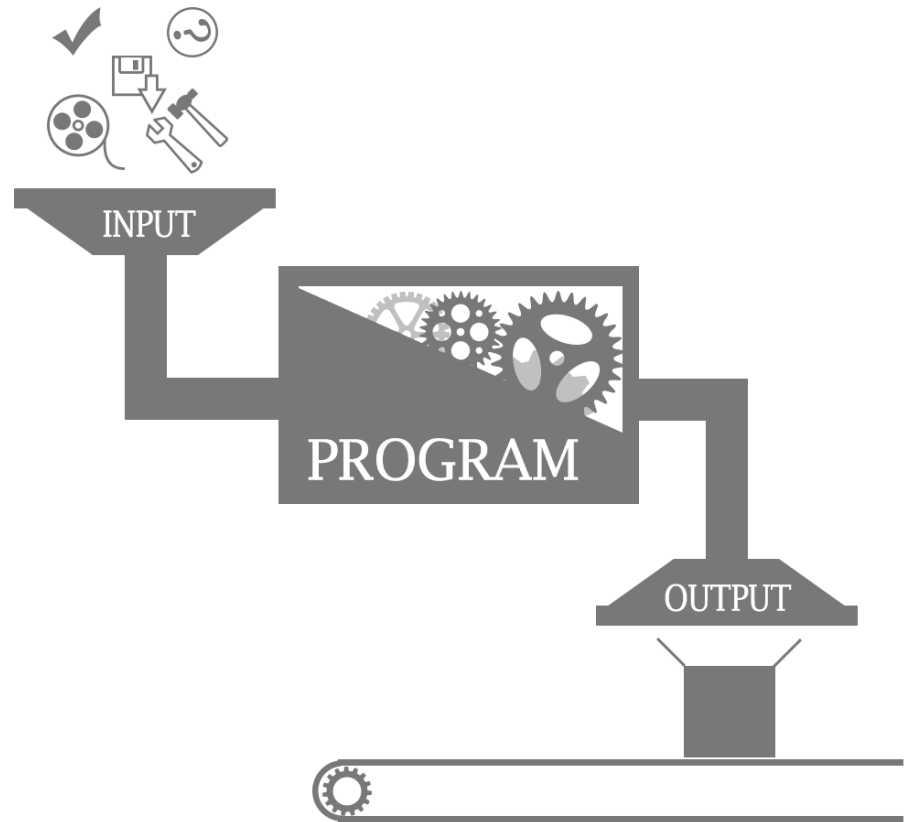


Draft Version

DSA\300 – Data Structures and
Algorithms with C#

Data Structures & Algorithms with C# – Lecture #7

Ahmed Mohyeldin



Lecture #7

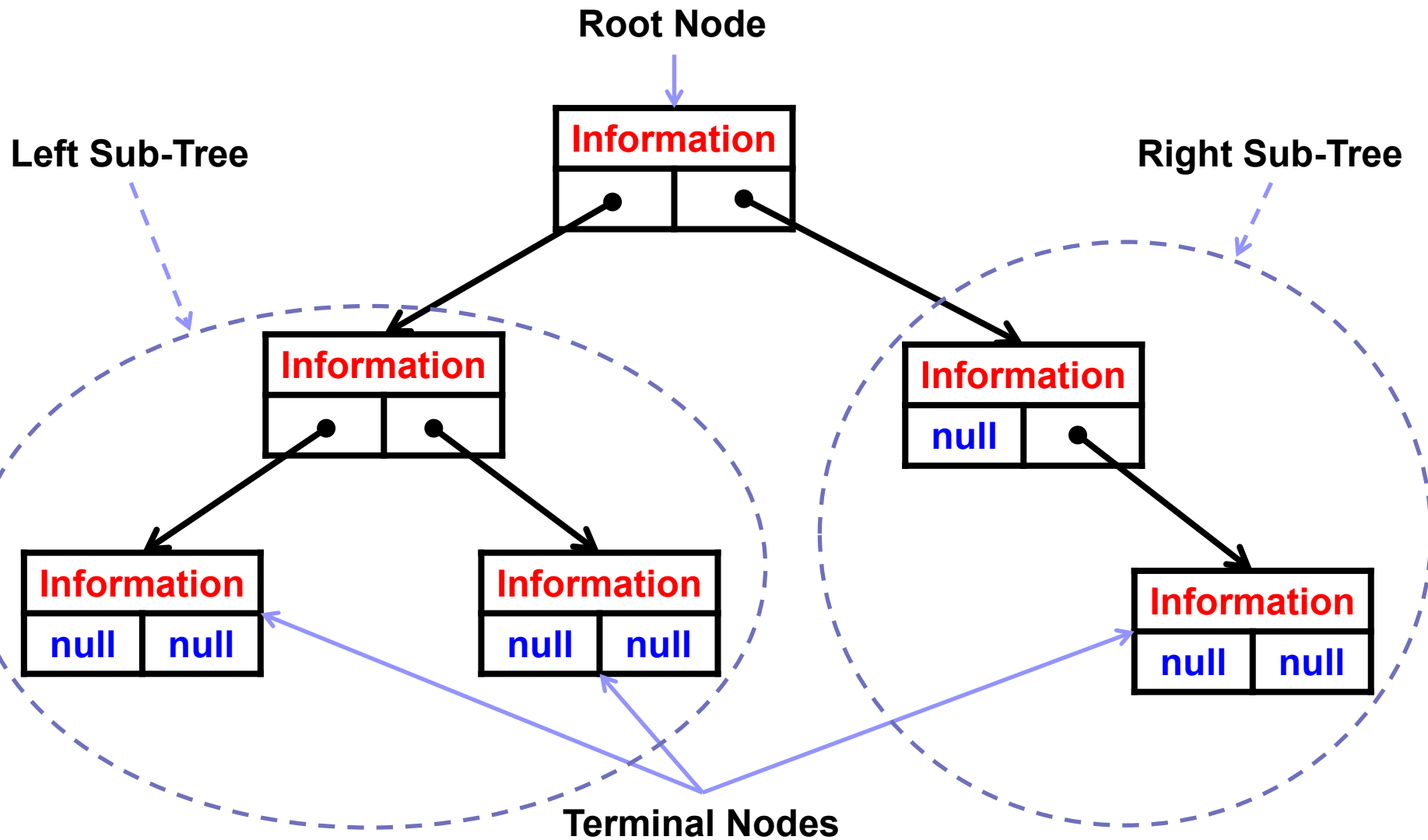
BINARY TREES

A Tree-Like Data Structure 😊

Binary Trees – The *What* ?

- A *Binary Tree* is a tree data structure in which each leaf (*i.e.*, node) has at most two children.
 - Typically the first node is known as the *Root Node* or *Parent Node*, and
 - The child nodes are called *Left Node* and *Right Node*.
- Although there can be many different types of Trees, *Binary Trees* are special because, when they are sorted, they lend themselves to rapid searches, insertions, and deletions.
 - Therefore, *Binary Trees* are commonly used to implement *Binary Search Trees* (BST) and *Binary Heaps* (BH).

Binary Trees – The *Structure* ?



A Sample Binary Tree of Height 3

Binary Trees –The *Terminology* ?

- The special terminology needed to discuss trees is a classic case of mixed metaphors:
 - *Node* (also called a *Leaf*) → is any data item in the tree.
 - *Root Node* (also called *Parent Node*) → is the first item in the tree.
 - *Subtree* → is any piece (*i.e.*, *Branch*) of thy tree.
 - *Terminal Node* → is a node that has no subtrees attached to it.
 - *Tree Height* → is equal to the number of layers deep that its root grows.

Binary Trees –The *Representation* ?

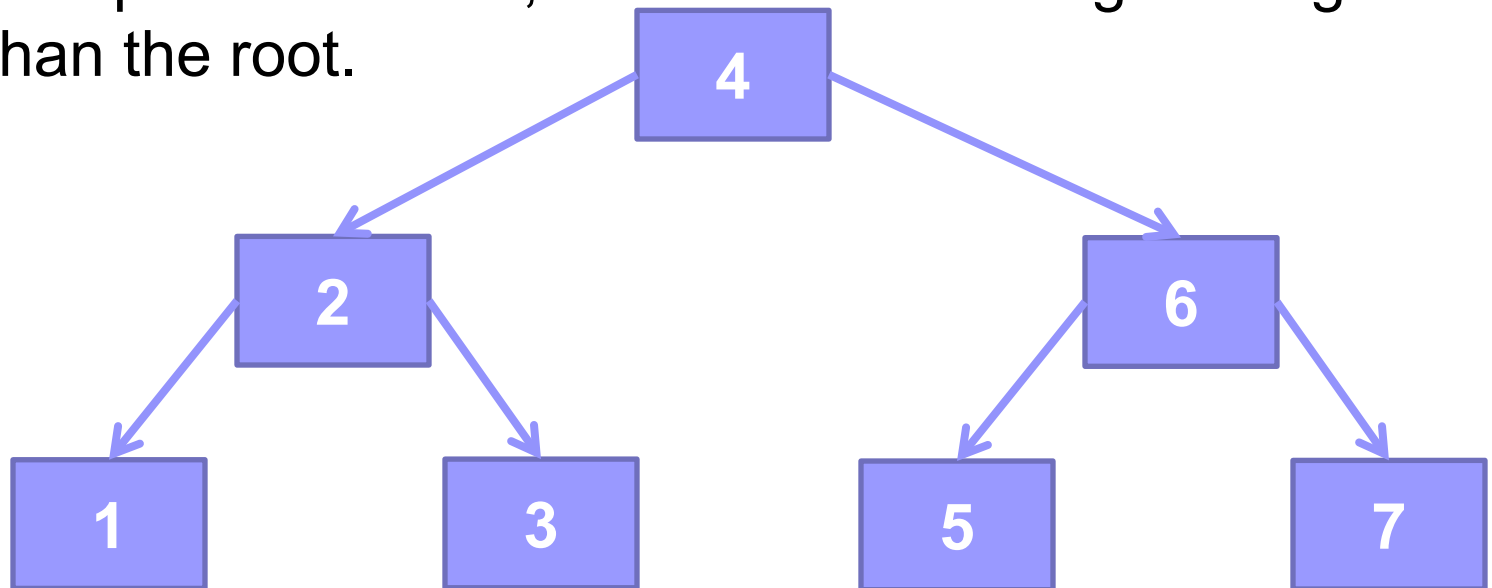
■ Representation of Binary Trees

- Logically, one can think of binary trees as appearing in memory as they do on paper, but remember that a tree is only a way to structure data in memory, which is linear in form.
- The *Binary Tree* is a special form of *Linked List*
 - Items can be inserted, deleted, and accessed in any order.
 - Also, the retrieval operation is nondestructive.

Binary Trees – The *Sorted Binary Trees* ?

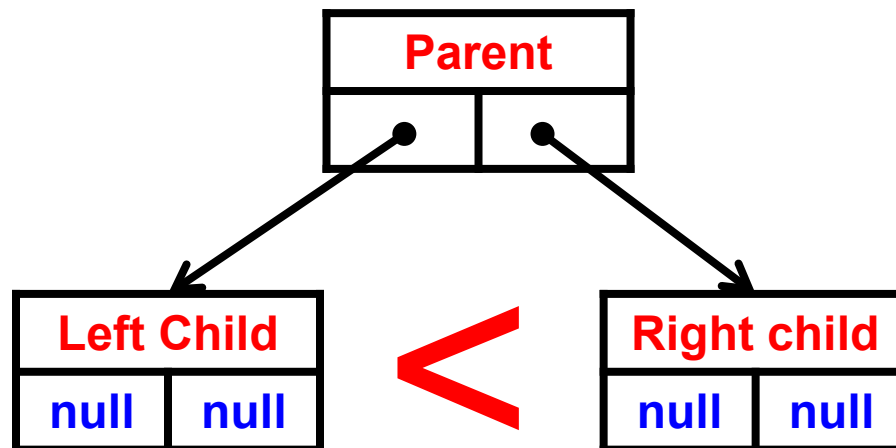
■ *Sorted Binary Tree* → *Binary Search Tree*

- Although a tree need not be sorted, most uses require it. What constitutes a sorted binary tree depends on how it will be traversed. The rest of this discussion assumes *inorder traversing*.
- Therefore, a *Sorted Binary Tree* is one where the subtree on the left contains nodes that are less than or equal to the root, and those on the right are greater than the root.



