

PS6 : Phys S12

1) A convolution has the following form in both the continuous & discrete limit:

$$h(y) = \int dx f(x) g(y-x) \Leftrightarrow h_i = \sum_j f_j g_{i-j}$$

We want to shift the elements of an array so we say
 $h_i = f'_i$ is the shifted array & we have:

$$f'_i = \sum_j f_j g_{i-j}$$

Here we see the purpose of g_{i-j} is to shift the elements of f_j , but how do we construct g ?

→ For a shift by γ , the new matrix should have the elements $f'_i = f_{i-\gamma}$

→ To see how this imposes a condition on g , let's expand the sum:

$$f'_i = f_0 g_{i-0} + f_1 g_{i-1} + f_2 g_{i-2} + \dots + \overbrace{f_{i-\gamma} g_{i-(i-\gamma)}}^{\gamma} + \dots + f_\gamma g_{i-\gamma} + \dots$$

Thus to have $f'_i = f_{i-\gamma}$, we look at the term $f_{i-\gamma}g_{i-(0-\gamma)} = f_{i-\gamma}g_\gamma$

↳ Naturally we set $g_\gamma = 1 \wedge g_j = 0$ for $j \neq \gamma$ & thus for a shift γ , the new element is simply:

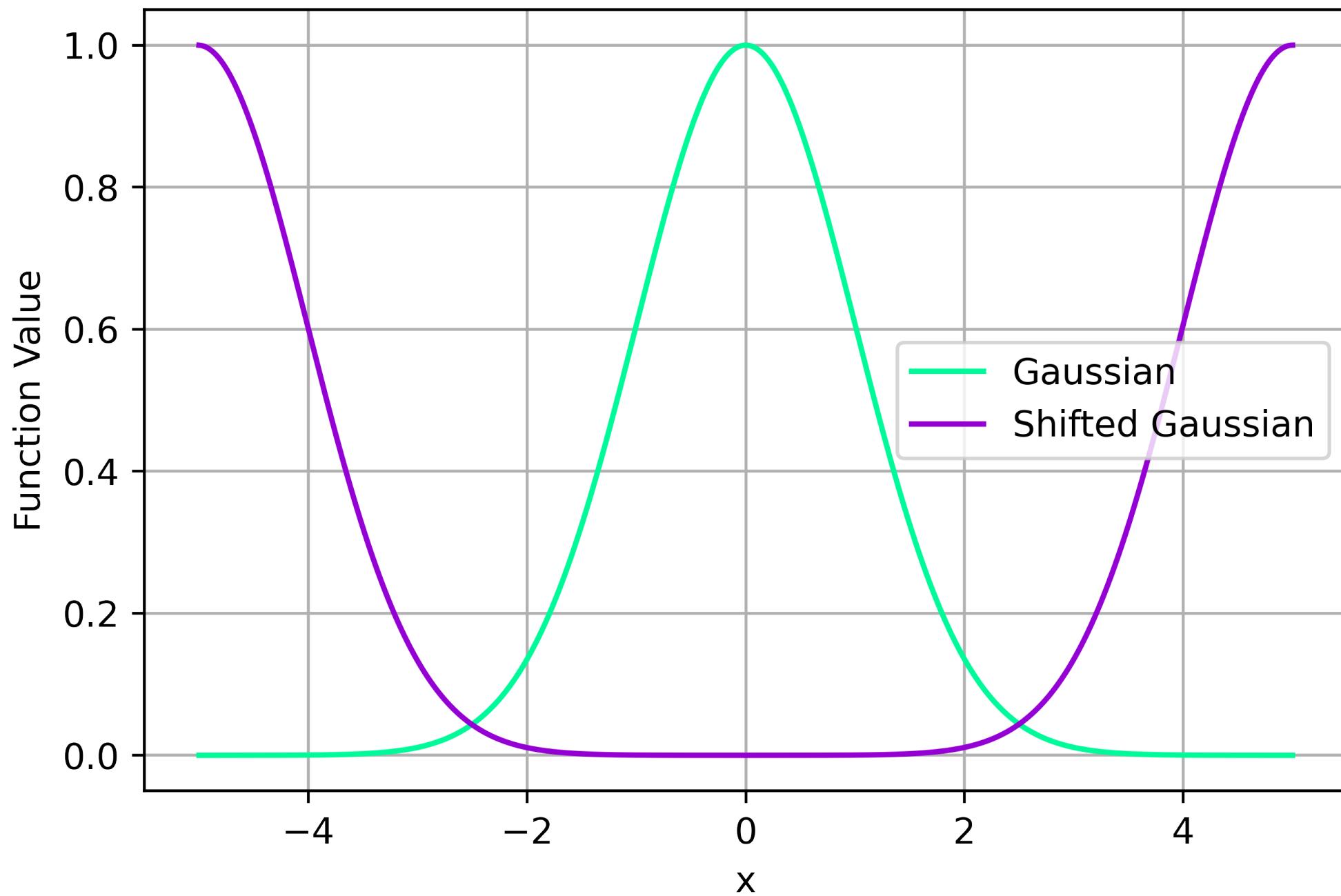
$$f'_i = \sum_j f_j g_{i-j} \rightarrow f_{i-\gamma} g_\gamma$$

Thus our routine will have $g_j = \begin{cases} 1, & j=\gamma \\ 0, & j \neq \gamma \end{cases}$ as the shifting array & we shift f_j via the convolution $f' = f * g$

↳ Moreover, to compute this we make use of the convolution theorem:

