

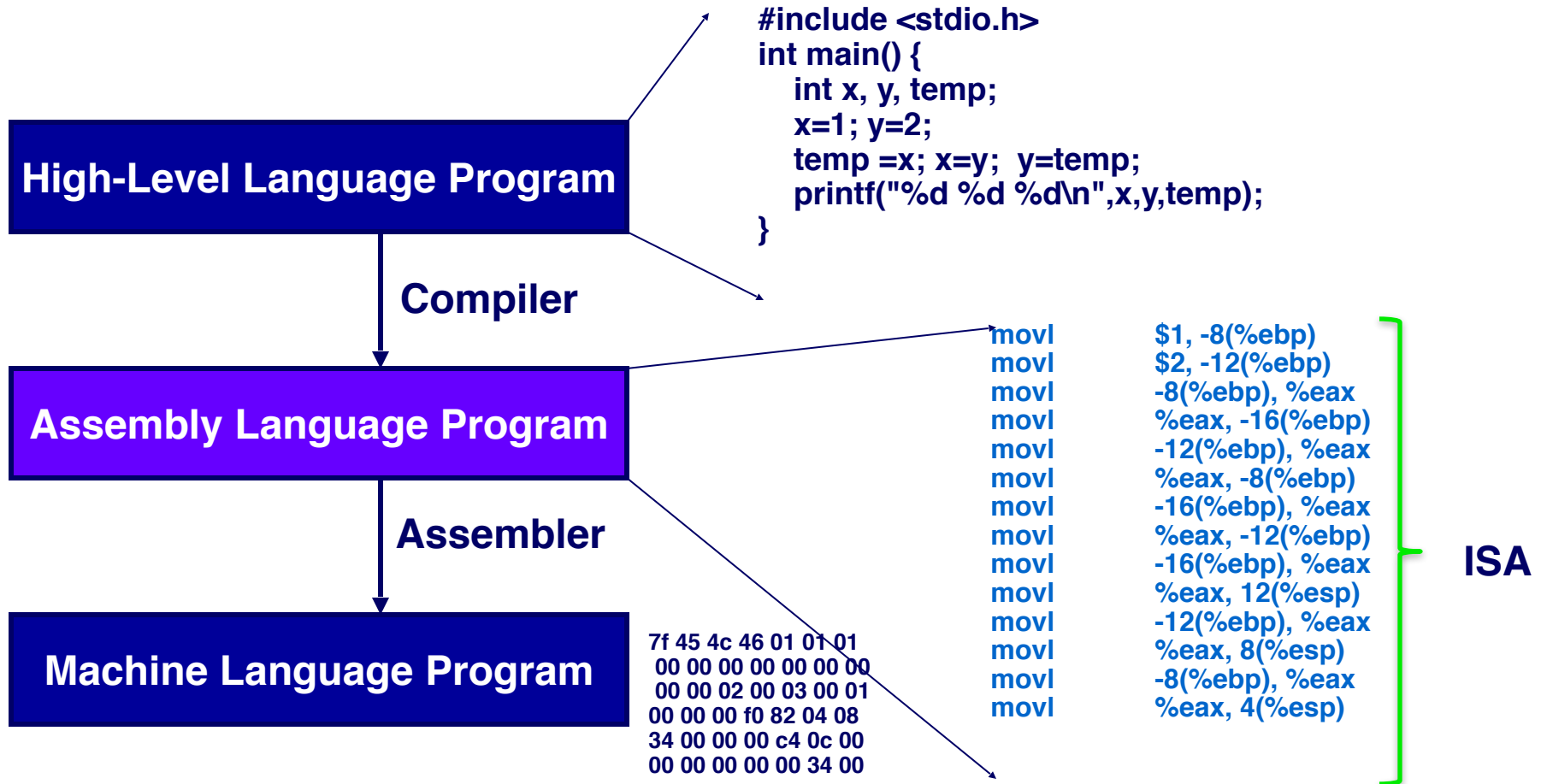
# 211: Computer Architecture Fall 2021

Instructor: Prof. David Menendez

Topics:

- Hardware-Software Interface
- Assembly Programming
  - Reading: Chapter 3

# Programming Meets Hardware



How do you get performance?

# Performance with Programs

(1) Program: Data structures + algorithms

(2) Compiler translates code

(3) Instruction set architecture

(4) Hardware Implementation

# Instruction Set Architecture

## (1) Set of instructions that the CPU can execute

- (1) What instructions are available?
- (2) How the instructions are encoded? Eventually everything is binary.

## (2) State of the system (Registers + memory state + program counter)

- (1) What instruction is going to execute next
- (2) How many registers? Width of each register?
- (3) How do we specify memory addresses?
  - Addressing modes

## (3) Effect of instruction on the state of the system

# IA32 (X86 ISA)

There are many different assembly languages because they are processor-specific

- IA32 (x86)
  - x86-64 for new 64-bit processors
  - IA-64 radically different for Itanium processors
  - **Backward compatibility: instructions added with time**
- PowerPC
- MIPS

We will focus on IA32/x86-64 because you can generate and run on iLab machines (as well as your own PC/laptop)

- IA32 is also dominant in the market although smart phone, eBook readers, etc. are changing this

# X86 Evolution

8086 – 1978 – 29K transistors – 5-10MHz

I386 – 1985 – 275K transistors – 16-33 MHz

Pentium4 – 2005 – 230M transistors – 2800-3800 MHz

Haswell – 2013 – > 2B transistors – 3200-3900 MHz

## Added features

- Large caches
- Multiple cores
- Support for data parallelism (SIMD) eg AVX extensions

# CISC vs RISC

CISC: complex instructions : eg X86

- Instructions such as strcpy/AES and others
- Reduces code size
- Hardware implementation complex?

RISC: simple instructions: eg Alpha

- Instructions are simple add/ld/st
- Increases code size
- Hardware implementation simple?

# Aside About Implementation of x86

About 30 years ago, the instruction set actually reflected the processor hardware

- E.g., the set of registers in the instruction set is actually what was present in the processor

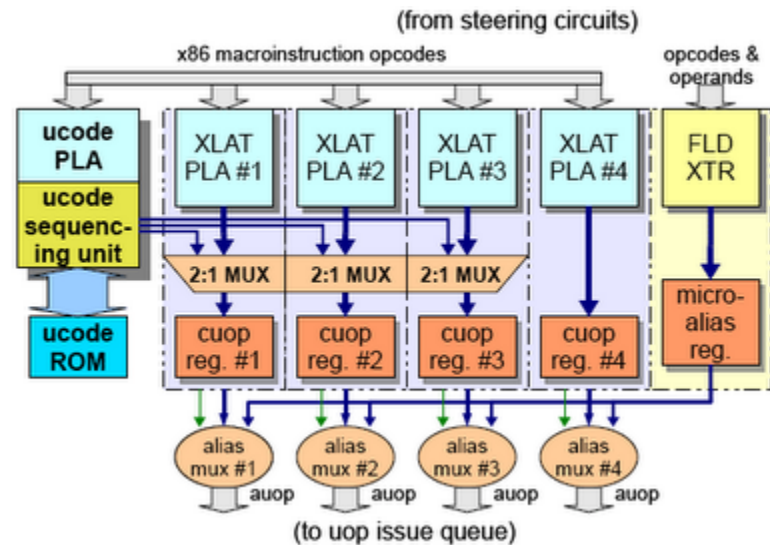
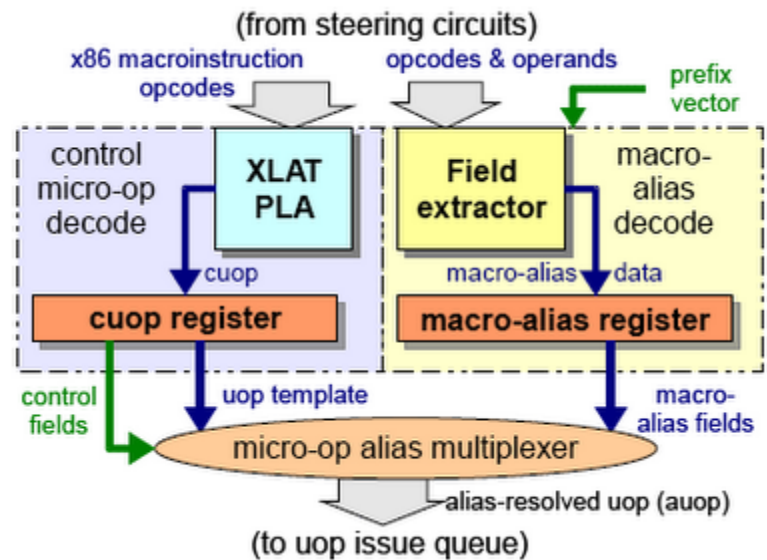
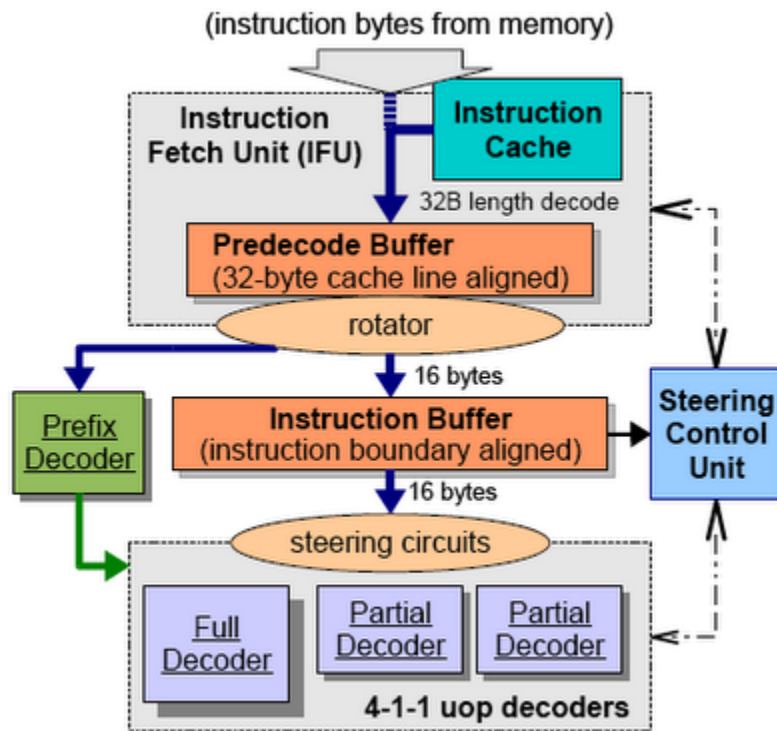
As hardware advanced, industry faced with choice

- Change the instruction set: bad for backward compatibility
- Keep the instruction set: harder to exploit hardware advances
  - Example: many more registers but only small set introduced circa 1980

Starting with the P6 (PentiumPro), IA32 actually got implemented by Intel using an “interpreter” that translates IA32 instructions into a simpler “micro” instruction set



# P6 Decoder/Interpreter



# Assembly Programming

Brief tour through assembly language programming

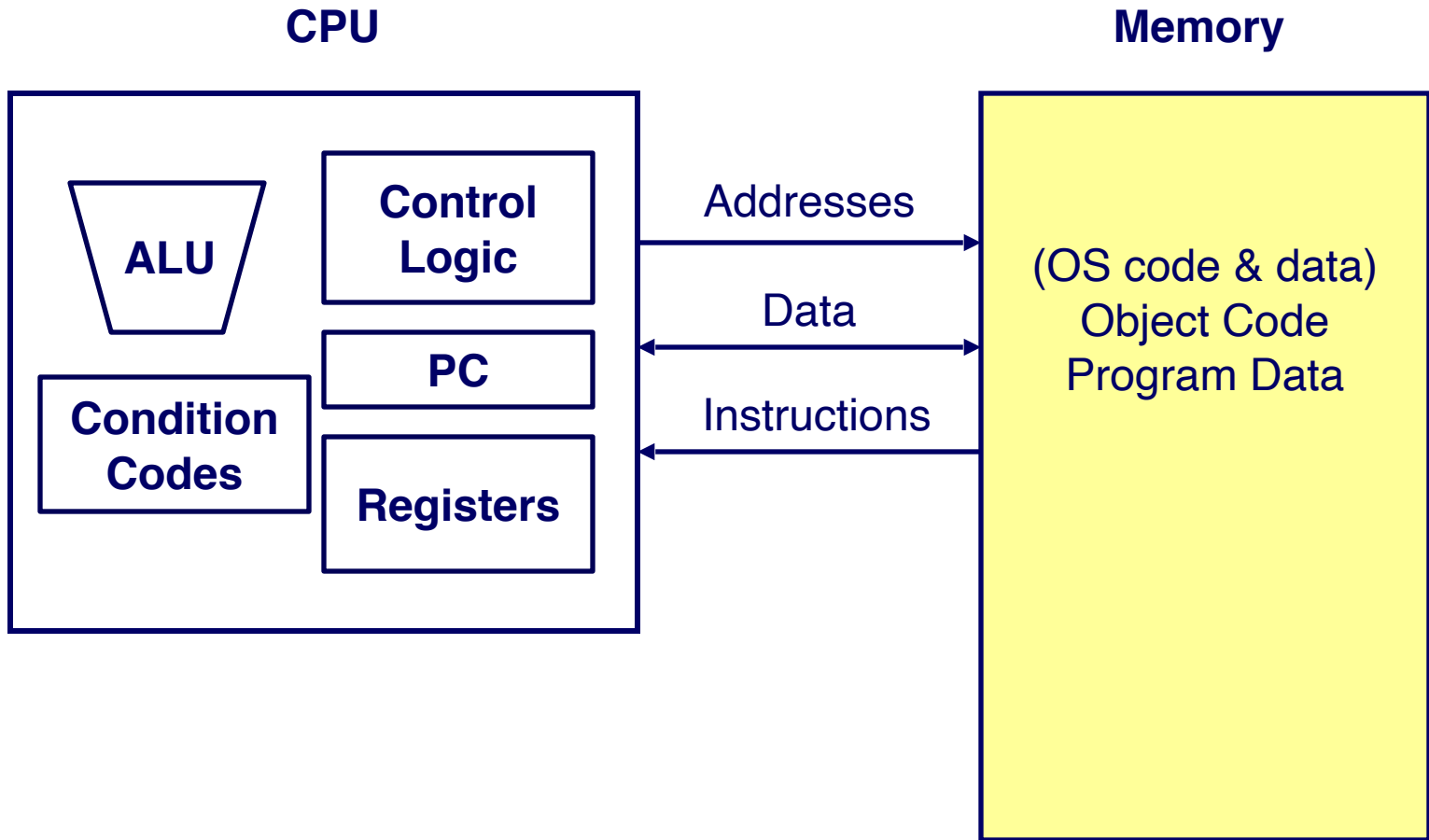
Why?

- Machine interface: where software meets hardware
- To understand how the hardware works, we have to understand the interface that it exports

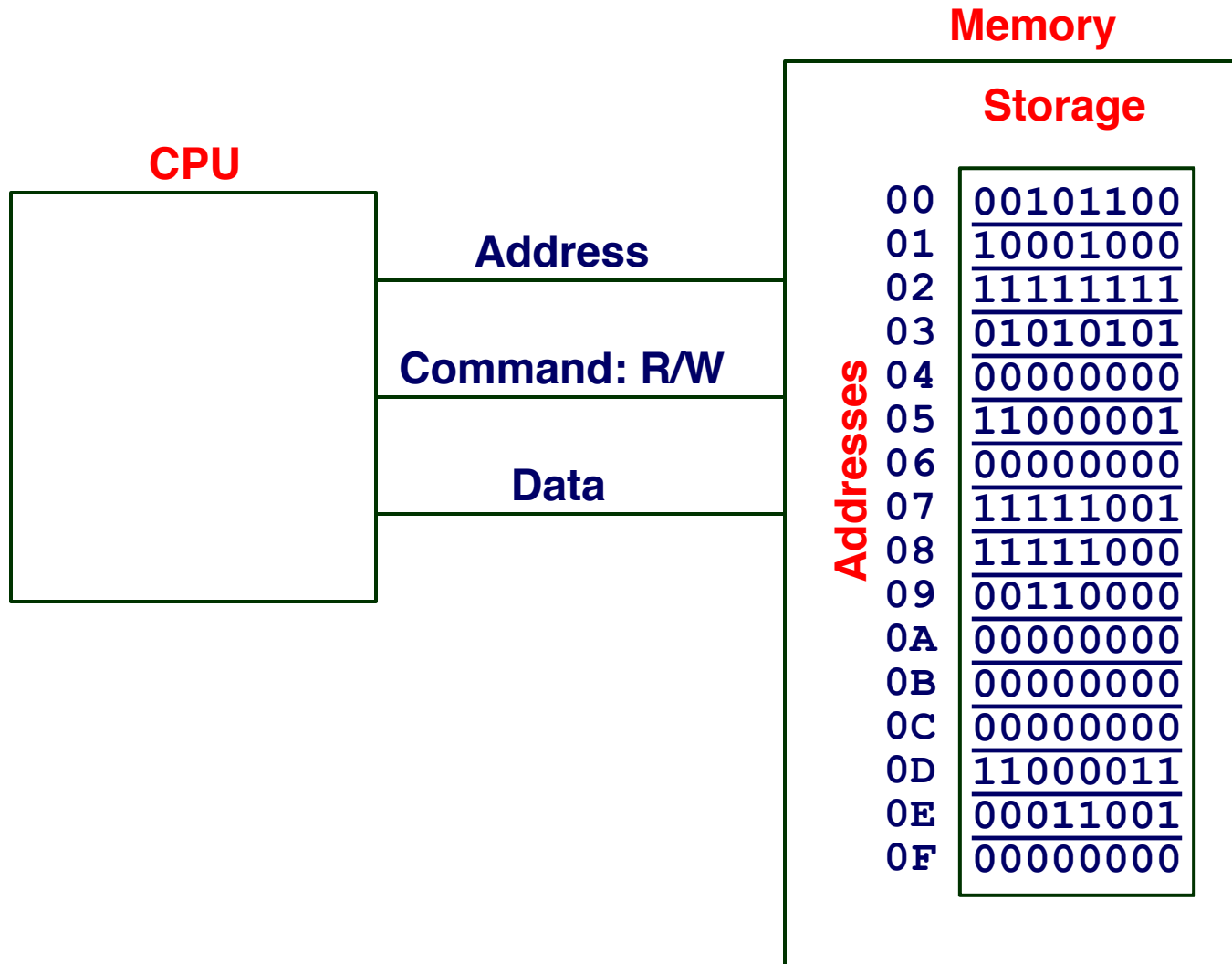
Why not binary language?

- Much easier for humans to read and reason about
- Major differences:
  - Human readable language instead of binary sequences
  - Relative instead of absolute addresses

