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Assignment 1

Hello dear students. You have successfully cloned the repo, great.

- Exercise 0: Warm up tasks.
- Exercise 1: Color spaces and morphological operators (Lecture 1)
- Exercise 2: Convolution and Canny Edge detection (Lecture 2)

Exercise 0 - Image-I/O

There are several python libraries for reading and displaying images. I recommend scikitimage. Execute the next cell and install missing libraries like scikit-image.

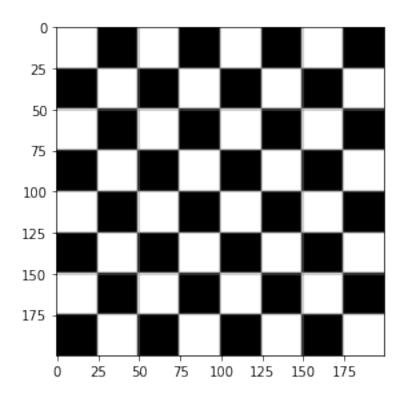
```
# imports
%matplotlib inline
from skimage import io, data, color
import matplotlib.pyplot as plt
import matplotlib.image as mpimg
import numpy as np
image = io.imread('images/dog.jpg')
io.imshow(image)
<matplotlib.image.AxesImage at 0x7fe0d26489a0>
```



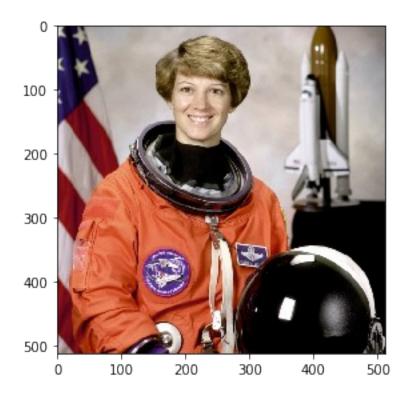
By the way, there are many test images in skimage.data that you can use for your tasks. Execute the next two cells.

io.imshow(data.checkerboard())

<matplotlib.image.AxesImage at 0x7fe0e81d0d90>

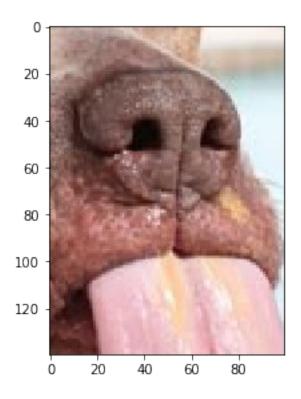


io.imshow(data.astronaut())
<matplotlib.image.AxesImage at 0x7fe0e81563d0>

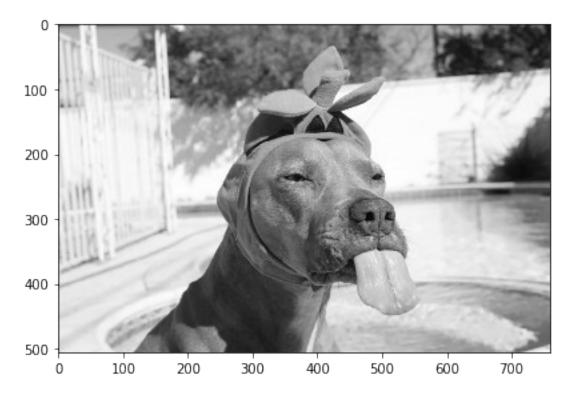


Add a line of code to the next cell to display $440 \le x \le 540$ and $250 \le y \le 390$ for the dog image!

```
image.shape
(506, 760, 3)
io.imshow(image[250:390,440:540,:])
<matplotlib.image.AxesImage at 0x7fe0e812d9a0>
```



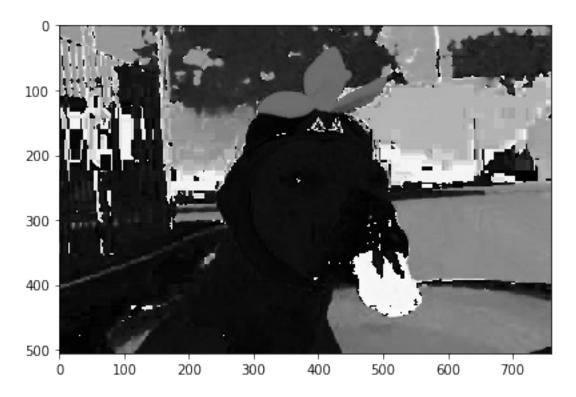
Now convert the color image to a grayscale image and display it!
io.imshow(color.rgb2gray(image))
<matplotlib.image.AxesImage at 0x7fe0e8093ee0>



There are other color spaces. For example, HSV will be used in the lecture. Convert your image to HSV and display the H-channel.

io.imshow(color.rgb2hsv(image)[...,0])

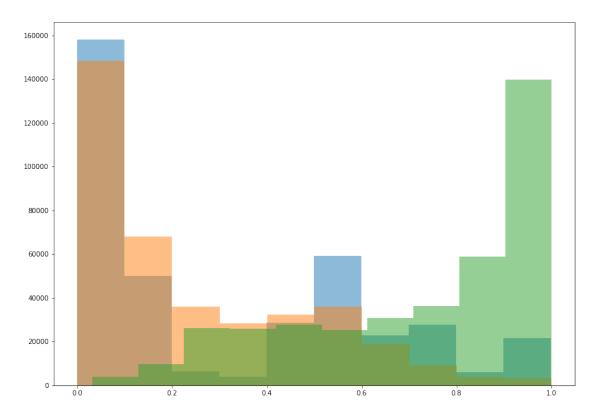
<matplotlib.image.AxesImage at 0x7fe0e37cc1c0>



Did you know that HSV now allows creating robust (i.e. lighting independent) color histograms? Create one with Matplotlib!

```
plt.figure(figsize = (14,10))
plt.hist(color.rgb2hsv(image)[...,0].flatten(), alpha= 0.5, label =
"Hue")
plt.hist(color.rgb2hsv(image)[...,1].flatten(), alpha= 0.5, label =
"Saturation")
plt.hist(color.rgb2hsv(image)[...,2].flatten(), alpha= 0.5, label =
"Value")

plt.legend
plt.show()
```



Exercise 1 - Color Spaces, Morphological Operators

Exercise 1.1

For an image of your choice, implement the simple binarization method as shown in the lecture. We've put some example images in /images and provided you with one in the next cell.

