```
Requirement already satisfied: numdifftools in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: scipy>=0.8 in /usr/local/lib/python3.7/dist-packages (Requirement already satisfied: statsmodels>=0.6 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: algopy>=0.4 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: numpy>=1.9 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: pandas>=0.19 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: patsy>=0.4.0 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: python-dateutil>=2.7.3 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: pytz>=2017.2 in /usr/local/lib/python3.7/dist-packages Requirement already satisfied: six in /usr/local/lib/python3.7/dist-packages (from patents)
```

```
import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
from numpy.linalg import norm
from numdifftools import Gradient
import copy
from sklearn.datasets import make_regression
```

Regression

```
class Regression:
 def __init__(self,X):
   self.w = np.random.randn(X.shape[1]+1, 1)
 def model(self,X, w):
    if X.shape[1] !=w.shape[0]:
     x = np.hstack((X, np.ones((X.shape[0],1))))
   else:
     X = X
   return x.dot(w)
 def lost_function(self,X, y, w):
   m = len(y)
   if X.shape[1] !=w.shape[0]:
     x = np.hstack((X, np.ones((X.shape[0],1))))
   else:
     x = X
   return 1/(2*m) * np.sum((self.model(x, w) - y)**2)
 def grad(self,X, y, w):
   m = len(y)
   return 1/m * X.T.dot(self.model(X, w) - y)
 def gradient_descent(self,X, y, w, alpha=0.001,e = 0.001,n_iter = 10000):
   cost history = [] # création d'un tableau de stockage pour enregistrer l'évolution du
```

```
i = 0
 while norm(self.grad(X,y,w).T) >e :
      w = w - alpha * self.grad(X, y, w)
      # mise a jour du parametre w (formule du gradient descent)
      cost_history.append(self.lost_function(X, y, w)) # on enregistre la valeur du Cout
      i+=1
      if i>n_iter:
        break
  return w, cost_history
def fit(self,X,y,alpha = 0.001,e = 0.001,n_iter = 100000):
 x = np.hstack((X, np.ones((X.shape[0],1))))
  self.w,self.cost history = self.gradient descent(x,y,self.w,alpha,e,n iter)
def lost_courbe(self):
  plt.plot(range(len(self.cost_history)), self.cost_history)
def coef_determination(self,X,y):
 u = ((y - self.model(X, self.w))**2).sum()
 v = ((y - y.mean())**2).sum()
  return 1 - u/v
```

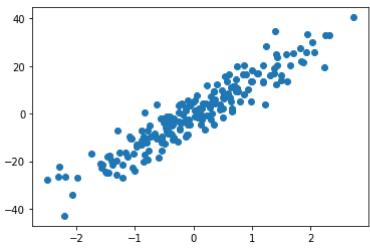
Dataset to test the algorithme

```
x,y = make_regression(n_samples=200,n_features=1,noise=5)
from sklearn.model_selection import train_test_split
X_train, y_train = x[:150], y[:150]
X_test, y_test = x[150:], y[150:]
print(X_train.shape)
print(X_test.shape)

(150, 1)
(50, 1)
```

```
plt.scatter(x,y)
```



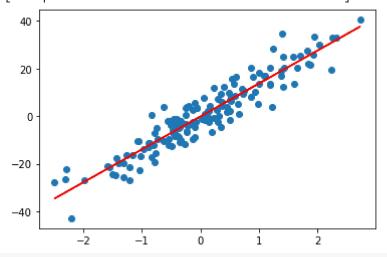


```
print(X_train.shape)
y_train = y_train.reshape((150,1))
y_test = y_test.reshape((50,1))
print(y_train.shape)
     (150, 1)
     (150, 1)
R = Regression(X_train)
R.w
     array([[0.52003023],
            [0.33285384]])
#Erreur initail
R.lost_function(X_train,y_train,R.w)
     105.6957445171955
R.fit(X_train,y_train)
R.lost_function(X_train,y_train,R.w)
     13.19936832629869
R.w
     array([[13.81204828],
            [-0.114275 ]])
R.lost_courbe()
      100
       80
       60
       40
       20
                   2000
                            4000
                                     6000
                                              8000
```

plt.scatter(X_train,y_train)

plt.plot(X_train,R.model(X_train,R.w),c = 'r')

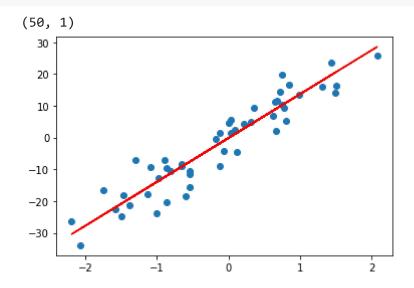
[<matplotlib.lines.Line2D at 0x7f2d3c11aed0>]



R.coef_determination(X_train,y_train)

0.8831910855472059

```
plt.scatter(X_test,y_test)
plt.plot(X_test,R.model(X_test,R.w),c = 'r')
X_test.shape
```



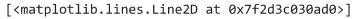
R.lost_function(X_test,y_test,R.w)

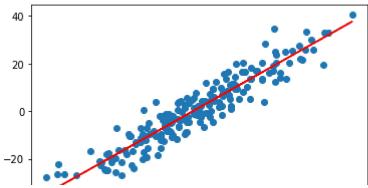
11.898624185183492

R.coef_determination(X_test,y_test)

0.8858715121110685

```
plt.scatter(x,y)
plt.plot(x,R.model(x,R.w),c = 'r')
```





▼ Exercice 1

```
from google.colab import drive
drive.mount("/content/drive/")
```

