

ISNAINI KHAIRIAH
123190004
PRAK-SCPK IF E

```
p1 = [1;1];  
p2 = [1;0];  
p3 = [0;1];  
p4 = [0;0];  
p = [p1 p2 p3 p4];
```

Pendefinisian pola input

```
t1 = 1;  
t2 = 1;  
t3 = 1;  
t4 = 0;  
t = [t1 t2 t3 t4];
```

Pendefinisian target tiap variabel

```
net = newp([0 1;0 1],1);
```

Membuat *perceptron* yang dapat mengenali pola fungsi logika “or” dengan dua (2) variabel x1 dan x2

```
bobot = [-1 1];  
net.IW{1,1} = bobot;
```

Pendefinisian bobot awal

```
bias = [1];  
net.b{1} = bias;
```

Pendefinisian bias awal $b=[1]$

```
y = sim(net,p);
```

Output

```
net = train(net,p,t)
```

Perintah untuk menjalankan pelatihan *perceptron*

```
disp (net.IW{1,1})
```

Menampilkan nilai bobot optimal

```
disp (net.b{1})
```

Menampilkan nilai bias optimal

Neural Network Training (nntraint...)

Neural Network

Algorithms

Training: Cyclical Weight/Bias Rule (trainc)
Performance: Mean Absolute Error (mae)
Calculations: MATLAB

Progress

Epoch:	0	4 iterations	1000
Time:		0:00:00	
Performance:	0.250	0.00	0.00

Plots

Performance (plotperform)
Training State (plottrainstate)

Plot Interval: 1 epochs

✓ Opening Performance Plot

Stop Training Cancel