Rough sketch:

- 1. define the "positive" subspace P in the RGB cube
- 2. iterate over all pixels in I and check if in P or \sim P
- 3. write result to new image
- 4. play around with size and shape of P and display binary image (RESULT)

```
image = io.imread('images/bottles.png')
io.imshow(image)
```

<matplotlib.image.AxesImage at 0x7f7767869a90>

```
50 -

100 -

150 -

200 -

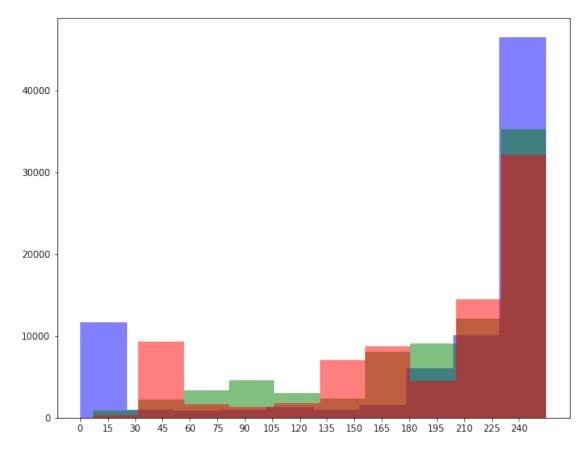
250 -

50 100 150 200 250
```

```
# plot color distribution
plt.figure(figsize = (10,8))
colors = ["b","g","r"]

for idx,i in enumerate(colors):
    plt.hist(image[...,idx].flatten(), color = i, alpha = 0.5)
    plt.xticks(range(0,255,15))

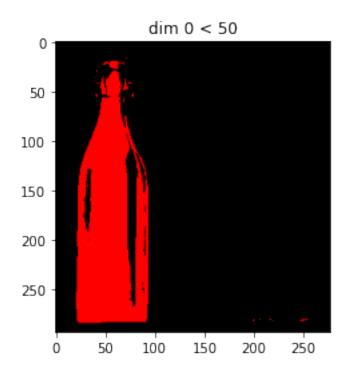
plt.show()
```



```
def binarization(image: np.ndarray, mask : tuple, used_dim: int,
description : str, plot : bool = True) -> np.ndarray:
    binarized_array = np.zeros_like(image)
    if used_dim == -1:
        binarized_array[mask[0], mask[1],:] = 255
    else:
        binarized_array[mask[0], mask[1],used_dim] = 255

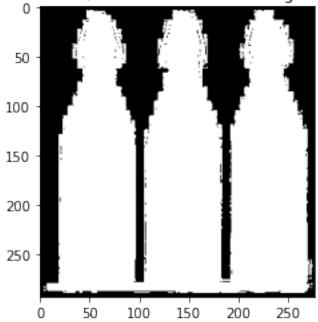
if plot:
    plt.imshow(binarized_array)
    plt.title(description)
    return binarized_array

mask = np.where(image[...,0] < 50)
binarized_array = binarization(image, mask, used_dim = 0, description = "dim 0 < 50")</pre>
```

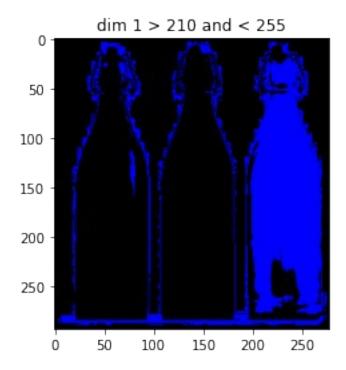


all three bottles
mask = np.where((image < 255))
binarized_array = binarization(image, mask, used_dim = -1, description
= "all dims < 255 (255 is the value of background color)")</pre>





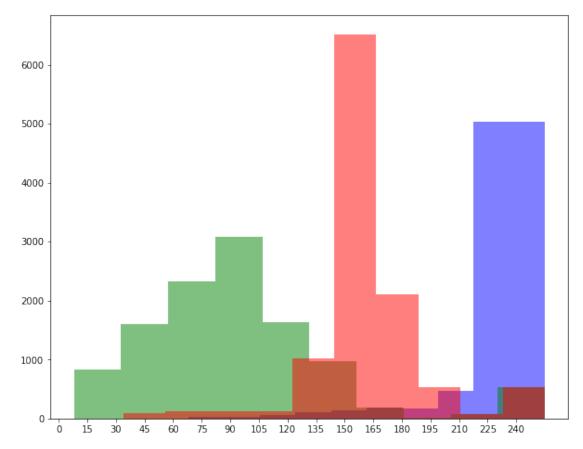
mask = np.where((image[...,1] > 210) & (image[...,1] < 255)) binarized_array = binarization(image, mask, used_dim = 2, description = "dim 1 > 210 and < 255")



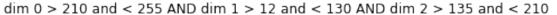
BGR ?

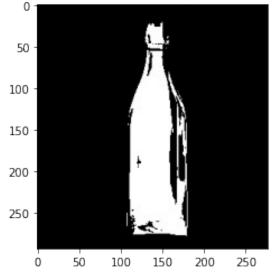
Bottle in the center

```
# plot color distribution of the center of the image (pink bottle)
plt.figure(figsize = (10,8))
colors = ["b", "g", "r"]
for idx,i in enumerate(colors):
    plt.hist(image[120:,110:175,:][...,idx].flatten(), color = i,
alpha = 0.5)
    plt.xticks(range(0,255,15))
plt.show()
```



mask = np.where(((image[...,0] > 210) & (image[...,0] < 255)) & ((image[...,1] > 12) & (image[...,1] < 130)) & ((image[...,2] > 135)&(image[...,2] < 210))) binarized_array = binarization(image, mask, used_dim = -1, description = "dim 0 > 210 and < 255 AND dim 1 > 12 and < 130 AND dim 2 > 135 and < 210")





