



Post-Processors : Config. Tags
<ul style="list-style-type: none">• Load dataset : <code>_LOAD_CANDIDATES</code>• Distance filter : <code>_DISTANCE_FILTER</code>• Tool center point angle twin: <code>_TCP_ANGLE_TWAIN</code>• Object angle twin: <code>_OBJ_ANGLE_TWAIN</code>• Graspit viewer: <code>_GRASPIT_VIEWER</code>• ROS viewer: <code>_ROS_VIEWER</code>

Caption

Event

Action

Decision

Start

Flow Success

Flow Unsuccess

Notes

Finish