

## Exercises and Problems

### 1 Exercises

**Ex.1.** Consider the following triplet  $(K, \mathcal{P}, \mathcal{N})$

- i)  $K = [0, 1]$ .
- ii)  $\mathcal{P}$  is the linear polynomials on  $K$ , i.e  $\mathbb{P}_1$ .
- iii)  $\mathcal{N}$  is :

$$N_1(p) = p(0.5), \quad N_2(p) = \int_0^1 p(x) dx.$$

Is this finite element unisolvent? Explain your answer

**Ex.2.** a) Obtain the nodal basis function  $\phi_1(x)$  for the finite element  $(K = [0, 1], \mathcal{P}_2, \mathcal{N})$ , with  $\mathcal{N} = (N_1, N_2, N_3)$  given by

$$\begin{aligned} N_1(f) &= f(0), \\ N_2(f) &= f(1), \\ N_3(f) &= \int_0^1 f dx. \end{aligned}$$

- b) What is the global continuity of finite element spaces constructed from the finite element described above ? Explain your answer.

**Ex.3.** Consider the finite element  $(K, \mathcal{P}, \mathcal{N})$  where

- $K$  is a non-degenerate triangle.
- $\mathcal{P}$  is the space of polynomials of degree 2 or less.
- $\mathcal{N} = (N_1, N_2, N_3, N_4, N_5, N_6)$  with

$$\begin{aligned} N_i(v) &= v(z_i), \quad i = 1, 2, 3, \\ N_4(v) &= v\left(\frac{z_1 + z_2}{2}\right), \\ N_5(v) &= v\left(\frac{z_1 + z_3}{2}\right), \\ N_6(v) &= v\left(\frac{z_2 + z_3}{2}\right), \end{aligned}$$

where  $z_1, z_2$  and  $z_3$  are the vertices of  $K$ .

Show that  $\mathcal{N}$  determines  $\mathcal{P}$ .

**Ex.4.** Now consider the finite element  $(K, \hat{\mathcal{P}}, \hat{\mathcal{N}})$  where

- $K$  is a non-degenerate triangle (with boundary  $\partial K$ ).
- $\hat{\mathcal{P}}$  is the space spanned by polynomials of degree 2 or less, plus the cubic "bubble" function  $B(x)$  satisfying  $B(x) = 0$  for all  $x \in \partial K$ , and  $\int_K B(x) dx = 1$ .
- $\hat{\mathcal{N}} = (N_1, N_2, N_3, N_4, N_5, N_6, N_7)$  with  $N_i$  as above for  $i = 1, \dots, 6$ , and
- 

$$N_7(v) = v \left( \frac{z_1 + z_2 + z_3}{3} \right).$$

Show that  $\hat{\mathcal{N}}$  determines  $\hat{\mathcal{P}}$ .

**Ex.5.** What is the choice of the geometric decomposition (allocation of nodal variables to cell and vertex entities) that leads to the maximum possible global continuity of finite element spaces defined on the interval  $[0, L]$  constructed from the following one-dimensional elements  $(K, P, N)$ . Justify your answer.

a)  $K = [a, b]$ ,  $P$  is linear polynomials,  $N = (N_1, N_2)$  where

$$N_1[u] = u((a+b)/2), \quad N_2[u] = u'((a+b)/2).$$

b)  $K = [a, b]$ ,  $P$  is quadratic polynomials,  $N = (N_1, N_2, N_3)$  where

$$N_1[u] = u(a), \quad N_2[u] = u(b), \quad N_3[u] = \int_a^b u \, dx.$$

c)  $K = [a, b]$ ,  $P$  is quadratic polynomials,  $N = (N_1, N_2, N_3)$  where

$$N_1[u] = u'(a), \quad N_2[u] = u'(b), \quad N_3[u] = u((a+b)/2).$$

**Ex.6.** Consider the interval  $[a, b]$ , with points :

$$a = x_0, x_1, x_2, \dots, x_{n-1}, x_n = b.$$

Let  $\mathcal{T}$  be a subdivision (i.e. a 1D mesh) of the interval  $[a, b]$  into subintervals

$$I_k = [x_k, x_{k+1}], \quad k = 0, \dots, N-1.$$

Consider the following three elements.