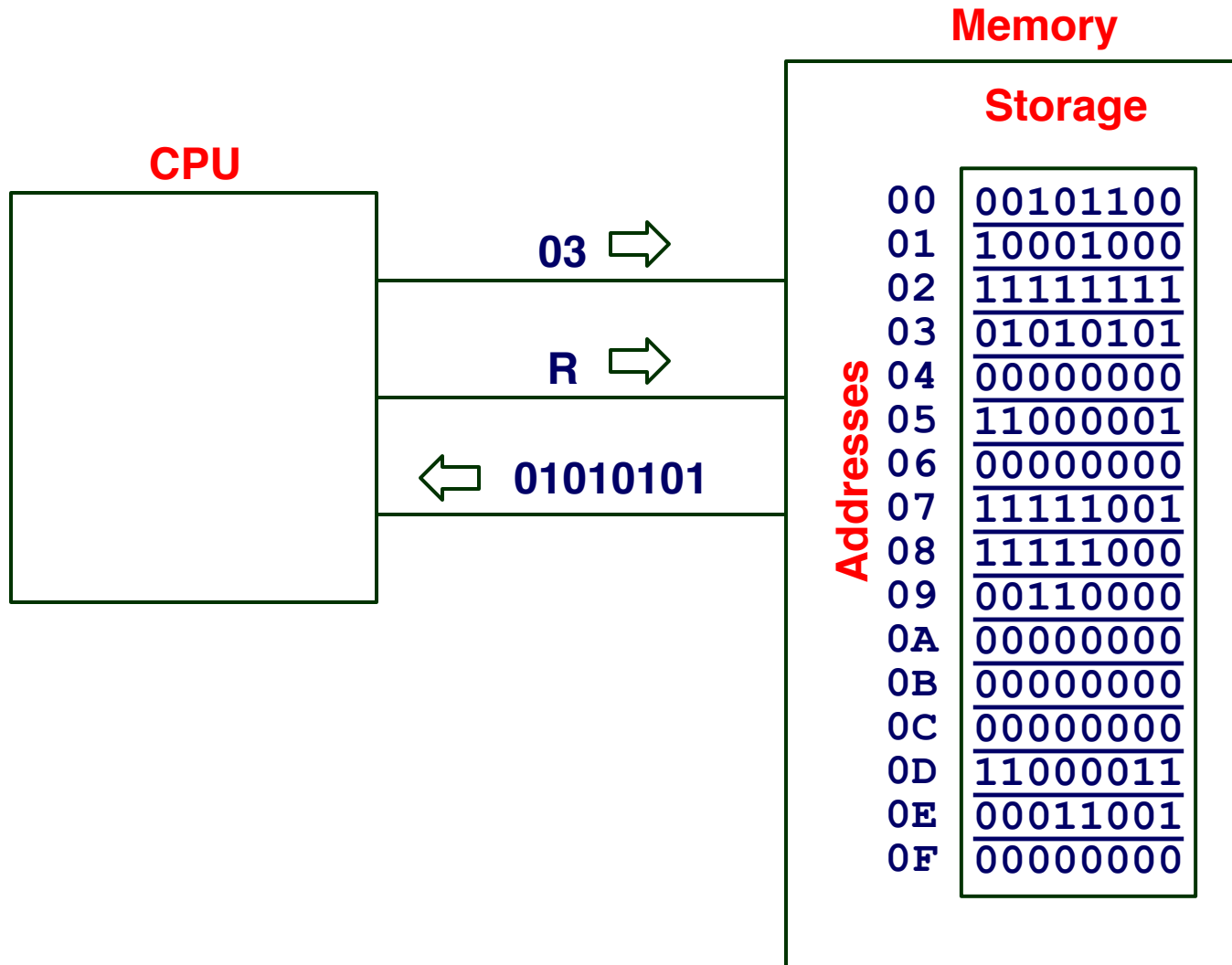
# Assembly Programmer's View



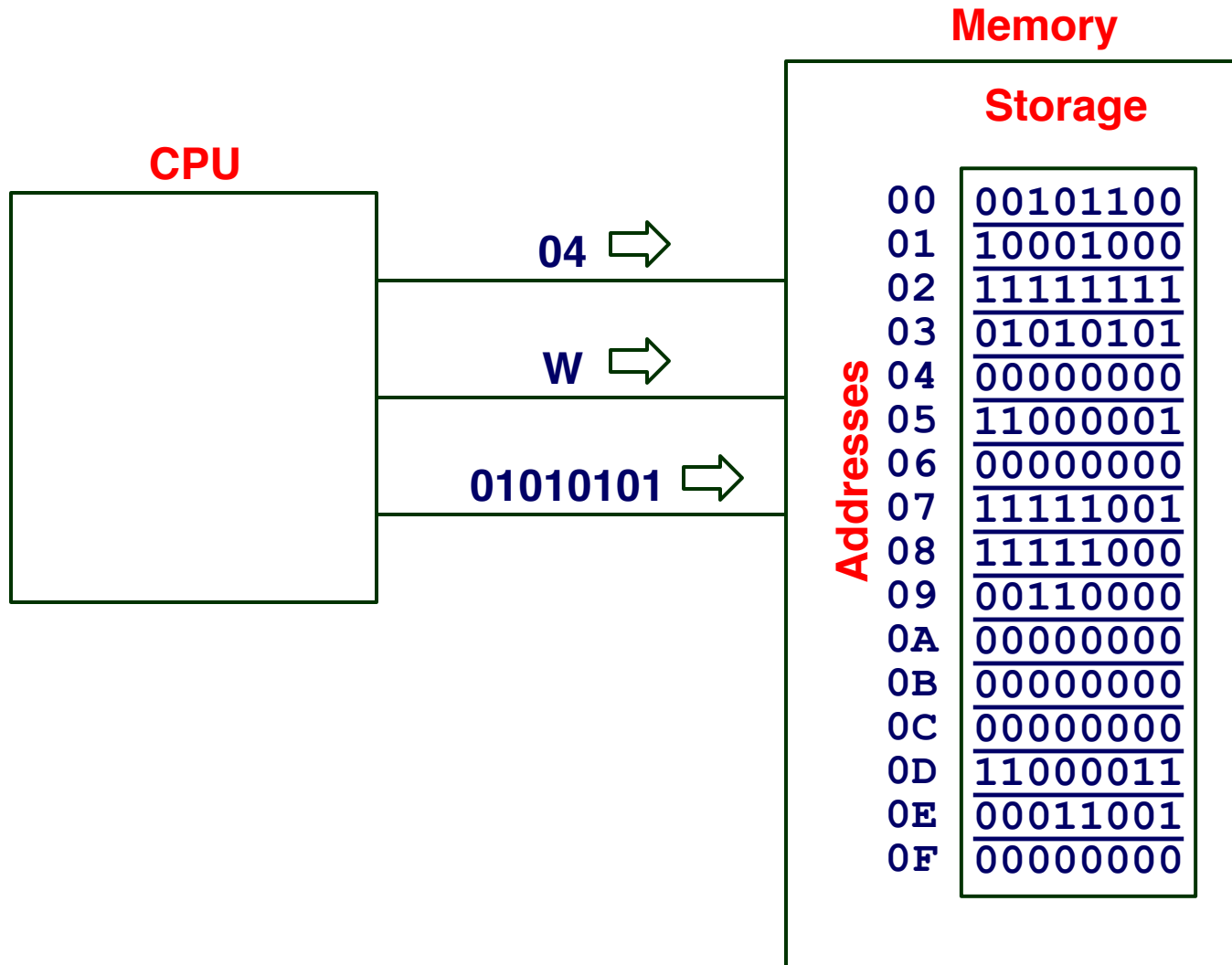
# Memory



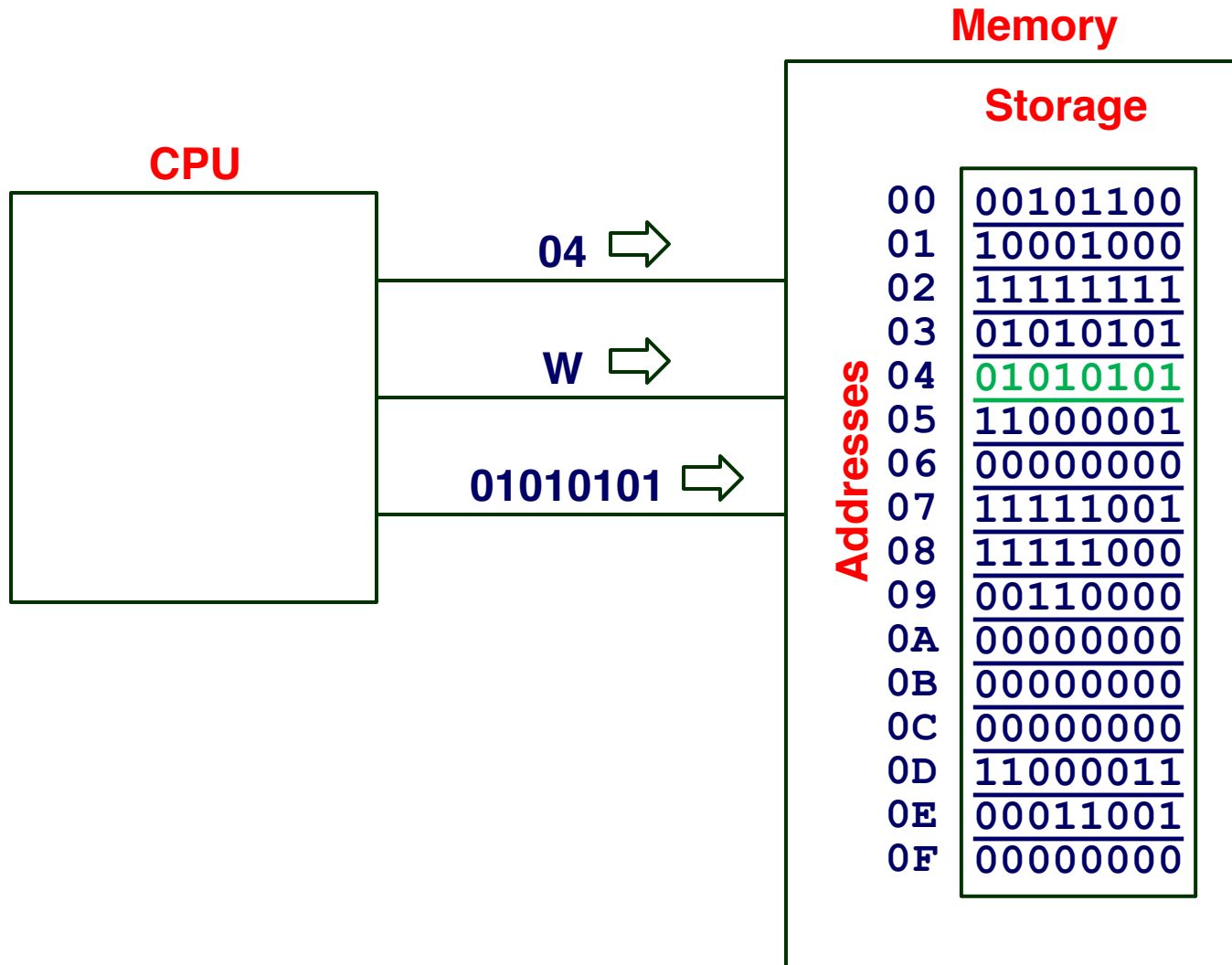
# Memory Access: Read



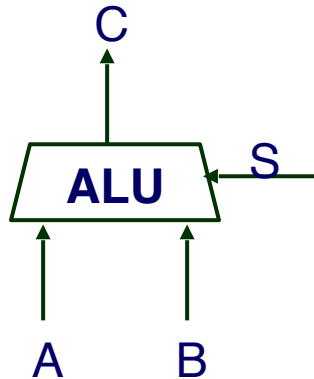
# Memory Access: Write



# Memory Access: Write

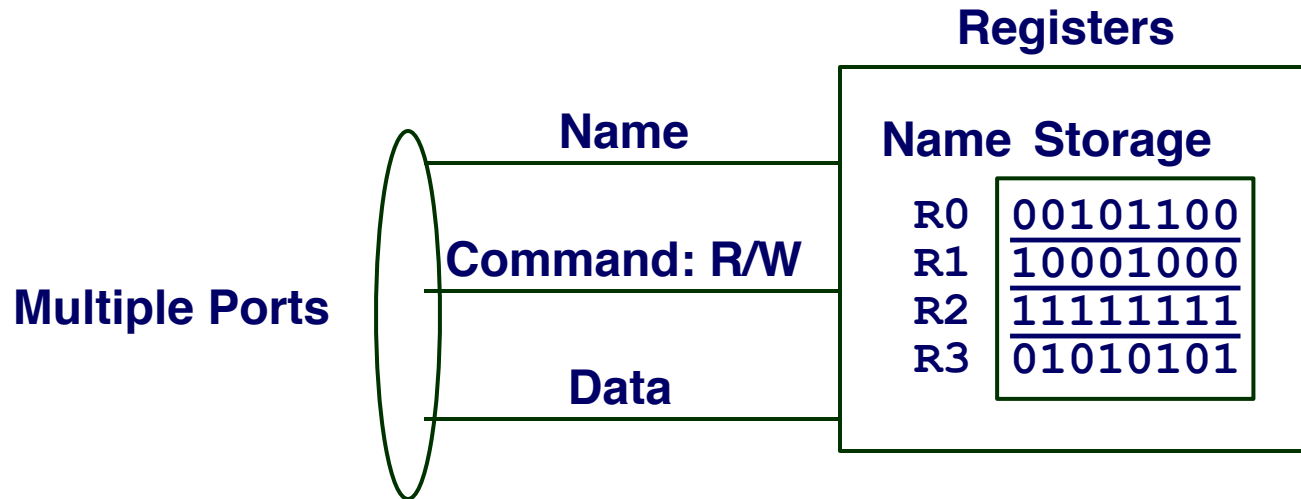


# Processor: ALU & Registers



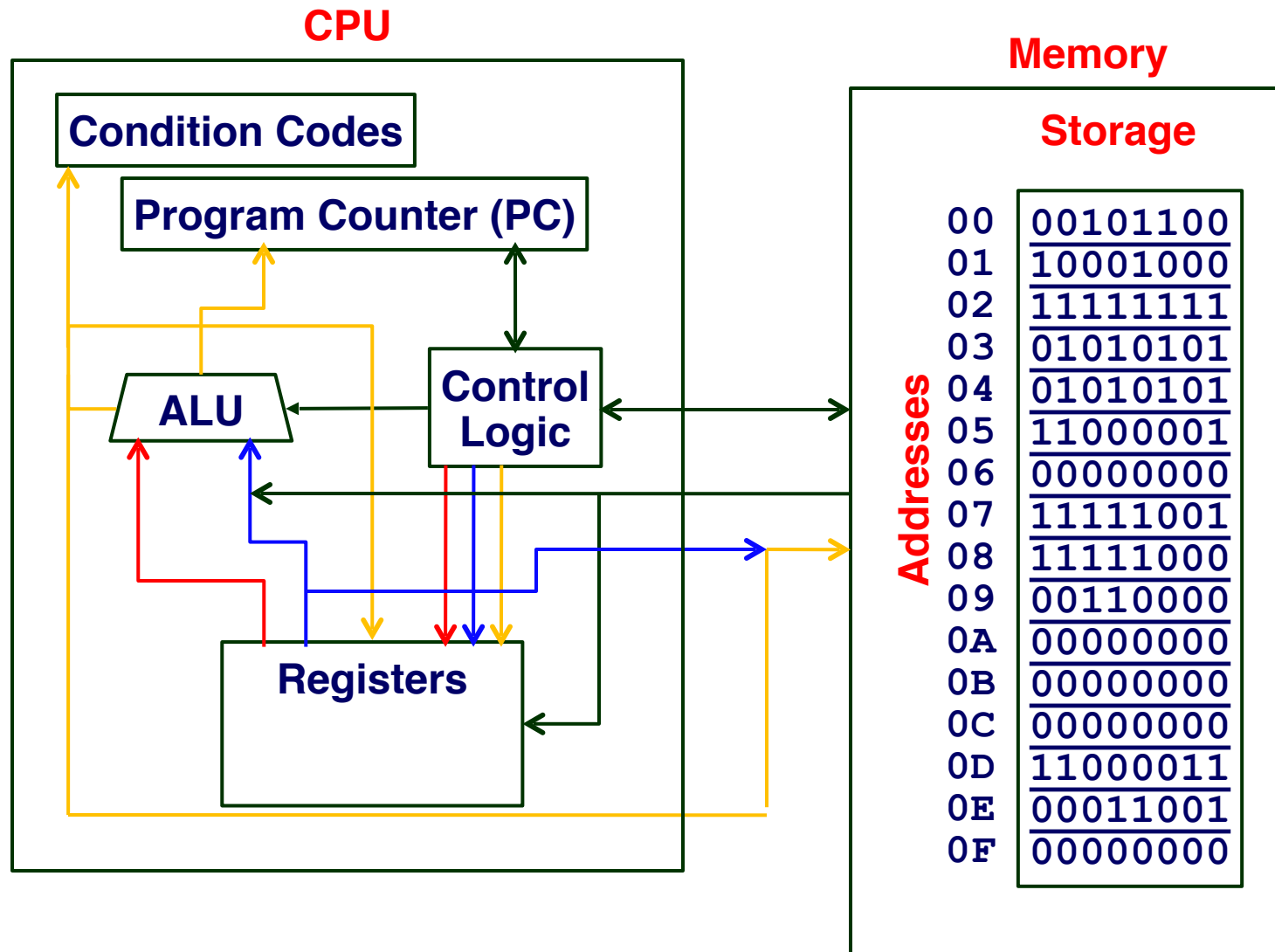
$$C = F_S(A, B)$$

**F** includes  
Arithmetic: +, -, \*, /, ~, etc.  
Logical: <, >, =, etc.

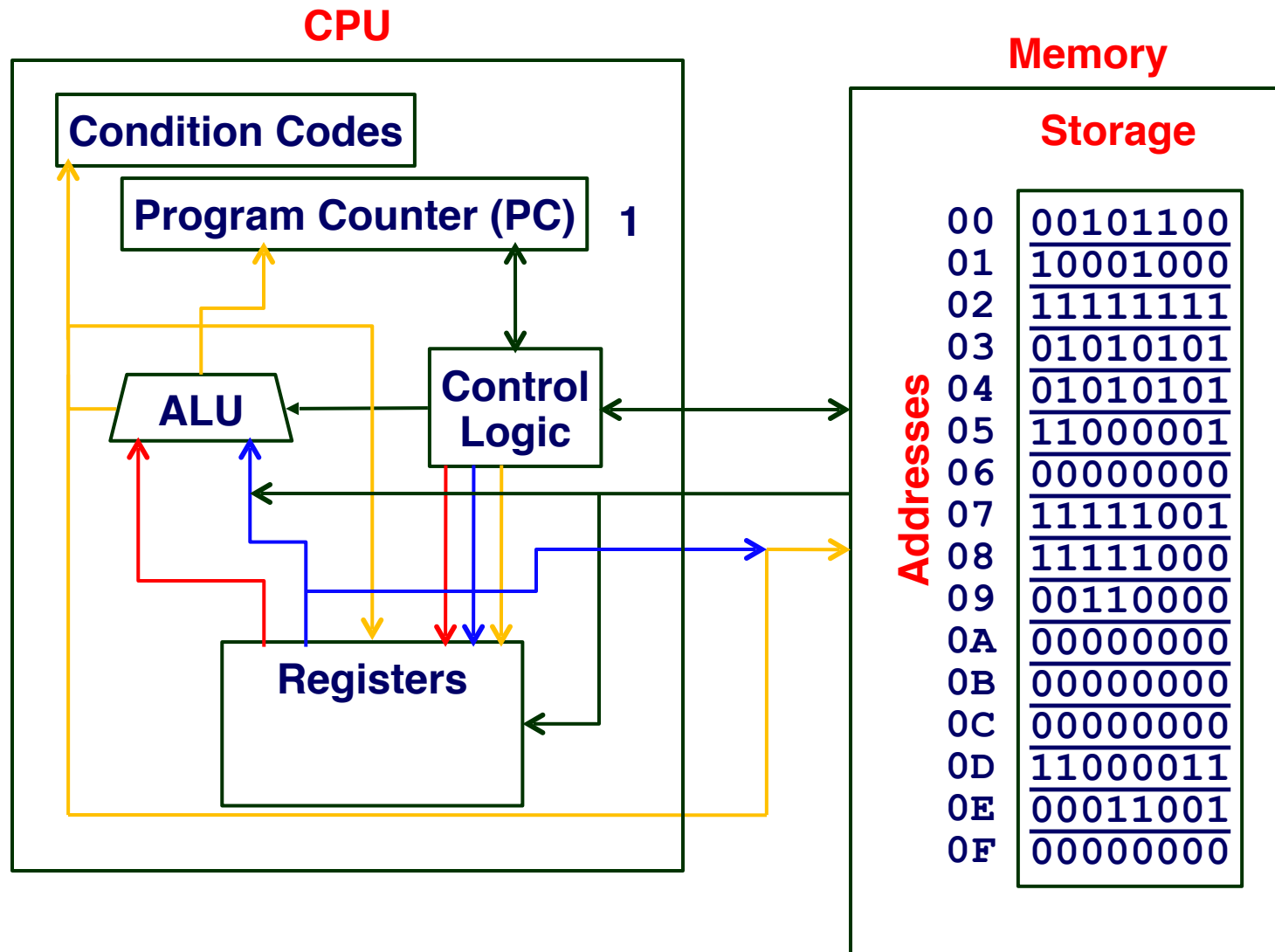




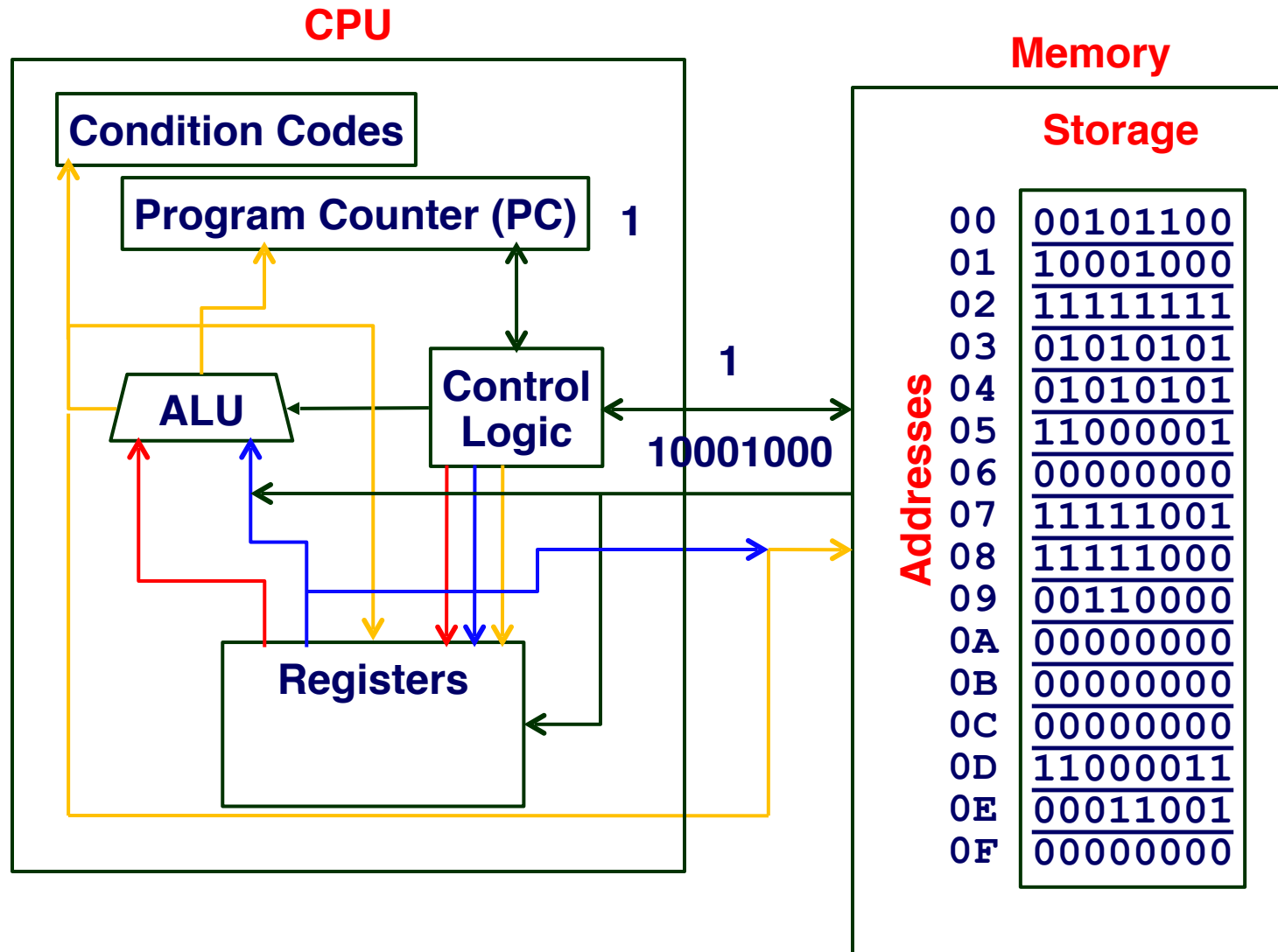
# Putting It All Together



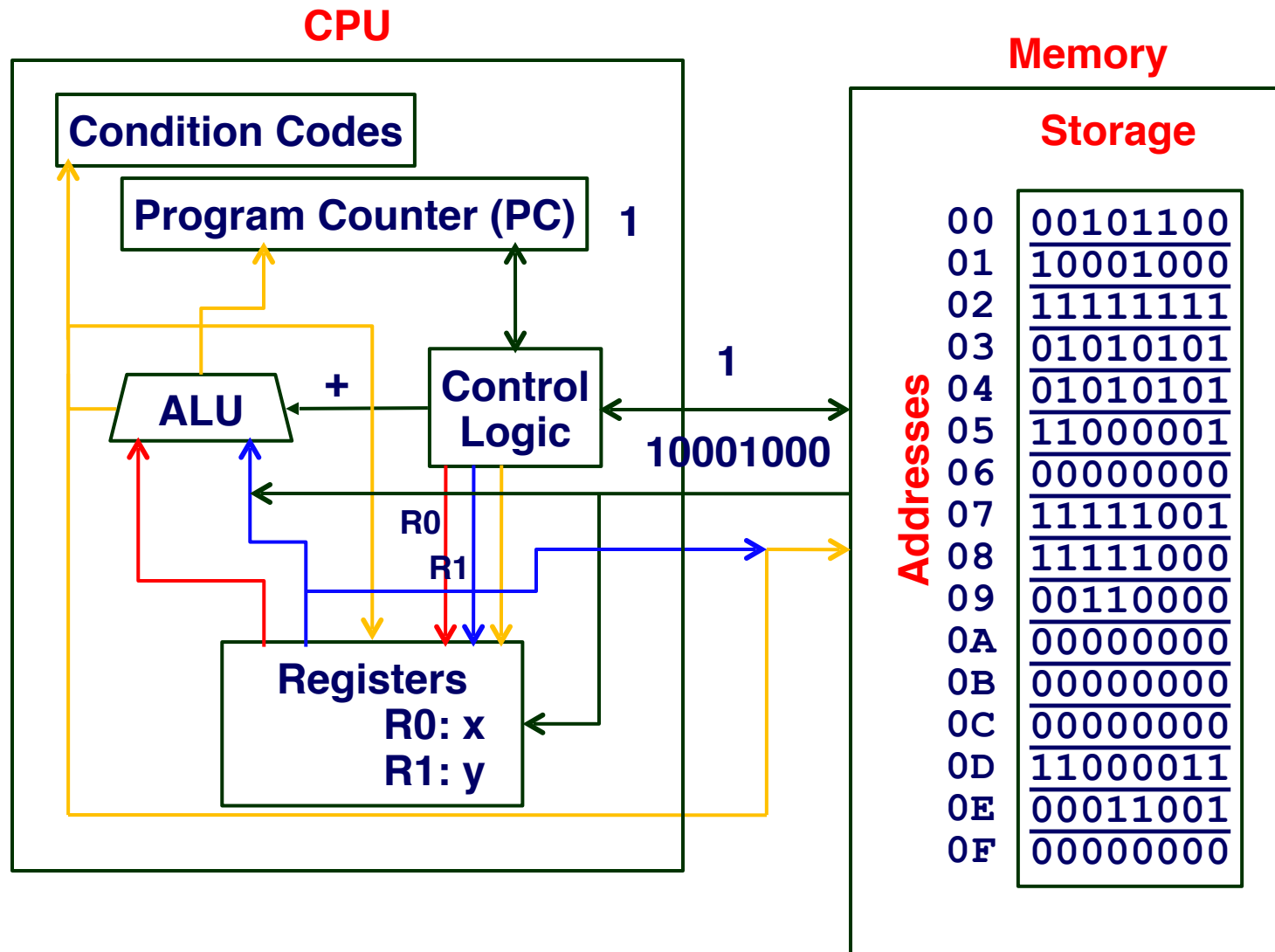
# Putting It All Together



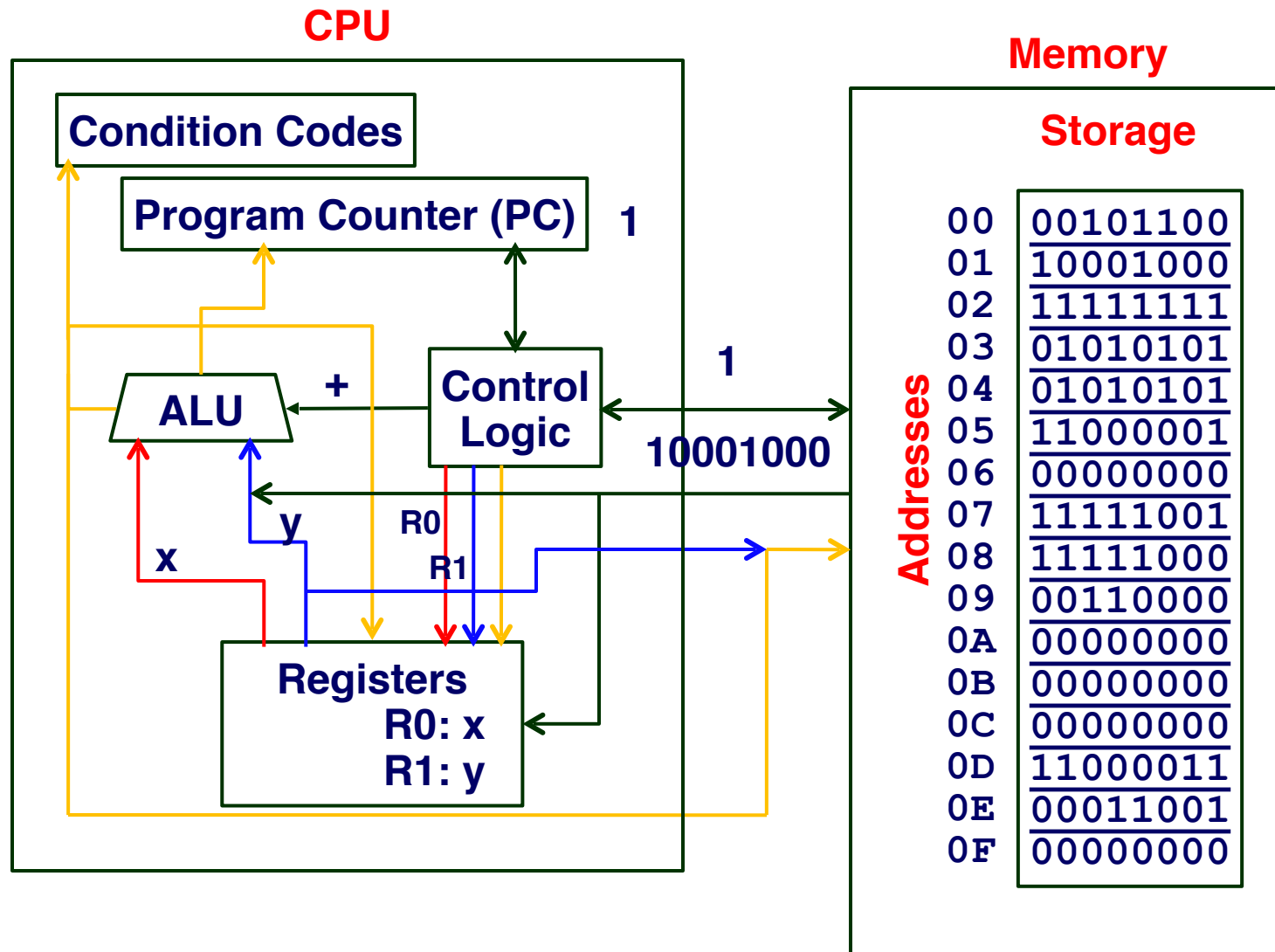
# Putting It All Together



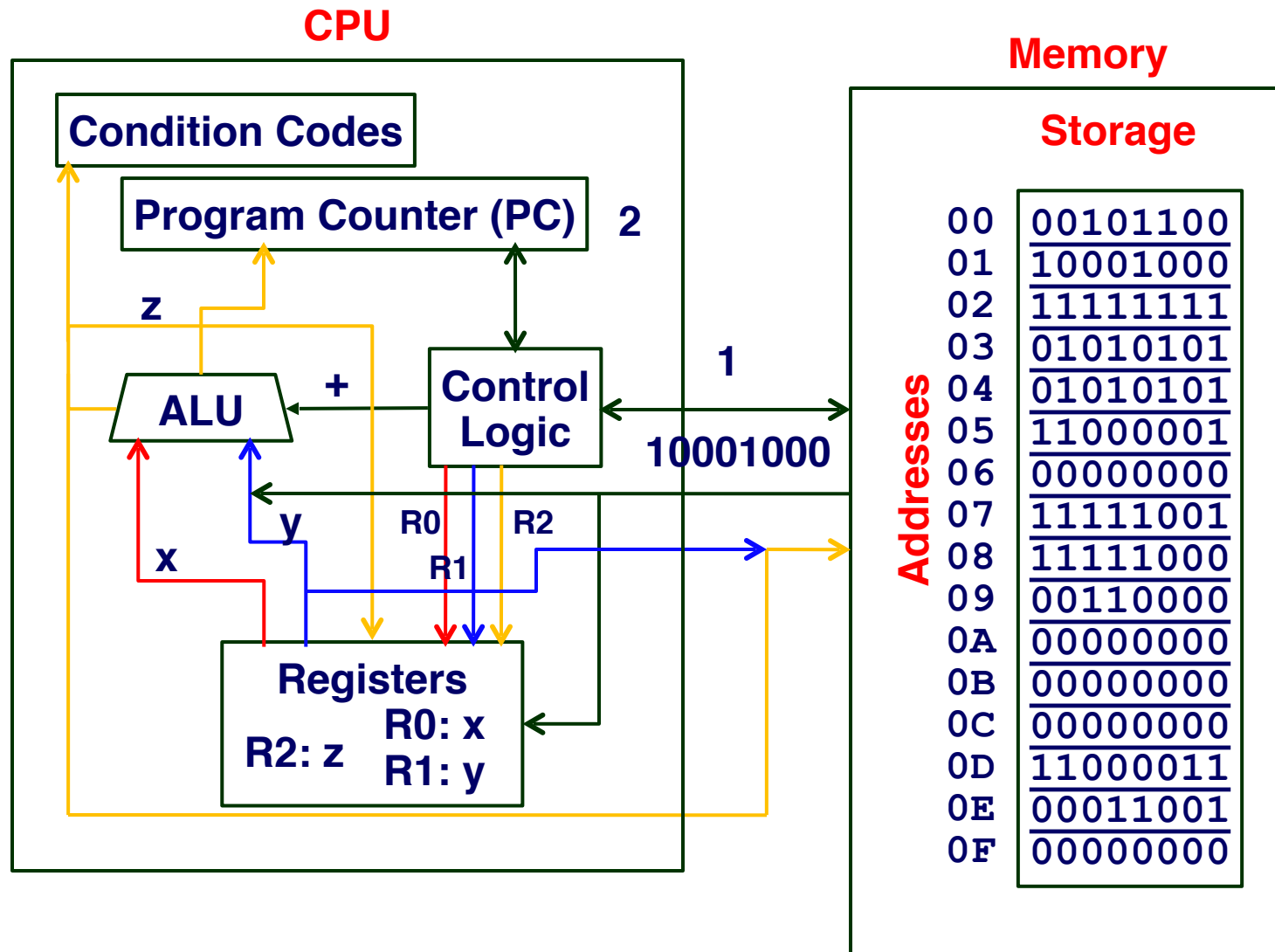
# Putting It All Together



# Putting It All Together



# Putting It All Together



# C & Assembly Code

## Sample C Code

```
int accum;
int sum(int x, int y)
{
    int t = x + y;
    accum += t;
    return t;
}
```

**gcc -O1 -m32 -S code.c**

## Generated Assembly

```
sum:
    push %ebp
    movl %esp, %ebp
    movl 12(%ebp), %eax
    addl 8(%ebp), %eax
    addl %eax, accum
    popl %ebp
    ret
```

