view_frames Result

Recorded at time: 1743498034.28406

base_footprint

Broadcaster: default_authority
Average rate: 15.673
Buffer length: 4.977
Most recent transform: 1743498034.201793
Oldest transform: 1743498029.225002

Broadcaster: default_authority
Average rate: 50.641
Buffer length: 1.56
Most recent transform: 35.883
Oldest transform: 34.323

base_link

sphere_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 15.374
Buffer length: 1.496
Most recent transform: 35.836
Oldest transform: 34.34

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

counterweight

head_x_link

imu_base_link

supports

wheel_connector

Broadcaster: default_authority
Average rate: 15.374
Buffer length: 1.496
Most recent transform: 35.836
Oldest transform: 34.34

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Buffer length: 0.0
Most recent transform: 0.0
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Broadcaster: default_authority
Average rate: 15.374
Buffer length: 1.496
Most recent transform: 35.836
Oldest transform: 34.34

head_y_link

support1_virtual

support2_virtual

support3_virtual

support4_virtual

support5_virtual

left_wheel

right_wheel

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

head

support1_sphere

support2_sphere

support3_sphere

support4_sphere

support5_sphere

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

lidar