(a)  $(K, P, N)$  where  $K = I_k$ ,  $P$  are polynomials of degree  $\leq 3$ , and  $N = (N_1, N_2, N_3, N_4)$  with:

$$\begin{aligned} N_1[u] &= u(x_k), & N_2[u] &= u(x_{k+1}), \\ N_3[u] &= \int_{x_k}^{x_{k+1}} u dx, & N_4[u] &= u'((x_{k+1} + x_k)/2). \end{aligned}$$

(b)  $(K, P, N)$  where  $K = I_k$ ,  $P$  are polynomials of degree  $\leq 3$ , and  $N = (N_1, N_2, N_3, N_4)$  with:

$$\begin{aligned} N_1[u] &= u(x_k), & N_2[u] &= u(x_{k+1}), \\ N_3[u] &= u'(x_k), & N_4[u] &= u'(x_{k+1}). \end{aligned}$$

- (c)  $(K, P, N)$  where  $K = I_k$ ,  $P$  are polynomials of degree  $\leq 3$ , and  $N = (N_1, N_2, N_3, N_4)$  with:

$$\begin{aligned} N_1[u] &= u((x_{k+1} + x_k)/2), \quad N_2[u] = u'((x_{k+1} + x_k)/2), \\ N_3[u] &= u''((x_{k+1} + x_k)/2), \quad N_4[u] = u'''((x_{k+1} + x_k)/2). \end{aligned}$$

- i) Which of the three elements above are suitable for the following variational problem? Find  $u \in H^1([a, b])$  such that

$$\int_a^b uv + u'v' dx = \int_a^b f v dx, \quad \forall v \in H^1([a, b]).$$

Justify your answer.

- ii) Which of the three elements above are suitable for the following variational problem? Find  $u \in H^2([a, b])$  such that

$$\int_a^b uv + u'v' + u''v'' dx = \int_a^b f v dx, \quad \forall v \in H^2([a, b]).$$

Justify your answer.

**Ex.7.** Let  $V_h$  be a finite-dimensional subspace of a Hilbert space  $V$ , and let  $u \in V$  and  $u_h \in V_h$  satisfy

$$a(u, v) = \ell(v) \quad \forall v \in V, \quad (\text{V})$$

$$a(u_h, v_h) = \ell(v_h) \quad \forall v_h \in V_h, \quad (\text{V}_h)$$

respectively, where  $a(\cdot, \cdot)$  is a symmetric bilinear form on  $V$  and  $\ell : V \rightarrow \mathbb{R}$  is a linear functional.

- (a) Show that the Galerkin solution  $u_h$  is the best approximation to  $u \in V$  when measured in the energy norm  $\|\cdot\|_E$ , that is,

$$\|u - u_h\|_E \leq \|u - v_h\|_E \quad \forall v_h \in V_h,$$

where

$$\|v\|_E^2 = a(v, v), \quad v \in V.$$

- (b) Suppose that we have an enhanced approximation space  $W_h$  such that

$$V_h \subset W_h \subset V,$$

with associated solution  $u_h^* \in W_h$  satisfying

$$a(u_h^*, v) = \ell(v) \quad \forall v \in W_h.$$

Use the fact that

$$a(u - u_h^*, v) = 0 \quad \forall v \in W_h$$

to show that

$$\|u - u_h\|_E^2 = \|u - u_h^*\|_E^2 + \|u_h^* - u_h\|_E^2.$$

Deduce that

$$\|u - u_h\|_E \geq \|u - u_h^*\|_E.$$

(c) Suppose that the enhanced space  $W_h$  can be written as

$$W_h = V_h \oplus Z$$

and that a strengthened Cauchy–Schwarz inequality holds:

$$|a(v_h, z_h)| \leq \gamma \|v_h\|_E \|z_h\|_E \quad \forall v_h \in V_h, \forall z_h \in Z,$$

with  $0 \leq \gamma < 1$ .

Consider the simplified error representation problem: find  $e_h \in Z$  satisfying

$$a(e_h, z_h) = \ell(z_h) - a(u_h, z_h) \quad \forall z_h \in Z. \quad (Z_h^*)$$

Show that  $e_h \in Z$  is equivalent to  $u_h^* - u_h \in W_h$  and that

$$\|e_h\|_E^2 \leq \|u_h^* - u_h\|_E^2 \leq \frac{1}{1 - \gamma^2} \|e_h\|_E^2, \quad 0 \leq \gamma < 1.$$

*Hint:* To establish the left-hand inequality, use the fact that

$$a(u_h^* - u_h, z_h) = a(e_h, z_h) \quad \forall z_h \in Z.$$

To establish the right-hand inequality, write

$$u_h^* - u_h = v_h + z_h, \quad v_h \in X, \quad z_h \in Z,$$

and use the inequality

$$a^2 + b^2 - 2\gamma ab \geq (1 - \gamma^2)b^2.$$

## 2 Problems.

Pb. 1) (Raviart-Thomas element)

In this work we consider the Raviart-Thomas finite element  $\text{RT}_0$ :

- $\mathcal{T}_h$  is a triangular mesh of a smooth, bounded, closed domain  $\Omega \subset \mathbb{R}^2$ ;
- $K_i$  denotes the generic triangle of the mesh, for  $i = 1, 2, \dots, I$ ;
- $e_j$  denotes its internal edges, for  $j = 1, 2, \dots, J$ ;
- $d_l$  denotes its boundary edges, for  $l = 1, 2, \dots, L$ .

