# GANs Mini-Project (Week 5 Peer-Graded Assignment)

```
In [78]: # Importing required libraries
import os
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
from PIL import Image
```

### PROBLEM DESCRIPTION

This mini-project is part of a Kaggle competition, where the main goal is to build a generative adversarial network (GAN) model that generates 7,000 to 10,000 Monet-style images. More project details and the dataset can be found in the following link to Kaggle.

Kaggle source: https://www.kaggle.com/competitions/gan-getting-started/overview

Contents for this project can be accessed in the following Github Repository:

Github Repository Link: ???

```
In [79]: # Defining the directories for the image locations
         monet ipegs = "data/monet ipg/"
         photos_jpegs = "data/photo_jpg"
         monet_tfrec = "data/monet_tfrec"
         photos_tfrec = "data/photo_tfrec"
In [80]: # Reading in the Monet and test JPEG images
         monet_list = os.listdir(monet_jpegs)
         monet_images = [file for file in monet_list if file.lower().endswith('.jpg')]
         photo_list = os.listdir(photos_jpegs)
         photo_images = [file for file in photo_list if file.lower().endswith('.jpg')]
In [81]: # Convert the training and test images into multidimensional arrays
         def images_to_arrays(image_paths):
             return [np.array(Image.open(path).convert('RGB')) for path in image_paths]
         # Assuming tif_images and test_images are your lists of image filenames
         monet_arrays = images_to_arrays([os.path.join(monet_jpegs, image) for image in monet_images])
         photo_arrays = images_to_arrays([os.path.join(photos_jpegs, image) for image in photo_images])
         print(len(monet arrays))
         print(len(photo_arrays))
         300
```

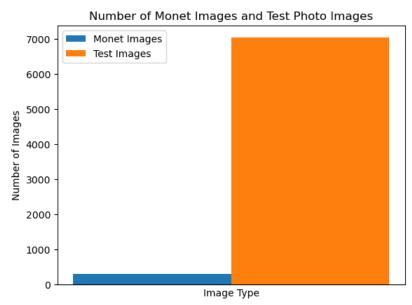
## **EXPLORATORY DATA ANALYSIS**

For the first part of exploratory data analysis, I retrieve the size of each image collection as well as the dimensions for each image in the given collections. Upon further investigation, all of the images in each collection have the same size, which is (256, 256, 3). In terms of the number of images, we are working with 300 Monet jpeg images to train with, and will prepare the GAN model as we run tests with it against the given test dataset, which contains 7,038 jpeg images. The following bar graph displays the proportion of training and test images that are involved with this project. In addition to the bar graph, there is also the inclusion of two histograms that present the frequency distributions of image values (each histogram to represent each image collection).

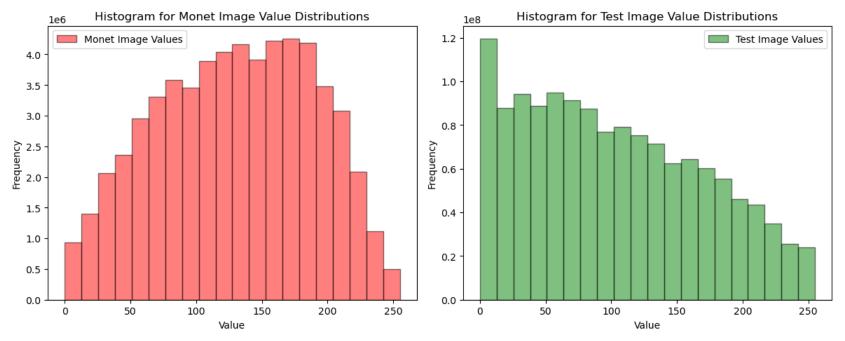
7038

The histograms reveal that there is a wide range of image values present within the input datasets (not only that, but the distribution is significantly different between the Monet images and test images). This information will be helpful to know as I move forward with setting up the GAN model architecture. I also included a helper function to clean the data, in case if there are any NULL image values or corrupted images within the datasets.

```
In [82]: # Helper function for cleaning the datasets
         def clean data(data):
             cleaned = [ele for ele in data if not np.isnan(ele).any()]
             return cleaned
In [83]: # Cleaning the data
         # Confirm that all multidimensional arrays have the same dimension
         # This is for both Monet images and the 'test' photo images
         clean data(monet arrays)
         clean_data(photo_arrays)
         for array in monet_arrays:
             if array.shape!=(256, 256, 3):
                 print(f'Different dimensions of {array.shape} for array {array}')
         for array in photo_arrays:
             if array.shape!=(256, 256, 3):
                 print(f'Different dimensions of {array.shape} for array {array}')
 In [7]: print(f"Dimensions for each Monet image: {monet_arrays[0].shape}")
         print(f"Dimensions for each 'test' photo image: {photo_arrays[0].shape}")
         Dimensions for each Monet image: (256, 256, 3)
         Dimensions for each 'test' photo image: (256, 256, 3)
 In [8]: # Create a group bar plot to show the number of Monet images and test images
         monet_count = len(monet_arrays)
         photo_count = len(photo_arrays)
         bar width = 0.22
         index = np.arange(1)
         plt.bar(index, [monet_count], bar_width, label='Monet Images')
         plt.bar(index + bar_width, [photo_count], bar_width, label='Test Images')
         plt.xlabel('Image Type')
         plt.ylabel('Number of Images')
         plt.title('Number of Monet Images and Test Photo Images')
         plt.xticks([])
         plt.legend()
         plt.show()
```



```
In [9]: # Histograms to Display Distribution of Pixel Values for each image
        # in a given list. One histogram per image collection
        # Flatten the 2D arrays to 1D arrays
        flattened_monet = np.concatenate([arr.flatten() for arr in monet_arrays])
        flattened_photo = np.concatenate([arr.flatten() for arr in photo_arrays])
        # Setting up subplots for each list
        fig, axes = plt.subplots(nrows=1, ncols=2, figsize=(12, 5))
        # Plotting histograms for each list
        axes[0].hist(flattened_monet, bins=20, alpha=0.5, label='Monet Image Values', color='red', edgecolor='black')
        axes[1].hist(flattened_photo, bins=20, alpha=0.5, label='Test Image Values', color='green', edgecolor='black')
        axes[0].set_title("Histogram for Monet Image Value Distributions")
        axes[1].set_title("Histogram for Test Image Value Distributions")
        for axis in axes:
            axis.set_xlabel('Value')
            axis.set_ylabel('Frequency')
            axis.legend()
        # Generate the plot
        plt.tight_layout()
        plt.show()
```



