### Machine learning from scratch Lecture 1: Mathematical background

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#### Before we start

IT STEP will be organizing a Tech night on **February 16th** (Thursday) from 7pm. I will (probably) be giving a talk. The course will most likely be postponed.

In supervised learning tasks, we are given a data set of the form:

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- n is the size of the data set (number of instances/samples)
- In most applications:
  - $\mathcal{X} = \mathbb{R}^d$  (d is the dimensionality)
  - $\mathcal{Y} = \mathbb{R}$  (regression) or  $\mathcal{Y} \subset \mathbb{N}$  (classification)
- $ightharpoonup x \in \mathcal{X}$  is the *feature vector* and  $y \in \mathcal{Y}$  is the *label*

Solving a **supervised learning problem** is finding (or *learning*) a function (or *hypothesis*)  $h: \mathcal{X} \mapsto \mathcal{Y}$  such that for  $(\mathbf{x}, \mathbf{y}) \in D$ ,  $h(\mathbf{x})$  is a *good* estimation (or approximation) of  $\mathbf{y}$ .

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#### This raises 2 questions:

- ► How to define *h*?
- ▶ How to assess whether  $\hat{y}$  is a good approximation of y?

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- ▶ Linear model:  $h(x) = \theta^T x$
- ▶ Polynomial kernel (degree k):  $h(x) = (1 + \theta^T x)^k$
- Other kernels exist, more on this when we talk about duality
- ▶ With a **neural net**, more on this later as well
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How you define h highly depends on the application, for example:

- Sometimes a lot of data preprocessing has been made and a simple model (e.g. linear) would work well
- ➤ You might have **time/hardware constraints**: In this case going for a too complex model might be crippling
- ► For neural net, the architecture depends a lot on the type of data you have

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Illustration of the introduced notations:

- $ightharpoonup \mathcal{X}=\mathbb{R}^2$  (d=2 dimensions: living area and # bedrooms)
- $ightharpoonup \mathcal{Y} = \mathbb{R}$  (regression task)
- $\mathbf{x}^{(1)} = [50, 1]^T$  and  $\mathbf{y}^{(1)} = 30000$

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Using a linear regression model gives

$$h_{\theta}(\mathbf{x}) = \theta_0 + \theta_1 x_1 + \theta_2 x_2$$

Generalization to any dimensionality d:

$$h(\mathbf{x}) = \sum_{j=0}^{d} \theta_{j} x_{j} = \theta^{T} \mathbf{x}$$

Here, we set  $\mathbf{x}_0 = 1$  so that  $\theta_0$  is included in  $\theta$ .  $\theta^T \mathbf{x}$  is called the dot product (or inner product) between *theta* and  $\mathbf{x}$  and is sometimes noted  $\langle \theta, \mathbf{x} \rangle$ .

#### Ordinary least squares

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Suppose we chose the following loss function:

$$\ell(y,\hat{y}) = \frac{1}{2}(y - \hat{y})^2$$

This leads to the following least squares cost function:

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} \left( h\left(\mathbf{x}^{(i)}\right) - y^{(i)} \right)^{2}$$

This problem the ordinary least squares (OLS) regression model.

### Least Mean Squares (LMS) update rule

We want to minimize the following cost function:

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} \left( h\left(\mathbf{x}^{(i)}\right) - y^{(i)} \right)^{2}$$

One way to do it is by using the gradient descent algorithm:

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_i} J(\theta)$$

for all  $j \in \{0, ..., d\}$ .  $\alpha$  is called the **step size** or the **learning** rate. This update rule can be rewritten in a more compact way:

$$\theta := \theta - \alpha \nabla J(\theta)$$

where  $\nabla J(\theta)$  is the **gradient** of J in  $\theta$ . We have, by definition:

$$\nabla J(\theta) = \left[\frac{\partial}{\partial \theta_1} J(\theta), \dots, \frac{\partial}{\partial \theta_d} J(\theta)\right]^T$$

#### Loss functions

Recall we want to know whether y a good prediction of  $\hat{y}$ .

# Regularization

### Optimization

Now, we want to minimize a function of the form

$$J(\theta) = \sum_{i=1}^{n} \ell\left(y^{(i)}, \hat{y}^{(i)}\right) + \lambda R(\theta) \tag{1}$$

#### Conclusion

Next week we will implement some of the concepts we've seen today.

# Thank you! Questions?

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https://github.com/azubiolo/itstep