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Object Tracking

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- What is tracking?
- Tracking in computer vison.
- Motion model and appearnace model.
- OpenCV API Tracker Class.

Goal

Given the initial location of an object, track location in subsequent frames



```
# import writib

import os
import sys
import cv2
import matplotlib.pyplot as plt

from zipfile import Zipfile
from urllib.request import urlretrieve

from IPython.display import FuncAnimation

from IPython.display import YouTubeVideo, display, HTML
from base64 import b64encode

%matplotlib inline
```

Download Assets

```
In []: M def download_and_unzip(url, save_path):
    print(f"Downloading and extracting assests...", end="")

# Downloading zip file using urllib package.
urlretrieve(url, save_path)

try:
    # Extracting zip file using the zipfile package.
    with Zipfile(save_path) as z:
        # Extract ZIP file contents in the same directory.
        z.extractall(os.path.split(save_path)[0])

    print("Done")

except Exception as e:
    print("\nInvalid file.", e)
```

Downloading and extracting assests....Done

Tracker Class in OpenCV

- 1. BOOSTING
- 2. MIL
- 3. KCF

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- 4. CRST
- 5. TLD
 - Tends to recover from occulusions
- 6. MEDIANFLOW
 - Good for predictable slow motion
- 7. GOTURN
 - Deep Learning based
 - Most Accurate
- 8. MOSSE
 - Fastest

```
In [2]: N video = YouTubeVideo("XkJCvtCRdVM", width=1024, height=640)
display(video)
```

```
In [3]: W video_input_file_name = "race_car.mp4"

def drawRectangle(frame, bbox):
    p1 = (int(bbox[0]), int(bbox[1]) + bbox[2]), int(bbox[1] + bbox[3]))
    cv2.rectangle(frame, p1, p2, (255, 0, 0), 2, 1)

def displayRectangle(frame, bbox):
    p1t.figure(figsize=(20, 10))
    frameCopy = frame.copy()
    drawRectangle(framecopy, bbox)
    frameCopy = cv2.vctColor(frameCopy, cv2.COLOR_RGB2BGR)
    p1t.inshow(frameCopy)
    p1t.axis("off")

def drawText(frame, txt, location, color=(50, 170, 50)):
    cv2.putText(frame, txt, location, cv2.FONT_HERSHEY_SIMPLEX, 1, color, 3)
```

GOTURN Tracker



```
In [4]:  

# Set up tracker
            tracker_types = [
                "BOOSTING",
                "MIL",
                "KCF",
                "CSRT",
                "TLD",
                "MEDIANFLOW",
                "GOTURN",
                "MOSSE",
            # Change the index to change the tracker type
            tracker_type = tracker_types[2]
            if tracker_type == "BOOSTING":
               tracker = cv2.legacy.TrackerBoosting.create()
            elif tracker_type == "MIL":
               tracker = cv2.legacy.TrackerMIL.create()
            elif tracker_type == "KCF":
               tracker = cv2.TrackerKCF.create()
            elif tracker_type == "CSRT":
               tracker = cv2.TrackerCSRT.create()
            elif tracker_type == "TLD":
               tracker = cv2.legacy.TrackerTLD.create()
            elif tracker_type == "MEDIANFLOW":
                tracker = cv2.legacy.TrackerMedianFlow.create()
            elif tracker_type == "GOTURN":
               tracker = cv2.TrackerGOTURN.create()
            else:
                tracker = cv2.legacy.TrackerMOSSE.create()
                                                      Traceback (most recent call last)
            AttributeError
            ~\AppData\Local\Temp\ipykernel_6356\4226330706.py in <module>
                 19 tracker = cv2.legacy.TrackerMIL.create()
                 20 elif tracker_type == "KCF":
            ---> 21 tracker = cv2.TrackerKCF.create()
                 22 elif tracker_type == "CSRT":
```

Read input video & Setup output Video

tracker = cv2.TrackerCSRT.create()

AttributeError: module 'cv2' has no attribute 'TrackerKCF'

11_objectTracking - Jupyter Notebook

Define Bounding Box

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```
In []:  # Define a bounding box
bbox = (1300, 405, 160, 120)
# bbox = cv2.selectROI(frame, False)
# print(bbox)
displayRectangle(frame, bbox)
```



Intilialize Tracker

- 1. One frame
- 2. A bounding box

Read frame and Track Object

```
In []: ▶ while True:
               ok, frame = video.read()
               if not ok:
                   break
               # Start timer
               timer = cv2.getTickCount()
               # Update tracker
               ok, bbox = tracker.update(frame)
               # Calculate Frames per second (FPS)
               fps = cv2.getTickFrequency() / (cv2.getTickCount() - timer)
               # Draw bounding box
               if ok:
                   drawRectangle(frame, bbox)
               else:
                   drawText(frame, "Tracking failure detected", (80, 140), (0, 0, 255))
               # Display Info
               drawText(frame, tracker_type + " Tracker", (80, 60))
               drawText(frame, "FPS : " + str(int(fps)), (80, 100))
               # Write frame to video
               video_out.write(frame)
           video.release()
           video_out.release()
!apt-get -qq install ffmpeg
           # Change video encoding of mp4 file from XVID to h264
           !ffmpeg -y -i {video_output_file_name} -c:v libx264 $"race_car_track_x264.mp4" -hide_banner -loglevel error
```

Render MP4 Video

```
In []: M mp4 = open("/content/race_car_track_x264.mp4", "rb").read()
data_url = "data:video/mp4;base64," + b64encode(mp4).decode()

HTML(f"""<video width=1024 controls><source src="{data_url}" type="video/mp4"></video>""")
```

The expected video rendered in the above cell should be the same as the following.

```
In []: W # Tracker: KCF
    video = YouTubeVideo("pk3tmdRX4ww", width=1024, height=640)

In []: W # Tracker: CSRT
    video = YouTubeVideo("6gGDf-7ypBE", width=1024, height=640)
    display(video)

In []: W # Tracker: GOTURN
    video = YouTubeVideo("0bnWxc4zMvY", width=1024, height=640)
    display(video)
```

Thank You!