

YOLOv8 Plastic Bottle Detection — Report

Video Link:

 `mainvideo.mp4`

1 Overall Process

This project focuses on training a YOLOv8-based object detection model to detect plastic bottles.

The key stages of the project are:

Dataset Preparation

- Two datasets were downloaded from Kaggle:
 - **Dataset 1:** “Plastic Bottle Image Dataset”
 - **Dataset 2:** “Drinking Waste Classification”
- Dataset 1 already contained properly labeled bottle images.
- Dataset 2 was cleaned by:
 - Filtering only PET bottle images.
 - Renaming files to remove commas for compatibility.
 - Remapping their labels to 0 (bottle class).
- Both datasets were then merged into a single YOLOv8-compatible directory structure with `train` and `val` splits.

Configuration

- Created a YOLO data configuration file (`bottle.yaml`) which defines:
 - Dataset path.
 - Train and validation folders.
 - Number of classes (`nc=1`).
 - Class names: `['bottle']`.

◆ Model Training

- Used the YOLOv8 nano pretrained weights (`yolov8n.pt`) for faster training.
- Trained the model for 20 epochs on the merged dataset.
- Saved the best-performing weights (`best.pt`) for later inference.

◆ Model Validation & Testing

- Ran validation on the held-out validation set to measure metrics:
 - Precision, Recall, mAP@0.5, and mAP@0.5:0.95.
- Ran inference on a test image and displayed the results inline.

2 Directory Structure

The final dataset and code are organized into a clear structure, as per YOLOv8 standards:

CSS

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/content/

```
|— bottle_data/
|   |— images/
|   |   |— train/
|   |   └─ val/
```

```
|   └─ labels/
|       └─ train/
|       └─ val/
├─ bottle.yaml           ← YOLO data configuration file
├─ bottle-detect/
|   └─ v8n-plastic/
|       └─ weights/
|           └─ best.pt
|           └─ last.pt
├─ bottle_detection.py  ← Main code script
```

Dataset folders:

- `images/train/` and `images/val/` contain the training and validation images.
- `labels/train/` and `labels/val/` contain corresponding YOLO-format annotation `.txt` files.

Config & Weights:

- `bottle.yaml` defines the dataset for YOLOv8.
- Best-trained model is saved as `best.pt` in `weights/`.


3 Code and Logic

Install and Configure Kaggle

python

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```
!pip install kaggle
!mkdir -p ~/.kaggle
!cp kaggle.json ~/.kaggle/
!chmod 600 ~/.kaggle/kaggle.json
```

 *Installs the Kaggle API and sets up credentials for downloading datasets.*

◆ Clean Dataset 2

python

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```
# Filters PET images, cleans filenames, and rewrites labels as class 0
# Saves cleaned files in PET_only/images and PET_only/labels
```

🔗 *Keeps only plastic PET bottles from Dataset 2 and prepares YOLO-format labels.*

◆ Merge Datasets

python

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```
# Copies Dataset 1 and cleaned Dataset 2 into /content/bottle_data
# Organizes into YOLOv8 structure: images/train, labels/train,
images/val, labels/val
```

🔗 *Creates the dataset folder YOLO expects.*

◆ Create Config File

python

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```
yaml_content = """
path: /content/bottle_data
train: images/train
val: images/val

nc: 1
names: ['bottle']
"""

with open('/content/bottle.yaml', 'w') as f:
```

```
f.write(yaml_content.strip())
```

🔗 Tells YOLOv8 where to find data and what classes to expect.

◆ Train YOLOv8

python

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```
from ultralytics import YOLO
model = YOLO('yolov8n.pt')
results = model.train(
    data='/content/bottle.yaml',
    epochs=20,
    imgsz=640,
    batch=16,
    project='bottle-detect',
    name='v8n-plastic'
)
```

🔗 Trains YOLOv8 for 20 epochs. Best weights are saved as *best.pt*.

◆ Validate & Test


python

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```
metrics = model.val(data='/content/bottle.yaml')

results = model('/content/test_image.jpg', save=True)

# Display result
from IPython.display import Image, display
import glob
output_dir = results[0].save_dir
predicted_image = glob.glob(f"{output_dir}/*.jpg")[0]
display(Image(filename=predicted_image))
```

 *Evaluates model performance and shows predictions on a test image.*



Summary

- Downloaded and prepared two datasets.
- Merged them into YOLOv8 format.
- Trained a YOLOv8-nano detector on plastic bottles.
- Evaluated its performance using standard detection metrics.
- Demonstrated detection on new images.