

# **Tutorial 01**

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### Content







Examples of human-robot interaction and its human-centered aspects.

• qiBullet: Introduction and Installation.





# Examples of Human-Robot Interaction



#### Search and Rescue...





https://www.youtube.com/watch?v=\_EnzZrXJwJo



https://www.youtube.com/watch?v=y-rEI4bezWc

... in close collaboration with human firefighters and emergency services.



### Search and Rescue...









https://youtu.be/c8lJg9pOcVc



# **Autism Therapy**











https://youtu.be/R9Tr9Qe0K2M

https://youtu.be/wT0RtnCR130



#### Rehabilitation













https://youtu.be/mW78KG-29lg



#### **Service Robots**









https://youtu.be/nJj8wJg6jNM



https://youtu.be/AHZ1AhdUS\_M



# Embodied + Depicted for Lively and Social Behaviors







https://youtu.be/7YRNjclHTHg

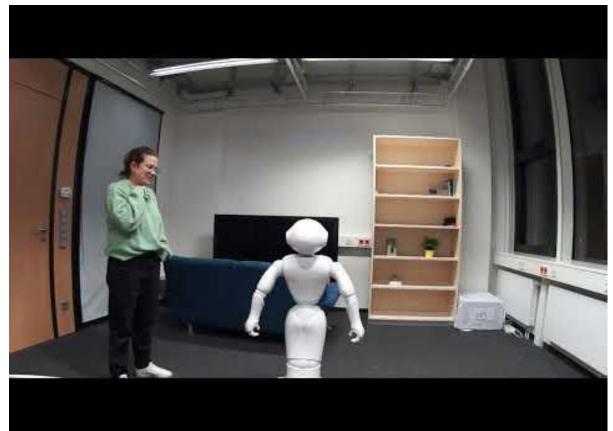
https://youtu.be/-nrp7geg6Wg

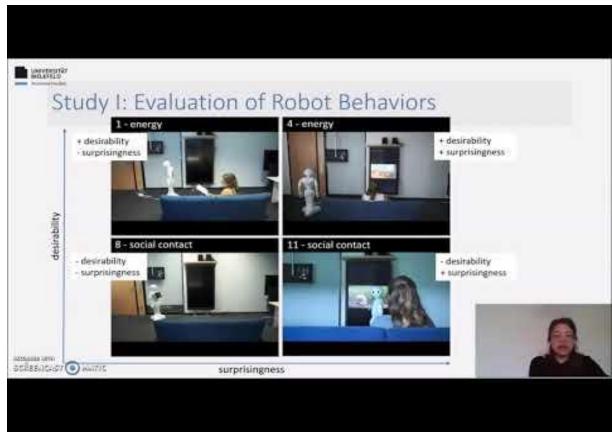
Combine the strengths of an embodied robot and virtual agent technologies...



# Self-Explaining Social Robots







https://youtu.be/yHI-hTbRECQ

https://youtu.be/4SGNsOFyMwg

An extension of this would be multimodal explanations that are both verbal and nonverbal...



# Learning from and Adapting to Humans...









https://youtu.be/cKoYE969OvM



https://youtu.be/VN1-bToWlac



## Mechanical Design





https://youtu.be/5n4vYPrmVug

- Hard versus soft materials
- Compliant versus stiff design



https://youtu.be/5n4vYPrmVug

Prof. Andrea Bonarini, Italy [Robotics and Design]



https://youtu.be/ZcTwO2dpX8A



qiBullet: Introduction and Installation.



## qiBullet Installation and Usage



#### Installation

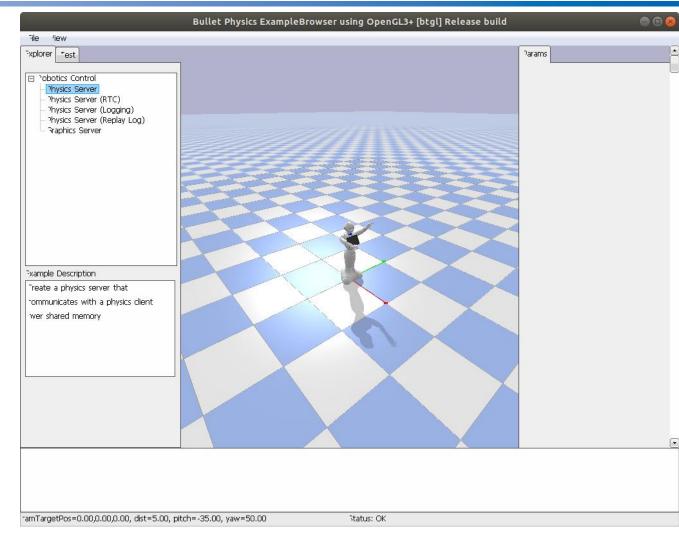
 https://github.com/softbankroboticsresearch/qibullet

#### Usage

 https://github.com/softbankroboticsresearch/qibullet/wiki/Tutorials:-Virtual-Robot

#### Warm-Up tasks:

- Spawn Pepper
- Make Pepper dance
- Add a table and objects to the environment
- Make Pepper lay the table





# Why Use qiBullet?







Cost savings by not requiring physical robots.

Faster development and testing.

Safe environment for experimentation.



# Key Features







High-quality physics simulation.

Support for Pepper and NAO robots.

Realistic sensor modeling.

Integration with popular Python libraries.



# Multimodal Behavior on Pepper



- TTS Engines
  - There are many libraries that you could use
    - gTTS with playsound: Documentation link or any other library of your preference.
      - » <a href="https://pypi.org/project/gTTS/">https://pypi.org/project/gTTS/</a>
      - » https://pypi.org/project/playsound/
    - pyttsx3:
      - » <a href="https://pypi.org/project/pyttsx3/">https://pypi.org/project/pyttsx3/</a>
  - If you use any other libraries, then please provide us the links with installation instruction.

- For parallel behaviors, use threads:
  - https://docs.python.org/3/library/th reading.html



# Thank you!

- For any queries:
  - LEA Forum
  - email to <u>ritwik.sinha@smail.inf.h-brs.de</u>