$$f' = f * g = F^{-1}[\hat{f}\hat{g}] \quad \text{w/ } \hat{f} = F[f]$$

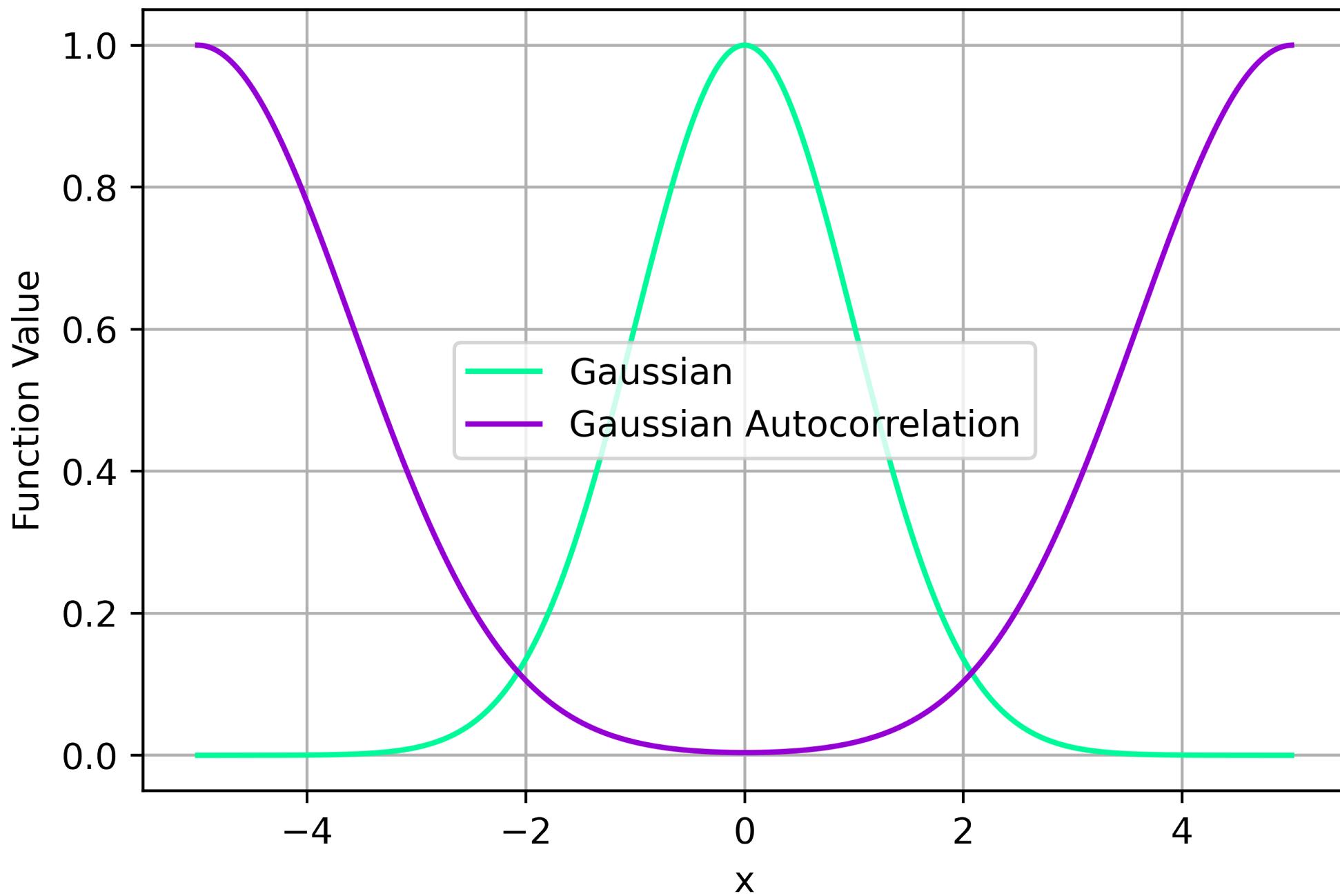
The Gaussian plot looks like the following:



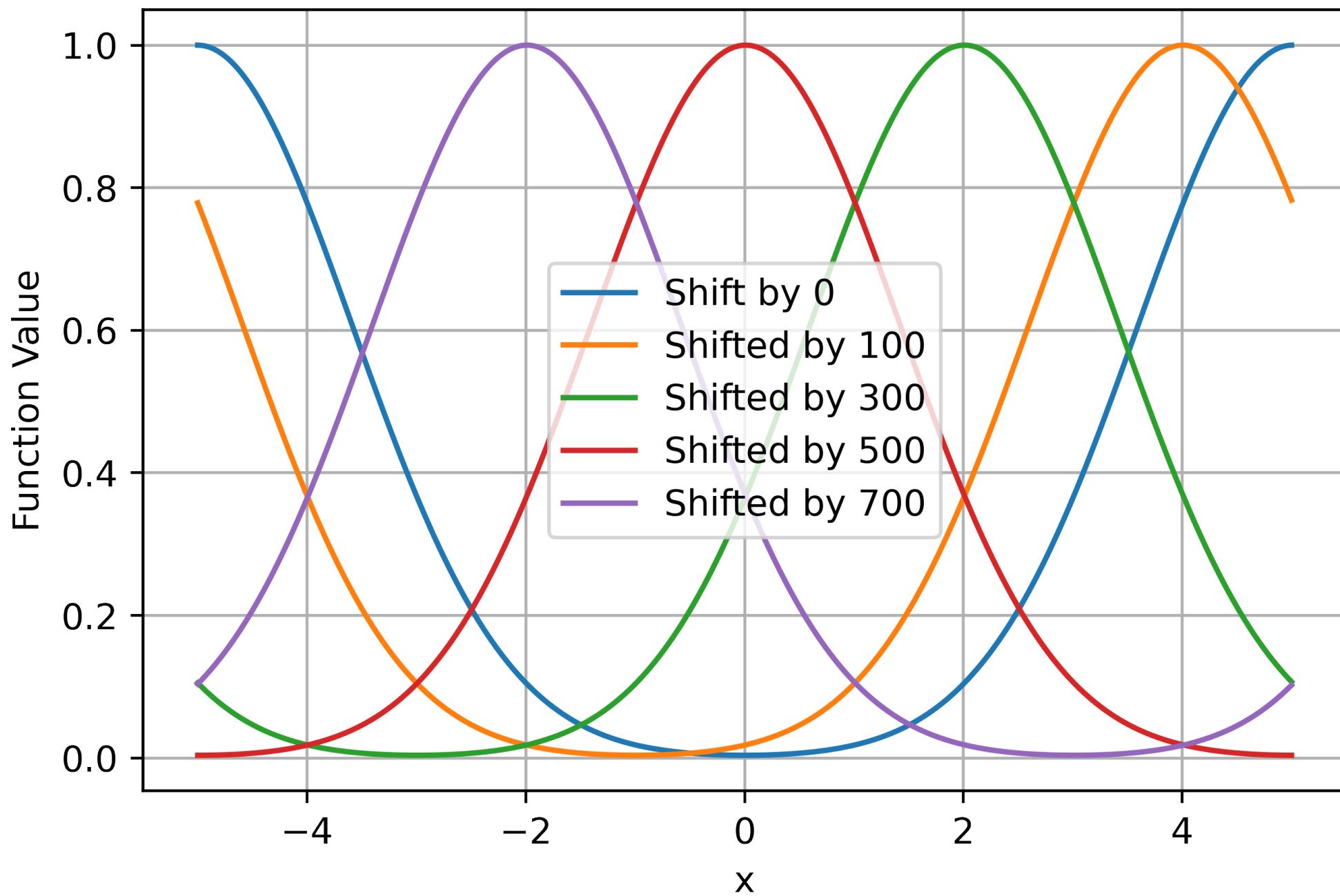
2c) Now we make use of another Fourier representation analogous for the cross correlation of two functions:

$$f' = f \otimes g = F^{-1}[\hat{f}\hat{g}^+] \text{ with } \hat{g}^+ = (\hat{g}^\top)^*$$