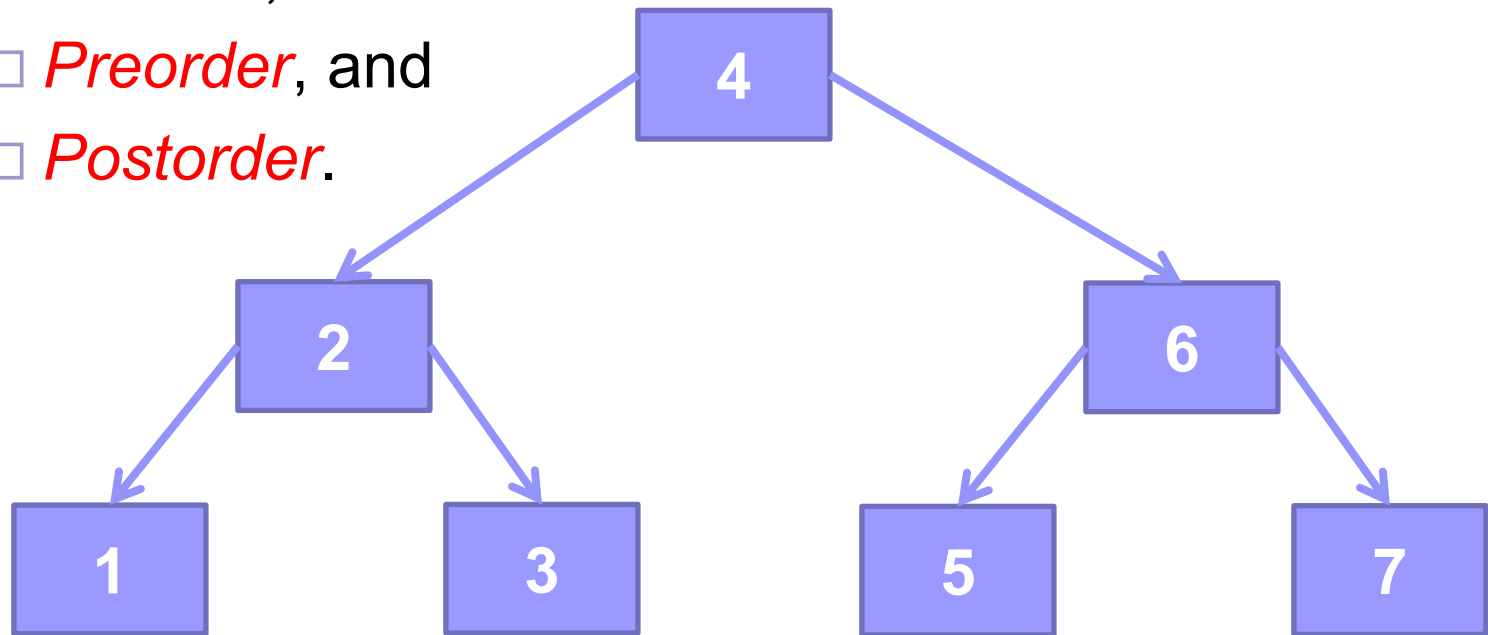
BSTs –The *Structure* (a formal definition)?

- A *Binary Search Tree* (*BST*) is a special kind of binary tree that exhibit the following property: for any node *n*, every descendant node's value in the left subtree of *n* is less than the value of *n*, and every descendant node's value in the right subtree is greater than the value of *n*.
 - *BST*s are designed this way to improve the efficiency of searching through the contents of a binary tree.



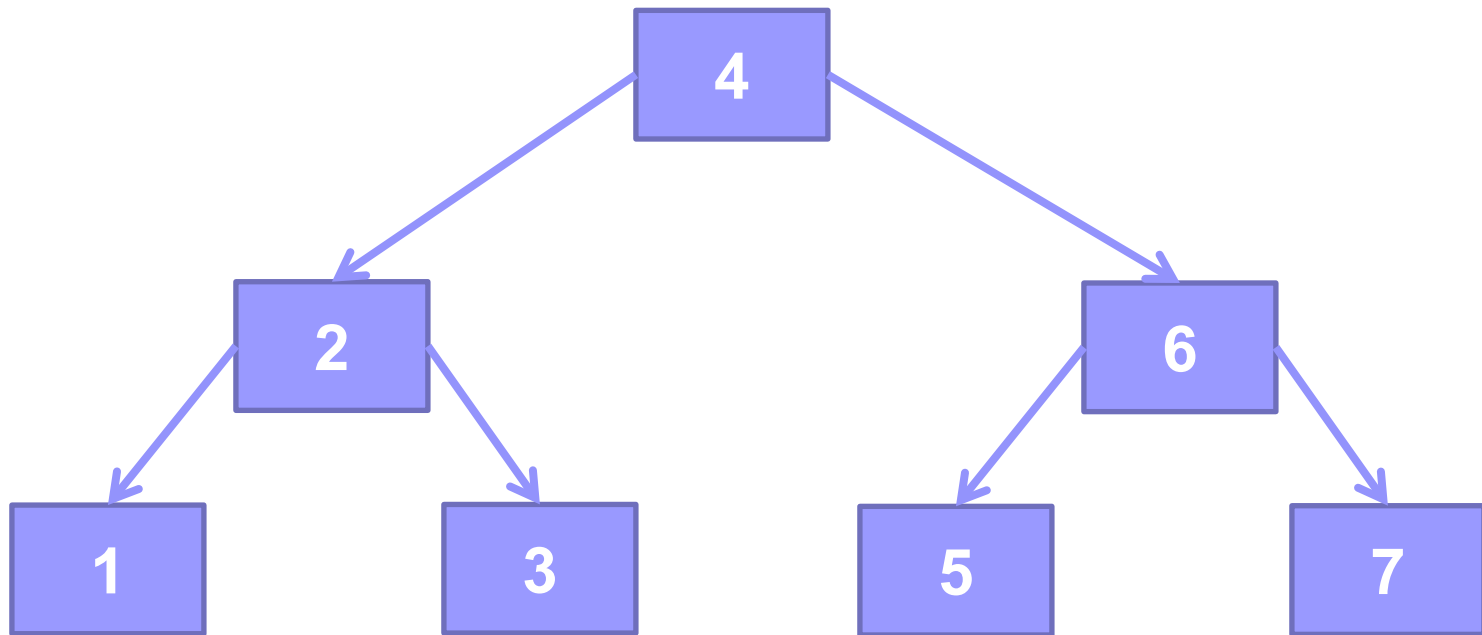
BSTs –The *Traversing* Methods?

- *Traversal of a Tree* is the process of accessing each node in the tree in specific sequence.
- How a tree is ordered depends on how it is going to be accessed. Generally, there are three ways to traverse a tree:
 - *Inorder*,
 - *Preorder*, and
 - *Postorder*.



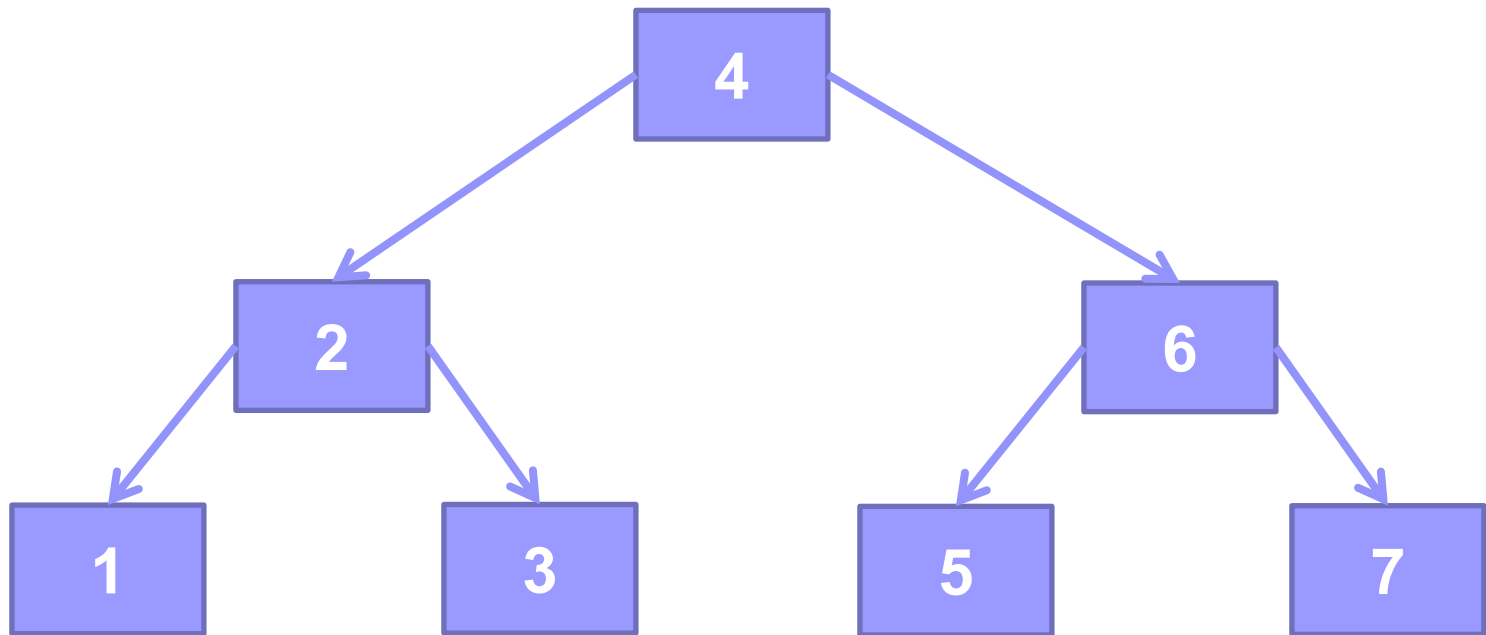
BSTs – The *Inorder Traversal* Method?