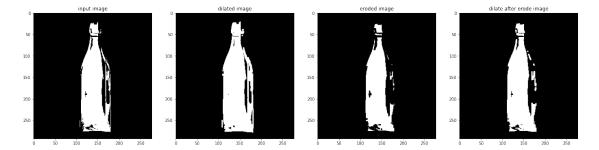
Exercise 1.2

- starting from the binary color detection image
- erase noise with an erosion operation
- dilate once to get original size of object
- find connected components with the two-pass algorithm
- extract bounding box on the fly
- draw bounding box on original image (RESULT)

```
Test on array from lecture
input array = np.array([[0,0,0,0,0],[0,1,1,0,0],[1,1,1,0,0],
[0,1,\overline{0},0,0], [0,0,0,0,0]]
print(input array)
[[0 0 0 0 0]]
 [0 1 1 0 0]
 [1 1 1 0 0]
 [0 1 0 0 0]
 [0 \ 0 \ 0 \ 0]
kernel = np.array([[0,1,0],[1,1,1],[0,1,0]])
print(kernel)
[[0 1 0]
[1 \ 1 \ 1]
[0 1 0]]
from tgdm.notebook import tgdm
def set steps(input array side size: int, kernel side size: int) ->
int:
    if (input array side size - kernel side size) % 2 != 0:
        return input array side size - kernel side size
    else:
        return input array side size - kernel side size + 1
def apply morphological operators(input array: np.ndarray, kernel:
np.ndarray, pixel value: int = 255, method: str = "dilate") ->
np.ndarray:
    kernel size = kernel.shape[0]
    output array = np.copy(input array)
    if input array.shape[0] % 2 != 0:
        print("padded input array")
        input array = np.pad(input array,1)
    steps height = set steps(input array.shape[0], kernel.shape[0])
    steps width = set steps(input array.shape[1],kernel.shape[1])
```

```
for i in tgdm(range(steps height)):
        for j in range(steps width):
            #print(input array[i:kernel size + i,j:kernel size + j])
                if method == "dilate":
                    if len(np.where((input array[i:kernel size +
i,j:kernel size + j] == kernel) \& ( input array[i:kernel size +
i,j:kernel size + j] == pixel value))[0]) > 0:
                        output array[i,j] = pixel_value
                elif method == "erode":
                    if len(np.where((input array[i:kernel size +
i,j:kernel size + j] == kernel) & ( input array[i:kernel size +
i,j:kernel size + j] == pixel value))[0]) == len(np.where(kernel != 0))
[0]):
                        output array[i,j] = pixel value
                    else:
                        output array[i,j] = 0
            except IndexError as e:
                print(e)
    return output array
input_array = np.array([[0,0,0,0,0],[0,1,1,0,0],[1,1,1,0,0],
[0,1,0,0,0], [0,0,0,0,0]]
output_array_dilate = apply_morphological_operators(input_array,
kernel, pixel value = 1, method = "dilate")
output array erode = apply morphological operators(input array,
kernel, pixel value = 1, method = "erode")
padded input array
{"version major":2, "version minor":0, "model id": "bfd6d6491c484b42b979d
74c8eb53037"}
padded input array
{"version major":2, "version minor":0, "model id": "ad19116ae47a4f2fa9c3f
6cd93c0a6d6"}
output array dilate
array([[0, 1, 1, 0, 0],
       [1, 1, 1, 1, 0],
       [1, 1, 1, 1, 0],
```

```
[1, 1, 1, 0, 0],
       [0, 1, 0, 0, 0]
output array erode
array([[0, 0, 0, 0, 0],
       [0, 0, 0, 0, 0],
       [0, 1, 0, 0, 0],
       [0, 0, 0, 0, 0],
       [0, 0, 0, 0, 0]])
binarized array = binarized array[...,0]
output array dilate = apply morphological operators(binarized array,
kernel = np.full((3,3), 255), pixel value = 255, method = "dilate")
output array erode = apply morphological operators(binarized array,
kernel = np.full((3,3), 255), pixel value = 255, method = "erode")
padded input array
{"version major":2, "version minor":0, "model id": "eedb1971e7874b3bb4417
f4cc44a82c4"}
padded input array
{"version major":2, "version minor":0, "model id": "c78fd9a334bc4a838509d
1a1a37e6649"}
fig, ax = plt.subplots(1,4, figsize = (24,8))
ax[0].imshow(binarized_array, cmap = "gray")
ax[0].set title("input image")
ax[1].imshow(output_array_dilate, cmap = "gray")
ax[1].set title("dilated image")
ax[2].imshow(output array erode, cmap = "gray")
ax[2].set_title("eroded image")
ax[3].imshow(apply morphological operators(output array erode, kernel
= np.full((3,3), 255), pixel value = 255, method = "dilate"), cmap = 1
"gray")
ax[3].set title("dilate after erode image")
padded input array
{"version major":2, "version minor":0, "model id": "d0baa331cbaa4ead9a983
2e9979928a8"}
Text(0.5, 1.0, 'dilate after erode image')
```



Connected components

```
Test on array from lecture
kernel = np.array([[0,1,0],[1,1,1],[0,1,0]])
print(kernel,"\n")

input_array = np.array([[0,0,0,0,0],[0,1,0,1,0], [1,1,1,1,0],
[0,1,0,0,0], [0,0,0,0,0]])
print(input_array)
plt.imshow(input_array, cmap = 'gray')

[[0 1 0]
[1 1 1]
[0 1 0]]

[[0 0 0 0 0]
[0 1 0 1 0]
[1 1 1 1 0]
[0 1 0 0 0]
[0 1 0 0 0]
```

<matplotlib.image.AxesImage at 0x7f776c508280>

```
1
  2
  3
  4
                    2
       0
              1
                           3
                                  4
input_array
array([[0, 0, 0, 0, 0],
       [0, 1, 0, 1, 0],
       [1, 1, 1, 1, 0],
       [0, 1, 0, 0, 0],
       [0, 0, 0, 0, 0]]
input_array = np.array([[0,0,0,0,0],[0,1,0,1,0],[1,1,1,1,0],
[0,1,0,0,0], [0,0,0,0,0]]
input_array
array([[0, 0, 0, 0, 0],
       [0, 1, 0, 1, 0],
       [1, 1, 1, 1, 0],
       [0, 1, 0, 0, 0],
       [0, 0, 0, 0, 0]]
output_array = np.zeros_like(input_array)
output_array
array([[0, 0, 0, 0, 0],
       [0, 0, 0, 0, 0],
       [0, 0, 0, 0, 0],
       [0, 0, 0, 0, 0],
```

