

QUESTION 1

(a) WE KNOW THAT FOR $\omega_0 = 0$, $x[n] = 1$

AND THAT THE CONSTANT SEQUENCE

IS ANNIHILATED BY A FILTER

WITH A ZERO AT $\omega = 0$.

WE THEN EXPECT $x[n] = e^{j\omega_0 n}$

TO BE ANNIHILATED BY $H(z) = (z - e^{j\omega_0})$

PROOF:

$$\begin{aligned} x[n] * h[n] &= \sum_k h[k] x[n-k] = e^{j\omega_0 n} \sum_k h[k] e^{-j\omega_0 k} \\ &= e^{j\omega_0 n} \underbrace{H(e^{j\omega_0})}_{=0} = 0 \end{aligned}$$

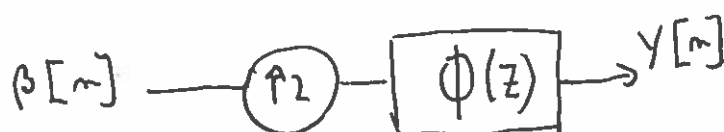
□

CONSEQUENTLY SINCE $x[n] = e^{j\omega_0 n} \cos \omega_0 n = e^{j\omega_0 n} \frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{2}$,

WE HAVE THAT $x[n]$ IS ANNIHILATED

BY $H(z) = (z - e^{j\omega_0})(z - e^{-j\omega_0})$

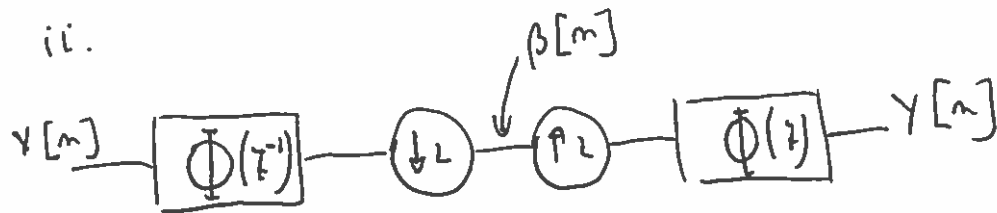
(b) i.



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Q1.(b) ii.



SINCE $\langle \phi[n], \phi[n-2k] \rangle = \delta_{k,0}$ THE SYSTEM

PERFORMS AN ORTHOGONAL PROJECTION OF

$x[n]$ ON $V = \text{SPAN} \{ \phi[n-2k] \}_{k \in \mathbb{Z}}$.

iii.

WE NEED $\psi[n]$ TO BE SUCH THAT

$$\langle \psi[n-2k], \phi[n-2\ell] \rangle = \delta_{k,\ell}$$

THIS IS ACHIEVED BY SETTING

$$\psi(z) = -z^{-1} \phi(-z^{-1}) = (-z^{-1} + 3 - 3z - z^2) / (2\sqrt{5})$$

MOREOVER

$$d[k] = \langle x[n], \psi^T[n-2k] \rangle$$

WHERE $\psi^T[n] = \psi[-n]$.

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QUESTION 2

$$(a) \quad \hat{X}(z) = \frac{1}{2} G_0(z) H_0(z) X(z) + \frac{1}{2} G_0(z) H_0(-z) X(-z) \\ + \frac{1}{2} G_1(z) H_1(z) X(z) - \frac{1}{2} G_1(z) H_1(-z) X(-z)$$

THIS LEADS TO THE FOLLOWING PR
CONDITIONS:

$$\begin{cases} G_0(z) H_0(z) + G_1(z) H_1(z) = 2 & (\text{DISTORTION-FREE CONDITION}) \\ G_0(z) H_0(-z) - G_1(z) H_1(-z) = 0 & (\text{ALIAS-FREE CONDITION}) \end{cases}$$

NOTE THE MINUS SIGN IN THE 'ALIAS-FREE' CONDITION.

