## Homework 03

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#### Question 01:

1.1

```
Fi. \{w_1, w_2, ..., w_c\} = \max\{0, \max\{w_y^T x_i - w_{y_i}^T x_i\}\}

when y = y_i

max (w_y^T x_i - w_{y_i}^T x_i) when y \neq y_i

\frac{\partial R}{\partial w_c} = \frac{\partial (\max\{w_y^T x_i - w_{y_i}^T x_i\})}{\partial w_c}

\frac{\partial R}{\partial w_c} = \frac{\partial (\max\{w_y^T x_i - w_{y_i}^T x_i\})}{\partial w_c}

= x_i when y \neq y_i

= -x_i otherwise.
```

1.2

```
Algorithm 1: Multiclass Perceptron

Input: A training set (x_1, y_1), \ldots, (x_n, y_n)

Initialization: w_1 = \cdots = w_C = 0

Repeat:

Andony pick an example (2n, y_n)

make prediction \hat{y} = \text{argmanks}(x_0, y_n)

if \hat{y} \neq y_n then

w\hat{y} \leftarrow w\hat{y} - 2n

wy_n \leftarrow wy_n + 2n
```

1.3

```
Algorithm 2: Multiclass Perceptron with kernel function k(\cdot, \cdot)

1 Input: A training set (x_1, y_1), \dots, (x_n, y_n)

2 Initialize: \alpha_{c,n} = 0 for all c \in [C] and i \in [n]

3 Repeat:

Andom by pick an example (x_n, y_n)

make prediction \hat{y} = \text{eign}(\hat{z}_{m+1}^N) \propto_m k(x_m, x_n)

if \hat{y} \neq y_n, then

x_n \leftarrow x_n + y_n
```

#### **Question 02:**

2.1

$$\frac{\partial x}{\partial v_{1}} = \frac{\partial y}{\partial \hat{y}} = \frac{\partial y}{\partial v_{2}}$$

$$= \frac{-ye^{-y\hat{y}}}{1+e^{-y\hat{y}}} = \frac{\partial y}{\partial v_{2}}$$

$$= \frac{-ye^{-y\hat{y}}}{1+e^{-y\hat{y}}} = \frac{\partial y}{\partial v_{2}}$$

$$= \frac{-ye^{-y\hat{y}}}{1+e^{-y\hat{y}}} = \frac{\partial y}{\partial v_{2}}$$

2.2

$$\frac{2.2}{3\omega_{1}} = \frac{31}{3\alpha_{1}} \frac{3\alpha_{1}}{3\omega_{1}} + \frac{31}{3\alpha_{2}} \frac{3\alpha_{2}}{3\omega_{1}}$$

$$= \frac{31}{3\hat{y}} \frac{3\hat{y}}{3\hat{y}} \frac{3\hat{$$

### 2.3

# Forward Propogation:

a1 = 21W1 + 22W2

a2 = 72W1 + 73W2

01 = max 10, a, }

02 = max [0, a2]

y = 01V1 + 02V2

## Backward Propogation: update:

w1 ← w1 - N[(5/4))-1)y(v1H(a1)21+ V2H(a2)22)]

ω2 ← ω2 - η [ σ(yŷ -1) y ( ViH(ai) x2 + V2 H(02) Z3)]

V1 ← V1 - 1 (-5)(-yŷ)yo1

V2 ← V2 - N(0(yy)-1)y02

### **Question 03:**

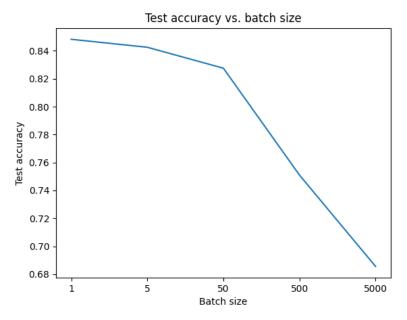
### 3.1.6

Plot of Training accuracy vs. epochs using plot\_train\_process.py



Plot of Testing accuracy and training time w.r.t batch size using plot\_batch.py





3.2.2

<u>Statictics for each batch size:</u>

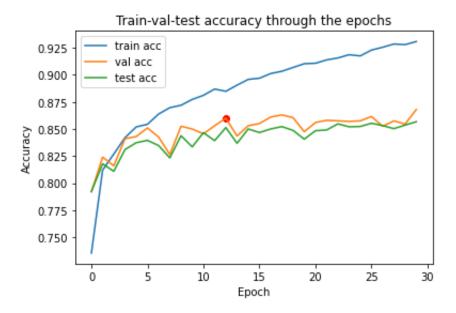
Batch Size = 1 Epochs = 13 Best Epoch = 10

```
Test Accuracy at Epoch = 0.8482
Batch Size = 5
Epochs = 13
Best Epoch = 10
Test Accuracy at Epoch 10 = 0.8425
Batch size = 50
Epochs = 38
Best Epoch = 35
Test Accuracy at Epoch 35 = 0.8275
Batch size = 500
Epochs = 42
Best Epoch = 39
Test Accuracy at Epoch 39 = 0.751
Batch size = 5000
Epochs = 161
Best Epoch = 158
Test Accuracy at Epoch 158 = 0.6856
Thus, for each batch the number of training epochs required to get the best model are:
Batch Size = 1, number of epochs = 13
Batch Size = 5, number of epochs = 13
Batch Size = 50, number of epochs = 38
Batch Size = 500, number of epochs = 42
Batch Size = 5000, number of epochs = 161
Number of gradient updates required to get the best model for each batch size:
Batch Size = 1, number of epochs = 10
Batch Size = 5, number of epochs = 10
Batch Size = 50, number of epochs = 35
Batch Size = 500, number of epochs = 39
Batch Size = 5000, number of epochs = 158
```

#### 3.2.3

- (i) No smaller batch size does not mean faster training. This is because smaller batch size means taking smaller steps and thereby it won't train the model faster but might infact be a bit slower as compared to bigger batch sizes.
- (ii) Increasing the batch size does not guarantee better test accuracy. This is because the batch size has a direct relation to the variation of the gradient estimator. Batch size controls the accuracy of the estimate of the error gradient when training neural networks.
- (iii) large batch size means the model makes very large gradient updates and takes more number of epochs to reach a convergence to minimizer. This does not necessarily mean that large batch sizes require less gradient updates

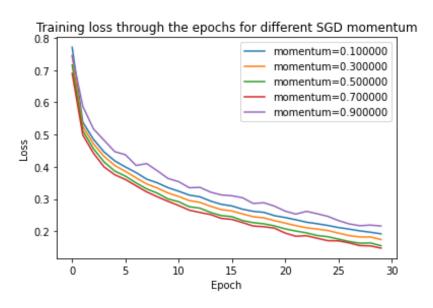
(i)



(ii) The trend after early stopping point: training accuracy increases greatly for each epoch whereas the testing and validation accuracy don't show any improvement but have a fluctuation within a certain range (iii) Setting it to zero or really small means that as soon as the performance measure gets worse from one epoch to the next, the training is terminated. This might not be ideal since, the model's performance is noisy and might go up or down from one epoch to the next. What we really care about is that the general trend should be improving.

3.4

(i)



(ii)

Based on this the suitable value of alpha is 0.7.