Let  $\text{RT}_0(\mathcal{T}_h)$  be the space of the Raviart–Thomas finite element functions. The generic  $\text{RT}_0$  function on a given triangle  $K$  can be written as

$$\varphi(x, y) = c \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} a \\ b \end{pmatrix}, \quad a, b, c \in \mathbb{R},$$

and it satisfies the following properties:

- (a)  $(\nabla \cdot \varphi)|_K \in P_0(K)$ ,
- (b)  $\varphi \cdot n$  is constant on each edge of  $K$ .

We can thus define the global  $\text{RT}_0(\mathcal{T}_h)$  finite element space as:

$$\text{RT}_0(\mathcal{T}_h) = \left\{ \varphi : \Omega \rightarrow \mathbb{R}^2 \mid \varphi|_{K_i} \text{ is linear } \forall K_i \in \mathcal{T}_h, \text{ with continuous normal components over } e_j, d_l \right\} \quad (1)$$

$\text{RT}_0$  functions are therefore determined by the values of their normal components over the edges of the mesh, i.e. their degrees of freedom are

$$\varphi_i = (\varphi \cdot n)|_{e_i},$$

and the analogous quantities on the boundary edges.

Similarly, we can define the  $\text{RT}_0$  interpolant of a function  $v$  as

$$I_{\text{RT}_0}(v) = \varphi_h \in \text{RT}_0(\mathcal{T}_h) : \quad (\varphi_h \cdot n)|_{e_i} = \frac{1}{|e_i|} \int_{e_i} v \cdot n, \quad (\varphi_h \cdot n)|_{d_l} = \frac{1}{|d_l|} \int_{d_l} v \cdot n.$$

Finally, the global  $\text{RT}_0(\mathcal{T}_h)$  finite element functions belong to  $H(\text{div}, \Omega)$ , as an immediate consequence of the following characterization.

## 2.1 Characterization of $H(\text{div}, \Omega)$ .

Let  $\varphi : \Omega \rightarrow \mathbb{R}^2$  be such that:

- (a)  $\varphi|_{K_i} \in H^1(K_i)^2$  for each  $K_i \in \mathcal{T}_h$ ;
- (b) For each internal edge  $e_j$  let  $K^+$ ,  $K^-$  be the two adjacent elements to  $e_j$ , with outward normals  $n^+$ ,  $n^-$  respectively,  $n^- = -n^+$ . The traces of the normal components of  $\varphi$  on  $e_j$ ,  $\varphi|_{K^+} \cdot n^+$  and  $\varphi|_{K^-} \cdot n^-$ , are the same, i.e.

$$\varphi|_{K^+} \cdot n^+ + \varphi|_{K^-} \cdot n^- = 0.$$

Then  $\varphi \in H(\text{div}, \Omega)$ .

## Questions

Prove the following points:

- (a) Prove property 1 of  $\text{RT}_0$  elements, i.e.

$$(\nabla \cdot \varphi)|_K \in P_0(K).$$

- (b) Prove property 2 of  $\text{RT}_0$  elements, i.e.  $\varphi \cdot n$  is constant on each edge of the triangle.

**Hint:** Let  $P_i, P_j$  be any two vertices of  $K \in \mathcal{T}_h$ . Write the expression of the line  $r(t)$ ,  $t \in \mathbb{R}$ , passing through  $P_i, P_j$ , and verify that  $\varphi|_{r(t)} \cdot n$  is a constant quantity.

- (c) Compute the expression of the  $\text{RT}_0$  basis functions on the reference triangle.

## 2.2 Darcy's Problem

Consider the Darcy equations for flows in porous media in the square domain

$$\Omega = [0, 1]^2$$

$$\begin{cases} -k\nabla p = u, & \text{in } \Omega, \\ \nabla \cdot u = f, & \text{in } \Omega, \\ p = 0, & \text{on } \partial\Omega, \end{cases} \quad (2)$$

where  $k : \Omega \rightarrow \mathbb{R}$  is such that

$$0 < k_{\min} \leq k(x, y) \leq k_{\max} < \infty, \quad \forall (x, y) \in \Omega.$$

We can combine the first and the second equations to obtain an equivalent elliptic problem:

$$\begin{cases} -\nabla \cdot (k\nabla p) = f, & \text{in } \Omega, \\ p = 0, & \text{on } \partial\Omega. \end{cases} \quad (3)$$

- (a) Let  $k = 1$  and

$$p(x, y) = \sin(\pi x) \sin(\pi y).$$

Derive the expression of  $u$  and compute  $f$  so that the above equations are satisfied.