- To Traverse a **BSTs** using *Inorder Traversal*:
 - You visit the left subtree, the root, and then the right subtree.
- Example:
 - Inorder Accessing Sequence: 1 2 3 4 5 6 7



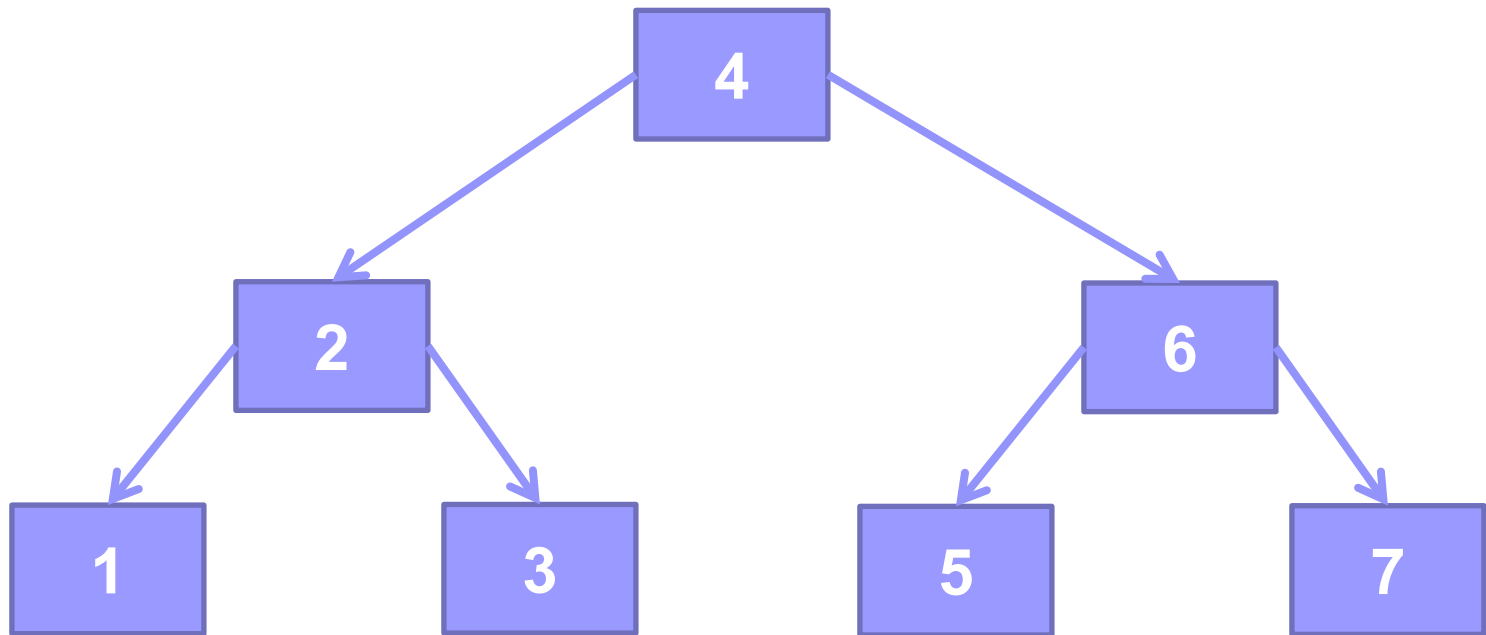
BSTs – The *Preorder Traversal* Method?

- To Traverse a **BSTs** using *Preorder Traversal*:
 - You visit the root, the left subtree and then the right subtree.
- Example:
 - Preorder Accessing Sequence: 4 2 1 3 6 5 7



BSTs – The *Postorder Traversal* Method?

- To Traverse a **BSTs** using *Postorder Traversal*:
 - You visit the left subtree, the right subtree, and then the root.
- Example:
 - Postorder Accessing Sequence: 1 3 2 5 7 6 4



BSTs – The *Operations* ?

- The primary operations that can be performed on a binary tree are:
 - *Creating a Tree* (i.e., *Inserting* New Nodes)
 - *Case 1*: insert root node.
 - *Case 2*: insert a leaf node.
 - *Traversing* the Tree
 - *Method 1*: Inorder.
 - *Method 2*: Preorder.
 - *Method 3*: Postorder.
 - *Deleting* Nodes
 - *Case 1*: delete a root node.
 - *Case 2*: delete a leaf node with one subtree.
 - *Case 3*: delete a leaf node with two subtree.
 - *Searching* for a particular Node.

Binary Trees – The *Construction* ?

- The required steps for building a binary tree are:
 - Step #1 → Node element definition.
 - Step #2 → Initializing the empty tree root pointer.
 - Step #3 → Adding nodes (leaves).
 - Step #4 → Traversing the tree.
 - Step #4(a) → Traversing the tree inorder.
 - Step #4(b) → Traversing the tree preorder.
 - Step #4(c) → Traversing the tree postorder.
 - Step #5 → Searching for a node.
 - Step #6 → Deleting nodes.
 - Step #7 → Removing the entire tree.

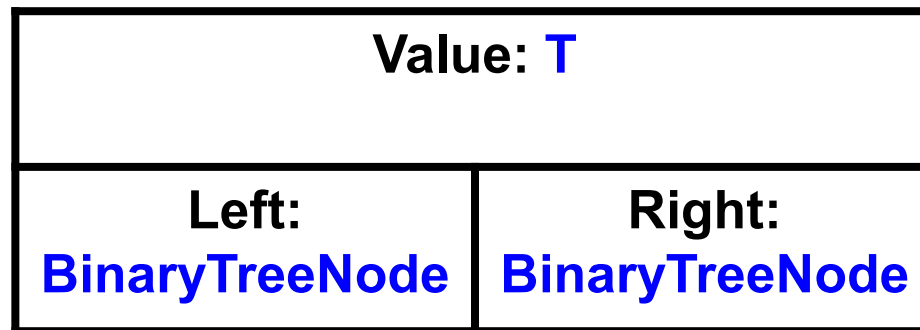
BTs – The *BinaryTree*<T> Class?

OOP Implementation

Basic object-oriented modelling and implementation of the "*Binary Tree*" data structure – The *BinaryTree*<T> and *BinaryTreeNode*<T> generic classes.

BTs – The *BinaryTreeNode*<T> Class?

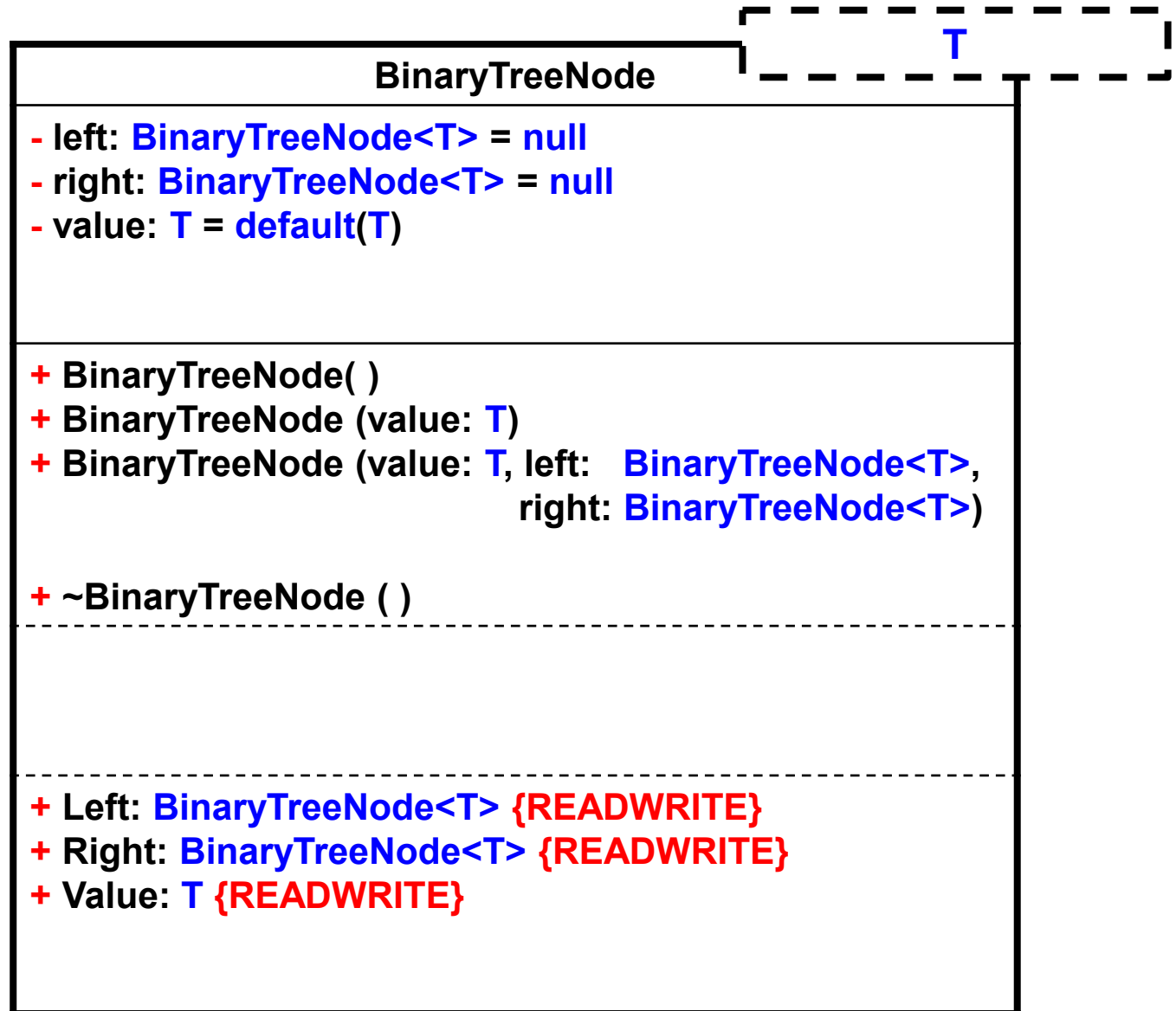
BinaryTreeNode<T>
Logical View
(Basic Version)



BTs – The *BinaryTreeNode*<T> Class?



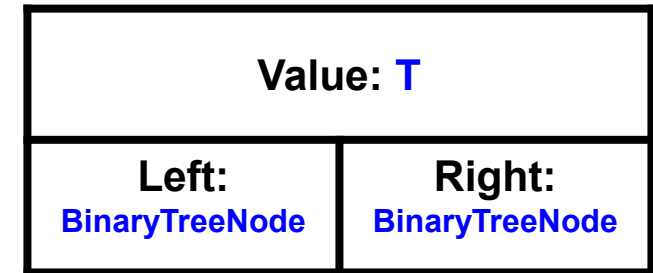
BinaryTreeNode<T>
Class
Diagram
(Basic Version)



BTs – The *BinaryTreeNode<T>* Class?

(...cont'd)

