



Not So Tiny Task №9 (1 point)

Generalize data structure that you've implemented in NSTT #1, #3 and #4 with help of templates!

Not So Tiny Task №10 (1 point)

Implement a `mix-in` to limit number of your class instances. Classes with such functionality should be successfully created only when there are less than specified number of instances, otherwise their construction should fail.

Use `CRTP` and non-type template argument (for the limit)

System Programming with C++

Templates



System Programming with C++

Templates



Eventually we will have standard catalogs of **generic components** with well-defined interfaces, with well-defined complexities. Programmers will stop programming at the micro level. You will **never** need to write a binary search routine again.

Alexander A. Stepanov, the author of STL

Generic programming

```
int max(int x, int y) {  
    return (x > y) ? x : y;  
}
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int max(int x, int y) {  
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float max(float x, float y) {  
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```

Generic programming

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```
Matrix max(Matrix x, Matrix y) {  
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```

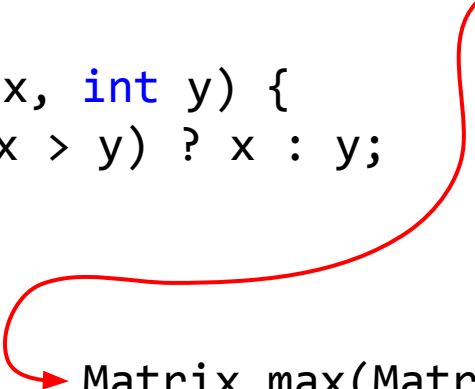
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Matrix max(Matrix x, Matrix y) {  
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What should Matrix have to make this method work?



Generic programming

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Generic programming

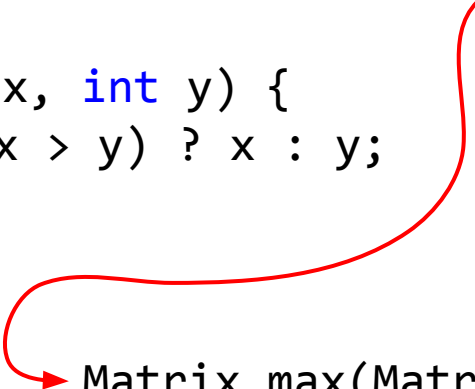
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How to fight with such copy-paste?

Generic programming

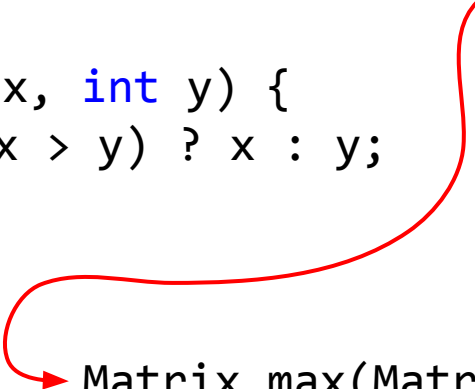
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How to fight with such copy-paste?

Nothing to do with **inheritance**, as int/float/Matrix are not connected

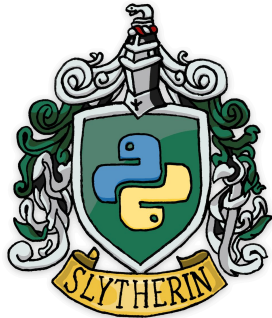
Generic programming

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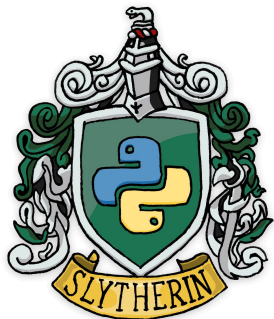


Generic programming

How other languages handle that?

```
def max(x, y) {  
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```

Dynamically typed languages
solve such problems easily:
no types specified => you
can pass anything here



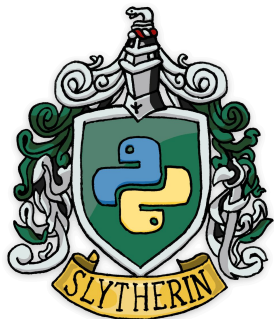
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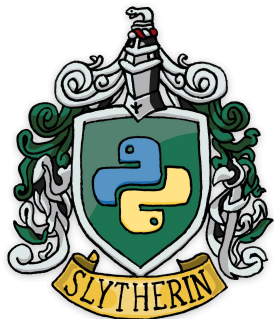
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Generic programming

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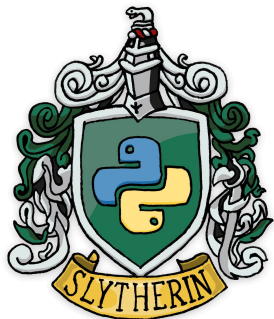
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- 1) Passing unsuitable types will cause RT exception

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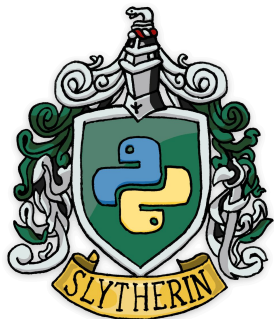
But there are **consequences**:

- 1) Passing unsuitable types will cause RT exception
- 2) Would be nice to find a problem before execution

Generic programming

How other languages handle that?

```
def max(x, y) {  
    return (x > y) ? x : y;  
}
```



Dynamically typed languages solve such problems easily: no types specified => you can pass anything here

But there are **consequences**:

3) Performance costs (to find a method and calls will be virtual of course)

Generic programming

How other languages handle that?

```
public static <T extends Comparable<T>> T max(T a, T b) {  
    if (a == null) {  
        if (b == null) return a;  
        else return b;  
    }  
    if (b == null) return a;  
    return a.compareTo(b) > 0 ? a : b;  
}
```



Generic programming

In Java we still try to solve it with **hierarchies**, because this is a way to specify **requirements** to this generic T argument.

