Graphs

Unweighted Graphs

Bjarki Ágúst Guðmundsson Tómas Ken Magnússon

Árangursrík forritun og lausn verkefna

School of Computer Science Reykjavík University

Today we're going to cover

- Graph basics
- Graph representation (recap)
- Depth-first search
- Connected components
- Breadth-first search
- Shortest paths in unweighted graphs

What is a graph?

What is a graph?

- Vertices
 - Road intersections
 - Computers
 - Floors in a house
 - Objects



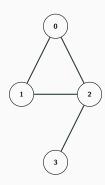




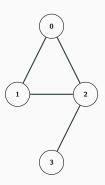


What is a graph?

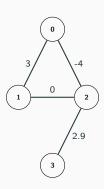
- Vertices
 - Road intersections
 - Computers
 - Floors in a house
 - Objects
- Edges
 - Roads
 - Ethernet cables
 - Stairs or elevators
 - Relation between objects



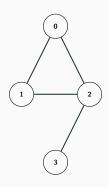
• Unweighted



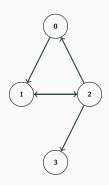
• Unweighted or Weighted



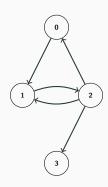
- Unweighted or Weighted
- Undirected



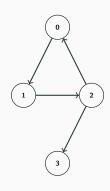
- Unweighted or Weighted
- Undirected or Directed



- Unweighted or Weighted
- Undirected or Directed

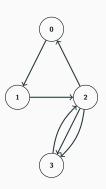


Multigraphs



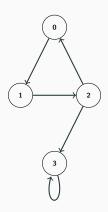
Multigraphs

• Multiple edges



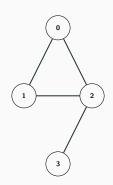
Multigraphs

- Multiple edges
- Self-loops



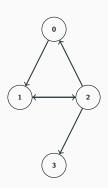
Adjacency list

```
0: 1, 2
1: 0, 2
2: 0, 1, 3
3: 2
vector<int> adj[4];
adj[0].push_back(1);
adj[0].push_back(2);
adj[1].push_back(0);
adj[1].push_back(2);
adj[2].push_back(0);
adj[2].push_back(1);
adj[2].push_back(3);
adj[3].push_back(2);
```

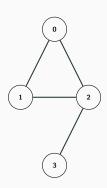


Adjacency list (directed)

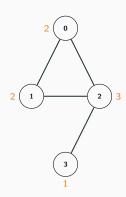
```
0:1
2: 0, 1, 3
3:
vector<int> adj[4];
adj[0].push_back(1);
adj[1].push_back(2);
adj [2] .push_back(0);
adj[2].push_back(1);
adj[2].push_back(3);
```



- Degree of a vertex
 - Number of adjacent edges
 - Number of adjacent vertices

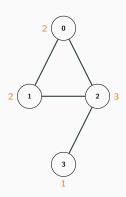


- Degree of a vertex
 - Number of adjacent edges
 - Number of adjacent vertices



- Degree of a vertex
 - Number of adjacent edges
 - Number of adjacent vertices
- Handshaking lemma

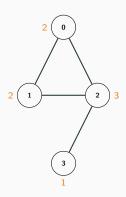
$$\sum_{v \in V} \deg(v) = 2|E|$$



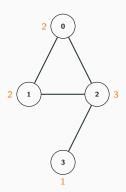
- Degree of a vertex
 - Number of adjacent edges
 - Number of adjacent vertices
- Handshaking lemma

$$\sum_{v \in V} \deg(v) = 2|E|$$

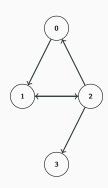
$$2+2+3+1=2\times 4$$



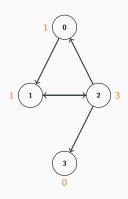
```
0: 1, 2
1: 0, 2
2: 0, 1, 3
3: 2
adj[0].size() // 2
adj[1].size() // 2
adj[2].size() // 3
adj[3].size() // 1
```



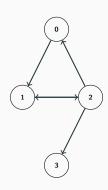
- Outdegree of a vertex
 - Number of outgoing edges



