

Introduction to Machine Learning

Lecture 6: Conclusion

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Outline

This lecture includes:

- ▶ A **model selection** lab
- ▶ A few aspects of machine learning we have not mentioned
 - ▶ **Feature engineering**
 - ▶ **Dimensionality reduction**
- ▶ Feedback and final Q&A

Dimensionality reduction

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- ▶ There are too many features
- ▶ Some of the features bring no information

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Hence, there is a need to pre-process the data.

Dimensionality reduction

In case there are too many samples, a simple solution is to apply subsampling, e.g. just take into account 10% of the samples.

- ▶ Recall the mini-batch k -means
- ▶ Be careful with the **class balance**
 - ▶ Imbalanced classes: **subsample the majority class**
 - ▶ Little to no imbalance: **Stratified sampling**

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It is also important to use common sense and expert knowledge when possible:

- ▶ Some variables might be intuitively meaningless to solve the ML problem
- ▶

Dimensionality reduction with PCA

PCA = Principal Component Analysis

Dimensionality reduction with PCA

PCA = Principal Component Analysis

Rough idea:

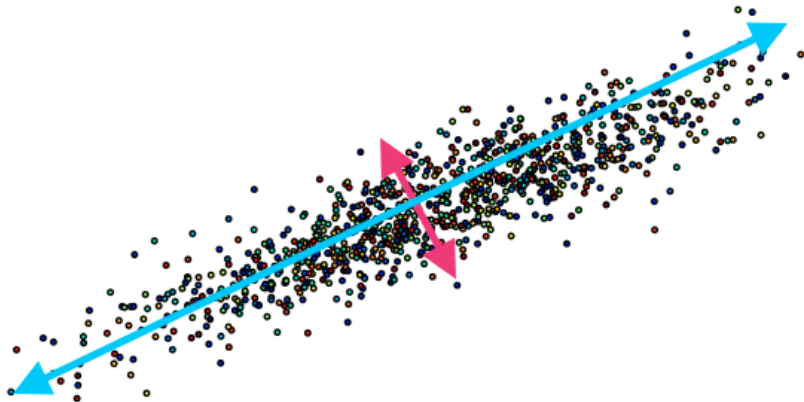
- ▶ Find high variance axes
- ▶ Select the k axes with the highest variances
- ▶ Project the data on these axes

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Feature engineering

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Feature engineering is often **data-dependent**: You won't use the same features from text data and from images or videos.

Feature engineering in text analysis: TF-IDF

There are several challenges when dealing with text data:

- ▶ Mining text can lead to a huge amount of data to process
- ▶ Not all the data is relevant
- ▶ Texts can be of different size
- ▶ ...

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Hence, there is **a need to preprocess** it before giving it to any ML algorithm.

Feature analysis in image processing

In images, we often want to detect interest points such as **edges** and **corners**.

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- ▶ (Affine) intensity change

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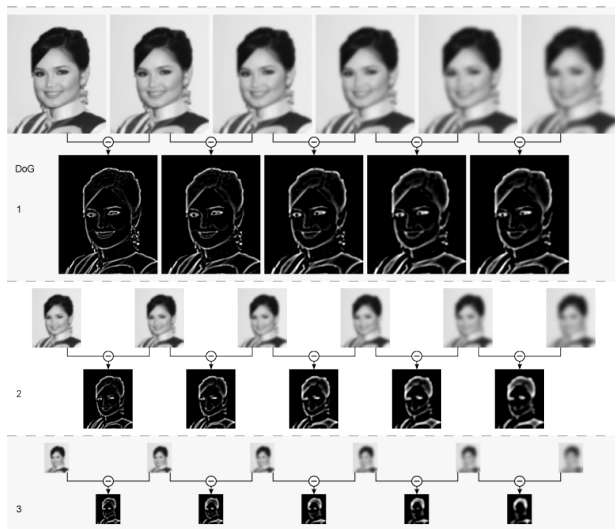
SIFT is patented and cannot be used in all situations: There exist alternatives based on the same idea such as SURF (Speeded-Up Robust Features)

SIFT algorithm

Key steps:

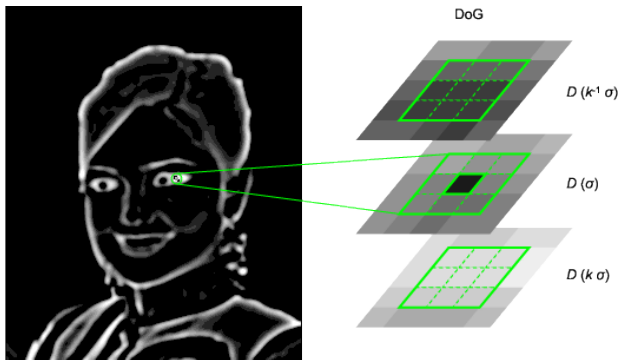
- ▶ Detect extrema at different scale by difference of gaussians
- ▶ Detect interest points in the image
- ▶ Assign orientations to create SIFT features