(b) FOR THE UPPER BRANCH WE IMPOSE
THE USUAL ORTHOGONALITY CONDITIONS:

$$\begin{cases} G_0(z) G_0(z^{-1}) + G_0(-z) G_0(-z^{-1}) = 2 \\ H_0(z) = G_0(z^{-1}) \end{cases}$$

FOR THE LOWER BRANCH, BECAUSE OF
THE DELAY WE NOW IMPOSE

$$\langle g_0[n], g_1[n-2k-1] \rangle = 0$$

WHICH LEADS TO

$$G_1(z) = G_0(-z^{-1})$$

AND THEN TO $H_1(z) = G_1(z^{-1})$

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Q2.

$$(c) \quad G_0(z) = \frac{1}{\sqrt{2}} (1 + z^{-1}) \quad \text{--- } H_0 \quad \circ$$

GIVEN $G_0(z)$ WE HAVE THAT

$$H_0(z) = G_0(z^{-1}) = \frac{1}{\sqrt{2}} (1 + z)$$

$$G_1(z) = G_0(-z^{-1}) = \frac{1}{\sqrt{2}} (1 - z)$$

$$H_1(z) = G_1(z^{-1}) = \frac{1}{\sqrt{2}} (1 - z^{-1})$$

(d)

WE FIRST NOTE THAT THE SOLUTION TO THIS PROBLEM IS NOT UNIQUE, MOREOVER BY CONSTRUCTION

$$G_0(z) H_0(z) + G_0(-z) H_0(-z) = 2$$

THROUGH SPECTRAL FACTORIZATION WE PICK

$$H_0(z) = \frac{\sqrt{2}}{8} (1 + z) (1 + z^{-1}) (-z + 4 - z^{-1})$$

$$\text{AND} \quad G_0(z) = \frac{1}{2\sqrt{2}} (1 + z) (1 + z^{-1})$$

THE ABOVE FILTERS ARE SYMMETRIC AS REQUESTED.

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Q 2 (ol) CONTINUED

BECAUSE OF THE DELAY, THE NEW

BIORTHOGONAL CONDITIONS ARE:

$$G_1(z) = H_0(-z) = \frac{\sqrt{2}}{8} (1-z)(1-z^{-1})(z+4+z^{-1})$$

AND

$$H_1(z) = G_0(-z) = \frac{1}{2\sqrt{2}} (1-z)(1-z^{-1}) .$$

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QUESTION 3

(a) i. SINCE $\tilde{\varphi}_i(t) = \sum_{k=1}^3 a_{i,k} \varphi_k(t)$

AND GIVEN THAT

$$\langle \tilde{\varphi}_i(t), \varphi_j(t) \rangle = \delta_{i,j}$$

WE CAN WRITE

$$\langle \tilde{\varphi}_i(t), \varphi_j(t) \rangle = \sum_{k=1}^3 a_{i,k} \langle \varphi_k(t), \varphi_j(t) \rangle = \delta_{i,j} \quad (1)$$

MOREOVER

$$\langle \varphi_1, \varphi_2 \rangle = 0.5, \quad \langle \varphi_1, \varphi_3 \rangle = 0.5, \quad \langle \varphi_2, \varphi_3 \rangle = 0.5$$

$$\text{AND} \quad \langle \varphi_i, \varphi_i \rangle = 1.5 \quad i=1,2,3.$$

COMBINING (1) WITH THE ABOVE EQUATIONS LEADS TO:

$$\begin{cases} \frac{3}{2} a_{1,1} + \frac{a_{1,2}}{2} + \frac{a_{1,3}}{2} = 1 \\ \frac{a_{1,1}}{2} + \frac{3}{2} a_{1,2} + \frac{a_{1,3}}{2} = 0 \\ \frac{a_{1,1}}{2} + \frac{a_{1,2}}{2} + \frac{3}{2} a_{1,3} = 0 \end{cases}$$