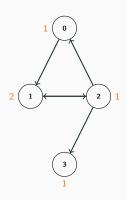
- Outdegree of a vertex
 - Number of outgoing edges



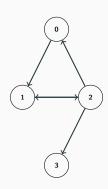
- Outdegree of a vertex
 - Number of outgoing edges
- Indegree of a vertex
 - Number of incoming edges



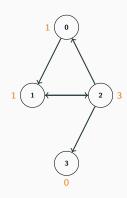
- Outdegree of a vertex
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- Outdegree of a vertex
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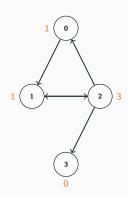


- Outdegree of a vertex
 - Number of outgoing edges
- Indegree of a vertex
 - Number of incoming edges



Adjacency list (directed)

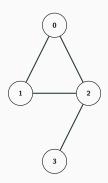
```
0: 1
1: 2
2: 0, 1, 3
3:
adj[0].size() // 1
adj[1].size() // 1
adj[2].size() // 3
adj[3].size() // 0
```



• Path / Walk / Trail:

$$e_1e_2\ldots e_k$$

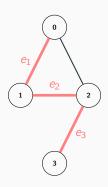
$$e_i \in E$$
 $e_i = e_j \Rightarrow i = j$ $\operatorname{to}(e_i) = \operatorname{from}(e_{i+1})$



• Path / Walk / Trail:

$$e_1e_2\ldots e_k$$

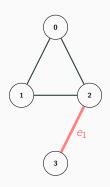
$$e_i \in E$$
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• Path / Walk / Trail:

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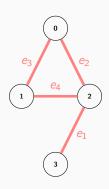
$$e_i \in E$$
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• Path / Walk / Trail:

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$$e_i \in E$$
 $e_i = e_j \Rightarrow i = j$ $to(e_i) = from(e_{i+1})$



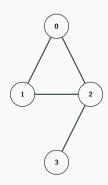
• Cycle / Circuit / Tour:

$$e_1e_2\ldots e_k$$

such that

$$e_i \in E$$
 $e_i = e_j \Rightarrow i = j$
 $to(e_i) = from(e_{i+1})$

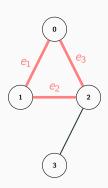
 $from(e_1) = to(e_k)$



• Cycle / Circuit / Tour:

$$e_1 e_2 \dots e_k$$

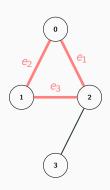
$$e_i \in E$$
 $e_i = e_j \Rightarrow i = j$
 $to(e_i) = from(e_{i+1})$
 $from(e_1) = to(e_k)$



• Cycle / Circuit / Tour:

$$e_1e_2\ldots e_k$$

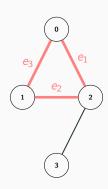
$$e_i \in E$$
 $e_i = e_j \Rightarrow i = j$
 $to(e_i) = from(e_{i+1})$
 $from(e_1) = to(e_k)$



• Cycle / Circuit / Tour:

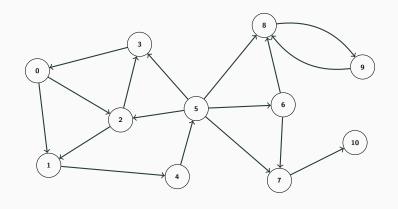
$$e_1e_2\ldots e_k$$

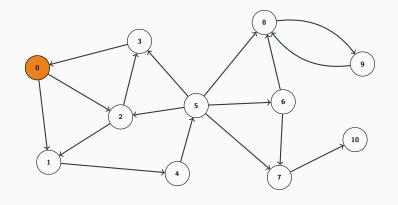
$$e_i \in E$$
 $e_i = e_j \Rightarrow i = j$
 $to(e_i) = from(e_{i+1})$
 $from(e_1) = to(e_k)$

