

Abstract State Machines Model Checking

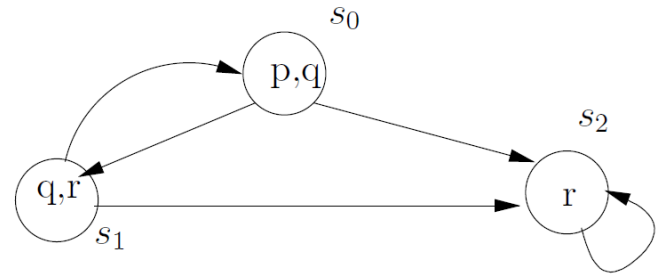


AsmetaSVM

Model checking

- Formal verification technique of properties defined in a temporal logic.
- A model checker works in three steps:
 1. definition of a model \mathcal{M} using the *Kripke structures*;
 2. definition of a temporal formula ϕ , that describes a property that we want to verify;
 3. the model checker verifies that $\mathcal{M} \models \phi$.
- Exhaustive verification of all the state space.
- Finite domains.

Kripke structure



A Kripke structure is defined by the 4-uple

$$\mathcal{M} = (S, \Delta, S_0, L)$$

where:

- S is a finite set of states;
- Δ (or \rightarrow) is a transition total relation, that is

$$\forall s \in S \ \exists s' \in S \text{ such that } s \rightarrow s'$$

- $S_0 \subseteq S$ is the set of initial states;
- $L : S \rightarrow 2^{AP}$ is a labelling function that links each state with a label; the label lists the atomic propositions that are true in that state. AP is a set of atomic propositions.

Temporal logics

Temporal logics are divided into:

- *Linear Time Logics* (LTL) represent time as infinite sequences of instant; you can declare properties that must be true over all sequences;
- *Branching Time Logics* (BTL) represent time as a tree, where the root is the initial instant and its children the possible evolutions of the system; you can declare properties concerning all the paths or just some of them.

Temporal logics, moreover, can be classified in continuous time logics and discrete time logics.

Computation Tree Logic (CTL)

- *Computation Tree Logic* (CTL), is a discrete time BTL.
- CTL permits to express logic formulas concerning paths, that is sequences of state transitions.
- Each CTL formula has a path quantifier that says if the formula must be true in all paths (*A, along All paths*) or if must be true in at least one path (*E, Exists at least one path*). Moreover can be used the temporal operators:
 - $X\ p$: the property p must be verified in the next state;
 - $F\ p$: the property p must be verified in a future state;
 - $G\ p$: the property p must be verified in all the states;
 - $p\ U\ q$: the property p must be true until the q property becomes true.

Computation Tree Logic (CTL) - Allowed formulas

Allowed formulas

It's $AP\{p, q, r, \dots\}$ a set of atomic formulas; CTL formulas can be expressed in the following way:

$$\phi ::= \top \mid \perp \mid p \in AP \mid \neg\phi \mid \phi \wedge \phi \mid \phi \vee \phi \mid \phi \rightarrow \phi \mid AX\phi \mid EX\phi \mid A[\phi U \phi] \mid E[\phi U \phi] \mid AG\phi \mid EG\phi \mid AF\phi \mid EF\phi$$

where \top , \perp , \neg , \wedge , \vee and \rightarrow are the connectives of propositional logic and AX , EX , AG , EG , AU , EU , AF and EF are temporal connectives .

Operators priority

The unary operators have the highest priority; then there are the binary operators \vee and \wedge and, at last, the binary operators \rightarrow , AU and EU .

NuSMV

- NuSMV¹ is a symbolic model checker derived from CMU SMV;
- permits to verify properties written both in *Computation Tree Logic* (CTL) and in *Linear Temporal Logic* (LTL);
- the internal representation of the model uses the *Binary Decision Diagrams* (BDDs);
- states are determined by the variables values;
- transitions between states are determined by the updates of the variables.

