Modeling with Differential Equations

Section 9.1

Outline

- Models of Population Growth
- A Model for the Motion of a Spring
- General Differential Equations

Modeling with Differential Equations

- Scientists usually formulate a mathematical model of a real world problem based on physical laws or intuitive reasoning about the phenomenon.
- The mathematical model often takes the form of a *differential equation*, that is, an equation that contains an unknown function and some of its derivatives.

• One model for the growth of a population is based on the assumption that the population grows at a rate proportional to the size of the population. This is reasonable under ideal conditions (unlimited environment, adequate nutrition, absence of predators, immunity from disease).

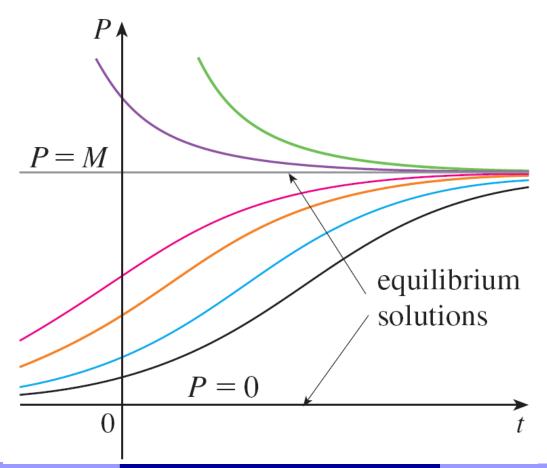
 $\frac{dP}{dt} = kP$ where k is the proportionality constant.

- ▶ A more realistic model must reflect the fact that a given environment has limited resources.
- ▶ We observe that many populations start by increasing in an exponential manner but the population levels off when it approaches its carrying capacity M (or decreases toward M if it ever exceeds M).

- We make two assumptions:
- $\blacktriangleright \frac{dP}{dt} \approx kP$ if P is small (Initially, the growth rate is proportional to P .)
- $lack rac{dP}{dt} < 0 \ \ {
 m if} \ \ P > M \ (\ P \ {
 m decreases} \ {
 m if} \ {
 m it} \ {
 m ever} \ {
 m exceeds} \ M$.)
- ▶ The *logistic differential equation*:

$$\frac{dP}{dt} = kP(1 - \frac{P}{M})$$

▶ Solutions for the *logistic differential equation*:



Prop Suppose that y'(t) = f(y) where f is continuous. y(t) = y, is a constant solution of the D.E. if $f(y_0) = 0$.

$$\mathbf{E}_{\mathbf{X}}$$
: The function $y(t)$ satisfies the differential equation

Find all constant solutions
$$\frac{dy}{dt} = y^4 - y^3 - 56y^2$$

A Model for the Motion of a Spring

- Hooke's Law says that if the spring is stretched (or compressed) x units from its natural length, then it exerts a force that is proportional to x: restoring force = -kx.
- By Newton's Second Law (force equals mass times acceleration), we have

$$m\frac{d^2x}{dt^2} = -kx$$

General Differential Equations

- In general, a differential equation is an equation that contains an unknown function and one or more of its derivatives.
- The order of a differential equation is the order of the highest derivative that occurs in the equation.

General Differential Equations

- A function f is called a **solution** of a differential equation if the equation is satisfied when y = f(x) and its derivatives are substituted into the equation.
- When we are asked to *solve* a differential equation we are expected to find all possible solutions of the equation.

General Differential Equations

- In many physical problems we need to find the particular solution that satisfies a condition of the form $y(t_0)=y_0$.
- ▶ This is called an **initial condition**, and the problem of finding a solution of the differential equation that satisfies the initial condition is called an **initial-value problem**.

Ex: Suppose that there is a chemical reaction

A+B -> C. Let x(t) be [C] at time t.

Assume that x'(+) is proportional to the product

of [A] and [B] and [A](0) = a, [B](0) = b.

Derive a differential equation for x(+).

Review

- What is a differential equation?
- What is the order of a differential equation?
 What is an initial value problem?