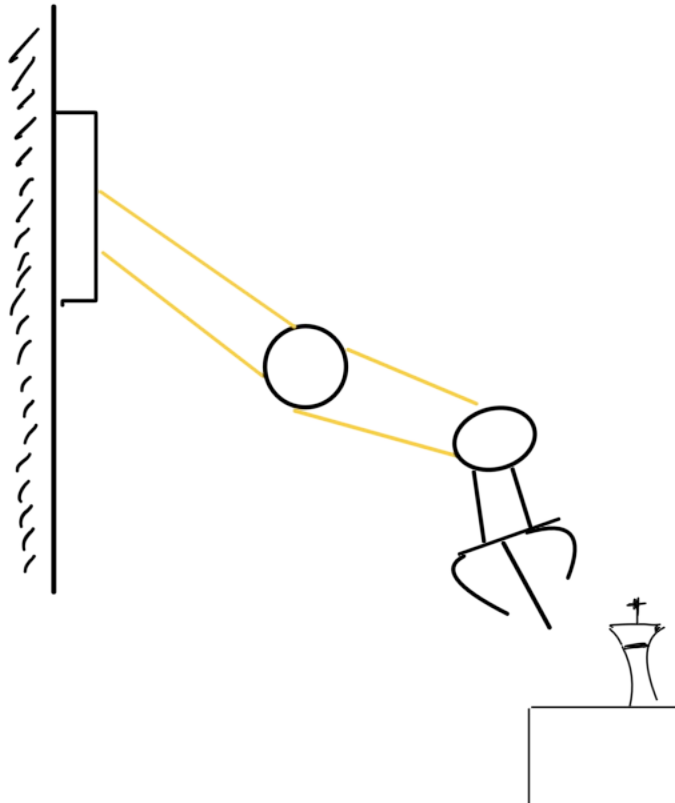
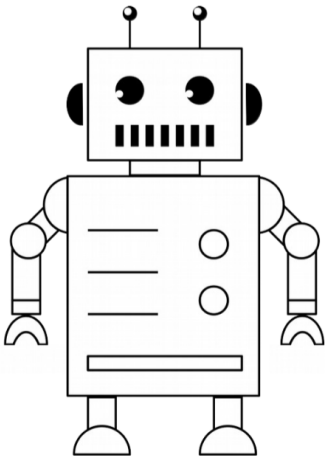


Robot Description & Illustration



Field of Application

11

Exposure to

robot

settings

Robot Task Specification

Data Exchange

Robot Morphology

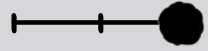
a z t

- appearance
- communication
- movement
- context

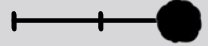
a (anthropomorphic),
z (zoomorphic),
t (technical)

Degree of Robot Autonomy

- +



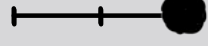
information
analyses



decision-making



action
implementation



Human Role

Communication Channel

input

Proximity

temporal

physical

Team Composition

$$N_H = N_R$$

$$N_H > N_R$$

$$N_H < N_R$$

output