Izzat Mukhanov

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Summary

I'm an engineer who likes programming, learning and team-working. I prefer simplicity over complexity and knowledge over ignorance.

Education

- M.S. in Robotics, Control Engineering, Applied Informatics

 École Centrale de Nantes

 B.S. in Telecommunications
 2012 2014
- B.S. in Telecommunications
 Tashkent University of Information Technologies

Work Experience

- Engineer, developer (C, C++, Python, Node.js)

 Improvement and development of a cross-platform library libpointing

 which allows direct access to the USB-HID pointing devices

 and can apply different transfer functions to the raw input.

 Creation of Java, Python, Node.js bindings and distribution with npm, apt, brew, etc.

 Company: INRIA with Nicolas Roussel and Géry Casiez
- Master's Project (C++, Python, Matlab)
 Implementation of Pedestrian Detection and Tracking system [thesis] [video]
 using Computer Vision and Machine Learning engineer algorithms
 Laboratory: IRCCyN with Philippe Martinet
- Intern (Python)
 2013 (4 months)
 Development of <u>OpenSymoro+</u> (SYmbolic MOdeling of RObots),
 including 3D visualization, Symbolic Computing and UI using *PyOpenGL* and *wxPython* Laboratory: <u>IRCCyN</u> with <u>Wisama Khalil</u>
- Software engineer (Objective-C)
 Development of client-server applications for iOS and Cocos2D games
 Company: SSD
- Intern, software developer (C/C++)
 Low-level API development for Blu-ray disks processing
 Implementation of the logging system for the project
 Company: ProDVD
- Intern, software developer and instructor (C#.NET)
 Application development for book catalogization of the city libraries
 Database management (Microsoft SQL)
 Company: BePro

Professional Skills

- Knowledgeable:
 - o C, C++, Python
 - o Cross-platform development, documentation
 - Building, and packaging (OS X, Linux, Windows)
 - o Git. Mercurial. SVN
 - Design Patterns, Test Driven Development
 - Matlab
 - JavaScript, Node.js, npm, Three.js, jQuery
 - o HTML, CSS, Bootstrap, Markdown, Latex
- Familiar:
 - o Objective-C, Pharo, C#.NET, PHP, SQL
 - o Continuous integration, Jenkins
 - o OpenGL, OpenCV
 - ROS (Robot Operating System)
 - Programming in Val/V+ for industrial robots
- Theoretical background:
 - o Computer Vision, Machine Learning, Artificial Intelligence
 - Robot Programming, Modeling and Control
 - Algorithms and Data Structures
 - o Math, Optimization, Simulation

Publications

OpenSYMORO: An open-source software package for Symbolic Modelling of Robots
 2014 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (355)

Miscellaneous

- Highly adaptable in quickly changing technical environments with very strong organizational and analytical skills
- · Excellent interpersonal and communications skills
- Life-long learning oriented
- Driver's license

Languages

- English fluent
- French fluent
- Russian native
- Uzbek native

Hobbies

- Following online courses (MOOCs)
- Foreign languages
- · Gym and cycling
- Reading