

# Reinforcement Learning for ICU Treatment Planning

Goureeesh Chandra	31	TVE22CS069
Ivin Mathew Kurian	33	TVE22CS075
Muhammed Farhan	39	TVE22CS094
Rethin Francis	72	LTVE22CS149

**Advisor: Prof. Divya S K**

College of Engineering, Trivandrum  
Dept. of Computer Science & Engineering

October 16, 2025

# Outline of Presentation

- 1 Introduction
- 2 Problem Statement and Objectives
- 3 Design Methodology and Algorithms
- 4 Implementation Setup Framework
- 5 Implementation Results
- 6 Individual Contributions
- 7 Future Works (Project Phase-2)
- 8 Conclusion
- 9 References

# Introduction

Doctors face tough decisions treating critically ill ICU patients with conditions like sepsis. Our AI system learns from ICU data to suggest better plans.

Using reinforcement learning, it builds a "digital twin" simulator to predict patient responses to treatments safely. This enables personalized, safer plans, supporting doctors and reducing risks/costs.

# Problem Statement and Objectives

**Problem:** Timely, personalized ICU treatment decisions are challenging due to dynamic conditions and fragmented data.

- High-stakes, dynamic trajectories.
- Incomplete EHR data.
- AI limited to historical mimicry.

**Objectives:**

- Build patient simulator from EHR data.
- Optimize RL policies safely.
- Provide clinical decision support.

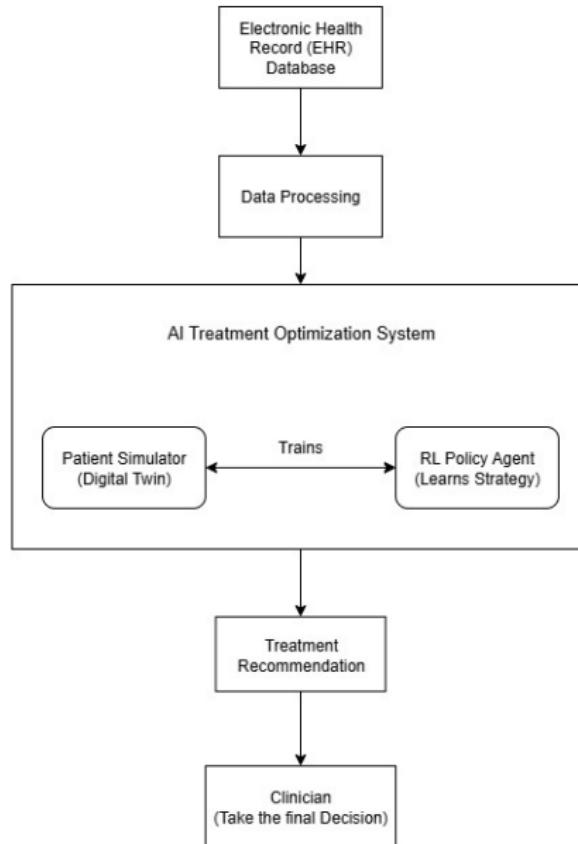
# Design Methodology and Algorithms

This approach is inspired by DreamerV3 and its clinical adaptation in medDreamer.

## Two sequential stages:

- ① Train the **Patient Simulator (World Model)** to predict patient outcomes.
- ② Train the **RL Agent (Policy)** using the simulator to discover optimal treatments.

# Design Methodology and Algorithms: Diagrams



# Algorithm 1: Patient Simulator Training

**Goal:** Learn patient health dynamics from EHR data to create a reliable "digital twin".

**Steps:**

- ① **Initialization:** Neural network parameters  $\phi$ 
  - Encoder
  - Dynamics predictor
  - Prediction heads (reconstruction, rewards, outcomes)
- ② **Training Loop:** For multiple epochs:
  - ① Sample patient trajectories (observations, actions, rewards)
  - ② Encode observations to latent states  $s_t$
  - ③ Predict next latent state  $s_{t+1}$  given  $s_t$  and action  $a_t$
  - ④ Reconstruct observations and predict rewards/outcomes
  - ⑤ Compute combined loss and update  $\phi$  via backpropagation
- ③ **Output:** Trained Patient Simulator for realistic patient trajectories

