

# Homework 3: A Posteriori Error Estimation and Flux Approximation

November 15, 2024

## 1 Problem Statement

Let  $\Omega$  be a bounded regular open set in  $\mathbb{R}^d$  ( $d = 1, 2, 3$ ), with  $f \in L^2(\Omega)$ , and constants  $k, \alpha > 0$ . We consider the partial differential equation

$$\begin{cases} -\operatorname{div}(k\nabla u) + \alpha u = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

The associated variational formulation is to find  $u \in V := H_0^1(\Omega)$  such that for all  $v \in V$ ,

$$\int_{\Omega} k\nabla u \cdot \nabla v + \alpha uv \, dx = \int_{\Omega} f v \, dx.$$

To determine a numerical approximation of  $u$ , we use a Galerkin-type method. In other words, we consider a finite-dimensional subspace  $V_h$  of  $V$  and denote by  $u_h$  the element of  $V_h$  such that for all  $v_h \in V_h$ ,

$$\int_{\Omega} k\nabla u_h \cdot \nabla v_h + \alpha u_h v_h \, dx = \int_{\Omega} f v_h \, dx.$$

We then introduce the approximation error  $e_h = u_h - u$  and use certain a priori estimates. Specifically, if we use the Lagrange P1 finite element method, there exists a constant  $C$  independent of  $f$  such that if the potential  $u$  is regular and  $h$  is the mesh size (assumed regular) of  $\Omega$ , we have

$$\|e_h\|_V \leq Ch\|u\|_{H^2(\Omega)},$$

where  $\|\cdot\|_V$  denotes the energy norm, defined as

$$\|v\|_V = \left( \int_{\Omega} k\nabla v \cdot \nabla v + \alpha |v|^2 \, dx \right)^{1/2}.$$

Unfortunately, we do not know the solution  $u$  a priori. Hence, the previous estimate only provides an order of magnitude of the error. We aim to bound the error by a quantity that only involves known or explicitly computable data.

### Question 1: A Posteriori Estimation

The approximation error  $e_h$  itself satisfies a variational problem. Indeed,  $e_h \in V$  is such that for all  $v \in V$ ,

$$\int_{\Omega} k\nabla e_h \cdot \nabla v + \alpha e_h v \, dx = \int_{\Omega} k\nabla u_h \cdot \nabla v + \alpha u_h v \, dx - \int_{\Omega} f v \, dx.$$

Show that for all  $\sigma \in H(\operatorname{div}) := \{\tau \in L^2(\Omega)^n \mid \nabla \cdot \tau \in L^2(\Omega)\}$ , we have

$$\frac{1}{2}\|e_h\|_V^2 \leq -G_h(\sigma),$$

where

$$G_h(\sigma) = -\frac{1}{2} \int_{\Omega} k^{-1} |\sigma - k\nabla u_h|^2 \, dx - \frac{1}{2} \int_{\Omega} \alpha^{-1} |f - \alpha u_h + \nabla \cdot \sigma|^2 \, dx.$$

### Question 2: Flux Approximation

We aim to optimize the second term of inequality (2) over a space  $W_h$ . Specifically, we introduce  $\sigma_h \in W_h \subset H(\text{div})$  such that

$$G_h(\sigma_h) = \max_{\tau \in W_h} G_h(\tau).$$

Show that  $\sigma_h \in W_h$  is such that for all  $\tau \in W_h$ ,

$$\int_{\Omega} k^{-1} \sigma_h \cdot \tau \, dx + \int_{\Omega} \alpha^{-1} (f + \nabla \cdot \sigma_h) \nabla \cdot \tau \, dx = 0.$$

Deduce that  $\sigma_h$  is an approximation of the flux  $\sigma = k \nabla u$ .

## 2 One-Dimensional Case

We consider the case  $\Omega = (0, 1)$  and use a finite element discretization to determine an approximation  $u_h$  of the potential  $u$  and an approximation  $\sigma_h$  of the flux  $\sigma$ . Specifically, we partition  $\Omega$  into  $N + 1$  intervals  $(x_i, x_{i+1})$  for  $i = 0, \dots, N$ , where  $x_i = ih$  and  $h = 1/(N + 1)$ . We introduce the finite element space  $V_h$  of P1 elements on  $(0, 1)$  that vanish on the boundary.

### Question 3: Optimality Conditions for the Potential

Show that  $U_h$  is the solution of the linear system

$$A_h U_h = b_h,$$

where  $A_h$  is the matrix  $A_h = kh^{-1}K + \alpha hM$ , with  $K, M$  being two matrices and  $b$  a vector to be determined.

### Question 4: Potential Calculation

Numerically calculate the solution of (3) for a constant function  $f$ . Plot the graph of  $u$ . Numerical application:  $N = 100$ ,  $f = 1$ ,  $k = 1$ , and  $\alpha = 1$ .

Following the same approach, we compute the approximation of the flux  $\Sigma_h \in \mathbb{R}^{N+1}$ . We choose the approximation space for the flux  $\sigma_h$  as the set of P1 finite elements,

$$W_h = \{\sigma_h \in H^1(\Omega) \mid v_h|_{(x_i, x_{i+1})} \in P1 \text{ for all } i = 0, \dots, N\}.$$

Let  $\Sigma_h$  denote the coordinates of  $\sigma_h$ , the Galerkin approximation of  $\sigma_h$  on  $W_h$ .