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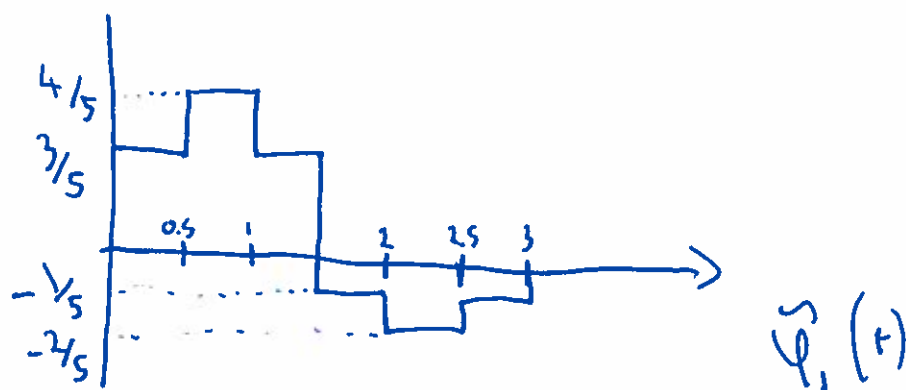
Q3 (a) i.

THEFORE

$$a_{1,1} = \frac{4}{5}, \quad a_{1,2} = -\frac{1}{5}, \quad a_{1,3} = -\frac{1}{5},$$

BY SYMMETRY WE CAN FIND THE OTHER $a_{i,n}$ 'S.

(i).



$\tilde{\psi}_2(t)$ AND $\tilde{\psi}_3(t)$ ARE GENERATED BY COMPUTING CIRCULAR SHIFTS BY ONE OF $\tilde{\psi}_1(t)$.

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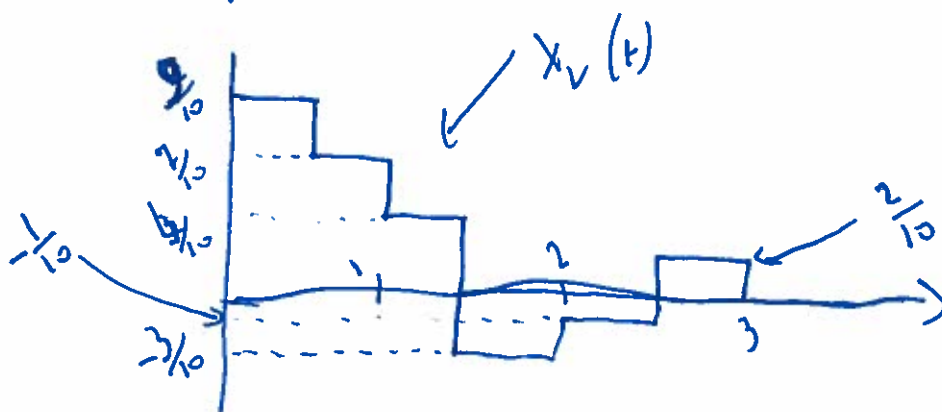
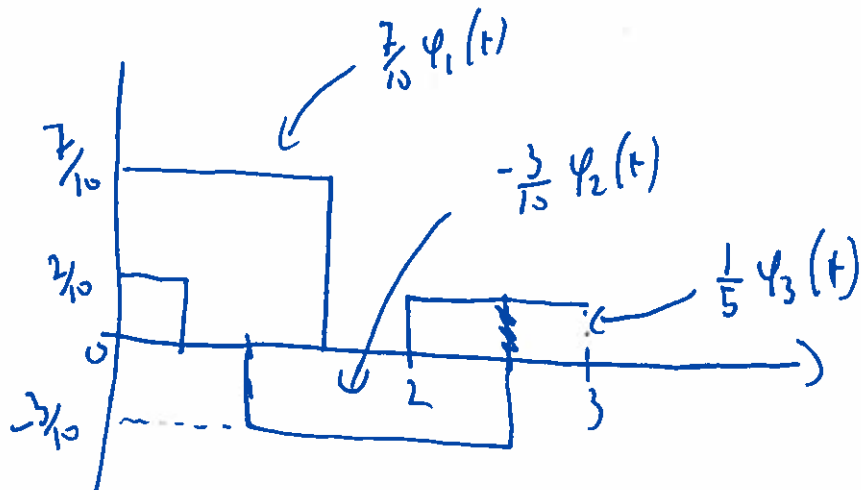
Q.3 (b)

