Unsupervised Learning: Introduction



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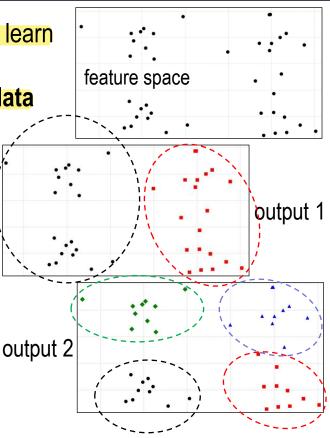
- Problem description
- Definition of clustering
- Proximity measures

Problem description

In unsupervised learning (UL), a program does not learn from labelled data. Instead, it attempts to discover patterns in the data, i.e. learn the structure of the data

bring out patterns and structure within the data,
 maybe informative by itself
 or serve as a guide to further analysis,
 e.g. learn features to build a supervised classifier

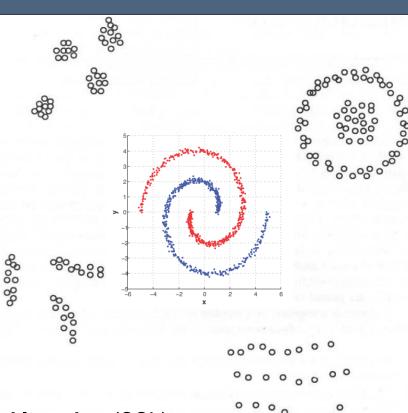
- known as exploratory analysis or knowledge discovery
- Using UL terminology: discover groups of related observations within the data called clusters
 - clustering or cluster analysis
 - assigns observations into groups such that samples in the same group are most similar to one another
 - e.g. discover segments of customers (marketing)
- More widely applicable than supervised learning: no need for labelled data
- Other names: Numerical taxonomy (biology), Typology (social sci.), Partitioning (graphs th.)



Problem description

- Meaningful clusters can be of diverse shapes:
 - This is problem dependent,
 i.e. problem semantics
 - Humans are very good at detecting clusters in two and three dimensions

- SL and UL can be thought as occupying opposite ends of a spectrum
- A different approach called semi-supervised learning (SSL)
 makes use of both supervised and unsupervised learning
 - The dataset is partially labelled
 - Located somewhere in-between SL and UL

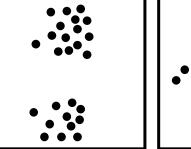


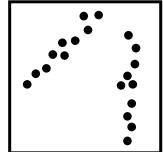
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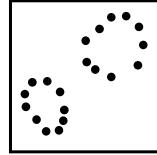
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Definition of clustering

- A cluster consists of a number of similar objects, given a certain similarity criterion.
- Other definitions (collected from here and there):
 - A cluster is a set of entities which are alike, while entities from different clusters are not alike
 - A cluster is an aggregation of **points** in the test space such that the distance between points in the same cluster is less than the distance between any point in the cluster and any point not in it
 - Clusters may be described as connected regions of a multi-dimensional space containing a relatively high density of points, separated from other such regions by a region containing a relatively low density of points
- A number of definitions based on rather vaguely defined terms which lead to a bunch of algorithms.
- In any case, the goal is to find the natural structure of the data, similarly to the human skill of grouping points in 2D/3D space, but for any amount of dimensions.







Definition of clustering

• Given a set of samples $X = \{x_1, x_2, ..., x_N\}$ defined in an L-dimensional space, a first **non-universal**, **but formal definition** of clustering would be as follows: an M-grouping of X is a partition of X into M sets C_1 , C_2 , ..., C_M , so that

$$(1) \quad C_i \neq \emptyset, \quad i = 1, \dots, M$$

$$(2) \quad \bigcup_{i=1}^{M} C_i = X$$

(3)
$$C_i \cap C_j = \emptyset$$
, $i \neq j$, $j = 1, \ldots, M$

- (4a) $d(a,b) < d(a,c), a,b \in C_i, c \in C_j$ [where $d(\cdot,\cdot)$ is a dissimilarity measure]
- (4b) $s(a,b) > s(a,c), \quad a,b \in C_i, \ c \in C_j$ [where $s(\cdot,\cdot)$ is a similarity measure]
- Summing up, a clustering problem involves:
 - A set of unlabelled samples
 - A proximity measure (either a similarity s or a dissimilarity d)
 - A clustering algorithm, from the many alternatives readily available:

- hierarchical 4. density-based 7. valley-seeking
- 2. optimization-based 5. graph-based 8. sequential

- 3. model-based
- 6. competitive
- 9. others ...