Drive already mounted at /content/drive/; to attempt to forcibly remount, call drive

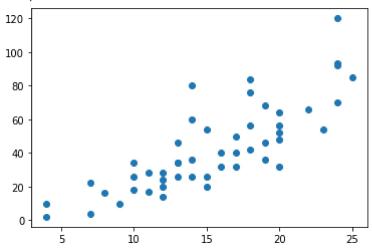
data_cars = pd.read_csv('/content/drive/My Drive/TP_machine_learning/cars.csv')

data_cars.head()

	Unnamed:	0	speed	dist
0		1	4	2
1		2	4	10
2		3	7	4
3		4	7	22
4		5	8	16

```
plt.scatter(data_cars['speed'],data_cars['dist'])
```

<matplotlib.collections.PathCollection at 0x7f2d3c14ad10>



```
X = np.array(data_cars['speed'])
y = np.array(data_cars['dist'])
print(X.shape)
print(y.shape)
     (50,)
     (50,)
X = X.reshape((X.shape[0],1))
y = y.reshape((y.shape[0],1))
X.shape
     (50, 1)
R1 = Regression(X)
R1.w
     array([[ 1.19573531],
            [-0.18256351]])
R1.lost_function(X,y,R1.w)
     522.3774213198348
plt.scatter(X,y)
plt.plot(X,R1.model(X,R1.w),c = 'r')
     [<matplotlib.lines.Line2D at 0x7f2d3bfc5290>]
      120
      100
       80
       60
       40
       20
                       10
                                 15
                                           20
R1.fit(X,y)
```

R1.w

array([[

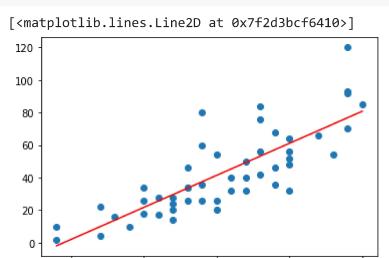
3.9318456],

```
[-17.56942403]])
```

```
R1.lost_function(X,y,R1.w)
```

113.53521535409273

```
plt.scatter(X,y)
plt.plot(X,R1.model(X,R1.w),c = 'r')
```



15

10

R1.coef_determination(X,y)

0.6510793658741216

▼ Exercice 3

data_pops = pd.read_excel('/content/drive/My Drive/TP_machine_learning/pop.xlsx')

20

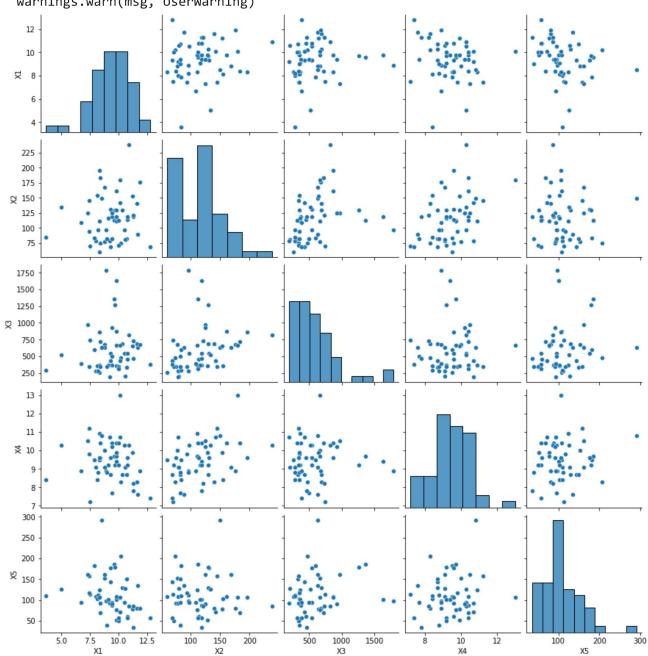
25

data_pops.head()

	X1	X2	Х3	X4	X 5
0	8.0	78	284	9.1	109
1	9.3	68	433	8.7	144
2	7.5	70	739	7.2	113
3	8.9	96	1792	8.9	97
4	10.2	74	477	8.3	206

import seaborn as sbs

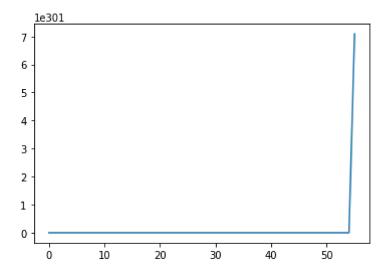
```
sbs.pairplot(data_pops, size=2.5);
```



```
X = np.array(data_pops[['X1','X2','X3','X4']])
y = np.array(data_pops['X5'])
```

```
print(X.shape)
print(y.shape)
```

```
(53, 4)
     (53,)
y = y.reshape((53,1))
y.shape
     (53, 1)
R3 = Regression(X)
R3.w
     array([[0.79979181],
            [0.31788753],
            [0.13969132],
            [0.63706308],
            [0.00935675]])
R3.lost_function(X,y,R3.w)
     2265.638482805931
R3.fit(X,y,alpha=0.001,e=0.1,n_iter= 3000)
     /usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:19: RuntimeWarning: over
     /usr/local/lib/python3.7/dist-packages/numpy/core/fromnumeric.py:87: RuntimeWarning:
       return ufunc.reduce(obj, axis, dtype, out, **passkwargs)
     /usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:30: RuntimeWarning: inva
R3.w
     array([[nan],
            [nan],
            [nan],
            [nan],
            [inf]])
R3.lost_function(X,y,R3.w)
     nan
R3.lost_courbe()
```



✓ 0 s terminée à 16:32

• X