Using this, the correlation of the Gaussian looks like: 



b) We shift the Gaussian by different arbitrary amounts
and correlate those w/ the original Gaussian
to get the following plot:



The correlation Function depends on the shift linearly;
it simply shifts the result of the correlation by the shift

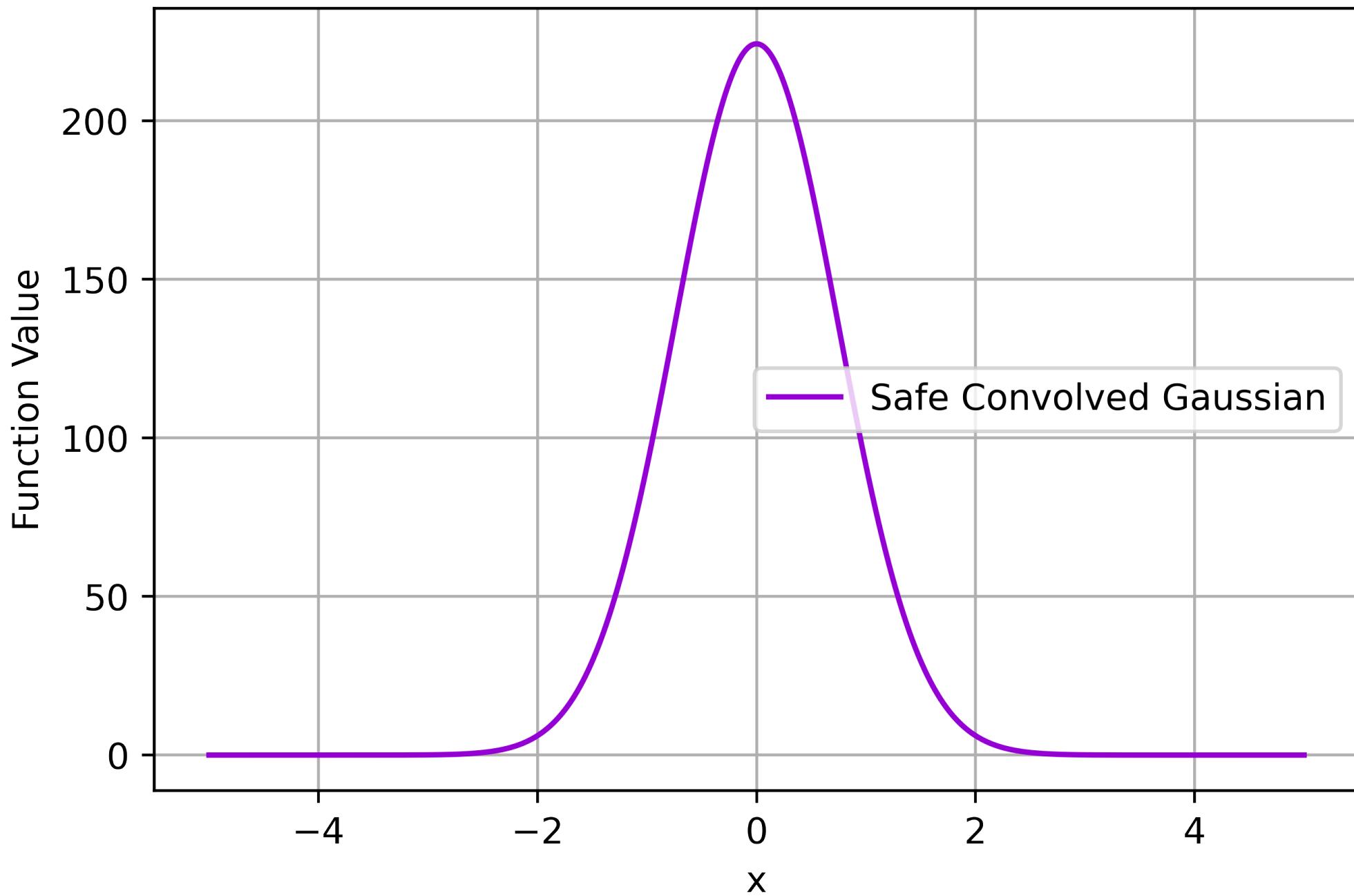
↳ This is not surprising (as hinted by Q3) of
the circulant / wrap-around nature of the DFT

3) Now we wish to write a routine that avoids
the circulant nature of the DFT

↳ This problem arises usually when the length of the
arrays mismatch and the difference gets wrapped around
via modulo

↳ To avoid this problem we pad the smaller
array w/ zeros, where the amount of zeros padded
is given by bigger Array - smaller Array

↳ The following is a plot of a convolution between
two identical Gaussians w/ one being 1000 elements
longer than the other:



$$4) a) \gamma \equiv \sum_{x=0}^{N-1} \exp(-2\pi i k x / N) = \sum_{x=0}^{N-1} \alpha^x \text{ where } \alpha = \exp(-2\pi i k / N)$$

$$\rightarrow \gamma = \sum_{x=0}^{N-1} \alpha^x = \frac{1 - \alpha^N}{1 - \alpha} = \frac{1 - \exp(-2\pi i k / N)^N}{1 - \exp(-2\pi i k / N)} = \frac{1 - \exp(-2\pi i k)}{1 - \exp(-2\pi i k / N)}$$

$$b) \lim_{k \rightarrow 0} \gamma = \lim_{k \rightarrow 0} \frac{1 - \exp(-2\pi i k)}{1 - \exp(-2\pi i k / N)} = \frac{1-1}{1-1} = 0 \quad \left. \begin{array}{l} \text{Not well} \\ \text{defined} \end{array} \right\}$$