## THE GANS MODEL AND ARCHITECTURE

For the setup of the model, I developed a class representation of the GAN model for further training purposes. This architecture includes the generator and discriminator as internal functionality, and the generator includes the following components: an input layer that takes the form on the latent dimentions, a series of Dense layers for augmenting the data, a series of Batch Normalization layers and ELU (Exponential Linear Unit) layers to handle overfitting and apply stability during training, and a reshaping layer to have the generator output have the same dimensions as the input images. In regards to the discriminator, these components form its instrastucture: a flattened layer, a series of leaky ReLU layers, and a series of Dense layers. This is the initial architecture that I have in place before I make further optimizations. More details on the optimization process and model changes can be found in the next section.

```
In [11]: # Readingin in libraries for the GAN model architecture setup
         import keras
         from keras import layers
         from keras.layers import Input, Conv2D, BatchNormalization, Activation, Conv2DTranspose
         from keras.models import Model, Sequential
         from keras.optimizers.legacy import Adam
         from keras.applications import VGG16
         from keras.models import Model
         from keras.layers import Input
In [12]: # Preprocessing the training data
         train_data = np.array(monet_arrays)
         X_train = train_data
         X \text{ train} = (X \text{ train.astype(np.float32)} - 127.5) / 127.5
         print(X_train[0].shape)
         (256, 256, 3)
In [13]: # Preprocessing the test data
         test_data = np.array(photo_arrays)
         # Rescale pixel values to the range [0, 255]
         test_data_rescaled = [(img + 1) * 127.5 for img in test_data]
```

```
# Convert images to PIL Image format
         test_data_pil = [Image.fromarray((img * 255).astype(np.uint8)) for img in test_data_rescaled]
         # Optionally, resize images to a specific size
         target_size = (256, 256)
         test_data_pil_resized = [img.resize(target_size, Image.ANTIALIAS) for img in test_data_pil]
         # Convert PIL Images back to numpy arrays
         test data processed = [np.array(imq) for imq in test data pil resized]
         /var/folders/k1/f3l1yym17tl9cvqg5972snr00000gn/T/ipykernel_44551/2856631142.py:11: DeprecationWarning: ANTIALIAS is deprecated and will be removed in Pillow 10 (2
         023-07-01). Use LANCZOS or Resampling.LANCZOS instead.
          test_data_pil_resized = [img.resize(target_size, Image.ANTIALIAS) for img in test_data_pil]
In [14]: # GAN model
         class GAN(keras.Model):
             def __init__(self, latent_dim, img_shape, alpha=0.2, dropout=0.5, learning_rate=0.001):
                  super(GAN, self).__init__()
                  self.latent dim = latent dim
                 self.dropout = dropout
                 self.alpha = alpha
                 self.img_shape = img_shape
                 self.generator_model = None
                  self.discriminator model = None
                  self.learning_rate = learning_rate
                 self.model = Sequential()
                 self.d_loss_arr = []
                 self.g_loss_arr = []
             def convert images(test images):
                  noise = np.random.normal(0, 1, (test_images.shape[0], latent_dim))
                  synthetic_images = self.generator_model.predict(noise)
                  return synthetic_images
             def generator(self):
                  self.generator_model = Sequential(
                         keras.Input(shape=(latent_dim)),
                         layers.Dense(256, input_dim=self.latent_dim),
                         layers.ELU(alpha=self.alpha),
                         layers.BatchNormalization(),
                         layers.Dense(512),
                         layers.ELU(alpha=self.alpha),
                         layers.BatchNormalization(),
                          layers.Dense(1024),
                          layers.ELU(alpha=self.alpha),
                          layers.BatchNormalization(),
                         layers.ELU(alpha=self.alpha),
                          layers.BatchNormalization(),
                         layers.Dense(np.prod(self.img_shape), activation="tanh"),
                         layers.Reshape(self.img_shape),
                     1.
                      name="generator"
             def discriminator(self):
                 self.discriminator_model = Sequential(
```

```
layers.Flatten(input_shape=self.img_shape),
            layers.Dense(1024),
            layers.LeakyReLU(alpha=self.alpha),
            layers.Dense(512),
            layers.LeakyReLU(alpha=self.alpha),
            layers.Dense(256),
            layers.LeakyReLU(alpha=self.alpha),
            layers.Dense(1, activation="sigmoid"),
        ],
        name="discriminator"
    self.discriminator_model.compile(loss="binary_crossentropy", optimizer=Adam(lr=0.001, beta_1=0.5), metrics=['accuracy'])
def buildGAN(self):
    self.discriminator_model.trainable = False
    self.model.add(self.generator_model)
    self.model.add(self.discriminator_model)
    self.model.compile(loss="binary_crossentropy",
                       optimizer=Adam(learning_rate=self.learning_rate, beta_1=0.5))
def trainGAN(self, data, epochs, batch_size):
    for epoch in range(epochs):
        d_total_loss = 0
        g_total_loss = 0
        idx = np.random.randint(0, data.shape[0], batch_size)
        real_images = data[idx]
        noise = np.random.normal(0, 1, (batch_size, self.latent_dim))
        true_labels = np.ones((batch_size, 1))
        synthetic_labels = np.zeros((batch_size, 1))
        #input_data = np.concatenate([noise, true_labels], axis=1)
        print(noise.shape)
        generated_images = self.generator_model.predict(noise)
        d_real_loss = self.discriminator_model.train_on_batch(real_images, true_labels)
        d fake loss = self.discriminator_model.train_on_batch(generated_images, synthetic_labels)
        d_total_loss += 0.5 * np.add(d_real_loss, d_fake_loss)
        self.d loss arr.append(d total loss[0])
        self.g_loss_arr.append(g_total_loss)
        # Training the generator
        noise = np.random.normal(0, 1, (batch_size, self.latent_dim))
        generator_labels = np.ones((batch_size, 1))
        g_total_loss += self.model.train_on_batch(noise, generator_labels)
        # Print progress and save generated images at intervals
        if epochs <= 100:
            if epoch % 10 == 0:
                print(f"Epoch {epoch}, Discriminator Loss: {d_total_loss[0]}, Generator Loss: {g_total_loss}")
        else:
            if epoch % 100 == 0:
                print(f"Epoch {epoch}, Discriminator Loss: {d_total_loss[0]}, Generator Loss: {g_total_loss}")
```

