Mimic Grasping

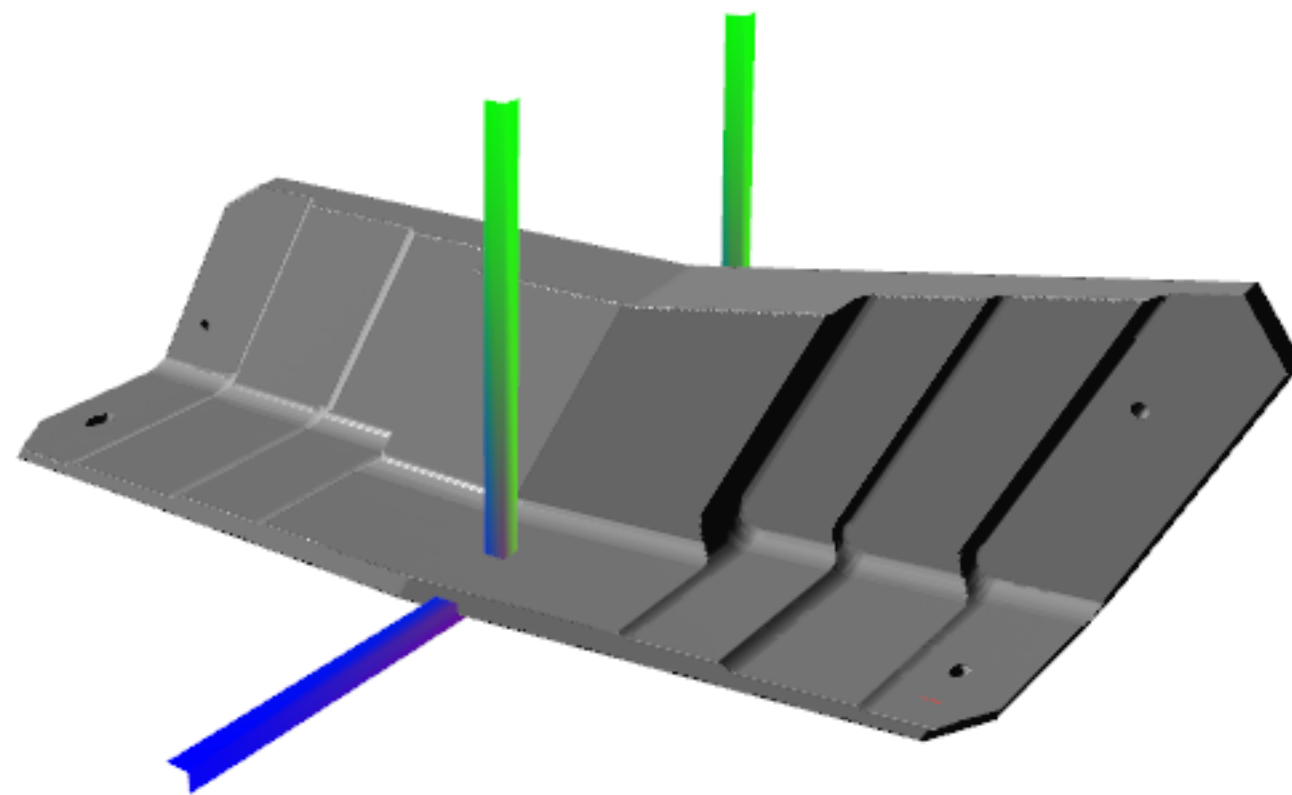Start   Finish   Export

3D Visualization:

<< >> Home   candidate_2   Total: 3

Output:

Firmware State: Not Initialized

[19:52:27] home
[19:52:27] Setup process has been completed.
[19:52:28] Initializing tool firmware communication...
[19:52:30] Initializing object localization plugin...
[19:52:32] Initializing tool localization plugin...
[19:52:33] ONE_SHOOT method active. Running object localization...
[19:52:51] Object detected.
[19:52:55] Initialization has been completed. Teaching process started.
[19:52:59] Save pose request received. Running tool localization...
[19:52:59]
[19:55:16] Save pose request received. Running tool localization...
[19:55:16]
[19:55:43] Save pose request received. Running tool localization...
[19:55:43]
[19:55:57] Finishing...
[19:55:59] Closed.