AsmetaSMV

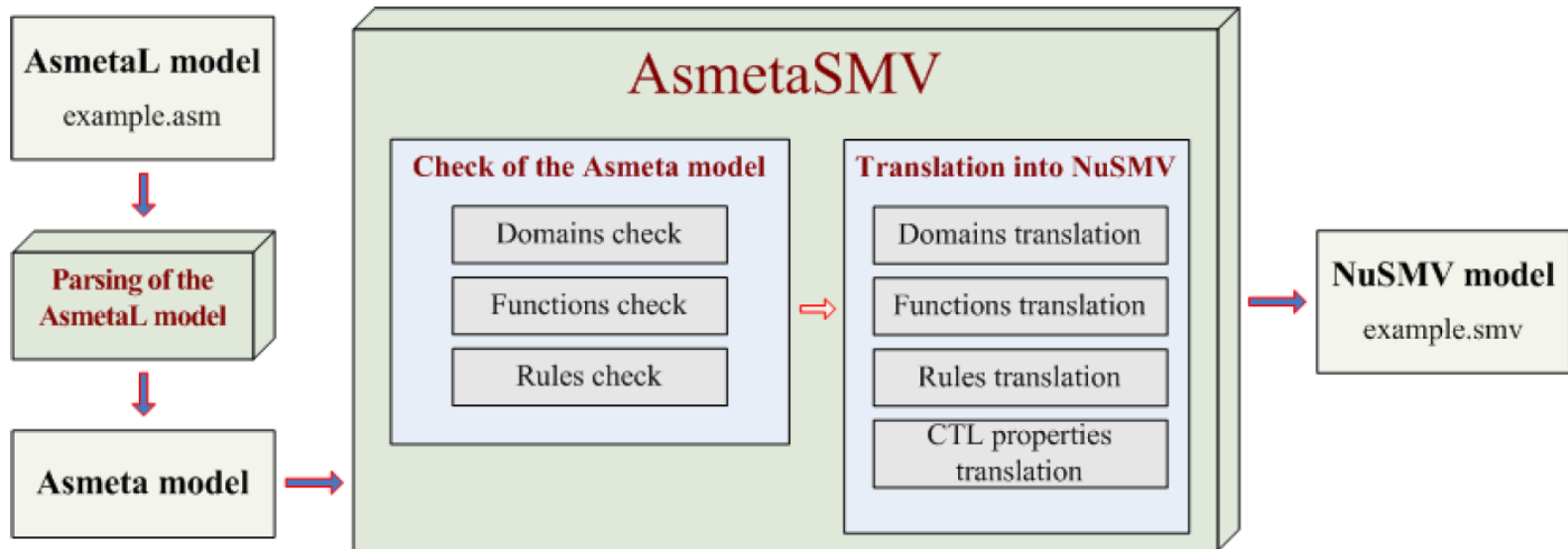
Goals

- Exploit the capabilities of NuSMV in ASMETA;
- to be able to define CTL and LTL properties directly in the AsmetaL model;
- the user could ignore the NuSMV syntax, he must only knows the temporal operators.

Functioning of the tool

- Writing of an AsmetaL code;
- translation of the AsmetaL code into a NuSMV code;
- execution of the NuSMV code with the model checker.

AsmetaSMV architecture



Mapping overview

- AsmetaSMV **cannot translate any AsmetaL element** into NuSMV; we say that an AsmetaL element is supported if it can be translated into NuSMV, otherwise that it's not supported;
- an AsmetaL element is not supported because:
 - it requires conditions that cannot be satisfied in NuSMV. For example, type domains Real, Integer, Char, don't have a corresponding type in NuSMV and so they cannot be used as domains or codomains of functions in AsmetaL models that must be translated;
 - the translation would be too complicated; it's the case of many turbo rules.

Domains

Classification of AsmetaL domains

- type domains:
 - basic type domains: *Complex*, *Real*, *Integer*, *Natural*, *String*, *Char*, *Boolean*, *Rule* and *Undef*;
 - structured type domains: *ProductDomain*, *SequenceDomain*, *PowersetDomain*, *BagDomain* and *MapDomain*;
 - abstract type-domains: are generic domains;
 - enum domains.
- concrete domains: subset of concrete domains.

