IZZEDDIN TEETI

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Oxford Brookes University ${\bf Linked In/Izzeddin}$

EDUCATION & SELECTED AWARDS

D.Phil (PhD) Autonomous Vehicles Technologies. Oxford Brookes University, UK

Jan 2021 - present

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- Research topic: Novel Deep Neural Network Architecture for Intention & Trajectory Prediction in Autonomous Driving.
- Project lead for Oxford Brookes Racing Autonomous team.
- Supervisors: Prof Fabio Cuzzolin, Dr Andrew Bradley.

M.Sc Robotics (with distinction). King's College London, UK

Sep 2018 - Sep 2019

- Thesis: "An Innovative Automated Assessment System for Engineering Drawing Sheets". Based on Computer Vision.
- Supervisor: Dr. Michael Spratling, a Reader in Computational Neuroscience and Visual Cognition.
- Overall Score = Distinction.
- Prize for the best overall performance on the MSc in Robotics for the 2018-2019 cohort.

B.Sc Mechanical Engineering (Excellent). American University of Madaba, Jordan Sep 2012 - Aug 2016

- Final year project: "Autonomous Tracking Vehicle". Based on Machine Learning and Computer Vision.
- Overall GPA = 93.1%, excellent.
- Graduated with the first rank among engineering graduates (2016).
- Certificate of Academic Excellence and Dean's List (Semester average ≥ 84%) for all semesters (2012 2016).
- Undergraduate Academic Excellence Scholarship for four successive years

National High School Diploma (Tawjihi) in Scientific Stream. Arroub High School, Palestine

2012

- Overall Score = 98.7%.
- Award for being within the top three matriculants regionally.

INTERNSHIPS & SUMMER SCHOOLS

Incoming Applied Science Intern, Amazon, Berlin, Germany

Nov 2022 - March 2023

- Incoming intern at Amazon Germany.

International Computer Vision Summer School (ICVSS), Sicily, Italy

July 2022

- Attended the summer school and presented a poster.

Data Science Intern, Bayt.com, Amman, Jordan

June 2016 - Aug 2016

- Searched some techniques in Natural Language Processing (NLP), apply them using Python to improve the CV-processing algorithm for Bayt company (one of the largest employment agencies in the Middle East).
- Contact: Yousef Sawalha v.sawalha@bayt.com

SCHOLARSHIPS, GRANTS & AWARDS

_	International Joint Conference of Artificial Intelligence (IJCAI) Registration and Travel Grant (925 \$).	2022
_	Essay Competition Award at the International Computer Vision Summer School (ICVSS).	2022
_	Oxford Brookes University Full-time Funded Research (DPhil) Studentship (100,000 £).	2021 - 2023

- King's College London and the British Council full scholarship (42,990 £). 2018 2019
- King Abdullah II Design and Development Bureau sponsorship for undergraduate projects (2,800 \$).
- The American University of Madaba tuition fees Scholarship for excellent students (27,000 \$). 2012 2016

WORK EXPERIENCE

AI Project Lead

Oxford Brookes Racing Autonomous Team

Feb 2021 - present Oxford, UK

- Leading a team of 25 BSc and MSc students in developing an autonomous driving system for Formula-1 car. The team
 won 1st and 2nd places in UK IMechE Formula Student AI 2020 and 2021 competitions, respectively.
- Writing the team's yearly plan and milestones. Supervising budget, recruitment, and research&industry connections.
- Contact: Dr Andrew Bradley abradley@brookes.ac.uk

Robotics Lecturer, Full-time

Sep 2020 - Jan 2021

Ramallah, Palestine

Al-Zaytona University of Science and Technology

- Delivered courses and supervised labs for the BSc Robotics programme.
- Participated in modifying the BSc Robotics programme's structure to include latest technology and suit market needs.
- Contact: Dr Fahoum Shalabi fahoum.shalabi@zust.edu.ps

Machine Learning Engineer, Full-time

Nov 2019 - Aug 2020

Nazareth

Alpha Omega Biomedical Engineering

- Applied LSTM to build a GPi-navigation software that classified microelectrode recordings series and detected the Striatum-GPe-GPi borders online in Parkinson's disease, with an accuracy of 91.1%.
- Worked inside the operating room with high credentials neurologists, observed the algorithm's performance, recorded feedback, and modified the algorithm accordingly.
- Worked within an AGILE environment and wrote the Software Requirements Specification (SRS) for the GPi-Navigation software.
- Contact: Dr Amir Abedelqadir a.abedelqadir@alphaomega-eng.com

