Deep Generative Models

Lecture 3

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2025, Autumn

Jacobian Matrix

Let $\mathbf{f}: \mathbb{R}^m \to \mathbb{R}^m$ be a differentiable function.

$$\mathbf{z} = \mathbf{f}(\mathbf{x}), \quad \mathbf{J} = \frac{\partial \mathbf{z}}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial z_1}{\partial x_1} & \cdots & \frac{\partial z_1}{\partial x_m} \\ \vdots & \ddots & \vdots \\ \frac{\partial z_m}{\partial x_1} & \cdots & \frac{\partial z_m}{\partial x_m} \end{pmatrix} \in \mathbb{R}^{m \times m}$$

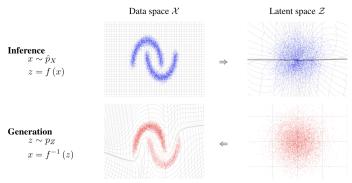
Change of Variables Theorem (CoV)

Let $\mathbf{x} \in \mathbb{R}^m$ be a random vector with density $p(\mathbf{x})$, and let $\mathbf{f} : \mathbb{R}^m \to \mathbb{R}^m$ be a C^1 -diffeomorphism (\mathbf{f} and \mathbf{f}^{-1} are continuously differentiable mappings). If $\mathbf{z} = \mathbf{f}(\mathbf{x})$, then

$$p(\mathbf{x}) = p(\mathbf{z})|\det(\mathbf{J}_{\mathbf{f}})| = p(\mathbf{z})\left|\det\left(\frac{\partial \mathbf{z}}{\partial \mathbf{x}}\right)\right| = p(\mathbf{f}(\mathbf{x}))\left|\det\left(\frac{\partial \mathbf{f}(\mathbf{x})}{\partial \mathbf{x}}\right)\right|$$
$$p(\mathbf{z}) = p(\mathbf{x})|\det(\mathbf{J}_{\mathbf{f}^{-1}})| = p(\mathbf{x})\left|\det\left(\frac{\partial \mathbf{x}}{\partial \mathbf{z}}\right)\right| = p(\mathbf{f}^{-1}(\mathbf{z}))\left|\det\left(\frac{\partial \mathbf{f}^{-1}(\mathbf{z})}{\partial \mathbf{z}}\right)\right|$$

Definition

A normalizing flow is a C^1 -diffeomorphism that transforms data \mathbf{x} to noise \mathbf{z} .



Log-Likelihood

$$\log p_{\boldsymbol{\theta}}(\mathbf{x}) = \log p(\mathbf{f}_{\mathcal{K}} \circ \cdots \circ \mathbf{f}_{1}(\mathbf{x})) + \sum_{k=1}^{\mathcal{K}} \log |\det(\mathbf{J}_{\mathbf{f}_{k}})|$$

Flow Log-Likelihood

$$\log p_{\theta}(\mathbf{x}) = \log p(\mathbf{f}_{\theta}(\mathbf{x})) + \log |\det(\mathbf{J}_{\mathbf{f}})|$$

One significant challenge is efficiently computing the Jacobian determinant.

Linear Flows

$$z = f_{\theta}(x) = Wx$$
, $W \in \mathbb{R}^{m \times m}$, $\theta = W$, $J_f = W^T$

LU Decomposition:

$$W = PLU$$
.

▶ QR Decomposition:

$$W = QR$$
.

Decomposition is performed only once during initialization. Then the decomposed matrices (P, L, U or Q, R) are optimized.

Consider an autoregressive model:

$$p_{\theta}(\mathbf{x}) = \prod_{j=1}^{m} p_{\theta}(x_{j}|\mathbf{x}_{1:j-1}), \quad p_{\theta}(x_{j}|\mathbf{x}_{1:j-1}) = \mathcal{N}\left(\mu_{j,\theta}(\mathbf{x}_{1:j-1}), \sigma_{j,\theta}^{2}(\mathbf{x}_{1:j-1})\right).$$

Gaussian Autoregressive Normalizing Flow

$$\mathbf{x} = \mathbf{f}_{\theta}^{-1}(\mathbf{z}) \quad \Rightarrow \quad x_j = \sigma_{j,\theta}(\mathbf{x}_{1:j-1}) \cdot z_j + \mu_{j,\theta}(\mathbf{x}_{1:j-1}).$$

$$\mathbf{z} = \mathbf{f}_{\theta}(\mathbf{x}) \quad \Rightarrow \quad z_j = (x_j - \mu_{j,\theta}(\mathbf{x}_{1:j-1})) \cdot \frac{1}{\sigma_{j,\theta}(\mathbf{x}_{1:j-1})}.$$

- ► This transformation is both C^1 -diffeomorphism, mapping $p(\mathbf{z})$ to $p_{\theta}(\mathbf{x})$.
- ▶ The Jacobian matrix for this transformation is triangular.

The generative function $\mathbf{f}_{\theta}^{-1}(\mathbf{z})$ is **sequential**, while the inference function $\mathbf{f}_{\theta}(\mathbf{x})$ is **not sequential**.