# C & Machine Code

## Sample C Code

```
int accum;
int sum(int x, int y){
    int t = x + y;
    accum += t;
    return t;
}
```

**gcc -O1 -m32 -c code.c**

**gdb code.o**

(gdb) x/100xb sum

## objdump -d code.o

00000000 <sum>:

0:	55	push %ebp
1:	89 e5	mov %esp,%ebp
3:	8b 45 0c	mov 0xc(%ebp),%eax
6:	03 45 08	add 0x8(%ebp),%eax
9:	01 05 00 00 00 00	add %eax, accum
f:	5d	pop %ebp
10:	c3	ret

<sum>: 0x55 0x89 0xe5 0x8b 0x45 0x0c 0x03 0x45

0x8 <sum+8>: 0x08 0x01 0x05 0x00 0x00 0x00 0x00 0x5d

0x10 <sum+16>: 0xc3 Cannot access memory at address 0x11



# Assembly Characteristics

Sequence of simple instructions

Minimal Data Types

- “Integer” data of 1, 2, or 4 bytes
  - Data values
  - Addresses (untyped pointers)
- Floating point data of 4, 8, or 10 bytes
- No aggregate types such as arrays or structures
  - Just contiguously allocated bytes in memory

No type checking

- Interpretation of data format depends on instruction
- No protection against misinterpretation of data

# Assembly Characteristics

## 3 types of Primitive Operations

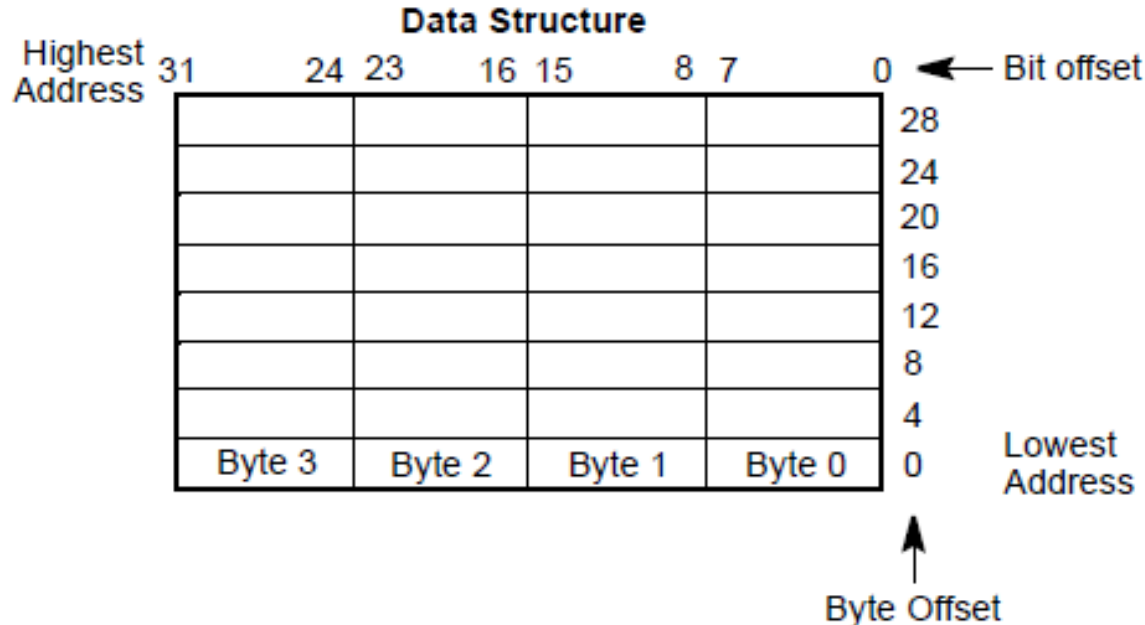
- Perform arithmetic function on register or memory data
- Transfer data between memory and register
  - Load data from memory into register
  - Store register data into memory
- Transfer control
  - Unconditional jumps to/from procedures
  - Conditional branches

# x86 Characteristics

Variable length instructions: 1-15 bytes

Can address memory directly in most instructions

Uses Little-Endian format (Least significant byte in the lowest address)



# Instruction Format

General format:

**opcode operands**

Opcode:

- Short mnemonic for instruction's purpose
  - `movb, addl, etc.`

Operands:

- Immediate, register, or memory
- Number of operands command-dependent

Example:

- `movl %ebx, (%ecx)`

# Machine Representation

Remember, each assembly instruction translated to a sequence of 1-15 bytes

Opcode	addressing mode	other bytes
--------	-----------------	-------------

First, the binary representation of the opcode

Second, instruction specifies the addressing mode

- The type of operands (registers or register and memory)
- How to interpret the operands

Some instructions can be single-byte because operands and addressing mode are implicitly specified by the instruction

- E.g., `pushl`

# x86 Registers

General purpose registers are 32 bit

- Although operations can access 8-bits or 16-bits portions

Originally categorized into two groups with different functionality

- Data registers (EAX, EBX, ECX, EDX)
  - Holds operands
- Pointer and Index registers (EBP, ESP, EIP,ESI,EDI)
  - Holds references to addresses as well as indexes

Now, the registers are mostly interchangeable

Segment registers

- Holds starting address of program segments
  - CS, DS, SS, ES

# x86 Registers

← 16 BITS →  
← 8 BITS →

<b>EAX</b>	<b>AX</b>	<b>AH</b>	<b>AL</b>
<b>ECX</b>	<b>CX</b>	<b>CH</b>	<b>CL</b>
<b>EDX</b>	<b>DX</b>	<b>DH</b>	<b>DL</b>
<b>EBX</b>	<b>BX</b>	<b>BH</b>	<b>BL</b>
<b>ESP --Stack Pointer</b>			
<b>EBP --- Base register of current stack frame</b>			
<b>ESI --- Source index for string operations</b>			
<b>EDI --- Destination index for string operations</b>			

← 32 BITS →

# x86 Programming

- Mov instructions to move data from/to memory
  - Operands and registers
- Addressing modes
- Understanding swap
- Arithmetic operations
- Condition codes
- Conditional and unconditional branches
- Loops and switch statements



# Data Format

Byte: 8 bits

- E.g., char

Word: 16 bits (2 bytes)

- E.g., short int

Double Word: 32 bits ( 4 bytes)

- E.g., int, float

Quad Word: 64 bits (8 bytes)

- E.g., double

Instructions can operate on any data size

- `movl, movw, movb`
  - Move double word, word, byte, respectively
- End character specifies what data size to be used

# MOV instruction

Most common instruction is data transfer instruction

- Mov SRC, DEST: Move source into destination
- SRC and DEST are operands
- DEST is a register or a location
- SRC can be the contents of register, memory location, constant, or a label.
- If you use gcc, you will see `movl <src>, <dest>`
- All the instructions in x86 are 32-bit

Used to copy data:

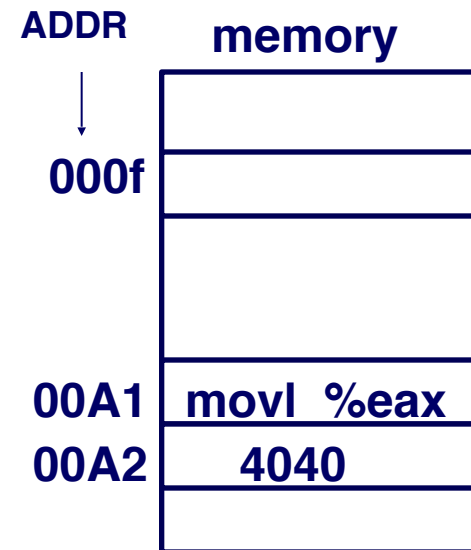
- Constant to register (immediate)
- Memory to register
- Register to memory
- Register to register

**Cannot copy memory to  
memory in a single  
instruction**

# Immediate Addressing

## Operand is immediate

- Operand value is found immediately following the instruction
- Encoded in 1, 2, or 4 bytes
- \$ in front of immediate operand
- E.g., `movl $0x4040, %eax`



# Register Mode Addressing

Use % to denote register

- E.g., %eax

Source operand: use value in specified register

Destination operand: use register as destination for value

Examples:

- `movl %eax, %ebx`
  - Copy content of %eax to %ebx
- `movl $0x4040, %eax` → immediate addressing
  - Copy 0x4040 to %eax
- `movl %eax, 0x0000f` → Absolute addressing
  - Copy content of %eax to memory location 0x0000f

# Indirect Mode Addressing

Content of operand is an address

- Designated as parenthesis around operand

Offset can be specified as immediate mode

Examples:

- `movl (%ebp), %eax`
  - Copy value from memory location whose address is in ebp into eax
- `movl -4(%ebp), %eax`
  - Copy value from memory location whose address is -4 away from content of ebp into eax

# Indexed Mode Addressing

Add content of two registers to get address of operand

- `movl (%ebp, %esi), %eax`
  - Copy value at (address =  $\text{ebp} + \text{esi}$ ) into `eax`
- `movl 8(%ebp, %esi), %eax`
  - Copy value at (address =  $8 + \text{ebp} + \text{esi}$ ) into `eax`

Useful for dealing with arrays

- If you need to walk through the elements of an array
- Use one register to hold base address, one to hold index
  - E.g., implement C array access in a for loop
- Index cannot be `ESP`

# Scaled Indexed Mode Addressing

Multiply the second operand by the scale (1, 2, 4 or 8)

- `movl 0x80(%ebx, %esi, 4), %eax`
  - Copy value at (address =  $\text{ebx} + \text{esi} * 4 + 0x80$ ) into `eax`

Where is it useful?

# Address Computation Examples

<code>%edx</code>	<code>0xf000</code>
<code>%ecx</code>	<code>0x100</code>

Expression	Computation	Address
<code>0x8(%edx)</code>	<code>0xf000 + 0x8</code>	<code>0xf008</code>
<code>(%edx,%ecx)</code>	<code>0xf000 + 0x100</code>	<code>0xf100</code>
<code>(%edx,%ecx,4)</code>	<code>0xf000 + 4*0x100</code>	<code>0xf400</code>
<code>0x80(,%edx,2)</code>	<code>2*0xf000 + 0x80</code>	<code>0x1e080</code>



# movl Operand Combinations

	Source	Destination	C Analog
movl	Imm	Reg	movl \$0x4,%eax      temp = 0x4;
		Mem	movl \$-147, (%eax)    *p = -147;
	Reg	Reg	movl %eax,%edx        temp2 = temp1;
		Mem	movl %eax, (%edx)     *p = temp;
	Mem	Reg	movl (%eax), %edx     temp = *p;

- Cannot do memory-memory transfers with single instruction

# Stack Operations

By convention, `%esp` is used to maintain a stack in memory

- Used to support C function calls

`%esp` contains the address of top of stack

Instructions to push (pop) content onto (off of) the stack

- `pushl %eax`
  - $\text{esp} = \text{esp} - 4$
  - $\text{Memory}[\text{esp}] = \text{eax}$
- `popl %ebx`
  - $\text{ebx} = \text{Memory}[\text{esp}]$
  - $\text{esp} = \text{esp} + 4$

Where does the stack start? We'll discuss later

# Using Simple Addressing Modes

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

swap:

```
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
```

} Set Up

```
    movl 12(%ebp),%ecx
    movl 8(%ebp),%edx
    movl (%ecx),%eax
    movl (%edx),%ebx
    movl %eax, (%edx)
    movl %ebx, (%ecx)
```

} Body

```
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

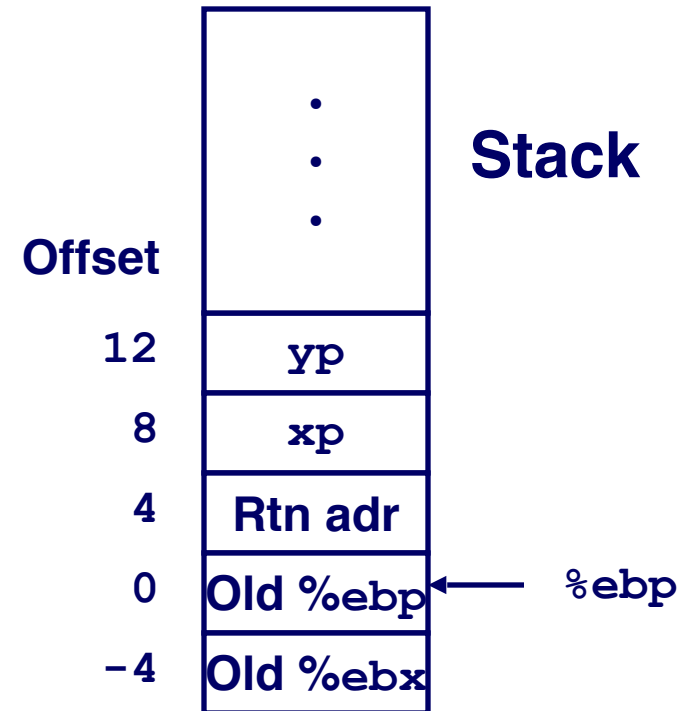
} Finish

# Understanding Swap

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

Register	Variable
%ecx	yp
%edx	xp
%eax	t1
%ebx	t0

```
movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
```



# Understanding Swap

%eax	
%edx	
%ecx	
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address	
		123	0x124
		456	0x120
			0x11c
			0x118
			0x114
yp	12	0x120	0x110
xp	8	0x124	0x10c
	4	Rtn adr	0x108
%ebp	→ 0		0x104
	-4		0x100

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
  
```

# Understanding Swap

%eax	
%edx	
%ecx	0x120
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address	
		123	0x124
		456	0x120
			0x11c
			0x118
			0x114
yp	12	0x120	0x110
xp	8	0x124	0x10c
	4	Rtn adr	0x108
%ebp	→ 0		0x104
	-4		0x100

```

movl 12(%ebp), %ecx    # ecx = yp
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movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

# Understanding Swap

%eax	
%edx	0x124
%ecx	0x120
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address	
		123	0x124
		456	0x120
			0x11c
			0x118
			0x114
yp	12	0x120	0x110
xp	8	0x124	0x10c
	4	Rtn adr	0x108
%ebp	→ 0		0x104
	-4		0x100

```

movl 12(%ebp), %ecx    # ecx = yp
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movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

# Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address	
		123	0x124
		456	0x120
			0x11c
			0x118
			0x114
yp	12	0x120	0x110
xp	8	0x124	0x10c
	4	Rtn adr	0x108
%ebp	→ 0		0x104
	-4		0x100

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```



# Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	123
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address	
		123	0x124
		456	0x120
			0x11c
			0x118
			0x114
yp	12	0x120	0x110
xp	8	0x124	0x10c
	4	Rtn adr	0x108
%ebp	→ 0		0x104
	-4		0x100

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
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movl (%edx), %ebx    # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

# Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	123
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address
		0x124
		0x120
		0x11c
		0x118
		0x114
yp	12	0x120
xp	8	0x124
	4	Rtn adr
%ebp	0	0x108
		0x104
	-4	0x100

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
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movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
    
```

# Understanding Swap

%eax	456
%edx	0x124
%ecx	0x120
%ebx	123
%esi	
%edi	
%esp	
%ebp	0x104

Offset		Address
		456
		123
yp	12	0x120
xp	8	0x124
	4	Rtn adr
%ebp	0	
	-4	

```

movl 12(%ebp), %ecx    # ecx = yp
movl 8(%ebp), %edx     # edx = xp
movl (%ecx), %eax      # eax = *yp (t1)
movl (%edx), %ebx      # ebx = *xp (t0)
movl %eax, (%edx)      # *xp = eax
movl %ebx, (%ecx)      # *yp = ebx
  
```

# Swap in x86-64: 64-bit Registers

<b>rax</b>	<b>eax</b>
<b>rcx</b>	<b>ecx</b>
<b>rdx</b>	<b>edx</b>
<b>rbx</b>	<b>ebx</b>
<b>rsp</b>	<b>esp</b>
<b>rbp</b>	<b>ebp</b>
<b>rsi</b>	<b>esi</b>
<b>rdi</b>	<b>edi</b>

<b>r8</b>
<b>r9</b>
<b>r10</b>
<b>r11</b>
<b>r12</b>
<b>r13</b>
<b>r14</b>
<b>r15</b>

# Swap in x86-64 bit

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

swap:

```
movl (%rdi), %edx
movl (%rsi), %eax
movl %eax, (%rdi)
movl %edx, (%rsi)
retq
```

Arguments passed in registers

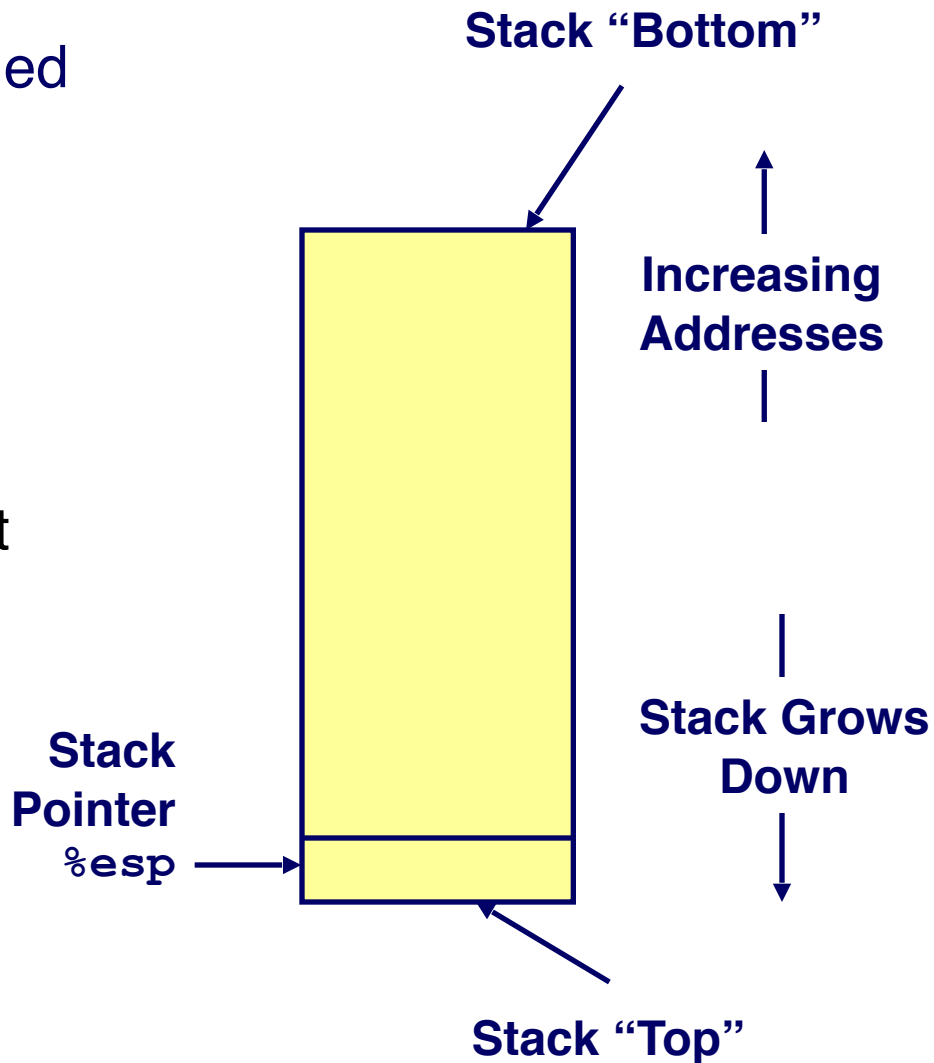
- First, xp in rdi and yp in rsi
- 64-bit pointers, data values are 32-bit ints, so uses eax/edx

No stack operations

What happens with long int?

# IA32 Stack

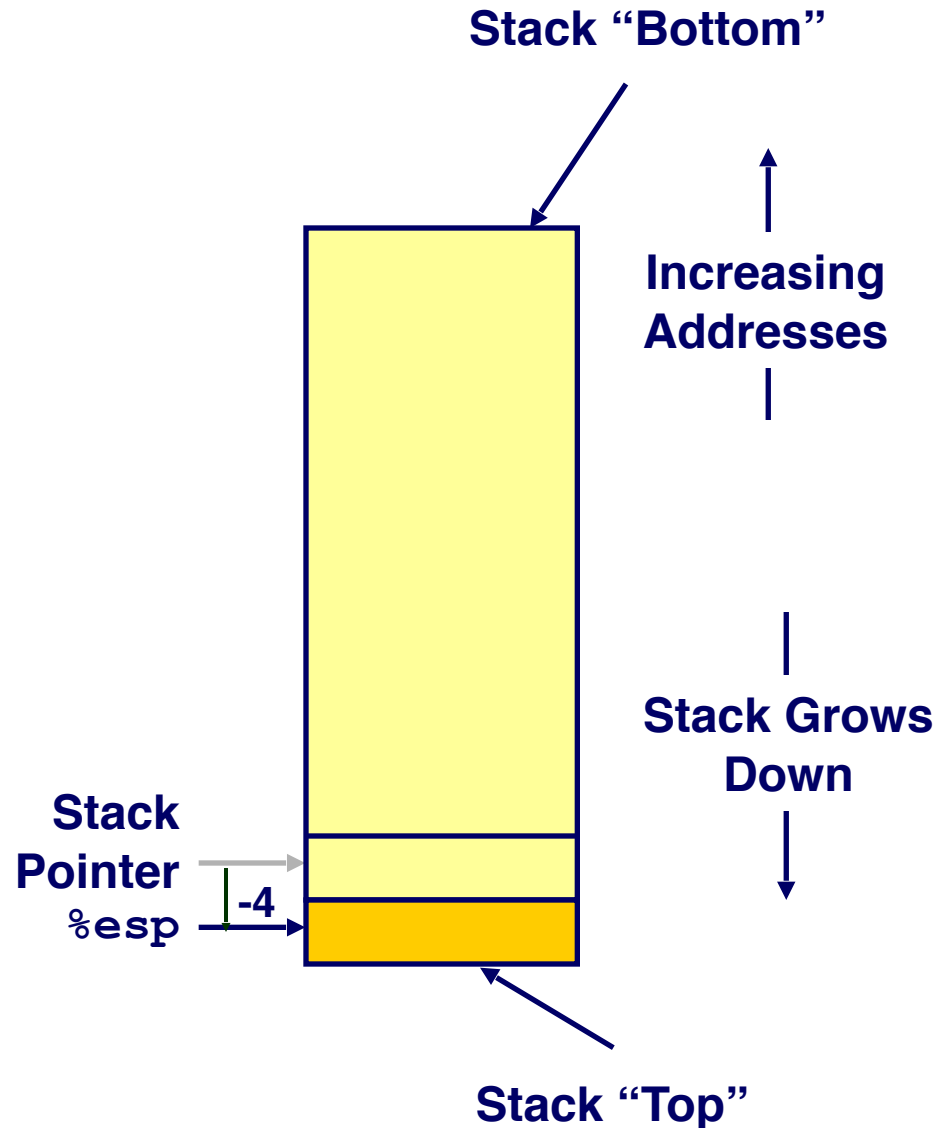
- Region of memory managed with stack discipline
- Grows toward lower addresses
- Register `%esp` indicates lowest stack address
  - address of top element



# IA32 Stack Pushing

## Pushing

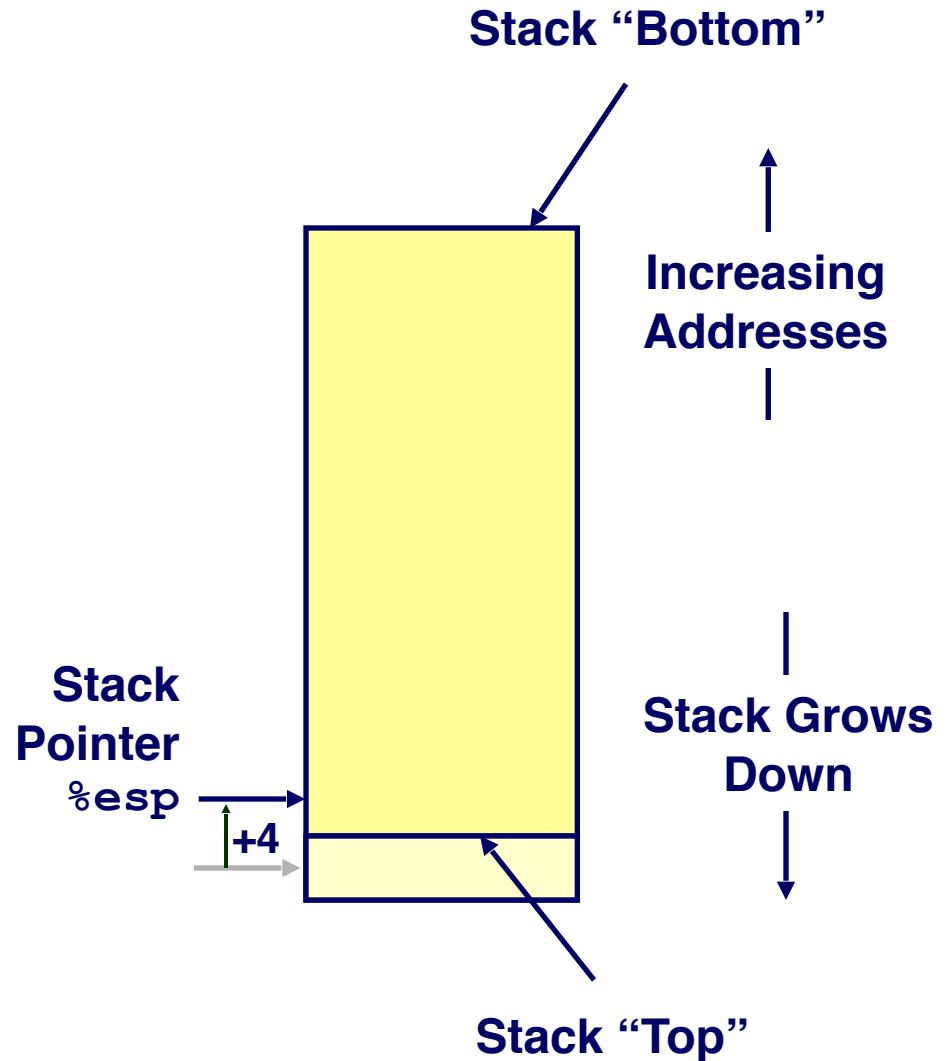
- `pushl Src`
- Fetch operand at *Src*
- Decrement `%esp` by 4
- Write operand at address given by `%esp`



# IA32 Stack Popping

## Popping

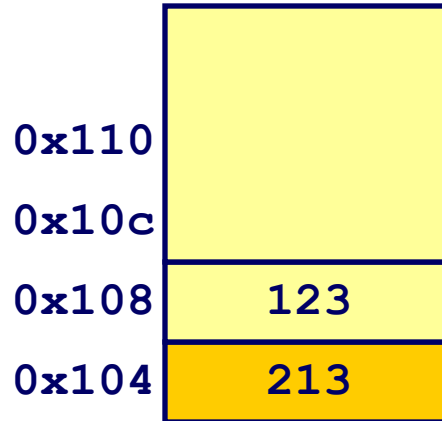
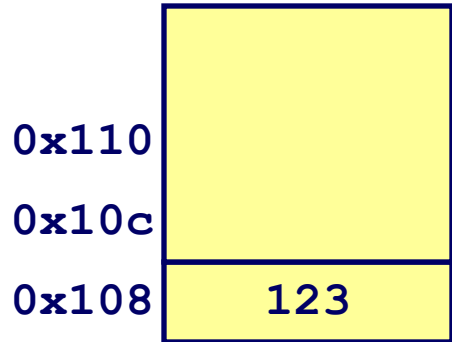
- `popl Dest`
- Read operand at address given by `%esp`
- Increment `%esp` by 4
- Write to *Dest*



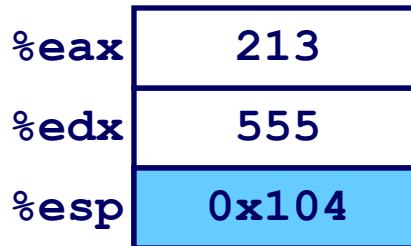
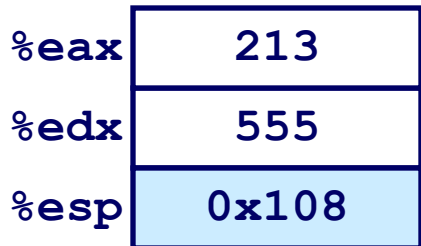
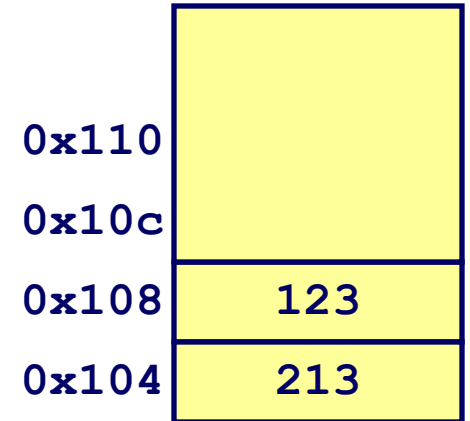


# Stack Operation Examples

`pushl %eax`



`popl %edx`



# Procedure Control Flow

- Use stack to support procedure call and return

## Procedure call:

`call label`                      Push return address on stack; Jump to `label`

## Return address value

- Address of instruction beyond `call`
- Example from disassembly

804854e:	e8 3d 06 00 00	<code>call</code>	8048b90 <main>
8048553:	50	<code>pushl</code>	%eax

- Return address = 0x8048553

## Procedure return:

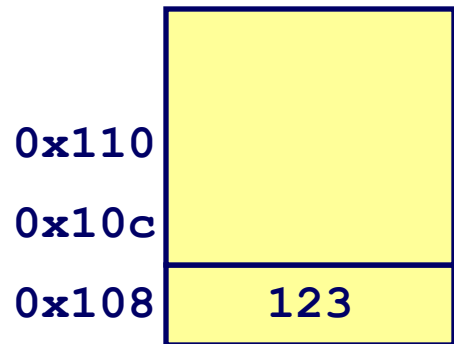
- `ret`                      Pop address from stack; Jump to address

# Procedure Call Example

804854e: e8 3d 06 00 00  
8048553: 50

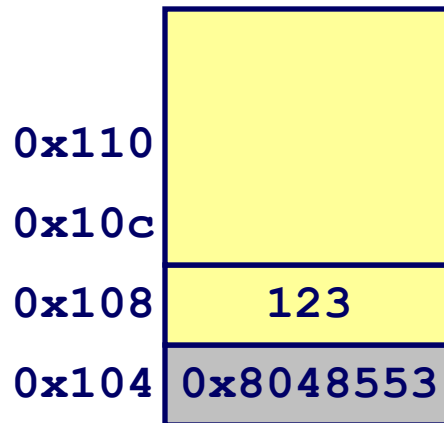
call 8048b90 <main>  
pushl %eax

call 8048b90



%esp 0x108

%eip 0x804854e



%esp 0x104

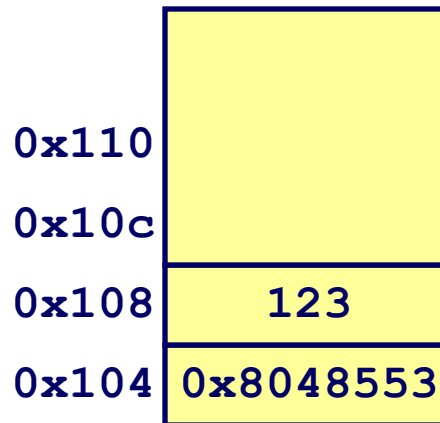
%eip 0x8048b90

%eip is program counter

# Procedure Return Example

8048591: c3

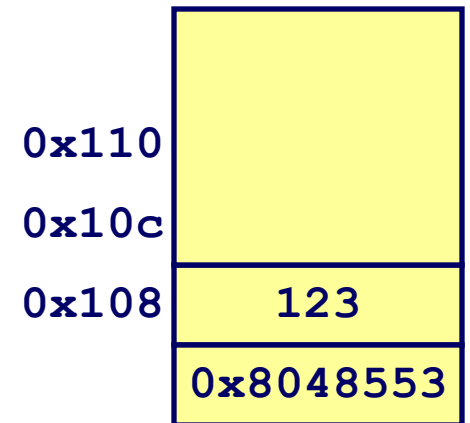
ret



`%esp` 0x104

`%eip` 0x8048591

ret



`%esp` 0x108

`%eip` 0x8048553

`%eip` is program counter

# Address Computation Instruction

leal: compute address using addressing mode without accessing memory

leal src, dest

- src is address mode expression
- Set dest to address specified by src

Use

- Computing address without doing memory reference
  - E.g., translation of  $p = \&x[i];$

Example:

- `leal 7(%edx, %edx, 4), %eax`
  - $eax = 4 * edx + edx + 7 = 5 * edx + 7$

# Some Arithmetic Operations

Instruction	Computation
<code>addl Src, Dest</code>	$Dest = Dest + Src$
<code>subl Src, Dest</code>	$Dest = Dest - Src$
<code>imull Src, Dest</code>	$Dest = Dest * Src$
<code>sall Src, Dest</code>	$Dest = Dest \ll Src$ (left shift)
<code>sarl Src, Dest</code>	$Dest = Dest \gg Src$ (right shift)
<code>xorl Src, Dest</code>	$Dest = Dest \wedge Src$
<code>andl Src, Dest</code>	$Dest = Dest \& Src$
<code>orl Src, Dest</code>	$Dest = Dest   Src$

# Some Arithmetic Operations

## Instruction

## Computation

`incl Dest`

$Dest = Dest + 1$

`decl Dest`

$Dest = Dest - 1$

`negl Dest`

$Dest = - Dest$

`notl Dest`

$Dest = \sim Dest$

# Using `leal` for Arithmetic Expressions

```
int arith
(int x, int y, int z)
{
    int t1 = x+y;
    int t2 = z+t1;
    int t3 = x+4;
    int t4 = y * 48;
    int t5 = t3 + t4;
    int rval = t2 * t5;
    return rval;
}
```

arith:

```
pushl %ebp
movl %esp,%ebp
```

} Set  
Up

```
movl 8(%ebp),%eax
movl 12(%ebp),%edx
leal (%edx,%eax),%ecx
leal (%edx,%edx,2),%edx
sall $4,%edx
addl 16(%ebp),%ecx
leal 4(%edx,%eax),%eax
imull %ecx,%eax
```

} Body

```
movl %ebp,%esp
popl %ebp
ret
```

} Finish



# Understanding arith

```
int arith
  (int x, int y, int z)
{
  int t1 = x+y;
  int t2 = z+t1;
  int t3 = x+4;
  int t4 = y * 48;
  int t5 = t3 + t4;
  int rval = t2 * t5;
  return rval;
}
```

Offset

16

12

8

4

0

·  
·  
·

z

y

x

Rtn adr

Old %ebp

Stack

← %ebp

movl 8(%ebp), %eax	# eax = x
movl 12(%ebp), %edx	# edx = y
leal (%edx, %eax), %ecx	# ecx = x+y (t1)
leal (%edx, %edx, 2), %edx	# edx = 3*y
sall \$4, %edx	# edx = 48*y (t4)
addl 16(%ebp), %ecx	# ecx = z+t1 (t2)
leal 4(%edx, %eax), %eax	# eax = 4+t4+x (t5)
imull %ecx, %eax	# eax = t5*t2 (rval)

# Understanding arith

```
int arith
(int x, int y, int z)
{
    int t1 = x+y;
    int t2 = z+t1;
    int t3 = x+4;
    int t4 = y * 48;
    int t5 = t3 + t4;
    int rval = t2 * t5;
    return rval;
}
```

```
# eax = x
movl 8(%ebp),%eax
# edx = y
movl 12(%ebp),%edx
# ecx = x+y (t1)
leal (%edx,%eax),%ecx
# edx = 3*y
leal (%edx,%edx,2),%edx
# edx = 48*y (t4)
sall $4,%edx
# ecx = z+t1 (t2)
addl 16(%ebp),%ecx
# eax = 4+t4+x (t5)
leal 4(%edx,%eax),%eax
# eax = t5*t2 (rval)
imull %ecx,%eax
```

# Another Example

```
int logical(int x, int y)
{
    int t1 = x^y;
    int t2 = t1 >> 17;
    int mask = (1<<13) - 7;
    int rval = t2 & mask;
    return rval;
}
```

$2^{13} = 8192, 2^{13} - 7 = 8185$

logical:

```
pushl %ebp
movl %esp,%ebp
```

} Set  
Up

```
movl 8(%ebp),%eax
xorl 12(%ebp),%eax
sarl $17,%eax
andl $8185,%eax
```

} Body

```
movl %ebp,%esp
popl %ebp
ret
```

} Finish

```
movl 8(%ebp),%eax
xorl 12(%ebp),%eax
sarl $17,%eax
andl $8185,%eax
```

```
eax = x
eax = x^y      (t1)
eax = t1>>17  (t2)
eax = t2 & 8185
```

# Mystery Function

What does the following piece of code do?

- A. Add two variables
- B. Subtract two variables
- C. Swap two variables
- D. No idea

```
movl 12(%ebp), %ecx  
movl 8(%ebp), %edx  
movl (%ecx), %eax  
movl (%edx), %ebx  
movl %eax, (%edx)  
movl %ebx, (%ecx)
```

# What does this function do?

```
.globl foo
.type   foo, @function
foo:
    pushl   %ebp

    movl    %esp, %ebp

    movl    16(%ebp), %eax

    imull   12(%ebp), %eax

    addl    8(%ebp), %eax

    popl    %ebp

    ret
```

# Control Flow/Conditionals

How do we represent conditionals in assembly?

A conditional branch can implement all control flow constructs in higher level language

- Examples: if/then, while, for

A unconditional branch for constructs like break/ continue

# Condition Codes

## Single Bit Registers

CF    Carry Flag

SF    Sign Flag

ZF    Zero Flag

OF    Overflow Flag

Can be set either **implicitly** or **explicitly**.

- Implicitly by almost all logic and arithmetic operations
- Explicitly by specific comparison operations

*Not* Set by `leal` instruction

- Intended for use in address computation only

# Jumping

## jX Instructions

- Jump to different part of code depending on condition codes

<b>jX</b>	<b>Condition</b>	<b>Description</b>
<b>jmp</b>	<b>1</b>	<b>Unconditional</b>
<b>je</b>	<b>ZF</b>	<b>Equal / Zero</b>
<b>jne</b>	<b>~ZF</b>	<b>Not Equal / Not Zero</b>
<b>js</b>	<b>SF</b>	<b>Negative</b>
<b>jns</b>	<b>~SF</b>	<b>Nonnegative</b>
<b>jg</b>	<b>~ (SF^OF) &amp; ~ZF</b>	<b>Greater (Signed)</b>
<b>jge</b>	<b>~ (SF^OF)</b>	<b>Greater or Equal (Signed)</b>
<b>jl</b>	<b>(SF^OF)</b>	<b>Less (Signed)</b>
<b>jle</b>	<b>(SF^OF)   ZF</b>	<b>Less or Equal (Signed)</b>
<b>ja</b>	<b>~CF &amp; ~ZF</b>	<b>Above (unsigned)</b>
<b>jb</b>	<b>CF</b>	<b>Below (unsigned)</b>



# Condition Codes

## Implicitly Set By Arithmetic Operations

`addl Src, Dest`

C analog: `t = a + b`

- CF set if carry out from most significant bit
  - Used to detect unsigned overflow
- ZF set if `t == 0`
- SF set if `t < 0`
- OF set if two's complement overflow

`(a > 0 && b > 0 && t < 0) || (a < 0 && b < 0 && t >= 0)`

# Setting Condition Codes (cont.)

## Explicit Setting by Compare Instruction

`cmpl Src2,Src1`

- `cmpl b, a` like computing `a-b` without setting destination
- NOTE: The operands are reversed. Source of confusion
- CF set if carry out from most significant bit
  - Used for unsigned comparisons
- ZF set if `a == b`
- SF set if `(a-b) < 0`
- OF set if two's complement overflow  
`(a>0 && b<0 && (a-b)<0) || (a<0 && b>0 && (a-b)>0)`

# Setting Condition Codes (cont.)

## Explicit Setting by Test instruction

`testl Src2,Src1`

- Sets condition codes based on value of *Src1* & *Src2*
  - Useful to have one of the operands be a mask
- `testl b,a` like computing `a&b` without setting destination
- ZF set when `a&b == 0`
- SF set when `a&b < 0`

# Conditional Branch Example

```

_max:
    pushl %ebp
    movl %esp,%ebp
    movl 8(%ebp),%edx
    movl 12(%ebp),%eax
    cmpl %eax,%edx
    jle L9
    movl %edx,%eax
L9:
    movl %ebp,%esp
    popl %ebp
    ret

```

Diagram illustrating the structure of the assembly code, grouped into three sections:

- Set Up**:
  - `pushl %ebp`
  - `movl %esp,%ebp`
- Body**:
  - `movl 8(%ebp),%edx`
  - `movl 12(%ebp),%eax`
  - `cmpl %eax,%edx`
  - `jle L9`
  - `movl %edx,%eax`
- Finish**:
  - `movl %ebp,%esp`
  - `popl %ebp`
  - `ret`

# Conditional Branch Example

```
int max(int x, int y)
{
    if (x <= y)
        return y;
    else
        return x;
}
```

**\_max:**

```
pushl %ebp
movl %esp,%ebp
```

} Set  
Up

```
movl 8(%ebp),%edx
movl 12(%ebp),%eax
cmpl %eax,%edx
jle L9
movl %edx,%eax
```

} Body

**L9:**

```
movl %ebp,%esp
popl %ebp
ret
```

} Finish

# Conditional Branch Example (Cont.)

```
int goto_max(int x, int y)
{
    int rval = y;
    int ok = (x <= y);
    if (ok)
        goto done;
    rval = x;
done:
    return rval;
}
```

```
int max(int x, int y)
{
    if (x <= y)
        return y;
    else
        return x;
}
```

- C allows “goto” as means of transferring control
  - Closer to machine-level programming style
- Generally considered bad coding style

```
movl 8(%ebp),%edx    # edx = x
movl 12(%ebp),%eax   # eax = y
cmpl %eax,%edx       # x : y
jle L9               # if <= goto L9
movl %edx,%eax       # eax = x
L9:                  # Done: }
```

Skipped when  $x \leq y$

# Mystery Function

```
.LC0:
    .string "%d"
    .text
.globl foo
.type  foo, @function
foo:
    pushl  %ebp
    movl   %esp, %ebp
    subl   $40, %esp
    leal   -12(%ebp), %eax
    movl   %eax, 4(%esp)
    movl   $.LC0, (%esp)
    call   scanf
    cmpl   $4, -12(%ebp)
    je     .L3
    call   explode_bomb
.L3:
    leave
    .p2align 4,,3
    ret
```

# “Do-While” Loop Example

## C Code

```
int fact_do(int x)
{
    int result = 1;
    do {
        result *= x;
        x = x-1;
    } while (x > 1);
    return result;
}
```



# “Do-While” Loop Example

## C Code

```
int fact_do(int x)
{
    int result = 1;
    do {
        result *= x;
        x = x-1;
    } while (x > 1);
    return result;
}
```

## Goto Version

```
int fact_goto(int x)
{
    int result = 1;
loop:
    result *= x;
    x = x-1;
    if (x > 1)
        goto loop;
    return result;
}
```

- Use backward branch to continue looping
- Only take branch when “while” condition holds

# “Do-While” Loop Compilation

## Goto Version

```
int fact_goto(int x)
{
    int result = 1;
loop:
    result *= x;
    x = x-1;
    if (x > 1)
        goto loop;
    return result;
}
```

## Assembly

```
_fact_goto:
    pushl %ebp                # Setup
    movl %esp,%ebp           # Setup
    movl $1,%eax              # eax = 1
    movl 8(%ebp),%edx          # edx = x

L11:
    imull %edx,%eax           # result *= x
    decl %edx                  # x--
    cmpl $1,%edx              # Compare x : 1
    jg L11                    # if > goto loop

    movl %ebp,%esp           # Finish
    popl %ebp                 # Finish
    ret                       # Finish
```

## Registers

%edx x

%eax result

# General “Do-While” Translation

## C Code

```
do  
    Body  
while (Test) ;
```

## Goto Version

```
loop:  
    Body  
    if (Test)  
        goto loop
```

- *Body* can be any C statement
  - Typically compound statement:

```
{  
    Statement1;  
    Statement2;  
    ...  
    Statementn;  
}
```

- *Test* is expression returning integer  
= 0 interpreted as false ≠ 0 interpreted as true

# “While” Loop Example #1

## C Code

```
int fact_while(int x)
{
    int result = 1;
    while (x > 1) {
        result *= x;
        x = x-1;
    };
    return result;
}
```

# Actual “While” Loop Translation

## C Code

```
int fact_while(int x)
{
    int result = 1;
    while (x > 1) {
        result *= x;
        x = x-1;
    };
    return result;
}
```

- Uses same inner loop as do-while version
- Guards loop entry with extra test

## Goto Version

```
int fact_while_goto2
(int x)
{
    int result = 1;
    if (!(x > 1))
        goto done;
loop:
    result *= x;
    x = x-1;
    if (x > 1)
        goto loop;
done:
    return result;
}
```

# General “While” Translation

## C Code

```
while (Test)  
    Body
```



## Do-While Version

```
if (!Test)  
    goto done;  
do  
    Body  
    while(Test) ;  
done:
```



## Goto Version

```
if (!Test)  
    goto done;  
loop:  
    Body  
    if (Test)  
        goto loop;  
done:
```

# Switch Statements

## Implementation Options

- Series of conditionals
  - Good if few cases
  - Slow if many
- Jump Table
  - Lookup branch target
  - Avoids conditionals
  - Possible when cases are small integer constants
- GCC
  - Picks one based on case structure
- Bug in example code
  - No default given

```
typedef enum
{ADD, MULT, MINUS, DIV, MOD, BAD}
  op_type;

char unparse_symbol(op_type op)
{
    switch (op) {
        case ADD :
            return '+';
        case MULT:
            return '*';
        case MINUS:
            return '-';
        case DIV:
            return '/';
        case MOD:
            return '%';
        case BAD:
            return '?';
    }
}
```

# Jump Table Structure

## Switch Form

```
switch(op) {  
  case val_0:  
    Block 0  
  case val_1:  
    Block 1  
    . . .  
  case val_n-1:  
    Block n-1  
}
```

## Jump Table

jtab:

Targ0
Targ1
Targ2
• • •
Targn-1

## Jump Targets

Targ0:

**Code Block  
0**

Targ1:

**Code Block  
1**

Targ2:

**Code Block  
2**

•  
•  
•

Targn-1:

**Code Block  
*n-1***

## Approx. Translation

```
target = JTab[op];  
goto *target;
```



# Switch Statement Example

## Branching Possibilities

```
typedef enum
{ADD, MULT, MINUS, DIV, MOD, BAD}
  op_type;

char unparse_symbol(op_type op)
{
    switch (op) {
        . . .
    }
}
```

## Enumerated Values

ADD	0
MULT	1
MINUS	2
DIV	3
MOD	4
BAD	5

## Setup:

```
unparse_symbol:
    pushl %ebp                # Setup
    movl %esp,%ebp           # Setup
    movl 8(%ebp),%eax         # eax = op
    cmpl $5,%eax             # Compare op : 5
    ja .L49                  # If > goto done
    jmp *.L57(,%eax,4)        # goto Table[op]
```

# Assembly Setup Explanation

## Table Structure

- Each target requires 4 bytes
- Base address at `.L57`

## Jumping

```
jmp .L49
```

- Jump target is denoted by label `.L49`

```
jmp *.L57(,%eax,4)
```

- Start of jump table denoted by label `.L57`
- Register `%eax` holds `op`
- Must scale by factor of 4 to get offset into table
- Fetch target from effective Address `.L57 + op*4`

# Jump Table

## Table Contents

```
.section .rodata
    .align 4
.L57:
    .long .L51 #Op = 0
    .long .L52 #Op = 1
    .long .L53 #Op = 2
    .long .L54 #Op = 3
    .long .L55 #Op = 4
    .long .L56 #Op = 5
```

## Enumerated Values

ADD	0
MULT	1
MINUS	2
DIV	3
MOD	4
BAD	5

## Targets & Completion

```
.L51:
    movl $43,%eax # '+'
    jmp .L49
.L52:
    movl $42,%eax # '*'
    jmp .L49
.L53:
    movl $45,%eax # '-'
    jmp .L49
.L54:
    movl $47,%eax # '/'
    jmp .L49
.L55:
    movl $37,%eax # '%'
    jmp .L49
.L56:
    movl $63,%eax # '?'
    # Fall Through to .L49
```

# Switch Statement Completion

<code>.L49:</code>	<code># Done:</code>
<code>movl %ebp,%esp</code>	<code># Finish</code>
<code>popl %ebp</code>	<code># Finish</code>
<code>ret</code>	<code># Finish</code>

## Puzzle

- What value returned when `op` is invalid?

## Answer

- Register `%eax` set to `op` at beginning of procedure
- This becomes the returned value

## Advantage of Jump Table

- Can do  $k$ -way branch in  $O(1)$  operations

# Reading Condition Codes

## SetX Instructions

- Set single byte based on combinations of condition codes

SetX	Condition	Description
<b>sete</b>	<b>ZF</b>	<b>Equal / Zero</b>
<b>setne</b>	<b><math>\sim</math>ZF</b>	<b>Not Equal / Not Zero</b>
<b>sets</b>	<b>SF</b>	<b>Negative</b>
<b>setns</b>	<b><math>\sim</math>SF</b>	<b>Nonnegative</b>
<b>setg</b>	<b><math>\sim (SF \wedge OF) \ \&amp; \ \sim ZF</math></b>	<b>Greater (Signed)</b>
<b>setge</b>	<b><math>\sim (SF \wedge OF)</math></b>	<b>Greater or Equal (Signed)</b>
<b>setl</b>	<b><math>(SF \wedge OF)</math></b>	<b>Less (Signed)</b>
<b>setle</b>	<b><math>(SF \wedge OF) \   \ ZF</math></b>	<b>Less or Equal (Signed)</b>
<b>seta</b>	<b><math>\sim CF \ \&amp; \ \sim ZF</math></b>	<b>Above (unsigned)</b>
<b>setb</b>	<b>CF</b>	<b>Below (unsigned)</b>

# Reading Condition Codes (Cont.)

## SetX Instructions

- Set single byte based on combinations of condition codes
- One of 8 addressable byte registers
  - Embedded within first 4 integer registers
  - Does not alter remaining 3 bytes
  - Typically use `movzbl` to finish job

```
int gt (int x, int y) {  
    return x > y;  
}
```

### Body

```
movl 12(%ebp),%eax    # eax = y  
cmpl %eax,8(%ebp)     # Compare x : y  
setg %al              # al = x > y  
movzbl %al,%eax       # Zero rest of %eax
```

%eax	%ah	%al
%edx	%dh	%dl
%ecx	%ch	%cl
%ebx	%bh	%bl
%esi		
%edi		
%esp		
%ebp		

Note  
inverted  
ordering!

# Can you write the C code for this assembly?