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- The proximity measure chosen plays a central role in cluster analysis
- Formal definition of similarity measure (SM) / dissimilarity measure (DM)
 - A dissimilarity measure d among elements of a set X is a function such that:

A dissimilarity measure d among elements of a set X is a function such that:
$$d: X \times X \to \mathbb{R}$$

$$= \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2}$$
 and
$$(1) \quad \exists d_0 \in \mathbb{R} : -\infty < d_0 \le d(a,b) < +\infty, \forall a,b \in X$$
 e.g. $d_0 = 0$
$$(2) \quad d(a,a) = d_0, \forall a \in X$$
 (the more dissimilar, the greater)
$$(3) \quad d(a,b) = d(b,a), \forall a,b \in X$$

A similarity measure s among elements of a set X is a function such that:

$$s: X \times X \to \mathbb{R}$$

and (1)
$$\exists s_0 \in \mathbb{R}: -\infty < s(a,b) \leq s_0 < +\infty, \forall a,b \in X$$
 e.g. s_0 = 1 (2) $s(a,a) = s_0, \forall a \in X$ (the more similar,

(3)
$$s(a,b) = s(b,a), \forall a,b \in X$$
 (the more similar, the greater)

 $s(a,b) = e^{-\|a-b\|}$

proximity

measure

over X

 $\wp: X \times X \to \mathbb{R}$

- The concept can be extended to measure proximity between sets (clusters)
- Formal definition of similarity measure (SM) / dissimilarity measure (DM)

$$\begin{array}{l} {\mathcal P}(\{0,1,2\}) = \\ \left\{\emptyset,\{0\},\{1\},\{2\},\\ \{0,1\},\{0,2\},\{1,2\},\\ \left\{0,1,2\}\right\}\right\} \end{array} \text{ and } \begin{array}{l} (1) \quad \exists d_0 \in \mathbb{R} : -\infty < d_0 \leq d(U,V) < +\infty, \forall U,V \in \mathcal P(X) \\ (2) \quad d(U,U) = d_0, \forall U \in \mathcal P(X) \end{array} \\ \text{ (2)} \quad d(U,V) = d(V,U), \forall U,V \in \mathcal P(X) \\ \text{ (3)} \quad d(U,V) = d(V,U), \forall U,V \in \mathcal P(X) \end{array} \\ \text{ (4)} \quad \text{(4)} \quad \text{(5)} \quad \text{(6)} \quad \text{(6)}$$

$$s: \mathcal{P}(X) \times \mathcal{P}(X) \to \mathbb{R}$$

and (1)
$$\exists s_0 \in \mathbb{R} : -\infty < s(U, V) \le s_0 < +\infty, \forall U, V \in \mathcal{P}(X)$$

- $(2) \quad s(U,U) = s_0, \forall U \in \mathcal{P}(X)$
- (3) $s(U, V) = s(V, U), \forall U, V \in \mathcal{P}(X)$

(the more similar, the greater)

$$\wp: \mathcal{P}(X) \times \mathcal{P}(X) \to \mathbb{R}$$

- A more restrictive concept is that of metric
 - A **metric** m among elements of a set *X* is a function such that

$$m: X \times X \to \mathbb{R}$$

and (1)
$$\exists m_0 \in \mathbb{R} : -\infty < m_0 \le m(a, b) < +\infty, \forall a, b \in X$$
 (e.g. $m_0 = 0$)

- (2) $m(a,a) = m_0, \forall a \in X$
- (3) $m(a,b) = m(b,a), \forall a,b \in X$

(4)
$$m(a,b) \le m(a,c) + m(c,b), \forall a,b,c \in X$$
 (triangle inequality)

- Captures the notion of dissimilarity
- Not all dissimilarity measures are metrics
- An DM can be obtained from a SM using any monotonically decreasing function, e.g.

$$d(a,b) = \max\{s(a,b)\} - s(a,b)$$

- Examples of proximity measures:
 - weighted L_p metric (or Minkowski measure) DM

$$d_p(a,b) = \left(\sum_{i=1}^L w_i |a_i - b_i|^p\right)^{\frac{1}{p}}, w_i \ge 0$$

$$d_2(a,b) = \sqrt{\sum_{i=1}^L (a_i - b_i)^2} \quad \text{(metric L_2 or Euclidean distance)}$$

$$d_1(a,b) = \sum_{i=1}^L |a_i - b_i| \quad \text{(metric L_1 or Manhattan distance} \quad \text{or City Block distance)}$$