Papamakarios G., Pavlakou T., Murray I. Masked Autoregressive Flow for Density Estimation, 2017

Let us partition **x** and **z** into two groups:

$$\mathbf{x} = [\mathbf{x}_1, \mathbf{x}_2] = [\mathbf{x}_{1:d}, \mathbf{x}_{d+1:m}]; \quad \mathbf{z} = [\mathbf{z}_1, \mathbf{z}_2] = [\mathbf{z}_{1:d}, \mathbf{z}_{d+1:m}].$$

Coupling Layer

$$\begin{cases} \mathbf{x}_1 = \mathbf{z}_1; \\ \mathbf{x}_2 = \mathbf{z}_2 \odot \boldsymbol{\sigma}_{\boldsymbol{\theta}}(\mathbf{z}_1) + \boldsymbol{\mu}_{\boldsymbol{\theta}}(\mathbf{z}_1). \end{cases} \begin{cases} \mathbf{z}_1 = \mathbf{x}_1; \\ \mathbf{z}_2 = (\mathbf{x}_2 - \boldsymbol{\mu}_{\boldsymbol{\theta}}(\mathbf{x}_1)) \odot \frac{1}{\boldsymbol{\sigma}_{\boldsymbol{\theta}}(\mathbf{x}_1)}. \end{cases}$$

Both density estimation and sampling require just a single pass!

Jacobian

$$\det\left(\frac{\partial \mathbf{z}}{\partial \mathbf{x}}\right) = \det\left(\frac{\mathbf{I}_d}{\frac{\partial \mathbf{z}_2}{\partial \mathbf{x}_1}} \quad \frac{0_{d \times (m-d)}}{\frac{\partial \mathbf{z}_2}{\partial \mathbf{x}_2}}\right) = \prod_{i=1}^{m-d} \frac{1}{\sigma_{j,\theta}(\mathbf{x}_1)}.$$

A coupling layer is a special instance of an gaussian autoregressive normalizing flow.

Posterior Distribution (Bayes' Theorem)

$$p(\theta|\mathbf{x}) = \frac{p(\mathbf{x}|\theta)p(\theta)}{p(\mathbf{x})} = \frac{p(\mathbf{x}|\theta)p(\theta)}{\int p(\mathbf{x}|\theta)p(\theta)d\theta}$$

- x observed variables;
- \bullet unobserved variables (latent parameters);
- $p_{\theta}(\mathbf{x}) = p(\mathbf{x}|\theta)$ likelihood;
- $p(\mathbf{x}) = \int p(\mathbf{x}|\theta)p(\theta)d\theta$ evidence;
- \triangleright $p(\theta)$ prior distribution;
- $ightharpoonup p(\theta|\mathbf{x})$ posterior distribution.

Outline

- 1. Latent Variable Models (LVM) (continued)
- 2. Variational Evidence Lower Bound (ELBO)
- 3. Amortized Inference
- 4. ELBO Gradients, Reparametrization Trick
- 5. Variational Autoencoder (VAE)

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Maximum Likelihood Extimation (MLE) Problem

$$m{ heta}^* = rg \max_{m{ heta}} p_{m{ heta}}(\mathbf{X}) = rg \max_{m{ heta}} \prod_{i=1}^n p_{m{ heta}}(\mathbf{x}_i) = rg \max_{m{ heta}} \sum_{i=1}^n \log p_{m{ heta}}(\mathbf{x}_i).$$

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The distribution $p_{\theta}(\mathbf{x})$ can be highly complex and often intractable (just like the true data distribution $p_{\text{data}}(\mathbf{x})$).

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Extended Probabilistic Model

Introduce a latent variable z for each observed sample x:

$$p_{\theta}(\mathbf{x}, \mathbf{z}) = p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z}); \quad \log p_{\theta}(\mathbf{x}, \mathbf{z}) = \log p_{\theta}(\mathbf{x}|\mathbf{z}) + \log p(\mathbf{z}).$$

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Motivation

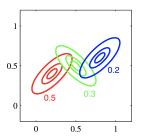
Both $p_{\theta}(\mathbf{x}|\mathbf{z})$ and $p(\mathbf{z})$ are usually much simpler than $p_{\theta}(\mathbf{x})$.

$$\log p_{m{ heta}}(\mathbf{x}) = \log \int p_{m{ heta}}(\mathbf{x}|\mathbf{z})p(\mathbf{z})d\mathbf{z}
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Examples

Mixture of Gaussians

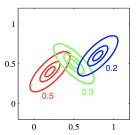


- $hophi p_{\theta}(\mathbf{x}|z) = \mathcal{N}(\mu_z, \mathbf{\Sigma}_z)$
- $ightharpoonup p(z) = \operatorname{Categorical}(\pi)$

$$\log p_{m{ heta}}(\mathbf{x}) = \log \int p_{m{ heta}}(\mathbf{x}|\mathbf{z})p(\mathbf{z})d\mathbf{z}
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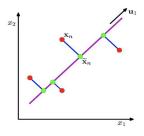
Examples