```
.globl test
```

```
.type test, @function
```

```
test:
```

```
    pushl %ebp
    movl  %esp, %ebp
    pushl %ebx
    movl  8(%ebp), %edx
    movl  12(%ebp), %ecx
    movl  $1, %eax
    cmpl  %ecx, %edx
    jge   .L3
```

```
.L6:
```

```
    leal  (%edx,%ecx), %ebx
    imull %ebx, %eax
    addl  $1, %edx
    cmpl  %edx, %ecx
    jg    .L6
```

```
.L3:
```

```
    popl  %ebx
    popl  %ebp
    ret
```

What does this function do?

What is the C code?

# Stack-Based Languages

## Languages that Support Recursion

- e.g., C, Pascal, Java
- Code must be “*Reentrant*”
  - Multiple simultaneous instantiations of single procedure
- Need some place to store state of each instantiation
  - Arguments, local variables, return pointer

## Stack Discipline

- State for given procedure needed for limited time
  - From when called to when return
- Callee returns before caller does

## Stack Allocated in *Frames* (*Activation records*)

- state for single procedure instantiation



# Call Chain Example

## Code Structure

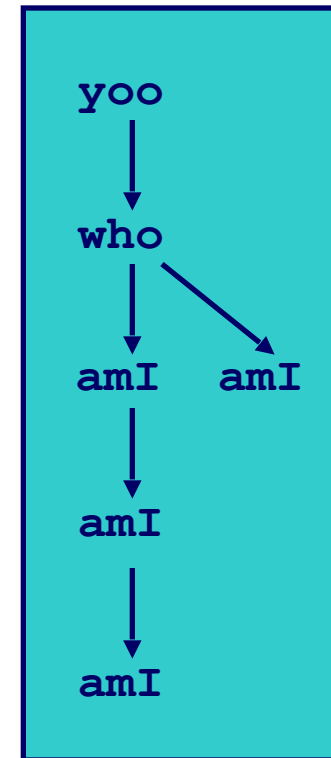
```
yoo (...)  
{  
  .  
  .  
  who () ;  
  .  
  .  
}
```

```
who (...)  
{  
  . . .  
  amI () ;  
  . . .  
  amI () ;  
  . . .  
}
```

```
amI (...)  
{  
  .  
  .  
  amI () ;  
  .  
  .  
}
```

- Procedure `amI` recursive

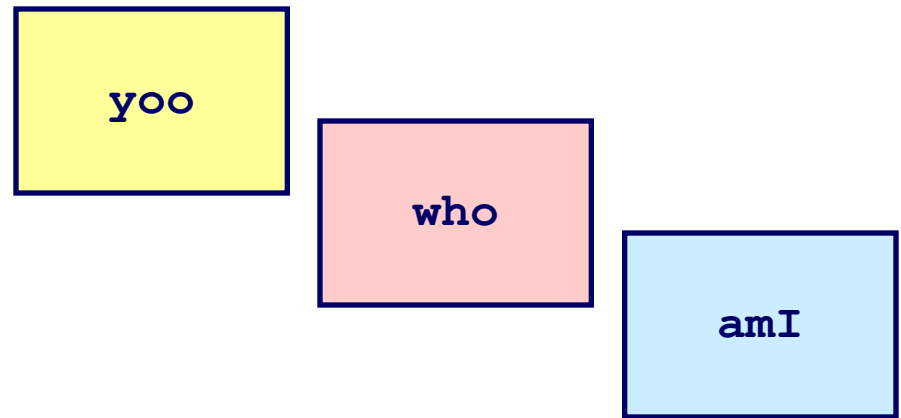
## Call Chain



# Stack Frames

## Contents

- Local variables, return value
- Temporary space

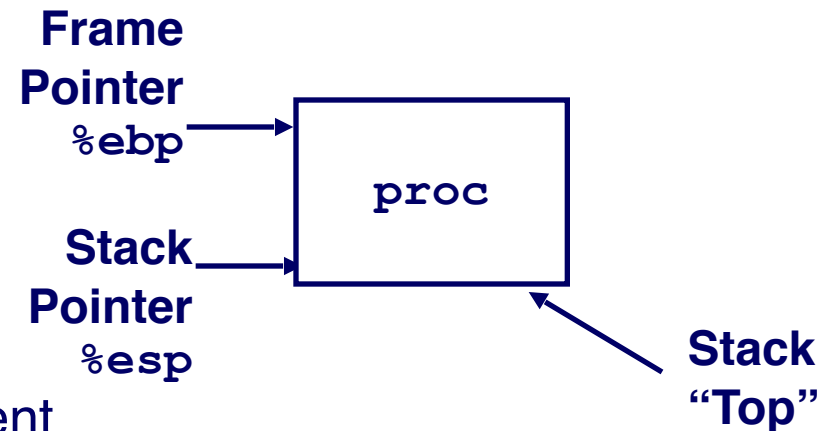


## Management

- Space allocated when enter procedure
  - “Set-up” code
- Deallocated when return
  - “Finish” code

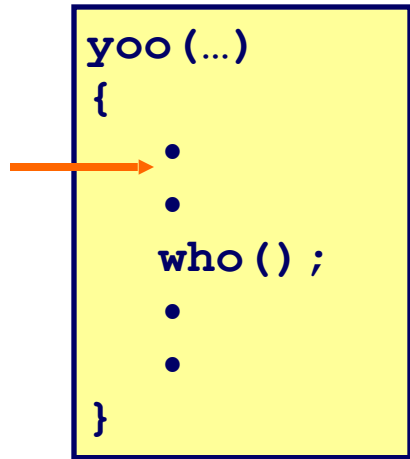
## Pointers

- Stack pointer `%esp` : stack top
- Frame pointer `%ebp` : start of current frame



# Stack Operation

## Call Chain

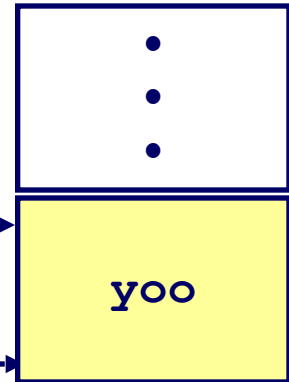


yoo

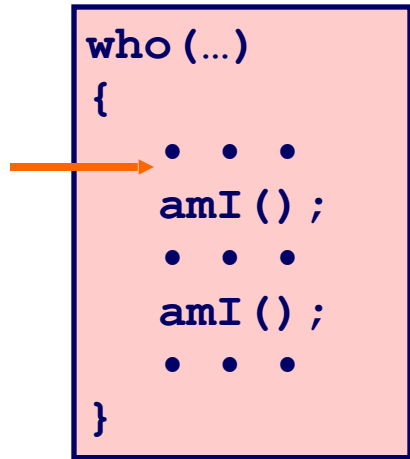
Frame  
Pointer

%ebp

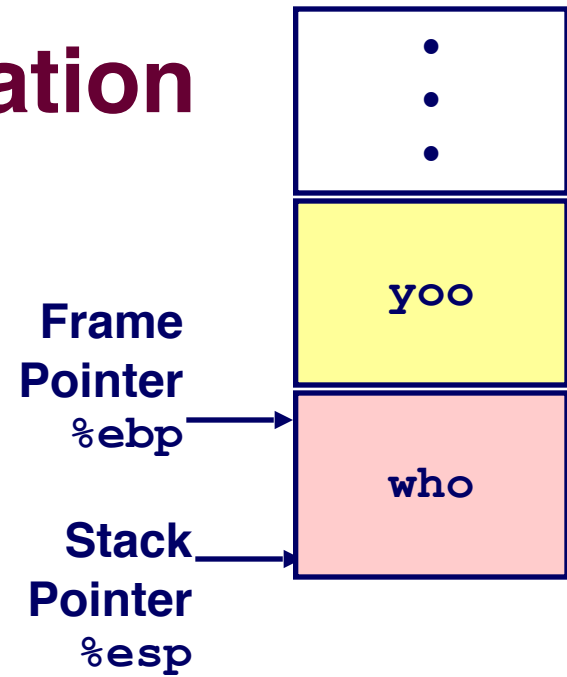
Stack  
Pointer  
%esp



# Stack Operation

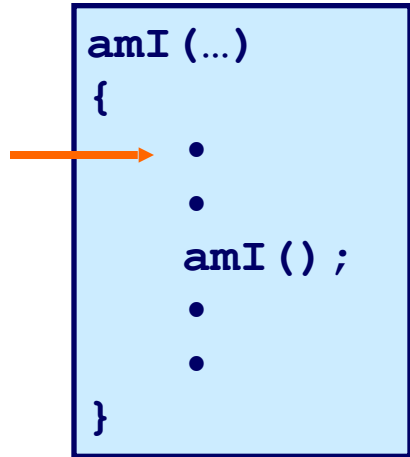


## Call Chain



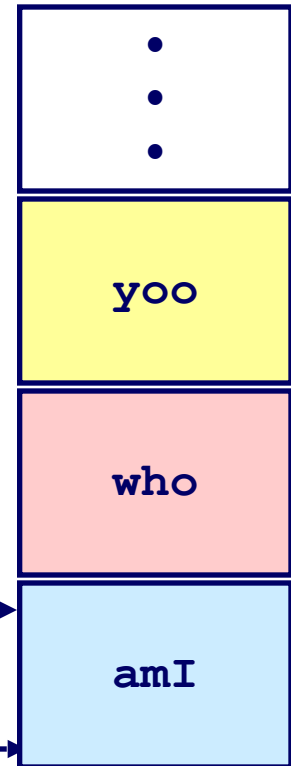
# Stack Operation

## Call Chain

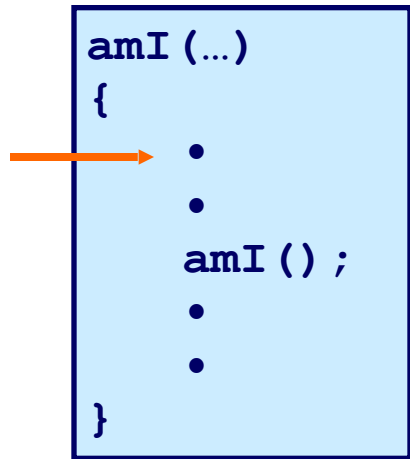


Frame  
Pointer  
`%ebp`

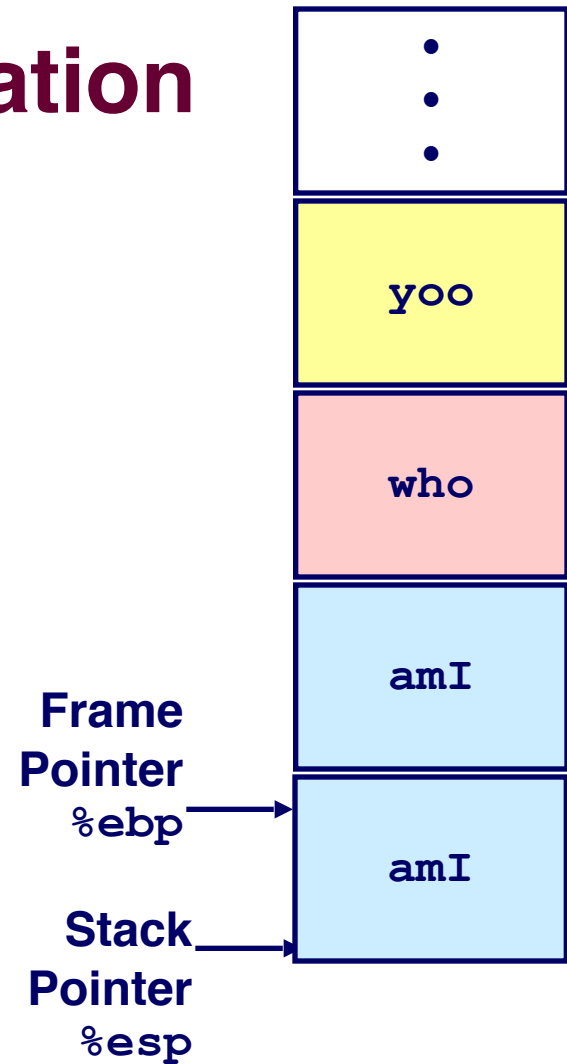
Stack  
Pointer  
`%esp`



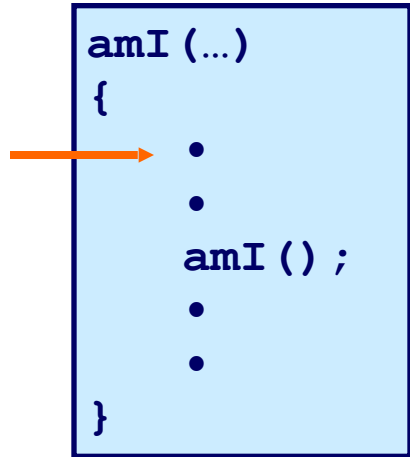
# Stack Operation



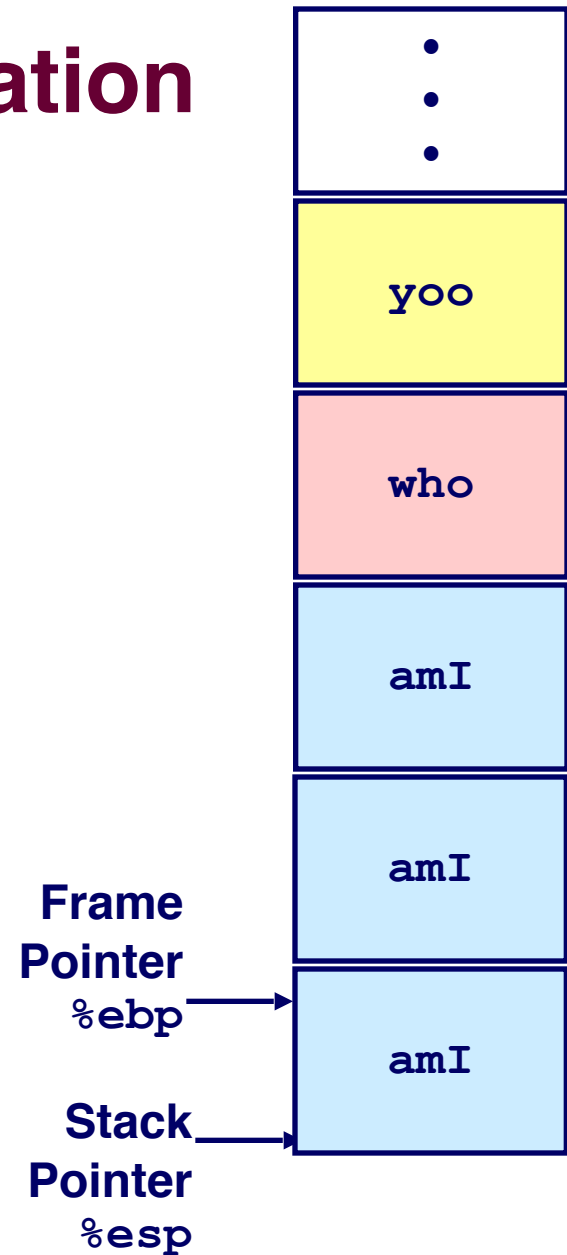
## Call Chain



# Stack Operation

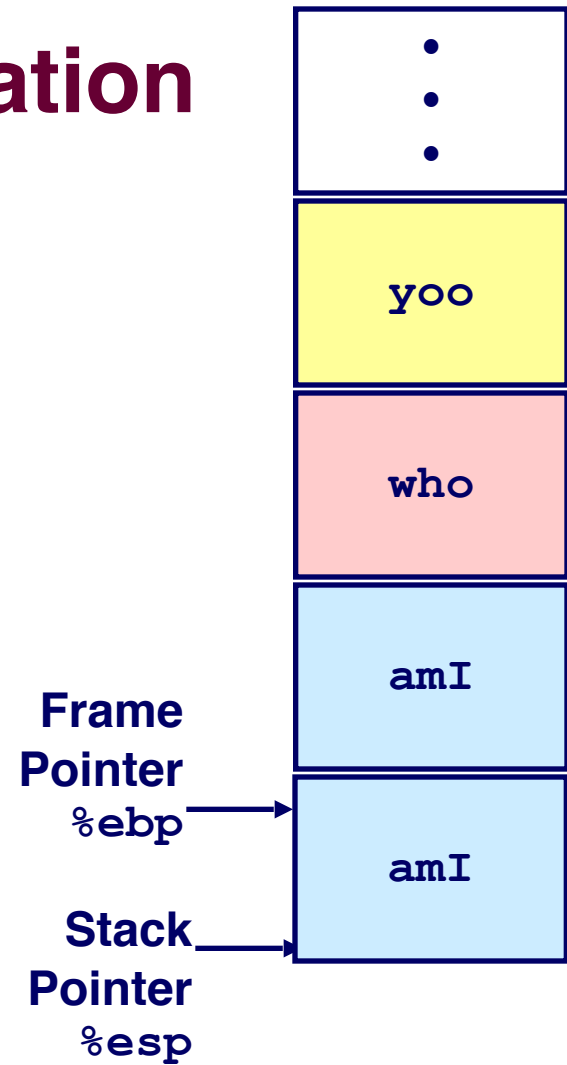
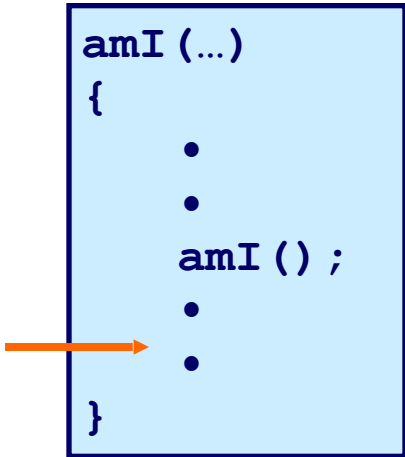


## Call Chain



# Stack Operation

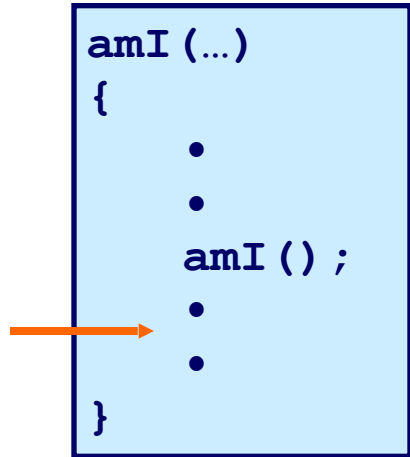
## Call Chain





# Stack Operation

## Call Chain



yoo



who



amI



amI

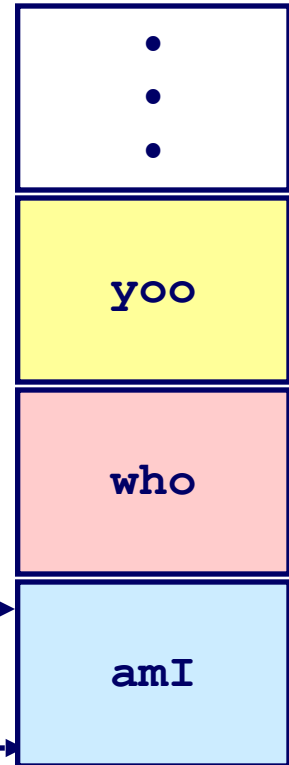


amI

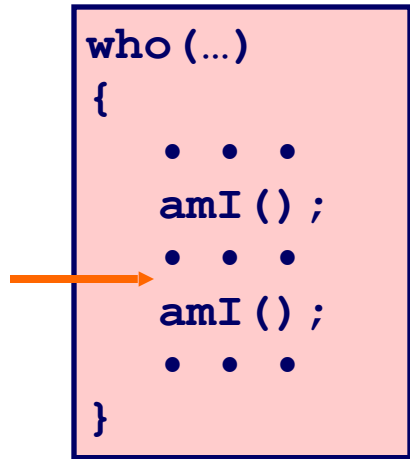
Frame  
Pointer  
`%ebp`



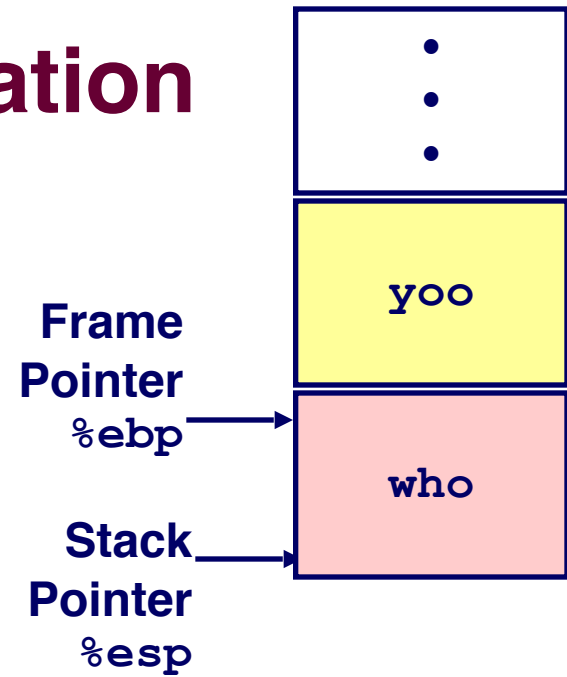
Stack  
Pointer  
`%esp`



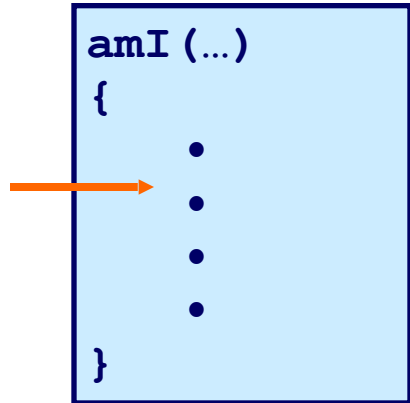
# Stack Operation



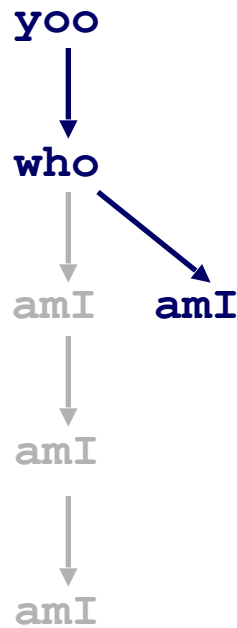
## Call Chain



# Stack Operation

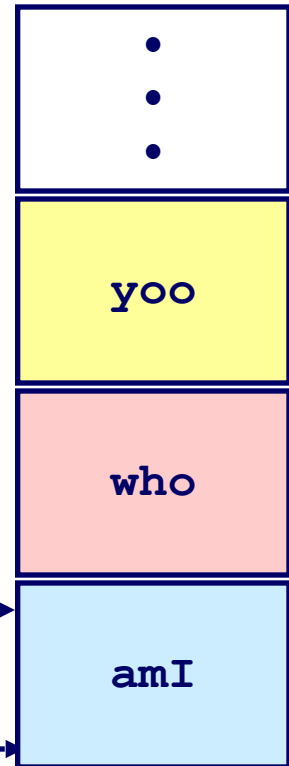


## Call Chain

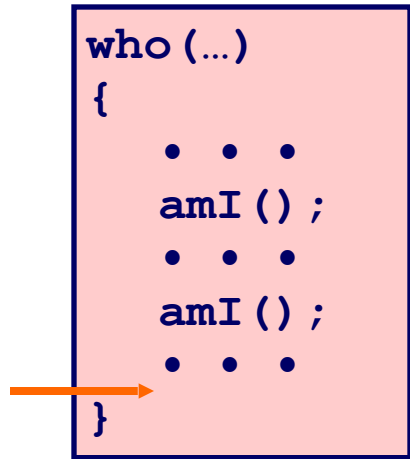


Frame  
Pointer  
`%ebp`

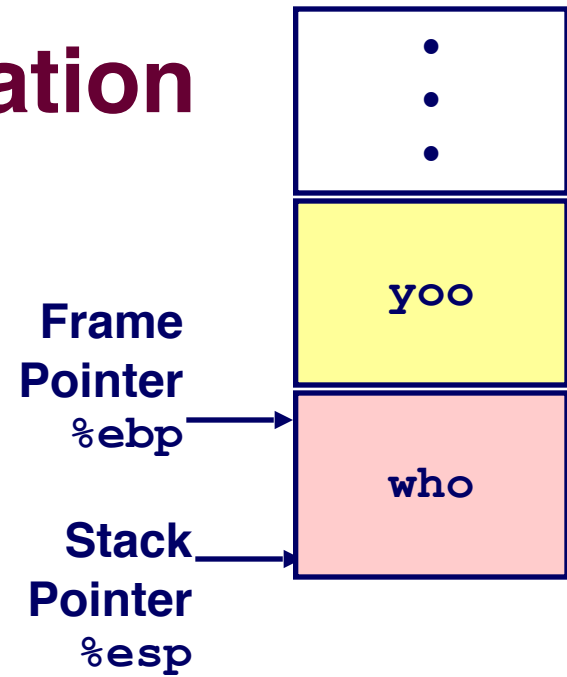
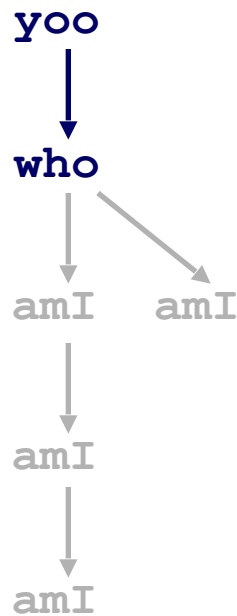
Stack  
Pointer  
`%esp`



# Stack Operation

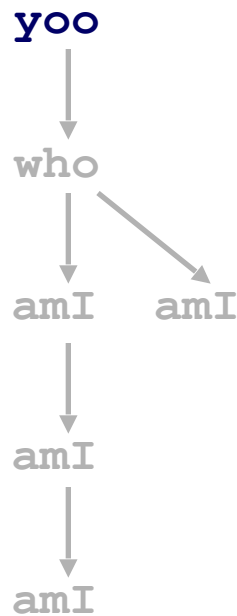
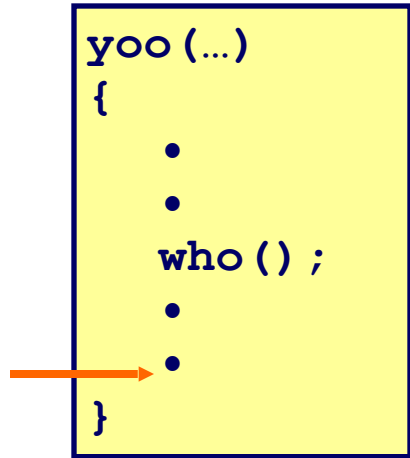


## Call Chain



# Stack Operation

## Call Chain



Frame

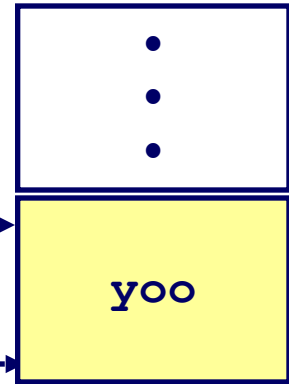
Pointer

`%ebp`

Stack

Pointer

`%esp`



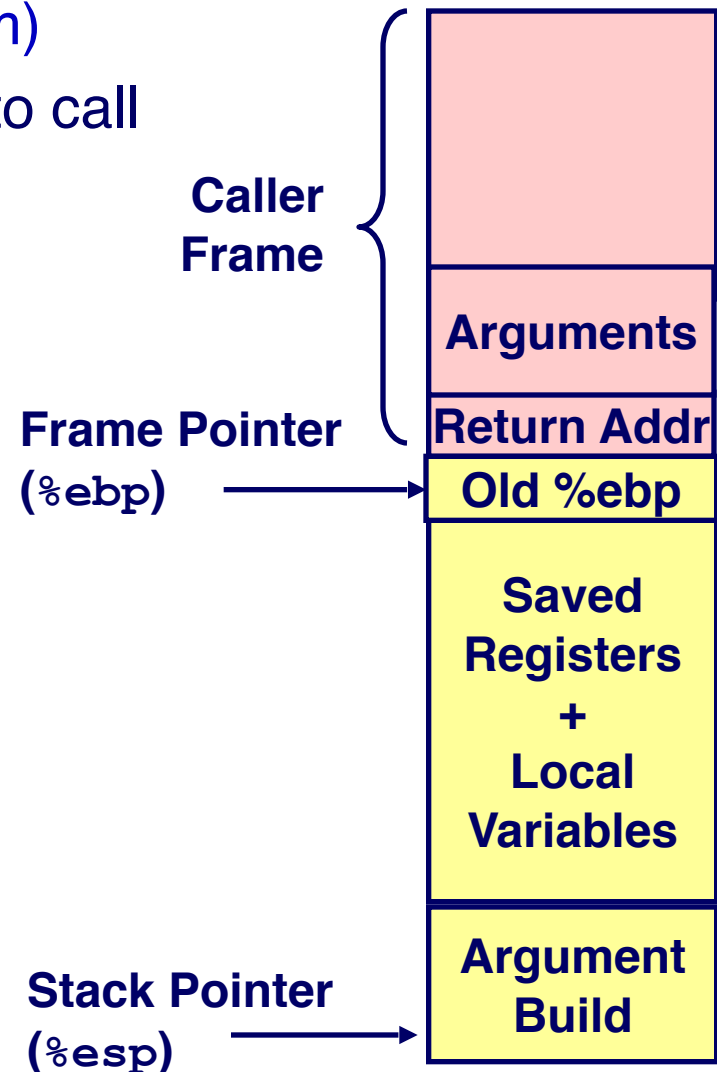
# IA32/Linux Stack Frame

## Current Stack Frame (“Top” to Bottom)

- Parameters for function about to call
  - “Argument build”
- Local variables
  - If can’t keep in registers
- Saved register context
- Old frame pointer

## Caller Stack Frame

- Return address
  - Pushed by `call` instruction
- Arguments for this call



# Revisiting swap

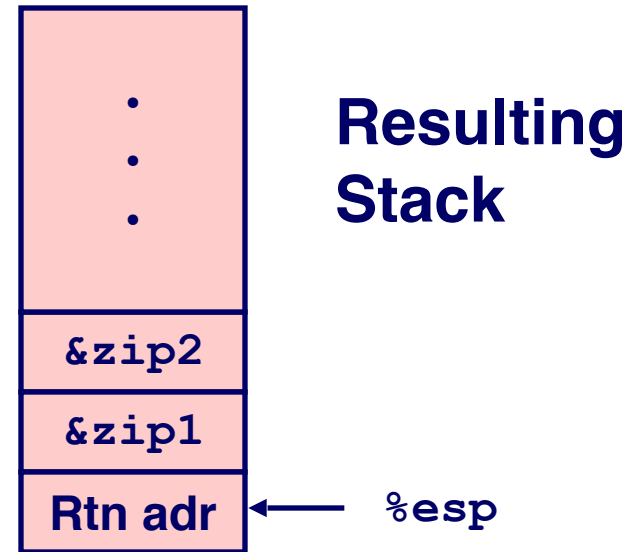
```
int zip1 = 15213;
int zip2 = 91125;