$$i. \quad \langle x(t), \tilde{\varphi}_1(t) \rangle = \frac{1}{2} \left(\frac{3}{5} + \frac{4}{5} \right) = \frac{7}{10}$$

$$\langle x(t), \tilde{\varphi}_2(t) \rangle = -\frac{1}{2} \left(\frac{2}{5} + \frac{1}{5} \right) = -\frac{3}{10}$$

$$\langle x(t), \tilde{\varphi}_3(t) \rangle = \frac{1}{2} \left(\frac{3}{5} - \frac{1}{5} \right) = \frac{1}{5}$$

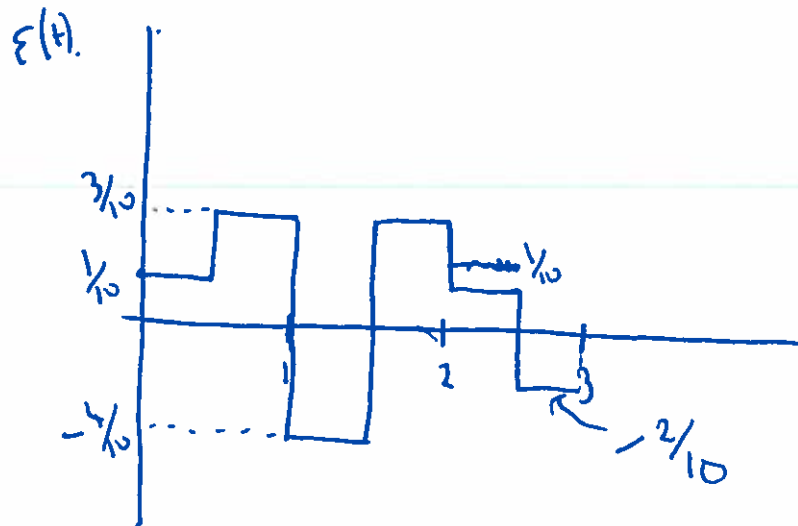
(i.)



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Q3 (b) iii



CONSEQUENTLY

$$\langle f(t), \psi_1(t) \rangle = \langle f(t), \psi_2(t) \rangle = \langle f(t), \psi_3(t) \rangle = 0$$