Mixture of Gaussians



- \triangleright $p(z) = \text{Categorical}(\pi)$

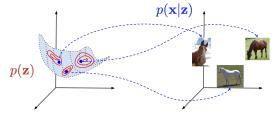
PCA Model



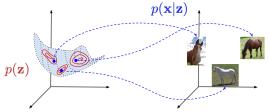
- $ho_{\theta}(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{W}\mathbf{z} + \boldsymbol{\mu}, \sigma^2 \mathbf{I})$
- $p(z) = \mathcal{N}(0, I)$

$$\sum_{i=1}^n \log p_{\boldsymbol{\theta}}(\mathbf{x}_i) = \sum_{i=1}^n \log \int p_{\boldsymbol{\theta}}(\mathbf{x}_i|\mathbf{z}_i) p(\mathbf{z}_i) d\mathbf{z}_i \to \max_{\boldsymbol{\theta}}.$$

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Naive Monte Carlo Estimation

$$\log p_{\boldsymbol{\theta}}(\mathbf{x}) = \log \mathbb{E}_{p(\mathbf{z})} p_{\boldsymbol{\theta}}(\mathbf{x}|\mathbf{z}) \geq \mathbb{E}_{p(\mathbf{z})} \log p_{\boldsymbol{\theta}}(\mathbf{x}|\mathbf{z}) \approx \frac{1}{K} \sum_{k=1}^{K} \log p_{\boldsymbol{\theta}}(\mathbf{x}|\mathbf{z}_k),$$
 where $\mathbf{z}_k \sim p(\mathbf{z})$.

$$\sum_{i=1}^n \log p_{\theta}(\mathbf{x}_i) = \sum_{i=1}^n \log \int p_{\theta}(\mathbf{x}_i|\mathbf{z}_i) p(\mathbf{z}_i) d\mathbf{z}_i \to \max_{\theta}.$$

$$p(\mathbf{z})$$

Naive Monte Carlo Estimation

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 where $\mathbf{z}_k \sim p(\mathbf{z})$.

Challenge: As the dimensionality of **z** increases, the number of samples needed to adequately cover the latent space grows exponentially.

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$$\log p_{\theta}(\mathbf{x}) = \log \int p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} = \log \int \frac{q(\mathbf{z})}{q(\mathbf{z})} p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z}$$

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$$= \log \mathbb{E}_q \left[\frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} \right]$$

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- ▶ Here, q(z) is any distribution such that $\int q(z)dz = 1$.
- ▶ We assume that $supp(q(\mathbf{z})) = supp(p_{\theta}(\mathbf{z}|\mathbf{x})) = \mathbb{R}^d$.

Inequality Derivation

$$\begin{split} \log p_{\theta}(\mathbf{x}) &= \log \int p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} = \log \int \frac{q(\mathbf{z})}{q(\mathbf{z})} p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} = \\ &= \log \mathbb{E}_q \left[\frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} \right] \geq \mathbb{E}_q \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} = \mathcal{L}_{q, \theta}(\mathbf{x}) \end{split}$$

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Variational Evidence Lower Bound (ELBO)

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log rac{p_{oldsymbol{ heta}}(\mathbf{x},\mathbf{z})}{q(\mathbf{z})} \leq \log p_{oldsymbol{ heta}}(\mathbf{x})$$

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$$\mathcal{L}_{q, heta}(\mathsf{x}) = \mathbb{E}_q \log rac{p_{ heta}(\mathsf{x},\mathsf{z})}{q(\mathsf{z})} \leq \log p_{ heta}(\mathsf{x})$$

This inequality holds for any choice of $q(\mathbf{z})$.

$$p_{ heta}(\mathbf{z}|\mathbf{x}) = rac{p_{ heta}(\mathbf{x},\mathbf{z})}{p_{ heta}(\mathbf{x})}$$

$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z}$$

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$$= \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{z}|\mathbf{x})p_{\theta}(\mathbf{x})}{q(\mathbf{z})} d\mathbf{z}$$

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$$= \log p_{\theta}(\mathbf{x}) - \text{KL}(q(\mathbf{z}) || p_{\theta}(\mathbf{z}|\mathbf{x}))$$

$$p_{\theta}(\mathbf{z}|\mathbf{x}) = \frac{p_{\theta}(\mathbf{x},\mathbf{z})}{p_{\theta}(\mathbf{x})}$$

Equality Derivation

$$\begin{split} \mathcal{L}_{q,\theta}(\mathbf{x}) &= \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z} = \\ &= \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{z}|\mathbf{x})p_{\theta}(\mathbf{x})}{q(\mathbf{z})} d\mathbf{z} = \\ &= \int q(\mathbf{z}) \log p_{\theta}(\mathbf{x}) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{z}|\mathbf{x})}{q(\mathbf{z})} d\mathbf{z} = \\ &= \log p_{\theta}(\mathbf{x}) - \mathrm{KL}(q(\mathbf{z}) || p_{\theta}(\mathbf{z}|\mathbf{x})) \end{split}$$

Variational Decomposition

$$\log p_{\theta}(\mathbf{x}) = \mathcal{L}_{q,\theta}(\mathbf{x}) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})) \geq \mathcal{L}_{q,\theta}(\mathbf{x}).$$

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Here, $\mathrm{KL}(q(\mathbf{z})||p_{\theta}(\mathbf{z}|\mathbf{x})) \geq 0$.