12/8/23, 8:01 PM

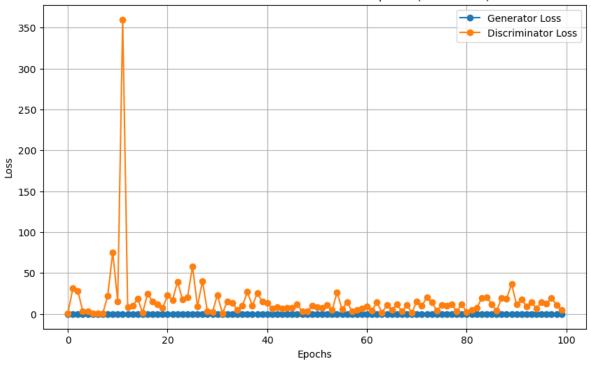
```
(16, 100)
1/1 [=======] - 0s 282ms/step
Epoch 0, Discriminator Loss: 0.8326811194419861, Generator Loss: 0.6115262508392334
1/1 [======= ] - 0s 101ms/step
(16. 100)
1/1 [======= ] - 0s 72ms/step
(16. 100)
1/1 [======] - 0s 62ms/step
(16, 100)
1/1 [======] - 0s 134ms/step
(16, 100)
(16. 100)
1/1 [=======] - 0s 67ms/step
(16. 100)
1/1 [======= ] - 0s 85ms/step
(16, 100)
1/1 [======] - 0s 62ms/step
(16, 100)
1/1 [======] - 0s 63ms/step
(16. 100)
1/1 [=======] - 0s 236ms/step
Epoch 10, Discriminator Loss: 15.456934928894043, Generator Loss: 228.24534606933594
1/1 [======= ] - 0s 79ms/step
(16, 100)
1/1 [======= ] - 0s 67ms/step
(16, 100)
1/1 [======] - 0s 77ms/step
1/1 [======= ] - 0s 67ms/step
(16, 100)
1/1 [======] - 0s 88ms/step
(16, 100)
1/1 [======= ] - 0s 130ms/step
(16. 100)
(16. 100)
1/1 [=======] - 0s 81ms/step
(16, 100)
1/1 [======] - 0s 64ms/step
(16, 100)
1/1 [======= ] - 0s 76ms/step
Epoch 20, Discriminator Loss: 22.48507857322693, Generator Loss: 57.546607971191406
(16, 100)
1/1 [====== ] - 0s 66ms/step
(16. 100)
1/1 [======= ] - 0s 60ms/step
(16, 100)
1/1 [======= ] - 0s 151ms/step
(16, 100)
1/1 [======= ] - 0s 85ms/step
(16. 100)
1/1 [======= ] - 0s 124ms/step
(16, 100)
1/1 [======= ] - 0s 69ms/step
(16, 100)
1/1 [======] - 0s 60ms/step
(16, 100)
(16, 100)
1/1 [=======] - 0s 63ms/step
1/1 [======] - 0s 63ms/step
```

```
Epoch 30, Discriminator Loss: 23.127241373062134, Generator Loss: 22.805646896362305
1/1 [======] - 0s 63ms/step
(16, 100)
(16. 100)
1/1 [======= ] - 0s 85ms/step
(16. 100)
1/1 [======] - 0s 74ms/step
(16, 100)
1/1 [======] - 0s 100ms/step
(16, 100)
1/1 [======= ] - 0s 59ms/step
(16. 100)
(16. 100)
1/1 [=======] - 0s 142ms/step
(16, 100)
1/1 [======] - 0s 66ms/step
1/1 [======] - 0s 63ms/step
Epoch 40, Discriminator Loss: 13.277485370635986, Generator Loss: 97.90290832519531
1/1 [======= ] - 0s 98ms/step
(16, 100)
1/1 [======= ] - 0s 142ms/step
(16, 100)
1/1 [======= ] - 0s 217ms/step
(16, 100)
1/1 [======] - 0s 58ms/step
1/1 [====== ] - 0s 196ms/step
(16, 100)
1/1 [======= ] - 0s 124ms/step
(16, 100)
1/1 [======] - 0s 60ms/step
(16. 100)
(16. 100)
1/1 [======= ] - 0s 62ms/step
1/1 [======] - 0s 60ms/step
Epoch 50, Discriminator Loss: 8.454237937927246, Generator Loss: 98.15725708007812
1/1 [======= ] - 0s 116ms/step
(16, 100)
(16. 100)
1/1 [======= ] - 0s 79ms/step
(16, 100)
1/1 [======] - 0s 82ms/step
(16, 100)
1/1 [======= ] - 0s 67ms/step
(16. 100)
(16, 100)
1/1 [======= ] - 0s 76ms/step
(16, 100)
1/1 [======] - 0s 78ms/step
(16, 100)
1/1 [=======] - 0s 63ms/step
1/1 [======] - 0s 72ms/step
Epoch 60, Discriminator Loss: 9.420711994171143, Generator Loss: 64.23968505859375
(16, 100)
```

```
1/1 [======] - 0s 69ms/step
(16, 100)
1/1 [======] - 0s 66ms/step
(16, 100)
(16. 100)
1/1 [======= ] - 0s 65ms/step
(16. 100)
1/1 [======] - 0s 62ms/step
(16, 100)
1/1 [======] - 0s 150ms/step
(16, 100)
1/1 [======= ] - 0s 71ms/step
(16. 100)
(16. 100)
1/1 [======= ] - 0s 71ms/step
(16, 100)
1/1 [======] - 0s 78ms/step
Epoch 70, Discriminator Loss: 15.466243743896484, Generator Loss: 53.13214874267578
1/1 [======= ] - 0s 94ms/step
(16, 100)
1/1 [======= ] - 0s 67ms/step
(16, 100)
1/1 [======= ] - 0s 92ms/step
(16, 100)
1/1 [======= ] - 0s 157ms/step
(16, 100)
1/1 [======= ] - 0s 132ms/step
1/1 [====== ] - 0s 74ms/step
(16, 100)
1/1 [======= ] - 0s 178ms/step