Research and Teaching Assistant, Full-time

Sep 2016 - June 2018

Birzeit University

Ramallah, Palestine

- Delivered laboratories, such as Control, Technical and Mechanical Drawing, Vibrations, Thermal Applications, Mechanics.
- Designed experiments in the labs, and delivered professional skills workshops for the students.
- Helped the department with administrative tasks and invigilate exams and tests.
- Contact: Mohammad Al Karaeen mkaraen@birzeit.edu

Research and Teaching Assistant, Part-time

Sep 2017 - June 2018

Palestine Polytechnic University

Hebron, Palestine

- Delivered Mechanical Drawing lab, and discussion lectures for Dynamics, Machines Dynamics, and Control Theory.
- Contact: Iyad Hashlamon iyad@ppu.edu

RESEARCH

Publications

- I. Teeti, S. Khan, A. Shahbaz, A. Bradley, and F. Cuzzolin. Vision-based Intention and Trajectory Prediction in Autonomous Vehicles: A Survey. Proceedings of the Thirty-First International Joint Conference on Artificial Intelligence (IJCAI22).
- A. Kanacı, I. Teeti, and F. Cuzzolin. Self-Supervised Pretraining for Object Detection in Autonomous Driving. Proceedings of the Thirty-First International Joint Conference on Artificial Intelligence (<u>IJCAI22</u>).
- I. Teeti, V. Musat, S. Khan, A. Rast, F. Cuzzolin, and A. Bradley. Vision in adverse weather: Augmentation using CycleGANs with various object detectors for robust perception in autonomous racing. Safe Learning for Autonomous Driving Workshop at International Conference on Machine Learning (ICML22).
- A. Benjumea, I. Teeti, F. Cuzzolin, and A. Bradley. YOLO-Z: Improving small object detection in YOLOv5 for autonomous vehicles. International Conference of Computer Vision (ICCV21).
- I. Fursa, E. Fandi, V. Musat, J. Culley, G. Esteller, I. Teeti, L. Bilous, I. V. Sluis, A. Rast, and A. Bradley. Worsening Perception: Real-Time Degradation of Autonomous Vehicle Perception Performance for Simulation of Adverse Weather Conditions. SAE International Journal of Connected and Automated Vehicles (SAE Intl. J CAV 2022).

Patents

Teeti, Izzeddin. 2020. Innovative Automatic Assessment System for Engineering Drawing Sheets. Palestine Patent 355, filed Oct 3, 2019, and issued Dec 15, 2020.

Reviewing

Serving as a reviewer in reputed conferences including NIPS, BMVC, WACV, CSA.

Invited Talks

- AI in Medical Applications, Palestinian Medical Students Association, Hebron University.

Feb 2022

- AI in Self Driving Cars, Google Developer Student Club at Palestine Polytechnic University.

Dec 2021

- Weaponized Computer Vision, ArabWIC Palestine.

May 2020

SKILLS

Programming Python, MATLAB, C++, Visual Basic, R, TCL

Framework Machine Learning (*PyTourch*, *TensorFlow*), Autonomous Cars (*CARLA*).

Software ANSYS, CATIA, SolidWorks, PTC Creo, AutoCAD, LATEX, Microsoft Office

Languages English (*Proficient User*), Arabic (*Native*), German (*Beginner*), Spanish (*Beginner*)

LEADERSHIP & EXTRACURRICULAR

Founder Fall, 2019

Palestinian Artificial Intelligence Community

Palestine

 I created the first Palestinian AI community which gathers the top students in a sustainable network that enhances their theoretical background and sharpens their practical skills.

Participant Fall, 2016
World Youth Alliance Amman, Jordan

- I participated in the Emerging Leaders of the Arab Region Program run by the World Youth Alliance (WYA).

Junior Consultant, Volunteer

2015 - 2016

Palestinian Medical Society

Bethlehem, Palestine

I helped the staff in launching their YouTube channel, and in implementing their campaign to their local communities.

Volunteer 2014 - 2015

Our Lady of Peace Center, Theodor-Schneller-Schule

Amman, Jordan

I volunteered to cheer children with special needs and children at orphans' schools.

Tourist GuideSummer, 2013 & Summer, 2014
Tent of Nations
Bethlehem, Palestine

- I escorted groups of tourists around the West Bank, explaining the history of each, and coordinate between the groups.

REFERENCES

Prof. Fabio Cuzzolin

Professor of Artificial Intelligence Director of the VAIL Laboratory School of Eng., Comp. and Math. Oxford Brookes University fabio.cuzzolin@brookes.ac.uk (+44) 01865 484526

Dr. Michael Spratling

Reader in Computational Neuroscience and Visual Cognition Department of Informatics King's College London michael.spratling@kcl.ac.uk (+44) 020 7848 2027

Dr. Amir Abedelgadir

Scrum Master, Development Manager Research and Development Alpha Omega Biomedical Engineering LTD a.abedelqadir@alphaomega-eng.com (+972) 54 286 5234