THIS MEANS THAT

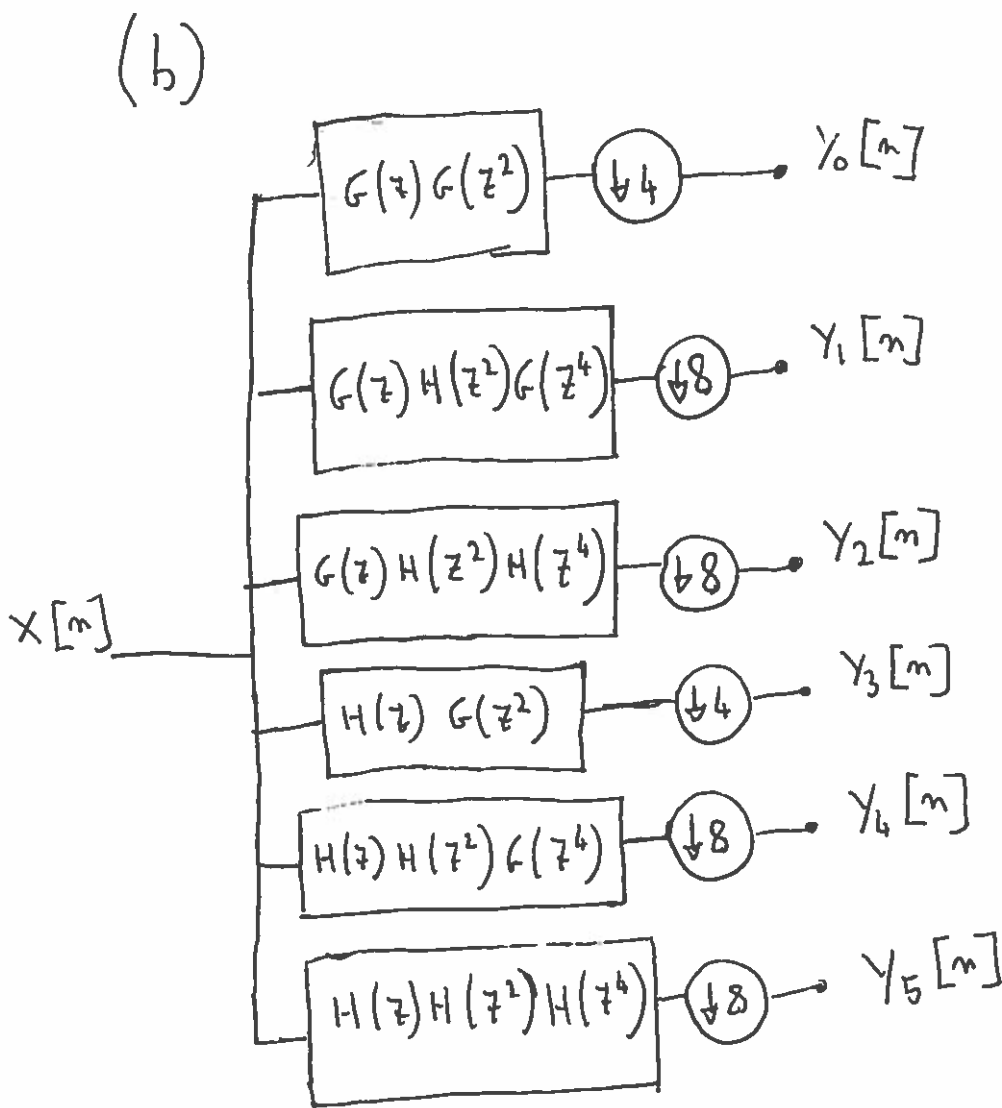
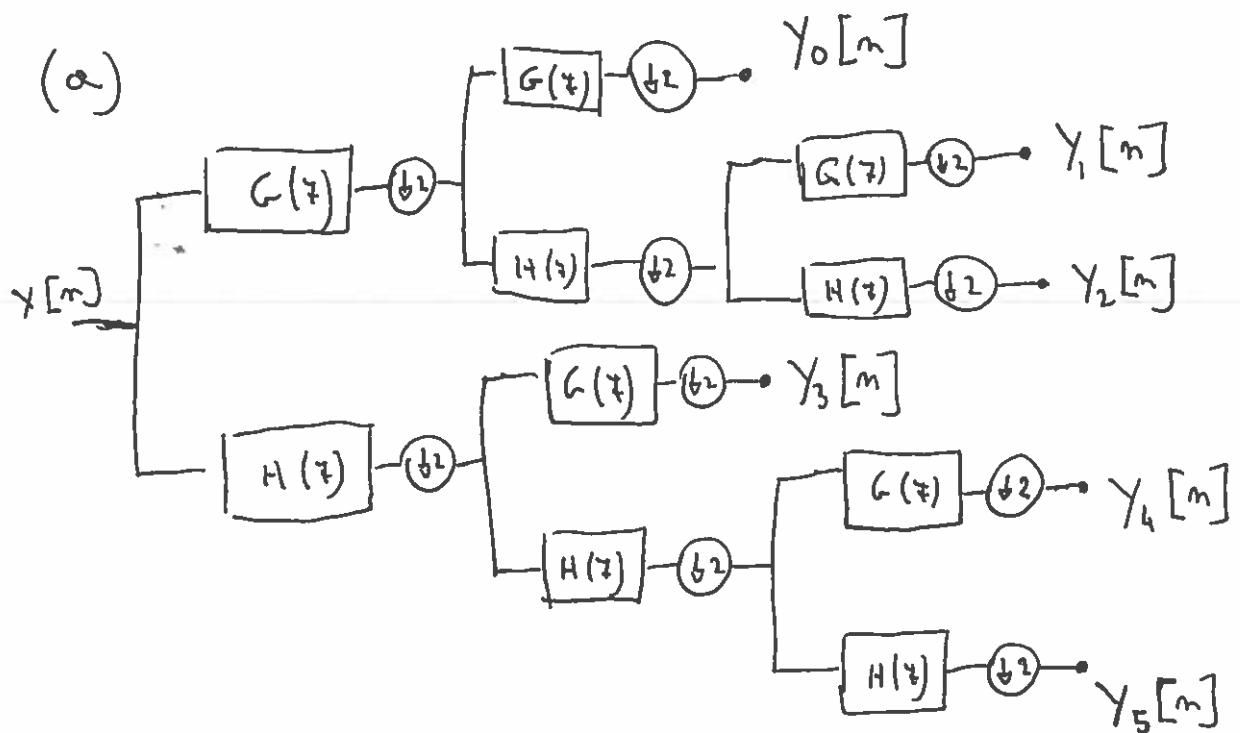
$$f(t) \perp V$$