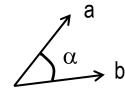
$$d_{\infty}(a,b) = \max_{1 \le i \le L} |a_i - b_i| \quad \text{(metric L_{∞} or Chebyshev distance)}$$

$$(= \lim_{p \to +\infty} d_p(a,b) \quad \text{if $w_i = 1$})$$

• Examples of proximity measures:

consider descriptors as nD-vectors instead of nD-points

– dot product – SM



Change of date of the exam

$$s_{\bullet}(a,b) = a^{T}b = \sum_{i=1}^{L} a_{i}b_{i} = ||a|| ||b|| \cos \alpha, ||a||, ||b|| \le m, \forall a, b \Rightarrow s_{\bullet} \in [-m^{2}, +m^{2}]$$

cosinus measure – SM

$$s_{\cos}(a,b) = \frac{a^T b}{\|a\| \|b\|}, \quad s_{\cos} \in [-1,+1], \quad s_{\cos}(a=\vec{0},b) = \frac{0}{0} \to 1$$

- Tanimoto measure - SM

$$s_{T}(a,b) = \frac{a^{T}b}{\|a\|^{2} + \|b\|^{2} - a^{T}b} = \frac{a^{T}b}{a^{T}a + b^{T}b - 2a^{T}b + a^{T}b}$$

$$= \frac{1}{1 + \frac{(a-b)^{T}(a-b)}{a^{T}b}} = \frac{1}{1 + \frac{(d_{2}(a,b))^{2}}{s_{\bullet}(a,b)}}$$

$$s_{T}(a,a) = \frac{1}{1 + \frac{0}{m^{2}}} = 1, \quad s_{T}(a,-a) = \frac{1}{1 + \frac{(2m)^{2}}{m^{2}}} = -\frac{1}{3}$$

- The previous proximity measures are intended for quantitative, real-valued descriptors
- Other proximity measures for these kind of data are the following:
 - Canberra distance DM

$$d_{\text{can}}(a,b) = \sum_{i=1}^{L} \frac{|a_i - b_i|}{|a_i| + |b_i|}, \quad d_{\text{can}}(\vec{0}, \vec{0}) = \frac{0}{0} \to 0$$

Bray-Curtis distance (Sorensen distance) – DM

$$d_{\mathrm{bc}}(a,b) = \frac{\sum_{i=1}^{L} |a_i - b_i|}{\sum_{i=1}^{L} (a_i + b_i)} \quad [\text{intended for } a_i, b_i \ge 0, \forall i]$$

correlation coefficient – SM

$$s_{\text{corr}}(a,b) = \frac{\sum_{i=1}^{L} (a_i - \overline{a})(b_i - \overline{b})}{\sqrt{\sum_{i=1}^{L} (a_i - \overline{a})^2 \sum_{i=1}^{L} (b_i - \overline{b})^2}}, \quad \overline{a} = \frac{1}{L} \sum_{i=1}^{L} a_i, \ \overline{b} = \frac{1}{L} \sum_{i=1}^{L} b_i$$

$$a = (p, q), b = (-p, -q), s_{\text{corr}}(a, a) = 1, s_{\text{corr}}(a, b) = -1$$

- For other kinds of data we need other proximity functions
- Proximity functions for binary-valued descriptors, i.e. $a_i = yes/no$, e.g. a = (0, 0, 1, 1, 0) $m_{00}(a, b) = \text{number of features at value 0 both in } a \text{ and } b$ b = (0, 1, 1, 0, 1) $m_{01}(a, b) = \text{number of features at value 0 in } a \text{ and 1 in } b$

 $m_{10}(a,b) = \text{number of features at value 1 in } a \text{ and 0 in } b$

 $m_{11}(a,b) = \text{number of features at value 1 both in } a \text{ and } b$

Hamming/matching distances – DM

$$d_{\text{ham}} = 3 d_{\text{ham}} = \frac{3}{5} = 0.6$$

$$d_{\text{ham}}(a, b) = m_{01}(a, b) + m_{10}(a, b)$$

$$d_{\text{mat}}(a, b) = \frac{m_{01} + m_{10}}{m_{00} + m_{01} + m_{10} + m_{11}} \Big|_{(a, b)}$$

Jaccard's coefficient – SM (frequency of occurrence of 0s and 1s is not the same)

$$s_{\text{jac}} = \frac{1}{4} = 0.25 \quad s_{\text{jac}}(a, b) = \left. \frac{m_{11}}{m_{11} + m_{01} + m_{10}} \right|_{(a, b)}$$