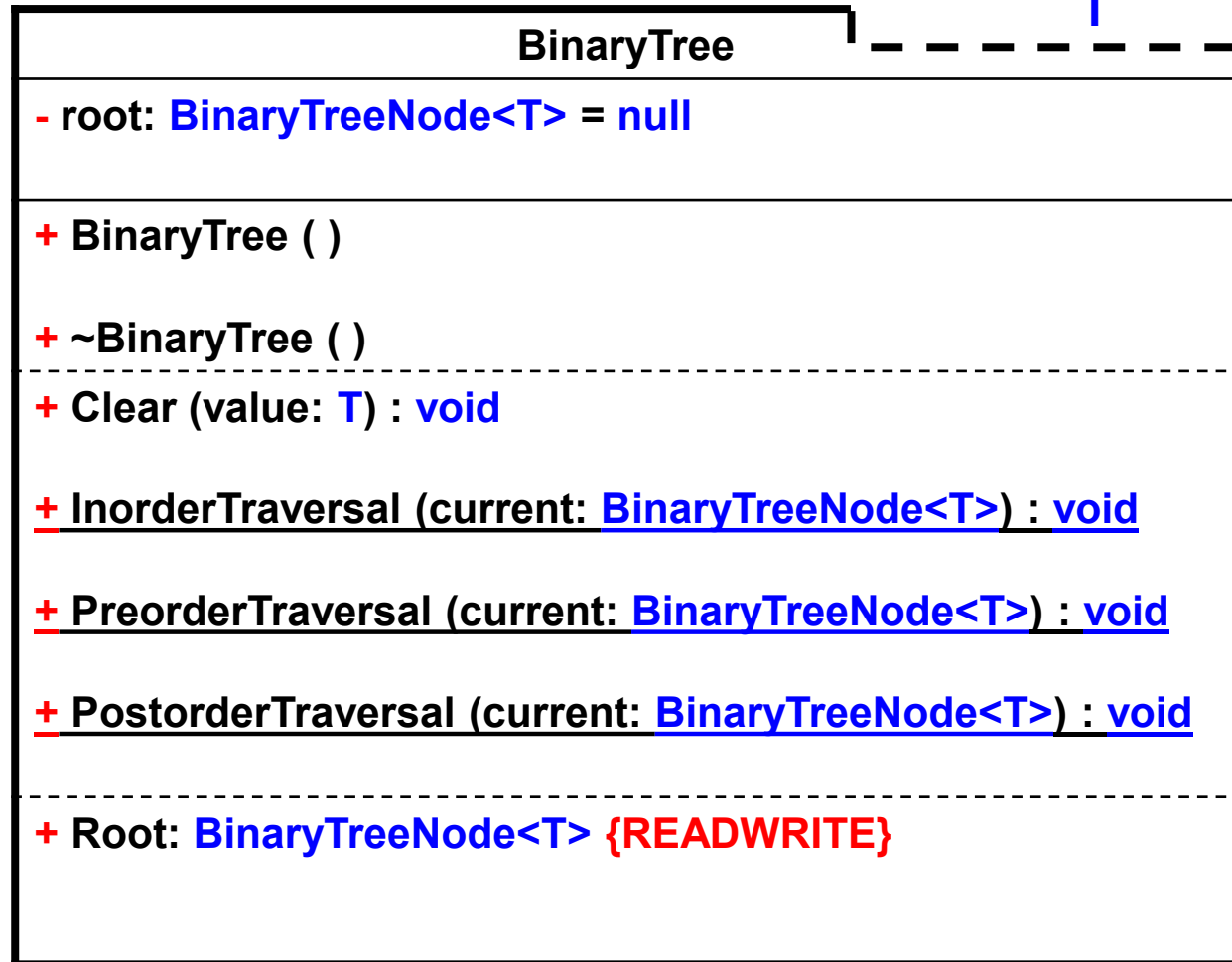
```
1 // Example: Binary Tree Data Structure - BinaryTreeNode<T>.
2 using System;
3
4 namespace Mohyeldin.DSA
5 {
6     public sealed class BinaryTreeNode<T>
7     {
8         public BinaryTreeNode( )
9         { // TODO: ... }
10        public BinaryTreeNode(T value)
11        { // TODO: ... }
12        internal BinaryTreeNode(T value, BinaryTreeNode<T> left,
13                                   BinaryTreeNode<T> right)
14        { // TODO: ... }
15
16        public T Value { get; set; } = default(T);
17
18        public BinaryTreeNode<T> Left { get; internal set; } = null;
19
20        public BinaryTreeNode<T> Right {get; internal set;} = null;
21        // TODO: Any other enhancements may be added here...
22    }
23 } /* (^_^) The BT Node Class Definition - Basic Version. (^_^) */
24
```



BTs – The *BinaryTree*<T> Class?



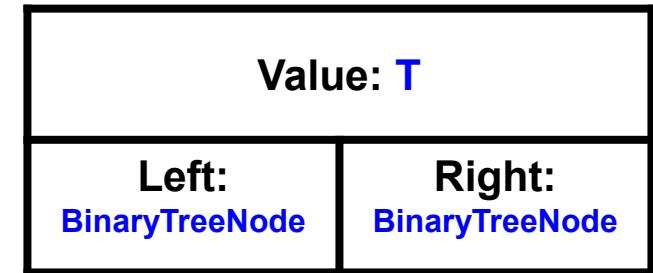
BinaryTree<T>
Class
Diagram
(Basic Version)



BTs – The *BinaryTree<T>* Class?

(...cont'd)

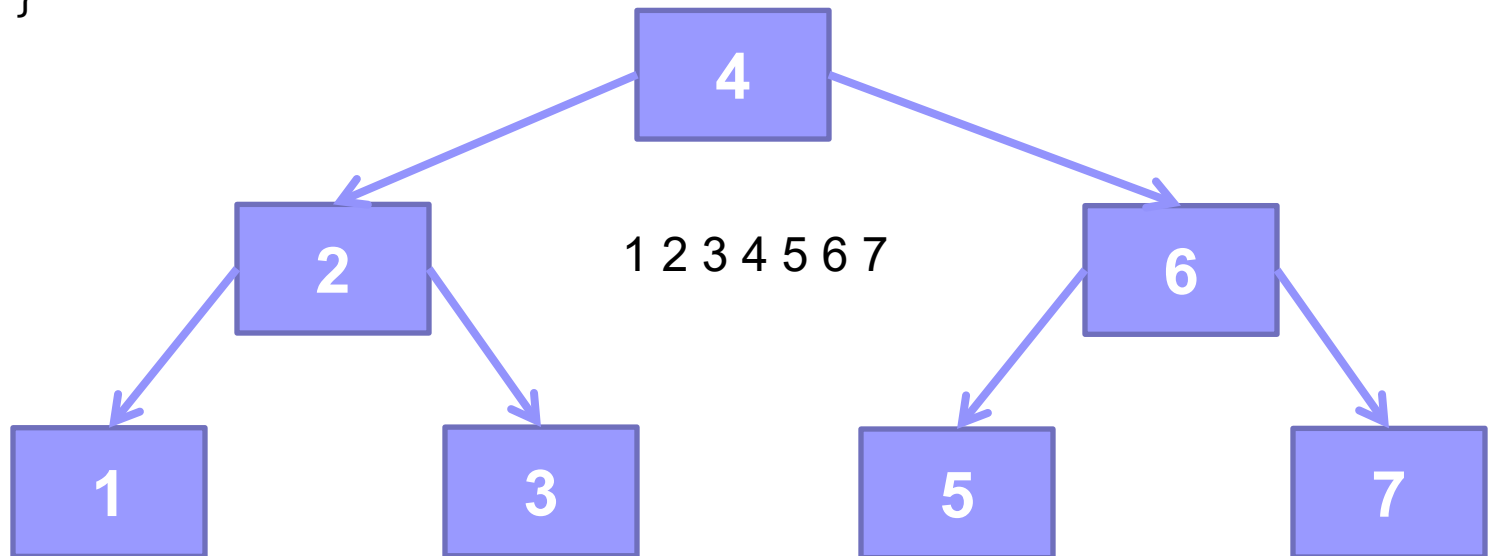
```
1 // Example: Binary Tree Data Structure - BinaryTree<T>.
2 using System;
3
4 namespace Mohyeldin.DSA
5 {
6     public class BinaryTree<T>
7     {
8         public BinaryTree( ) { Root = null; }
9
10        public virtual void Clear() { Root = null; }
11
12        public static void InorderTraversal(BinaryTreeNode<T> current)
13        { // TODO: ... }
14        public static void PreorderTraversal(BinaryTreeNode<T> current)
15        { // TODO: ... }
16        public static void PostorderTraversal(BinaryTreeNode<T> current)
17        { // TODO: ... }
18
19        public BinaryTreeNode<T> Root {get; internal set;} = null;
20
21        // TODO: Any other enhancements may be added here...
22    }
23 }/* (^_^) The Binary Tree Class Definition - Basic Version. (^_^) */
24
```



BTs – The *BinaryTree<T>* Class?

(...cont'd)

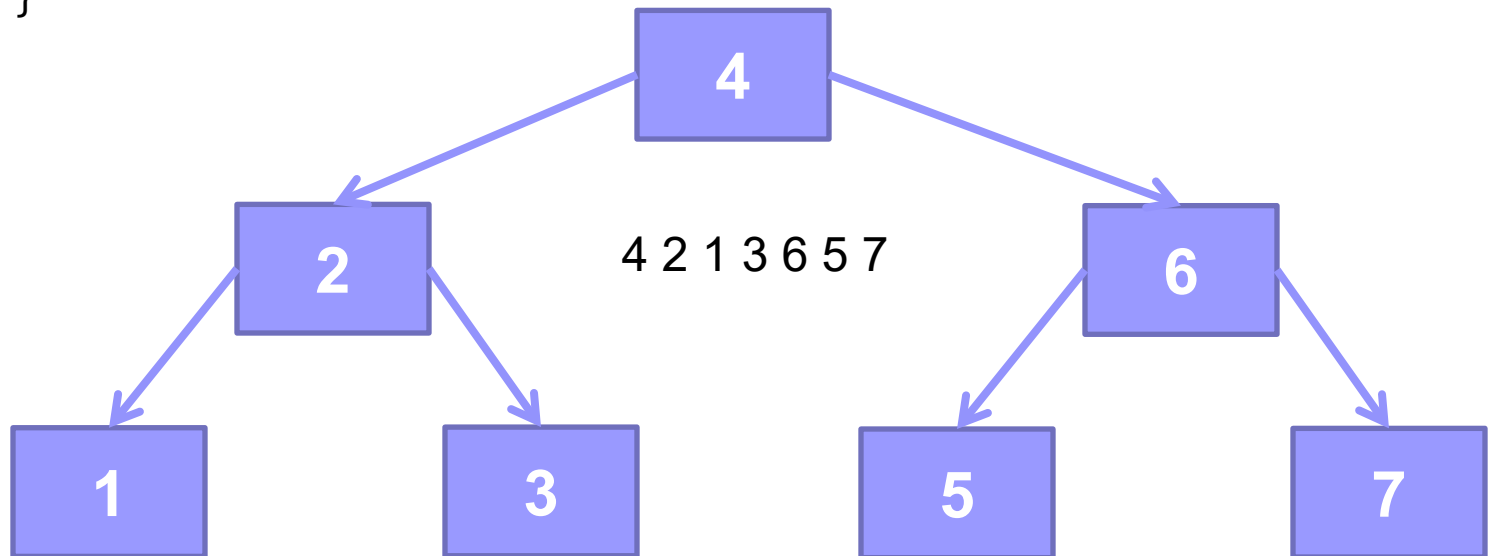
```
1 // InorderTraversal( ) - Performs an inorder traversal of a binary
2   tree, given a "BinaryTreeNode<T>" as the root node.
3 public static void InorderTraversal(BinaryTreeNode<T> current)
4 {
5     if (current != null)
6     {
7         // Visit the left child... (a recursive process!).
8         InorderTraversal(current.Left);
9         // Visit the node (Output the value of the current node).
10        Console.WriteLine(current.Value);
11        // Visit the right child... (a recursive process!).
12        InorderTraversal(current.Right);
13    }
14 }
```



BTs – The *BinaryTree*<T> Class?

