rangle|$$