void call_swap()
{
    swap(&zip1, &zip2);
}
```

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

## Calling swap from call\_swap

```
call_swap:
    . . .
    pushl $zip2    # Global Var
    pushl $zip1    # Global Var
    call swap
    . . .
```



# Revisiting swap

```
void swap(int *xp, int *yp)
{
    int t0 = *xp;
    int t1 = *yp;
    *xp = t1;
    *yp = t0;
}
```

swap:

```
pushl %ebp
movl %esp,%ebp
pushl %ebx
```

} Set  
Up

```
movl 12(%ebp),%ecx
movl 8(%ebp),%edx
movl (%ecx),%eax
movl (%edx),%ebx
movl %eax, (%edx)
movl %ebx, (%ecx)
```

} Body

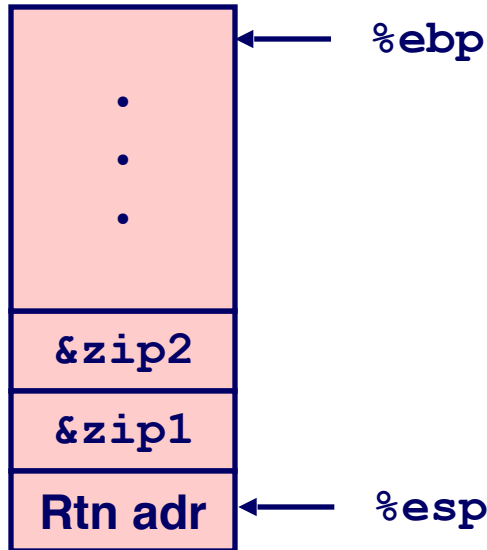
```
movl -4(%ebp),%ebx
movl %ebp,%esp
popl %ebp
ret
```

} Finish

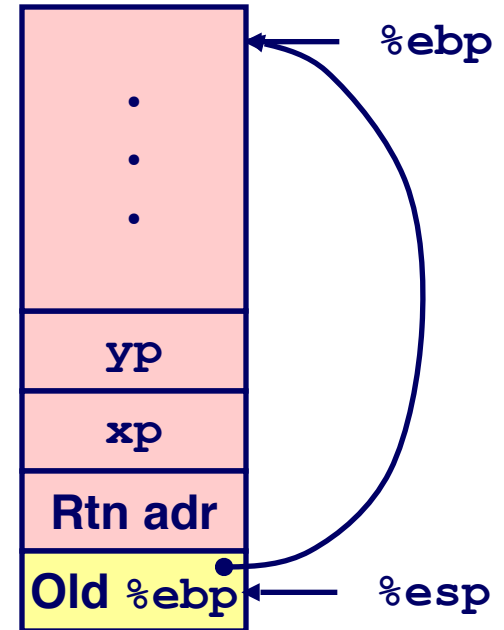


# swap Setup #1

## Entering Stack



## Resulting Stack

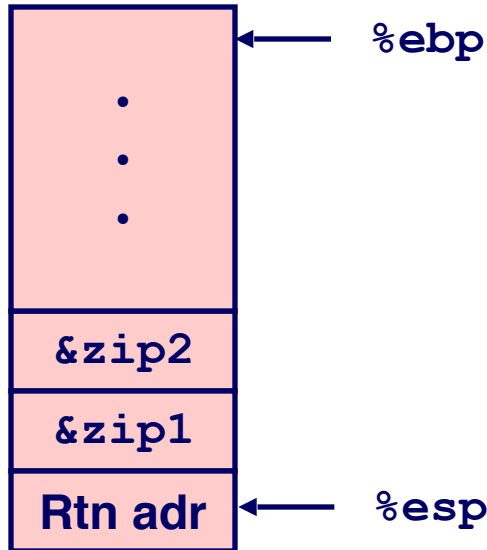


swap:

```
pushl %ebp  
movl %esp,%ebp  
pushl %ebx
```

# swap Setup #2

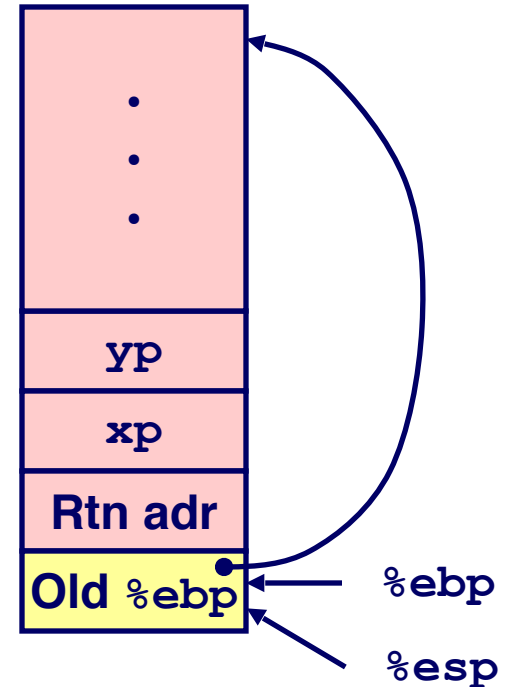
## Entering Stack



`swap:`

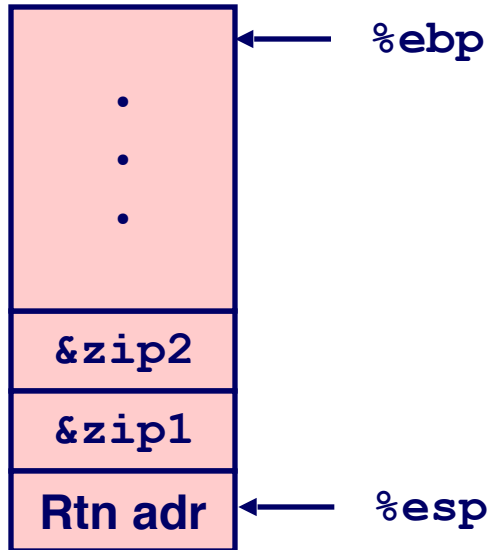
```
pushl %ebp  
movl %esp, %ebp  
pushl %ebx
```

## Resulting Stack



# swap Setup #3

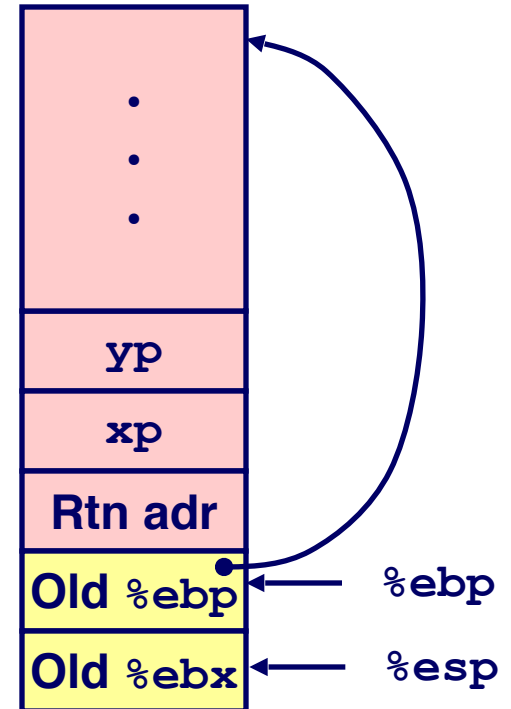
## Entering Stack



swap:

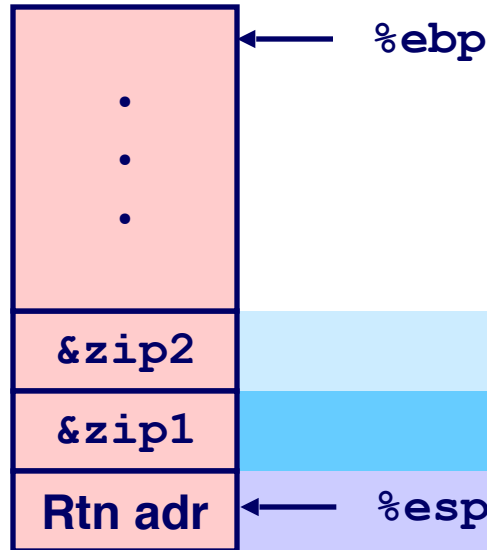
```
pushl %ebp  
movl %esp,%ebp  
pushl %ebx
```

## Resulting Stack



# Effect of swap Setup

## Entering Stack



Offset  
(relative to `%ebp`)

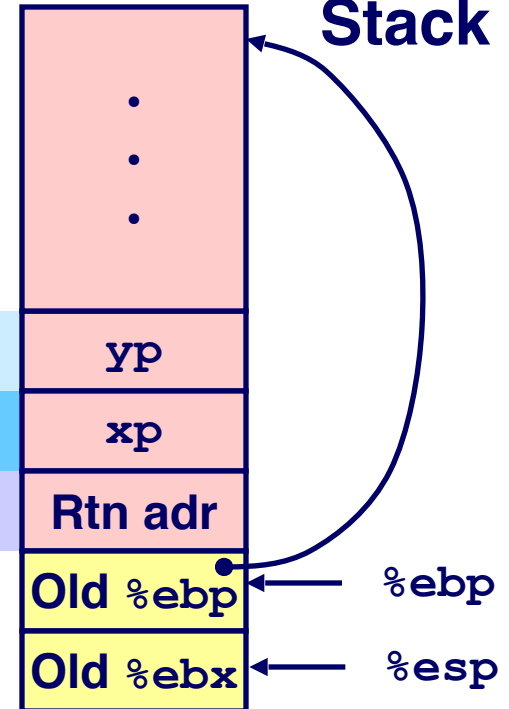
12

8

4

0

## Resulting Stack

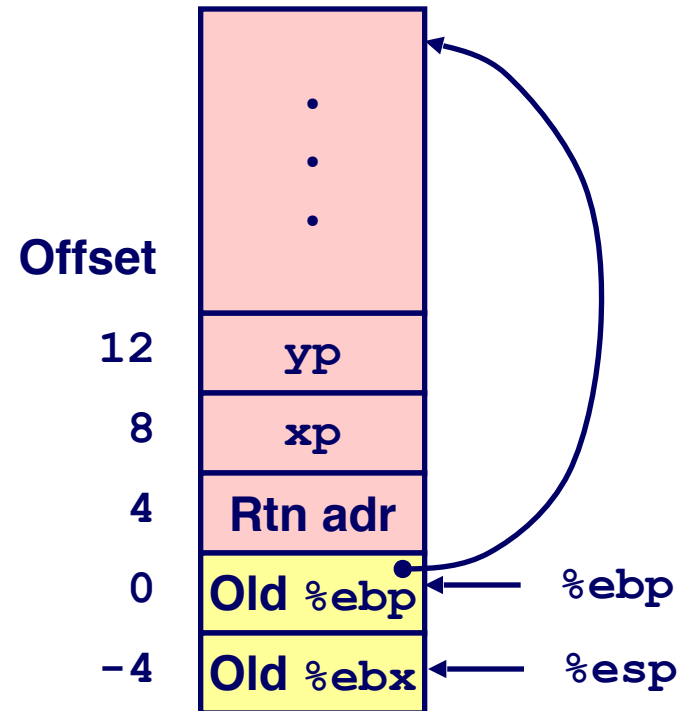
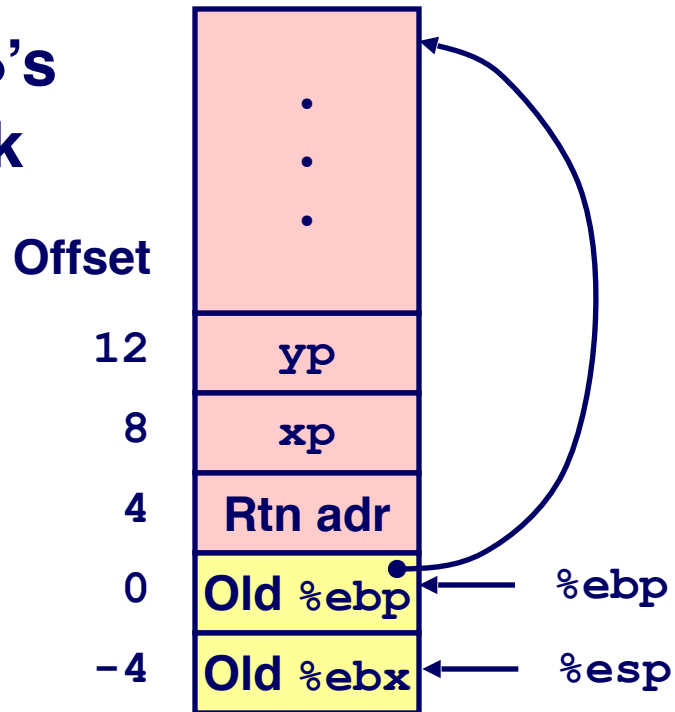


```
movl 12(%ebp),%ecx # get yp
movl 8(%ebp),%edx  # get xp
. . .
```

} Body

# swap Finish #1

swap's  
Stack



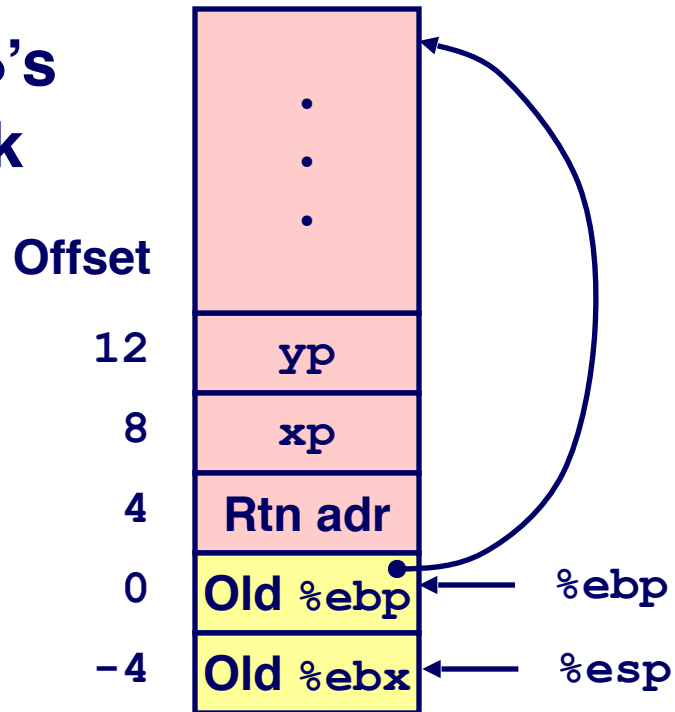
```
movl -4(%ebp), %ebx  
movl %ebp, %esp  
popl %ebp  
ret
```

## Observation

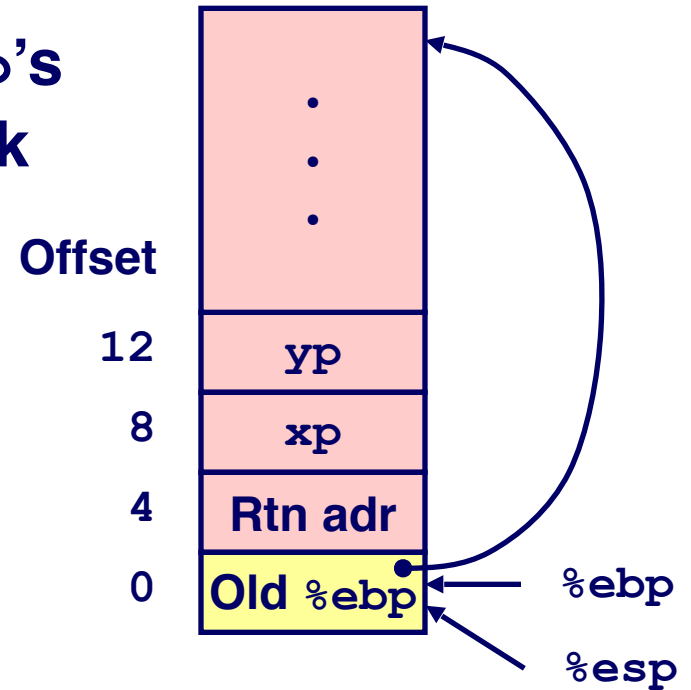
- Saved & restored register %ebx

# swap Finish #2

swap's  
Stack



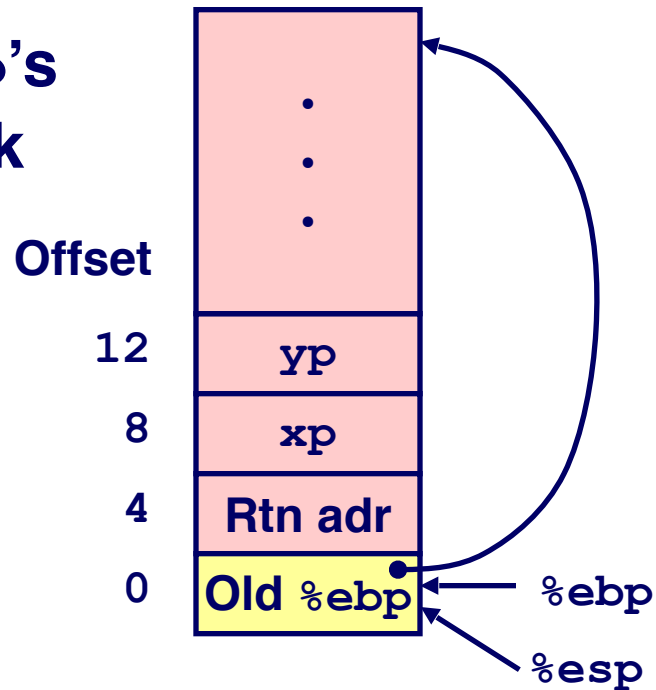
swap's  
Stack



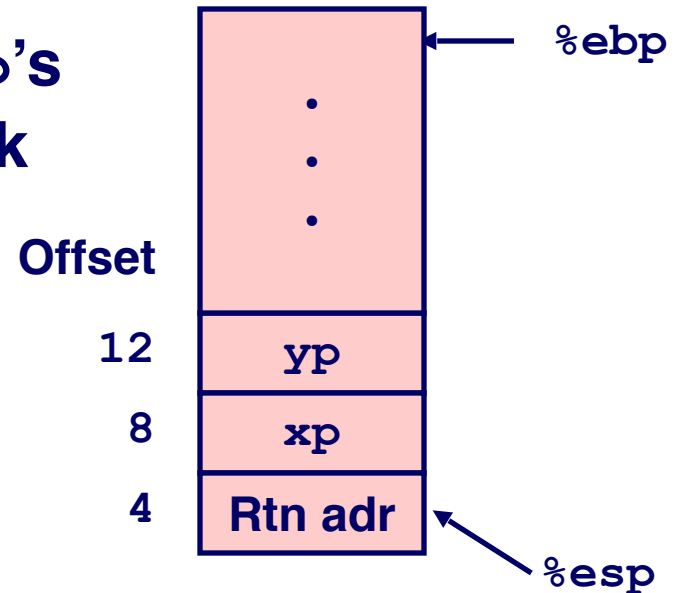
```
movl -4(%ebp), %ebx  
movl %ebp, %esp  
popl %ebp  
ret
```

# swap Finish #3

swap's  
Stack



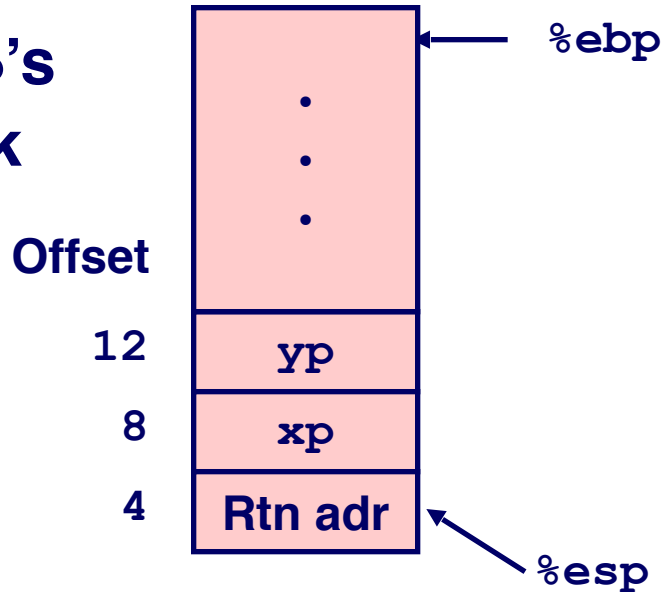
swap's  
Stack



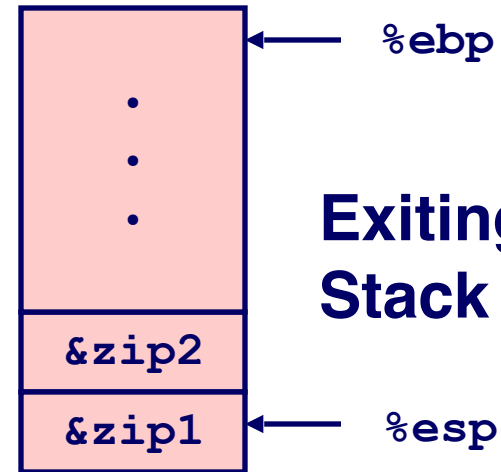
```
movl -4(%ebp), %ebx  
movl %ebp, %esp  
popl %ebp  
ret
```

# swap Finish #4

swap's  
Stack



Exiting  
Stack



## Observation

- Saved & restored register %ebx
- Didn't do so for %eax, %ecx, or %edx

```
movl -4(%ebp), %ebx
movl %ebp, %esp
popl %ebp
ret
```



# Register Saving Conventions

When procedure `yoo` calls `who`:

- `yoo` is the *caller*, `who` is the *callee*

Can Register be Used for Temporary Storage?