(...cont'd)

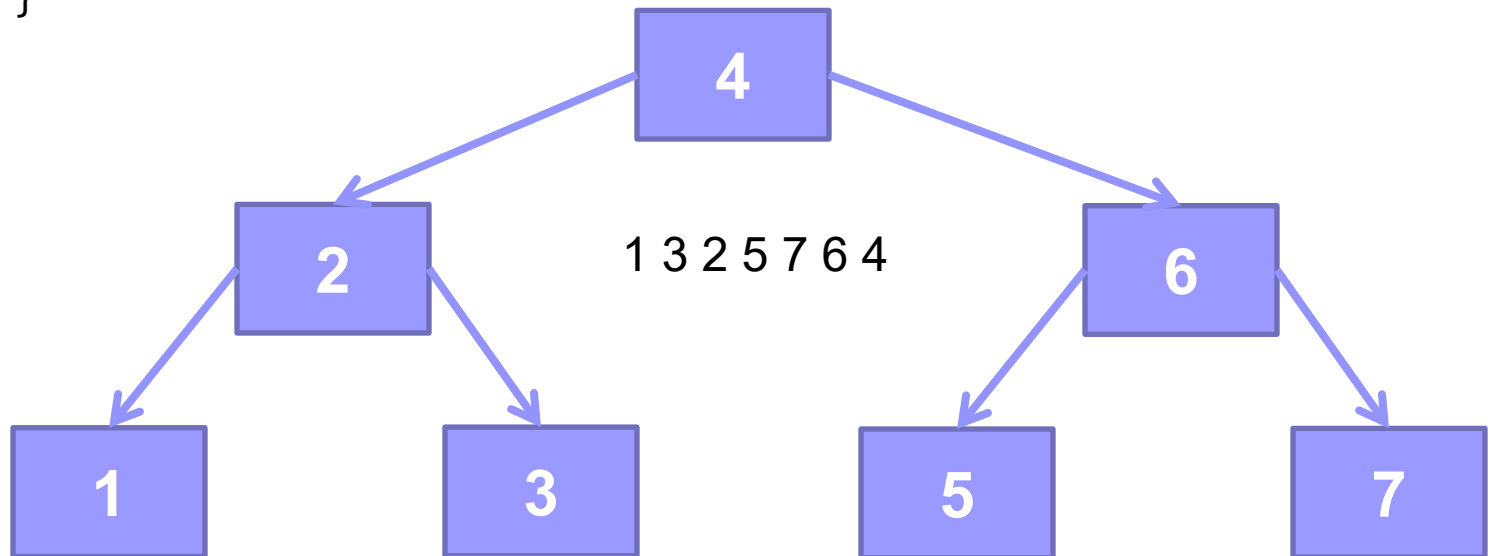
```
1 // PreorderTraversal( ) - Performs a preorder traversal of a binary
2   tree, given a "BinaryTreeNode<T>" as the root node.
3 public static void PreorderTraversal(BinaryTreeNode<T> current)
4 {
5     if (current != null)
6     {
7         // Output the value of the current node.
8         Console.WriteLine(current.Value);
9
10        // Recursively print the left and right children.
11        PreorderTraversal(current.Left);
12        PreorderTraversal(current.Right);
13    }
14 }
```



BTs – The *BinaryTree*<T> Class?

(...cont'd)


```
1 // PostorderTraversal( )- Performs a postorder traversal of a binary
2   tree, given a "BinaryTreeNode<T>" as the root node.
3 public static void PostorderTraversal(BinaryTreeNode<T> current)
4 {
5     if (current != null)
6     {
7         // Visit the left child... (a recursive process!).
8         PostorderTraversal(current.Left);
9         // Visit the right child... (a recursive process!).
10        PostorderTraversal(current.Right);
11        // Visit the node (Output the value of the current node).
12        Console.WriteLine(current.Value);
13    }
14 }
```



BTs – The *BinaryTree<T>* Class?

(...cont'd)

```
1  // Binary Tree Data Structure - BinaryTree<T> Class.
2
3
4
5
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7
8
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10
11
12
13
14
15
16
17
18
19
20 // TODO: Write a C# generic classes that implements the BT data
21 // structure ("BinaryTree<T>" and "BinaryTreeNode<T>") UML class
22 // diagrams with a complete "Test Driver" to demonstrate using the
23 // different binary tree traversal( ) methods.
24
```



DEMO



Object-Oriented Implementation of Binary-Trees in C# –
The `BinaryTree<T>` Generic Class.

BSTs – The *BinarySearchTree<T>* Class?

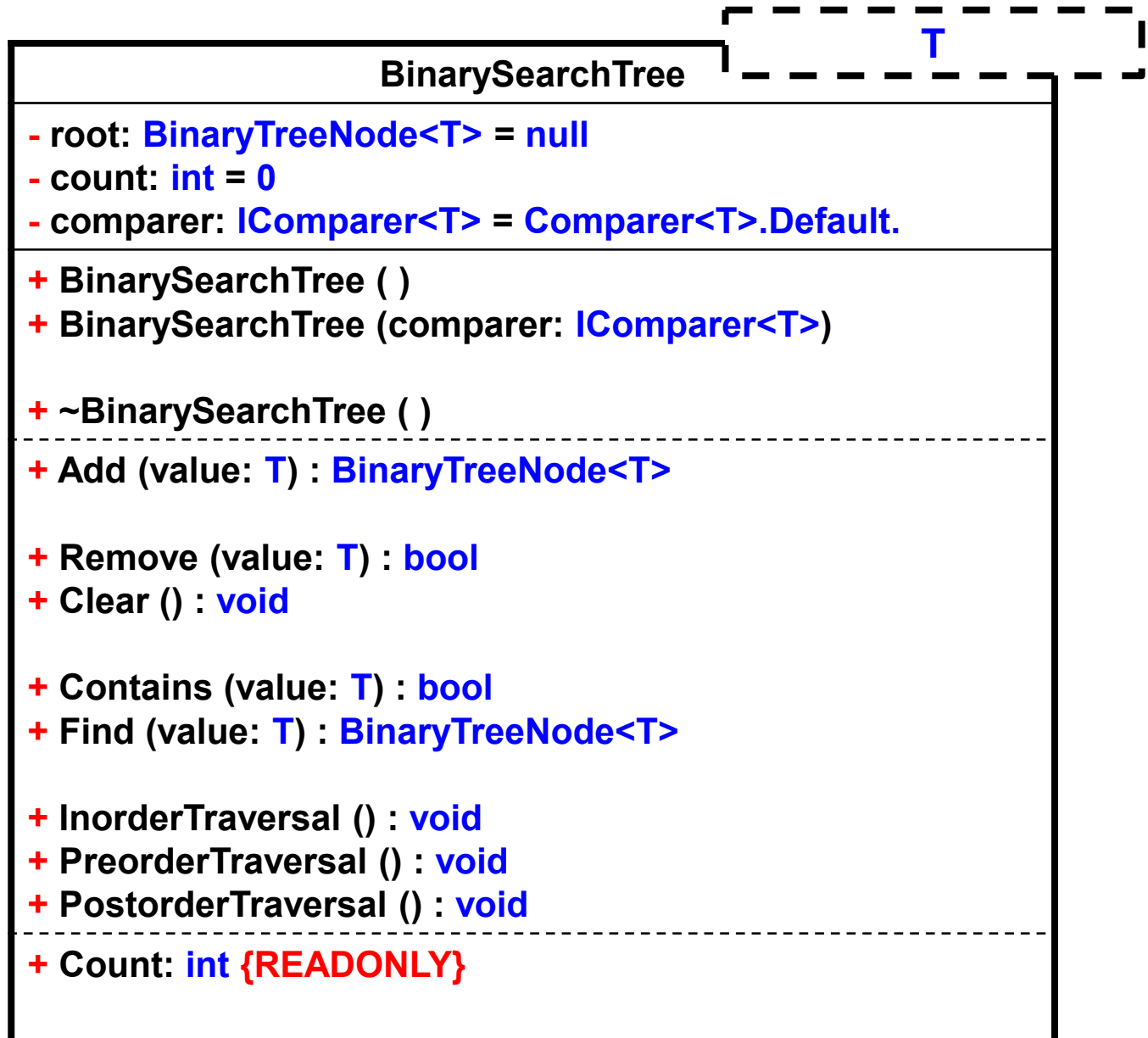
OOP Implementation

Basic object-oriented modelling and implementation of the "*Binary Search Tree*" data structure – The *BinarySearchTree<T>* and *BinaryTreeNode<T>* generic classes.

BSTs – The *BinarySearchTree<T>* Class?

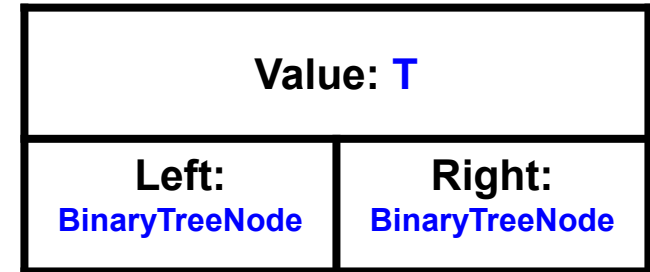


BinarySearchTree<T>
Class
Diagram
(Basic Version)



BSTs – The *BinarySearchTree<T>* Class? (...cont'd)

```
1 // Example: Binary Tree Data Structure - BinarySearchTree<T>.
2 using System;
3
4 namespace Mohyeldin.DSA
5 {
6     public class BinarySearchTree<T>
7     {
8         public BinarySearchTree( ) { // TODO: ... }
9         public BinarySearchTree(IComparer<T> comparer) { // TODO: ... }
10
11         public BinaryTreeNode<T> Add(T value) { // TODO: ... }
12         public bool Remove(T value) { // TODO: ... }
13         public virtual void Clear() { // TODO: ... }
14         public bool Contains(T value) { // TODO: ... }
15         public BinaryTreeNode<T> Find(T value) { // TODO: ... }
16
17         public void InorderTraversal() { // TODO: ... }
18         public void PreorderTraversal() { // TODO: ... }
19         public void PostorderTraversal() { // TODO: ... }
20         public int Count {get; private set;} = 0;
21         // TODO: Any other enhancements may be added here...
22     }
23 } /* (^_^) The BST Class Definition – Basic Version. (^_^) */
24
```



BSTs – The *Add(T value)* Method (1/3)?

(...cont'd)

```
1 // Add( ) - Adds a new node containing the specified value to the
2 //           BinarySearchTree<T> --- Iterative implementation(1/3).
3 public virtual BinaryTreeNode<T> Add(T value)
4 {
5     // Create a new node instance.
6     BinaryTreeNode<T> node = new BinaryTreeNode<T>(value);
7     int result;
8
9     // Now, insert node into the tree
10    // trace down the tree until we hit a NULL
11    BinaryTreeNode<T> current = root, parent = null;
12    while (current != null)
13    {
14        result = comparer.Compare(current.Value, value);
15        if (result == 0)
16            // They are equal - attempting to enter a duplicate - do
17            // nothing.
18            return null;
19        else if (result > 0)
20        {
21            // Current.Value > value, must add node to current's
22            // left subtree.
23
24            // continued...
```

BSTs – The *Add(T value)* Method (2/3)?

(...cont'd)

```
1 // Add( ) - Adds a new node containing the specified value to the
2 //           BinarySearchTree<T> --- Iterative implementation(2/3).
3
4         parent = current;
5         current = current.Left;
6     }
7     else if (result < 0)
8     {
9         // Current.Value < value, must add node to current's
10        // right subtree.
11        parent = current;
12        current = current.Right;
13    }
14 }
15
16 // We're ready to add the node!
17 count++;
18 if (parent == null)
19 {
20     // The tree was empty, make node the root.
21     root = node;
22 }
23
24                                     // continued...
```

BSTs – The *Add(T value) Method* (3/3)?

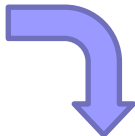
(...cont'd)

```
1 // Add( ) - Adds a new node containing the specified value to the
2 //           BinarySearchTree<T> --- Iterative implementation(3/3).
3     else
4     {
5         result = comparer.Compare(parent.Value, value);
6         if (result > 0)
7             // parent.Value > value, therefore node must be added to
8             // the left subtree.
9             parent.Left = node;
10        else
11            // parent.Value < value, therefore node must be added to
12            // the right subtree.
13            parent.Right = node;
14    }
15
16    return node; // Return the node containing the value.
17 }
18
19 /*(^_^) The BinarySearchTree.Add(T value) operation is done (^_^).*/
20
21
22
23
24
```

BSTs – The *Add(T value) Recursive* (1/2)? (...cont'd)

```
1 // Add( ) - Adds a new node containing the specified value to the
2 //           BinarySearchTree<T> --- Non-recursive public wrapper.
3 public virtual BinaryTreeNode<T> Add(T value)
4 {
5     return root = Add(root, value);
6 }
7
8 // Add( ) - Adds a new node containing the specified value to the
9 //           BinarySearchTree<T> --- Recursive implementation(1/2).
10 private BinaryTreeNode<T> Add(BinaryTreeNode<T> node, T value)
11 {
12     if (node == null)
13     {
14         node = new BinaryTreeNode<T>(value);
15         count++;
16     }
17     else
18     {
19         int result = comparer.Compare(node.Value, value);
20         if (result > 0)
21         {
22             node.Left = Add(node.Left, value);
23         }
24     }
25 }
```

Recursive Implementation




// continued...