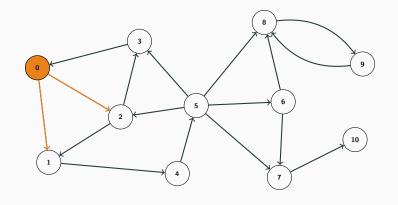


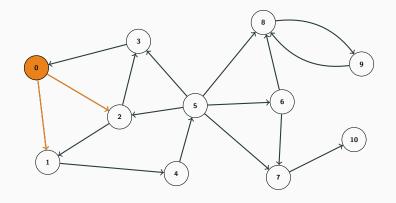
Depth-first search

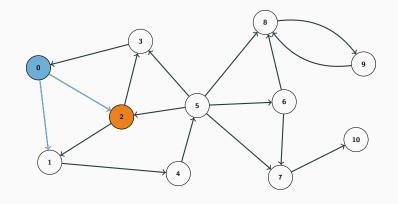
- Given a graph (either directed or undirected) and two vertices u and v, does there exist a path from u to v?
- Depth-first search is an algorithm for finding such a path, if one exists
- It traverses the graph in depth-first order, starting from the initial vertex u
- We don't actually have to specify a v, since we can just let it visit
 all reachable vertices from u (and still same time complexity)
- But what is the time complexity?
- Each vertex is visited once, and each edge is traversed once
- O(n+m)

