





## elevator control.v

/home/itzzinfinity/Cozy Drive/100daysofRTL/day 097/project 1/project 1.srcs/sources 1/new/elevator control.v

```
Q
1
        `timescale 1ns / 1ps
2 🖨
        3 ¦
        // Engineer: Anjan Prasad
4
        // Create Date: 12/27/2024 09:40:53 AM
5 ¦
        '// Module Name: elevator control
6 🖒
        7
8 🖨
        module elevator_control(
9
           input clk,
10
            input reset,
11
            input [3:0] floor request, // Requested floor (1 to 4)
12
            input emergency stop,
13
            output reg [1:0] state,
14
            output reg [1:0] current floor,
15
            output reg door open
16
        );
17
18
           localparam IDLE
                                = 2'b00,
                      MOVING UP = 2'b01.
19
20
                      MOVING DOWN = 2'b10,
21
                      DOOR OPEN = 2'b11;
22
23
            reg [3:0] target floor; // Holds the requested floor
24
25 🖨
            always @(posedge clk or posedge reset) begin
26 🖨
               if (reset) begin
     0
27
                   state <= IDLE;
28
                   current floor <= 2'b01; // Assume starting at floor 1</pre>
29
                   door open <= 0;
30
                   target floor <= 4'b0;
     \circ
31 🖨
               end else if (emergency stop) begin
32
     0
                   state <= IDLE;
33 ¦
     0
                   door open <= 1;
34 🖨
     0
               end else begin
35 🖨
                   case (state)
                       IDLE: begin
36 🖨
     0
37 🖨
                          if (floor request != current floor) begin
38
     \circ
                              target floor <= floor request;
     0
39 🖨
                              if (floor request > current floor)
     0
40
                                  state <= MOVING UP;
     0
41
                              else
42 🖨
                                  state <= MOVING DOWN;
     0
43 🖒
                          end
44
                       end
45 🖨
                       MOVING UP: begin
46 🖨
                          if (current floor == target floor) begin
47
     0
                              state <= DOOR OPEN;
     0
48
                              door open <= 1;
     0
49 🖨
                          end else begin
50
                              current floor <= current floor + 1;
```

## elevator\_control.v

/home/itzzinfinity/Cozy Drive/100daysofRTL/day\_097/project\_1/project\_1.srcs/sources\_1/new/elevator\_control.v

```
50
                                   current_floor <= current_floor + 1;
51 <u>|</u>
      0
                              end
                          end
53 ⊖
                          MOVING DOWN: begin
54 Ď
                              if (current floor == target floor) begin
55 l
      0
                                   state <= DOOR OPEN;
      0
56
                                   door open <= 1;
57 🖨
      0
                              end else begin
58
                                   current_floor <= current_floor - 1;
59 🖒
      0
                              end
60 🛆
                          end
61 ₫
                          DOOR OPEN: begin
62
                              door open <= 0;
63
      0
                              state <= IDLE;
64 🖒
                          end
65 🛆
                      endcase
66 🛆
                  end
67 🛆
              end
68
         endmodule
69
70
71
72
73
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```

## elevator\_control\_tb.v

/home/itzzinfinity/Cozy Drive/100daysofRTL/day 097/project 1/project 1.srcs/sim 1/new/elevator control tb.v

```
Q
                    1 📥
        `timescale 1ns / 1ps
2 🖨
       3 ¦
        // Engineer: Anjan Prasad
4
       // Create Date: 12/27/2024 09:42:00 AM
5 ¦
        // Module Name: elevator control tb
6 🖒
        7
8
        module elevator_control_tb;
9
10
           reg clk;
11
           reg reset;
12
           reg [3:0] floor request;
13
           reg emergency stop;
14
           wire [1:0] state;
15
           wire [1:0] current floor;
           wire door_open;
16
17
18
           elevator control DUT (
19
               .clk(clk),
20
               .reset(reset),
21
               .floor request(floor request),
22
               .emergency_stop(emergency_stop),
23
               .state(state),
24
               .current_floor(current_floor),
25
               .door open(door open)
26
           );
27
28
           always \#5 clk = \simclk;
     0
29
30
           initial begin
31
32
               clk = 0;
33
     0
               reset = 1:
34
     0
               floor_request = 0;
     0
35
               emergency stop = 0;
36
37
               #10 \text{ reset} = 0;
38
39
     0
40
               #10 floor request = 3;
41
               #50 floor request = 0;
42
     0
     0
43
               // Emergency stop
44
               #20 emergency stop = 1;
45
               #10 emergency stop = 0;
     0
46
47
               // Request floor 1
48
               #10 floor request = 1;
49
               #50 floor request = 0;
50
```

```
elevator_control_tb.v
/home/itzzinfinity/Cozy Drive/100daysofRTL/day_097/project_1/project_1.srcs/sim_1/new/elevator_control_tb.v
Q
                        50
      0
      Õ
51
                  // Request floor 4
52
                  #10 floor_request = 4;
53
                  #50 floor request = 0;
      0
54
      0
55
                  #50 $finish;
56
              end
      \bigcirc
57
58
              initial begin
         $monitor("Time: %0t | State: %b | Current Floor: %d | Door Open: %b | Emergency Stop:
59
                           $time, state, current_floor, door_open, emergency_stop);
60
      0
61
              end
62
         endmodule
63
64
65
66
67
68
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72
73
74
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76
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```