BSTs – The *Add(T value) Recursive* (2/2)? (...cont'd)

```
1 // Add( ) - Adds a new node containing the specified value to the
2 //           BinarySearchTree<T> --- Recursive implementation(2/2).
3
4     else if (result < 0)
5     {
6         node.Right = Add(node.Right, value);
7     }
8
9     else
10    {
11        throw new ArgumentException("Duplicate node.",
12                                    nameof(value));
13    }
14 }
15
16 return node;
17 }
18
19 /*(^_^) The BinarySearchTree.Add(T value) operation is done (^_^).*/
20
21
22
23
24
```

BSTs – The *BinarySearchTree<T>* Class? (...cont'd)

```
1  // Binary Search Tree Data Structure - BinarySearchTree<T> Class.
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16
17
18
19
20 // TODO: Write a C# generic classes that implements the BST data
21 // structure (BinarySearchTree<T> and BinaryTreeNode<T>) UML class
22 // diagrams with a complete "Test Driver" to demonstrate using the
23 // different binary search tree traversal( ) methods.
24
```



DEMO



Object-Oriented Implementation of Binary-Search Trees
in C# – The `BinarySearchTree<T>` Generic Class.

BSTs – The *BinarySearchTree<T>* Class?

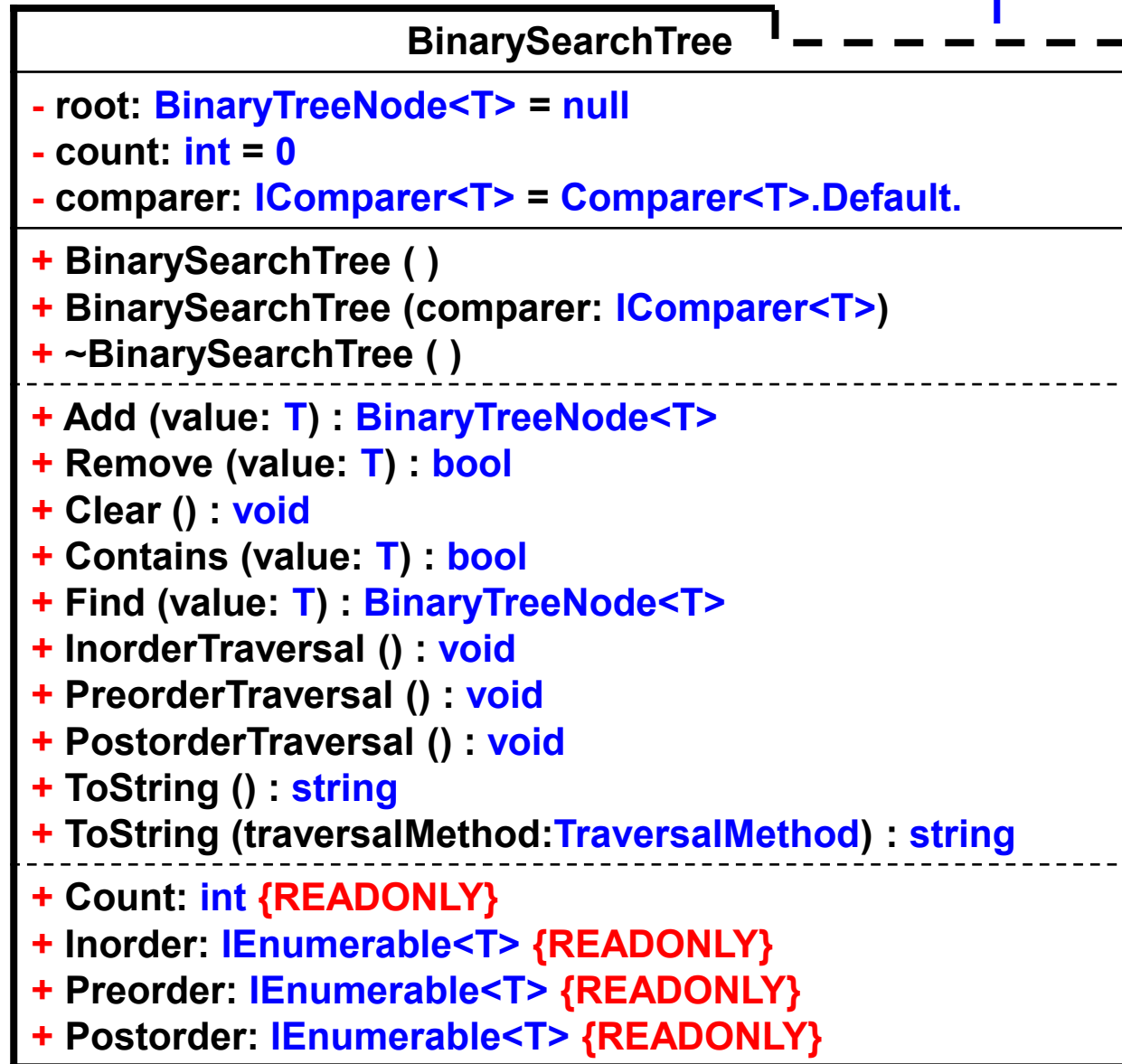
OOP Implementation

Enhanced object-oriented modelling and implementation of the "*Binary Search Tree*" data structure – The *BinarySearchTree<T>* and *BinaryTreeNode<T>* generic classes.

BSTs – The *BinarySearchTree<T>* Class?

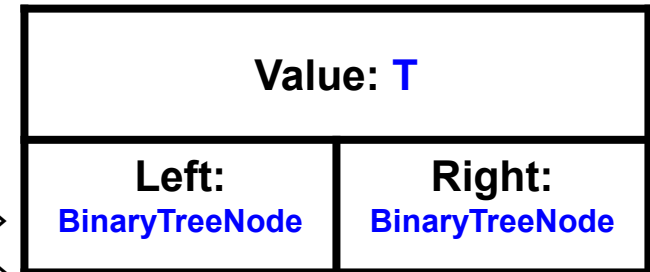


BinarySearchTree<T>
Class
Diagram
(Enhanced Version)



BSTs – The *BinarySearchTree<T>* (1/2)? (...cont'd)

```
1 // Example: Binary Tree Data Structure - BinarySearchTree<T> (1/2).
2 using System;
3
4 namespace Mohyeldin.DSA
5 {
6     public sealed class BinarySearchTree<T>
7         : ICollection<T>, IEnumerable<T>
8     {
9         public BinarySearchTree( ) { // TODO: ... }
10        public BinarySearchTree(IComparer<T> comparer) { // TODO: ... }
11
12        public BinaryTreeNode<T> Add(T value) { // TODO: ... }
13        public bool Remove(T value) { // TODO: ... }
14        public virtual void Clear() { // TODO: ... }
15
16        public bool Contains(T value) { // TODO: ... }
17        public BinaryTreeNode<T> Find(T value) { // TODO: ... }
18
19        public void InorderTraversal() { // TODO: ... }
20        public void PreorderTraversal() { // TODO: ... }
21        public void PostorderTraversal() { // TODO: ... }
22
23
24
```



// continued...

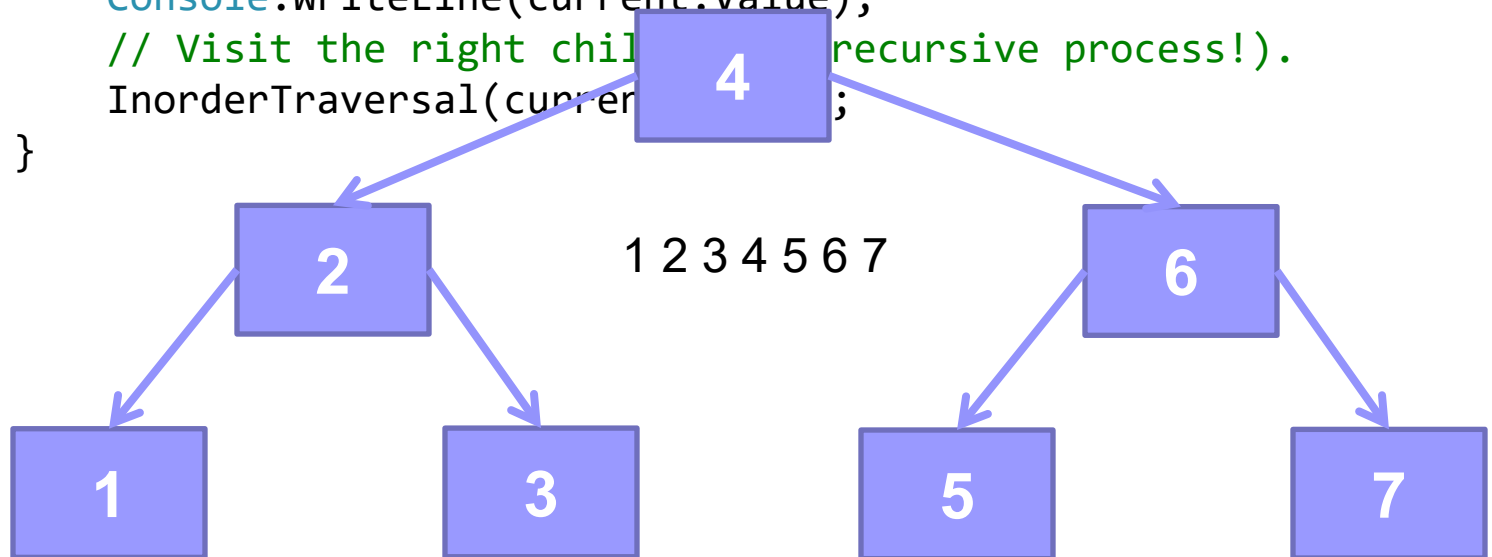
BST – The *BinarySearchTree<T>* (2/2)?

(...cont'd)

```
25 // Example: Binary Tree Data Structure - BinarySearchTree<T> (2/2).
26     public override string ToString() { // TODO: ... }
27     public string ToString(TraversalMethod traversalMethod)
28     { // TODO: ... }
29
30     public virtual IEnumerator<T> GetEnumerator() { // TODO: ... }
31     public virtual IEnumerator<T> GetEnumerator(TraversalMethod
32                                     TraversalMethod) { // TODO: ... }
33     IEnumerator IEnumerable.GetEnumerator() { // TODO: ... }
34
35     public int Count {get; private set;} = 0;
36
37     public IEnumerable<T> Inorder {get { // TODO: ... }}
38     public IEnumerable<T> Preorder {get { // TODO: ... }}
39     public IEnumerable<T> Postorder {get { // TODO: ... }}
40
41     // TODO: Any other enhancements may be added here...
42 }
43 } /* (^_^) The BST Class Definition - Enhanced Version. (^_^) */
44
45
46
47
48
```

BTs – The *BinaryTree*<T> Class? (Note1) (...cont'd)

```
1 // InorderTraversal( ) - Performs an inorder traversal of a binary
2   tree, given a "BinaryTreeNode<T>" as the root node.
3 public void InorderTraversal() {// Call: bTree.InorderTraversal();
4     InorderTraversal(root);
5 }
6 private static void InorderTraversal(BinaryTreeNode<T> current)
7 {
8     if (current != null)
9     {
10         // Visit the left child... (a recursive process!).
11         InorderTraversal(current.Left);
12         // Visit the node (Output the value of the current node).
13         Console.WriteLine(current.Value);
14         // Visit the right child... (a recursive process!).
15         InorderTraversal(current.Right);
16     }
17 }
```



Nodes – The *Node<T>* Classes Hierarchy?