(16, 100)
1/1 [======] - 0s 87ms/step
(16, 100)
1/1 [======= ] - 0s 62ms/step
Epoch 80, Discriminator Loss: 2.6000486612319946, Generator Loss: 83.31434631347656
(16, 100)
1/1 [======] - 0s 65ms/step
(16, 100)
1/1 [======= ] - 0s 68ms/step
(16, 100)
1/1 [======= ] - 0s 62ms/step
(16. 100)
1/1 [=======] - 0s 146ms/step
(16, 100)
1/1 [======] - 0s 67ms/step
(16, 100)
1/1 [======= ] - 0s 72ms/step
(16. 100)
(16, 100)
1/1 [======= ] - 0s 64ms/step
(16, 100)
1/1 [======] - 0s 78ms/step
(16, 100)
1/1 [======] - 0s 80ms/step
Epoch 90, Discriminator Loss: 11.472704887390137, Generator Loss: 66.26622772216797
(16, 100)
1/1 [====== ] - 0s 74ms/step
(16, 100)
```

```
1/1 [======] - 0s 80ms/step
        (16, 100)
       1/1 [=====
        (16, 100)
       1/1 [========]
                                      - 0s 106ms/step
       (16, 100)
       1/1 [=======] - 0s 236ms/step
       (16, 100)
       1/1 [=====
        (16, 100)
       1/1 [=====
       (16, 100)
       (16, 100)
       1/1 [======= ] - 0s 77ms/step
In [16]: # Plotting the generator and discriminator loss metrics
        plt.figure(figsize=(10, 6))
        g_loss = list(gan_model0.g_loss_arr)
        d_loss = list(gan_model0.d_loss_arr)
        epoch_list = range(epochs)
       plt.plot(epoch_list, g_loss, label='Generator Loss', marker='o')
       plt.plot(epoch_list, d_loss, label='Discriminator Loss', marker='o')
        plt.title('Generator and Discriminator Loss Over Epochs (GAN Model)')
        plt.xlabel('Epochs')
       plt.ylabel('Loss')
       plt.legend()
       plt.grid(True)
        plt.show()
```

#### Generator and Discriminator Loss Over Epochs (GAN Model)



# UPDATING AND TRAINING THE GANS MODEL (OPTIMIZATION AND TUNING HYPERPARAMETERS)

According the readouts from the loss values above, the discriminator and generator values fluctuate and end up being fairly high. On the first epoch, they both start closer to zero. However, as the number of epochs increase, the discriminator values become more inconsistent and sporadic (same case with the generator). Overall, it seems that the generator is struggling to generate synthetic images that are similar to the real ones (which explains why the discriminator seems to perform well during certain epochs).

As a result, I realized that I needed to incorporate convolutions for the generator and discriminator, which would help with image processing and augmentation purposes. I decided to learn from the CycleGAN tutorial that is linked to the Kaggle competition. I followed the tutorial in order to restructure my GAN model. I followed a similar format to what was taught in the tutorial, but I also main some key changes that are different. The key differences included the following:

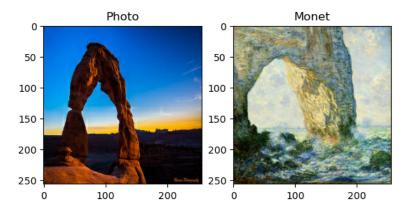
- 1.) The generator and discriminator components are set up differently. Unlike the components presented in the tutorial, the generator and discriminator components here do not depend on additional upsampling and downsampling methods (these operations are directly incorporated in the components and derives from the 'Keras' library).
- 2.) For the included optimizers, I added a learning rate with a value of 0.0001 to provide stability for the model during training procedures.
- 3.) As an additional change, I decided to switch from the the JPEG images and use the TFREC version of the images instead.