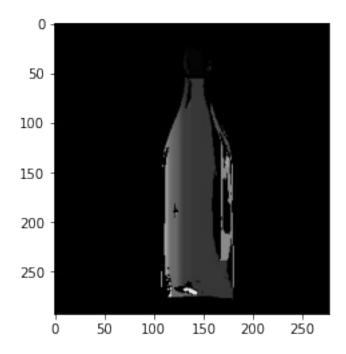
[0, 0, 0, 0, 0]]

```
def first pass(input array: np.ndarray) -> np.ndarray:
    # init output array with values = 0 and same shape as input
    output array = np.zeros like(input array)
    # pas input array with zeroes
    input array = np.pad(input array,1)
    label = 1
    for i in tgdm(range(1,input array.shape[0])):
        for j in range(1,input array.shape[1]):
            # skip if background
            if input array[i,j] == 0:
                continue
            else:
                # if current pixel == both pixels(west and north)
                if (input array[i,j] == input array[i,j - 1]) &
(input array[i, j] == input array[i-1,j]):
                    # if their labels are equal assign it to new pixel
                    if output array[i-1,j-2] == output array[i-2,j-1]:
                        output array[i-1,j-1] = output array<math>[i-1,j-2]
                    else:
                        # assign minimum of west vs north pixels
                        output array[i-1,j-1] = min(output array[i-
1,j-2, output array[i-2,j-1])
                # if current pixel == pixel to the west then assign
its value
                elif input array[i,j] == input array[i,j - 1]:
                    # output_array[i-1,j-1] = label
                    output array[i-1,j-1] = output array<math>[i-1,j-2]
                # if current pixel == pixel to the north then assign
its value
                elif input_array[i, j] == input_array[i-1,j]:
                    output array[i-1,j-1] = output array<math>[i-2,j-1]
                else:
                    output array[i-1,j-1] = label
                    label += 1
    return output array
```

```
output array = first pass(input array)
output array
{"version major":2, "version minor":0, "model id": "3020b169e30d4786ad10d
b2ae63a7015"}
array([[0, 0, 0, 0, 0],
       [0, 1, 0, 2, 0],
       [3, 1, 1, 1, 0],
       [0, 1, 0, 0, 0],
       [0, 0, 0, 0, 0]
Second pass
def second_pass(input_array: np.ndarray, kernel: np.ndarray) ->
np.ndarray:
    kernel size = kernel.shape[0]
    output 2d pass = np.copy(input array)
    input_array = np.pad(input_array,1)
    steps height = set steps(input array.shape[0], kernel.shape[0])
    steps width = set steps(input array.shape[1],kernel.shape[1])
    for i in tqdm(range(steps_height)):
        for j in range(steps width):
            not background =
np.where((input array[i:kernel size+i,j:kernel size+j]!=0) & (kernel !
=⊙ ) )
            if len(not background[0]) > 0:
                unique labels in window =
np.unique(input_array[i:kernel_size+i,j:kernel size+j])
                label =
min(unique labels in window[unique labels in window!=0])
                output 2d pass[i:kernel size+i,j:kernel size+j]
[output 2d pass[i:kernel size+i,j:kernel size+j] != 0 ] = label
    return output 2d pass
```

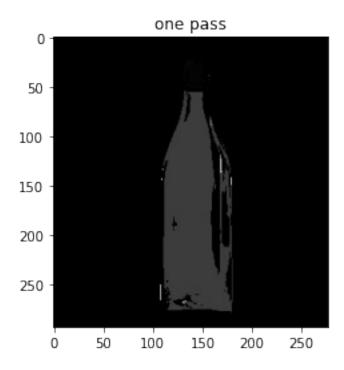
```
output 2d pass = second pass(output_array, kernel)
output 2d pass
{"version major":2, "version minor":0, "model id": "8cd8e739dde34110b8a70
7d7c9e51b3c"}
array([[0, 0, 0, 0, 0],
       [0, 1, 0, 1, 0],
       [1, 1, 1, 1, 0],
       [0, 1, 0, 0, 0],
       [0, 0, 0, 0, 0]
One-pass
def one pass(input array: np.ndarray, kernel: np.ndarray) ->
np.ndarray:
    kernel size = kernel.shape[0]
    output 1 pass = np.zeros like(input array)
    input array = np.pad(input array,1)
    steps height = set steps(input array.shape[0], kernel.shape[0])
    steps width = set steps(input array.shape[1],kernel.shape[1])
    label = 1
    for i in tgdm(range(steps height)):
        for j in range(steps width):
            not background =
np.where((input array[i:kernel size+i,j:kernel size+j]!=0) & (kernel !
=0)
            if len(not background[0]) > 0:
                # check neighborhood , if some pixels are labeled,
take their label
                unique labels in window = np.unique(output 1 pass[i +
not background[0] - 1, j + not background[1]-1])
                if
len(unique labels in window[unique labels in window!=0]) < 1:</pre>
                    output 1 pass[i + not background[0] - 1, j +
not background[1]-1] = label
                    label += 1
                else:
                    label in window =
min(unique labels in window[unique labels in window!=0])
```

```
output 1 pass[i + not background[0] - 1, j +
not background[1]-1] = label in window
    # relable sequentially
    for idx,i in enumerate(np.unique(output 1 pass)):
        output 1 pass[np.where(output 1 pass == i)] = idx
    return output 1 pass
output 1 pass = one pass(input array, kernel = np.ones((3,3)))
output 1 pass
{"version major":2, "version minor":0, "model id": "Ocbed23a1d3945ed9cd76
cdf03ea2be2"}
array([[0, 0, 0, 0, 0],
       [0, 1, 0, 1, 0],
       [1, 1, 1, 1, 0],
       [0, 1, 0, 0, 0],
       [0, 0, 0, 0, 0]]
output binarized array 1st pass = first pass(binarized array)
{"version major":2, "version minor":0, "model id": "1d4b34fabf844e3e9afec
7930e9cd71a"}
output_binarized_array_2d_pass =
second pass(output binarized array 1st pass, kernel)
{"version major":2, "version minor":0, "model id": "17a2c621479e47f4ac827
cef53cfa711"}
plt.imshow(output binarized array 2d pass, cmap = 'gray')
<matplotlib.image.AxesImage at 0x7f77741141f0>
```



```
plt.imshow(one_pass(binarized_array, kernel = np.full((3,3),1)), cmap
= 'gray')
plt.title("one pass")
plt.show()
```

