

Exercises

Ex.1. In lectures we proved that for a stable discretisation of a stable (noncoercive) problem of the form

$$a(u, v) = F(v) \text{ for all } v \in V \quad (\text{T})$$

a Galerkin approximation satisfies the quasi-optimality result

$$\|u - u_h\|_V \leq (1 + c) \inf_{v_h \in V_h} \|u - v_h\|_V$$

where u_h is the solution to the Galerkin approximation of (T) over a closed subspace $V_h \subsetneq V$. Here $c = C/\tilde{\gamma}$, where C is the continuity constant of a and $\tilde{\gamma}$ is the discrete inf-sup constant.

(i) Prove that (under the same conditions) the Galerkin approximation is stable, i.e. u_h satisfies

$$\|u_h\|_V \leq c \|u\|_V$$

for the same constant $c = C/\tilde{\gamma}$.

(ii) For fixed $V_h \subsetneq V$ and a , consider the operator $P : V \rightarrow V_h$ defined by

$$a(u_h, v_h) = a(u, v_h) \quad \text{for all } v_h \in V_h$$

In this equation we think of u as an input and $u_h = Pu$ as an output. Prove that P is linear and is a projection, i.e. $P^2 = P$.

(iii) A result from functional analysis states that for a bounded linear projection

$$P : V \rightarrow V$$

satisfying $0 \neq P^2 = P \neq I$ (I the identity operator on V),

$$\|P\|_{\mathcal{L}(V,V)} = \|I - P\|_{\mathcal{L}(V,V)}$$

where the $\|\cdot\|_{\mathcal{L}(V,V)}$ norm is the operator norm

$$\|Q\|_{\mathcal{L}(V,V)} = \sup_{\substack{u \in V \\ u \neq 0}} \frac{\|Qu\|_V}{\|u\|_V}$$

Using this result, derive the improved quasi-optimality estimate

$$\|u - u_h\|_V \leq c \inf_{v_h \in V_h} \|u - v_h\|_V$$

Ex.2. Let $V = H_0^1(\Omega; \mathbb{R}^n)$ and $Q = L_0^2(\Omega)$. Let

$$L(u, p) = \frac{1}{2} \int_{\Omega} \nabla u : \nabla u \, dx - \int_{\Omega} f \cdot u \, dx - \int_{\Omega} p \nabla \cdot u \, dx$$

We say (u, p) is a saddle point of L iff

$$L(u, q) \leq L(u, p) \leq L(v, p), \quad \forall v \in V, q \in Q$$

Show that (u, p) is a weak solution of the Stokes equations if and only if it is a saddle point of the Lagrangian. (This is why these problems are called saddle point problems!)

Ex.3. Consider the mixed Poisson equation: find $(\sigma, u) \in H(\text{div}, \Omega) \times L^2(\Omega)$ such that

$$\int_{\Omega} \sigma \cdot \tau \, dx - \int_{\Omega} \nabla \cdot \tau u - \int_{\Omega} \nabla \cdot \sigma w \, dx = - \int_{\Omega} f w \, dx$$

for all $(\tau, w) \in H(\text{div}, \Omega) \times L^2(\Omega)$.

- (i) Write the mixed Poisson equation as the derivative of a Lagrangian $L(\tau, w)$.
- (ii) What constrained optimisation problem is encoded by this Lagrangian?