The updated GAN model seemed to perform much better for the second training process, and I decided to stay with the model for the final result. More details on the revised model architecture and training process are shown below.

```
In [17]: # Installing more required libraries
         pip install tensorflow addons
         Requirement already satisfied: tensorflow addons in /Users/israeliohnson/anaconda3/lib/python3.10/site-packages (0.23.0)
         Requirement already satisfied: packaging in /Users/israeljohnson/anaconda3/lib/python3.10/site-packages (from tensorflow addons) (22.0)
         Requirement already satisfied: typeguard<3.0.0,>=2.7 in /Users/israeljohnson/anaconda3/lib/python3.10/site-packages (from tensorflow_addons) (2.13.3)
         Note: you may need to restart the kernel to use updated packages.
In [18]: # Reading in further Python libraries for further model setup and training purposes.
         import tensorflow as tf
         from tensorflow import keras
         from tensorflow.keras import layers
         import tensorflow_addons as tfa
         import matplotlib.pyplot as plt
         import numpy as np
         /Users/israeljohnson/anaconda3/lib/python3.10/site-packages/tensorflow_addons/utils/tfa_eol_msq.py:23: UserWarning:
         TensorFlow Addons (TFA) has ended development and introduction of new features.
         TFA has entered a minimal maintenance and release mode until a planned end of life in May 2024.
         Please modify downstream libraries to take dependencies from other repositories in our TensorFlow community (e.g. Keras, Keras-CV, and Keras-NLP).
         For more information see: https://github.com/tensorflow/addons/issues/2807
           warnings.warn(
In [19]: MONET_FILES = tf.io.gfile.glob(str('data'+ '/monet_tfrec/*.tfrec'))
         PHOTO_FILES = tf.io.gfile.glob(str('data'+ '/photo_tfrec/*.tfrec'))
         # Showing the number of Monet and Test images from the TFREC collections
         print('Monet TFRecord Files:', len(MONET_FILES))
         print('Photo TFRecord Files:', len(PHOTO_FILES))
         Monet TFRecord Files: 5
         Photo TFRecord Files: 20
In [20]: # Establishing helper functions to read in the TFREC images and load the datasets.
         IMAGE SIZE = [256, 256]
```

```
def decode_image(image):
             image = tf.image.decode_jpeg(image, channels=3)
             image = (tf.cast(image, tf.float32) / 127.5) - 1
             image = tf.reshape(image, [*IMAGE_SIZE, 3])
             return image
         def read_tfrecord(example):
             tfrecord_format = {
                 "image_name": tf.io.FixedLenFeature([], tf.string),
                 "image": tf.io.FixedLenFeature([], tf.string),
                  "target": tf.io.FixedLenFeature([], tf.string)
             example = tf.io.parse_single_example(example, tfrecord_format)
             image = decode_image(example['image'])
             return image
In [21]: # Establishing helper functions to read in the TFREC images and load the datasets.
         AUTOTUNE = tf.data.experimental.AUTOTUNE
         def load_dataset(filenames, labeled=True, ordered=False):
             dataset = tf.data.TFRecordDataset(filenames)
             dataset = dataset.map(read_tfrecord, num_parallel_calls=AUTOTUNE)
             return dataset
In [22]: monet_dataset = load_dataset(MONET_FILES, labeled=True).batch(1)
         photo_dataset = load_dataset(PHOTO_FILES, labeled=True).batch(1)
In [23]: # Displaying sample images from the different datasets
         example_monet = next(iter(monet_dataset))
         example_photo = next(iter(photo_dataset))
         plt.subplot(121)
         plt.title('Photo')
         plt.imshow(example_photo[0] * 0.5 + 0.5)
         plt.subplot(122)
         plt.title('Monet')
         plt.imshow(example_monet[0] * 0.5 + 0.5)
```