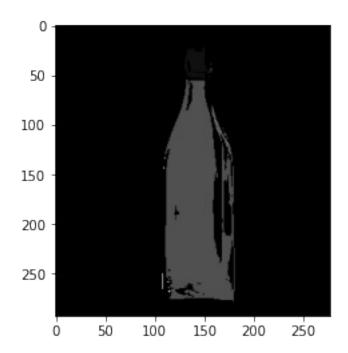
{"version_major":2,"version_minor":0,"model_id":"07425e610c51478a8464d
b561df6d1ad"}



```
baseline, opency-python
```

```
import cv2
```

```
num_labels, labels = cv2.connectedComponents(binarized_array)
plt.imshow(labels, cmap = 'gray')
<matplotlib.image.AxesImage at 0x7f776e7320d0>
```



Extract bounding box

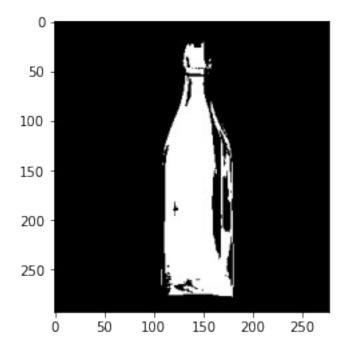
```
# dilate with large kernel to make a solide picture
binarized_array_dilated =
apply_morphological_operators(binarized_array, kernel = np.full((8,8),
1),pixel_value = 1, method = "dilate")

plt.imshow(binarized_array_dilated , cmap = 'gray')
padded input array

{"version_major":2,"version_minor":0,"model_id":"739a68a300db47078a7ae
c72ef90f8c8"}

/tmp/ipykernel_13169/3385474689.py:28: DeprecationWarning: elementwise
comparison failed; this will raise an error in the future.
   if len(np.where((input_array[i:kernel_size + i,j:kernel_size + j] ==
kernel) & (input_array[i:kernel_size + i,j:kernel_size + j] ==
pixel_value))[0]) > 0:

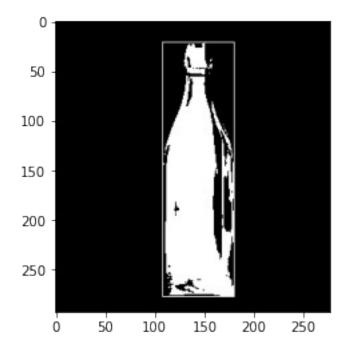
<matplotlib.image.AxesImage at 0x7f7767849df0>
```



bounding box over dilated image

```
def draw bbox(input image : np.ndarray, over label: int = -1,
return_only_bbox : bool = False) -> np.ndarray:
    output image = np.copy(input image)
    labels = np.unique(input image)
    # draw over particular label
    if over label != -1:
        labels = [0,over label]
    for i in tqdm(labels[1::]):
        indices = np.where(input_image == i)
        top = max(indices[0])
        left = min(indices[1])
        bottom = min(indices[0])
        right = max(indices[1])
        # create dummy dataframe to simulate bounding box
        # if straight line
        if (right - left) == 0:
            # if just 1 pixel - skip it
            try:
                dummy bbox = np.ones((3, top-bottom+1)) -
```

```
np.pad(np.ones((1 , top-bottom -1 )),1)
            except ValueError:
                continue
        else:
            dummy bbox = np.ones((right-left +1, top-bottom+1)) -
np.pad(np.ones((right-left -1 , top-bottom -1 )),1)
        # indices of bbox
        indices = np.where(dummy bbox == 1)
        # draw bbox
        output image[indices[1] + bottom, indices[0] + left] = i
    # return bbox if not all labels selected (used in tracking later)
    if return only bbox and over label != -1:
        only_bbox = np.zeros_like(input_image)
        only bbox[indices[1] + bottom, indices[0] + left] = over label
        return only bbox
    return output image
image with bbox = draw bbox(binarized array dilated)
# # Map component labels to hue val
# label hue = np.uint8(179*image with bbox/np.max(image with bbox))
# blank ch = 255*np.ones like(label hue)
# labeled img = np.transpose(np.stack([label hue, blank ch,
blank ch]), (1,2,0))
# labeled img = color.hsv2rgb(labeled img)
# # set background label to black
# labeled img[label hue==0] = 0
plt.imshow(image with bbox)
{"version major":2, "version minor":0, "model id": "926b7e72b6244c26959ec
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<matplotlib.image.AxesImage at 0x7f77677ceac0>
```



draw bboxes after one-pass algorithm
image with bbox = draw bbox(output 1 pass)

