

22.9.2025

3-16-19

sym. double loop ipm 30°

-USANS - mono

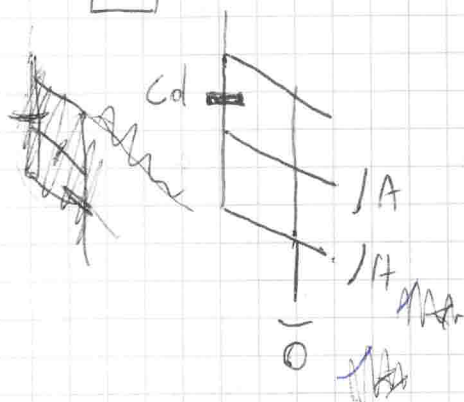
IT WAS
AUX

196



H-Def scan: -62.5

TILT SCAN (25/point H fit)



ϕ_1	PEAK	FWHM	
-1.70	3803	0.000358	
-1.73	4407	0.000365	
-1.76	4563	0.000383	(FLAT PEAK, UNUSUAL SHAPE)
-1.79	4574	0.000327	(UNUSUAL SHAPE)
-1.82	4026	0.000364	
-1.77	4561	0.000343	✓ (NORMAL SHAPE)



CAMERA3-IN.SC (Pos 7.00)

CAMERA3-OUT.SC (Pos 70.00)

ifg1-test.SC (TEST PS 1)

ifg1-test-22Sep1847.inf (C ~ 0.55, NO OSCILLATION IN
H-BEAM, PROBABLY WRONG DET. POSITION)

NEW H-DETECTOR POS: -58.5

ifg1-test-22Sep1855.inf (C ~ 0.55)

~~22.9.2025~~

ifg1-3p200s 22Sep1930

up to 73% locally

ifg2-3p200s 22Sep2123

23.9.2025 ifm moved 3mm ←

R0-23Sep0826, 0835

(ifg1-3p200s-23Sep0837)

0854

Aperture Z from 15 to 17

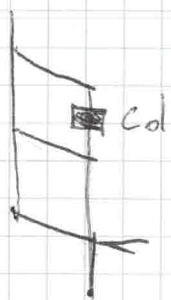
Camera 3mm ↓

C ≈ 70% (PIXEL 5,5)

C ≈ 78% (PIXEL 3,3)

A bit of phase gradient





iFg2-3p200s-B1-23 Sep 1203.inf

Intensity drift, probably peak drift.
Repeating the measurement.

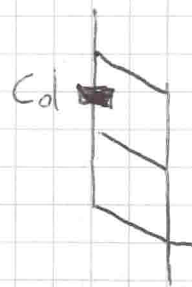
197

iFg2-3p200s-B1-23 Sep 1406.inf

Big phase gradient, placed post-it under IFM as last time (page 166).

TILT SCAN (2 s ~~ANAL~~ FIT)

P_1	PEAK	FWHM
-1.67	1182	0.000355 ✓
-1.64	1139	0.000379
-1.70	1106	0.000395



~~Phase~~ Robot prepared to block each path.

~~Robot~~ Robot diag pos:

PATH 1 → -10000, 30 deg rotation

PATH 2 → 10000, -30 deg rotation

PATH 3 → 45000, 30 deg rotation



Started IFM for each loop

24.09.2025

iFg2-3p200s-B1-24 Sep 0018.inf

iFg1-3p200s-B2-24 Sep 0211.inf

iFg2-3p200s-B2-24 Sep 0402.inf

iFg1-3p200s-B3-24 Sep 0555.inf

Overall good contrast and phase ~~stable~~

Unfortunately, bumped robot with Col into ~~section~~ IFM.

Starting ~~again~~ again from scratch.

198 TILT SCAN (2 s H-DET)

P1 P1	PEAK	FWHM
-1.6	983	0.000376 ✓
-1.65	866	0.000395
-1.56	947	0.000367
-1.58	954	0.000375
-1.62	968	0.000367

Piezo stopped working, somehow fixed it.
Starting again from scratch.

