



Robot Description & Illustration

Field of Application

Exposure to

robotsettings

Robot Task Specification

Robot Morphology

a z t

- appearance
- communication
- movement
- context

a (anthropomorphic),
z (zoomorphic),
t (technical)

Degree of Robot Autonomy

- +

information
acquisition

information
analyses

decision-
making

action
implementation

Human Role

Communication Channel

input

Proximity

temporal

physical

Team Composition

$$N_H = N_R$$

$$N_H > N_R$$

$$N_H < N_R$$

output