```
yoo:
    . . .
    movl $15213, %edx
    call who
    addl %edx, %eax
    . . .
    ret
```

```
who:
    . . .
    movl 8(%ebp), %edx
    addl $91125, %edx
    . . .
    ret
```

- Contents of register `%edx` overwritten by `who`

# Register Saving Conventions

When procedure `yoo` calls `who`:

- `yoo` is the *caller*, `who` is the *callee*

Can Register be Used for Temporary Storage?

Conventions

- “Caller Save”
  - Caller saves temporary in its frame before calling
- “Callee Save”
  - Callee saves temporary in its frame before using

# IA32/Linux Register Usage

Two have special uses

- `%ebp`, `%esp`

Three managed as callee-save

- `%ebx`, `%esi`, `%edi`
- Old values saved on stack prior to using

Three managed as caller-save

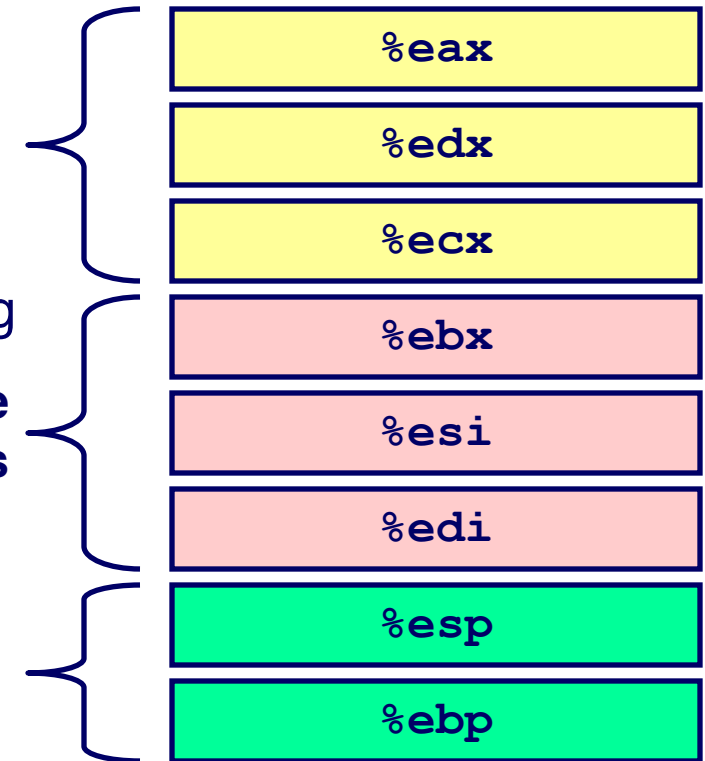
- `%eax`, `%edx`, `%ecx`
- Do what you please, but expect any callee to do so, as well

Register `%eax` also stores returned value

**Caller-Save  
Temporaries**

**Callee-Save  
Temporaries**

**Special**



# Recursive Function

```
.globl rfact
.type
rfact,@function
rfact:
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
    movl 8(%ebp),%ebx
    cmpl $1,%ebx
    jle .L78
    leal -1(%ebx),%eax
    pushl %eax
    call rfact
    imull %ebx,%eax
    jmp .L79
    .align 4
.L78:
    movl $1,%eax
.L79:
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

# Recursive Factorial

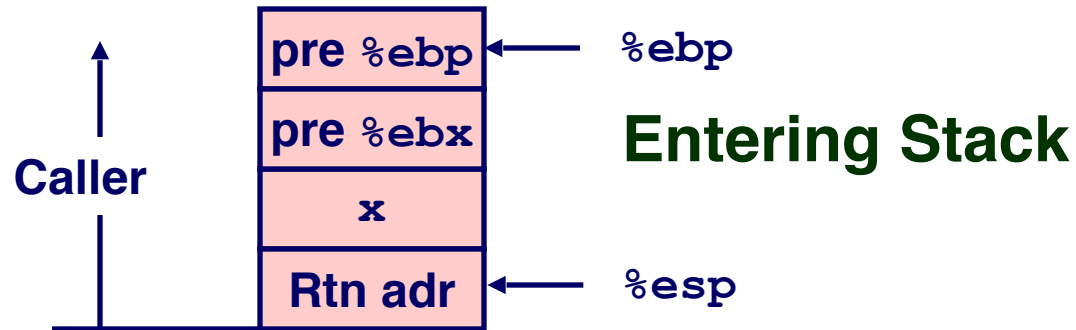
```
int rfact(int x)
{
    int rval;
    if (x <= 1)
        return 1;
    rval = rfact(x-1);
    return rval * x;
}
```

## Registers

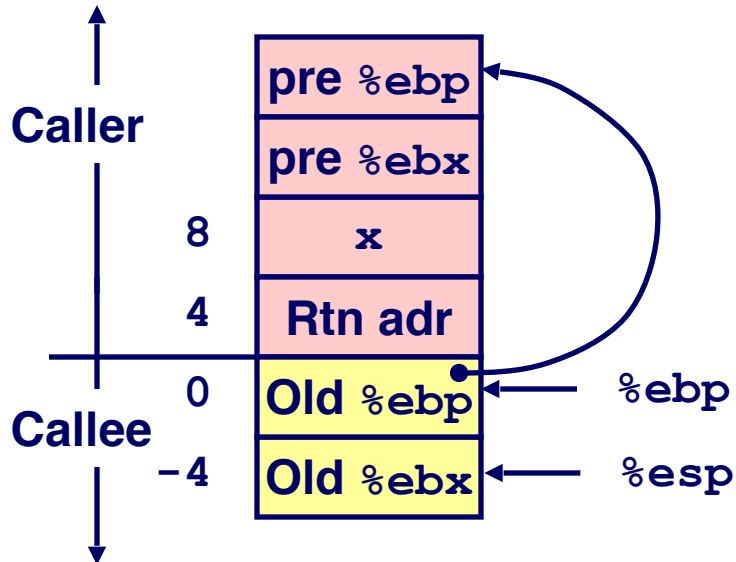
- `%eax` used without first saving
- `%ebx` used, but save at beginning & restore at end

```
.globl rfact
.type
rfact,@function
rfact:
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
    movl 8(%ebp),%ebx
    cmpl $1,%ebx
    jle .L78
    leal -1(%ebx),%eax
    pushl %eax
    call rfact
    imull %ebx,%eax
    jmp .L79
    .align 4
.L78:
    movl $1,%eax
.L79:
    movl -4(%ebp),%ebx
    movl %ebp,%esp
    popl %ebp
    ret
```

# Rfact Stack Setup

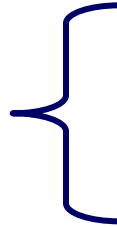


```
rfact:
    pushl %ebp
    movl %esp,%ebp
    pushl %ebx
```



# Rfact Body

Recursion



```
movl 8(%ebp),%ebx    # ebx = x
cmpl $1,%ebx         # Compare x : 1
jle .L78             # If <= goto Term
leal -1(%ebx),%eax   # eax = x-1
pushl %eax           # Push x-1
call rfact           # rfact(x-1)
imull %ebx,%eax      # rval * x
jmp .L79             # Goto done
.L78:                # Term:
    movl $1,%eax      # return val = 1
.L79:                # Done:
```

```
int rfact(int x)
{
    int rval;
    if (x <= 1)
        return 1;
    rval = rfact(x-1) ;
    return rval * x;
}
```

## Registers

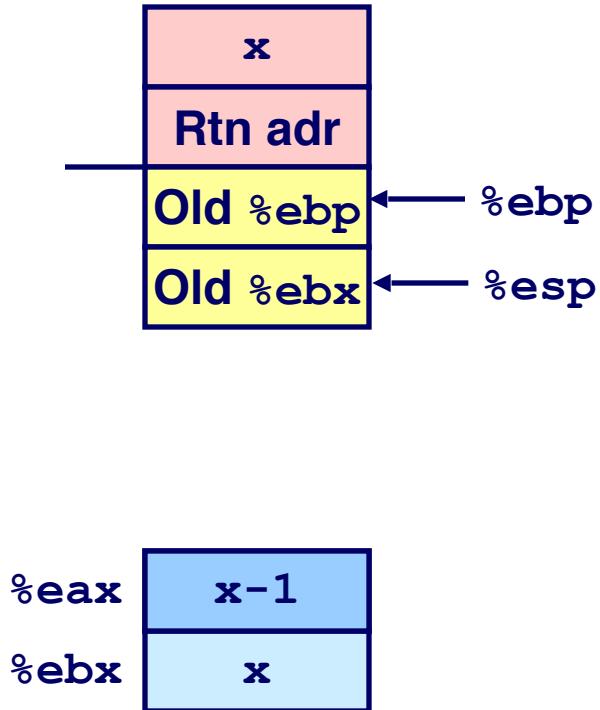
%ebx Stored value of x

%eax

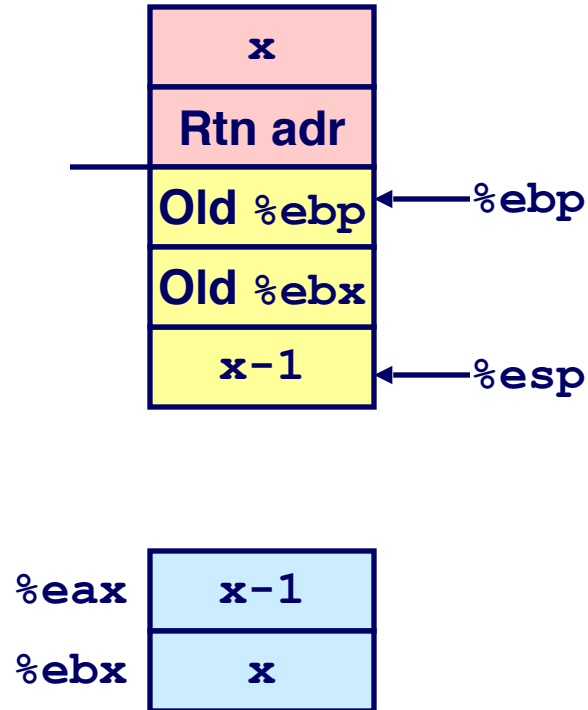
- Temporary value of  $x-1$
- Returned value from `rfact(x-1)`
- Returned value from this call

# Rfact Recursion

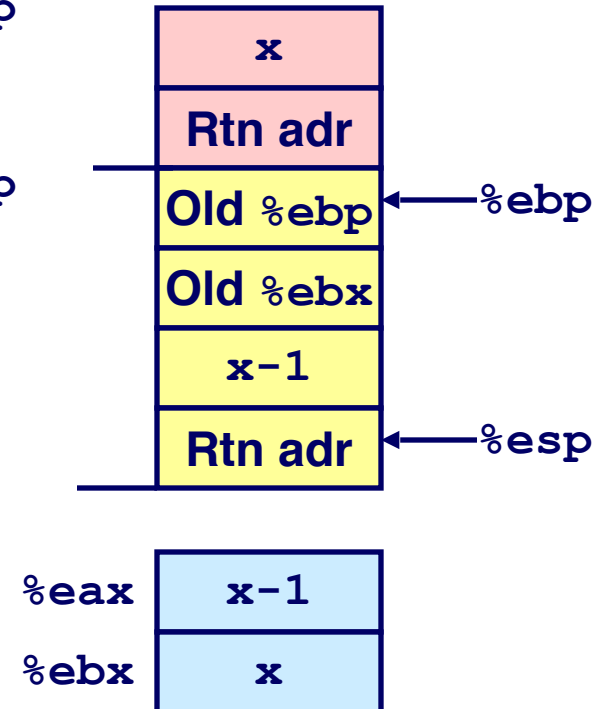
```
leal -1(%ebx), %eax
```



```
pushl %eax
```



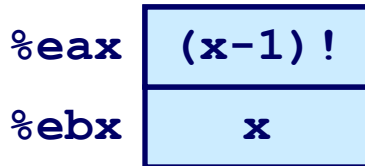
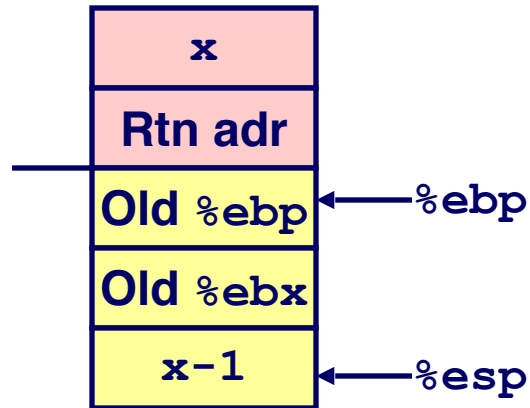
```
call rfact
```





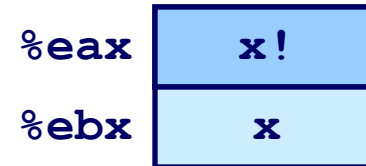
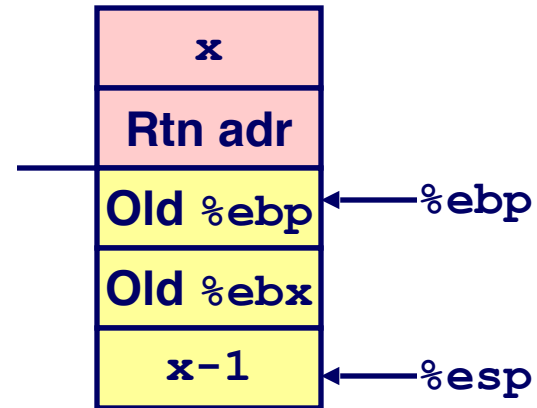
# Rfact Result

Return from Call



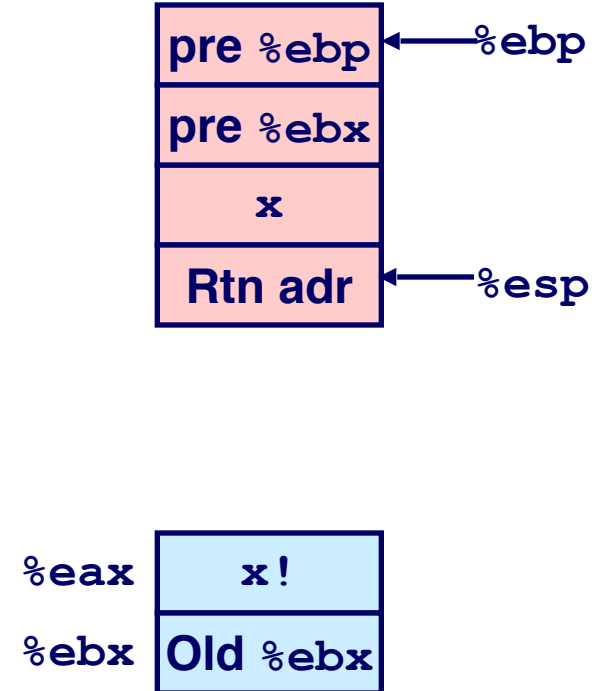
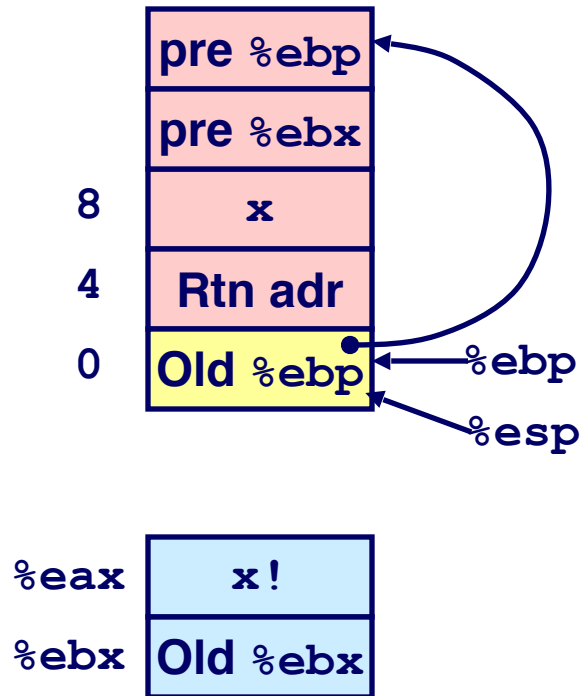
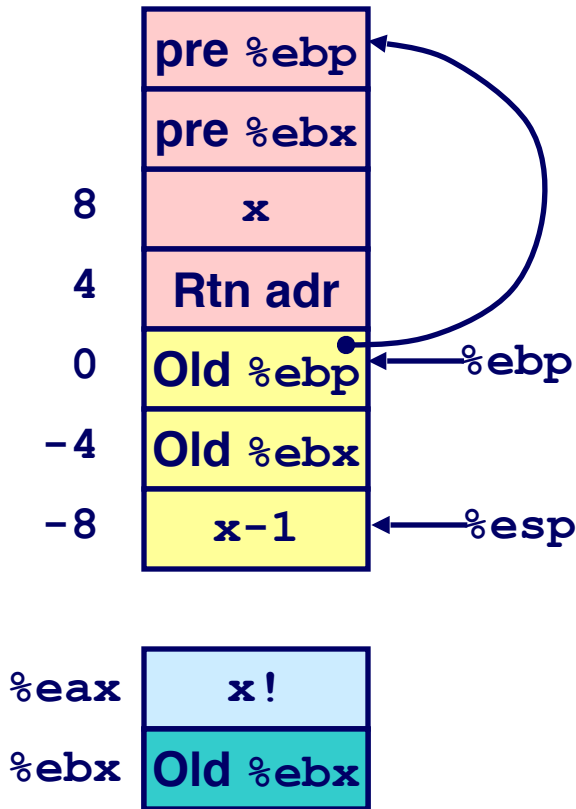
Assume that `rfact(x-1)` returns `(x-1) !` in register `%eax`

`imull %ebx,%eax`



# Rfact Completion

```
movl -4(%ebp), %ebx
movl %ebp, %esp
popl %ebp
ret
```



# Basic Data Types

## Integral

- Stored & operated on in general registers
- Signed vs. unsigned depends on instructions used

Intel	GAS	Bytes	C
byte	b	1	[unsigned] char
word	w	2	[unsigned] short
double word	l	4	[unsigned] int

## Floating Point

- Stored & operated on in floating point registers

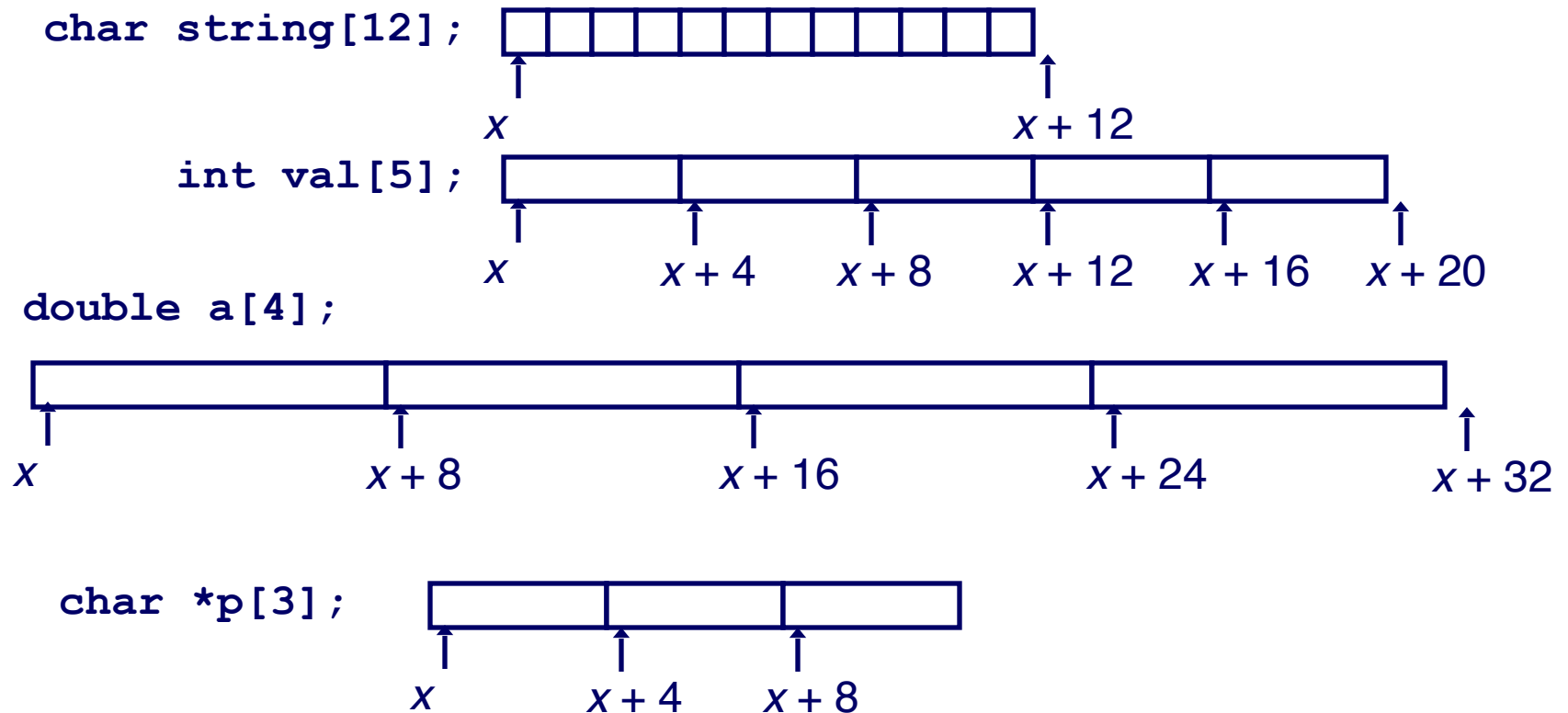
Intel	GAS	Bytes	C
Single	s	4	float
Double	l	8	double
Extended	t	10/12	long double