#### <matplotlib.image.AxesImage at 0x176ab00d0>



```
In [24]: # The restructured generator for the updated GAN model
         def generator():
             inputs = layers.Input(shape=[256, 256, 3])
```

```
down stack = [
    layers.Conv2D(64, 4, strides=2, padding='same', activation='relu'),
    layers.Conv2D(128, 4, strides=2, padding='same', activation='relu'),
    layers.Conv2D(256, 4, strides=2, padding='same', activation='relu'),
    layers.Conv2D(512, 4, strides=2, padding='same', activation='relu'),
up_stack = [
    layers.Conv2DTranspose(512, 4, strides=2, padding='same', activation='relu'),
    layers.Conv2DTranspose(256, 4, strides=2, padding='same', activation='relu'),
    layers.Conv2DTranspose(128, 4, strides=2, padding='same', activation='relu'),
    layers.Conv2DTranspose(64, 4, strides=2, padding='same', activation='relu'),
initializer = tf.random_normal_initializer(0., 0.02)
last = layers.Conv2DTranspose(3, 4,
                              strides=2,
                              padding='same',
                              kernel_initializer=initializer,
                              activation='tanh') # (bs, 256, 256, 3)
x = inputs
# Downsampling through the model
skips = []
for down in down_stack:
    x = down(x)
    skips.append(x)
skips = reversed(skips[:-1])
# Upsampling and establishing the skip connections
for up, skip in zip(up_stack, skips):
    x = up(x)
    x = layers.Concatenate()([x, skip])
x = last(x)
return keras.Model(inputs=inputs, outputs=x)
```

```
In [25]: # The restructured discriminator for the updated GAN model
def discriminator():
    inputs = layers.Input(shape=[256, 256, 3])

x = layers.Conv2D(64, 4, strides=2, padding='same', activation='relu')(inputs)
x = layers.Conv2D(128, 4, strides=2, padding='same', activation='relu')(x)
x = layers.Conv2D(256, 4, strides=2, padding='same', activation='relu')(x)
x = layers.Conv2D(512, 4, strides=2, padding='same', activation='relu')(x)
x = layers.Conv2D(1, 4, strides=1, padding='valid')(x)
return keras.Model(inputs=inputs, outputs=x)
```

```
In [26]: # Setting up the training process for the new GAN model
             strategy = tf.distribute.experimental.TPUStrategy(tpu)
         except:
             strategy = tf.distribute.get strategy()
In [27]: # Creating generators and discriminators for the Monet images and Test images, respectively.
         with strategy.scope():
             monet_generator = generator()
             photo_generator = generator()
             monet discriminator = discriminator()
             photo discriminator = discriminator()
In [29]: # Setting up the new GAN model
         class GAN(keras.Model):
             def __init__(self,monet_generator,photo_generator,monet_discriminator,photo_discriminator,lambda_cycle=10,):
                 super(GAN, self).__init__()
                 self.m_gen = monet_generator
                 self.p gen = photo generator
                 self.m disc = monet discriminator
                 self.p_disc = photo_discriminator
                 self.lambda_cycle = lambda_cycle
                 self.d_loss_arr = []
                 self.g_loss_arr = []
             def compile(self,m_gen_optimizer,p_gen_optimizer,m_disc_optimizer,p_disc_optimizer,gen_loss_fn,disc_loss_fn,cycle_loss_fn,identity_loss_fn):
                 super(GAN, self).compile()
                 self.m_gen_optimizer = m_gen_optimizer
                 self.p_gen_optimizer = p_gen_optimizer
                 self.m_disc_optimizer = m_disc_optimizer
                 self.p_disc_optimizer = p_disc_optimizer
                 self.gen_loss_fn = gen_loss_fn
                 self.disc_loss_fn = disc_loss_fn
                 self.cycle_loss_fn = cycle_loss_fn
                 self.identity_loss_fn = identity_loss_fn
             def train_step(self, batch_data):
                  real_monet, real_photo = batch_data
                 with tf.GradientTape(persistent=True) as tape:
                     # photo to monet back to photo
                      fake monet = self.m gen(real photo, training=True)
                      cycled_photo = self.p_gen(fake_monet, training=True)
                      # monet to photo back to monet
                      fake_photo = self.p_gen(real_monet, training=True)
                      cycled_monet = self.m_gen(fake_photo, training=True)
                      # generating itself
                      same_monet = self.m_gen(real_monet, training=True)
                      same_photo = self.p_gen(real_photo, training=True)
                      # Using discriminator to check, inputing real images
                      disc_real_monet = self.m_disc(real_monet, training=True)
                      disc_real_photo = self.p_disc(real_photo, training=True)
                      # discriminator used to check, inputing fake images
                      disc fake monet = self.m disc(fake monet, training=True)
                      disc fake photo = self.p disc(fake photo, training=True)
                      # evaluates generator loss
                      monet_gen_loss = self.gen_loss_fn(disc_fake_monet)
                      photo_gen_loss = self.gen_loss_fn(disc_fake_photo)
```

```
# evaluates total cycle consistency loss
                      total_cycle_loss = self.cycle_loss_fn(real_monet, cycled_monet, self.lambda_cycle) + self.cycle_loss_fn(real_photo, cycled_photo, self.lambda_cycle)
                      # evaluates total generator loss
                      total_monet_gen_loss = monet_gen_loss + total_cycle_loss + self.identity_loss_fn(real_monet, same_monet, self.lambda_cycle)
                      total_photo_gen_loss = photo_gen_loss + total_cycle_loss + self.identity_loss_fn(real_photo, same_photo, self.lambda_cycle)
                      # evaluates discriminator loss
                      monet_disc_loss = self.disc_loss_fn(disc_real_monet, disc_fake_monet)
                      photo_disc_loss = self.disc_loss_fn(disc_real_photo, disc_fake_photo)
                  # Calculate the gradients for generator and discriminator
                  monet_generator_gradients = tape.gradient(total_monet_gen_loss,
                                                            self.m_gen.trainable_variables)
                  photo_generator_gradients = tape.gradient(total_photo_gen_loss,
                                                            self.p_gen.trainable_variables)
                  monet_discriminator_gradients = tape.gradient(monet_disc_loss,
                                                                self.m_disc.trainable_variables)
                  photo_discriminator_gradients = tape.gradient(photo_disc_loss,