## Algorithm 2: RL Agent Training

**Goal:** Train an optimal treatment policy safely in the simulated environment.

**Steps:**

- ① Load trained Patient Simulator (weights frozen)
- ② Initialize RL Agent: policy network  $\theta$  (actor), value network  $\psi$  (critic)

### Phase 1: Clinically Grounded Policy Initialization

- Generate hybrid trajectories (real data + short simulator rollouts)
- Train actor and critic:
  - Critic: evaluate long-term state values
  - Actor: choose actions leading to high-value states

## Algorithm 2 (cont.): Strategic Refinement

### **Phase 2: Strategic Refinement through Long-Horizon Imagination**

- Generate fully imagined trajectories using the Patient Simulator
- Fine-tune actor and critic to improve long-term planning

**Output:** Final trained **Optimal Treatment Policy** that recommends actions given a patient's current state

# Implementation Setup Framework

## 4.1 Hardware and Software Requirements

- **Hardware:** GPU-enabled system (RTX 4060/4090 or cloud GPUs).
- **Software:** Python, PyTorch, Ray RLlib, pandas, NumPy, scikit-learn.

## 4.2 Implementation Environment Setup

- Datasets: MIMIC-III, MIMIC-IV, eICU.
- Preprocessing: Clean and structure EHR data into trajectories.
- Frameworks: PyTorch for neural networks, Ray RLlib for RL.

# Implementation Results

**Phase-1 Results:** As this is Phase-1, full implementation is ongoing.  
Preliminary results include:

- Data preprocessing completed for MIMIC-IV demo.
- Patient Simulator training initiated (e.g., loss curves placeholder).
- Synthetic FHIR Bundle generation for data validation.

# Individual Contributions

- **Goureesh Chandra (TVE22CS069):** Algorithm design and data preprocessing.
- **Ivin Mathew Kurian (TVE22CS075):** Model implementation and simulator training, and notebook development.
- **Muhammed Farhan (TVE22CS094):** RL agent training and evaluation.
- **Rethin Francis (LTVE22CS149):** Data handling and FHIR mapping.

## Future Works (Project Phase-2)

- Complete full RL training and evaluation on larger datasets.
- Extend framework to other diseases (e.g., diabetes, cancer care).
- Incorporate multi-modal data (genomics, imaging).
- Clinician-in-the-loop evaluation and real-world validation.

# Conclusion

- We are developing a **model-based reinforcement learning framework** trained on ICU data for clinical decision support.
- By building a **digital twin of patients**, the system safely explores treatment strategies without direct risk to patients.
- The approach enables **personalized and safer treatment recommendations**, reducing unnecessary interventions and improving patient outcomes.
- Future work includes extending the model to more diverse patient populations and validating in real-world clinical settings.

# References



Qianyi Xu, Dilruk Perera, Gousia Habib, and Mengling Feng (2025).

medDreamer: Model-Based Reinforcement Learning with Latent Imagination on Complex EHRs for Clinical Decision Support.

*arXiv preprint arXiv:2505.19785.*



Arthur Komorowski et al. (2021).

Challenges with reinforcement learning model transportability for sepsis treatment in emergency care.

*Critical Care Medicine.*



Ali Amarahmadi, Mattias Ohlsson, and Kobra Etminani (2023).

Deep learning prediction models based on EHR trajectories: A systematic review.

*Journal of Biomedical Informatics.*



Mila Nambiar et al. (2023).

Deep offline reinforcement learning for real-world treatment optimization applications.

*arXiv preprint arXiv:2302.07549.*



Anon. Authors (2023).

Mastering Memory Tasks with World Models.

*ICML.*



Edward De Brouwer, Javier González Hernández, and Stephanie Hyland (2022).

Predicting the impact of treatments over time with uncertainty aware neural differential equations.

*AISTATS.*



Flemming Kondrup et al. (2023).

Towards Safe Mechanical Ventilation Treatment Using Deep Offline Reinforcement Learning.

*AAAI-23.*

# Thank You!