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$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z}$$

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Log-Likelihood Decomposition

$$\begin{split} \log p_{\theta}(\mathbf{x}) &= \mathcal{L}_{q,\theta}(\mathbf{x}) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})) = \\ &= \mathbb{E}_{q} \log p_{\theta}(\mathbf{x} | \mathbf{z}) - \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z})) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})). \end{split}$$

$$\begin{split} \mathcal{L}_{q,\theta}(\mathbf{x}) &= \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z} \\ &= \int q(\mathbf{z}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p(\mathbf{z})}{q(\mathbf{z})} d\mathbf{z} \\ &= \mathbb{E}_q \log p_{\theta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q(\mathbf{z})||p(\mathbf{z})) \end{split}$$

Log-Likelihood Decomposition

$$\begin{split} \log p_{\theta}(\mathbf{x}) &= \mathcal{L}_{q,\theta}(\mathbf{x}) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})) = \\ &= \mathbb{E}_{q} \log p_{\theta}(\mathbf{x} | \mathbf{z}) - \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z})) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})). \end{split}$$

▶ Instead of maximizing the likelihood, maximize the ELBO:

$$\max_{m{ heta}} p_{m{ heta}}(\mathbf{x}) \quad o \quad \max_{q,m{ heta}} \mathcal{L}_{q,m{ heta}}(\mathbf{x})$$

$$\begin{split} \mathcal{L}_{q,\theta}(\mathbf{x}) &= \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z} \\ &= \int q(\mathbf{z}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p(\mathbf{z})}{q(\mathbf{z})} d\mathbf{z} \\ &= \mathbb{E}_q \log p_{\theta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q(\mathbf{z}) || p(\mathbf{z})) \end{split}$$

Log-Likelihood Decomposition

$$\log p_{\theta}(\mathbf{x}) = \mathcal{L}_{q,\theta}(\mathbf{x}) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})) =$$

$$= \mathbb{E}_{q} \log p_{\theta}(\mathbf{x} | \mathbf{z}) - \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z})) + \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})).$$

▶ Instead of maximizing the likelihood, maximize the ELBO:

$$\max_{\boldsymbol{\theta}} p_{\boldsymbol{\theta}}(\mathbf{x}) \quad o \quad \max_{\boldsymbol{a}.\boldsymbol{\theta}} \mathcal{L}_{q,\boldsymbol{\theta}}(\mathbf{x})$$

Maximizing the ELBO with respect to the variational distribution q is equivalent to minimizing the KL divergence:

$$rg \max_{q} \mathcal{L}_{q,\theta}(\mathbf{x}) \equiv rg \min_{q} \mathrm{KL}(q(\mathbf{z}) \| p_{\theta}(\mathbf{z} | \mathbf{x})).$$

Variational Posterior

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z}))
ightarrow \max_{q, heta}.$$

What is the optimal distribution $q^*(\mathbf{z})$ given fixed θ^* ?

Variational Posterior

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z}))
ightarrow \max_{q,m{ heta}}.$$

What is the optimal distribution $q^*(z)$ given fixed θ^* ?

$$egin{aligned} q^*(\mathbf{z}) &= rg \max_q \mathcal{L}_{q, m{ heta}^*}(\mathbf{x}) = \ &= rg \min_q \mathrm{KL}(q(\mathbf{z}) \| p_{m{ heta}^*}(\mathbf{z} | \mathbf{x})) = p_{m{ heta}^*}(\mathbf{z} | \mathbf{x}). \end{aligned}$$

Here we got the intuition about $q(\mathbf{z})$ – it estimates the posterior $p_{\theta^*}(\mathbf{z}|\mathbf{x})$.

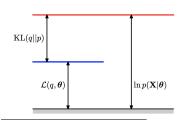
Variational Posterior

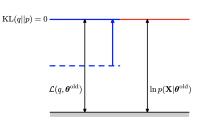
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Here we got the intuition about $q(\mathbf{z})$ – it estimates the posterior $p_{\theta^*}(\mathbf{z}|\mathbf{x})$.





Outline

- 1. Latent Variable Models (LVM) (continued
- 2. Variational Evidence Lower Bound (ELBO)
- 3. Amortized Inference
- 4. ELBO Gradients, Reparametrization Trick
- 5. Variational Autoencoder (VAE)

Variational Posterior

$$q(\mathbf{z}) = rg \max_{q} \mathcal{L}_{q, \boldsymbol{\theta}^*}(\mathbf{x}) = rg \min_{q} \mathrm{KL}(q \| p) = p_{\boldsymbol{\theta}^*}(\mathbf{z} | \mathbf{x}).$$

Variational Posterior

$$q(\mathbf{z}) = rg \max_{q} \mathcal{L}_{q, \boldsymbol{\theta}^*}(\mathbf{x}) = rg \min_{q} \mathrm{KL}(q \| p) = p_{\boldsymbol{\theta}^*}(\mathbf{z} | \mathbf{x}).$$

- $ightharpoonup p_{\theta^*}(\mathbf{z}|\mathbf{x})$ may be **intractable**;
- $ightharpoonup q(\mathbf{z})$ is individual for each data point \mathbf{x} .

