

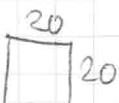
22.9.2025

3-16-19

sym. double loop ifm 30°

-USANS-Mono

196



H-Def scan: -62.5

IT WAS

AUX



TILT SCAN (2s/point) fit

	φ _z	PEAK	FWHM
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IA	-1.70	3803	0.000338
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IA	-1.73	4407	0.000365
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IA	-1.76	4563	0.000383 (FLAT PEAK, UNUSUAL SHAPE)
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IA	-1.79	4574	0.000327 (UNUSUAL SHAPE)
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	-1.82	4026	0.000364
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	-1.77	4561	0.000343 ✓**
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			(NORMAL SHAPE)
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PGM camera-IN.sc (Pos 7.00)

camera-OUT.sc (Pos 70.00)

ifg1-test.sc (TEST PS1)

ifg1-test-22 Sep 1847.inf ($C \sim 0.55$, NO OSCILLATION IN H-BEAM, PROBABLY WRONG POSITION)

NEW H-DETECTOR POS: -58.5

ifg1-test-22 Sep 1855.inf ($C \sim 0.55$)~~23.9.2025~~

ifg1-3p 200s 22 Sep 1930 up to 73% locally

ifg2-3p 200s 22 Sep 2123

23.9.2025 ifm moved 3mm ↙

R0-23 Sep 0826, 0835

Aperture 2 from 15 to 17

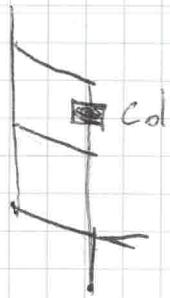
(ifg1-3p 200s-23 Sep 0837)

camera 3mm ↓

0854 $C \approx 70\%$ (PIXEL 5,5) $C \approx 78\%$ (PIXEL 3,3)

A bit of phase gradient





BLOCK PATH 1
iPg2-3P200s-B1-23 Sep 1203.inf

Intensity drift, probably peak drift.
Repeating the measurement.

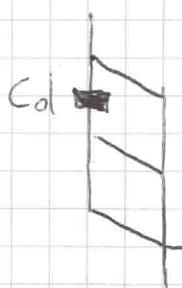
197

iPg2-3P200s-B1-23 Sep 1406.inf

Big phase gradient, placed just under IFM as last time (page 166).

TI LT SCAN (2 s ~~AUD FIT~~)

P_1	PEAK	H FWHM
-1.67	1182	0.000355 ✓
-1.64	1139	0.000379
-1.70	1106	0.000395



~~Robot~~ Robot prepared to block each path.

~~Robot~~ Robot diag pos:

PATH 1 → -10000, 30 deg rotation

PATH 2 → 10000, -30 deg rotation

PATH 3 → 45000, 30 deg rotation



Started IFG for each loop

24.09.2025

iPg2-3P200s-B1-24 Sep 0018.inf

iPg1-3P200s-B2-24 Sep 0211.inf

iPg2-3P200s-B2-24 Sep 0402.inf

iPg1-3P200s-B3-24 Sep 0555.inf

Overall good contrast and phase ~~misalignment~~

Unfortunately bumped robot with Col into ~~IFM~~ IFM.

Starting ~~again~~ again from scratch.

198 TILT SCAN (2 s H-DET)

P1	PEAK	FWHM	
-1.6	983	0.000376	✓
-1.65	866	0.000395	
-1.56	947	0.000367	
-1.58	954	0.000375	
-1.62	968	0.000367	

Piezo stopped working, somehow fixed it.
Starting again from scratch.

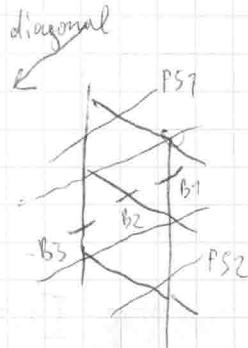
TILT SCAN (2 s H-DET)

P1	PEAK	FWHM	
-1.5	1076	0.000382	
-1.55	1031	0.000377	✓
-1.6	875	0.000456	

Robot re-prepared to block each path.