Mapping of AsmetaL domains

Are supported **only finite domains** and whose type is available in NuSMV:

- *Boolean*;
- *enum domain*;
- concrete domains of *Integer* and *Natural*.

Mapping functions

AsmetaL Model

```
asm arity2and3
import ./StandardLibrary

signature:
  domain SubDom subsetof Integer
  enum domain EnumDom = {AA | BB}
  dynamic controlled foo2:
    Prod(Boolean, EnumDom) -> SubDom
  dynamic controlled foo3:
    Prod(SubDom, EnumDom, SubDom) -> Boolean

definitions:
  domain SubDom = {1..2}

  main rule r_Main =
    skip
```

NuSMV Model

```
MODULE main
  VAR
    foo2_FALSE_AA: {-2147483647, 1, 2};
    foo2_FALSE_BB: {-2147483647, 1, 2};
    foo2_TRUE_AA: {-2147483647, 1, 2};
    foo2_TRUE_BB: {-2147483647, 1, 2};
    foo3_1_AA_1: boolean;
    foo3_1_AA_2: boolean;
    foo3_1_BB_1: boolean;
    foo3_1_BB_2: boolean;
    foo3_2_AA_1: boolean;
    foo3_2_AA_2: boolean;
    foo3_2_BB_1: boolean;
    foo3_2_BB_2: boolean;
```

Limitations

- Limited domains
- No equivalence between ASM and NuSVM model due to the Boolean undef
- All functions mapped to variables
 - Too many variables may compromise the NuSMV performance

CTL/LTL library

CTL properties in NuSMV

SPEC p_{CTL}

where p_{CTL} is a CTL formula.

LTL properties in NuSMV

LTLSPEC p_{LTL}

where p_{LTL} is a LTL formula.

CTL and LTL operators in AsmetaL

In order to write CTL and LTL formulas in AsmetaL, we have created the libraries *CTLlibrary.asm* and *LTLlibrary.asm* where, for each CTL and LTL operator, an equivalent function is declared.

CTLlibrary.asm

Mapping of CTL operators into CTL functions

NuSMV CTL operator	AsmetaL CTL function
EG p	static eg: Boolean \rightarrow Boolean
EX p	static ex: Boolean \rightarrow Boolean
EF p	static ef: Boolean \rightarrow Boolean
AG p	static ag: Boolean \rightarrow Boolean
AX p	static ax: Boolean \rightarrow Boolean
AF p	static af: Boolean \rightarrow Boolean
E[p U q]	static e: Prod(Boolean, Boolean) \rightarrow Boolean
A[p U q]	static a: Prod(Boolean, Boolean) \rightarrow Boolean

LTLlibrary.asm

Mapping of LTL operators into LTL functions

NuSMV LTL operator	AsmetaL LTL function
X p	static x: Boolean \rightarrow Boolean
G p	static g: Boolean \rightarrow Boolean
F p	static f: Boolean \rightarrow Boolean
p U q	static u: Prod(Boolean, Boolean) \rightarrow Boolean
p V q	static v: Prod(Boolean, Boolean) \rightarrow Boolean
Y p	static y: Boolean \rightarrow Boolean
Z p	static z: Boolean \rightarrow Boolean
H p	static h: Boolean \rightarrow Boolean
O p	static o: Boolean \rightarrow Boolean
p S q	static s: Prod(Boolean, Boolean) \rightarrow Boolean
p T q	static t: Prod(Boolean, Boolean) \rightarrow Boolean

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Mapping example

```
asm ctIExample
import ./StandardLibrary
import ./CTLlibrary

signature:
  dynamic controlled fooA: Boolean
  dynamic controlled fooB: Boolean
  dynamic monitored mon: Boolean

definitions:
  CTLSPEC ag(fooA iff ax(not(fooA))) //true
  CTLSPEC ag(not(fooA) iff ax(fooA)) //true
  //false. Gives counterexample.
  CTLSPEC not(ef(fooA != fooB))

  main rule r_Main =
    par
      fooA := not(fooA)
      if(mon) then
        fooB := not(fooB)
      endif
    endpar

default init s0:
  function fooA = true
  function fooB = true
```