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QUESTION 4

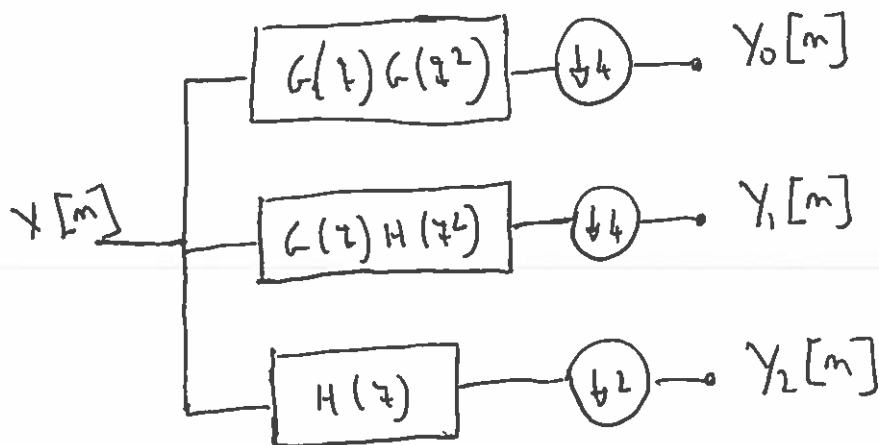


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Q.4 (c)

i.



ii.

WE FIRST NOTE THAT

$$H(1) = 0.$$

MOREOVER

$$\frac{dH(z)}{dz} = \sqrt{2} (2z + 2 - 2z^{-2} - 2z^{-3})$$

THEREFORE

$$\left. \frac{dH(z)}{dz} \right|_{z=1} = 0$$

THIS MEANS THAT $H(z)$ HAS TWO
ROOT AT $\omega=0$ AND SO ANNIHILATES
LINEAR POLYNOMIALS. THIS IMPLIES ~~$y_1[n]$~~
~~AND~~ $y_1[n] = y_2[n] = 0$. SINCE $G(z)$ HAS
NO ZEROS AT $\omega=0$, $y_0[n] \neq 0$.