## 1. Summary

Def: a clothoid is a plane curve with curvature a linear function of arc length.

Problem: We have a clothoid segment of fixed arc length s=1 and angles relative to the chord  $\theta_0$  and  $\theta_1$  and we wish to understand the curvature of this segment.

$$\kappa(s) = \kappa_0 + \kappa_1 s$$
 and  $-\frac{1}{2} \le s \le \frac{1}{2}$ 

integrating we find

$$\theta(s) = \kappa_0 s + \frac{\kappa_1}{2} s^2$$
$$z(s) = x + iy = \int_0^s e^{i\theta(t)} dt$$

Let's look at the drawing:

$$\psi = \arctan(\frac{y(\frac{1}{2}) - y(-\frac{1}{2})}{x(\frac{1}{2}) - x(-\frac{1}{2})})$$

$$\theta_0 = \psi - \theta(-\frac{1}{2}), \theta_1 = \theta(\frac{1}{2}) - \psi$$

Substituting our expression for  $\theta$  yields

$$\theta_0 = \frac{\kappa_0}{2} - \frac{\kappa_1}{8} + \psi$$
$$\theta_1 = \frac{\kappa_0}{2} + \frac{\kappa_1}{8} - \psi$$

An expression for  $\kappa_0$  follows

$$\kappa_0 = \theta_0 + \theta_1$$

We now only need to solve for a single variable  $\kappa_1$ 

$$0 = \kappa_1 - 8\psi + 4(\theta_0 - \theta_1)$$

This is our first task i.e. finding a numerical recipe for  $\kappa_1$ 

1.1. **implementation for fix point iteration.** First consider this as a fixed point iteration for  $\kappa_1$ . Starting with

(1.1) 
$$\kappa_1 = 8\psi - 4(\theta_0 - \theta_1).$$

Let  $F(\kappa_1)$  be defined as follows

(1.2) 
$$F(\kappa_1) = 8 \arctan \left( \frac{\Im \mathfrak{m} \int_{-1/2}^{1/2} e^{\mathrm{i}(\kappa_0 s + \frac{\kappa_1}{2} s^2)} ds}{\Re \mathfrak{e} \int_{-1/2}^{1/2} e^{\mathrm{i}(\kappa_0 s + \frac{\kappa_1}{2} s^2)} ds} \right) - 4(\theta_0 - \theta_1)$$

We can write this fixed point iteration as:

$$\kappa_1^{n+1} = F(\kappa_1^n)$$

Using a first order Taylor approximation we have the equation

(1.4) 
$$\frac{\kappa_1^3}{5184} + \frac{2\kappa_1}{3} + 4\theta_0 - 4\theta_1 = 0$$

We can use the real root of this as the initial guess. That is saying

(1.5) 
$$\kappa_1^0 - F(\kappa_1^0) \approx 0$$

Using the Python code, it seems that the above setup converges very fast. The trapozoid rule gives good convergence results.

1.2. **implementation for netwons method.** Using the above equation we can consider  $G(\kappa_1) = \kappa_1 - F(\kappa_1) = 0$  and apply Newton's method. The derivative of  $G(\kappa_1)$  is computed as

(1.6) 
$$G'(\kappa_1) = 1 - 8 \frac{g^2}{f^2 + g^2} \left( \frac{f'g - g'f}{g^2} \right)$$

Where  $f = f(\kappa_1)$  and  $g = g(\kappa_1)$  are the following

(1.7) 
$$f(\kappa_1) = \Re \int_{-1/2}^{1/2} e^{i(\kappa_0 s + \frac{\kappa_1}{2}s^2)} ds$$

(1.8) 
$$g(\kappa_1) = \Im \mathfrak{m} \int_{-1/2}^{1/2} e^{i(\kappa_0 s + \frac{\kappa_1}{2} s^2)} ds$$

With derivatives computed to be

(1.9) 
$$f'(\kappa_1) = \Re \int_{-1/2}^{1/2} i \frac{s^2}{2} e^{i(\kappa_0 s + \frac{\kappa_1}{2} s^2)} ds$$

(1.10) 
$$g'(\kappa_1) = \Im \mathfrak{m} \int_{-1/2}^{1/2} i \frac{s^2}{2} e^{i(\kappa_0 s + \frac{\kappa_1}{2} s^2)} ds$$

Newtons iteration can then be written as

(1.11) 
$$\kappa_1^{n+1} = \kappa_1^n - \frac{G(\kappa_1^n)}{G'(\kappa_1^n)}$$

Using the built in functions, this converges faster than the above fixed point iteration.

1.3. Clothoid Interpolation. The clothoid primitive is

(1.12) 
$$z_p(\alpha, s) = s_1 F_1(1/2, 3/2, i\alpha s^2/2)$$
$$T_p(\alpha, s) = \exp(i\alpha s^2/2)$$
$$\kappa(s) = \alpha s$$

A clothoid segment is a piece of a clothoid primitive with a rotation and a translation:

(1.13) 
$$z(s) = T_0 z_p(\alpha, s) + z_0, \quad s \in [s_i, s_f]$$

To find the parameters first we look at the unit length.

(1.14) 
$$\kappa_0 = \arg(T_f/T_i)$$

 $\kappa_1$  is obtained with a fixed point iteration, making sure that the total variation of  $\theta$  is less than  $2\pi$ . Now we use this information to find our true segment.

(1.15) 
$$\lambda = \frac{\|z_f - z_i\|}{\|z_p(\kappa_1, \kappa_0/\kappa_1 + 1/2) - z_p(\kappa_1, \kappa_0/\kappa_1 - 1/2)}$$

(1.16) 
$$\kappa_i = (\kappa_0 - \kappa_1/2)/\lambda$$

(1.17) 
$$\kappa_f = (\kappa_0 + \kappa_1/2)/\lambda$$

$$(1.18) \alpha = \kappa_1/\lambda^2$$

$$(1.19) s_i = \lambda(\kappa_0/\kappa_1 - 1/2)$$

$$(1.20) s_f = \lambda(\kappa_0/\kappa_1 + 1/2)$$

$$(1.21) T_0 = T_i/T_p(\alpha, s_i)$$

$$(1.22) z_0 = z_i - T_0 z_p(\alpha, s_i)$$

1.4.  $G_2$  continuity. Given a set of points,  $G_2$  continuity requires the curvature be continuous. We will look at minimizing the bending energy this is

with  $\gamma$  being the interpolating curve. Given a set of points  $\{p_i\}$ , i=0 to n, and clothoid segments  $C_i$ , i=0 to n-1, where  $C_i$  is the segment from  $p_i$  to  $p_{i+1}$ . we can realize this discretely as

(1.24) 
$$\sum_{i=0}^{n-1} |C_{i+1}(\kappa_i) - C_i(\kappa_f)|^2$$

where  $C_{i+1}(\kappa_i)$  is the initial curvature value for  $C_{i+1}$  at  $p_{i+1}$  and  $C_i(\kappa_f)$  is curvature at the endpoint for  $C_i$ . With the above we can start by using CG. This will form a next set of iterations. The outer iterations will consider the tangent the inner will consider the curvature. The inner set is already done with the python code.