AG specific node per is SAFETY

```
MODULE main
VAR
  fooA: boolean; —controlled
  fooB: boolean; —controlled
  mon: boolean; —monitored
ASSIGN
  init(fooA) := TRUE;
  init(fooB) := TRUE;
  next(fooA) := !(fooA);
  next(fooB) :=
    case
      (mon): !(fooB);
      TRUE: fooB;
    esac;

—CTL properties
CTLSPEC AG(fooA <=> AX(!(fooA)));
CTLSPEC AG(!(fooA) <=> AX(fooA));
CTLSPEC !(EF(fooA != fooB));
```

Execution

```
[user@localhost asmetasmv]$ NuSMV ctlExample.smv
*** This is NuSMV 2.5.2 (compiled on Sat Oct 30 12:18:33 UTC 2010)
*** Enabled addons are: compass
*** For more information on NuSMV see <http://nusmv.fbk.eu>
*** or email to <nusmv-users@list.fbk.eu>.
*** Please report bugs to <nusmv-users@fbk.eu>

-- specification AG (fooA <-> AX !fooA)  is true
-- specification AG (!fooA <-> AX fooA)  is true
-- specification !(EF fooA != fooB)    is false
-- as demonstrated by the following execution sequence
Trace Description: CTL Counterexample
Trace Type: Counterexample
-> State: 1.1 <-
    fooA = TRUE
    fooB = TRUE
    mon  = FALSE
-> State: 1.2 <-
    fooA = FALSE
```

Mapping invariants

AsmetaL Model

```
asm ag
import ./StandardLibrary
import ./CTLlibrary

signature:
  dynamic controlled fooA: Boolean
  dynamic controlled fooB: Boolean

definitions:

  //invariant for simulation with AsmetaS
  invariant over fooA, fooB: fooA != fooB

  //property for NuSMV
  CTLSPEC ag(fooA != fooB)

  main rule r_Main =
    par
      fooA := not(fooA)
      fooB := not(fooB)
    endpar

  default init s0:
    function fooA = true
    function fooB = false
```

NuSMV Model

```
MODULE main
  VAR
    fooA: boolean; —controlled
    fooB: boolean; —controlled
  ASSIGN
    init(fooA) := TRUE;
    init(fooB) := FALSE;
    next(fooA) := !(fooA);
    next(fooB) := !(fooB);
  —CTL properties
  CTLSPEC AG(fooA != fooB);
```

Execution of the NuSMV Model

```
[user@localhost code]$ NuSMV ag.smv
*** This is NuSMV 2.4.1 (compiled on Sat Jun 13 10:57:42 UTC 2009)
*** For more information on NuSMV see <http://nusmv.irst.itc.it>
*** or email to <nusmv-users@irst.itc.it>.
*** Please report bugs to <nusmv@irst.itc.it>.

-- specification AG fooA != fooB is true
```

Verification properties

- Reachability property
 - Safety property
 - Liveness property
 - Absence of deadlock
 - Other property to guarantee correctness of specification
-
- They have precise specification patterns

Reachability Property

- Reachability: “exists a future state satisfying a property φ ”
 - φ is called “present tense formula” (no temporal operators inside)
 - For instance, “A process will enter its critical section”
- In CTL $EF\varphi$
 - $EF \text{ critical}_1$

Safety property

- Safety: “Nothing bad will happen”.
 - For instance, “Only one process is in its critical section at any time”.
- In CTL $AG\phi$
 - (with 2 processes only):
 - $AG(\neg(\text{critical1} \wedge \text{critical2}))$

Liveness property

- Liveness: “Something good will eventually happen”.
 - For instance: “Whenever any process requests to enter its critical section, it will eventually be permitted to do so”.
- In CTL $AG + AF$ or $AG + EF$
 - $AG(\text{request} \rightarrow AF(\text{critical}))$

Deadlock absence

- In CTL $AG\ EX\ true$
 - whatever the status reached (AG), there is a status immediately successor ($EX\ true$)
 - No deadlock

Examples

- Ferryman
 - Counter example for the well-known path
- Tic tac toe
- Children
- SwapBoard