- (b) Solve the mixed problem (2) using an  $\text{RT}_0$  finite element discretization for  $u$  and a  $P_0$  discretization for  $p$ . Recall the expected convergence rate and verify your results.

**FreeFem hint:**

```
fespace Vh(Th,RT0);
fespace Qh(Th,P0);
Vh [uh1, uh2], [tauh1, tauh2];
Qh ph,qh;
problem Darcy([uh1,uh2,ph],[tauh1,tauh2,qh]) = ...
```

- (c) Solve the elliptic problem (3) using a  $P_1$  discretization for  $p$ . Recall the convergence rate for the  $L^2$  norm of the error and verify your results.
- (d) Compare the two error convergence curves for  $p$  in the same plot and comment the results you obtain. Which approximation is the most accurate?
- (e) Reconstruct a numerical approximation for  $u \in P_0$  starting from the  $P_1$  approximation of  $p$  in (3). What rate of convergence do you expect for the  $L^2$  error on  $u$ ?

**Hint:** In FreeFem it is possible to directly obtain a numerical reconstruction of  $u \in P_0$  from the computed  $P_1$  approximation of  $p$  by using the commands `dx()` and `dy()`.

- (f) Compare the two error convergence curves for  $u$  (i.e. the one obtained with the mixed formulation and the one reconstructed from the elliptic approximation) on the same plot and comment the results you obtain. Which approximation is the most accurate?

Pb. 2) (Crouzeix-Raviart element) Consider the unit square

$$\Omega = (0, 1)^2.$$

Let  $\mathcal{T}_h$  be a regular mesh for  $\Omega$ ,  $F_h$  be the set of edges of  $\mathcal{T}_h$ , and  $F_h^{\text{int}}$  be the set of interior edges of  $\mathcal{T}_h$ . For each edge  $F \in F_h^{\text{int}}$ , let us denote with  $K_{F,+}$  and  $K_{F,-}$  the two elements  $K \in \mathcal{T}_h$  separated by  $F$ .

Moreover, let us consider a function  $v : \Omega \rightarrow \mathbb{R}$  and its restrictions on  $K_{F,+}$  and  $K_{F,-}$ , that we denote as  $v_{F,+}(x)$  and  $v_{F,-}(x)$  respectively. If  $v$  is a continuous function over  $\Omega$ , its value on each edge  $F$  is uniquely defined; if instead we only require continuity separately in each triangle  $K \in \mathcal{T}_h$ , the value of  $v_{F,+}$  and  $v_{F,-}$  on  $F$  may differ. Such difference is called the *jump* of  $v$  across  $F$  and it is denoted by  $[v]_F$ , i.e.

$$[v]_F(x) = v_{F,+}(x) - v_{F,-}(x), \quad x \in F.$$

The Crouzeix–Raviart finite element space is the space of piecewise linear functions whose jumps over internal edges have zero mean:

$$V_h = \left\{ v_h \in L^2(\Omega) : v_h|_K \in \mathbb{P}_1(K) \ \forall K \in \mathcal{T}_h, \text{ and } \int_F [v_h] = 0 \ \forall F \in F_h^{\text{int}} \right\}.$$

- (a) Show that Crouzeix–Raviart functions are continuous in the midpoint of each internal edge (see Figure ??).

**Hint:** Show the continuity in the midpoint by applying the midpoint quadrature rule to the condition  $\int_F [v_h] = 0$ .

- (b) Let  $a_F$  denote the midpoint of the edge  $F \in F_h$ . Show that the values  $v_h(a_j)$  uniquely identify a function in  $V_h$ .
- (c) Draw the basis functions associated to the generic degree of freedom.
- (d) Let  $I_{h,\text{ref}}^{CR} : H^2(\hat{K}) \rightarrow V_h(\hat{K})$  be the interpolant operator on the reference triangle:

$$I_{h,\text{ref}}^{CR}(\hat{u})(x) = \sum_{j=1}^3 \hat{u}(a_j) \hat{\varphi}_j(x).$$

Observe that from here on, quantities related to the reference triangle will be denoted by a hat. Show that  $I_{h,\text{ref}}^{CR}$  is continuous from  $H^2(\hat{K})$  to  $V_h(\hat{K})$  with  $H^1(\hat{K})$  norm.