<matplotlib.image.AxesImage at 0x7f776c458760>

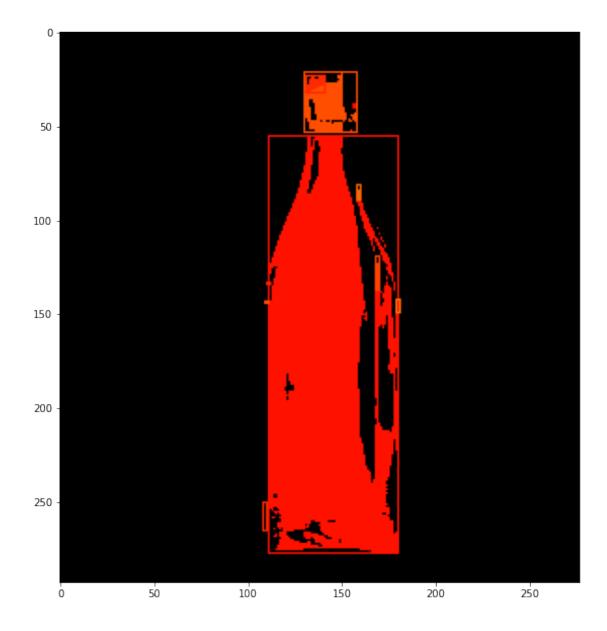
```
# Map component labels to hue val
label_hue = np.uint8(179*image_with_bbox/np.max(image_with_bbox))
blank_ch = 255*np.ones_like(label_hue)

labeled_img = np.transpose(np.stack([label_hue, blank_ch, blank_ch]),
(1,2,0))

labeled_img = color.hsv2rgb(labeled_img)
# set background label to black
labeled_img[label_hue==0] = 0

plt.figure(figsize=(10,10))
plt.imshow(labeled_img)

{"version_major":2,"version_minor":0,"model_id":"a7a4078d6760476fb7837
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```



Exercise 1.3

- · use your color detection and connected components algorithm
- · implement simplest tracking algorithm
- draw history of all previous points on frame (**RESULT**)

(see images/racecar or images/taco for sample image sequences)

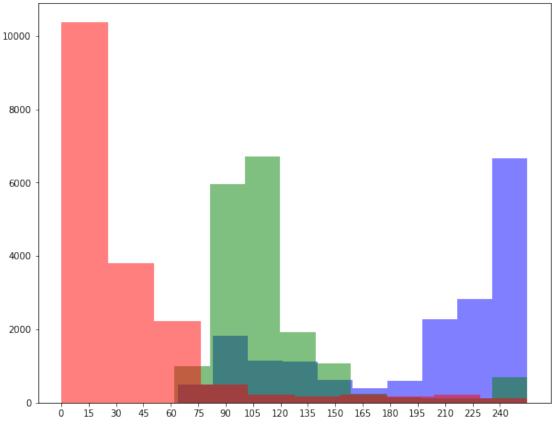
```
image = io.imread("images/taco/010.jpg")
#plt.imshow(image)
plt.imshow(image[170:350,0:100])
<matplotlib.image.AxesImage at 0x7f776ce92700>
```

```
0
20
40
60
80
100
120
140
160
```

```
# plot color distribution
plt.figure(figsize = (10,8))
colors = ["b","g","r"]

for idx,i in enumerate(colors):
    plt.hist(image[170:350,0:100,idx].flatten(), color = i, alpha =
0.5)
    plt.xticks(range(0,255,15))

plt.show()
```



```
def find taco label(input array: np.ndarray) -> int:
    we assume that after finding connected components based on our
color threshold
    the "taco=label" will be most-represented ( will have highest
number of pixels )
    label sizes = []
    # omit background
    for label in np.unique(input array)[1:]:
        label_sizes.append(np.sum(one_pass_taco == label))
    return np.argmax(label sizes) + 1
image.shape
(480, 854, 3)
import os
path to taco = os.path.join("images","taco")
bboxes = []
for i in tqdm(os.listdir(path_to_taco)):
    path to image = os.path.join(path to taco, i)
```

```
image = io.imread(path to image)
    # get taco
    mask = np.where(((image[...,0] > 180) \& (image[...,0] < 255)) \&
((image[...,1] > 80) \& (image[...,1] < 135)) \& ((image[...,2] > 1)
0)&(image[...,2] < 75)))
    binarized array = binarization(image, mask, used dim = -1,
description = "dim 0 > 180 \text{ and } < 255 \text{ AND } dim 1 > 80 \text{ and } < 135 \text{ AND } dim
2 > 0 and < 75", plot = False)
    # dilate with large kernel to make a solide view of taco
    binarized array dilated =
apply_morphological_operators(binarized_array[...,0], kernel =
np.full((5,5), 1), pixel value = 1, method = "dilate")
    # find connected components
    one pass taco = one pass(binarized array dilated, kernel =
np.full((5,5), 1))
    # get taco label
    taco label = find taco label(one pass taco)
    # get bbox
    only bbox = draw bbox(one pass taco, over label = taco label,
return only bbox=True)
    bboxes.append(only bbox)
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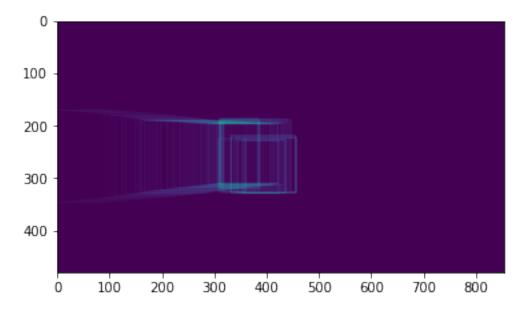
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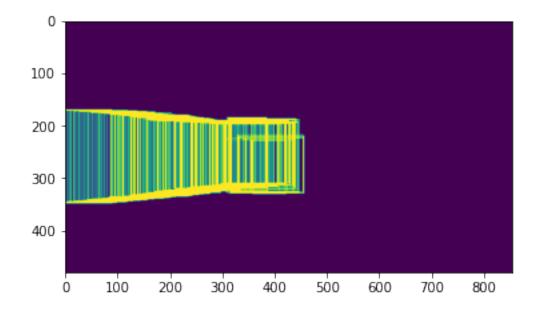
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{"version major":2, "version minor":0, "model id": "cb3ba26fcbc646adbe52d
34a482d4273"}
plt.imshow(sum(bboxes))
<matplotlib.image.AxesImage at 0x7f77657a0640>
```