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Problems:

1. Doesn't work with **primitives** without boxing

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}
```



Problems:

1. Doesn't work with **primitives** without boxing
2. Type information is lost because of implementation (performance drop)
3. Requirements via inheritance is not always good

Generic programming in C++

```
template <typename T>  
T max(T x, T y) {  
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}
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T max(T x, T y) {
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}
```

both `typename` and `class` can be used here (and there discussions about it), I will use `typename` in lectures.

Generic programming in C++

```
template <typename T>  
T max(T x, T y) {  
    return (x > y) ? x : y;  
}
```

T - formal template parameter

Generic programming in C++

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

T - formal template parameter

```
int a, b, c;
...
a = max<int>(b, c);
```

int - actual parameter type in this instantiation.

Generic programming in C++

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

T - formal template parameter

```
float a, b, c;
```

```
...
```

```
a = max<float>(b, c);
```

float - actual parameter type in this instantiation.

Generic programming in C++

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

T - formal template parameter

```
Matrix a, b, c;
```

```
...
```

```
a = max<Matrix>(b, c);
```

Matrix - actual parameter type
in this instantiation. Will it
compile?

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template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
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Matrix a, b, c;
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```
...
```

```
a = max<Matrix>(b, c);
```

Matrix - actual parameter type in this instantiation. Will it compile? It depends on Matrix! 30

Generic programming in C++

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

T - formal template parameter

In `instantiation` of 'T max(T, T) [with T = Matrix]':
`error`: no match for '`operator>`' (operand types are
'Matrix' and 'Matrix')
return (a > b) ? a : b;
~~~~^~~~

-----

```
Matrix a, b, c;
```

```
...
```

```
a = max<Matrix>(b, c);
```

Matrix - actual parameter type  
in this instantiation. Will it  
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# Generic programming in C++

The code of the method `max` defines **requirements** for the type that will be substituted

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```
Matrix a, b, c;
```

```
...
```

```
a = max<Matrix>(b, c);
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Matrix - actual parameter type
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Generic programming in C++

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template <typename T>
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}
```

T - formal template parameter

```
class Matrix {
    Matrix(const Matrix& other) {
        ...
    }

    bool operator>(const Matrix& other) {
        ...
    }
};
```

```
Matrix a, b, c;
...
a = max<Matrix>(b, c);
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Generic programming in C++

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    }
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```

```
Matrix a, b, c;
...
a = max<Matrix>(b, c);
```

Now this will indeed compile.

Templates: how does it work?

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

```
int a, b = 3, c = 10;
a = max<int>(b, c);
```

```
Matrix k, l, m;
k = max<Matrix>(l, m);
```

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

Compiler finds set of all
actual types:

T = {int, Matrix}

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k = max<Matrix>(l, m);
```

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

```
int max_1(int x, int y) {
    return (x > y) ? x : y;
}
```

```
Matrix max_2(Matrix x, Matrix y) {
    return (x > y) ? x : y;
}
```

Compiler finds set of all actual types:

$T = \{\text{int}, \text{Matrix}\}$

Then generates versions of method max (instantiate)

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Then generates versions of method max (instantiate). And updates calls!

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Compiler finds set of all actual types:

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Then generates versions of method max (instantiate). And updates calls! This process is called **monomorphization**.

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| | | |
|--|---|--|
| <pre> main: push rbp mov rbp, rsp sub rsp, 16 mov DWORD PTR [rbp-4], 3 mov DWORD PTR [rbp-8], 10 mov edx, DWORD PTR [rbp-8] mov eax, DWORD PTR [rbp-4] mov esi, edx mov edi, eax call int max<int>(int, int) mov DWORD PTR [rbp-12], eax call Matrix max<Matrix>(Matrix, Matrix) mov eax, DWORD PTR [rbp-12] leave ret </pre> | <pre> int max<int>(int, int): push rbp mov rbp, rsp mov DWORD PTR [rbp-4], edi mov DWORD PTR [rbp-8], esi mov eax, DWORD PTR [rbp-4] cmp eax, DWORD PTR [rbp-8] jle .L6 mov eax, DWORD PTR [rbp-4] jmp .L8 .L6: mov eax, DWORD PTR [rbp-8] .L8: pop rbp ret </pre> | <pre> Matrix max<Matrix>(Matrix, Matrix): push rbp mov rbp, rsp sub rsp, 16 lea rdx, [rbp-2] lea rax, [rbp-1] mov rsi, rdx mov rdi, rax call Matrix::operator>(Matrix&) test al, al nop leave ret </pre> |
|--|---|--|

<https://godbolt.org/z/KMMEnvT7M>

main:

```
push    rbp
mov     rbp, rsp
sub     rsp, 16
mov     DWORD PTR [rbp-4], 3
mov     DWORD PTR [rbp-8], 10
mov     edx, DWORD PTR [rbp-8]
mov     eax, DWORD PTR [rbp-4]
mov     esi, edx
mov     edi, eax
call    int max<int>(int, int)
mov     DWORD PTR [rbp-12], eax
call    Matrix max<Matrix>(Matrix, Matrix)
mov     eax, DWORD PTR [rbp-12]
leave
ret
```

int max<int>(int, int):

```
push    rbp
mov     rbp, rsp
mov     DWORD PTR [rbp-4], edi
mov     DWORD PTR [rbp-8], esi
mov     eax, DWORD PTR [rbp-4]
cmp     eax, DWORD PTR [rbp-8]
jle     .L6
mov     eax, DWORD PTR [rbp-4]
jmp     .L8
.L6:
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.L8:
pop     rbp
ret
```

Matrix max<Matrix>(Matrix, Matrix):

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call    Matrix::operator>(Matrix&)
test    al, al
nop
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mov     edi, eax
call    int max<int>(int, int)
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.L8:
pop     rbp
ret
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Matrix max<Matrix>(Matrix, Matrix):

```
push    rbp
mov     rbp, rsp
sub     rsp, 16
lea     rdx, [rbp-2]
lea     rax, [rbp-1]
mov     rsi, rdx
mov     rdi, rax
call    Matrix::operator>(Matrix&)
test    al, al
nop
leave
ret
```

<https://godbolt.org/z/KMMEnvT7M>

Monomorphization: pros and cons

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Monomorphization: pros and cons

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2. **Type-safety** is still here: no sudden exceptions during execution, compiler will check types!

Cons:

1. Compilation time/size of binary.
2. Errors in templates can be a mess



```

const string&*>; T2 = jinja2::EmptyValue>
1320 /home/travis/build/flexferrum/Jinja2Cpp/thirdparty/nonstd/variant-light/include/nonstd/variant.hpp:1597:17: required from 'static R nonstd::variants::detail::VisitorApplicatorImpl<R,
VT>::apply(const Visitor&, const T&) [with Visitor = nonstd::variants::detail::TypedVisitorUnwrapper<2u1, jinja2::Value, jinja2::detail::UCInvoker<const
UserCallableTest_SimpleUserCallableWithParams2_Test::TestBody()::<lambda(const string&, const string&)>&>, jinja2::EmptyValue>; T = bool; R = jinja2::Value; VT = bool]'
```

```

1321 /home/travis/build/flexferrum/Jinja2Cpp/thirdparty/nonstd/variant-light/include/nonstd/variant.hpp:1807:59: required from 'static R
nonstd::variants::detail::VisitorApplicator<R>::apply_visitor(const Visitor&, const V1&) [with long unsigned int Idx = 1u1; Visitor = nonstd::variants::detail::TypedVisitorUnwrapper<2u1,
jinja2::Value, jinja2::detail::UCInvoker<const UserCallableTest_SimpleUserCallableWithParams2_Test::TestBody()::<lambda(const string&, const string&)>&>, jinja2::EmptyValue>; V1 =
nonstd::variants::variant<jinja2::EmptyValue, bool, std::basic_string<char>, std::basic_string<wchar_t>, long int, double, nonstd::vptr::value_ptr<std::vector<jinja2::Value>,
nonstd::vptr::detail::default_clone<std::vector<jinja2::Value>>>, nonstd::vptr::value_ptr<std::unordered_map<std::basic_string<char>,
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jinja2::Value>>>, std::default_delete<std::unordered_map<std::basic_string<char>, jinja2::Value>>>, std::default_delete<std::unordered_map<std::basic_string<char>, jinja2::Value>>>,
jinja2::GenericList, jinja2::GenericMap, nonstd::vptr::value_ptr<jinja2::UserCallable, nonstd::vptr::detail::default_clone<jinja2::UserCallable>, std::default_delete<jinja2::UserCallable>>>>; R =
jinja2::Value]'
```

```

1322 /home/travis/build/flexferrum/Jinja2Cpp/thirdparty/nonstd/variant-light/include/nonstd/variant.hpp:1778:44: required from 'static R nonstd::variants::detail::VisitorApplicator<R>::apply(const
Visitor&, const V1&) [with Visitor = nonstd::variants::detail::TypedVisitorUnwrapper<2u1, jinja2::Value, jinja2::detail::UCInvoker<const
UserCallableTest_SimpleUserCallableWithParams2_Test::TestBody()::<lambda(const string&, const string&)>&>, jinja2::EmptyValue>; V1 = nonstd::variants::variant<jinja2::EmptyValue, bool,
std::basic_string<char>, std::basic_string<wchar_t>, long int, double, nonstd::vptr::value_ptr<std::vector<jinja2::Value>, nonstd::vptr::detail::default_clone<std::vector<jinja2::Value>>,
std::default_delete<std::vector<jinja2::Value>>>, nonstd::vptr::value_ptr<std::unordered_map<std::basic_string<char>, jinja2::Value>,
nonstd::vptr::detail::default_clone<std::unordered_map<std::basic_string<char>, jinja2::Value>>>, std::default_delete<std::unordered_map<std::basic_string<char>, jinja2::Value>>>,
jinja2::GenericList, jinja2::GenericMap, nonstd::vptr::value_ptr<jinja2::UserCallable, nonstd::vptr::detail::default_clone<jinja2::UserCallable>, std::default_delete<jinja2::UserCallable>>>>; R =
jinja2::Value]'
```

```

1323 /home/travis/build/flexferrum/Jinja2Cpp/thirdparty/nonstd/variant-light/include/nonstd/variant.hpp:1735:43: [ skipping 5 instantiation contexts, use -ftemplate-backtrace-limit=0 to disable ]
1324 /home/travis/build/flexferrum/Jinja2Cpp/thirdparty/nonstd/variant-light/include/nonstd/variant.hpp:1871:45: required from 'typename nonstd::variants::detail::VisitorImpl<sizeof... (V), Visitor, V
...>::result_type nonstd::variants::visit(const Visitor&, const V& ...) [with Visitor = jinja2::detail::UCInvoker<const UserCallableTest_SimpleUserCallableWithParams2_Test::TestBody()::<lambda(const
string&, const string&)>&>; V = {nonstd::variants::variant<jinja2::EmptyValue, bool, std::basic_string<char>, std::allocator<char>>, std::basic_string<wchar_t,
std::char_traits<wchar_t>, std::allocator<wchar_t>>>, long int, double, nonstd::vptr::value_ptr<std::vector<jinja2::Value, std::allocator<jinja2::Value>>>,
nonstd::vptr::detail::default_clone<std::vector<jinja2::Value, std::allocator<jinja2::Value>>>>, std::default_delete<std::vector<jinja2::Value, std::allocator<jinja2::Value>>>>,
nonstd::vptr::value_ptr<std::unordered_map<std::basic_string<char>, std::char_traits<char>, std::allocator<char>>>, jinja2::Value, std::hash<std::basic_string<char>, std::char_traits<char>,
std::allocator<char>>>>, std::equal_to<std::basic_string<char>, std::char_traits<char>, std::allocator<char>>>>, std::allocator<std::pair<const std::basic_string<char>, std::char_traits<char>,
std::allocator<char>>>, jinja2::Value>>>, nonstd::vptr::detail::default_clone<std::unordered_map<std::basic_string<char>, std::char_traits<char>, std::allocator<char>>>, jinja2::Value,
std::hash<std::basic_string<char>, std::char_traits<char>, std::allocator<char>>>>, std::equal_to<std::basic_string<char>, std::char_traits<char>, std::allocator<char>>>>,
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jinja2::GenericMap, nonstd::vptr::value_ptr<jinja2::UserCallable, nonstd::vptr::detail::default_clone<jinja2::UserCallable>, std::default_delete<jinja2::UserCallable>>>,
nonstd::variants::detail::TX<nonstd::variants::detail::S11>, nonstd::variants::detail::TX<nonstd::variants::detail::S12>, nonstd::variants::detail::TX<nonstd::variants::detail::S13>,
nonstd::variants::detail::TX<nonstd::variants::detail::S14>, nonstd::variants::detail::TX<nonstd::variants::detail::S15>>, nonstd::variants::variant<jinja2::EmptyValue, bool,
std::basic_string<char>, std::char_traits<char>, std::allocator<char>>>, std::basic_string<wchar_t, std::char_traits<wchar_t>, std::allocator<wchar_t>>>, long int, double,
nonstd::vptr::value_ptr<std::vector<jinja2::Value, std::allocator<jinja2::Value>>>, nonstd::vptr::detail::default_clone<std::vector<jinja2::Value, std::allocator<jinja2::Value>>>>,
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Specialization

```
template <typename T>  
T max(T x, T y) {  
    return (x > y) ? x : y;  
}
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Specialization

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```
template <>  
Matrix max(Matrix x, Matrix y) {  
    return (x[0][0] > y[0][0]) ? x : y;  
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Explicitly **specialize**
a template with some
concrete type



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Matrix c = max<Matrix>(a, b);
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Matrix c = max<Matrix>(a, b);
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Specialized version
will be called

Specialization

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template <typename T>  
T max(T x, T y) {  
    return (x > y) ? x : y;  
}
```

← Primary template
definition

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template <>  
Matrix max(Matrix x, Matrix y) {  
    return (x[0][0] > y[0][0]) ? x : y;  
}
```

← Explicitly **specialize**
a template with some
concrete type

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Matrix c = max<Matrix>(a, b);
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← Specialized version
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Specialization

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T max(T x, T y) {
    return (x > y) ? x : y;
}
```

```
void foo() {
    Matrix a, b;
    Matrix c = max<Matrix>(a, b);
}
```

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template <>
Matrix max(Matrix x, Matrix y) {
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Matrix max(Matrix x, Matrix y) {
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```

error: specialization of 'T max(T, T)
[with T = Matrix]' after instantiation
749 | Matrix max(Matrix x, Matrix y) {
^

Order of declaration matters!

```
template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
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```
void foo() {
    Matrix a, b;
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}
```

```
template <>
Matrix max(Matrix x, Matrix y) {
    return (x[0][0] > y[0][0]) ? x : y;
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```
error: specialization of 'T max(T, T)
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    ^
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```
template <typename T>
T max(T x, T y) {
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}
```

```
void foo() {
    Matrix a, b;
    Matrix c = max<Matrix>(a, b);
}
```

```
template <>                                     [with  
Matrix max(Matrix x, Matrix y) {             749  
    return (x[0][0] > y[0][0]) ? x : y;  
}
```

Order of declaration matters!
If instantiation comes first,
before specialization => there
will be a compilation error.



```
error: specialization of 'T max(T, T)
[with T = Matrix]' after instantiation
749 | Matrix max(Matrix x, Matrix y) {
      |                                     ^
```

```
template <typename T>  
T max(T x, T y) {  
    return (x > y) ? x : y;  
}
```

```
template <>  
Matrix max(Matrix x, Matrix y) = delete;
```

```
template <typename T>  
T max(T x, T y) {  
    return (x > y) ? x : y;  
}
```

```
template <>  
Matrix max(Matrix x, Matrix y) = delete;
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You can **prohibit** anyone to specialize your template for some concrete classes.


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template <typename T>
T max(T x, T y) {
    return (x > y) ? x : y;
}
```

```
template <>
Matrix max(Matrix x, Matrix y) = delete;
```

You can **prohibit** anyone to specialize your template for some concrete classes. But again: this specialization should be placed before any **instantiation**!

Template classes

Template classes

```
class Vector {  
    size_t size_;  
    size_t cap_;  
    int* data_;  
public:  
    Vector(size_t initial_capacity) {  
        size_ = 0;  
        cap_ = initial_capacity;  
        data_ = new int[cap_];  
    }  
  
    int& operator[](size_t index) {  
        return data_[index];  
    }  
};
```

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class Vector {
    size_t size_;
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public:
    Vector(size_t initial_capacity) {
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        return data_[index];
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template<typename T>
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public:
    Vector(size_t initial_capacity) {
        size_ = 0;
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        data_ = new T[cap_];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

Template classes

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class Vector {
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public:
    Vector(size_t initial_capacity) {
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        data_ = new T[cap_];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

```
Vector<int>    v1{16};
Vector<float>  v2{8};
Vector<Matrix> v3{};
```

Template classes

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template<typename T>
class Vector {
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    Vector(size_t initial_capacity) {
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Implemented (almost) the same.

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Compiler again finds all possible actual template parameters.

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Vector<int>    v1{16};
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Implemented (almost) the same.

Compiler again finds all possible actual template parameters.

Ang generates... well, some part of corresponding classes.

<https://godbolt.org/z/4qqqhqbWs>

Template classes

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template<typename T>
class Vector {
    size_t size_;
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public:
    Vector(size_t initial_capacity) {
        size_ = 0;
        cap_ = initial_capacity;
        data_ = new T[cap_];
    }

    T& operator[](size_t index) {
        return data_[index]->size;
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Build finished OK

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    Vector(size_t initial_capacity) {
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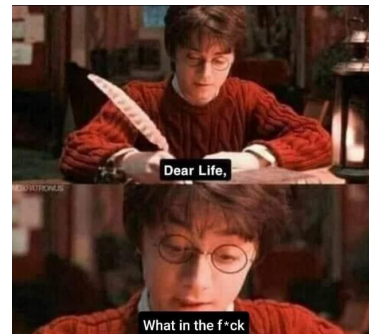
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Vector<int>    v1{16};
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Build finished OK

Why???

What is `data_[index]->size`, if `data_` is `int*`?



Template classes

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Instantiation of functions inside
template classes is made **lazily**.

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Vector<int>    v1{16};
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Vector<Matrix> v3{};
```

Build finished OK

Instantiation of functions inside template classes is made **lazily**.

If there are no uses of some function, it will **not** be generated during monomorphization.

Template classes

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class Vector {
    size_t size_;
    size_t cap_;
    T* data_;
public:
    Vector(size_t initial_capacity) {
        size_ = 0;
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```
Vector<int> v1{16};
int x = v1[10];
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In instantiation of
'T& Vector<T>::operator[](size_t)
[with T = int;
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error: base operand of '->' is not a pointer
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We have a **usage**, so, compiler tried
to generate operator[] (and **failed**)

Template classes

Why instantiation of functions in template classes is lazy?

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1. To reduce compilation time,
2. To reduce size of binary,

Template classes

Why instantiation of functions in template classes is lazy?

1. To **reduce** compilation time,
2. To **reduce** size of binary,

It is a bit counter-intuitive, but **uncontrolled generation of code** can be a problem (imagine that you have many template arguments)

Template classes

Why instantiation of functions in template classes is lazy?

1. To **reduce** compilation time,
2. To **reduce** size of binary,
3. You can indeed use only **some parts** of the template class for actual template parameter,

Template classes

Why instantiation of functions in template classes is lazy?

1. To **reduce** compilation time,
2. To **reduce** size of binary,
3. You can indeed use only **some parts** of the template class for actual template parameter,
4. It will break some meta-programming stuff (will discuss later)

Template classes

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        return data_[index]->size;
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```

This is a direct order to
compiler: **instantiate** it now!

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template class Vector<int>;

Vector<int> v1{16};
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| ^~~~~

It is rarely used as **laziness** of template classes instantiation is a default and preferable way.

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

Template classes: specialization

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template <typename T, typename U>
struct Pair {
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};
```

```
template <>
struct Pair<int, int> {
    int first;
    int second;

    int getSum() {
        return first + second;
    }
};
```



usual specialization, will work
when both types are ints

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    int getSum() {
        return first + second;
    }
};
```



usual specialization, will work
when both types are ints

```
Pair<int, int> p2{3, 5};
std::cout << p2.getSum();
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```



this is **partial** specialization

still a template class, but
one of template parameters
reduced

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```



this is **partial** specialization

still a template class, but
one of template parameters
reduced

```
Pair<double, double> p2(3.14);
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```

```
template <>
struct Pair<int, int> {
    int first;
    int second;

    int getSum() {
        return first + second;
    }
};
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```

```
Pair<int, int> p(3);
```

```
template <>
struct Pair<int, int> {
    int first;
    int second;

    int getSum() {
        return first + second;
    }
};
```

Will it compile?

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```

```
Pair<int, int> p(3);
```

```
template <>
struct Pair<int, int> {
    int first;
    int second;

    int getSum() {
        return first + second;
    }
};
```

Template classes: specialization

Will it compile? Which specialization will be chosen?

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
Pair<int, int> p(3);
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```

```
template <>
struct Pair<int, int> {
    int first;
    int second;

    int getSum() {
        return first + second;
    }
};
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```


Will it compile? Which specialization will be chosen?

```
Pair<int, int> p(3);
```

```
<source>:27:24: error: no matching
function for call to 'Pair<int,
int>::Pair(int)'
27 |     Pair<int, int> p2(3);
```

```
template <>
struct Pair<int, int> {
    int first;
    int second;

    int getSum() {
        return first + second;
    }
};
```



Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```

Which specialization will be chosen?

The general rule: **the most specific** specialization is chosen.

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val), second(val) {}
};
```

Which specialization will be chosen?

The general rule: **the most specific** specialization is chosen.

Specialization forms a partial order over "more-specialized-than" relation, described [here](#).

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};

template <typename T>
struct Pair<int, T> {
    int first;
    T second;

    void print() {
        std::cout << "key = " << first
            << "; data = " << second
            << std::endl;
    }
};
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};

template <typename T>
struct Pair<int, T> {
    int first;
    T second;

    void print() {
        std::cout << "key = " << first
                    << "; data = " << second
                    << std::endl;
    }
};
```

```
template <typename T>
using PairForTreap = Pair<int, T>;
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};

template <typename T>
struct Pair<int, T> {
    int first;
    T second;

    void print() {
        std::cout << "key = " << first
                    << "; data = " << second
                    << std::endl;
    }
};
```

```
template <typename T>
using PairForTreap = Pair<int, T>;

PairForTreap<float> f{13, 5.23};
f.print();
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};

template <typename T>
struct Pair<int, T> {
    int first;
    T second;

    void print() {
        std::cout << "key = " << first
                    << "; data = " << second
                    << std::endl;
    }
};
```

```
template <typename T>
using PairForTreap = Pair<int, T>;

PairForTreap<float> f{13, 5.23};
f.print();
```

Another example of **partial specialization** (first type argument is int) + using to just name this specialization.

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T, typename U>
struct Pair<T*, U*> {
    T* first;
    U* second;

    bool has_null_pointers() {
        return first == nullptr || second == nullptr;
    }
};
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T, typename U>
struct Pair<T*, U*> {
    T* first;
    U* second;

    bool has_null_pointers() {
        return first == nullptr || second == nullptr;
    }
};
```

```
double d = 3.14;
Pair<Matrix*, double*> p4{nullptr, &d};
std::cout << p4.has_null_pointers();
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T, typename U>
struct Pair<T*, U*> {
    T* first;
    U* second;

    bool has_null_pointers() {
        return first == nullptr || second == nullptr;
    }
};
```

```
double d = 3.14;
Pair<Matrix*, double*> p4{nullptr, &d};
std::cout << p4.has_null_pointers();
```

Partial specialization for case of pointers.

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T, typename U>
struct Pair<T*, U*> {
    T* first;
    U* second;

    bool has_null_pointers() {
        return first == nullptr ||
               second == nullptr;
    }
};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val),
                second(val) {}
};
```


Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T, typename U>
struct Pair<T*, U*> {
    T* first;
    U* second;

    bool has_null_pointers() {
        return first == nullptr ||
               second == nullptr;
    }
};
```

```
double d = 3.14;
Pair<double*, double*> p4{nullptr, &d};
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val),
                second(val) {}
};
```

Which specialization will be chosen?

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T, typename U>
struct Pair<T*, U*> {
    T* first;
    U* second;

    bool has_null_pointers() {
        return first == nullptr ||
               second == nullptr;
    }
};
```

```
double d = 3.14;
Pair<double*, double*> p4{nullptr, &d};
error: ambiguous template instantiation for
'struct Pair<double*, double*>'
```

```
template <typename T>
struct Pair<T, T> {
    T first;
    T second;

    Pair(T val): first(val),
                 second(val) {}
};
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<Vector<T>, Vector<T>> {
    T first_element_left;
    T first_element_right;

    Pair(Vector<T>& v1, Vector<T>& v2) {
        first_element_left = v1[0];
        first_element_right = v2[0];
    }
};
```

Template classes: specialization

```
template <typename T, typename U>
struct Pair {
    T first;
    U second;
};
```

```
template <typename T>
struct Pair<Vector<T>, Vector<T>> {
    T first_element_left;
    T first_element_right;

    Pair(Vector<T>& v1, Vector<T>& v2) {
        first_element_left = v1[0];
        first_element_right = v2[0];
    }
};
```

```
Vector<int> v1;
Vector<int> v2;

Pair<Vector<int>,
    Vector<int>> pv(v1, v2);

Vector<float> v3;
Vector<float> v4;
Pair<Vector<float>,
    Vector<float>> pv2(v3, v4);
```

Specialization will work for
any variants of vectors

Templates: non-type parameters

Templates: non-type parameters

```
template<typename T>
class Vector {
    size_t size_;
    size_t cap_;
    T* data_;
public:
    Vector(size_t initial_capacity) {
        size_ = 0;
        cap_ = initial_capacity;
        data_ = new T[cap_];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

Templates: non-type parameters

```
template<typename T>
class Vector {
    size_t size_;
    size_t cap_;
    T* data_;
public:
    Vector(size_t initial_capacity) {
        size_ = 0;
        cap_ = initial_capacity;
        data_ = new T[cap_];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

What if we want to work with vectors, which capacity is **fixed** and known in compile time?

Templates: non-type parameters

```
template<typename T, int cap>
class Vector {
    size_t size_;
    size_t cap_;
    T* data_;
public:
    Vector(size_t initial_capacity) {
        size_ = 0;
        cap_ = initial_capacity;
        data_ = new T[cap_];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

What if we want to work with vectors, which capacity is **fixed** and known in compile time?

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

What if we want to work with vectors, which capacity is **fixed** and known in compile time?

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

What if we want to work with vectors, which capacity is **fixed** and known in compile time?

```
FixedSizeVector<int, 16> fsv;
FixedSizeVector<float, 2> fsv2;
```

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

What if we want to work with vectors, which capacity is **fixed** and known in compile time?

```
FixedSizeVector<int, 16> fsv;
FixedSizeVector<float, 2> fsv2;
```

Works as **usual**: for each actual value of **cap**, new class will be generated.

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

What if we want to work with vectors, which capacity is **fixed** and known in compile time?

```
FixedSizeVector<int, 16> fsv;
FixedSizeVector<float, 2> fsv2;
```

Works as **usual**: for each actual value of **cap**, new class will be generated.

Of course it is **dangerous**! Type sets are limited, set of values - not really (it is **huge**).

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};

template<typename T> class FixedSizeVector <T, 0>;
```

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

Specialization over non-type parameters
still works.

```
template<typename T> class FixedSizeVector <T, 0>;
```

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

Specialization over non-type parameters still works. This one is an analogue of "`=delete`;" for functions specialization.

```
template<typename T> class FixedSizeVector <T, 0>;
```

Templates: non-type parameters

```
template<typename T, int cap>
class FixedSizeVector {
    size_t size_;
    T* data_;
public:
    FixedSizeVector () {
        size_ = 0;
        data_ = new T[cap];
    }

    T& operator[](size_t index) {
        return data_[index];
    }
};
```

```
template<typename T> class FixedSizeVector <T, 0>;
```

```
FixedSizeVector<int, 0> fsv;
```

error: aggregate FixedSizeVector<int, 0> fsv' has incomplete type and cannot be defined

Specialization over non-type parameters still works. This one is an analogue of "**=delete;**" for functions specialization.

Templates: compile time execution

Templates: compile time execution

So, we can define a template with `non-type` (for example numeric) parameter...

Templates: compile time execution

So, we can define a template with `non-type` (for example numeric) parameter... but also specialize it for some values.

Templates: compile time execution

So, we can define a template with `non-type` (for example numeric) parameter... but also specialize it for some values.

Sounds like a good combination for recursion!

Templates: compile time execution (teaser)

```
template <int N>  
int fib() {  
    return fib<N-1>() + fib<N-2>();  
}
```

Templates: compile time execution (teaser)

```
template <int N>  
int fib() {  
    return fib<N-1>() + fib<N-2>();  
}
```

```
template <> int fib<1>() { return 1; }  
template <> int fib<2>() { return 1; }
```

Templates: compile time execution (teaser)

```
template <int N>
int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> int fib<1>() { return 1; }
template <> int fib<2>() { return 1; }

int main() {
    std::cout << fib<4>();
    return 0;
}
```

Templates: compile time execution (teaser)

```
template <int N>
int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> int fib<1>() { return 1; }
template <> int fib<2>() { return 1; }

int main() {
    std::cout << fib<4>();
    return 0;
}
```

If compiler will be very straightforward here, it will generate 4 specializations of fib: fib<1>, fib<2>, fib<3>, fib<4> and just run them

(nothing interesting here)

<https://godbolt.org/z/rxYGjve86>

Templates: compile time execution (teaser)

```
template <int N>
int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> int fib<1>() { return 1; }
template <> int fib<2>() { return 1; }

int main() {
    std::cout << fib<900>();
    return 0;
}
```

If compiler will be very straightforward here, it will generate 4 specializations of fib: fib<1>, fib<2>, fib<3>, fib<4>, ..., fib<900> and just run them

(nothing interesting here, just exponential complexity, good like with waiting for result)

<https://godbolt.org/z/rxYGjve86>

Templates: compile time execution (teaser)

```
template <int N>
int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> int fib<1>() { return 1; }
template <> int fib<2>() { return 1; }

int main() {
    std::cout << fib<900>();
    return 0;
}
```

But if this is an optimizing compiler...

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}
```

```
template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}
```

```
int main() {
    std::cout << fib<900>();
    return 0;
}
```

But if this is an optimizing compiler and maybe with some help from us...

`inline` is hint for compiler: please try to place the code of this function directly in caller

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

But if this is an optimizing compiler and maybe with some help from us the **magic** will happen:

```
int fib<1>():
    mov     eax, 1
    ret

int fib<2>():
    mov     eax, 1
    ret

main:
    sub     rsp, 8
    mov     esi, 372038192
    mov     edi, OFFSET FLAT:_ZSt4cout
    call    std::basic_ostream<char, std::
    xor     eax, eax
    add     rsp, 8
    ret
```

<https://godbolt.org/z/3YrdvdYe9>

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

But if this is an optimizing compiler and maybe with some help from us the **magic** will happen:

```
int fib<1>():
    mov     eax, 1
    ret

int fib<2>():
    mov     eax, 1
    ret

main:
    sub     rsp, 8
    mov     esi, 372038192 ←
    mov     edi, OFFSET FLAT:_ZSt4cout
    call    std::basic_ostream<char, std:
    xor     eax, eax
    add     rsp, 8
    ret
```

<https://godbolt.org/z/3YrdvdYe9>

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

- 1) Compiler **inlined** each and every template function body inside it's callers

Templates: compile time execution (teaser)

```
inline int fib_1() { return 1; }

inline int fib_2() { return 1; }

inline int fib_3() { return fib_2() + fib_1(); }

inline int fib_4() { return fib_3() + fib_2(); }

void main() {
    cout << fib_4();
}
```

Templates: compile time execution (teaser)

```
inline int fib_2() { return 1; }  
  
inline int fib_3() { return fib_2() + 1; }  
  
inline int fib_4() { return fib_3() + fib_2(); }  
  
void main() {  
    cout << fib_4();  
}
```



Templates: compile time execution (teaser)

```
inline int fib_3() { return 1 + 1; }  
  
inline int fib_4() { return fib_3() + 1; }  
  
void main() {  
    cout << fib_4();  
}
```



Templates: compile time execution (teaser)

```
inline int fib_4() { return 1 + 1 + 1; }  
  
void main() {  
    cout << fib_4();  
}
```



Templates: compile time execution (teaser)

```
void main() {  
    cout << 1 + 1 + 1;  
}
```



Templates: compile time execution (teaser)

```
void main() {  
    cout << 3;  
}
```



Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

- 1) Compiler **inlined** each and every template function body inside it's callers

```
int fib<1>():
    mov     eax, 1
    ret

int fib<2>():
    mov     eax, 1
    ret

main:
    sub     rsp, 8
    mov     esi, 372038192 ←
    mov     edi, OFFSET FLAT:_ZSt4cout
    call    std::basic_ostream<char, std:
    xor     eax, eax
    add     rsp, 8
    ret
```

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

- 1) Compiler **inlined** each and every template function body inside it's callers
- 2) Removed bodies of all **inlined** specializations (except explicit one)

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

- 1) Compiler **inlined** each and every template function body inside its callers
- 2) Removed bodies of all **inlined** specializations (except explicit one)
- 3) Didn't itself suffer from exponential complexity! Why?

Templates: compile time execution (teaser)

```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}

template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}

int main() {
    std::cout << fib<900>();
    return 0;
}
```

- 1) Compiler **inlined** each and every template function body inside its callers
- 2) Removed bodies of all **inlined** specializations (except explicit one)
- 3) Didn't itself suffer from exponential complexity! Because templates instantiations are cached (hello, **memoization**!)

Templates: compile time execution (teaser)



```
template <int N>
inline int fib() {
    return fib<N-1>() + fib<N-2>();
}
```

```
template <> inline int fib<1>() {...}
template <> inline int fib<2>() {...}
```

```
int main() {
    std::cout << fib<900>();
    return 0;
}
```

So, we will have an answer immediately, without any calculations in run-time.

```
int fib<1>():
    mov     eax, 1
    ret
int fib<2>():
    mov     eax, 1
    ret
main:
    sub     rsp, 8
    mov     esi, 372038192 ←
    mov     edi, OFFSET FLAT:_ZSt4cout
    call    std::basic_ostream<char, std:
    xor     eax, eax
    add     rsp, 8
    ret
```

Templates: compile time execution (teaser #2)

The same can be done much easier (and without currying favor with the compiler).

Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

Templates: compile time execution (teaser #2)

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```
template<int X, int Y> // X^Y
struct Pow {
    static const int result = ???;
};
```

Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

```
template<int X, int Y> //  $X^Y = X * (X^{(Y-1)})$ 
struct Pow {
    static const int result = ???;
};
```

Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

```
template<int X, int Y> //  $X^Y = X * (X^{(Y-1)}) = X * (Pow(X, Y-1))$ 
struct Pow {
    static const int result = ???;
};
```

Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

```
template<int X, int Y> //  $X^Y = X * (X^{(Y-1)}) = X * (Pow(X, Y-1))$ 
struct Pow {
    static const int result = X * Pow<X, Y - 1>::result;
};
```

Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

```
template<int X, int Y> //  $X^Y = X * (X^{(Y-1)}) = X * (Pow(X, Y-1))$ 
struct Pow {
    static const int result = X * Pow<X, Y - 1>::result;
};

template<int X>
struct Pow<X, 1> {
    static const int result = X;
};
```


Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

```
template<int X, int Y> //  $X^Y = X * (X^{(Y-1)}) = X * (Pow(X, Y-1))$ 
struct Pow {
    static const int result = X * Pow<X, Y - 1>::result;
};

template<int X>
struct Pow<X, 1> {
    static const int result = X;
};

int main() {
    std::cout << Pow<2, 30>::result;
    return 0;
}
```

Templates: compile time execution (teaser #2)

This time we want to calculate the power of a number.

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template<int X, int Y> //  $X^Y = X * (X^{(Y-1)}) = X * (Pow(X, Y-1))$ 
struct Pow {
    static const int result = X * Pow<X, Y - 1>::result;
};
```

```
template<int X>
struct Pow<X, 1> {
    static const int result = X;
};

int main() {
    std::cout << Pow<2, 30>::result;
    return 0;
}
```

```
1  main:
2      push    rbp
3      mov     rbp, rsp
4      mov     esi, 1073741824 ←
5      mov     edi, OFFSET FLAT:_ZSt4cout
6      call    std::basic_ostream<char, std::
7      mov     eax, 0
8      pop     rbp
9      ret
```

Templates and inheritance

Templates and inheritance

Templates as well as inheritance is an instrument to write a `polymorphic` code.

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Templates as well as inheritance is an instrument to write a **polymorphic** code.

Inheritance allows you to use **subtyping polymorphism**. It is a **dynamic** polymorphism (implemented via virtual calls).

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Templates and inheritance

Templates as well as inheritance is an instrument to write a **polymorphic** code.

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On the other hand, templates define **static polymorphism**, that is evaluated completely in compile time.

Templates and inheritance

Templates as well as inheritance is an instrument to write a **polymorphic** code.

Inheritance allows you to use **subtyping polymorphism**. It is a **dynamic** polymorphism (implemented via virtual calls).

Templates are very different. Because of specializations, each **instantiation** of a template can be very **different** from the primary template. So, no LSP.

On the other hand, templates define **static polymorphism**, that is evaluated completely in compile time.

But what if combine both approaches?

CRTP via Templates

CRTP via Templates

Task: we need a mechanism to count instances of a class.

C RTP via Templates

Task: we need a mechanism to count instances of **any** class.

```
template <typename T>  
struct Counter {
```

```
};
```

```
template <typename T>
struct Counter {
    static int objects_created;
    static int objects_alive;

    Counter() {
        ++objects_created;
        ++objects_alive;
    }

    Counter(const Counter&) {
        ++objects_created;
        ++objects_alive;
    }
protected:
    ~Counter() {
        --objects_alive;
    }
};
```

```

template <typename T>
struct Counter {
    static int objects_created;
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    Counter() {
        ++objects_created;
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    }

    Counter(const Counter&) {
        ++objects_created;
        ++objects_alive;
    }
protected:
    ~Counter() {
        --objects_alive;
    }
};

template <typename T> int Counter<T>::objects_created(0);
template <typename T> int Counter<T>::objects_alive(0);

```

template <typename T> ← Strange, we have T, but it is not used!

```
struct Counter {  
    static int objects_created;  
    static int objects_alive;
```

```
    Counter() {  
        ++objects_created;  
        ++objects_alive;  
    }
```

```
    Counter(const Counter&) {  
        ++objects_created;  
        ++objects_alive;  
    }
```

```
protected:
```

```
    ~Counter() {  
        --objects_alive;  
    }
```

```
};
```

```
template <typename T> int Counter<T>::objects_created(0);
```

```
template <typename T> int Counter<T>::objects_alive(0);
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```
template <typename T>
struct Counter {
    static int objects_created;
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    Counter() {
        ++objects_created;
        ++objects_alive;
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    Counter(const Counter&) {
        ++objects_created;
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    }
protected:
    ~Counter() {
        --objects_alive;
    }
};
```

```
class Foo: Counter<Foo> {};
class Bar: Counter<Bar> {};
```



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template <typename T>
struct Counter {
    static int objects_created;
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class Foo: Counter<Foo> {};
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Instantiation of Counter
for Foo and Bar

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template <typename T>
struct Counter {
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Static vars are created
for each instantiation

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class Foo: Counter<Foo> {};
class Bar: Counter<Bar> {};
```

Instantiation of Counter
for Foo and Bar

Static vars are created
for each instantiation

```
int main() {
    {
        Foo f;
        Foo *pf = new Foo();
        Bar b;
    }
    return 0;
}
```

```

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struct Counter {
    static int objects_created;
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    }
};

```

```

class Foo: Counter<Foo> {};
class Bar: Counter<Bar> {};

```

Instantiation of Counter
for Foo and Bar

Static vars are created
for each instantiation

```

int main() {
    {
        Foo f;
        Foo *pf = new Foo();
        Bar b;
        cout << Counter<Foo>::objects_created;
        cout << Counter<Foo>::objects_alive;
        cout << Counter<Bar>::objects_created;
        cout << Counter<Bar>::objects_alive;
    }
    return 0;
}

```

```

template <typename T>
struct Counter {
    static int objects_created;
    static int objects_alive;

    Counter() {
        ++objects_created;
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    }
protected:
    ~Counter() {
        --objects_alive;
    }
};

```

```

class Foo: Counter<Foo> {};
class Bar: Counter<Bar> {};

```

Instantiation of Counter
for Foo and Bar

Static vars are created
for each instantiation

```

int main() {
    {
        Foo f;
        Foo *pf = new Foo();
        Bar b;
        cout << Counter<Foo>::objects_created; // 2
        cout << Counter<Foo>::objects_alive;    // 2
        cout << Counter<Bar>::objects_created;  // 1
        cout << Counter<Bar>::objects_alive;    // 1
    }
    return 0;
}