                                                               self.p_disc.trainable_variables)
                  # Apply the gradients to the optimizer
                  self.m_gen_optimizer.apply_gradients(zip(monet_generator_gradients,
                                                           self.m_gen.trainable_variables))
                  self.p_gen_optimizer.apply_gradients(zip(photo_generator_gradients,
                                                           self.p_gen.trainable_variables))
                  self.m_disc_optimizer.apply_gradients(zip(monet_discriminator_gradients,
                                                            self.m_disc.trainable_variables))
                  self.p_disc_optimizer.apply_gradients(zip(photo_discriminator_gradients,
                                                            self.p disc.trainable variables))
                  self.g_loss_arr.append(total_monet_gen_loss + total_photo_gen_loss)
                  self.d_loss_arr.append(monet_disc_loss + photo_disc_loss)
                  return {
                      "monet_gen_loss": total_monet_gen_loss,
                      "photo gen loss": total photo gen loss,
                      "monet_disc_loss": monet_disc_loss,
                      "photo disc loss": photo disc loss
In [30]: # Calculating the total discriminator loss
         with strategy.scope():
             def discriminator_loss(real, generated):
                  real_loss = tf.keras.losses.BinaryCrossentropy(from_logits=True, reduction=tf.keras.losses.Reduction.NONE)(tf.ones_like(real), real)
                  generated_loss = tf.keras.losses.BinaryCrossentropy(from_logits=True, reduction=tf.keras.losses.Reduction.NONE)(tf.zeros_like(generated), generated)
                  total_disc_loss = real_loss + generated_loss
                  return total_disc_loss * 0.5
In [31]: # Computing the generator loss
         with strategy.scope():
             def generator_loss(generated):
                  return tf.keras.losses.BinaryCrossentropy(from_logits=True, reduction=tf.keras.losses.Reduction.NONE)(tf.ones_like(generated), generated)
In [32]: # Computing the cycle consistency loss
         with strategy.scope():
             def calc_gan_loss(real_image, cycled_image, LAMBDA):
```

```
loss1 = tf.reduce mean(tf.abs(real image - cycled image))
                 return LAMBDA * loss1
In [33]: # Computing the identity loss of the GAN model
         with strategy.scope():
             def identity_loss(real_image, same_image, LAMBDA):
                 loss = tf.reduce_mean(tf.abs(real_image - same_image))
                 return LAMBDA * 0.5 * loss
In [34]: # Setting up Adam optimizers for the generators and discriminators, with the added learning rate
         with strategy.scope():
             monet generator optimizer = tf.keras.optimizers.Adam(2e-4, beta 1=0.5, lr=0.0001)
             photo_generator_optimizer = tf.keras.optimizers.Adam(2e-4, beta_1=0.5, lr=0.0001)
             monet_discriminator_optimizer = tf.keras.optimizers.Adam(2e-4, beta_1=0.5, lr=0.0001)
             photo_discriminator_optimizer = tf.keras.optimizers.Adam(2e-4, beta_1=0.5, lr=0.0001)
         WARNING:absl:At this time, the v2.11+ optimizer `tf.keras.optimizers.Adam` runs slowly on M1/M2 Macs, please use the legacy Keras optimizer instead, located at `t
         f.keras.optimizers.legacy.Adam`.
         WARNING:absl:`lr` is deprecated in Keras optimizer, please use `learning_rate` or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.
         WARNING:absl:At this time, the v2.11+ optimizer `tf.keras.optimizers.Adam` runs slowly on M1/M2 Macs, please use the legacy Keras optimizer instead, located at `t
         f.keras.optimizers.legacy.Adam`.
         WARNING:absl:`lr` is deprecated in Keras optimizer, please use `learning rate` or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.
         WARNING:absl:At this time, the v2.11+ optimizer `tf.keras.optimizers.Adam` runs slowly on M1/M2 Macs, please use the legacy Keras optimizer instead, located at `t
         f.keras.optimizers.legacy.Adam`.
         WARNING:absl:`lr` is deprecated in Keras optimizer, please use `learning_rate` or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.
         WARNING:absl:At this time, the v2.11+ optimizer `tf.keras.optimizers.Adam` runs slowly on MI/M2 Macs, please use the legacy Keras optimizer instead, located at `t
         f.keras.optimizers.legacy.Adam`.
         WARNING:absl: 'Ir' is deprecated in Keras optimizer, please use 'learning rate' or use the legacy optimizer, e.g.,tf.keras.optimizers.legacy.Adam.
In [35]: # Instantiating and compiling the GAN model
         with strategy.scope():
             gan_model = GAN(
                 monet generator, photo generator, monet discriminator, photo discriminator
             gan_model.compile(
                 m_gen_optimizer = monet_generator_optimizer,
                 p_gen_optimizer = photo_generator_optimizer,
                 m_disc_optimizer = monet_discriminator_optimizer,
                 p_disc_optimizer = photo_discriminator_optimizer,
                 gen_loss_fn = generator_loss,
                 disc_loss_fn = discriminator_loss,
                 cycle_loss_fn = calc_gan_loss,
                 identity_loss_fn = identity_loss
In [36]: # Training the GAN model
         history = gan_model.fit(tf.data.Dataset.zip((monet_dataset, photo_dataset)), epochs=10)
```

```
Epoch 1/10
300/300 [===
               Epoch 2/10
300/300 [===
                       =====] - 1183s 4s/step - monet gen loss: 4.0500 - photo gen loss: 3.9548 - monet disc loss: 0.6511 - photo disc loss: 0.6391
Epoch 3/10
300/300 [=============] - 430s 1s/step - monet_gen_loss: 3.7803 - photo_gen_loss: 3.7860 - monet_disc_loss: 0.6371 - photo_disc_loss: 0.5708
Epoch 4/10
300/300 [=============] - 348s 1s/step - monet_gen_loss: 3.4509 - photo_gen_loss: 3.4310 - monet_disc_loss: 0.6170 - photo_disc_loss: 0.6340
Epoch 5/10
300/300 [===
                 :========] - 350s 1s/step - monet gen loss: 3.2897 - photo gen loss: 3.3359 - monet disc loss: 0.6314 - photo disc loss: 0.6085
Epoch 6/10
300/300 [====
               Epoch 7/10
300/300 [============] - 341s 1s/step - monet_gen_loss: 3.1344 - photo_gen_loss: 3.3411 - monet_disc_loss: 0.6103 - photo_disc_loss: 0.6180
Epoch 8/10
300/300 [============] - 342s 1s/step - monet_gen_loss: 3.0265 - photo_gen_loss: 3.1923 - monet_disc_loss: 0.6044 - photo_disc_loss: 0.6020
Epoch 9/10
300/300 [==============] - 343s 1s/step - monet_gen_loss: 2.9889 - photo_gen_loss: 3.3650 - monet_disc_loss: 0.6130 - photo_disc_loss: 0.6104
Epoch 10/10
300/300 [====
```