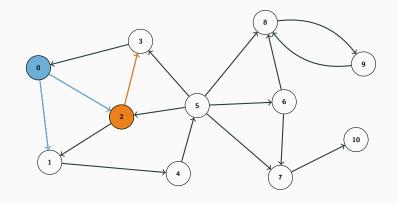


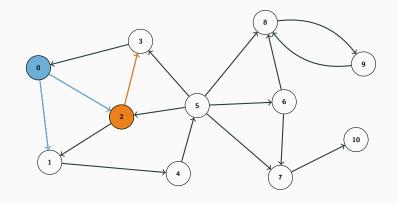


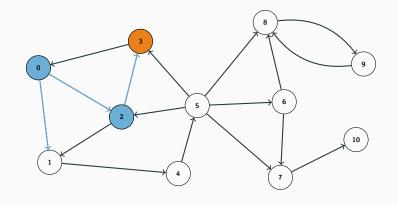


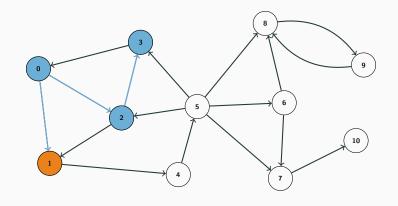


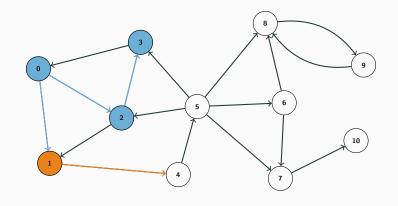


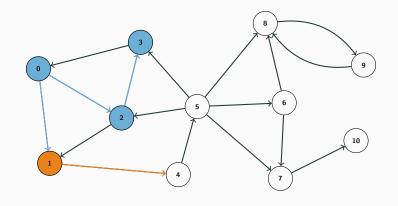


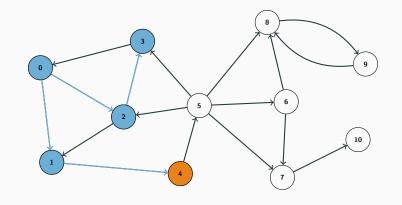


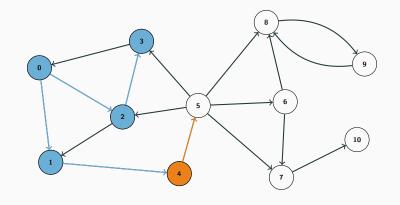


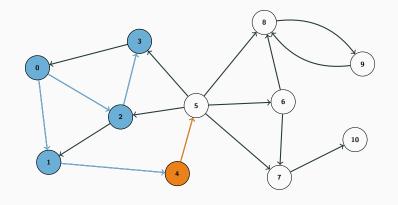


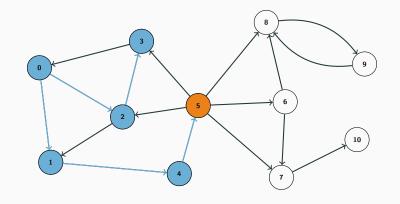


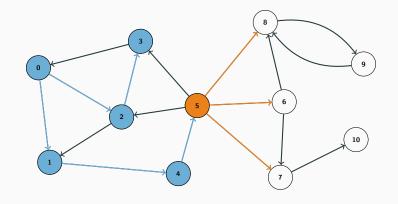


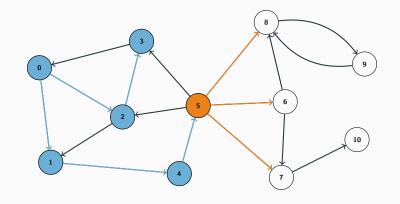


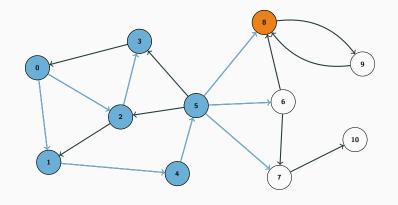


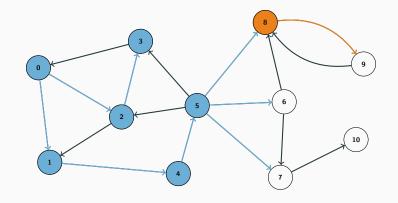


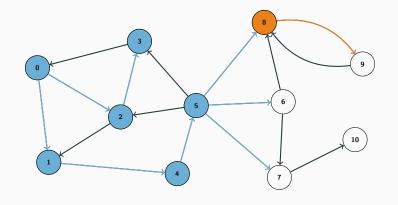


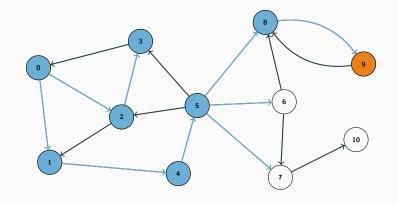


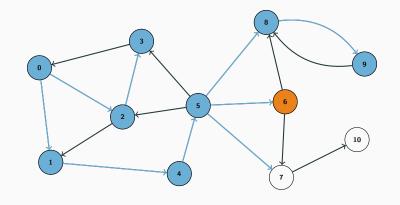


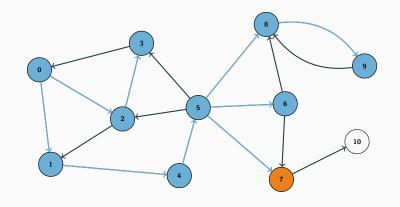


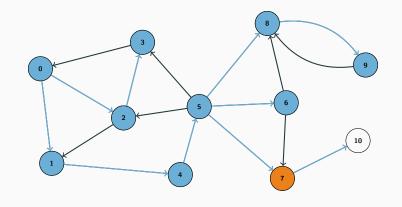


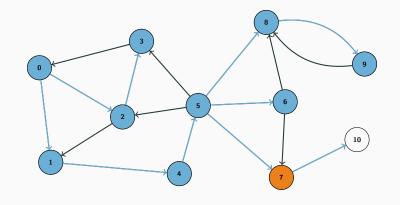


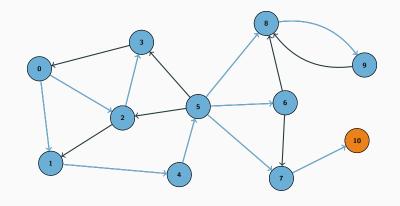


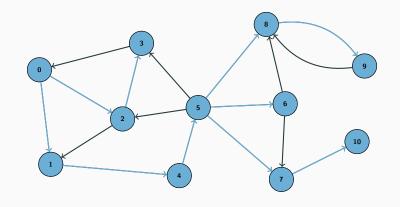






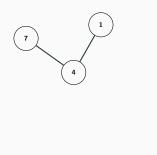


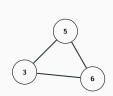




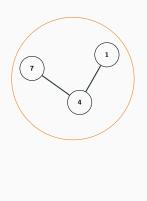
```
vector<int> adj[1000];
vector<bool> visited(1000, false);
void dfs(int u) {
    if (visited[u]) {
        return;
    }
    visited[u] = true;
    for (int i = 0; i < adj[u].size(); i++) {</pre>
        int v = adj[u][i];
        dfs(v);
```

