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/home/joaopedro/ros_ws/catkin_bin_picking_ws/src/grasp_synthesis/launch/run_manual_example.l
joaopedro@hp: ~
/home/joaopedro/ros_ws/catkin_bin_picking_ws/src/grasp_synthesis/launch/run_manual_example.launch http://local
Creating links
Link 0
Link 1
Creating dynamic joints
No normalization data found; using factors of 1.0
Read 1 eigengrasps from EG file
Using eigengrasps from file: eigen/eigen.xml
Loaded virtual contacts from file virtual/contacts7.xml
[ INFO] [1594310815.189875463]: Loading gripper model: /home/joaopedro/ros_ws/catkin_bin_pickin
[ INFO] [1594310815.206040909]: Positioning the robot
[ INFO] [1594310815.206096432]: > World loaded successfully
[ WARN] [1594310815.206127959]: #####
[ INFO] [1594310815.206142173]: > Initializing interface
[ WARN] [1594310815.206166829]: #####
[ WARN] [1594310815.206188192]: c -> close gripper
[ WARN] [1594310815.206204782]: o -> open gripper
[ WARN] [1594310815.206218611]: r -> record
[ WARN] [1594310815.206232329]: d -> delete
[ WARN] [1594310815.206248067]: e -> exit
[ WARN] [1594310815.206266456]: #####
[ INFO] [1594310879.194288953]: Closing the gripper:
c
[ INFO] [1594310880.872358808]: Opening the gripper:
o
[ INFO] [1594310886.522802679]: Closing the gripper:
c
[ INFO] [1594310888.003661561]: Opening the gripper:
o
[ INFO] [1594310892.443915156]: Closing the gripper:
c
[ INFO] [1594310902.171866980]: Opening the gripper:
o
[ INFO] [1594310908.337618295]: Opening the gripper:
o
[ INFO] [1594310913.553392167]: Closing the gripper:
c
[ INFO] [1594310914.842602351]: Opening the gripper:
o
[ INFO] [1594310938.915160225]: Closing the gripper:
c
[ INFO] [1594310970.027148796]: Opening the gripper:
o
[ INFO] [1594310976.144078193]: Closing the gripper:
c
[ INFO] [1594310995.281794187]: Opening the gripper:
o
[ INFO] [1594311003.737276310]: Closing the gripper:
c
[ INFO] [1594311019.665372259]: Opening the gripper:
o
[ INFO] [1594311036.713740906]: Closing the gripper:
c
[ INFO] [1594311057.068129876]: > Recording...
[ INFO] [1594311057.076091473]: Getting gripper data
created new L1 Norm GWS.
deleting GWS
[ INFO] [1594311057.662082304]: Calculating Quality
[ INFO] [1594311057.662130976]: Current Eps Quality: -1
[ INFO] [1594311057.662149568]: Current Vol Quality: 9.92837e-06
[ INFO] [1594311058.254504356]: Invalid Energy Type
[ INFO] [1594311058.254758301]: Calculating Energy
[ INFO] [1594311058.254823188]: Current Energy: 0
[ INFO] [1594311058.254857785]: Grasp Candidate #1 added.
```