Variational Posterior

$$q(\mathbf{z}) = rg \max_{q} \mathcal{L}_{q, \boldsymbol{\theta}^*}(\mathbf{x}) = rg \min_{q} \mathrm{KL}(q \| p) = p_{\boldsymbol{\theta}^*}(\mathbf{z} | \mathbf{x}).$$

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Amortized Variational Inference

We restrict the family of possible distributions $q(\mathbf{z})$ to a parametric class $q_{\phi}(\mathbf{z}|\mathbf{x})$, conditioned on data \mathbf{x} and parameterized by ϕ .

Variational Posterior

$$q(\mathbf{z}) = rg \max_{q} \mathcal{L}_{q, \boldsymbol{\theta}^*}(\mathbf{x}) = rg \min_{q} \mathrm{KL}(q \| p) = p_{\boldsymbol{\theta}^*}(\mathbf{z} | \mathbf{x}).$$

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Amortized Variational Inference

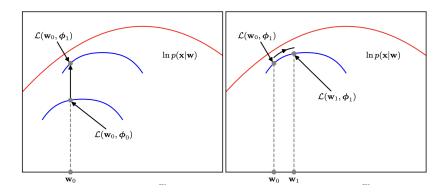
We restrict the family of possible distributions $q(\mathbf{z})$ to a parametric class $q_{\phi}(\mathbf{z}|\mathbf{x})$, conditioned on data \mathbf{x} and parameterized by ϕ .

Gradient Update

$$\begin{bmatrix} \phi_k \\ \theta_k \end{bmatrix} = \begin{bmatrix} \phi_{k-1} + \eta \cdot \nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x}) \\ \theta_{k-1} + \eta \cdot \nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x}) \end{bmatrix} \Big|_{(\phi_{k-1},\theta_{k-1})}$$

Gradient Update

$$\begin{bmatrix} \boldsymbol{\phi}_k \\ \boldsymbol{\theta}_k \end{bmatrix} = \begin{bmatrix} \boldsymbol{\phi}_{k-1} + \boldsymbol{\eta} \cdot \nabla_{\boldsymbol{\phi}} \mathcal{L}_{\boldsymbol{\phi}, \boldsymbol{\theta}}(\mathbf{x}) \\ \boldsymbol{\theta}_{k-1} + \boldsymbol{\eta} \cdot \nabla_{\boldsymbol{\theta}} \mathcal{L}_{\boldsymbol{\phi}, \boldsymbol{\theta}}(\mathbf{x}) \end{bmatrix} \bigg|_{(\boldsymbol{\phi}_{k-1}, \boldsymbol{\theta}_{k-1})}$$



ELBO

$$egin{aligned} \log p_{m{ heta}}(\mathbf{x}) &= \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}) + \mathrm{KL}(q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \| p_{m{ heta}}(\mathbf{z}|\mathbf{x})) \geq \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}). \ & \mathcal{L}_{q,m{ heta}}(\mathbf{x}) &= \mathbb{E}_q \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z})) \end{aligned}$$

ELBO

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$$\begin{bmatrix} \phi_k \\ \theta_k \end{bmatrix} = \begin{bmatrix} \phi_{k-1} + \eta \cdot \nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x}) \\ \theta_{k-1} + \eta \cdot \nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x}) \end{bmatrix} \Big|_{(\phi_{k-1},\theta_{k-1})}$$

- lacktriangledown ϕ denotes the parameters of the variational posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$.
- $m{\theta}$ represents the parameters of the generative model $p_{m{\theta}}(\mathbf{x}|\mathbf{z})$.

ELBO

$$egin{aligned} \log p_{m{ heta}}(\mathbf{x}) &= \mathcal{L}_{\phi,m{ heta}}(\mathbf{x}) + \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p_{m{ heta}}(\mathbf{z}|\mathbf{x})) \geq \mathcal{L}_{\phi,m{ heta}}(\mathbf{x}). \ & \mathcal{L}_{q,m{ heta}}(\mathbf{x}) &= \mathbb{E}_q \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z})) \end{aligned}$$

Gradient Update

$$\begin{bmatrix} \phi_k \\ \theta_k \end{bmatrix} = \begin{bmatrix} \phi_{k-1} + \eta \cdot \nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x}) \\ \theta_{k-1} + \eta \cdot \nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x}) \end{bmatrix} \Big|_{(\phi_{k-1},\theta_{k-1})}$$

- $ightharpoonup \phi$ denotes the parameters of the variational posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$.
- \triangleright θ represents the parameters of the generative model $p_{\theta}(\mathbf{x}|\mathbf{z})$.

The remaining step is to obtain **unbiased** Monte Carlo estimates of the gradients: $\nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x})$ and $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$.