### APPLYING TEST DATA TO THE GANS MODEL

As a result of the training process, the discriminator and generator loss metrics appear to be much more consistent. The discriminator loss values appear to stay low, which indicate that it is effective in distinguishing real samples from generated samples. 'More details are given in the Evaluation Metrics and Results' section. During testing and according to the below results, the generated images appear to be quite similar to the real images, indicating success.

```
In [71]: predictions = []
    real_images = []
    fig, ax = plt.subplots(5, 2, figsize=(12, 12))
    for i, img in enumerate(photo_dataset.take(5)):
        prediction = monet_generator(img, training=False)[0].numpy()
        prediction = (prediction * 127.5 + 127.5).astype(np.uint8)
        predictions.append(prediction)
        img = (img[0] * 127.5 + 127.5).numpy().astype(np.uint8)

        ax[i, 0].imshow(img)
        ax[i, 1].imshow(prediction)
        ax[i, 0].set_title("Real Image")
        ax[i, 1].set_title("Synthetic Image")
        ax[i, 1].axis("off")
        ax[i, 1].axis("off")
        plt.show()
```

Real Image



Real Image



Real Image



Real Image



Real Image



Synthetic Image



Synthetic Image



Synthetic Image



Synthetic Image



Synthetic Image

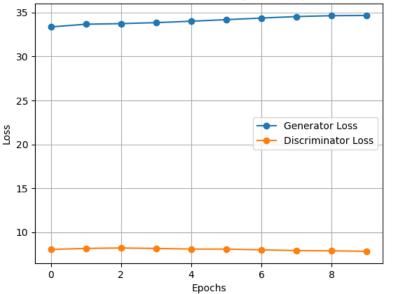


**EVALUATION METRICS AND RESULTS** 

The loss metrics in the plot below present an interesting behavior of the generator and discriminator components. The generator loss is high, indicating the the generators are struggling to deceive the discriminator with the generated images. However, both loss metrics appear to stabilize, which means that there is a well-defined balance between the performances of the generator and discriminator components. Overall, the updated GAN model is much more effective, and with further hyperparameter tuning, the GAN model can achieve an even greater performance.

```
In [77]: g_loss = sum(history.history['monet_gen_loss'], history.history['photo_gen_loss'])
         d_loss = sum(history.history['monet_disc_loss'], history.history['photo_disc_loss'])
         # Plotting the discriminator and generator loss metrics
         epoch_list = range(10)
         g_loss = g_loss.flatten()
         g_{loss} = g_{loss}[:10]
         d_loss = d_loss.flatten()
         d_loss = d_loss[:10]
         plt.plot(epoch_list, g_loss, label='Generator Loss', marker='o')
         plt.plot(epoch_list, d_loss, label='Discriminator Loss', marker='o')
         plt.title('Generator and Discriminator Loss Over Epochs (Improved GAN Model)')
         plt.xlabel('Epochs')
         plt.ylabel('Loss')
         plt.legend()
         plt.grid(True)
         plt.show()
```

#### Generator and Discriminator Loss Over Epochs (Improved GAN Model)



```
import PIL
! mkdir ../images

mkdir: ../images: File exists

In [73]: # Save the generated images into a local 'images' folder
    i = 1
    for img in photo_dataset:
        prediction = monet_generator(img, training=False)[0].numpy()
        prediction = (prediction * 127.5 + 127.5).astype(np.uint8)
        im = PIL.Image.fromarray(prediction)
```

```
im.save("../images/" + str(i) + ".jpg")
i += 1

In [76]: # Archive the generated images into a zip file
import shutil
shutil.make_archive("/images", 'zip', "/images")
```

# DISCUSSION, LESSONS LEARNED, AND CONCLUSION

I faced many challenges in working through this mini-project, but the greatest challenges to overcome turned out to be the following factors: properly preprocessing the input data before applying it to the GAN model and optimizing the GAN model itself. The development process involved many changes and updates to both the generator and discriminator components. Initially, I was not getting the proper results (the output generated images were literally gray images with no additional features). This led me to make changes to how I was preprocessing the data, which improved the output and generated a more feasible result. As this point, the synthetic images still had a lot of noise and were more distinguishable from the reference images, so as a next step, I made further updates to the generator and discriminator components for my GAN model. Once I made updates to these components, this led to more satisfactory results.

In terms of lessons learned, I learned the importance of the generator and discriminator components for a given GAN model (including how they are structured). Depending on your use case and what you are trying to achieve with the GAN model, the structure of the generators and discriminators can be significant factor in overall performance. With more time, I would definitely go back and make further updates to the generator and discriminator in order see how I can optimize the model even further for this use case.

In []: