# Sorting Correctly and Efficiently Week 7

COMP 1201 (Algorithmics)

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# Previously...

- Pseudocode
- Basics of sorting algorithms (sorts)
- Stable vs unstable sorts
- In-place sorts
- Simple sorts: **Insertion Sort**, **Selection Sort**
- Examples of their operation and pseudocode.

# What we care about in algorithms

Algorithms need to be *correct*, *efficient* and *easy to implement*.

In that order.

# Showing correctness requires mathematical proof

- (A) Mathematics is common sense,
- (B) Do not ask whether a statement is true until you know what it means,
- (C) A proof is any completely convincing argument.
  - Errett Bishop, 1973.

### **Algorithm 1** A simple program

```
1: procedure Foo(n)
                                                \triangleright Input is a positive integer n
        while n \neq 1 do
2:
             if n = 0 \mod 2 then
                                                          \triangleright If n is even, halve it
3:
4:
                  n \leftarrow n/2
5:
             else
                                             \triangleright If n is odd, triple it and add 1
6:
                  n \leftarrow 3n + 1
        return true
                                                              \triangleright Stop when n=1
7:
```

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$$Foo(10) = true$$

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        return true
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```

$$Foo(1000) = true$$

#### **Algorithm 1** A simple program

```
1: procedure Foo(n)
                                                \triangleright Input is a positive integer n
        while n \neq 1 do
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        return true
                                                              \triangleright Stop when n=1
7:
```

$$Foo(18061815) = true$$

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```
1: procedure Foo(n)
                                                \triangleright Input is a positive integer n
        while n \neq 1 do
2:
             if n = 0 \mod 2 then
                                                          \triangleright If n is even, halve it
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                                                              \triangleright Stop when n=1
7:
```

$$Foo(21101805) = \mathsf{true}$$

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```
1: procedure Foo(n)
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5:
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$$Foo(25101415) = true$$

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Collatz conjecture (1937): the above program terminates on any valid input. (No proof. Major unsolved problem in mathematics.)

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$$Foo(n) =$$
true checked for all  $n \in [1, 87 \times 2^{60}]$ 

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A more modest property we can prove about the above program: value of n is always above zero.

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```

A more modest property we can prove about the above program: value of n is always above zero.

This property is *true initially*, and is *maintained* by all the operations within the loop.

### Loop invariants

A **loop invariant** is a *property of a loop* that helps us understand why an algorithm is correct.

A property is a loop invariant if we can show the following:

- i **Initialisation**: it holds true prior to the first iteration of the loop.
- **Maintenance**: If it is true before an iteration of the loop, it remains true before the *next* iteration.
- **Termination**: When the loop terminates, the invariant gives us a useful property that helps us show that the algorithm is correct.

# Correctness of Sorting Algorithms

Fortunately, showing that sorting algorithms terminate is usually straightforward.

### When is a sorting algorithm correct?

- When its output is in non-decreasing order (i.e. the output is sorted according to some total order), and
- 2 the items in the output are a *permutation* of the items in the input.

We often prove correctness of sorting algorithms using loop invariants (though it can take a surprising amount of work to do this rigorously!) [CLRS, Ch. 2]

# Correctness of Sorting Algorithms

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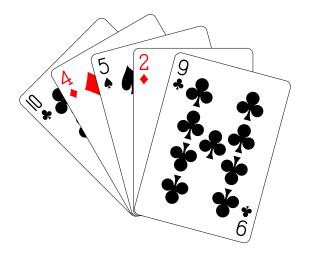
(Proofs of correctness using loop invariants will not be examinable.)

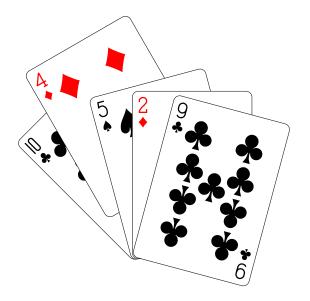
Recall: Insertion Sort keeps a sub-array of items on the left in (correctly) sorted order.

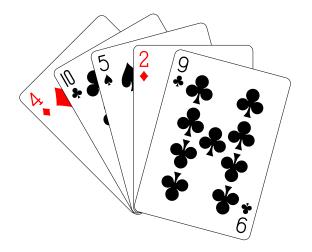
- This sub-array is increased by inserting the next item into its (relatively) correct position in the sorted sub-array.
- With each iteration we move the current item one to the right.

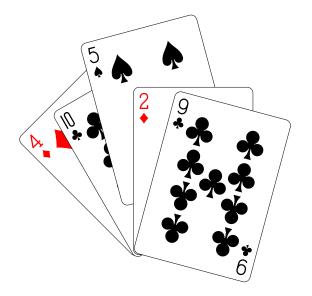
#### Algorithm 2 Insertion Sort

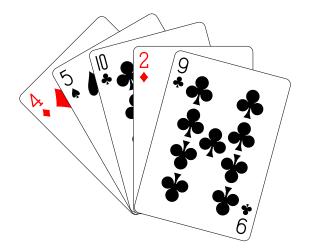
```
1: procedure InsertionSort(a)
        for i \leftarrow 2 to a length do
2:
3:
             key \leftarrow a_i
             i \leftarrow j-1
4:
             while i > 0 and a_i > key do
5:
6:
                 a_{i+1} \leftarrow a_i
                 i \leftarrow i - 1
7:
             a_{i+1} \leftarrow key
8:
9:
        return a
```

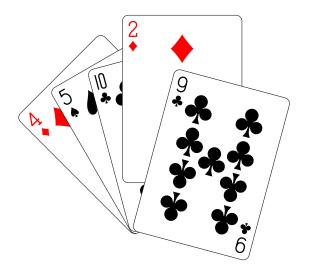


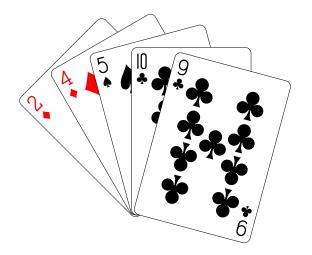


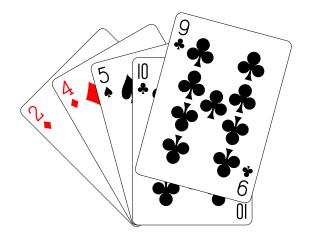


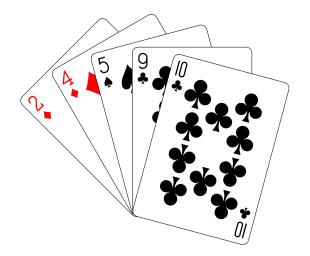












In order to prove correctness of Insertion Sort, we can use the following loop invariant:

"At the start of each iteration of the **for** loop, the sub-array  $a_1a_2\ldots a_{j-1}$  consists of all items originally in  $a_1a_2\ldots a_{j-1}$ , but in sorted order."

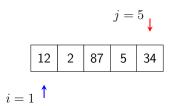
**Bubble sort** is another example of *simple sorting algorithm*.

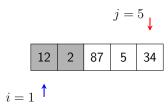
<u>Main idea</u>: keep swapping neighbouring items until the array is sorted.

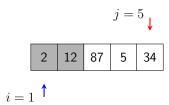
- Intuition: items "bubble up" through the array into their correct position.
- Bubble Sort is **stable** and **in-place** (O(1) space complexity).
- Time complexity is  $O(n^2)$ .
- Not a bad simple sort, but does more work than insertion sort and selection sort.

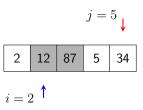
#### **Algorithm 3** Bubble Sort

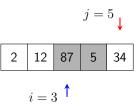
```
1: procedure BUBBLESORT(a)
2: for j \leftarrow \mathbf{a}.length to 2 do
3: for i \leftarrow 1 to j - 1 do
4: if a_i > a_{i+1} then
5: swap(a_i, a_{i+1}) \triangleright Exchange adjacent elements
6: return a \triangleright Sorted sequence
```

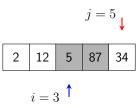


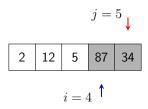


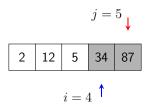


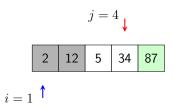


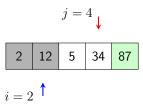


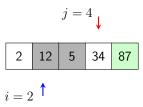


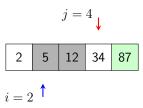


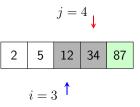


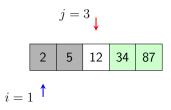


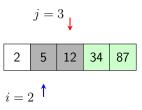


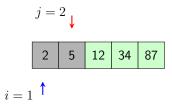


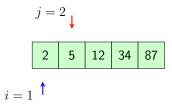












### **Algorithm 4** Bubble Sort

```
1: procedure BUBBLESORT(\mathbf{a})
2: for j \leftarrow \mathbf{a}.length to 2 do
3: for i \leftarrow 1 to j - 1 do
4: if a_i > a_{i+1} then
5: swap(a_i, a_{i+1}) \triangleright Exchange adjacent elements
6: return \mathbf{a} \triangleright Sorted sequence
```

Question: can you think of a loop invariant for Bubble Sort?

## More on correctness and loop invariants:

■ Chapter 2 in Cormen (CLRS) Introduction to Algorithms.

Optional material for those interested in correctness:

- Edsger Dijkstra's 1990 lecture "Reasoning about programs" https://www.youtube.com/watch?v=GX3URhx6i2E
- 2 Paper that exposed a bug in OpenJDK's implementation of TimSort is by **Stijn de Gouw et al.** "OpenJDK's java.utils.Collection.sort() is broken:The good, the bad and the worst case". Computer Aided Verification (CAV) 2015.

## Back to efficiency

- Lower bound on the complexity of *comparison-based* sorts
- Efficient sorts (comparison-based):
  - Merge Sort
  - Quicksort

## Comparison-based sorting algorithms

A comparison-based sorting algorithm (comparison-based sort):

- a sorting algorithm
- can *only* gain information about the items in the input sequence  $a_1, a_2, \ldots, a_n$  by performing *pairwise-comparisons*.

A pairwise-comparison is a query such as "is  $a_i < a_j$ ?"

Most general-purpose sorting algorithms are comparison-based.

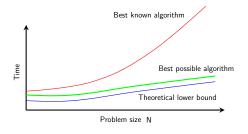
#### Examples:

- Insertion Sort, Selection Sort, Bubble Sort,
- Merge Sort, Quicksort.

## Lower bounds on time complexity

Given a problem we would like to know what is the time complexity of the **best possible algorithmic solution**.

- A lower bound of f(n) is a guarantee that no one can use fewer than f(n) operations.
- lacksquare Solving the general problem **requires** at least f(n) operations.
- Lower bounds give the difficulty of the problem.

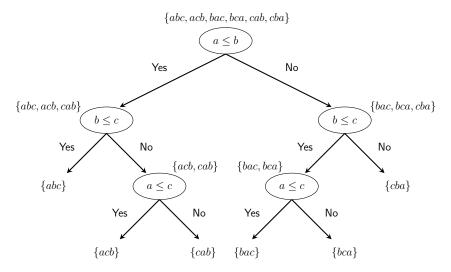


#### **Decision Trees**

We are interested in establishing a lower bound on the number of *comparisons* needed for sorting.

- Decision trees are a way to visualise many algorithms (at least in principle).
- A decision tree shows a series of decisions made during an algorithm.
- In the case of sorting algorithms, a decision tree will show what the algorithm does at every comparison.

### Decision Tree for Insertion Sort



## Decision Trees and Time Complexity

The time taken to complete the task is the *depth of the tree* at which we finish (i.e. the **leaf nodes**).

We can use decision trees to read off the time complexity:

- Worst case: depth of the deepest leaf.
- Best case: depth of the shallowest leaf.
- Average case: average depth of leaves.

Different sorting strategies will have different decision trees.

Decision trees are usually far too large to write down in practice.

# Correctness Requirements for Sorting

Any sorting algorithm based on pairwise-comparisons must have a leaf in its decision tree for every possible way of sorting the list.

For an input abc we must consider all possible permutations:

$$\{abc, acb, bac, bca, cab, cba\}$$

These correspond to different paths in the decision tree.

- Each leaf of the decision tree gives one possible ordering of elements.
- n! possible permutations (number of leaves).

Height of the decision tree  $\geq \log_2(n!)$ .

# Lower Bound on Comparison-based Sorting

$$\begin{split} \log_2(n!) &= \log_2(1) + \log_2(2) + \dots + \log_2(n) \\ &\leq \log_2(n) + \log_2(n) + \dots + \log_2(n) \\ &= n \log_2(n). \end{split}$$
 So 
$$\log_2(n!) &= O(n \log_2(n)). \quad \text{[Nice, but not what we need.]} \\ \log_2(n!) &= \log_2(1) + \log_2(2) + \dots + \log_2(n) \\ &\geq \log_2\left(\frac{n}{2}\right) + \dots + \log_2(n) \\ &\geq \frac{n}{2} \log_2\left(\frac{n}{2}\right) = \frac{n}{2} \log_2\left(n\right) - \frac{n}{2}. \end{split}$$
 So 
$$\log_2(n!) &= \Omega(n \log_2(n)). \quad \text{[We have a lower bound!]} \end{split}$$

- Invented by John von Neumann in 1945.
- Employs a divide-and-conquer strategy.
- The problem is divided into a number of parts recursively.
- The solution is obtained by recombining the parts.



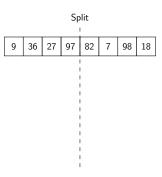
John von Neumann

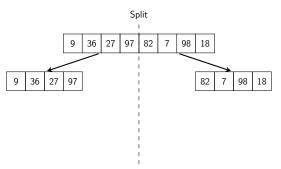
<u>Basic idea</u>: divide the array into two halves and recursively sort each half; then <u>merge</u> the two sorted halves to obtain the solution.

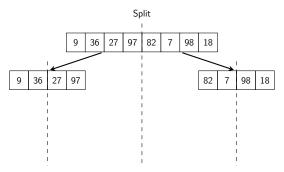
#### **Algorithm 5** Merge Sort

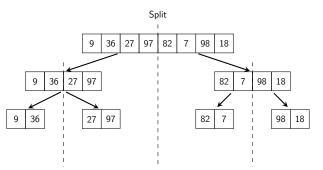
```
1: procedure MergeSort(a, start, end)
     if start < end then
2:
         mid \leftarrow |(start + end)/2|
3:
                                              Divide problem
         MERGESORT(\mathbf{a}, start, mid)
4:
                                              5:
         MERGESORT(\mathbf{a}, mid + 1, end)
                                              Merge(\mathbf{a}, start, mid, end)
                                                    ▷ Combine
6:
     else
7:
         return
                                                   ▶ Base case
8:
```

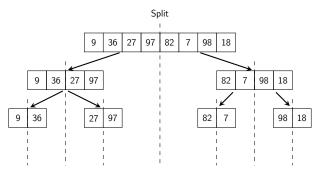
9 36 27 97 82 7 98 18

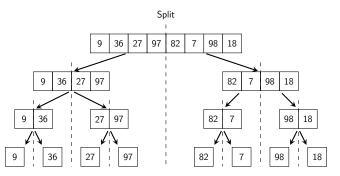


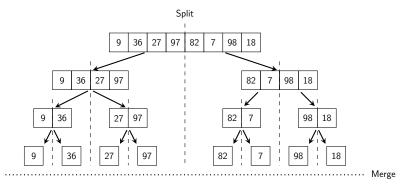


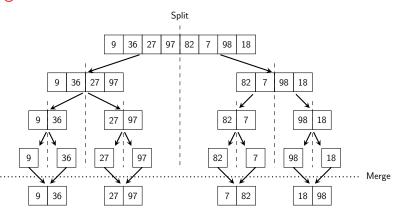


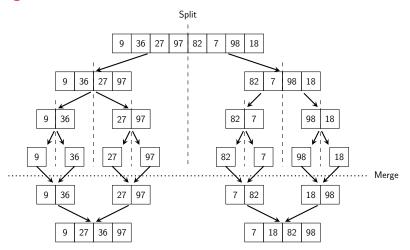


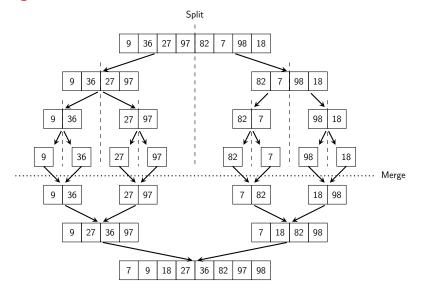












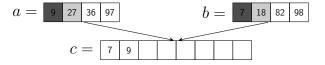
In order to merge two sorted arrays  ${\bf a},\,{\bf b}$  into one sorted array  ${\bf c}$  we follow a simple procedure:

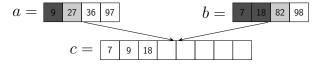
- lacksquare Compare current elements of  ${f a}$  and  ${f b}$ ,
- $lue{}$  Choose the smaller one and store it in  ${f c}$ ,
- Move to the next element in the array of the chosen element.

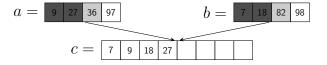


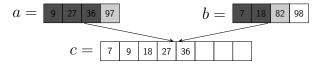


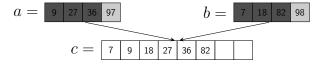


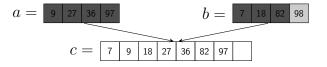


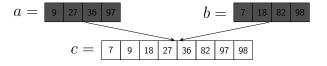








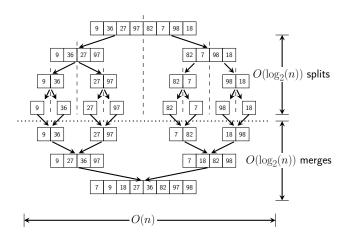




### Properties of Merge Sort

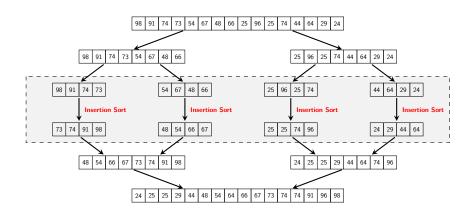
- Merge Sort is stable, i.e. it preserves the order of two entries with same value (provided we merge carefully).
- Merge Sort is **not in-place**: we need an array of at most size n to do the merging! (Space complexity is O(n).)
- Merging sub-arrays is **quick**: given two arrays of size n, we need to perform at most n-1 comparisons to merge them.
- Recurrence relation:  $T(n) = 2T(\frac{n}{2}) + O(n)$ .
  - Worst case time complexity:  $O(n \log(n))$ .
- Merge Sort is **asymptotically optimal**.

### Complexity of Merge Sort



### Improving Merge Sort with Insertion Sort

<u>Main idea</u>: if sub-array size falls below a certain threshold, we switch to Insertion Sort (which is fast for short arrays).



### Quicksort

- Invented by **Sir Tony Hoare** in 1959.
- Later implemented in ALGOL-60 (using recursion) and published in 1961.
- One of the most influential algorithms in computer science.
- Improvements made by Bob Sedgewick in the 1970s.



Sir Tony Hoare

<u>Basic idea</u>: **divide-and-conquer** by separating the array into two parts depending on whether the elements are smaller or greater than some **pivot** element; recurse on both parts until the array is sorted.

### Quicksort

#### Algorithm 6 Quicksort

```
1: procedure QUICKSORT(a, start, end)
       if start < end then
2:
           pivot \leftarrow ChoosePivot(\mathbf{a}, start, end)
3:
           part \leftarrow Partition(\mathbf{a}, pivot, start, end)
4:
5:
           QuickSort(\mathbf{a}, start, part - 1)
                                                                 ⊳ Recurse
           QuickSort(\mathbf{a}, part + 1, end)
6:
                                                                 Recurse
       else
7:
           return
                                                               ▶ Base case
8:
```

# **Optimising Partitioning**

Choose pivot:

$$\mathbf{a} = a_1, a_2, a_3, \dots, a_{n-1}, \overbrace{a_n}^p$$

Partition:

$$\underbrace{a'_1, a'_2, a'_3, \dots, a'_{m-1}}_{\leq p}, p, \underbrace{a'_{m+1}, a'_{m+2}, \dots, a'_{n}}_{\geq p}$$

There are many different ways of performing partitioning.

■ Worst case scenario: pivot is the smallest or the largest element (this results in an inefficient partitioning: an array of size n-1 and an array of size 1).

# **Optimising Partitioning**

**Main question**: how to *efficiently* choose the pivot? Some possibilities:

- Choose the first element in the array.
- Choose the median of the first, middle and last element of the array [Bentley-Mcllory, 1993]. (This increases the likelihood of the pivot being close to the median of the whole array.)
- Choose the pivot randomly (makes worst case unlikely).

#### Quicksort with Insertion Sort

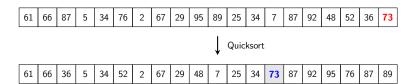
Idea: We recursively partition the array until each partition is small enough to sort using Insertion Sort.

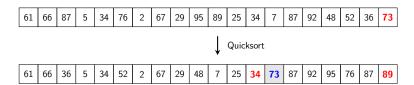
#### Algorithm 7 Quicksort

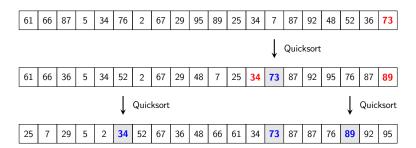
```
1: procedure QUICKSORT(a, start, end)
        if end - start < threshold then
2:
            InsertionSort(\mathbf{a}, start, end)
3:
4.
        if start < end then
            pivot \leftarrow CHOOSEPIVOT(\mathbf{a}, start, end)
5:
            part \leftarrow Partition(\mathbf{a}, pivot, start, end)
6:
            QuickSort(\mathbf{a}, start, part - 1)
7:
                                                                 ⊳ Recurse
            QuickSort(\mathbf{a}, part + 1, end)
                                                                 Recurse
8:
        else
9.
                                                               ▶ Base case
10:
            return
```

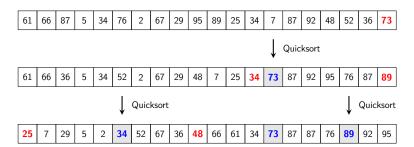
61   66   87   5   34   76   2   67   29   95   89   25   34   7   87   92   48   52   36	61	66 87	5	34	76	2	67	29	95	89	25	34	7	87	92	48	52	36	73
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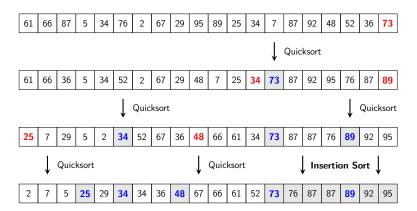
61	66	87	5	34	76	2	67	29	95	89	25	34	7	87	92	48	52	36	73

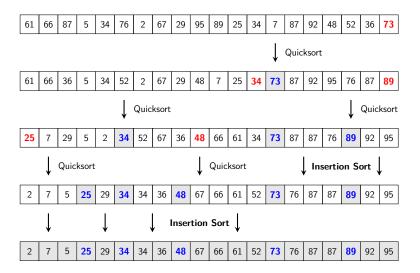












### Time Complexity of Quicksort

- Partitioning an array of size n takes  $\Theta(n)$  operations.
- When the pivot element is the smallest for each partitioning, we need n-1 partitioning rounds, i.e. O(n).
- Worst case:  $O(n^2)$  time complexity.
- Ideally, the pivot is the median value and splits the array in half. In this case we have  $\Omega(\log(n))$  partitions.
- On average, Quicksort is  $O(n \log(n))$ .

In practice, Quicksort is very fast (close to O(n)).

- 39% more comparisons than Merge Sort,
- But faster because there is less data movement.

### Summary

Sorting is important: one of the most common operations.

- Lower bound on the complexity of comparison-based sorts is:  $\boxed{\Omega(n\log_2(n))}$
- We can achieve this optimal bound with efficient comparison-based sorting algorithms.
- Today we've seen two efficient sorting algorithms: Merge Sort and Quicksort.

### Further Reading:

- Merge Sort: Chapter 2 in Cormen (CLRS) Introduction to Algorithms.
- Quicksort: Chapter 7 in Cormen (CLRS) Introduction to Algorithms.

#### Optional material:

■ Sir Tony Hoare speaking about his discovery of Quicksort https://www.youtube.com/watch?v=tAl6wzDTrJA&t=13m

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