```

```

template <typename T>
struct Counter {
    static int objects_created;
    static int objects_alive;

    Counter() {
        ++objects_created;
        ++objects_alive;
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class Foo: Counter<Foo> {};
class Bar: Counter<Bar> {};

```

Instantiation of Counter
for Foo and Bar

Static vars are created
for each instantiation

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int main() {
    Foo f;
    Foo *pf = new Foo();
    Bar b;
    cout << Counter<Foo>::objects_created; // 2
    cout << Counter<Foo>::objects_alive;   // 2
    cout << Counter<Bar>::objects_created;  // 1
    cout << Counter<Bar>::objects_alive;    // 1

    cout << Counter<Foo>::objects_created;
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    cout << Counter<Bar>::objects_created;
    cout << Counter<Bar>::objects_alive;
    return 0;
}

```

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class Foo: Counter<Foo> {};
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```

Instantiation of Counter
for Foo and Bar

Static vars are created
for each instantiation

```

int main() {
    Foo f;
    Foo *pf = new Foo();
    Bar b;
    cout << Counter<Foo>::objects_created; // 2
    cout << Counter<Foo>::objects_alive;   // 2
    cout << Counter<Bar>::objects_created;  // 1
    cout << Counter<Bar>::objects_alive;    // 1

    cout << Counter<Foo>::objects_created;  // 2
    cout << Counter<Foo>::objects_alive;    // 1
    cout << Counter<Bar>::objects_created;  // 1
    cout << Counter<Bar>::objects_alive;    // 0
    return 0;
}

```

```
template <typename T>
struct Counter {
    static int objects_created;
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    Counter() {
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    }
};
```

class Foo: Counter<Foo> {};
class Bar: Counter<Bar> {};

Instantiation of Counter
for Foo and Bar

```
class Vector: Counter<Vector> {
    ...
};
```



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struct Counter {
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```

```

class Foo: Counter<Foo> {};      Instantiation of Counter
class Bar: Counter<Bar> {};      for Foo and Bar

```

```

template <typename T>
class Vector: Counter<Vector<T>> {
    ...
};

```

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```

```

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class Bar: Counter<Bar> {};      for Foo and Bar

```

```

template <typename T>
class Vector: Counter<Vector<T>> {
    ...
};

```

Counter will be instantiated for each instantiation of Vector!

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template <typename T>
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```

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template <typename T>
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Counter will be instantiated for each instantiation of Vector!

Such trick is called CRTP:
Curiously Recurring Template Pattern

```

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struct Counter {
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```

```

class Foo: Counter<Foo> {};      Instantiation of Counter
class Bar: Counter<Bar> {};      for Foo and Bar

```

```

template <typename T>
class Vector: Counter<Vector<T>> {
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};

```

Counter will be instantiated for each instantiation of Vector!

Such trick is called CRTP:
Curiously Recurring Template Pattern

And it is much more powerful!

CRTP via Templates

CRTP allows you to `mix-in` new functionality into your classes.

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Actually, it is not about "`is-a`" relationship, so, we use `private` inheritance here.

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Works really well thanks to multiple inheritance: you can `mix-in` a lot of features into your classes because of it.

C RTP via Templates

C RTP allows you to `mix-in` new functionality into your classes.

Actually, it is not about "`is-a`" relationship, so, we use `private` inheritance here.

Works really well thanks to multiple inheritance: you can `mix-in` a lot of features into your classes because of it.

But that's not all! You can simulate subtyping polymorphism and virtual calls with C RTP.


```
template<typename Derived>
class Person {
public:
    void print() {
        static_cast<Derived*>(this)->print_impl();
    }
};
```

```
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class Person {
public:
    void print() {
        static_cast<Derived*>(this)->print_impl();
    }
};
```

Here we specify that:

1. Derived **must** have print_impl method
2. Person instance can be casted into Derived **statically**.

```
template<typename Derived>
class Person {
public:
    void print() {
        static_cast<Derived*>(this)->print_impl();
    }
};

class Student: public Person<Student> {
public:
    void print_impl() {
        std::cout << "student print";
    }
};
```

Here we specify that:

1. Derived **must** have print_impl method
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```

template<typename Derived>
class Person {
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    void print() {
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    }
};

class Student: public Person<Student> {
public:
    void print_impl() {
        std::cout << "student print";
    }
};

template<typename Derived>
void polymorphic_print(Person<Derived>& p) {
    p.print();
}

```

Here we specify that:

1. Derived **must** have print_impl method
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```

template<typename Derived>
class Person {
public:
    void print() {
        static_cast<Derived*>(this)->print_impl();
    }
};

class Student: public Person<Student> {
public:
    void print_impl() {
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};

template<typename Derived>
void polymorphic_print(Person<Derived>& p) {
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Here we specify that:

1. Derived **must** have print_impl method
2. Person instance can be casted into Derived **statically**.

Student& can be
substituted here



```
template<typename Derived>
class Person {
public:
    void print() {
        static_cast<Derived*>(this)->print_impl();
    }
};
```

```
class Student: public Person<Student> {
public:
    void print_impl() {
        std::cout << "student print";
    }
};
```

```
template<typename Derived>
void polymorphic_print(Person<Derived>& p) {
    p.print();
}
```

```
Student s;
polymorphic_print(s);
```


Here we specify that:

1. Derived **must** have print_impl method
2. Person instance can be casted into Derived **statically**.

```
template<typename Derived>
class Person {
public:
    void print() {
        static_cast<Derived*>(this)->print_impl();
    }
};
```

```
class Student: public Person<Student> {
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    void print_impl() {
        std::cout << "student print";
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};
```

```
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Student s;
polymorphic_print(s);  in some situations type here can be omitted
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template<typename Derived>
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```

Student s;
polymorphic_print(s);  in some situations type here can be omitted

```

Here we specify that:

1. Derived **must** have print_impl method
2. Person instance can be casted into Derived **statically**.

Here we have the same behaviour as with **virtual calls**, but for free (however, not so convenient, as many things should be done manually)

Further directions

- More detailed templates implementation + meta-programming + compile-time evaluation

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- Is it really necessary to specify a type explicitly each time for `instantiation`?

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- More detailed templates implementation + meta-programming + compile-time evaluation
- Is it really necessary to specify a type explicitly each time for `instantiation`?
- `Variadic` templates and `requires`

Not So Tiny Task №9 (1 point)



Generalize data structure that you've implemented in NSTT #1, #3 and #4 with help of templates!



Not So Tiny Task №9 (1 point)

Generalize data structure that you've implemented in NSTT #1, #3 and #4 with help of templates!

Not So Tiny Task №10 (1 point)

Implement a `mix-in` to limit number of your class instances. Classes with such functionality should be successfully created only when there are less than specified number of instances, otherwise their construction should fail.

Use `CRTP` and non-type template argument (for the limit)