

# PSI Comp Phys

1) a) Consider the derivatives with transient points  $x \pm \delta$  &  $x \pm 2\delta$ :

$$\begin{aligned}\tilde{f}'(x) &\equiv \frac{f(x+\delta) - f(x-\delta)}{2\delta} = \frac{1}{2\delta} \left[ f'(x) + f''(x)\delta + \frac{f'''(x)\delta^2}{2!} + \frac{f''''(x)\delta^3}{3!} + O(\delta^4) \right. \\ &\quad \left. - \left( f'(x) - f''(x)\delta + \frac{f'''(x)\delta^2}{2!} - \frac{f''''(x)\delta^3}{3!} + O(\delta^4) \right) \right] \\ &= \frac{1}{2\delta} [2f'(x)\delta + 2f'''(x)\delta^3/3! + O(\delta^4)] \\ &= f'(x) + \frac{1}{6}f'''(x)\delta^2 + O(\delta^4)\end{aligned}$$

$$\begin{aligned}\tilde{f}'(x) &\equiv \frac{f(x+2\delta) - f(x-2\delta)}{2(2\delta)} = \frac{1}{4\delta} [2f'(x)(2\delta) + 2f'''(x)(2\delta)^3/3! + O((2\delta)^4)] \\ &= f'(x) + \frac{2}{3}f'''(x)\delta^2 + O((2\delta)^4) \Rightarrow f'''(x) = \frac{3}{2\delta^2} [\tilde{f}'(x) - f'(x) - O((2\delta)^4)]\end{aligned}$$

Plugging  $f'''[\tilde{f}'(x)]$  in  $\tilde{f}'(x)$  gives:

$$\begin{aligned}\tilde{f}'(x) &= f'(x) + \frac{1}{6} \left( \frac{3}{2\delta^2} [\tilde{f}'(x) - f'(x) - O((2\delta)^4)] \right) \delta^2 + O(\delta^4) \\ &= f'(x) + \frac{1}{4} \tilde{f}'(x) - \underbrace{\frac{1}{4} f'(x) - \frac{1}{4} O((2\delta)^4)}_{g[\delta^4]} + O(\delta^4) \\ &\Rightarrow \tilde{f}'(x) = \frac{3}{4} f'(x) + \frac{1}{4} \tilde{f}'(x) + g[\delta^4] \\ &\Rightarrow f'(x) = \frac{4}{3} \left[ \tilde{f}'(x) - \frac{1}{4} \tilde{f}'(x) + g[\delta^4] \right] = \frac{4}{3} \tilde{f}'(x) - \frac{1}{3} \tilde{f}'(x) + \tilde{g}[\delta^4] \\ &= \frac{4}{3} \left( \frac{f(x+\delta) - f(x-\delta)}{2\delta} \right) - \frac{1}{3} \left( \frac{f(x+2\delta) - f(x-2\delta)}{4\delta} \right) + \tilde{g}[\delta^4] \\ &= \frac{4f(x+\delta) - 4f(x-\delta) - f(x+2\delta) + f(x-2\delta)}{12\delta} + \tilde{g}[\delta^4]\end{aligned}$$

normalized  $O(\delta^4)$   
functional

b) Now we wish to construct the error function  $E(\delta)$  for our derivative.

↪ First we have the theoretical error:  $E_T$ :

$$E_T(\delta) = f'(x) - g'(x) = \frac{1}{3} \tilde{f}'(x) - \frac{1}{3} \tilde{g}'(x) + \tilde{g}[\delta^4] - g'(x)$$

$$= \frac{4}{3} f'(x) + \frac{2}{9} f'''(x) \delta^2 + \frac{1}{90} f''''(x) \delta^4 + O(\delta^5) - \frac{1}{3} f'(x) - \frac{2}{9} f'''(x) \delta^2 \\ - \frac{4}{45} f''''(x) \delta^4 + O(2\delta)^5 + \tilde{g}[\delta^4] - g'(x)$$

$$= \underbrace{-\frac{7}{90} f''''(x) \delta^4}_{\text{take modulus}} + \underbrace{O(\delta^5)}_{j[\delta^4, \delta^5]} + \underbrace{O(2\delta)^5}_{O(\delta^4), O(2\delta)^4, O(\delta^5), O(2\delta)^5} + \tilde{g}[\delta^4]$$

functional

$$\Rightarrow E_T(\delta) \rightarrow |E_T(\delta)| = \frac{7}{90} |f''''(x) \delta^4| + j[\delta^4, \delta^5]$$

Next we have the roundoff error: which is proportional to  $f(x)/\delta$  w/ a prefactor  $\varepsilon$  s.t.  $\varepsilon \ll 1$ :

$$E_R(\delta) \propto f(x)/\delta, \varepsilon \Rightarrow E_R(\delta) \approx \varepsilon |f(x)/\delta|$$

Thus the error function we wish to minimize is the sum of the errors squared (variances) (dropping  $j[\delta^4, \delta^5] \ll 1$ ):

$$E(\delta) = |E_T(\delta)|^2 + |E_R(\delta)|^2 = \frac{49}{8100} (f''''(x))^2 \delta^8 + \varepsilon^2 f^2(x) / \delta^2$$

$$\Rightarrow \partial \delta E(\delta) = \frac{98}{2025} (f''''(x))^2 \delta^7 - 2 \varepsilon^2 f^2(x) / \delta^3$$

$$\Rightarrow \frac{98}{2025} (f''''(x))^2 \delta^7 = \frac{2 \varepsilon^2 f^2(x)}{\delta^3} \Rightarrow \delta^10 = \frac{2025}{98} \frac{2 \varepsilon^2 f^2(x)}{(f''''(x))^2}$$

$$\Rightarrow \delta_0 = \sqrt[10]{\frac{2025}{196}} \sqrt{\frac{\varepsilon f(x)}{f''''(x)}} \quad \left\{ \begin{array}{l} \text{Optimal } \delta \end{array} \right.$$

Now we wish to see if our  $\hat{S}_0$  results in a proper estimation for  $f(x) = e^x$ ,  $e^{x/100}$

$$f(x) = e^x : f'''(x) = f(x) = e^x \Rightarrow \hat{S}_0(x) = \sqrt{\frac{2025}{196}} \sqrt{\frac{\varepsilon e^x}{e^x}}$$