BLOCK PATH	ROBOT DIA#	ROT
1	-20000	30
2	-4000	-30
3	28000	30

Started IFG for each loop (120 s/point, hoping for two IFG each loop)



2nd loop ifg 2-3 pt 120s - B1 - 25 Sep 0055

b1, b2, b3
1st loop: 1 2 3

intensity high up

area of
good cond.

D



→ rocking failed B



B

2nd lamella?
PS1?

10 operun 2 moved to 15 (before: 17)

mono Lo Gran - 23 Sep 0838 → -1,25 (before: -1,1)
7800 cps (before 7500 cps)

199

11 A H mono Rel - 25 Sep 0842

31,01 (bef: 31,00)

0	3	Aux FWHM	in 2s
-1,05	0,000454	1239	
-1,1	347	1770	
-1,15	397	1833	
-1,20	37	1519	
-1,23	365	1828	

15 20 PS1 cleaned

- ifg1-3p120s-B2-25Sep0922 big loop ◻ low contrast area
ifg2-3p120s-B1-25Sep1045 second loop ◻
ifg1-3p120s-B3-25Sep1150 first loop ◻ low contrast area

Cleaned IFM, starting again.

TILT SCAN			AUX		
P1	PEAK	FWHM	PEAK	FWHM	
1000	800	0.000478	2000	0.000478	
-1,2	1063	0.000343	4084	0.000344	✓
-1,1	640	0.000609	2332	0.000627	
-1,3	860	0.000441	3227	0.000427	
-1.25	1017	0.000382	4050	0.000370	
-1.15	861	0.000453	3148	0.000448	
-1.22	1088	0.000381	4069	0.000418	
-1.11	981	0.000410	30909	0.000365	

ifg1-3p120s-B2-25Sep1545.inf

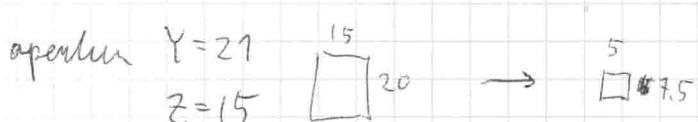
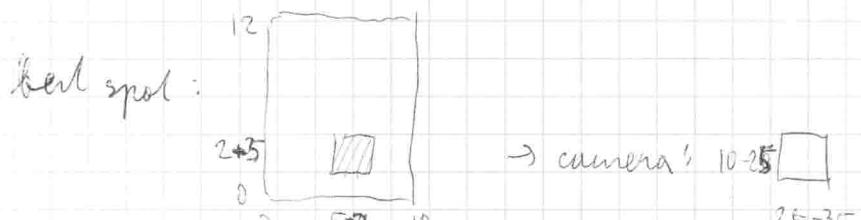


low contrast spot still there, moved IFM ↓



TILT SCAN (2 s)			AUX	
P1	PEAK	FWHM	PEAK	FWHM
200 - 1.2	196.5	0.000347	215.18	0.000360 ✓

Started measurements for each loop
26/09/2025 (FFG CAMERA)



~~Contrast~~ Contrast $\geq 60\%$. $\sim 65\%$ for all paths, good enough.

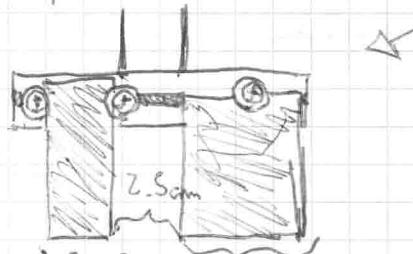
Prepared Col slit for beams position/thickness

robot-diag-slit-Col-90deg...inf

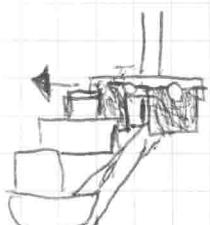
BEAM THICKNESS $\sim 7.5 \text{ mm}$.

ROBOT ROT BIG

Prepared double Col blocker



Scanned double Col blocker



robot-diag-double-Col-90deg...inf