Jaccard's distance – DM (frequency of occurrence of 0s and 1s is not the same)

$$d_{\text{jac}} = \frac{3}{4} = 0.75$$
 $d_{\text{jac}}(a, b) = 1 - s_{\text{jac}}(a, b) = \left. \frac{m_{01} + m_{10}}{m_{11} + m_{01} + m_{10}} \right|_{(a, b)}$

- Proximity functions for nominal/categorical variables, e.g. a_i = red | green | blue
 - Encode categorical values as binary values and make use of corresp. proximity functions
 - Example: a = (gender, colour) = (male | female, red | white | blue)
 - 1. gender $\to \{0, 1\}$, colour $\to \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ a = [male, red], b = [female, white], c = [female, blue] a = [0, (1, 0, 0)], b = [1, (0, 1, 0)], c = [1, (0, 0, 1)] $d_{\text{ham}}(a, b) = (1, 2) \to 1 + 2 = 3 \text{ or } d'_{\text{mat}}(a, b) = (1/1 + 2/3)/2 = 5/6$ $d_{\text{ham}}(a, c) = (1, 2) \to 1 + 2 = 3 \text{ or } d'_{\text{mat}}(a, c) = (1/1 + 2/3)/2 = 5/6$ $d_{\text{ham}}(b, c) = (0, 2) \to 0 + 2 = 2 \text{ or } d'_{\text{mat}}(b, c) = (0/1 + 2/3)/2 = 2/6$
- be careful with coding !! a = [male, red], b = [female, white], c = [female, blue] a = [0, (0, 0)], b = [1, (0, 1)], c = [1, (1, 0)] d(red, white) = d(red, blue) < d(red, blue) < d(white, blue) $d_{\text{ham}}(a, c) = (1, 1) \rightarrow 1 + 1 = 2 \text{ or } d'_{\text{mat}}(a, c) = (1/1 + 1/2)/2 = 3/4$ $d_{\text{ham}}(b, c) = (0, 2) \rightarrow 0 + 2 = 2 \text{ or } d'_{\text{mat}}(b, c) = (0/1 + 2/2)/2 = 1/2$

- Proximity functions for ordinal variables (i.e. there exists an order),
 e.g. a_i = excellent | good | average | poor
 - Encode ordinal values as real values and make use of corresp. proximity functions
 - Example:

```
a_i = \text{excellent}|\text{good}|\text{average}|\text{poor} \to 3 \mid 2 \mid 1 \mid 0 \to 1 \mid 2/3 \mid 1/3 \mid 0
a = [\text{excellent}, \text{average}, \text{average}], b = [\text{poor}, \text{good}, \text{average}]
a = [1, 1/3, 1/3], b = [0, 2/3, 1/3]
d_2(a, b)^2 = 1^2 + (1/3)^2 + 0^2 = 10/9 [Spearman distance]
d_1(a, b) = 1 + 1/3 + 0 = 4/3 [(Spearman) footrule distance]
```

Examples of proximity measures between points and clusters

$$\wp = DM \text{ or } SM$$

cluster has no representive

$$\wp_{\max}(a, C) = \max_{b \in C} \wp(a, b)$$

$$\wp_{\min}(a, C) = \min_{b \in C} \wp(a, b)$$

$$\wp_{\text{avg}}(a, C) = \frac{1}{n_C} \sum_{b \in C} \wp(a, b)$$



<u>cluster has a representative μ</u>

$$\wp_{\text{rep}}(a,C) = \wp(a,\mu_C)$$

where typically

$$\mu_C = \frac{1}{n_C} \sum_{b \in C} b$$

... at a formal level, they are relevant, but, at a practical level, proximity measures are more useful when defined between clusters



Examples of proximity measures between clusters

clusters have no representatives
$$\begin{cases} \wp_{\max}(C_1,C_2) = \max_{a \in C_1,b \in C_2} \wp(a,b) \\ \wp_{\min}(C_1,C_2) = \min_{a \in C_1,b \in C_2} \wp(a,b) \\ \wp_{\text{avg}}(C_1,C_2) = \frac{1}{n_1n_2} \sum_{a \in C_1} \sum_{b \in C_2} \wp(a,b) \end{cases}$$

each cluster has a representative
$$\mu$$

$$\begin{cases} \wp_{\mathrm{mean}}(C_1,C_2) = \wp(\mu_1,\mu_2) \\ \wp_{\mathrm{ward}}(C_1,C_2) = \sqrt{\frac{n_1n_2}{n_1+n_2}}\wp(\mu_1,\mu_2) \end{cases}$$

– Some of these functions may not be metric functions: e.g. \wp_{max} when \wp is a DM, \wp_{min} when \wp is an SM, or \wp_{avg} either if \wp is a DM or a SM

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