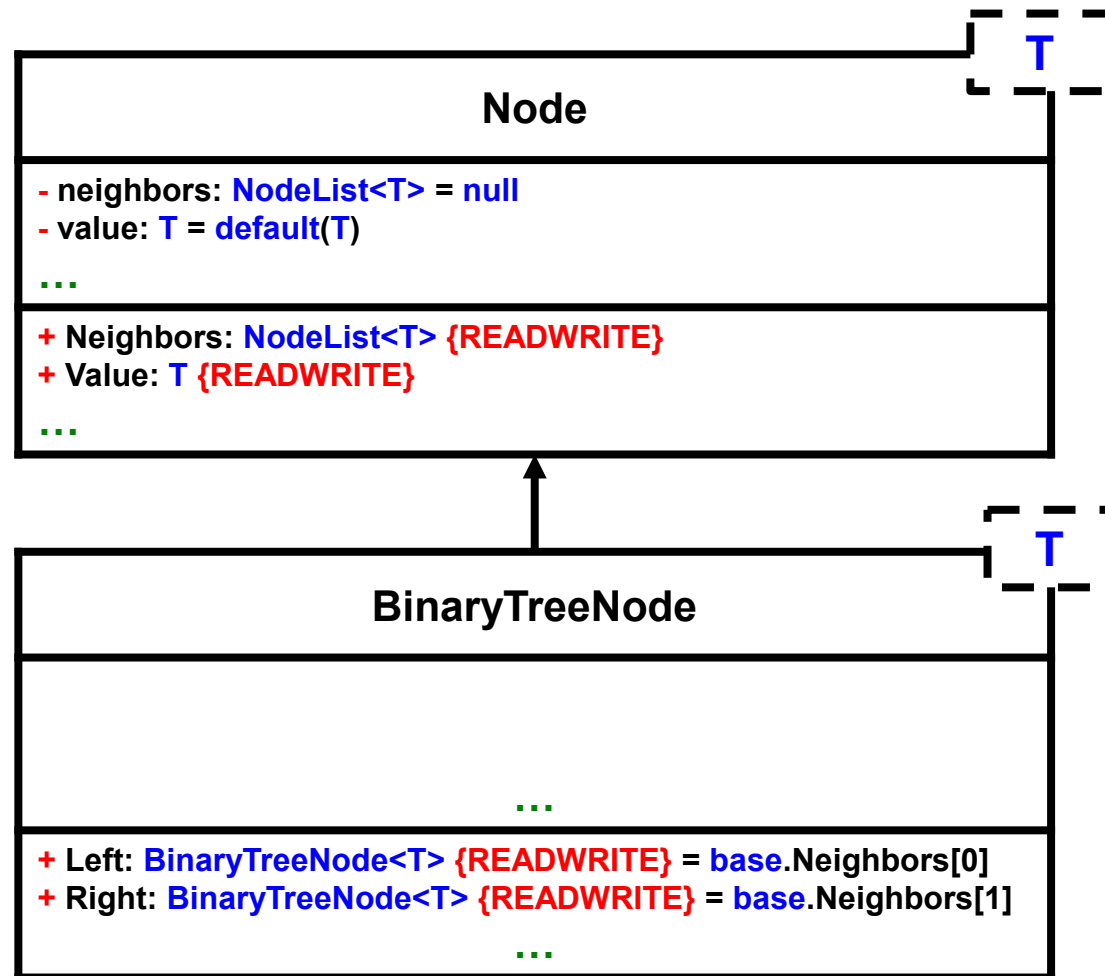
OOP Implementation

Enhanced object-oriented modelling and implementation of the "*Node*" class to fit the needs of all the *Node-Based Data Structures*, e.g., *Trees*, *Graphs*, *Linked-Lists*, etc.

Nodes – The *Node<T>* Classes Hierarchy?



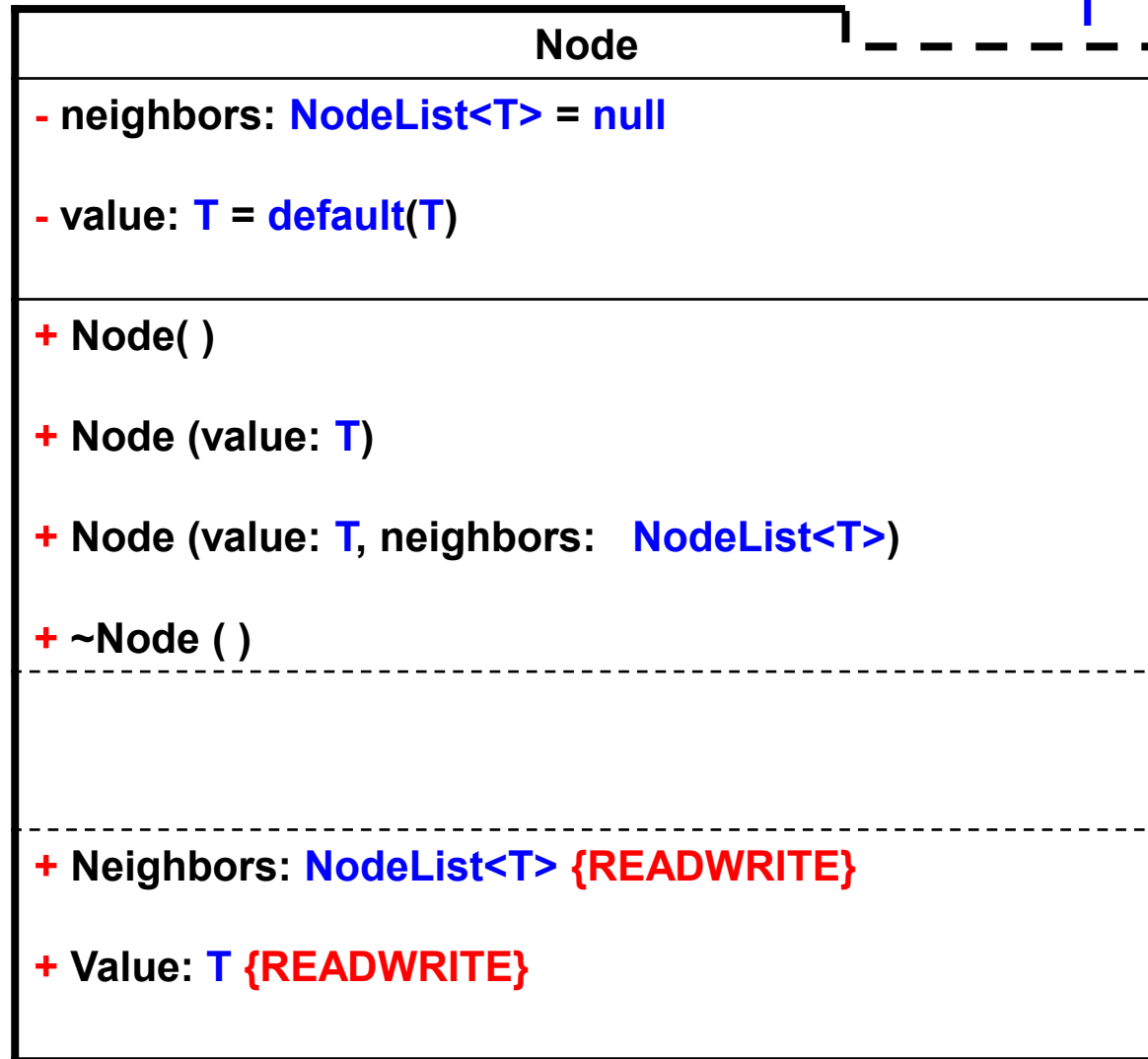
Nodes Hierarchy Class Diagram (Basic Version)



Nodes – The *Node<T>* Base Class?



Node<T>
Base Class
Diagram
(Basic Version)



Nodes – The *Node<T>* Base Class?

(...cont'd)

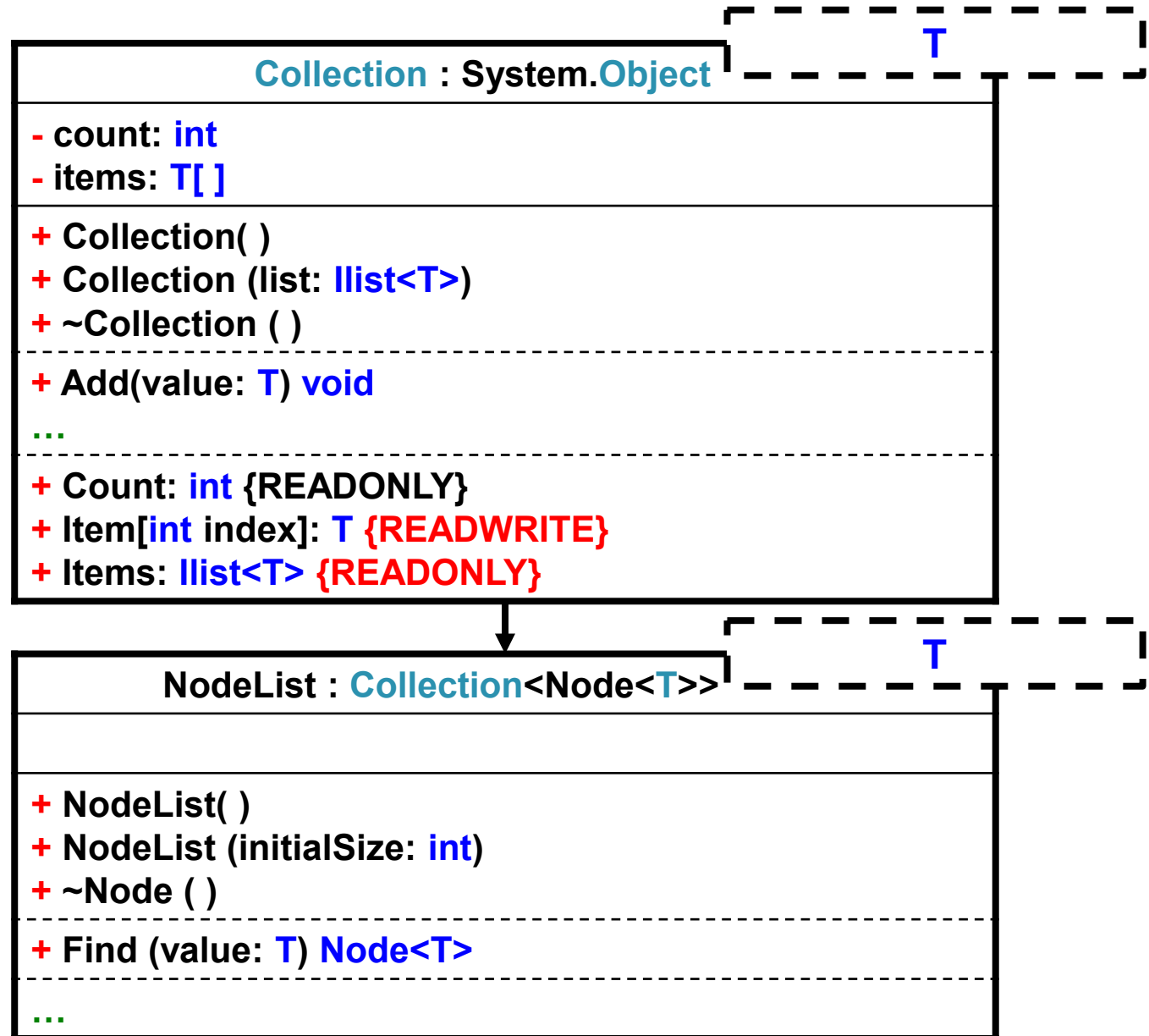
```
1  // Example: Node-Based Data Structures - Node<T>.
2  using System;
3
4
5  namespace Mohyeldin.DSA
6  {
7      public class Node<T>
8      {
9          public Node () : base() { }
10
11          public Node(T value) : this(value, null) { }
12
13          public Node(T value, NodeList<T> neighbors)
14          {
15              this.Value = value;
16              this.Neighbors = neighbors;
17          }
18
19          public T Value { get; set; } = default(T);
20
21          protected NodeList<T> Neighbors { get; set; } = default(T);
22      }
23  } /* (^_^) The Base Node Class Definition – Basic Version. (^_^) */
24
```

Value: T
Neighbors: NodeList

Nodes – The *NodeList<T>* Collection?