```
import pickle
with open("tracking_tacko2.pickle", "wb") as f:
    pickle.dump( bboxes, f)

test = sum(bboxes)
test = np.where(test!=0,255,0)
plt.imshow(test)
```

<matplotlib.image.AxesImage at 0x7f77656970a0>



create video
import cv2

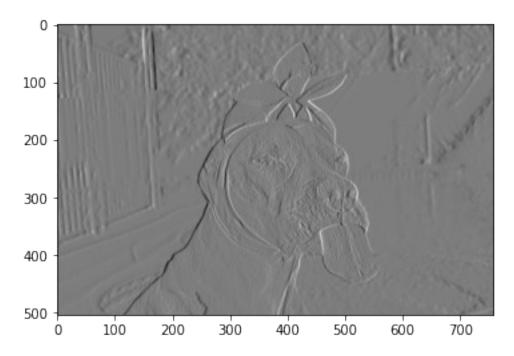
```
fourcc = cv2.VideoWriter fourcc('M','J','P','G')
video = cv2.VideoWriter("flying taco video.avi", fourcc, 10, (854,
480), isColor=True)
for idx, i in tqdm(enumerate(os.listdir(path to taco))):
    path to image = os.path.join(path to taco, i)
    image = cv2.imread(path to image)
    sub bbox = bboxes[idx]
    image[...,0][np.where(sub bbox != 0)] = 255
    image[...,1:][np.where(sub bbox != 0)] = 0
    video.write(image)
{"version major":2, "version minor":0, "model id": "bdf87977057b4885961be
0b610c9c67f"}
# Video is here:
https://github.com/IvanMatoshchuk/cv2122 assignments/blob/dev-ivan/
flying taco video.mp4
from IPython.display import Video, HTML
Video("flying taco video.mp4", embed=True)
<IPython.core.display.Video object>
Exercise 1.4 (BONUS)
     find connected components using a one-pass algorithm
     plot the resulting image and compare it to the result of your two-pass
     implementation (RESULT)
# implemented above
# here is it once again:
def one pass(input array: np.ndarray, kernel: np.ndarray) ->
np.ndarray:
    kernel size = kernel.shape[0]
    output 1 pass = np.zeros like(input array)
    input array = np.pad(input array,1)
```

```
steps height = set steps(input array.shape[0], kernel.shape[0])
    steps width = set steps(input array.shape[1],kernel.shape[1])
    label = 1
    for i in tgdm(range(steps height)):
        for j in range(steps width):
            not background =
np.where((input array[i:kernel size+i,j:kernel size+j]!=0) & (kernel !
=0)
            if len(not background[0]) > 0:
                # check neighborhood , if some pixels are labeled,
take their label
                unique labels in window = np.unique(output_1_pass[i +
not background[0] - 1, j + not background[1]-1])
len(unique labels in window[unique labels in window!=0]) < 1:</pre>
                    output 1 pass[i + not background[0] - 1, j +
not background[1]-1] = label
                    label += 1
                else:
                     label in window =
min(unique labels in window[unique labels in window!=0])
                    output 1 pass[i + not background[0] - 1, j +
not background[1]-1] = label in window
    # relable sequentially
    for idx,i in enumerate(np.unique(output 1 pass)):
        output 1 pass[np.where(output 1 pass == i)] = idx
    return output 1 pass
Exercise 2: Convolution and Canny edge detection
Exercise 2.1: Convolution
Implement the convolution operation for 2-D images (i.e. no colors here, sorry).
def conv2d(image, kernel):
    m, n = kernel.shape
    if (m == n):
        y, x = image.shape
        y = y - m + 1
        x = x - m + 1
        new image = np.zeros((y,x))
    for i in range(y):
        for j in range(x):
            new_image[i][j] = np.sum(image[i:i+m, j:j+m]*kernel)
```

```
return new image
```

```
image = color.rgb2gray(io.imread('images/dog.jpg'))
plt.imshow(conv2d(image, np.array([[-1,0,1],[-1,0,1],[-1,0,1]])),
cmap='gray')
```

<matplotlib.image.AxesImage at 0x7fe0d254aa90>



Convolve an image of your choice with a Gaussian kernel. Play around with the size of the kernel and the standard deviation of the Gaussian. Show your results (*RESULT*).

```
def dnorm(x, mu, sd):
    return 1 / (np.sqrt(2 * np.pi) * sd) * np.e ** (-np.power((x - mu)
/ sd, 2) / 2)

def gaussian_kernel(size, sigma=1, verbose=False):
    kernel_1D = np.linspace(-(size // 2), size // 2, size)
    for i in range(size):
        kernel_1D[i] = dnorm(kernel_1D[i], 0, sigma)
        kernel_2D = np.outer(kernel_1D.T, kernel_1D.T)

    kernel_2D *= 1.0 / kernel_2D.max()

if verbose:
    plt.imshow(kernel_2D, interpolation='none', cmap='gray')
    plt.title("Image")
```

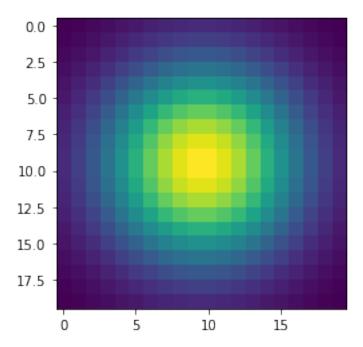
```
plt.show()

return kernel_2D
kernel = gaussian_kernel(20,5)
plt.imshow(conv2d(image, kernel), cmap='gray')
plt.title("gaussian smoothing, mean = 0, std = 5")
plt.show()
```

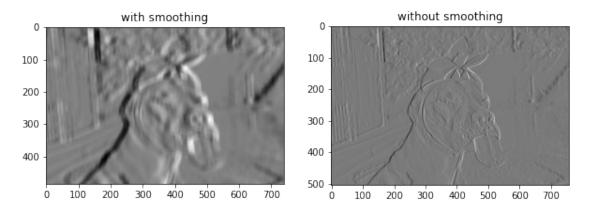


plt.imshow(kernel)

<matplotlib.image.AxesImage at 0x7fe0e1d54f70>



Now, implement a simple edge detector by first filtering with a Sobel operator and then thresholding the **RESULT**. How does smoothing the input change the **RESULT**?



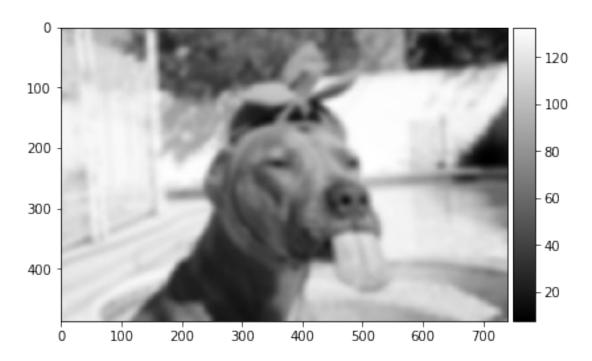
Exercise 2.2: Canny Edge Detection

Preprocessing

If you haven't yet: smooth the image with a Gaussian of your choice. Then use the Sobel operator to create the gradient magnitude and direction matrices (see slides page 23). Round the gradient directions to the 8-neighbor's directions. Display all intermediate **RESULT**s!

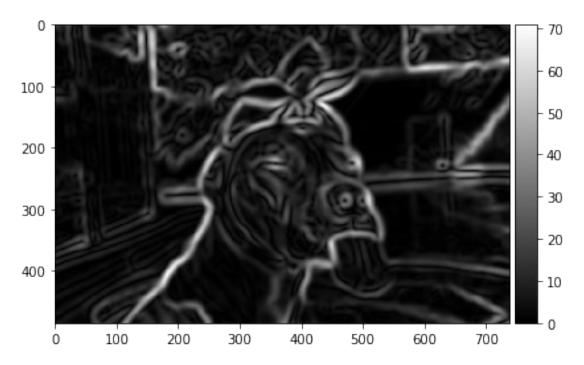
```
# Smooth the image with a Gaussian
```