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$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \mathbb{E}_q \log p_{\theta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) || p(\mathbf{z}))$$

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Gradient
$$\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$$

$$abla_{m{ heta}} \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}) = \mathbf{\nabla}_{m{ heta}} \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z}$$

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Gradient $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

$$egin{aligned}
abla_{m{ heta}} \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}) &= ar{f V}_{m{ heta}} \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &= \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) ar{f V}_{m{ heta}} \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \end{aligned}$$

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Gradient $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

$$egin{aligned}
abla_{m{ heta}} \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}) &= ar{f V}_{m{ heta}} \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &= \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) ar{f V}_{m{ heta}} \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &pprox
abla_{m{ heta}} \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}^*), \quad \mathbf{z}^* \sim q_{m{\phi}}(\mathbf{z}|\mathbf{x}). \end{aligned}$$

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Gradient $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

$$egin{aligned}
abla_{m{ heta}} \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}) &=
abla_{m{ heta}} \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &= \int q_{m{\phi}}(\mathbf{z}|\mathbf{x})
abla_{m{ heta}} \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &pprox
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Naive Monte Carlo Estimation

$$\log p_{\theta}(\mathbf{x}) \geq \int \log p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z})d\mathbf{z} \approx \frac{1}{K} \sum_{k=1}^{K} \log p_{\theta}(\mathbf{x}|\mathbf{z}_{k}), \quad \mathbf{z}_{k} \sim p(\mathbf{z}).$$

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Gradient $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

$$egin{aligned}
abla_{m{ heta}} \mathcal{L}_{m{\phi},m{ heta}}(\mathbf{x}) &=
abla_{m{ heta}} \int q_{m{\phi}}(\mathbf{z}|\mathbf{x}) \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &= \int q_{m{\phi}}(\mathbf{z}|\mathbf{x})
abla_{m{ heta}} \log p_{m{ heta}}(\mathbf{x}|\mathbf{z}) d\mathbf{z} \ &pprox
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The variational posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$ typically concentrates more probability mass in a much smaller region than the prior $p(\mathbf{z})$.

Gradient
$$\nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x})$$

Unlike the θ -gradient, the density $q_{\phi}(\mathbf{z}|\mathbf{x})$ now depends on ϕ , so standard Monte Carlo estimation can't be applied:

$$abla_{\phi} \mathcal{L}_{\phi, heta}(\mathbf{x}) =
abla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{ heta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} -
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$$\neq \int q_{\phi}(\mathbf{z}|\mathbf{x}) \nabla_{\phi} \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

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Reparametrization Trick (LOTUS Trick)

Assume $\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})$ is generated by a random variable $\epsilon \sim p(\epsilon)$ via a deterministic mapping $\mathbf{z} = \mathbf{g}_{\phi}(\mathbf{x}, \epsilon)$. Then,

$$\mathbb{E}_{\mathsf{z} \sim q_{\phi}(\mathsf{z}|\mathsf{x})} \mathsf{f}(\mathsf{z}) = \mathbb{E}_{\epsilon \sim p(\epsilon)} \mathsf{f}(\mathsf{g}_{\phi}(\mathsf{x},\epsilon))$$

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$$\nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x})$$

Unlike the θ -gradient, the density $q_{\phi}(\mathbf{z}|\mathbf{x})$ now depends on ϕ , so standard Monte Carlo estimation can't be applied:

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Note: The LHS expectation is with respect to the parametric distribution $q_{\phi}(\mathbf{z}|\mathbf{x})$, while the RHS is for the non-parametric $p(\epsilon)$.

Reparametrization Trick (LOTUS Trick)

$$\nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \mathbf{f}(\mathbf{z}) d\mathbf{z} = \nabla_{\phi} \int p(\epsilon) \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon)) d\epsilon$$

Reparametrization Trick (LOTUS Trick)

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$$= \int p(\epsilon) \nabla_{\phi} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon)) d\epsilon \approx \nabla_{\phi} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon^{*})),$$

where $\epsilon^* \sim p(\epsilon)$.

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$$= \int p(\epsilon) \nabla_{\phi} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon)) d\epsilon \approx \nabla_{\phi} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon^{*})),$$

where $\epsilon^* \sim p(\epsilon)$.

Variational Assumption

$$egin{aligned} p(\epsilon) &= \mathcal{N}(0, \mathbf{I}); \quad \mathbf{z} = \mathbf{g}_{\phi}(\mathbf{x}, \epsilon) = \sigma_{\phi}(\mathbf{x}) \odot \epsilon + \mu_{\phi}(\mathbf{x}); \\ q_{\phi}(\mathbf{z}|\mathbf{x}) &= \mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}^2(\mathbf{x})). \end{aligned}$$

Here, $\mu_{\phi}(\cdot)$ and $\sigma_{\phi}(\cdot)$ are parameterized functions (outputs of a neural network).

Thus, we can write $q_{\phi}(\mathbf{z}|\mathbf{x}) = NN_{e,\phi}(\mathbf{x})$, the **encoder**.

$$\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x}) = \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

$$\nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x}) = \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Reconstruction Term

$$\begin{split} \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} &= \int p(\epsilon) \nabla_{\phi} \log p_{\theta}(\mathbf{x}|\mathbf{g}_{\phi}(\mathbf{x},\epsilon)) d\epsilon \approx \\ &\approx \nabla_{\phi} \log p_{\theta} \left(\mathbf{x}|\sigma_{\phi}(\mathbf{x}) \odot \epsilon^* + \mu_{\phi}(\mathbf{x}) \right), \quad \text{where } \epsilon^* \sim \mathcal{N}(0,\mathbf{I}) \end{split}$$

$$\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x}) = \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

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$$\begin{split} &\nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} = \int p(\epsilon) \nabla_{\phi} \log p_{\theta}(\mathbf{x}|\mathbf{g}_{\phi}(\mathbf{x},\epsilon)) d\epsilon \approx \\ &\approx \nabla_{\phi} \log p_{\theta} \left(\mathbf{x}|\boldsymbol{\sigma}_{\phi}(\mathbf{x}) \odot \epsilon^* + \boldsymbol{\mu}_{\phi}(\mathbf{x})\right), \quad \text{where } \epsilon^* \sim \mathcal{N}(0,\mathbf{I}) \end{split}$$

The generative distribution $p_{\theta}(\mathbf{x}|\mathbf{z})$ can be implemented as a neural network.

