

3 zyg $A = \begin{pmatrix} 1 & -1 & 2 \\ 2 & 2 & -4 \\ 3 & 1 & -2 \end{pmatrix}$, $B = \begin{pmatrix} -1 & -2 & 1 & 1 \\ -2 & 0 & 2 & -2 \\ -3 & -2 & 3 & -1 \end{pmatrix}$

$$A \cdot X = B$$

Проверка за обрз. на A^{-1}

$$\begin{vmatrix} 1 & -1 & 2 \\ 2 & 2 & -4 \\ 3 & 1 & -2 \end{vmatrix} = -4 + 12 + 4 - 12 - 4 + 4 = 0$$

$\Rightarrow A$ не е обратима

$$A_{3 \times 3} \quad B = 3 \times 4 \Rightarrow X_{3 \times 4}$$

$$\begin{pmatrix} 1 & -1 & 2 \\ 2 & 2 & -4 \\ 3 & 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} x_{11} & x_{12} & x_{13} & x_{14} \\ x_{21} & x_{22} & x_{23} & x_{24} \\ x_{31} & x_{32} & x_{33} & x_{34} \end{pmatrix} = \begin{pmatrix} -1 & -2 & 1 & 1 \\ -2 & 0 & 2 & -2 \\ -3 & -2 & 3 & -1 \end{pmatrix}$$

$$\begin{array}{l} r_1: x_{11} - x_{21} + 2x_{31} = -1 \\ r_2: 2x_{11} + 2x_{21} - 4x_{31} = -2 \\ r_3: 3x_{11} + x_{21} + 2x_{31} = -3 \end{array} \quad \begin{array}{l} r_1 + r_3: 4x_{11} = -4 \Rightarrow x_{11} = -1 \\ r_2: 2x_{21} = 4x_{31} \\ \text{Ili} x_{31} = p, p \in \mathbb{Q} \Rightarrow x_{21} = 2p \end{array}$$

$$\begin{array}{l} r_4: x_{12} - x_{22} + 2x_{32} = -2 \\ r_5: 2x_{12} + 2x_{22} - 4x_{32} = 0 \\ r_6: 3x_{12} + x_{22} + 2x_{32} = -2 \end{array} \quad \begin{array}{l} r_4 + r_6: 4x_{12} = -4 \Rightarrow x_{12} = -1 \\ r_5: 2x_{22} = 4x_{32} + 2 \\ \text{Ili} x_{32} = q, q \in \mathbb{Q} \Rightarrow x_{22} = 2q + 1 \end{array}$$

$$\begin{array}{l} r_7: x_{13} - x_{23} + 2x_{33} = 1 \\ r_8: 2x_{13} + 2x_{23} - 4x_{33} = 2 \\ r_9: 3x_{13} + x_{23} + 2x_{33} = 3 \end{array} \quad \begin{array}{l} r_7 + r_9: 4x_{13} = 4 \quad x_{13} = 1 \\ r_8: 2x_{23} = 4x_{33} \\ \text{Ili} x_{33} = t, t \in \mathbb{Q} \Rightarrow x_{23} = 2t \end{array}$$

$$\begin{array}{l} r_{10}: x_{14} - x_{24} + 2x_{34} = 1 \\ r_{11}: 2x_{14} + 2x_{24} - 4x_{34} = -2 \\ r_{12}: 3x_{14} + x_{24} + 2x_{34} = -1 \end{array} \quad \begin{array}{l} r_{10} + r_{12}: 4x_{14} = 0 \quad x_{14} = 0 \\ r_{11}: 2x_{24} = 4x_{34} - 2 \\ \text{Ili} x_{34} = s, s \in \mathbb{Q} \\ \Rightarrow x_{24} = 2s - 1 \end{array}$$

$$X = \begin{pmatrix} -1 & -1 & 1 & 0 \\ 2p & 2q+1 & 2t & 2s-1 \\ p & q & t & s \end{pmatrix}$$