```
kernel = gaussian_kernel(20,5)
image_conv = conv2d(image, kernel)
io.imshow(image_conv, cmap = 'gray')
<matplotlib.image.AxesImage at 0x7fe0d22c5a00>
```



```
filter_kernel = np.array([[-1,0,1],[-2,0,2],[-1,0,1]])
new_image_x = conv2d(image_conv, filter_kernel)
new_image_y = conv2d(image_conv,np.transpose(filter_kernel))
gradient_magnitude = np.sqrt(np.square(new_image_x) +
np.square(new_image_y))

io.imshow(gradient_magnitude, cmap = 'gray')
theta = np.arctan2(new_image_y, new_image_x)
```



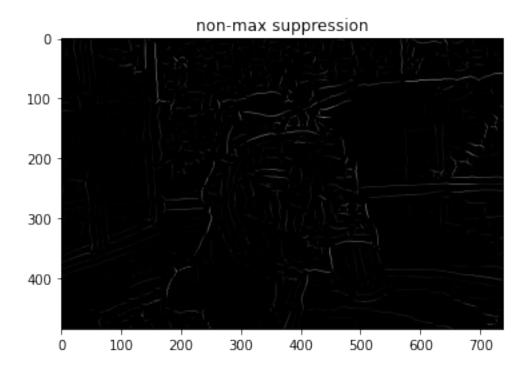
Non-Maximum Suppression

Implement the Non-Maximum Suppression step as described in the lecture. Subtract the result from the gradient magnitude image and show the **RESULT**!

```
def non_max_suppression(img, D):
    M, N = img.shape
    Z = np.zeros((M,N), dtype=np.int32)
    angle = D * 180. / np.pi
    angle[angle < 0] += 180

for i in range(1,M-1):
    for j in range(1,N-1):
        try:
        q = 255
        r = 255
        r = 255</pre>
```

```
if (0 <= angle[i,j] < 22.5) or (157.5 <= angle[i,j] <=</pre>
180):
                     q = img[i, j+1]
                     r = img[i, j-1]
                #angle 45
                elif (22.5 \le angle[i,j] < 67.5):
                    q = img[i+1, j-1]
                     r = img[i-1, j+1]
                #angle 90
                elif (67.5 <= angle[i,j] < 112.5):
                    q = img[i+1, j]
                     r = img[i-1, j]
                #angle 135
                elif (112.5 <= angle[i,j] < 157.5):</pre>
                    q = img[i-1, j-1]
                     r = img[i+1, j+1]
                if (img[i,j] >= q) and (img[i,j] >= r):
                     Z[i,j] = img[i,j]
                else:
                    Z[i,j] = 0
            except IndexError as e:
                pass
    return Z
image nms = non max suppression(gradient magnitude, theta)
plt.imshow(image nms, cmap='gray')
plt.title("non-max suppression")
Text(0.5, 1.0, 'non-max suppression')
```



Thresholding and Edge Tracing

Implement the edge tracing as described in the lecture and show the final result for three different threshold pairs: two low thresholds (e.g. 20 and 50), high thresholds (e.g. 80 and 120) and thresholds with large spacing (e.g. 40 and 140). (*RESULT*)

```
def threshold(img, threshold_low_ratio=0.1, threshold_top_ratio=0.15):
    threshold_top_boundary = img.max() * threshold_top_ratio;
    threshold_low_boundary = threshold_top_ratio *
threshold_low_ratio;

M, N = img.shape
    res = np.zeros((M,N), dtype=np.int32)

    weak = np.int32(25)
    strong = np.int32(255)

    strong_i, strong_j = np.where(img >= threshold_top_boundary)
    zeros_i, zeros_j = np.where(img < threshold_low_boundary)

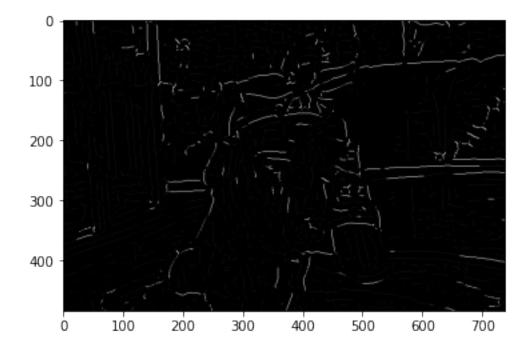
    weak_i, weak_j = np.where((img <= threshold_top_boundary) & (img >= threshold_low_boundary))

    res[strong_i, strong_j] = strong
    res[weak_i, weak_j] = weak

    return (res, weak, strong)
```

```
(image_nms_thres, w, s) = threshold(image_nms, threshold_low_ratio = 0.12, threshold_top_ratio = 0.25) plt.imshow(image_nms_thres, cmap='gray')
```

<matplotlib.image.AxesImage at 0x7fe0d90753d0>



Congratz, you made it! You can now try to solve this optional exercise.

This exercise is not graded, but might be a good preparation for the exam.

Please go to the following link: https://forms.gle/wMNmbTu1sAAWQz8d8.

In the form, you will find the optional task (and the corresponding consent form in case you agree with us processing your data). The task is formulated in German, and we would prefer German as the language for your answer. However, if you don't feel comfortable with that, please feel free to solve it in English.