$$\Rightarrow \hat{S}_0 = \sqrt{\frac{2025}{196}} \sqrt{\varepsilon}$$

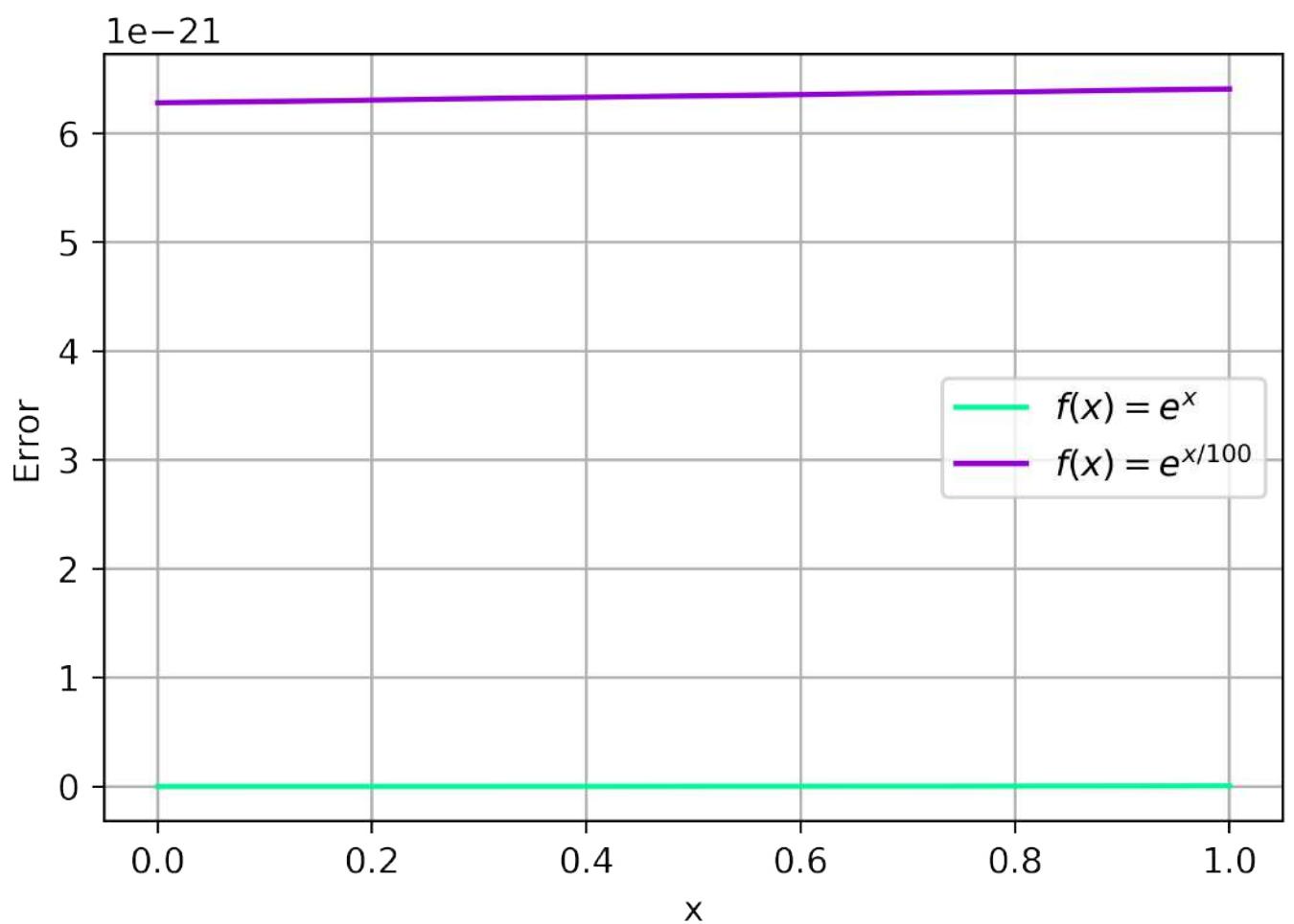
$$\Rightarrow E(x; \hat{S}_0) = \frac{49}{8100} e^{2x} \hat{S}_0^8 + \varepsilon^2 e^{2x} / \hat{S}_0^2$$

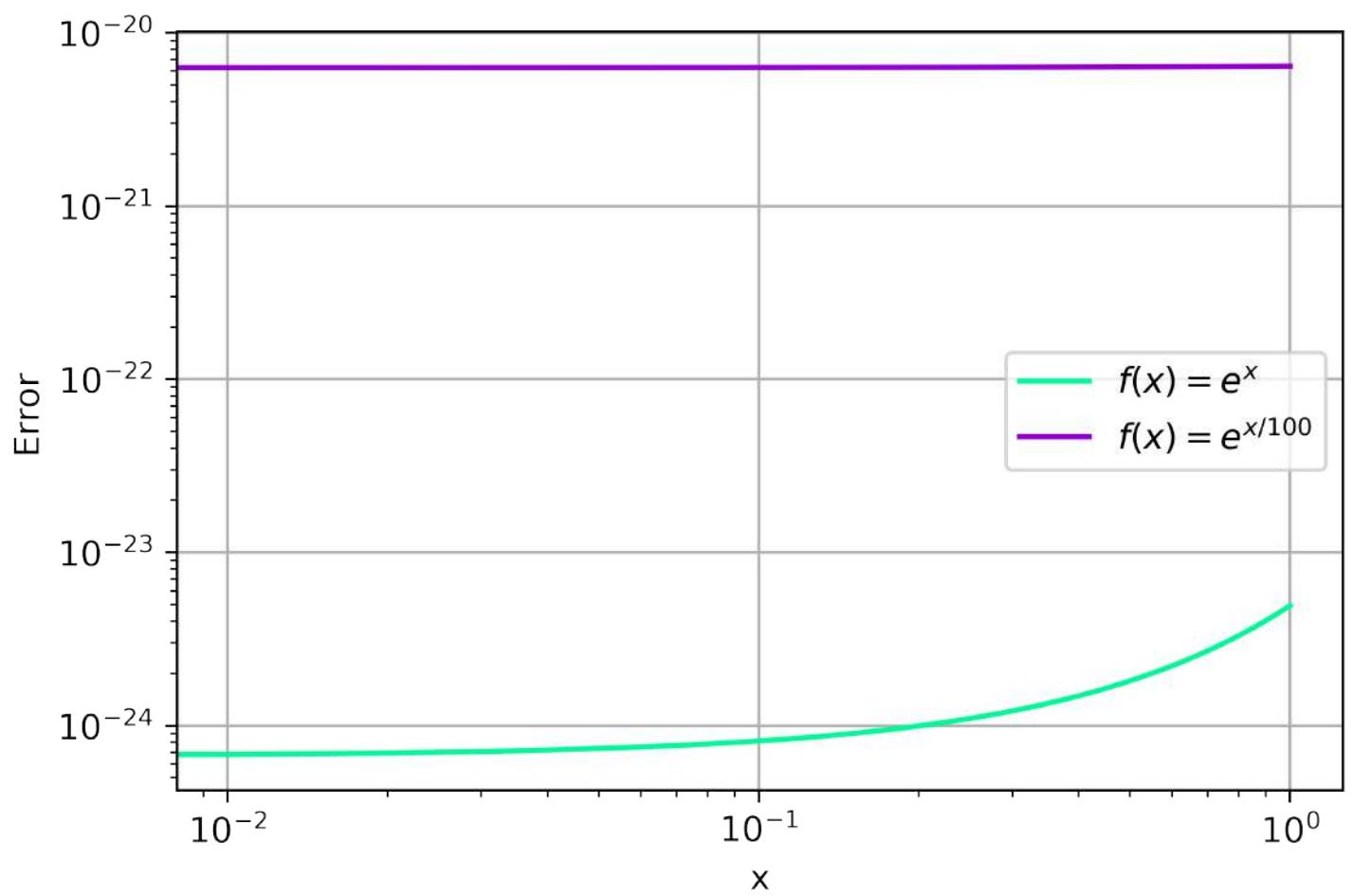
$$f(x) = e^{x/100} : f'''(x) = \left(\frac{1}{100}\right)^3 e^{x/100} \Rightarrow \hat{S}_0(x) = \sqrt{\frac{2025}{196}} \sqrt{\frac{\varepsilon}{100^3}} \frac{e^{x/100}}{e^{x/100}}$$

$$\Rightarrow \hat{S}'_0 = \sqrt{\frac{2025}{196}} \frac{\sqrt{\varepsilon}}{100}$$

$$\Rightarrow E(x; \hat{S}'_0) = \frac{49}{8100} \left( \left( \frac{1}{100} \right)^3 e^{x/100} \right)^2 \hat{S}'_0^8 + \varepsilon^2 e^{x/50} / \hat{S}'_0^2$$

