

Grasping Framework

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graph TD; A[Grasping Framework] --> B[Grasping Synthesis<br/>Collection of tools to generate feasible grasps candidates in dataset fashion.<br/>Offline Architecture]; A --> C[Grasping Selection<br/>Evaluate generated grasp with task-oriented analysis.<br/>Run-time Architecture];
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Grasping Synthesis

Collection of tools to generate feasible grasps candidates in dataset fashion.

Offline Architecture

Grasping Selection

Evaluate generated grasp with task-oriented analysis.

Run-time Architecture