We may write $p_{\theta}(\mathbf{x}|\mathbf{z}) = NN_{d,\theta}(\mathbf{z})$, called the **decoder**.

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Reconstruction Term

$$\begin{split} &\nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} = \int p(\epsilon) \nabla_{\phi} \log p_{\theta}(\mathbf{x}|\mathbf{g}_{\phi}(\mathbf{x},\epsilon)) d\epsilon \approx \\ &\approx \nabla_{\phi} \log p_{\theta} \left(\mathbf{x}|\boldsymbol{\sigma}_{\phi}(\mathbf{x}) \odot \epsilon^* + \boldsymbol{\mu}_{\phi}(\mathbf{x})\right), \quad \text{where } \epsilon^* \sim \mathcal{N}(0,\mathbf{I}) \end{split}$$

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KL Term

 $p(\mathbf{z})$ is the prior over latents \mathbf{z} , typically $p(\mathbf{z}) = \mathcal{N}(0, \mathbf{I})$.

$$\nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z})) = \nabla_{\phi} \mathrm{KL}\left(\mathcal{N}(\boldsymbol{\mu}_{\phi}(\mathbf{x}), \boldsymbol{\sigma}_{\phi}^{2}(\mathbf{x})) \| \mathcal{N}(0, \mathbf{I})\right)$$

ELBO Gradient: $\nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

$$\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x}) = \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

Reconstruction Term

$$\begin{split} &\nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} = \int p(\epsilon) \nabla_{\phi} \log p_{\theta}(\mathbf{x}|\mathbf{g}_{\phi}(\mathbf{x},\epsilon)) d\epsilon \approx \\ &\approx \nabla_{\phi} \log p_{\theta} \left(\mathbf{x}|\boldsymbol{\sigma}_{\phi}(\mathbf{x}) \odot \epsilon^* + \boldsymbol{\mu}_{\phi}(\mathbf{x})\right), \quad \text{where } \epsilon^* \sim \mathcal{N}(0,\mathbf{I}) \end{split}$$

The generative distribution $p_{\theta}(\mathbf{x}|\mathbf{z})$ can be implemented as a neural network.

We may write $p_{\theta}(\mathbf{x}|\mathbf{z}) = NN_{d,\theta}(\mathbf{z})$, called the **decoder**.

KL Term

 $p(\mathbf{z})$ is the prior over latents \mathbf{z} , typically $p(\mathbf{z}) = \mathcal{N}(0, \mathbf{I})$.

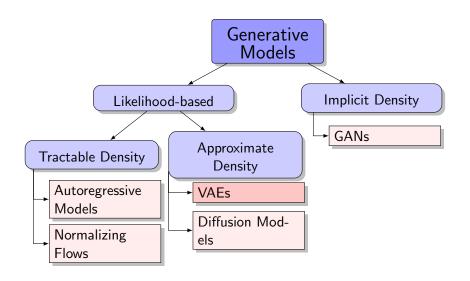
$$\nabla_{\phi} \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z})) = \nabla_{\phi} \mathrm{KL}\left(\mathcal{N}(\boldsymbol{\mu}_{\phi}(\mathbf{x}), \boldsymbol{\sigma}_{\phi}^{2}(\mathbf{x})) \| \mathcal{N}(\mathbf{0}, \mathbf{I})\right)$$

This expression admits a closed-form analytic solution.

Outline

- 1. Latent Variable Models (LVM) (continued)
- 2. Variational Evidence Lower Bound (ELBO)
- Amortized Inference
- 4. ELBO Gradients, Reparametrization Trick
- 5. Variational Autoencoder (VAE)

Generative Models Zoo



Training

▶ Pick a batch of samples $\{\mathbf{x}_i\}_{i=1}^B$ (here we use Monte Carlo technique).

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- Compute the objective for each sample (apply the reparametrization trick):

$$egin{aligned} m{\epsilon}^* \sim p(m{\epsilon}); \quad \mathbf{z}^* &= \mathbf{g}_{m{\phi}}(\mathbf{x}, m{\epsilon}^*); \ & \mathcal{L}_{m{\phi}, m{ heta}}(\mathbf{x}) pprox \log p_{m{ heta}}(\mathbf{x} | \mathbf{z}^*) - \mathrm{KL}(q_{m{\phi}}(\mathbf{z} | \mathbf{x}) \| p(\mathbf{z})). \end{aligned}$$

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▶ Update parameters via stochastic gradient steps with respect to ϕ and θ .

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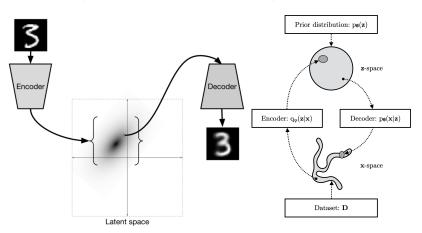
Inference

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Note: The encoder $q_{\phi}(\mathbf{z}|\mathbf{x})$ isn't needed during generation.

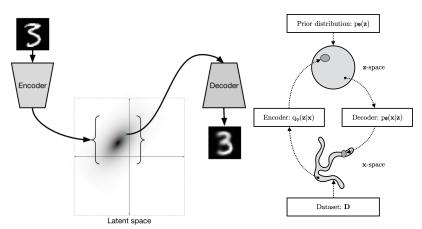
Variational Autoencoder

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p_{ heta}(\mathbf{x}|\mathbf{z}) - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$



Variational Autoencoder

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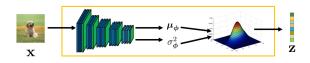


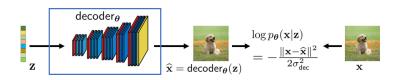
VAEs are widely used as a preliminary stage of projecting data onto low-dimensional space.

image credit: http://ijdykeman.github.io/ml/2016/12/21/cvae.html Kingma D. P., Welling M., An Introduction to Variational Autoencoders, 2019

Variational Autoencoder

- lacksquare The encoder $q_{\phi}(\mathbf{z}|\mathbf{x}) = \mathsf{NN}_{e,\phi}(\mathbf{x})$ outputs $\mu_{\phi}(\mathbf{x})$ and $\sigma_{\phi}(\mathbf{x})$.
- ▶ The decoder $p_{\theta}(\mathbf{x}|\mathbf{z}) = \mathsf{NN}_{d,\theta}(\mathbf{z})$ outputs parameters of the observed data distribution.





VAE vs Normalizing Flows

	VAE	NF
Objective	ELBO $\mathcal L$	Forward KL/MLE
		deterministic
	stochastic	$z = f_{oldsymbol{ heta}}(x)$
Encoder	$ \mathbf{z} \sim q_{oldsymbol{\phi}}(\mathbf{z} \mathbf{x})$	$q_{m{ heta}}(\mathbf{z} \mathbf{x}) = \delta(\mathbf{z} - \mathbf{f}_{m{ heta}}(\mathbf{x}))$
		deterministic
	stochastic	$x = g_{oldsymbol{ heta}}(z)$
Decoder	$\mathbf{x} \sim p_{m{ heta}}(\mathbf{x} \mathbf{z})$	$p_{m{ heta}}(\mathbf{x} \mathbf{z}) = \delta(\mathbf{x} - \mathbf{g}_{m{ heta}}(\mathbf{z}))$
Parameters	$\phi, oldsymbol{ heta}$	$ heta \equiv \phi$

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	VAE	NF
Objective	ELBO $\mathcal L$	Forward KL/MLE
Encoder	stochastic $\mathbf{z} \sim q_{oldsymbol{\phi}}(\mathbf{z} \mathbf{x})$	$\begin{aligned} deterministic \\ \mathbf{z} &= \mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}) \\ q_{\boldsymbol{\theta}}(\mathbf{z} \mathbf{x}) &= \delta(\mathbf{z} - \mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x})) \end{aligned}$
Decoder	$\begin{aligned} &stochastic \\ &x \sim p_{\theta}(x z) \end{aligned}$	$\begin{aligned} deterministic \\ \mathbf{x} &= \mathbf{g}_{\boldsymbol{\theta}}(\mathbf{z}) \\ p_{\boldsymbol{\theta}}(\mathbf{x} \mathbf{z}) &= \delta(\mathbf{x} - \mathbf{g}_{\boldsymbol{\theta}}(\mathbf{z})) \end{aligned}$
Parameters	ϕ, θ	$ heta \equiv \phi$

Theorem

MLE for a normalizing flow is equivalent to maximizing the ELBO for a VAE where:

$$p_{\theta}(\mathbf{x}|\mathbf{z}) = \delta(\mathbf{x} - \mathbf{f}_{\theta}^{-1}(\mathbf{z})) = \delta(\mathbf{x} - \mathbf{g}_{\theta}(\mathbf{z}));$$

$$q_{\theta}(\mathbf{z}|\mathbf{x}) = \delta(\mathbf{z} - \mathbf{f}_{\theta}(\mathbf{x})).$$

Nielsen D., et al., SurVAE Flows: Surjections to Bridge the Gap Between VAEs and Flows. 2020

Summary

- ► LVMs introduce latent representations for observed data, enabling more interpretable models.
- ► LVMs maximize the variational evidence lower bound (ELBO) to obtain maximum likelihood estimates for the parameters.
- Parametric posterior distribution $q_{\phi}(\mathbf{z}|\mathbf{x})$ makes the method scalable.
- The reparametrization trick provides unbiased gradients with respect to the variational posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$.
- ► The VAE model is a latent variable model parameterized by two neural networks: a stochastic encoder $q_{\phi}(\mathbf{z}|\mathbf{x})$ and a stochastic decoder $p_{\theta}(\mathbf{x}|\mathbf{z})$.
- Nowadays, the main role of VAEs is to project data into low-dimensional latent space.