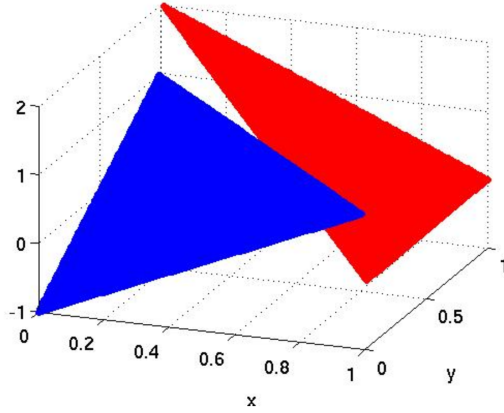


Figure 1: Crouzeix–Raviart functions are linear in each triangle and discontinuous among triangles but continuous at the midpoints of internal edges.

(a) Let  $I_h^{CR} : H^2(\Omega) \rightarrow V_h$  be the global interpolant operator

$$I_h^{CR}(u)(x) = \sum_{F \in F_h} u(a_F) \varphi_F(x).$$

Prove that

$$\begin{aligned} \sum_{K \in \mathcal{T}_h} |u - I_h^{CR}(u)|_{H^1(K)} &\leq Ch|u|_{H^2(\Omega)}, \\ \|u - I_h^{CR}(u)\|_{L^2(\Omega)} &\leq Ch^2|u|_{H^2(\Omega)}. \end{aligned}$$

**Hint:** Work on each element. You will need the following properties:

- i. The seminorm transformation lemma: for all integer  $m \geq 0$  and all  $v \in H^m(K)$ ,  $\hat{v} \in H^m(\hat{K})$ , there exists a constant  $C = C(m) > 0$  such that

$$|\hat{v}|_{H^m(\hat{K})} \leq C \|B_K\|^m |\det B_K|^{-1/2} |v|_{H^m(K)},$$

$$|v|_{H^m(K)} \leq C \|B_K^{-1}\|^m |\det B_K|^{1/2} |\hat{v}|_{H^m(\hat{K})},$$

where  $B_K$  is the matrix of the linear mapping from  $\hat{K}$  to  $K$ . Moreover,

$$\|B_K\| \leq \frac{h_K}{\hat{\rho}}, \quad \|B_K^{-1}\| \leq \frac{\hat{h}}{\rho_K}.$$

- ii. The fact that  $I_h^{CR}(u) = I_{h,\text{ref}}^{CR}(\hat{u})$ .
- iii.  $v_h = I_h^{CR}(v_h)$  for  $v_h \in V_h$ .
- iv. The continuity of  $I_{h,\text{ref}}^{CR}$  on the reference element.



- v. The Deny–Lions lemma: for every  $r \geq 0$  let  $\mathbb{P}_r(\widehat{K})$  be the set of polynomials of degree  $r$  over  $\widehat{K}$ . Then there exists a constant  $C = C(r, \widehat{K})$  such that

$$\inf_{\widehat{p} \in \mathbb{P}_r(\widehat{K})} \|\widehat{p} + \widehat{v}\|_{H^{r+1}(\widehat{K})} \leq C |\widehat{v}|_{H^{r+1}(\widehat{K})}, \quad \forall \widehat{v} \in H^{r+1}(\widehat{K}).$$

- vi. For a regular mesh the ratio  $h_K/\rho_K$  is uniformly bounded by a constant independent of  $h$ :

$$\frac{h_K}{\rho_K} \leq \delta < \infty.$$

### 3 Condition Number of the Galerkin Matrix

Consider the Laplacian problem on the unit square:

$$\begin{cases} -\Delta u = f & \text{in } \Omega = (0,1)^2, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (4)$$

- (a) Using FreeFem++, compute the Galerkin matrix for this problem and save it to file. Use the following commands:

```
• varf a(u,v)= int2d(..)(..) + on(..);
• matrix A = a(Vh,Vh);
• ofstream matrixfile("A.dat");
• matrixfile << A << endl;
```

- (b) Compute the condition number using `cond(A)`.

- (c) Repeat for  $n = 5, 10, 20, 40$  elements per side. Fill the table:

$n$	$h = 1/n$	$\text{cond}(A_h)$
5	—	—
10	—	—
20	—	—
40	—	—

- (d) Repeat the analysis for a non-structured mesh built with `border` and `buildmesh`. Compare with the structured case.

- (e) Consider a grid refined toward the boundaries:

```
mesh Th = square(n,n);
Th = movemesh(Th, [(1-cos(pi*x))/2., (1-cos(pi*y))/2.]);
```

Repeat the analysis. What happens?