We make use of L'Hopital's rule wrt k : (5)

$$\lim_{k \rightarrow 0} \gamma = \lim_{k \rightarrow 0} \frac{\partial_k (1 - e^{-2\pi i k})}{\partial_k (1 - e^{-2\pi i k/N})} = \left. \frac{(-2\pi i) e^{-2\pi i k}}{(-2\pi i/N) e^{-2\pi i k/N}} \right|_{k=0}$$
$$= \frac{2\pi i}{2\pi i/N} = N$$

Moreover if $n, k \in \mathbb{Z}$ such that $k \neq nN$, then:

$$\gamma = \frac{1 - e^{-2\pi i k}}{1 - e^{-2\pi i k/N}} = \frac{1 - 1}{1 - e^{-2\pi i k/N}} = 0$$

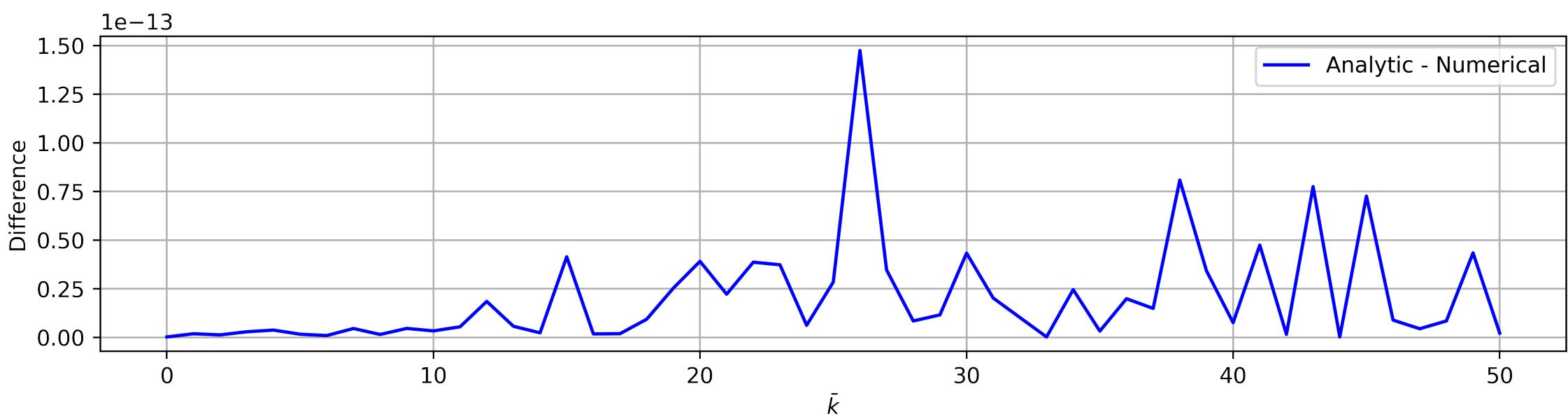
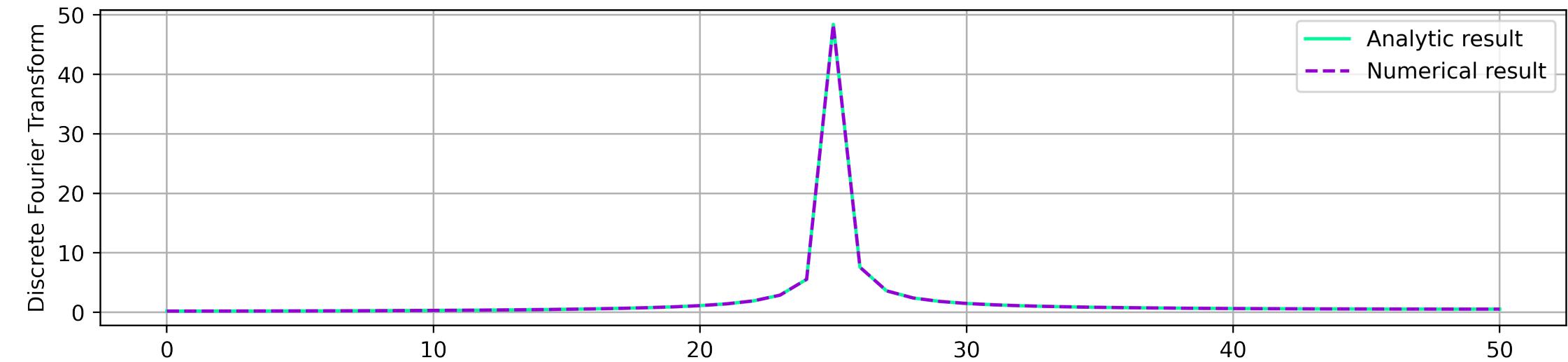
$\underbrace{1 - e^{-2\pi i k/N}}_{\neq 0} \quad \}$

c) I spent a while computing $DFT[\sin(2\pi kx)]$ analytically & using the trick(s) from Q+a-b but although the fit looked close, the difference was of order $O(10^\circ) - O(10')$

↳ If you're curious you can look at the files in the 'old' folder!

We instead will compute the DFT somewhat analytically by doing the DFT sum $\sum_{x=0}^N$ with a few for loops & compare w/ np.fft

↳ We plot our 'analytic sum estimate' w/ the python FFT & their difference for $K = 8\pi$, $N = 100$