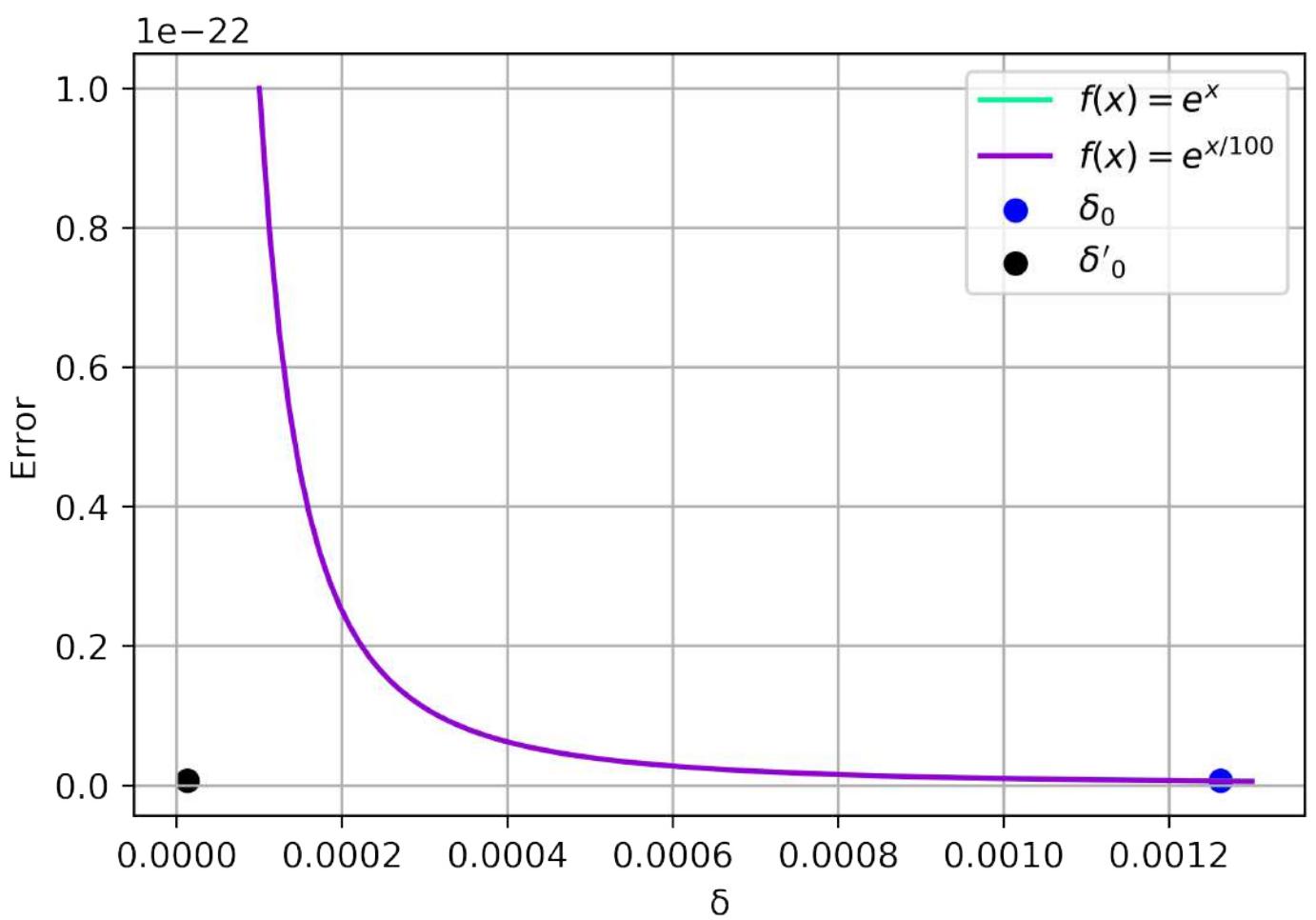
To see how good our approximation is, we shall plot  $E(x; \hat{S})$  for  $x \in [0, 1]$ . For  $\varepsilon \sim 10^{-15}$  for normal & logarithmic axes:





As can be seen above, we have  $E(x; \delta) \sim O(10^{-21})$   
which is a sufficient estimate ( $O(10^{21})$  &  $O(10^{20})$ ) for the  
log-log plot).

We can also fix  $x = 0$  & plot for different  $\delta$  to see how  
our approximation holds:



Once again we have  $O(10^{-2})$  for error which is sufficient.

↳ We can see so results in minimal error while  
so does not

Let  $\partial x \equiv h$

2) Consider  $f'(x) = \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$

Proceeding analogously from what was done in 1)b)  
as in class, for  $\varepsilon \in \mathbb{R}$  we can write the error function:

$$E(h) = h^2 f''' + \varepsilon f/h$$

We can then again minimize this w.r.t  $h$  to get:

$$0 = \partial_h E \Big|_{h=h_0} = \frac{1}{3} h_0^2 f''' + \varepsilon f/h_0^2 \Rightarrow \frac{1}{3} h_0 f''' = \varepsilon f/h_0^2 \Rightarrow h_0 = \sqrt[3]{\frac{3\varepsilon f}{f'''}} \cdot \sqrt{\frac{2}{3}}$$

For this estimate to work we need an expression for  $f''(x)$ ,  
so we will once again expand:

$$f(x \pm h) = f(x) \pm f'(x)h + \frac{1}{2} f''(x)h^2 \pm \frac{1}{6} f'''(x)h^3 + O(h^4)$$

$$f(x \pm 2h) = f(x) \pm 2f'(x)h + 2f''(x)h^2 \pm \frac{4}{3} f'''(x)h^3 + O(h^4)$$

$$\Rightarrow f(x+h) - f(x-h) = 2f'(x)h + \frac{1}{3} f'''(x)h^3 + O(h^4) : A$$

$$\Rightarrow f(x+2h) - f(x-2h) = 4f'(x)h + \frac{8}{3} f'''(x)h^3 + O(h^4) : B$$

$$\Rightarrow B - 2A : f(x+2h) - f(x-2h) - 2f(x+h) + 2f(x-h) = 2f'''(x)h^3 + O(h^4)$$

$$\Rightarrow f'''(x) = \frac{f(x+2h) - f(x-2h) - 2f(x+h) + 2f(x-h)}{2h^3} + O(h^4)$$

Dropped in code

Notice!:  $f'''(x)$  has an implicit  $h$  dependence  $f(x \pm nh)$ ,  $n \in \mathbb{Z}$   
so when trying to get an optimal  $h$  we run into:

$$h_0 \sim \underbrace{\left( f(x+2h_0) - \dots \right)^{-1/3}}$$

We cannot get an explicit expression for  $h_0$ !

What do we do? Panic? OK, then what? For  $h_0$  within the argument of  $f(x \pm nh)$  in  $f''(x)$  we will take a small enough  $h$

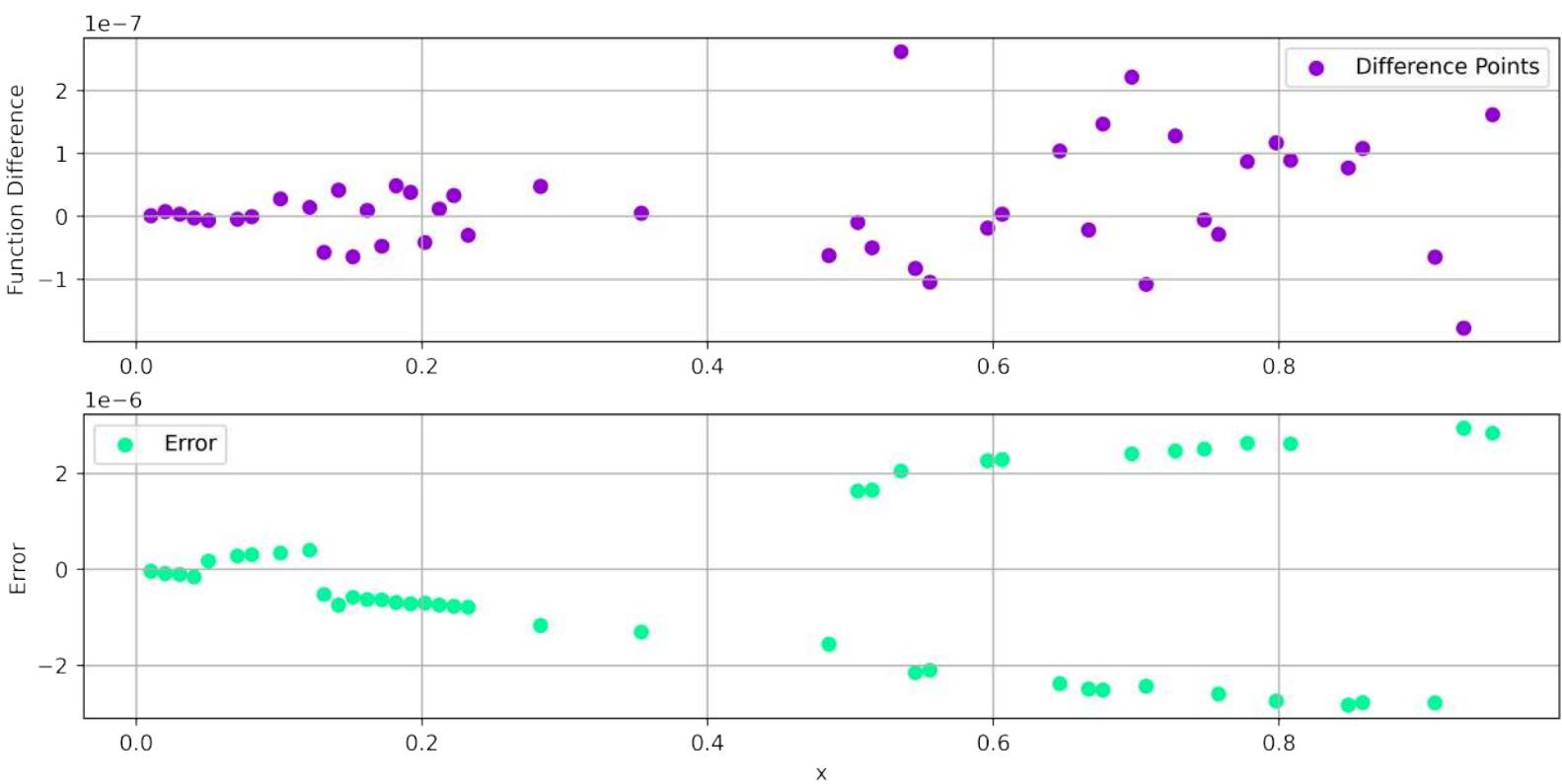
→ The error in  $h$  doesn't matter since it doesn't affect the answer directly. We call this fixed small  $h$ ,  $\gamma$ :

$$h_0(x) = \sqrt[3]{\frac{3\epsilon f(x)}{f''(x)}} = \left[ 3\epsilon f(x) \cdot \left\{ \frac{2\gamma^3}{f(x+2\gamma) - f(x-2\gamma) - 2f(x+\gamma) + 2f(x-\gamma)} \right\} \right]^{1/3}$$

where  $R \ni \epsilon, \gamma \ll 1$ . With the above expression for the optimal  $h(x)$ , we can write a numerical differentiator.

Now to test this, we choose for example  $\text{fun} = \text{np.sin}$  & plot the difference between our differentiator & the actual derivative ( $\text{ndiff}(x) - \text{np.cos}(x)$ )

→ We also plot the error  $E(x)$  in the subplot under:



As we can see, the difference between our derivative & the analytic derivative is of  $O(10^{-7})$  & the error is of order  $O(10^{-6})$

→ Note: To get the error at  $x$  you must run  
`ndiff(func, x, True)[1]`. The [1] is because when  
Full = True, `ndiff` returns (derivative, error)

Moreover we can make `ndiff` take in arrays by differentiating between points & arrays via:

if `np.isscalar(x) == True`

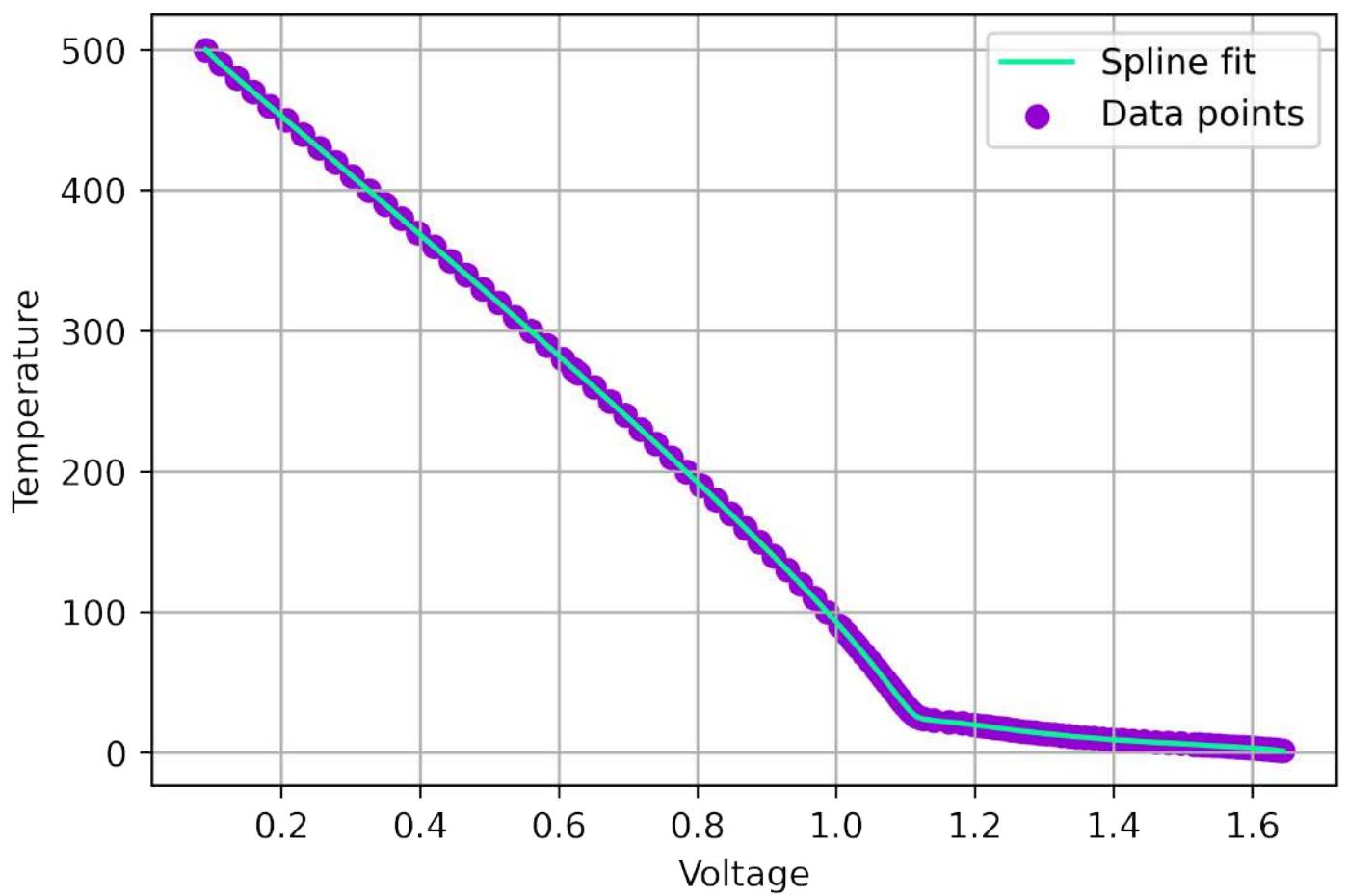
Turn all you need to do is act ndiff on the array  $x$ , I have not done it as I am behind in string lectures.

$$3) I = 10 \mu A = 10(10^{-9}) A = 10^{-10} A$$

For the first part of the question, to have a routine that takes in an arbitrary  $V$  & returns a  $T$ , we fit a cubic spline through the points

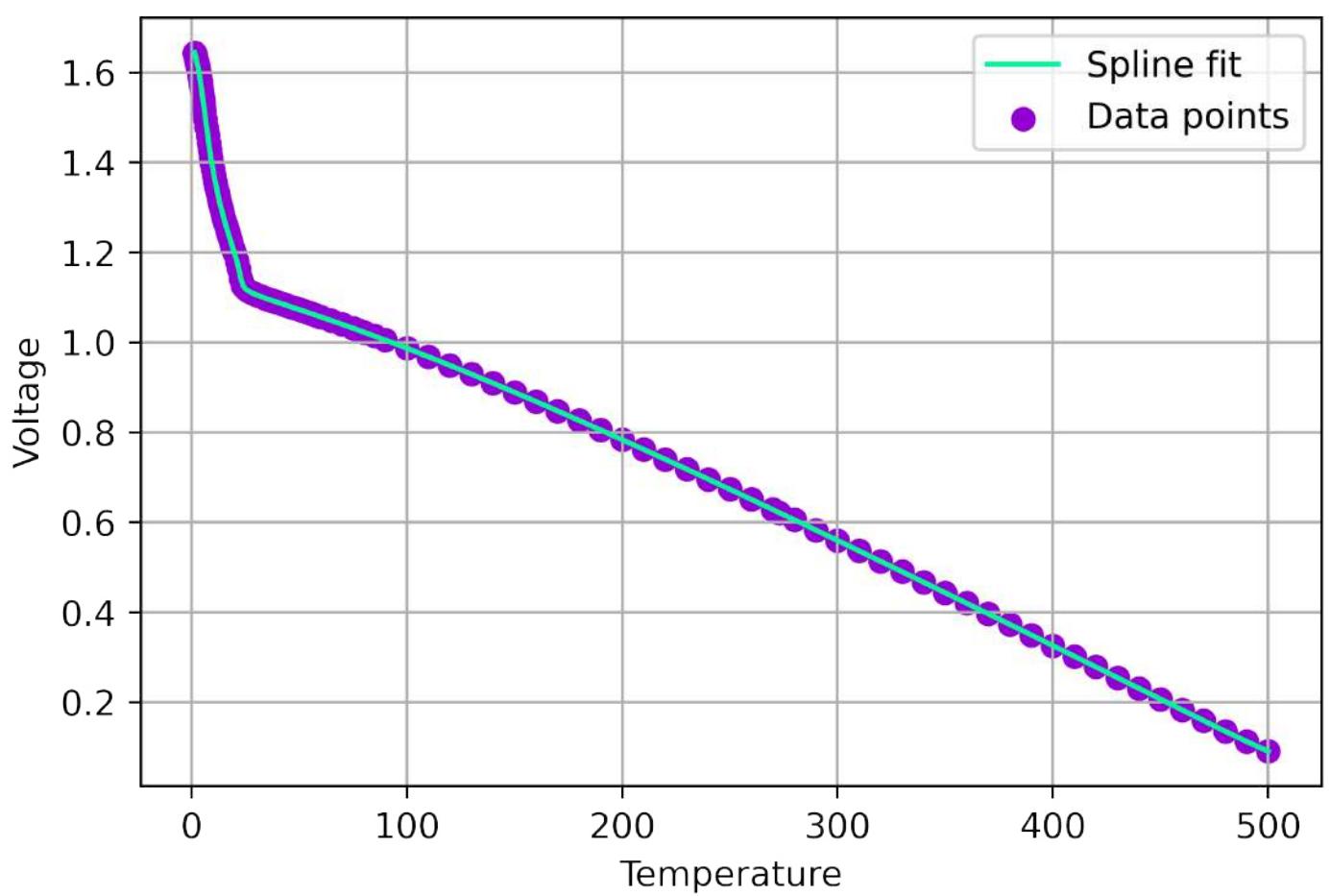


→ This allows us to interpolate any values between the data points & the fit looks like:

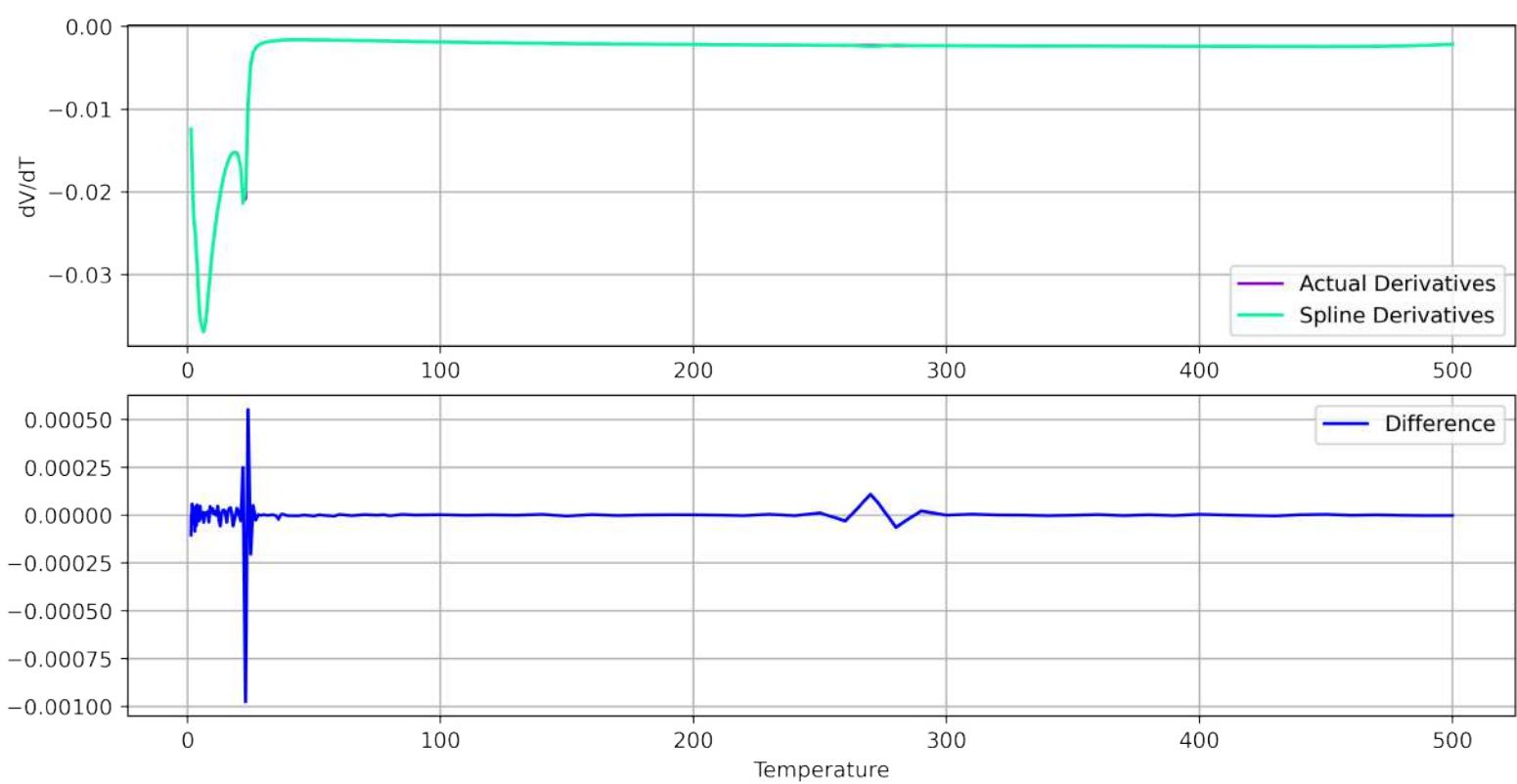


Now for the estimate I propose a possibly strange approach. The error will be a function of the derivative error (since we have  $\frac{dV}{dT}$ ) & the error in the interpolat

First, we want the error in the derivative. Initially, we must invert our  $T(V)$  interpolation to  $V(T)$  since we have  $\frac{dV}{dT}$ . This doesn't change the error & looks like:



Now, we will compute the derivative of the spline at each point & then plot the difference of the spline derivative to the actual derivative values  $\frac{dV}{dT}$  & this will be our derivative error. We plot the different  $\frac{dV}{dT}$  & below it the difference:



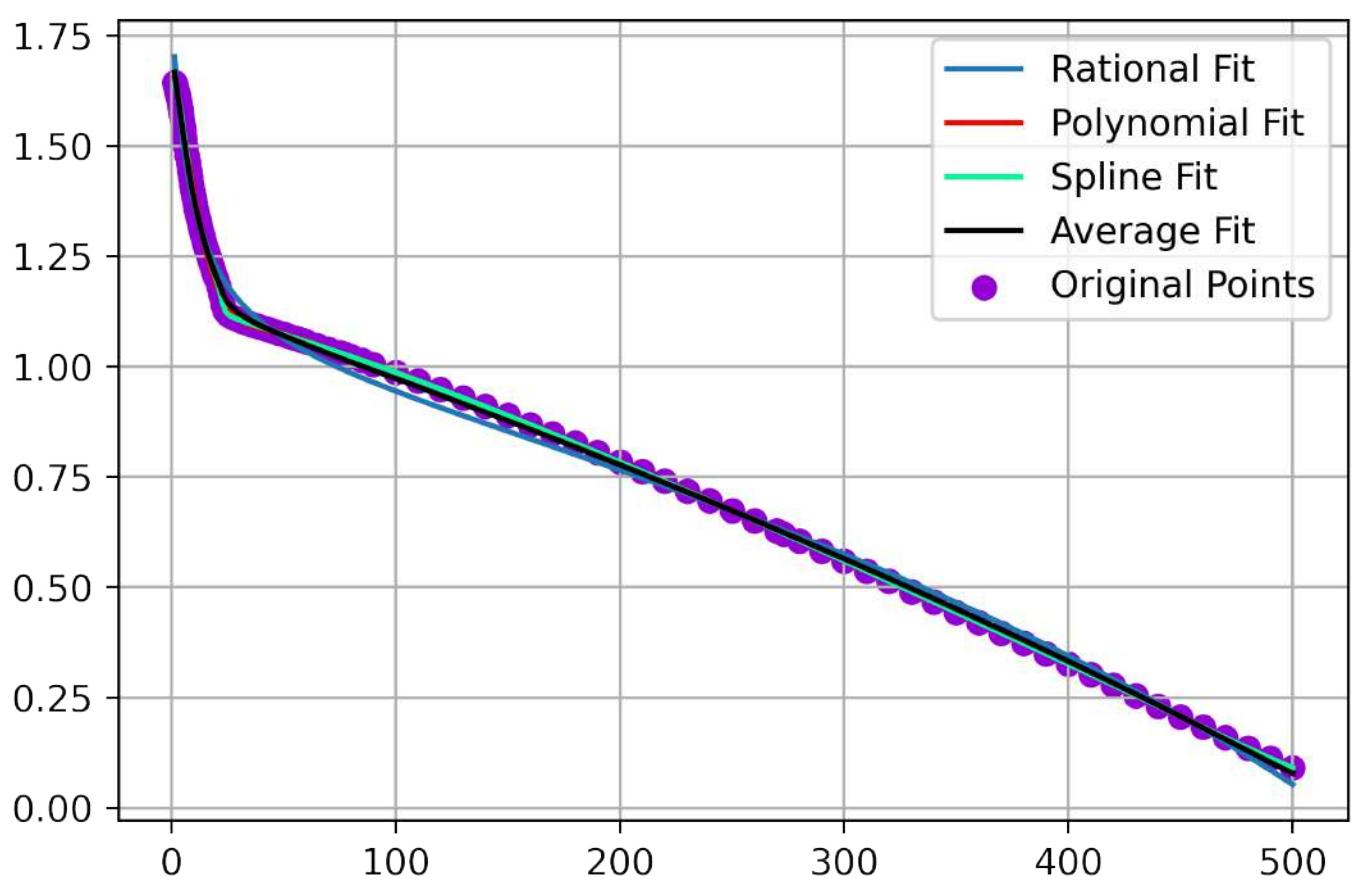
As we can see above, the derivative of the spline follows closely with the actual derivative values.

→ The difference (derivative error) is of  $O(10^{-4})$  which is decent.

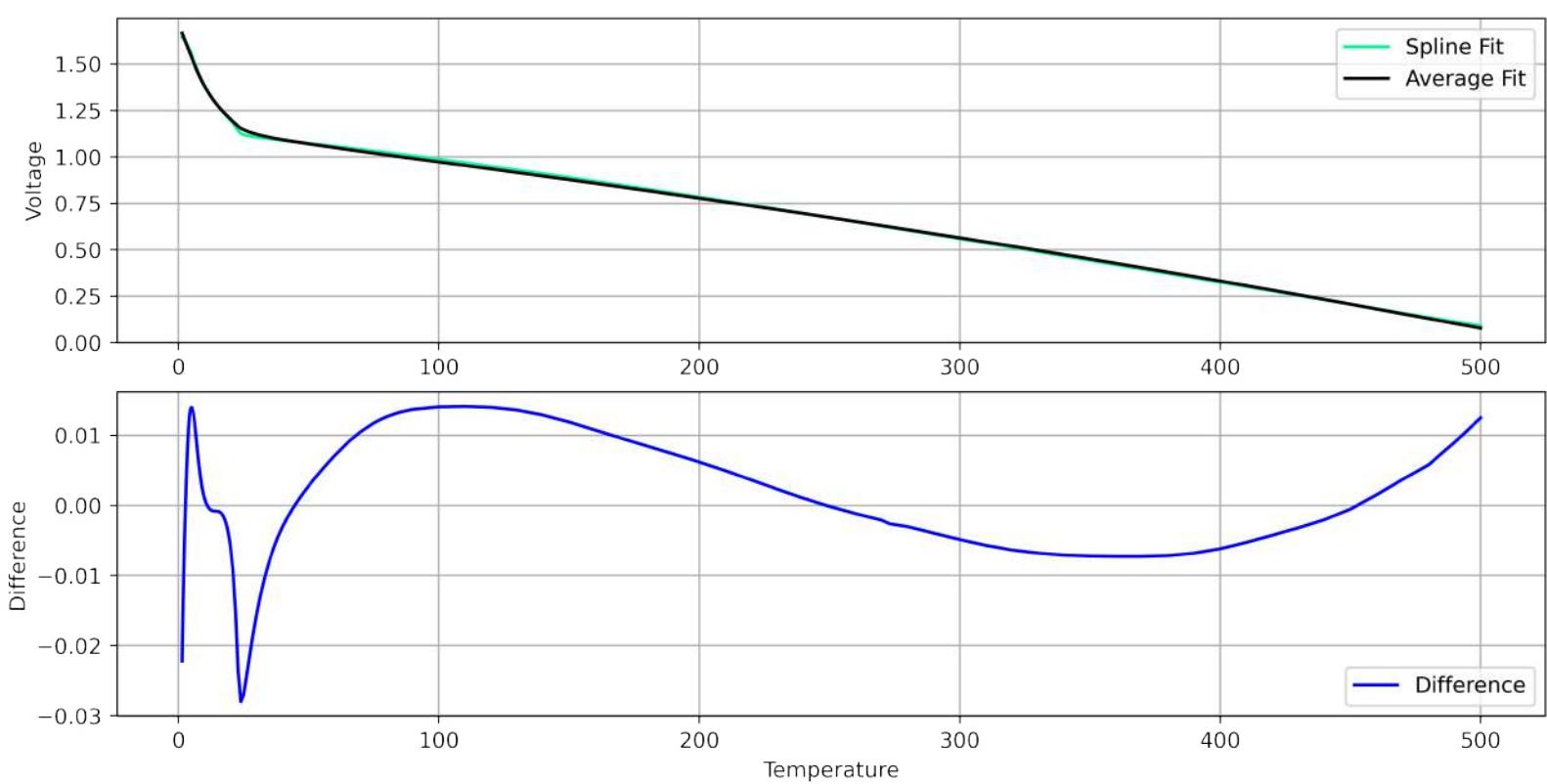
Next, we would like an estimate for the error in our spline fit values. To do so we take a somewhat naive approach.

→ Our 'true' value will be the average of a spline, polynomial & rational function fits & our error will be the difference between the 'true' values & the spline fit.

The following is a plot of all the different fits & the average of the fits ('true value').



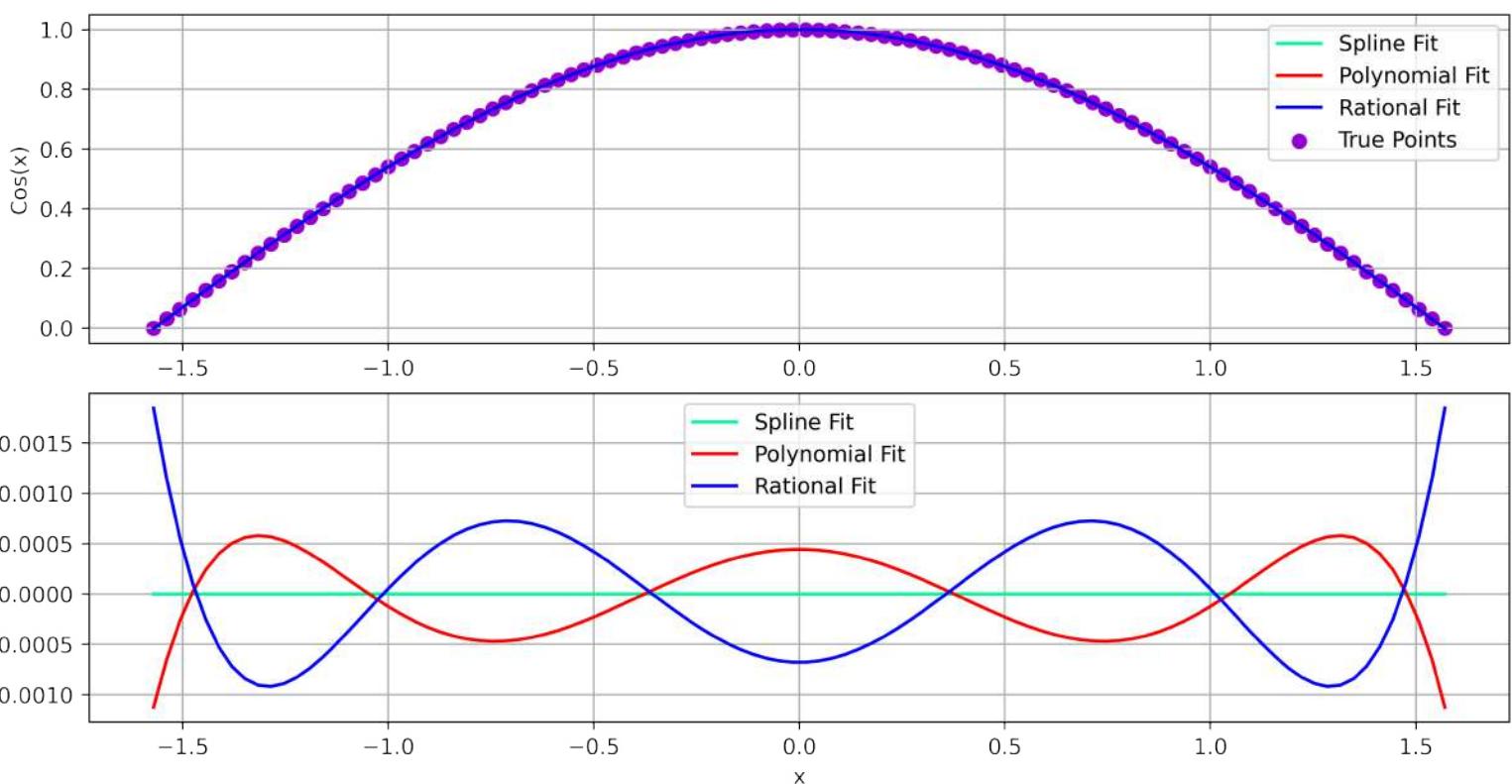
Finally, we plot just the noisy spline fit, average fit in one subplot, & in the subplot below we plot the difference between the spline fit & average plot (spline fit error):



As we can see from the plot above, our difference or error is of  $O(10^{-2})$  which is pretty poor.

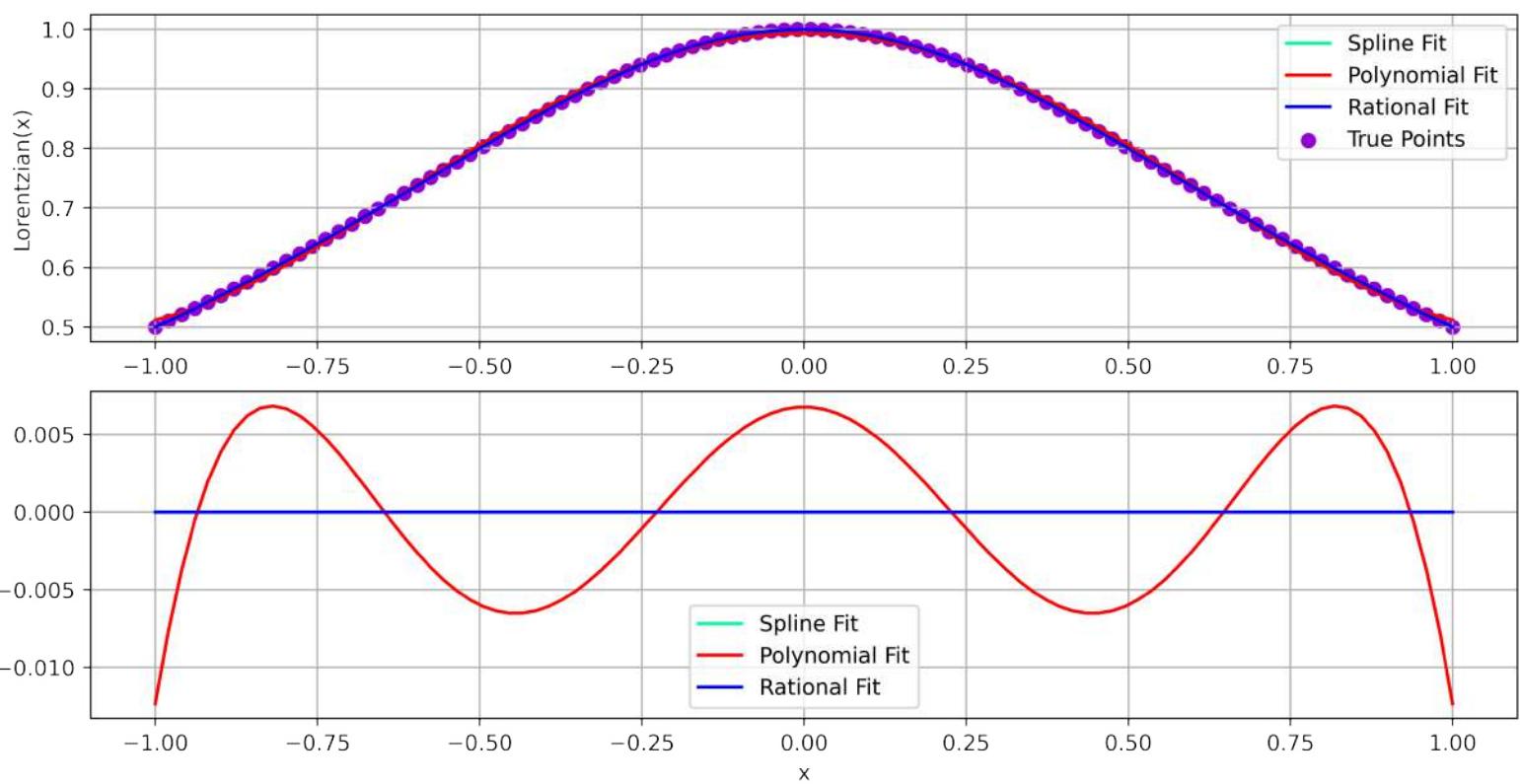
=> From the derivative of the spline error we have  $O(10^{-4})$  error while the naive 'tree' error has  $O(10^{-2})$  error  
=>  $\simeq O(10^{-3})$  error overall

4) First we fit  $\cos x$ ,  $x \in [-\frac{\pi}{2}, \frac{\pi}{2}]$  with three different fits, plot the fits (top subfigure), and plot the difference between the function values & the fit values (bottom subfigure):



As can be seen, the spline fit has an extremely small error while the polynomial & rational fit errors oscillate at  $O(10^{-3})$

Now we repeat the same for the Lorentzian:



Here we see the rational & spline fit dominate w/ extremely small error while the polynomial fit error oscillates at  $O(10^{-3})$

The error of the Lorentzian with a rational function fit in principle (in practice) is zero as the Lorentzian is a rational function.

↳ What we have agrees with our expectations  
For higher orders as the rational function still decays for  $x \rightarrow \pm\infty$  & thus properly fits the Lorentzian.

When we switch from np.linalg.inv to np.linalg.pinv, all the singular eigenvalues ( $\lambda_k = 0$ ) get removed/ignored

↳ Analytically this is an issue as  $\det A|_{\lambda_k=0} \rightarrow \infty$ ,  
but numerically cutting them out avoids the issue

Looking at  $P_{89}$ , using  $\text{inv}$  (instead of  $\text{pinv}$ ) results in much larger coefficient values due to inverting a matrix with near singular eigenvalues.

- ↳ This gives us a pole in the denominator & the error blows up.
- ↳ This is mitigated by using  $\text{pinv}$  which removes the singularities