```
r3::CollisionObject
    # m collisionPrimitive
     # m transform
     + ~CollisionObject()
     + setCollisionPrimitive()
     + getCollisionPrimitive()
     + getTransform()
     + getTransform()
    # CollisionObject()
          r3::RigidBody
# m physicsMaterial
# m collisionMask
# m mass
# m inverseMass
# m linearDamping
# m_angularDamping
# m velocity
# m acceleration
# m_lastFrameAcceleration
# m rotation
and 6 more...
+ RigidBody()
+ RigidBody()
+ ~RigidBody()
+ init()
+ calculateDerivedData()
+ setInertiaTensor()
+ getInverseTensor()
+ setMass()
+ getMass()
+ setInverseMass()
and 41 more...
# calculateTransformationMatrix()
# transformInertiaTensor()
```