SIFT: Difference of Gaussians (DoG)



SIFT: Extrema detection

Interest points are among the local extrema in the $3 \times 3 \times 3$ neighborhood:



SIFT: Extrema detection

Post-processing:

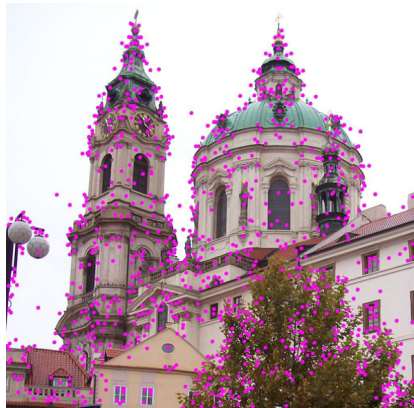
- ▶ Remove low-contrast points
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SIFT: Extrema detection

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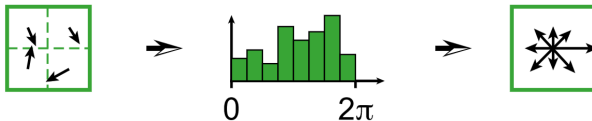
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Before/after:

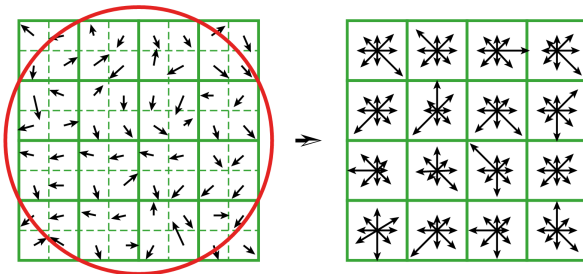


SIFT: Orientation assignment

For each interest point, compute the orientation histogram:



Do it for a neighborhood of the interest point:



SIFT applications

SIFT has other applications, such as aligning images, creating panoramas, video tracking, ...

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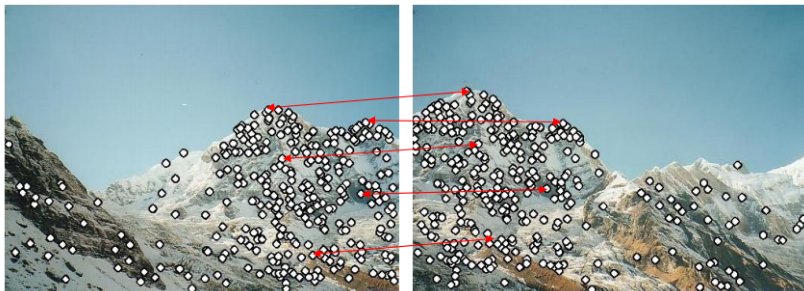
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YouTube video example

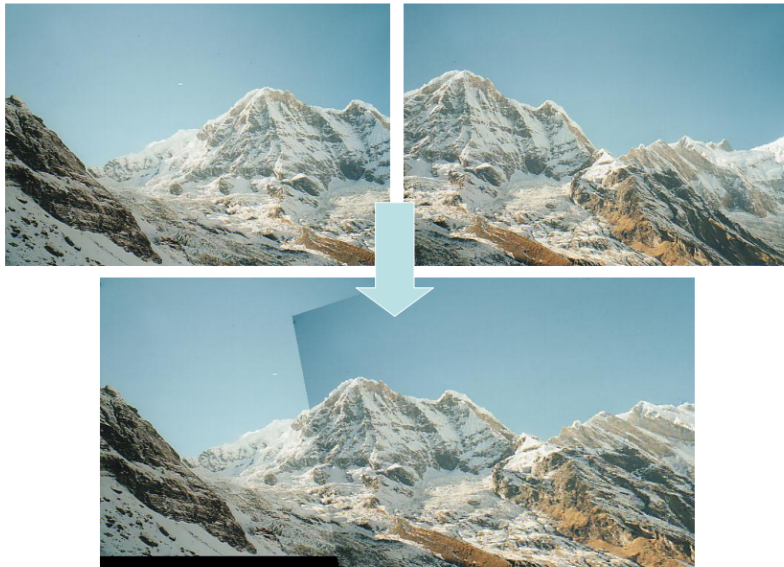
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SIFT illustration: Panorama



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There's **no general-purpose solution** (at least for now): It is important to **look at the data** and **adapt to the situation**.

Thank you! Questions?
Any feedback?