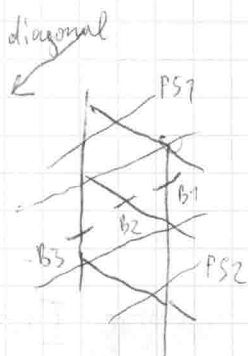
TILT SCAN (2 S H-DET)

P1	PEAK	FWHM
-1.5	1076	0.000382
-1.55	1031	0.000377 ✓
-1.6	875	0.000456

Robot re-prepared to block each path.

BLOCK PATH	ROBOT DIAU	ROT
1	-20000	30
2	-4000	-30
3	28000	30

Started IFG for each loop (120 s/point, hoping for two IFG each loop)



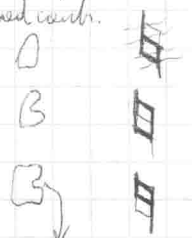
2nd loop ifg 2-3 p120s - B1 - 25 Sep 0055

big loop {	1	B2	0207
	2	B2	0317
1st loop {	1	B3	0428

intensity high up

area of good count.

→ rocking failed



2nd lamella?
P51?



aperture 2 moved to 15 (before: 17)
mono Lo Gran - 25 Sep 0838

→ -1,25 (before: -1,1)

7800 cps (before 7500 cps)

199



mono Pol - 25 Sep 0842

31,07 (bef: 31,00)

0

3

Aux FWHM

in 2s

-1,05

0,000454

1231

-1,1

347

1770

-1,15

397

1833

-1,20

37

1519

-1,13

365

1828

15



20

BS1 cleaned



ifg1-3p120s-B2-25 Sep 0922

big loop

⊙ low contrast area

ifg2-3p120s-B1-25 Sep 1045

second loop



ifg1-3p120s-B3-25 Sep 1150

first loop

⊠ low contrast area

~~Cleaned~~ Cleaned IFM, starting again.

TILT SCAN

H

AUX

P1

PEAK

FWHM

PEAK

FWHM

~~-1,13~~ ~~800~~ ~~0,000478~~ ~~2351~~ ~~0,000478~~

-1,2 1063 0,000343 4084 0,000344 ✓

-1,1 640 0,000609 2332 0,000627

-1,3 860 0,000441 3227 0,000427

-1,25 1017 0,000382 4050 0,000370

-1,15 861 0,000453 3148 0,000448

-1,22 1088 0,000381 4068 0,000418

-1,18 981 0,000410 3090 0,000365

ifg1-3p120s-B2-25 Sep 1545 inf



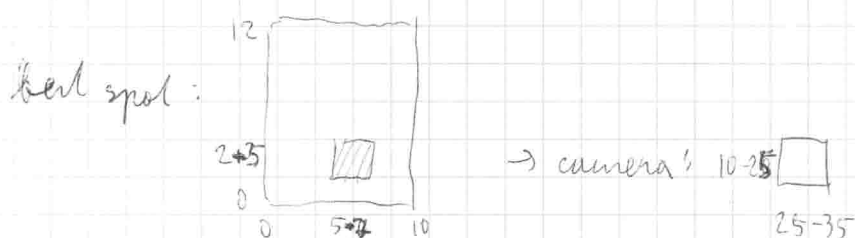
low contrast spot still there, moved IFM



BEAM
←

TILT SCAN (25)		M		AUX	
P1		PEAK	FWHM	PEAK	FWHM
200	-1.2	1765	0.000347	4518	0.000360 ✓

Started measurements for each loop
(IFG CAMERA)
26/09/2025



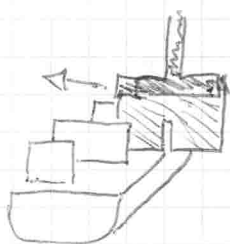
~~Contrast~~ Contrast $\geq 60\%$ $\sim 65\%$ for all parts, good enough.

Prepared Col slit for beams position / thickness

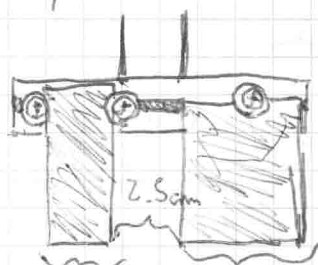
robot-diag-slit-Col-90deg-inf

BEAM THICKNESS ~ 7.5 mm.

ROBOT ROT BIG



Prepared double Col blocker



2.5cm 4.2cm

Scanned double Col blocker

robot-diag-double-Col-90deg-inf