NodeList<T>
Collection Class
Diagram
(Basic Version)



Nodes – The *NodeList<T>* Collection?

(...cont'd)

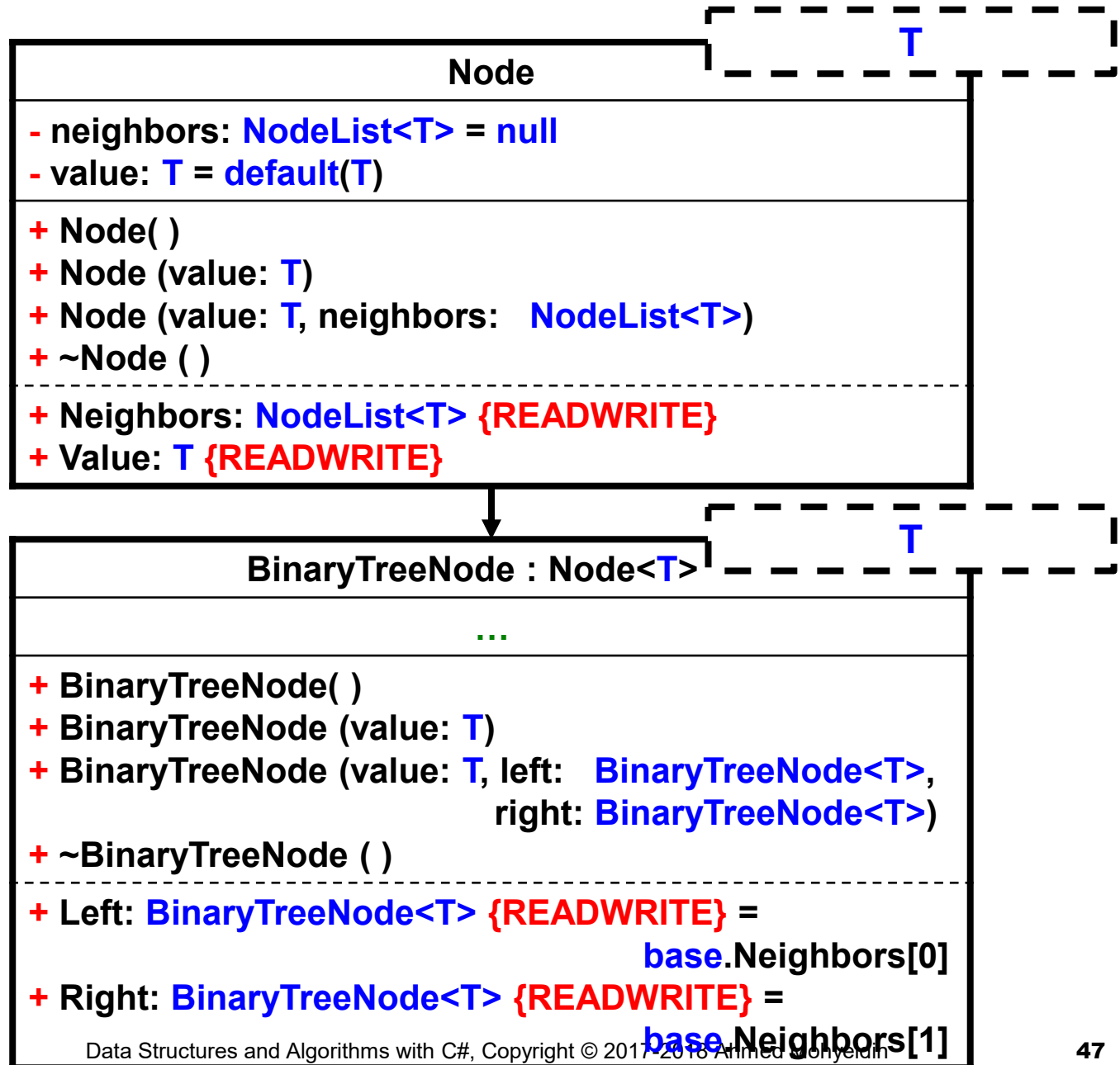
```
1 // Example: Node-Based Data Structures - NodeList<T>.
2 using System;
3 using System.Collections.ObjectModel;
4
5 namespace Mohyeldin.DSA
6 {
7     public class NodeList<T> : Collection<Node<T>>
8     {
9         public NodeList() : base() { }
10        public NodeList(int initialSize)
11        {    // Add the specified number of items.
12            for (int i = 0; i < initialSize; i++)
13                base.Items.Add(default(Node<T>));
14        }
15        public Node<T> FindByValue(T value)
16        {    // Search the list for the value.
17            foreach (Node<T> node in Items)
18                if (node.Value.Equals(value))
19                    return node; // Match is found; return the node.
20            return null;        // No match is found; return null.
21        }
22    }
23 } /* (^_^) The NodeList Class Definition - Basic Version. (^_^) */
24
```

Collection.Items: Node<T>[]

Nodes – The *BinaryTreeNode<T>* Class?



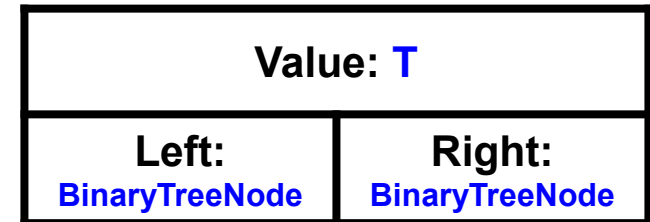
BinaryTreeNode<T>
Class
Diagram
(Basic Version)



Nodes – The *BinaryTreeNode<T>* ? (1/3) (...cont'd)

```
1 // Example: Node-Based Data Structures - BinaryTreeNode<T> (1/3).
2 using System;
3
4
5 namespace Mohyeldin.DSA
6 {
7     public sealed class BinaryTreeNode<T> : Node<T>
8     {
9         public BinaryTreeNode() : base()
10         { // TODO: ... }
11
12         public BinaryTreeNode(T value) : base(value, null)
13         { // TODO: ... }
14
15         public BinaryTreeNode(T value, BinaryTreeNode<T> left,
16                                 BinaryTreeNode<T> right)
17         {
18             base.Value = value;
19             NodeList<T> children = new NodeList<T>(2);
20             children[0] = left;
21             children[1] = right;
22             base.Neighbors = children;
23         }
24 }
```

// continued...



Nodes – The *BinaryTreeNode<T>* ? (2/3) (...cont'd)

```
25 // Example: Node-Based Data Structures - BinaryTreeNode<T> (2/3).
26     public BinaryTreeNode<T> Left
27     {
28         get
29         {
30             if (base.Neighbors == null)
31                 return null;
32             else
33                 return (BinaryTreeNode<T>) base.Neighbors[0];
34         }
35         set
36         {
37             if (base.Neighbors == null)
38                 base.Neighbors = new NodeList<T>(2);
39
40             base.Neighbors[0] = value;
41         }
42     }
43
44     // TODO: Any other enhancements may be added here...
45 }
46
47 // continued...
48
```

Nodes – The *BinaryTreeNode<T>* ? (3/3) (...cont'd)

```
49 // Example: Node-Based Data Structures - BinaryTreeNode<T> (3/3).
50     public BinaryTreeNode<T> Right
51     {
52         get
53         {
54             if (base.Neighbors == null)
55                 return null;
56             else
57                 return (BinaryTreeNode<T>)base.Neighbors[1];
58         }
59         set
60         {
61             if (base.Neighbors == null)
62                 base.Neighbors = new NodeList<T>(2);
63
64             base.Neighbors[1] = value;
65         }
66     }
67
68     // TODO: Any other enhancements may be added here...
69 }
70 }
71 /* (^_^)The BinaryTreeNode Class Definition - Basic Version. (^_^)*/
72
```

DEMO



Object-Oriented Implementation of Binary-Trees and Binary-Search Trees in C# – Using The Node<T> Generic Class.

BSTs – The *Time* Analysis?

- *Examining the efficiency of common operations, on a binary search tree consisting of n nodes?*

BSTs – The *Performance* Summary?

■ *Performance Analysis:*

- *Binary trees* offer tremendous power, flexibility, and efficiency when used with database management programs because the information for these databases must reside on disk and because access times are important. Because a balanced *binary tree has as a worst cases, $\log_2 n$ comparisons in searching it performs for better than a linked list, which must rely on a sequential search.*

■ *Time Analysis:*

- Worst Case $O(n)$ for Indexing, Search, Insertion & Deletion.
- Average Case for Indexing $O(\log_2 n)$, Search $O(\log_2 n)$, Insertion $O(\log_2 n)$, and Deletion $O(\log_2 n)$
 - Where, n is the number of items being sorted.

Lab Assignments

Linked Lists – *Lab Assignments*

■ Structured Programming Implementation:

1. Implement the operations of the **BST** data structure using a group of static class methods. The nodes can be implemented as a POD structure that has a generic information field of type **T**, and two link fields to represent the left and right children of the node. Finally, write an appropriate test driver for each of the tree operations.

■ Object-Oriented Programming Implementation:

2. Create a **BinarySearchTree<T>** and **BinaryTreeNode<T>** generic classes that implement the **BST** data structure with an appropriate test driver. The nodes can hold items of any specified data type **T** that implements the **Comparable<T>** interface.

- **Bonus:** Create a **Node<T>** generic class that represents the base concept of a node for a linked list, tree or graph; a node that contains a data item and has an arbitrary number of neighbors. Then, use it to derive the **BinaryTreeNode<T>** generic class that represents a node in a binary tree. Finally, rework the previous assignment using these node classes.

SUMMARY – Binary Trees

- **Tree** → is a data structure that simulates a hierarchical tree structure, with a root value and subtrees of children with a parent node, represented as a set of linked nodes.
- **Binary Tree (BT)** → is a tree data structure in which each leaf (i.e., node) has at most two children.
- **Binary Search Tree (BST)** → is a special kind of binary tree that exhibit the following property: for any node ***n***, every descendant node's value in the left subtree of ***n*** is less than the value of ***n***, and every descendant node's value in the right subtree is greater than the value of ***n***.
- **Time Analysis** → Binary Search Trees
 - Insertion/Deletion → $O(n)$ worst case, $O(\log_2 n)$ average case.
 - Traversal → $O(n)$ worst case, $O(\log_2 n)$ average case.
 - Searching → $O(n)$ worst case, $O(\log_2 n)$ average case.
- **Space Analysis** → Binary Search Trees
 - Wasted Space → $O(n)$ worst case, $O(n)$ average case.



Please consider the environment before printing this material.

Now, Let's go to the DSA programming Lab 😊



Lecture #7: Binary Trees

A Tree-Like Data Structure 😊

SUMMARY – Q & A

Feedbacks: email to ameldin@gmail.com. We value your feedback!
(Please include the following prefix in the subject field: **[DSA-C#]**)