### Question 5: Optimality Conditions for the Flux

Show that  $\Sigma_h$  is the solution of the system

$$B_h \Sigma_h = (k^{-1}hM' + \alpha^{-1}h^{-1}K')\Sigma_h = c_h,$$

with  $K', M'$  being two matrices and  $c_h$  a vector to be determined.

### Question 6: Flux Calculation

Numerically compute the solution of (4). Plot the graph of  $\sigma_h$  using the same numerical values as in the previous question.

**Question 7: Discretization of the Injection Operator  $V_h$  into  $W_h$** 

7.a) Show that the matrix  $I_V$ , which associates the coordinates  $U_h$  of  $u_h$  in the basis of  $V_h$  to its coordinates in  $W_h$ , is the  $(N+2) \times N$  matrix of the form:

$$I_V = \begin{pmatrix} 0 \\ \text{Id} \\ 0 \end{pmatrix}$$

7.b) Write a freefem++ code that implements the matrix  $I_V$ .

**Question 8: Discretization of the Injection Operator  $W_h$  into  $X_h$** 

8.a) Show that the matrix  $I_W$ , which associates the coordinates  $\Sigma_h$  of  $\sigma_h$  in  $W_h$  to its coordinates in  $X_h$ , is the  $2(N+1) \times (N+2)$  matrix of the form:

$$I_W = \begin{pmatrix} 1 & 0 & \cdots & \cdots & 0 \\ 0 & c & \ddots & & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & & \ddots & c & 0 \\ 0 & \cdots & \cdots & 0 & 1 \end{pmatrix}, \quad \text{with } c = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

8.b) Write a freefem++ code that implements the matrix  $I_W$ .

**Question 9: Discretization of the Gradient Operator on  $X_h$** 

Let  $v_h$  be an element of  $X_h$  and  $\tau_h \in X_h$  defined for all  $i = 0, \dots, N$  by:

$$\tau_h|_{(x_i, x_{i+1})} = \nabla v_h|_{(x_i, x_{i+1})}.$$

Denoting by  $V$  and  $T$  the respective coordinates of  $v_h$  and  $\tau_h$  in  $X_h$ ,

9.a) Show that:

$$T = D_h V,$$

where  $D_h$  is the  $2(N+1) \times 2(N+1)$  matrix:

$$D_h = h^{-1} \begin{pmatrix} D & 0 & \cdots & 0 \\ 0 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & D \end{pmatrix}, \quad \text{with } D = \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix}.$$

9.b) Write a freefem++ code that implements the matrix  $D_h$ .

**Question 10: Discretization of the Mass Operator on  $X_h$** 

Let  $\tau_h$  be an element of  $X_h$  with coordinates  $T$ .

10.a) Show that:

$$\int_{\Omega} |\tau_h|^2 dx = N_h T \cdot T,$$

where:

$$N_h = \frac{h}{6} \begin{pmatrix} N & 0 & \cdots & 0 \\ 0 & \ddots & \ddots & \vdots \\ \vdots & & \ddots & 0 \\ 0 & \cdots & 0 & N \end{pmatrix}, \quad \text{with } N = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}.$$

10.b) Write a freefem++ code using varf that implements the matrix  $N_h$ .

### Question 11: Error Estimation

To slightly simplify the analysis, assume  $f \in X_h$ . Let  $F_h$  be the coordinates of  $f$  in  $X_h$ . Deduce from the estimation (2) that:

$$2\|e_h\|_V \leq k^{-1}N_h (I_W \Sigma_h - kD_h I_W I_V U_h) \cdot (I_W \Sigma_h - kD_h I_W I_V U_h) \\ + \alpha^{-1}N_h (F_h - \alpha I_W I_V U_h + D_h I_W \Sigma_h) \cdot (F_h - \alpha I_W I_V U_h + D_h I_W \Sigma_h).$$

Using this estimation, calculate an upper bound for the error  $\|e_h\|_V$  in the calculation of  $u$ . Use the same data as in the previous questions, with  $N = 100$  and  $N = 1000$ .

## 3 Two-Dimensional Case

Consider now the two-dimensional case with the unit disk as the domain  $\Omega$ .

### Question 12: Potential Calculation

Using FreeFem++, find an approximation of the potential using the P1 finite element method. Use a mesh with a density  $\delta_n$  of elements per unit length with  $\delta_n = 10$ . Also, choose  $f = 1$ ,  $\alpha = 1$ , and  $k = 1$ . Plot the isovalues of the potential and provide the average of  $u_h$  on  $\Omega$ .

### Question 13: Flux Calculation

Using FreeFem++, find an approximation of the flux with Raviart-Thomas elements of degree zero (RT0 in FreeFem++). Use the same mesh and data as in the previous question. Plot the resulting field  $\sigma_h$  on a graph.

### Question 14: Error Estimation

Determine an upper bound on the error  $\|e_h\|_V$ . Use the same mesh and data as in the previous two questions.

### Question 15: Convergence Rate

Plot the graph, in logarithmic coordinates, of the error  $\|e_h\|_V$  as a function of the density  $\delta_n$  of points on the boundary per unit length (choose  $\delta_n$  from 10 to 100). What is the observed convergence rate? Compare the obtained rate to the theoretical convergence rate of the error.