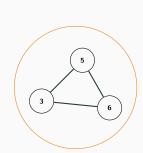
- An undirected graph can be partitioned into connected components
- A connected component is a maximal subset of the vertices such that each pair of vertices is reachable from each other
- We've already seen this in a couple of problems, but we've been using Union-Find to keep track of the components













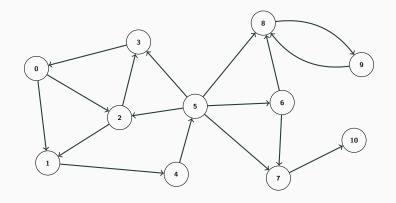
- Also possible to find these components using depth-first search
- Pick some vertex we don't know anything about, and do a depth-first search from that vertex
- All vertices reachable from that starting vertex are in the same component
- Repeat this process until you have all the components
- Time complexity is O(n+m)

```
vector<int> adj[1000];
vector<int> component(1000, -1);
void find_component(int cur_comp, int u) {
    if (component[u] != -1) {
        return;
    component[u] = cur_comp;
    for (int i = 0; i < adj[u].size(); i++) {</pre>
        int v = adj[u][i];
        find_component(cur_comp, v);
int components = 0;
for (int u = 0; u < n; u++) {
    if (component[u] == -1) {
        find_component(components, u);
        components++;
```

Depth-first search tree

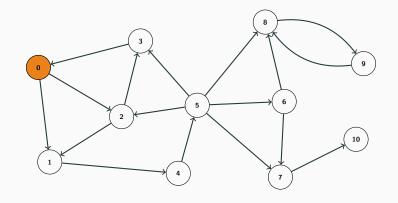
- When we do a depth-first search from a certain vertex, the edges that we go over form a tree
- When we go from a vertex to another vertex that we haven't visited before, the edge that we take is called a forward edge
- When we go from a vertex to another vertex that we've already visited before, the edge that we take is called a backward edge
- To be more specific: the forward edges form a tree
- see example

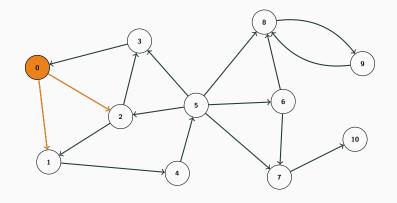
Breadth-first search

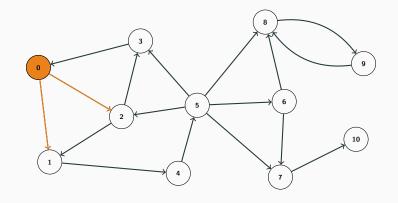


Queue:

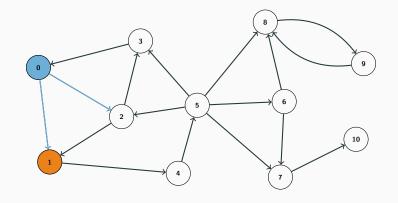
Breadth-first search



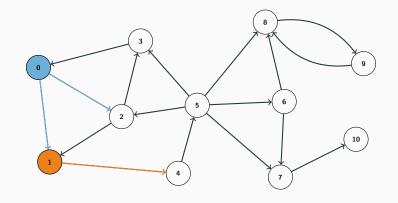




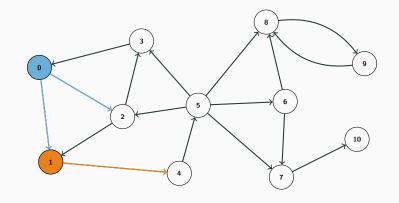
Queue: 0 1 2



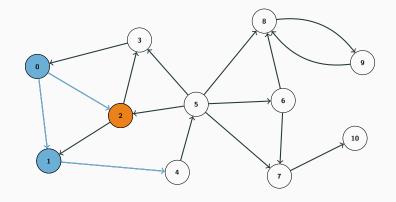
Queue: 1 2

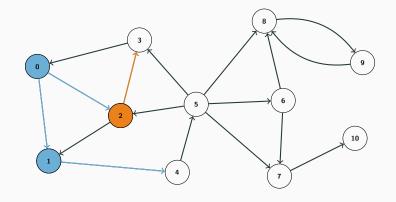


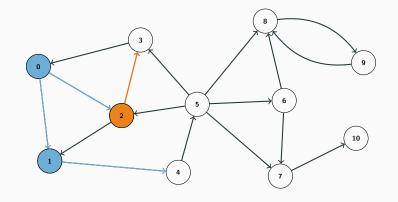
Queue: 1 2

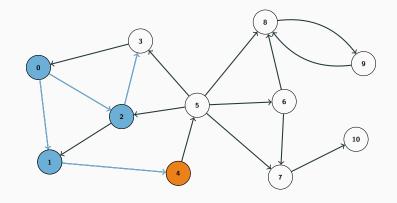


Queue: 1 2 4

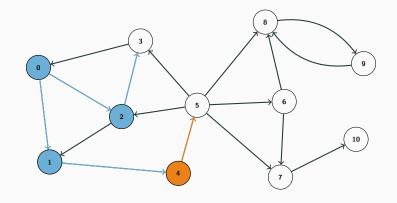




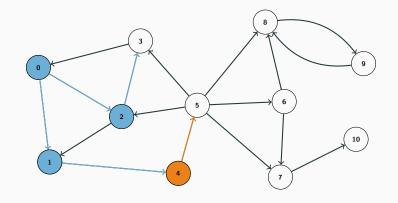




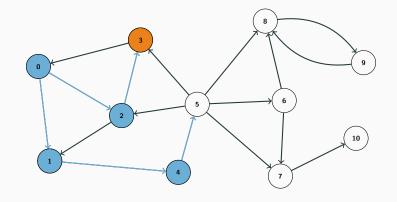
Queue: 4 3



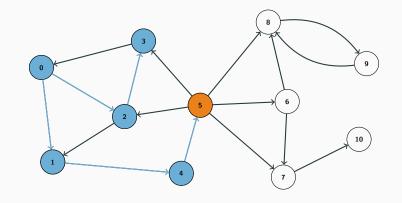
Queue: 4 3

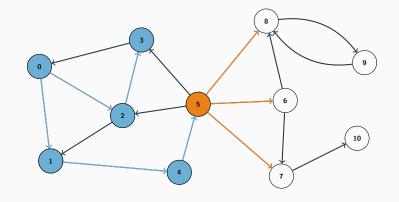


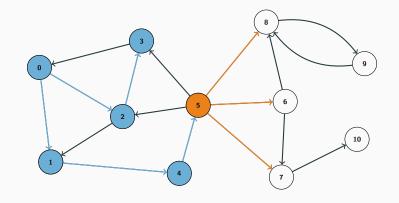
Queue: 4 3 5



Queue: 3 5

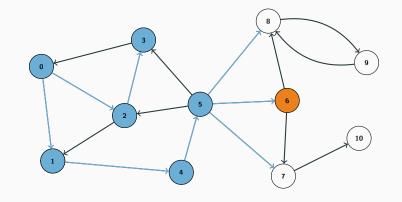




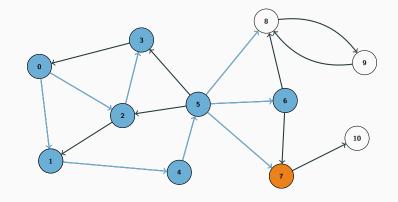


Queue: 5 6 7 8

marked 0 1 2 3 4 5 6 7 8 9 10 1 1 1 1 1 0 0

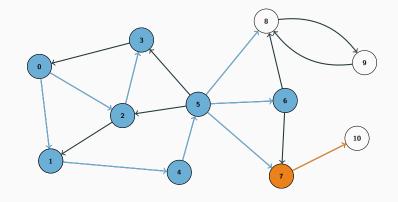


Queue: 6 7 8



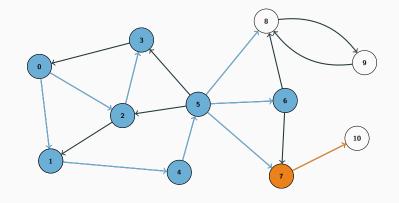
Queue: 78

	0	1	2	3	4	5	6	7	8	9	10
marked	1	1	1	1	1	1	1	1	1	0	0



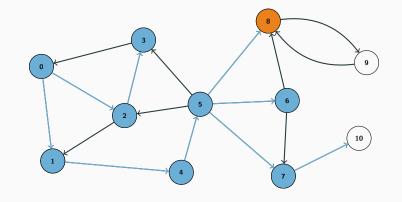
Queue: 78

	0	1	2	3	4	5	6	7	8	9	10
marked	1	1	1	1	1	1	1	1	1	0	0



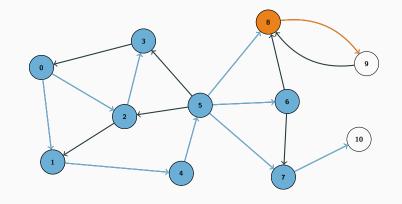
Queue: 7 8 10

marked 1 1 1 1 1 1 1 1 1 0 1



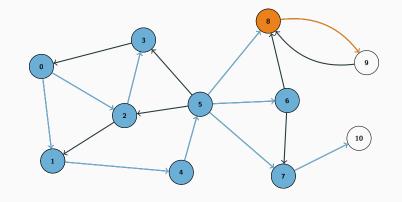
Queue: 8 10

marked 1 1 1 1 1 1 1 1 1 0 1

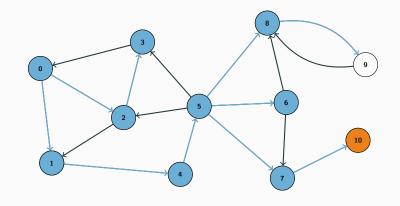


Queue: 8 10

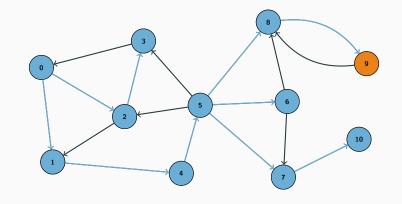