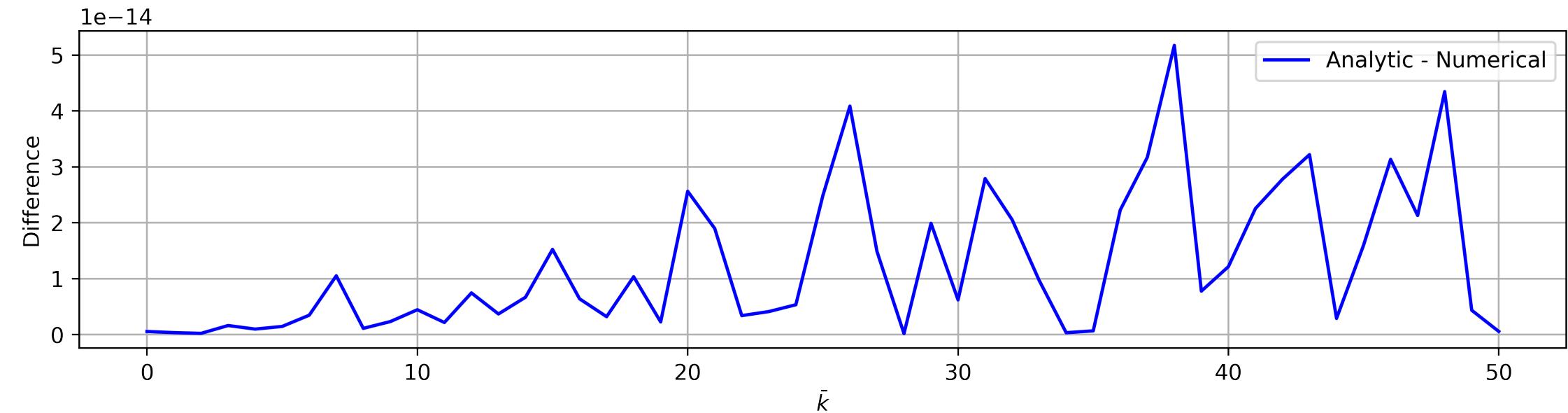
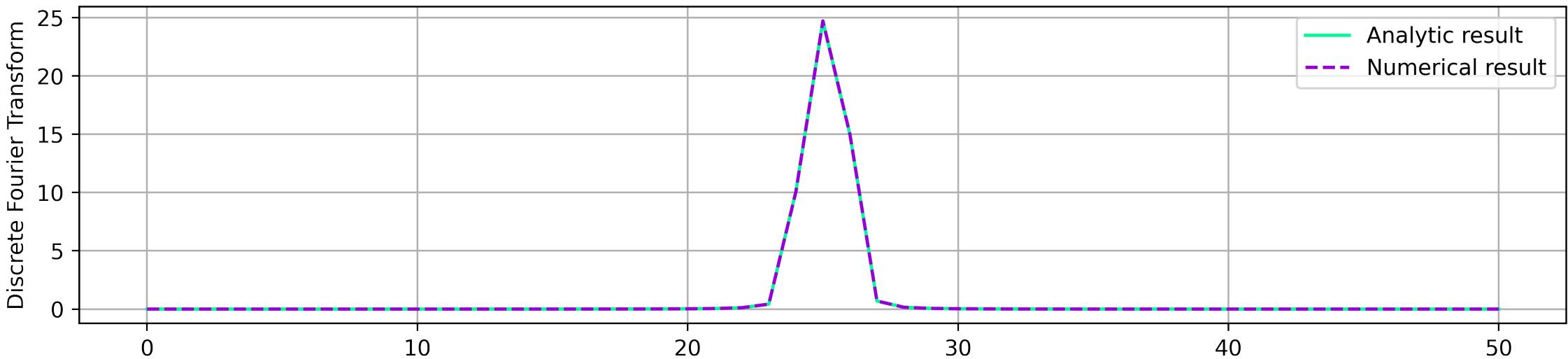
We can see they agree up to an order of magnitude $O(10^{-13})$. Not bad plotted the modulus of the complex output.

↳ This looks too rigid (not smooth) to be a perfect delta function but we're close!

c) To prevent the leakage of modes at the edges of the interval, we make use of a window function w/ decaying edges

↳ A multiplication in position space is a convolution in Fourier space

The result of windowing the input function is seen in the following:



Although the error is better ($O(10^{-14})$), the peak seems to be wider & thus deviates more from a delta. I'm not sure about this result.

e) Let's Fourier transform the window function:

$$\begin{aligned}\bar{T} &\equiv \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} dx e^{ikx} \left[\frac{1}{2} - \frac{1}{2} \cos(2\pi x/N) \right] \\ &= \frac{1}{\sqrt{8\pi}} \left[\underbrace{\int_{\mathbb{R}} dx e^{ikx}}_{\gamma_1} - \underbrace{\int_{\mathbb{R}} dx e^{ikx} \cos(2\pi x/N)}_{\gamma_2} \right].\end{aligned}$$

$$\underline{\gamma_1} : \gamma_1 = \delta(k)$$

$$\begin{aligned}\underline{\gamma_2} : \gamma_2 &= \frac{1}{2} \int_{\mathbb{R}} dx e^{ikx} \left[e^{i2\pi x/N} + e^{-i2\pi x/N} \right] \\ &= \frac{1}{2} \left[\int_{\mathbb{R}} dx e^{i(k+2\pi/N)x} + \int_{\mathbb{R}} dx e^{i(k-2\pi/N)x} \right] \\ &= \frac{1}{2} \left[\delta(k+2\pi/N) + \delta(k-2\pi/N) \right]\end{aligned}$$

$$\Rightarrow \bar{T} = \frac{1}{\sqrt{8\pi}} \left[\delta(k) + \frac{1}{2} \delta(k+2\pi/N) + \frac{1}{2} \delta(k-2\pi/N) \right]$$

We thus have 3 spikes at $N/2$, $N/4$ & $-N/4$
 \Rightarrow The Fourier transform of the window
is $[N/2 \ N/4 \ 0 \dots \ 0 \ N/4]$

FT ≡ Fourier transform

Now, we wish to show that the Fourier's window Function is recoverable by some combination of each point of the unwindowed FT & some neighbours.

Let the unwindowed FT array be $F[i]$, $i = 0, \dots, N-1$ & the FT of the window be $G[i] = [N/2, N/4, 0, \dots, 0, N/4]$ the convolution is thus:

$$Y[i] = \sum_{j=0}^{N-1} F[j] G[i-j] \quad (1)$$

The only terms that survive are $i-j = 0, 1, -1$
thus $j \geq i, i+1, i-1$:

$$\begin{aligned} Y[i] &= F[i] G[0] + F[i+1] G[1] + F[i-1] G[-1] \\ &= \frac{N}{2} F[i] + \frac{N}{4} F[i+1] + \frac{N}{4} F[i-1] \end{aligned}$$

Windowed FT recovered via
certain points of the unwindowed FT

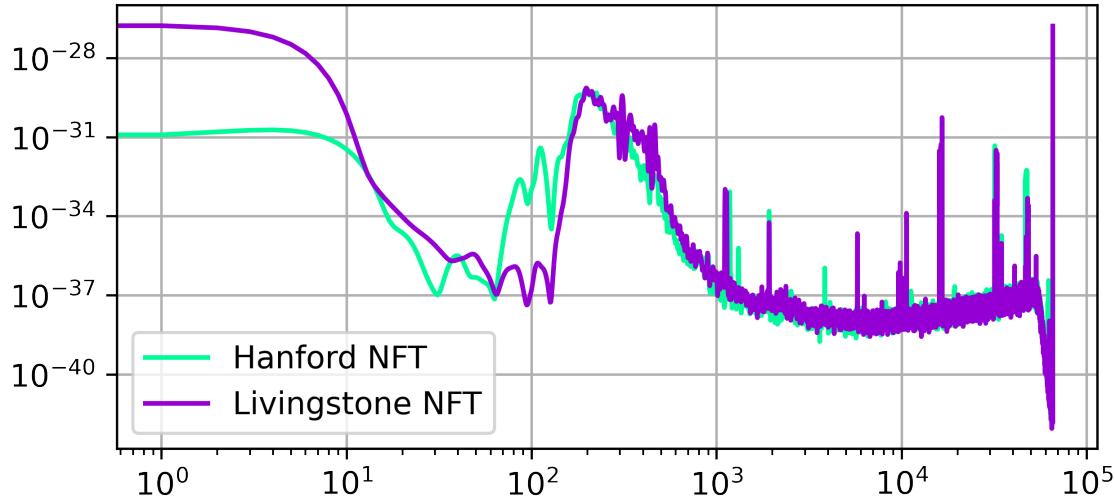
5)a) Making use of the Wiener-Khinchin theorem ($Cov(g, g)$)
 $= |F(k)|^2$, we model the noise as the power spectrum
of the strain: $F[N] = |F[S]|^2$

$\begin{matrix} \text{noise} \equiv NFT \\ \text{strain} \equiv SFT \end{matrix}$

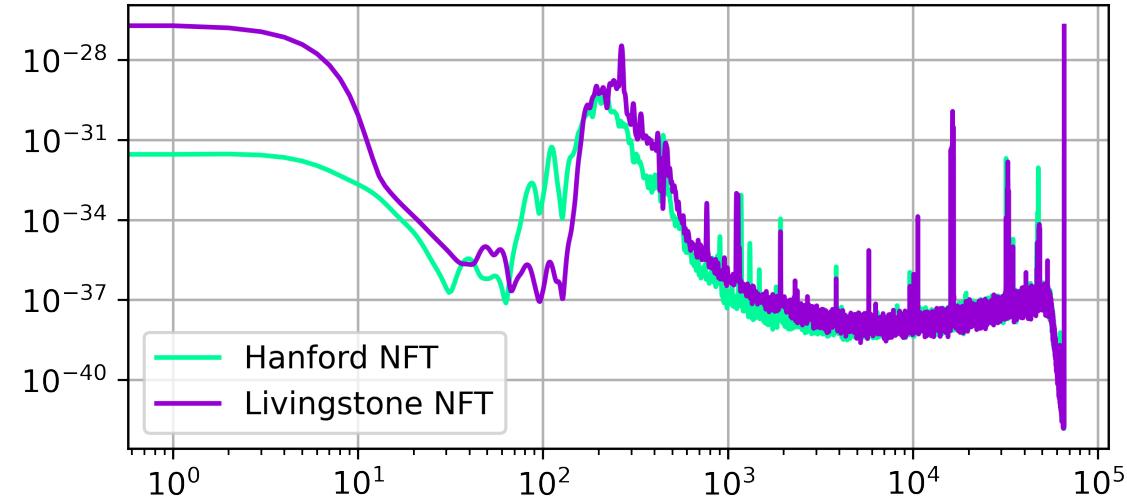
Moreover, we smooth the data by averaging the noise
w/ the flat rolling window function from class, over
the two adjacent neighbours.

→ The noise estimate for each event (NFT) can
be seen in the following plot:

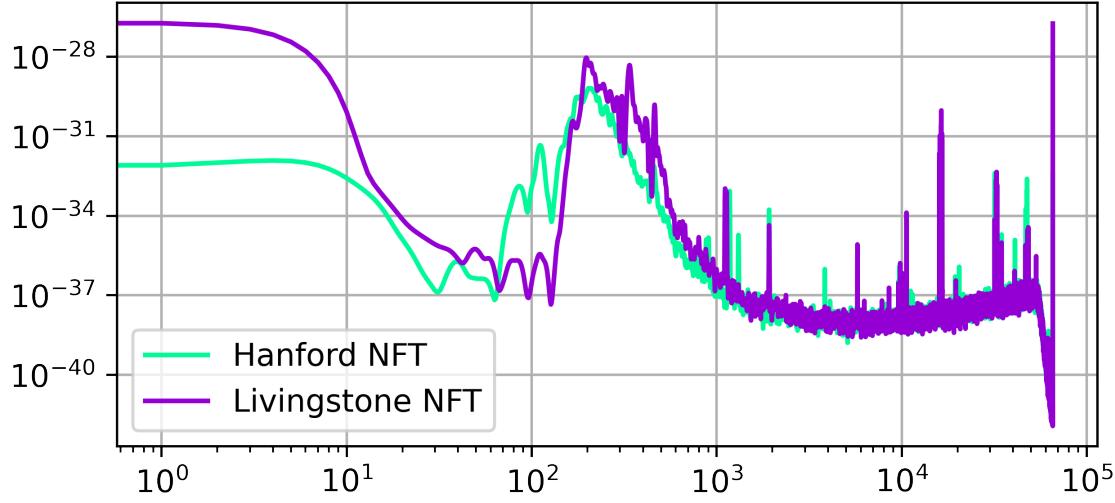
GW150914



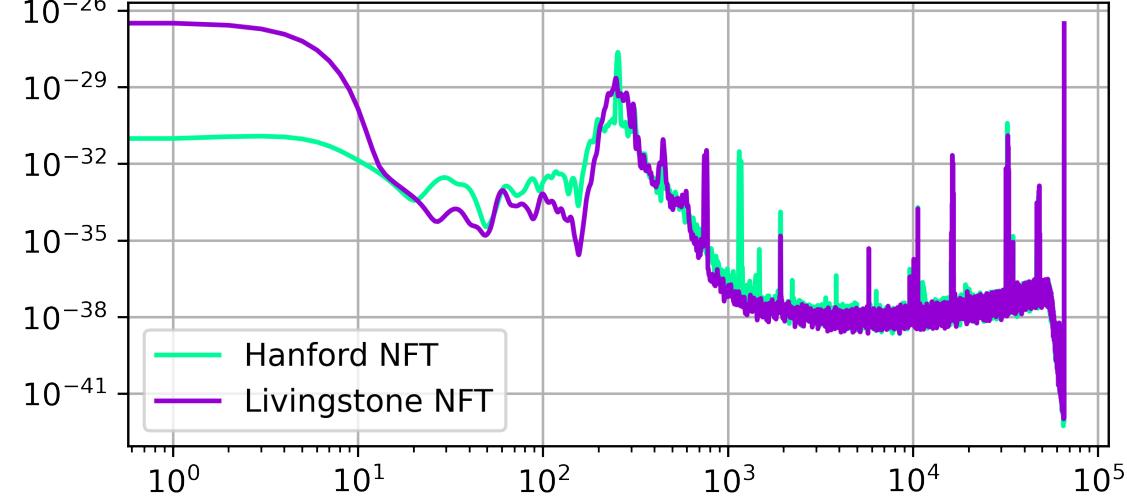
GW151226



LVT151012



GW170104

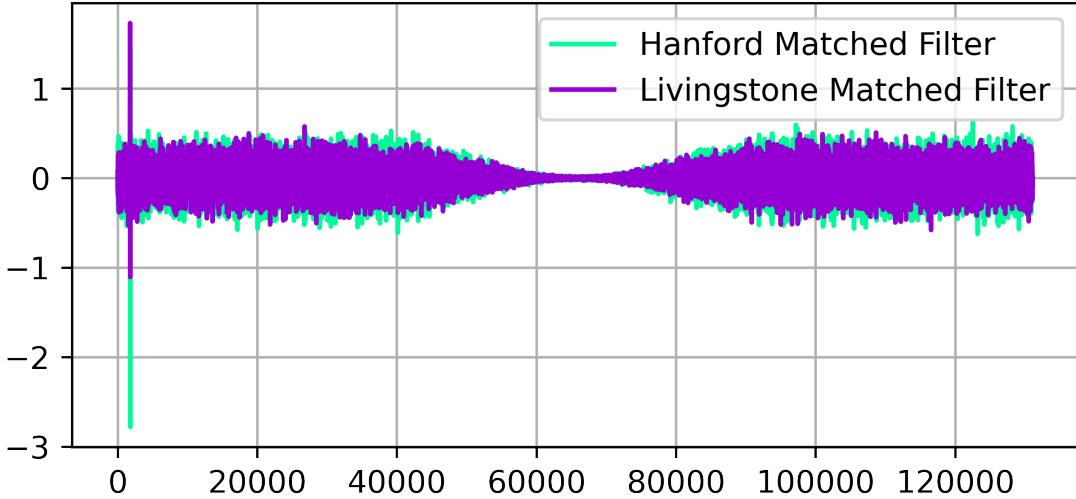


b) Now we went to search for four sets of events
for any signals lurking using a matched filter

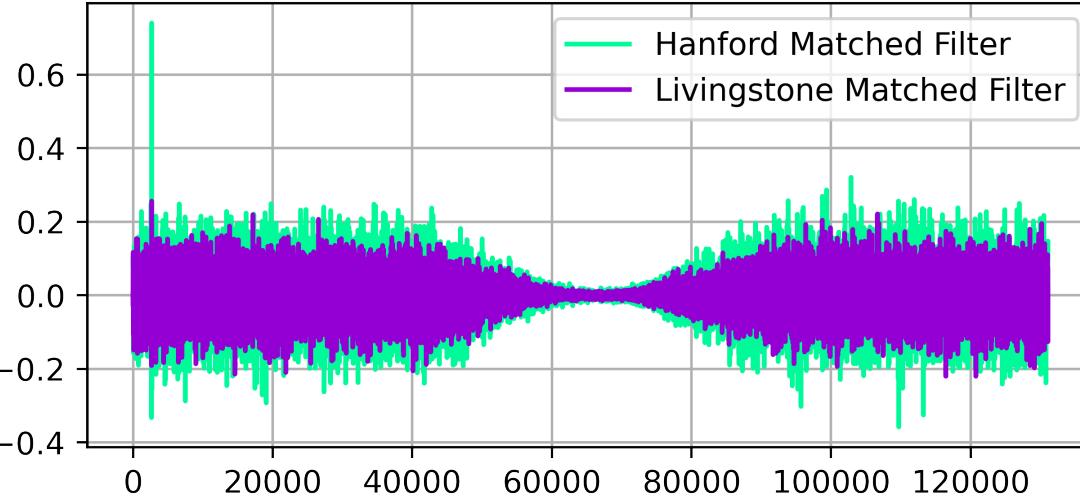
↳ We do this by cross correlation the templates with
data which should include the signal & the noise,
using FFTs

↳ The output of the match filters for each
event looks like:

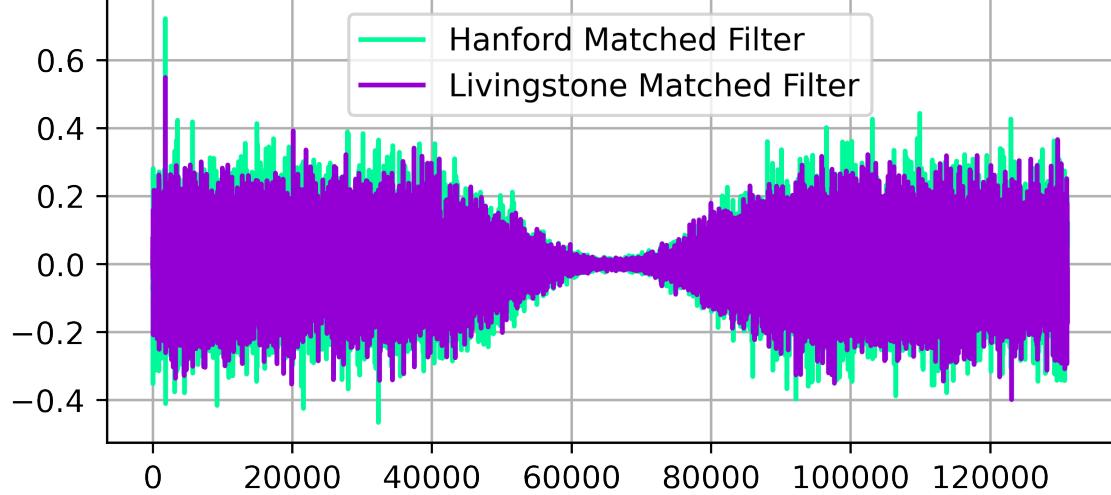
GW150914



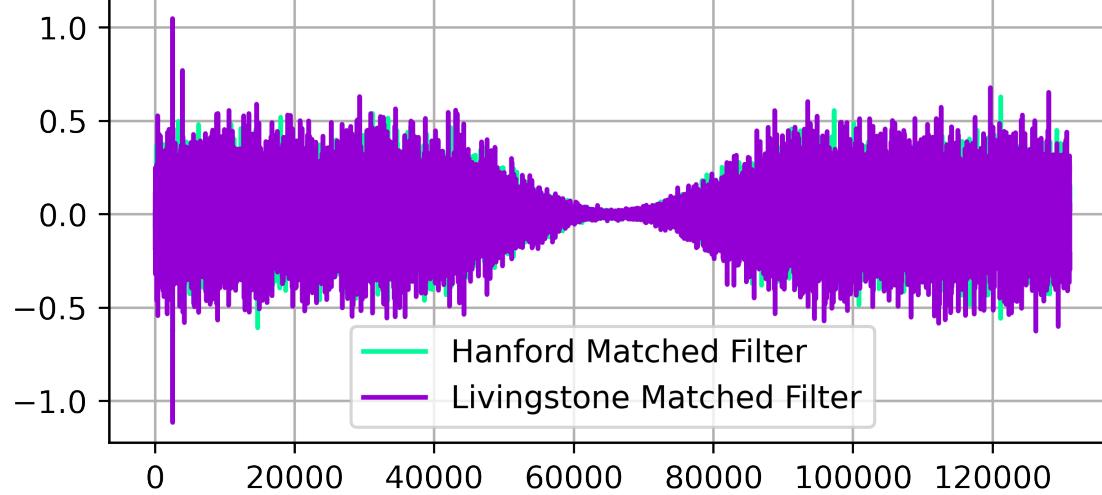
GW151226



LVT151012



GW170104



Note: We prewhitened the strain to remove spikes prior
to the matched filter.

We see the spikes on the left are the signals we
are looking for in each plot/event.

c) Now we wish to compute the signal-to-noise ratio (SNR) by taking the quotient of the match filter output to the noise estimate of each count.

→ How should we go about estimating the noise for each event? We take the std of the output of the match filter (making sure we work in the region in which the window function isn't suppressing the data) (we cut anything past 40,000 on the horizontal axis)

→ Moreover, to get the SNR for the combined data of the detectors, we do:

$$\text{SNR}_c^2 = \text{SNR}_H^2 + \text{SNR}_L^2$$

The results of the SNR analysis are the following:

GW150914: $\text{SNR}_H = 16.5964$, $\text{SNR}_L = 11.8901$, $\text{SNR}_c = 20.4160$

LVT151012: $\text{SNR}_H = 6.4956$, $\text{SNR}_L = 5.4856$, $\text{SNR}_c = 8.5020$

GW151226: $\text{SNR}_H = 9.8021$, $\text{SNR}_L = 4.7836$, $\text{SNR}_c = 10.9071$

GW170104: $\text{SNR}_H = 7.3974$, $\text{SNR}_L = 6.4062$, $\text{SNR}_c = 9.7857$

d) First we define the signal template relative to the whitened noise model as TFT

→ Then, the analytic form of the SNR is:

$$\text{SNR} = \max_R \left\{ \frac{\text{Match Filter}}{\text{std}(F^{-1}[F[TFT]])} \right\}$$

Computing this using the data for each event results in:

$$\underline{\text{GW150914}}: \text{SNR}_H = 9.8841, \text{SNR}_L = 13.6327, \text{SNR}_C = 16.7580$$

$$\underline{\text{LVT151012}}: \text{SNR}_H = 7.2475, \text{SNR}_L = 6.1777, \text{SNR}_C = 9.5613$$

$$\underline{\text{GW151226}}: \text{SNR}_H = 10.9169, \text{SNR}_L = 5.4238, \text{SNR}_C = 12.1900$$

$$\underline{\text{GW170104}}: \text{SNR}_H = 5.1512, \text{SNR}_L = 6.8138, \text{SNR}_C = 8.5414$$

The results are in same order of magnitude but not quite the values we expected.

↳ Any significant deviation is due to the noise being underestimated in the matched filter.

- c) We want to find the Frequency from each event where half the weight comes from above & below that frequency, respectively.

↳ Normally we'd set the integral over the range to $1/2$ to isolate for the frequency, but in our discrete case we do:

$$\frac{1}{2} = \frac{1}{N_{\text{data}}} \sum_{\text{normalization}} \text{TFT}(k) \quad \text{isolate for } k$$

Note: Similar to what we did in c), we take a branch cut at 6000 to avoid the TFT being suppressed by the window

→ Note: These frequencies tell us where in the noise curve where the peak signal is sitting (-Jon) δ

The results of solving the fixed, normalized sum gives us the Frequencies:

$$\text{GW150914: } f_H = 101.2188 \text{ Hz}, f_L = 115.3750 \text{ Hz}$$

$$\text{LVT151012: } f_H = 76.3438 \text{ Hz}, f_L = 95.9063 \text{ Hz}$$

$$\text{GW151226: } f_H = 74.3750 \text{ Hz}, f_L = 107.1250 \text{ Hz}$$

$$\text{GW170104: } f_H = 93.3750 \text{ Hz}, f_L = 75.4688 \text{ Hz}$$

f) Finally, we wish to localize the time of arrival of the signal & the relative positional uncertainty from the two Detectors

→ For the time localization part, I base my work Jon on Prof Dale Gary's radio astronomy lectures (G) from the NJ Institute of Technology:

$$\approx 2 \times 10^3 \text{ km}$$

Taking the detector separation to be $\Delta x \approx 2 \times 10^6 \text{ m}$, the angular position of the event signal is:

$$\Theta = \arcsin\left(\frac{ct}{\Delta x}\right)$$

ct is the path difference
Detector difference

Moreover the uncertainty propagated in the position is:

$$\sigma_\Theta = \arcsin\left(\frac{c \sigma_t}{\Delta x}\right)$$

Thus using the above we can calculate how well we can localize the time of arrival:

$$\sigma_\Theta = 2.9666^\circ$$

Moreover, we expect the typical positional uncertainty between the two detectors to be of the order $O(10^3)$ m.