# Array Allocation

## Basic Principle

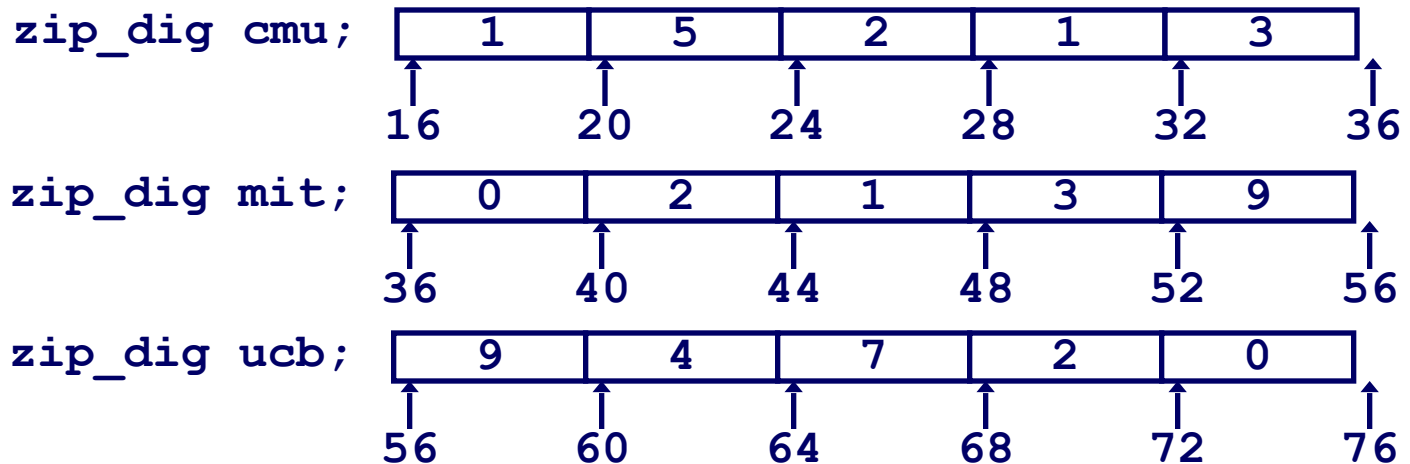
$T \ A[L];$

- Array of data type  $T$  and length  $L$
- Contiguously allocated region of  $L * \text{sizeof}(T)$  bytes



# Array Example

```
typedef int zip_dig[5];  
  
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```



## Notes

- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in successive 20 byte blocks
  - Not guaranteed to happen in general

# Array Accessing Example

## Computation

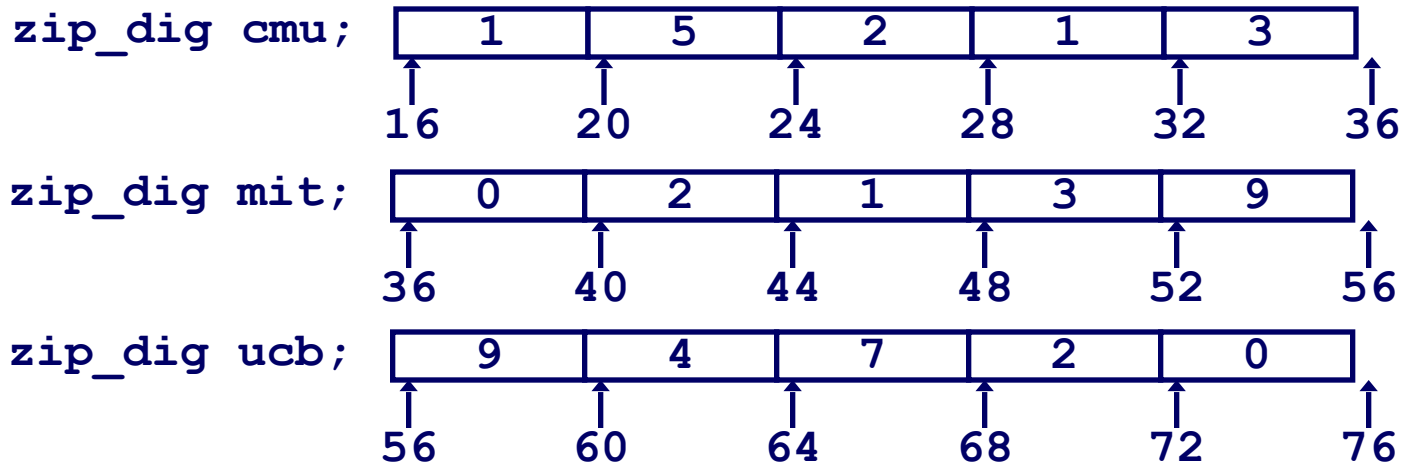
- Register `%edx` contains starting address of array
- Register `%eax` contains array index
- Desired digit at  $4 * \%eax + \%edx$
- Use memory reference (`%edx, %eax, 4`)

```
int get_digit  
    (zip_dig z, int dig)  
{  
    return z[dig];  
}
```

## Memory Reference Code

```
# %edx = z  
# %eax = dig  
movl (%edx,%eax,4),%eax # z[dig]
```

# Referencing Examples



Code Does Not Do Any Bounds Checking!

Reference	Address	Value	Guaranteed?
<code>mit[3]</code>	$36 + 4 * 3 = 48$	3	Yes
<code>mit[5]</code>	$36 + 4 * 5 = 56$	9	No
<code>mit[-1]</code>	$36 + 4 * -1 = 32$	3	No
<code>cmu[15]</code>	$16 + 4 * 15 = 76$	??	No

- Out of range behavior implementation-dependent
  - No guaranteed relative allocation of different arrays

# Array Loop Example

## Original Source

```
int zd2int(zip_dig z)
{
    int i;
    int zi = 0;
    for (i = 0; i < 5; i++) {
        zi = 10 * zi + z[i];
    }
    return zi;
}
```

## Transformed Version

- As generated by GCC
- Eliminate loop variable *i*
- Convert array code to pointer code
- Express in do-while form
  - No need to test at entrance

```
int zd2int(zip_dig z)
{
    int zi = 0;
    int *zend = z + 4;
    do {
        zi = 10 * zi + *z;
        z++;
    } while(z <= zend);
    return zi;
}
```



# Array Loop Implementation

## Registers

%ecx    z  
%eax    zi  
%ebx    zend

## Computations

- $10 * zi + *z$  implemented as  $*z + 2 * (zi + 4 * zi)$
- $z++$  increments by 4

```
int zd2int(zip_dig z)
{
    int zi = 0;
    int *zend = z + 4;
    do {
        zi = 10 * zi + *z;
        z++;
    } while(z <= zend);
    return zi;
}
```

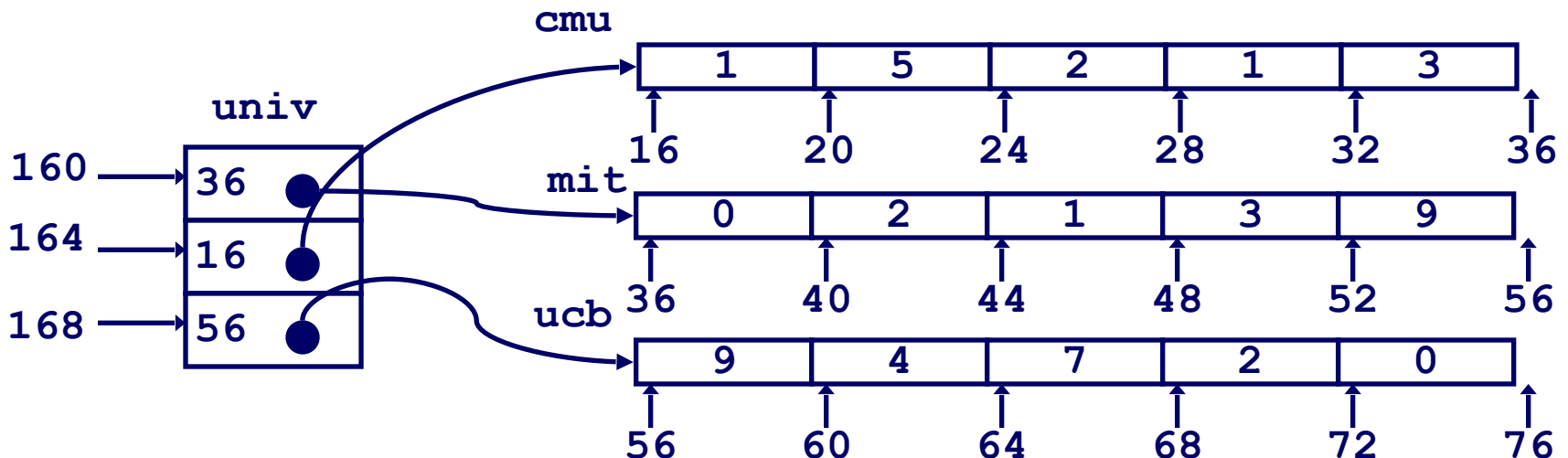
```
# %ecx = z
xorl %eax,%eax           # zi = 0
leal 16(%ecx),%ebx        # zend = z+4
.L59:
leal (%eax,%eax,4),%edx   # 5*zi
movl (%ecx),%eax          # *z
addl $4,%ecx              # z++
leal (%eax,%edx,2),%eax   # zi = *z + 2*(5*zi)
cmpl %ebx,%ecx           # z : zend
jle .L59                 # if <= goto loop
```

# Multi-Level Array Example

- Variable `univ` denotes array of 3 elements
- Each element is a pointer
  - 4 bytes
- Each pointer points to array of `int`'s

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, ucb};
```



# Element Access in Multi-Level Array

```
int get_univ_digit
(int index, int dig)
{
    return univ[index][dig];
}
```

## Computation

- Element access

$\text{Mem}[\text{Mem}[\text{univ} + 4 * \text{index}] + 4 * \text{dig}]$

- Must do two memory reads

- First get pointer to row array
- Then access element within array

```
# %ecx = index
# %eax = dig
leal 0(,%ecx,4),%edx      # 4*index
movl univ(%edx),%edx      # Mem[univ+4*index]
movl (%edx,%eax,4),%eax   # Mem[...+4*dig]
```

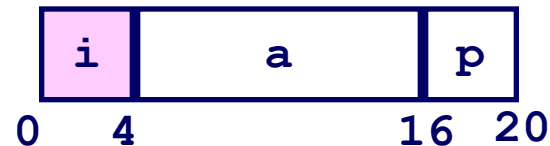
# Structures

## Concept

- Contiguously-allocated region of memory
- Refer to members within structure by names
- Members may be of different types

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```

## Memory Layout



## Accessing Structure Member

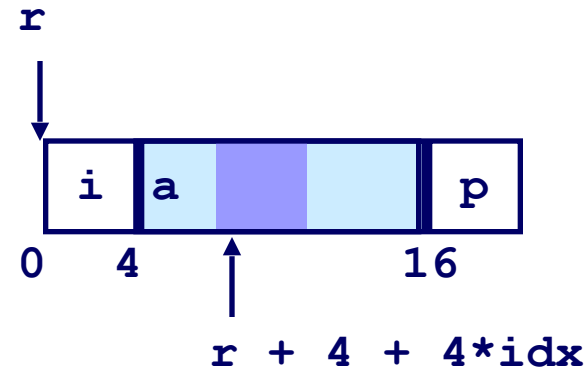
```
void  
set_i(struct rec *r,  
      int val)  
{  
    r->i = val;  
}
```

## Assembly

```
# %eax = val  
# %edx = r  
movl %eax, (%edx)    # Mem[r] = val
```

# Generating Pointer to Struct. Member

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```



## Generating Pointer to Array Element

- Offset of each structure member determined at compile time

```
int *  
find_a  
(struct rec *r, int idx)  
{  
    return &r->a[idx];  
}
```

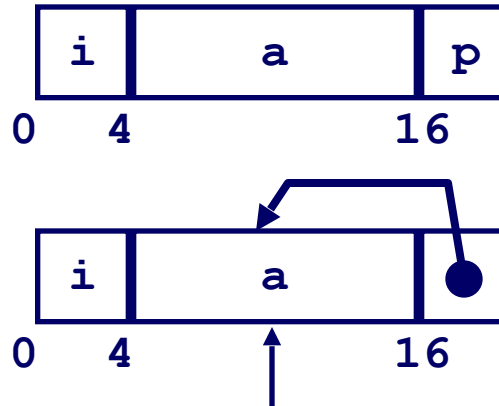
```
# %ecx = idx  
# %edx = r  
leal 0(,%ecx,4),%eax # 4*idx  
leal 4(%eax,%edx),%eax # r+4*idx+4
```

# Structure Referencing (Cont.)

## C Code

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```

```
void  
set_p(struct rec *r)  
{  
    r->p =  
        &r->a[r->i];  
}
```



Element i

```
# %edx = r  
movl (%edx), %ecx          # r->i  
leal 0(, %ecx, 4), %eax     # 4*(r->i)  
leal 4(%edx, %eax), %eax    # r+4+4*(r->i)  
movl %eax, 16(%edx)        # Update r->p
```

# Alignment

## Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K
- Required on some machines; advised on IA32
  - treated differently by Linux and Windows!

## Motivation for Aligning Data

- Memory accessed by (aligned) double or quad-words
  - Inefficient to load or store datum that spans quad word boundaries

## Compiler

- Inserts gaps in structure to ensure correct alignment of fields

# Specific Cases of Alignment

## Size of Primitive Data Type:

- 1 byte (e.g., `char`)
  - no restrictions on address
- 2 bytes (e.g., `short`)
  - lowest 1 bit of address must be  $0_2$
- 4 bytes (e.g., `int`, `float`, `char *`, etc.)
  - lowest 2 bits of address must be  $00_2$
- 8 bytes (e.g., `double`)
  - Windows (and most other OS's & instruction sets):
    - » lowest 3 bits of address must be  $000_2$
  - Linux:
    - » lowest 2 bits of address must be  $00_2$
    - » i.e., treated the same as a 4-byte primitive data type
- 12 bytes (`long double`)
  - Linux:
    - » lowest 2 bits of address must be  $00_2$
    - » i.e., treated the same as a 4-byte primitive data type



# Satisfying Alignment with Structures

## Offsets Within Structure

- Must satisfy element's alignment requirement

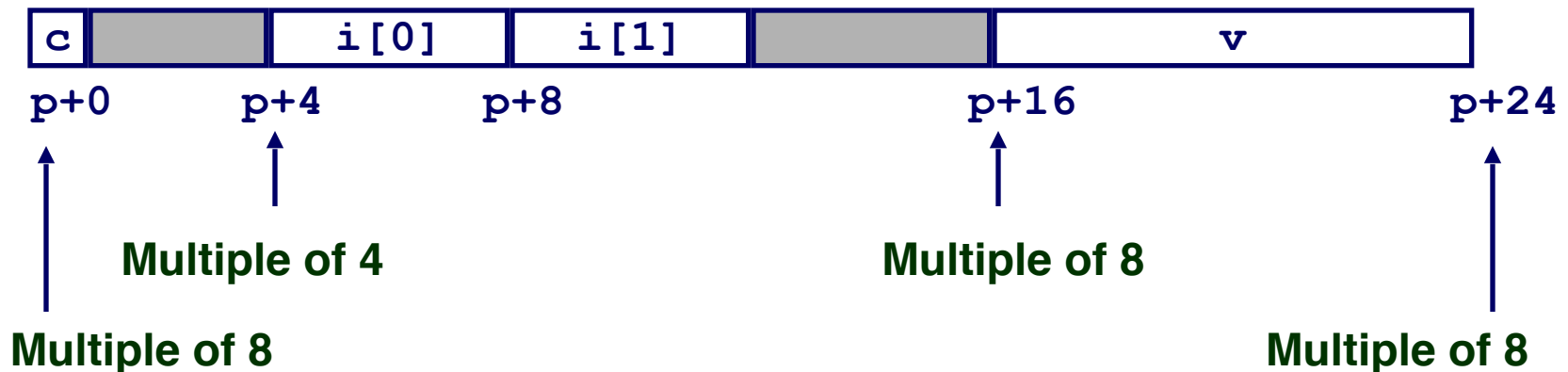
## Overall Structure Placement

- Each structure has alignment requirement K
  - Largest alignment of any element
- Initial address & structure length must be multiples of K

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

## Example (under Windows):

- $K = 8$ , due to `double` element

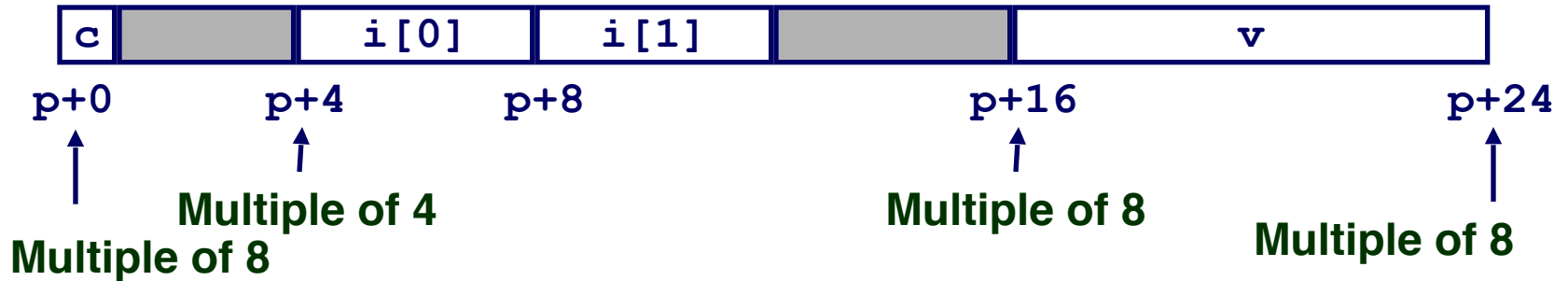


# Linux vs. Windows

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

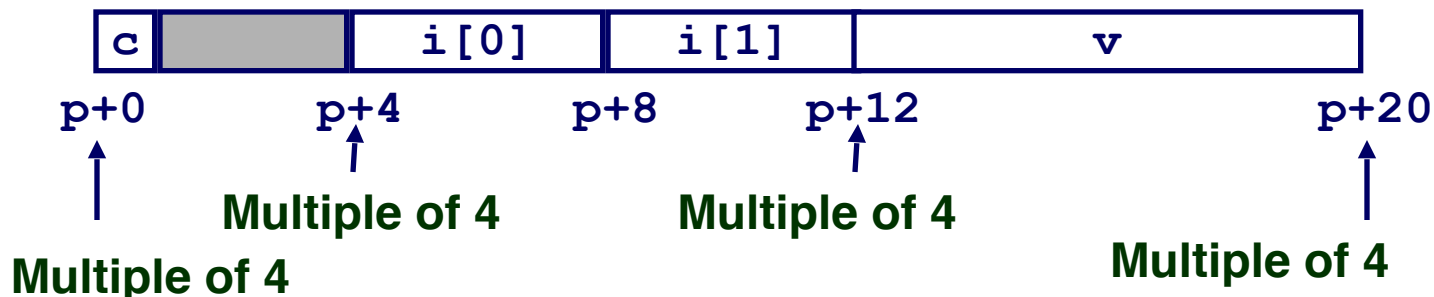
Windows (including Cygwin):

- $K = 8$ , due to `double` element



Linux:

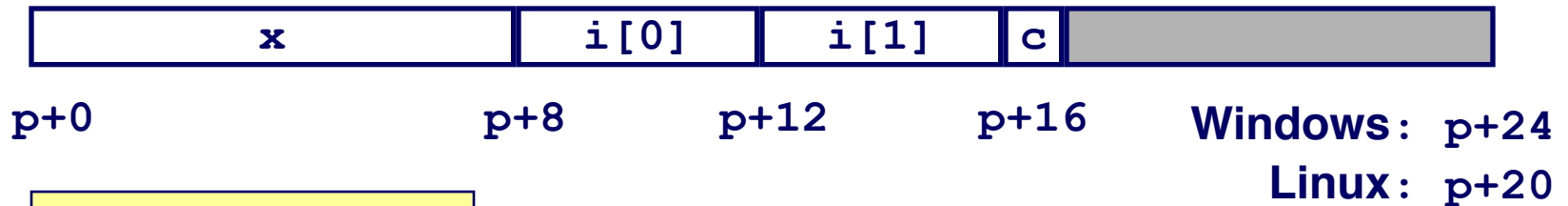
- $K = 4$ ; `double` treated like a 4-byte data type



# Overall Alignment Requirement

```
struct S2 {  
    double x;  
    int i[2];  
    char c;  
} *p;
```

**p must be multiple of:**  
**8 for Windows**  
**4 for Linux**



```
struct S3 {  
    float x[2];  
    int i[2];  
    char c;  
} *p;
```

**p must be multiple of 4 (in either OS)**



# Ordering Elements Within Structure

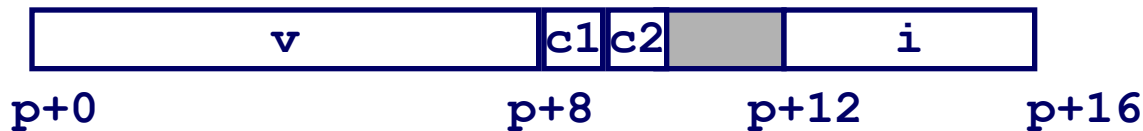
```
struct S4 {  
    char c1;  
    double v;  
    char c2;  
    int i;  
} *p;
```

10 bytes wasted space in Windows



```
struct S5 {  
    double v;  
    char c1;  
    char c2;  
    int i;  
} *p;
```

2 bytes wasted space

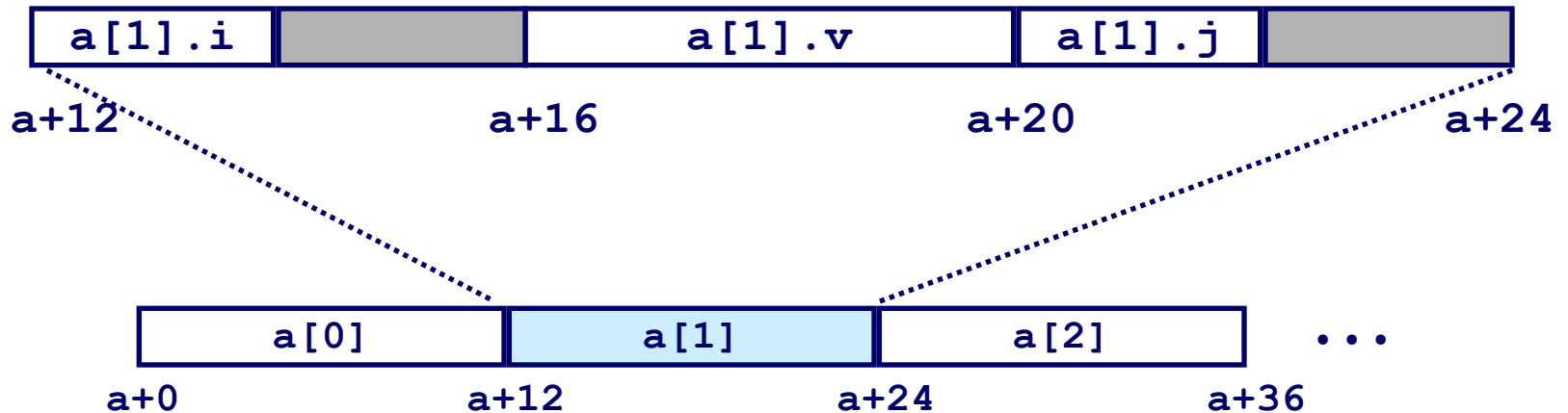


# Arrays of Structures

## Principle

- Allocated by repeating allocation for array type
- In general, may nest arrays & structures to arbitrary depth

```
struct S6 {  
    short i;  
    float v;  
    short j;  
} a[10];
```

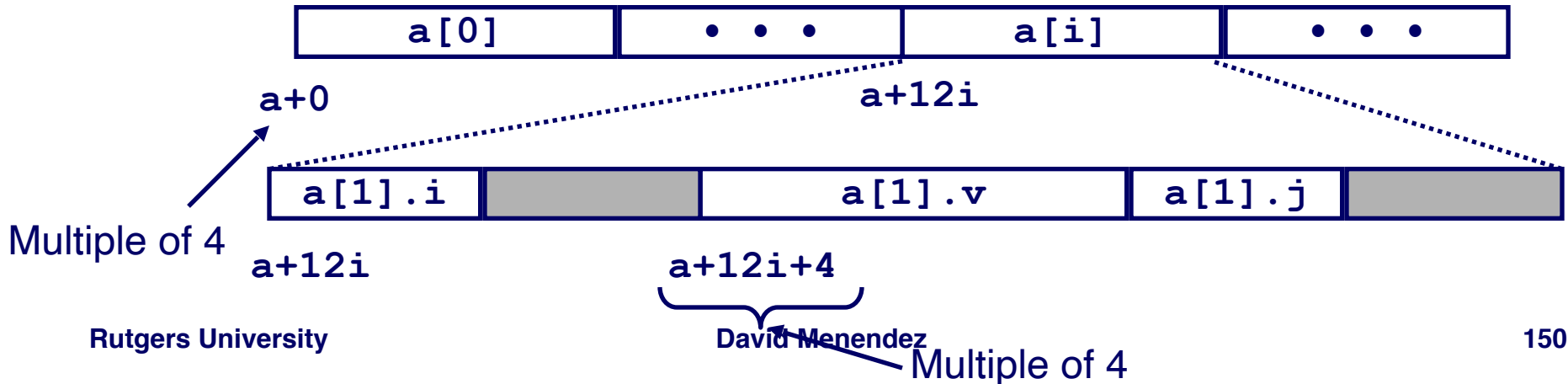


# Satisfying Alignment within Structure

## Achieving Alignment

- Starting address of structure array must be multiple of worst-case alignment for any element
  - $a$  must be multiple of 4
- Offset of element within structure must be multiple of element's alignment requirement
  - $v$ 's offset of 4 is a multiple of 4
- Overall size of structure must be multiple of worst-case alignment for any element
  - Structure padded with unused space to be 12 bytes

```
struct S6 {  
    short i;  
    float v;  
    short j;  
} a[10];
```



# Summary

## Arrays in C

- Contiguous allocation of memory
- Pointer to first element
- No bounds checking

## Compiler Optimizations

- Compiler often turns array code into pointer code (`zd2int`)
- Uses addressing modes to scale array indices
- Lots of tricks to improve array indexing in loops

## Structures

- Allocate bytes in order declared
- Pad in middle and at end to satisfy alignment