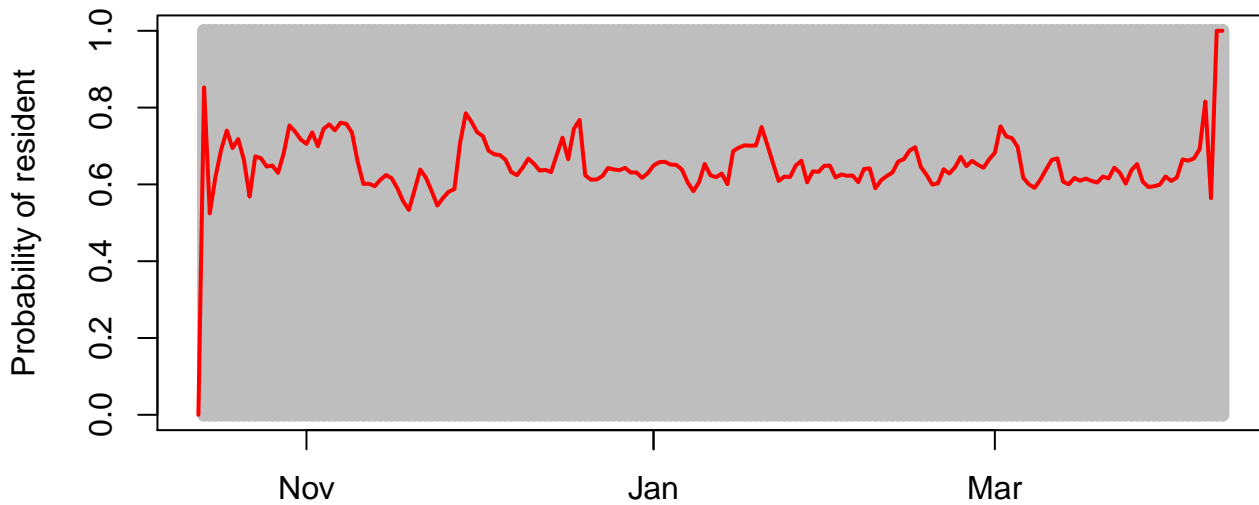


## Estimated behaviour



## Estimated movements