marked 1 1 1 1 1 1 1 1 1 0 1



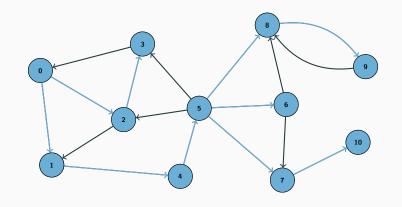
Queue: 8 10 9



Queue: 10 9



Queue: 9



Queue:

```
vector<int> adj[1000];
vector<bool> visited(1000, false);
queue<int> Q;
Q.push(start);
visited[start] = true;
while (!Q.empty()) {
    int u = Q.front(); Q.pop();
    for (int i = 0; i < adj[u].size(); i++) {</pre>
        int v = adj[u][i];
        if (!visited[v]) {
            Q.push(v);
            visited[v] = true;
```

Shortest path in unweighted graphs

- We have an unweighted graph, and want to find the shortest path from A to B
- That is, we want to find a path from A to B with the minimum number of edges
- Breadth-first search goes through the vertices in increasing order of distance from the start vertex
- Just do a single breadth-first search from A, until we find B
- Or let the search continue through the whole graph, and then we have the shortest paths from A to all other vertices
- Shortest path from A to all other vertices: O(n+m)

Shortest path in unweighted graphs

```
vector<int> adj[1000];
vector<int> dist(1000, -1);
queue<int> Q;
Q.push(A);
dist[A] = 0;
while (!Q.empty()) {
    int u = Q.front(); Q.pop();
    for (int i = 0; i < adj[u].size(); i++) {</pre>
        int v = adj[u][i];
        if (dist[v] == -1) {
            Q.push(v);
            dist[v] = 1 + dist[u];
        }
printf("%d\n", dist[B]);
```