

## This ULU

The *ULU.07 Universal 4-bit display* can be used to show a four-bit, binary value in several ways: as a bit pattern, a hexadecimal number and a signed or unsigned number. It is implemented using an Arduino Nano.

## Used parts

The following standard parts are used:

1x black aluminum casing 50\*80\*20mm;  
4x black M3 bolt 5mm, button head;  
2x 7mm female/female brass M3 standoff;  
1x 50\*25mm 2.54mm prototype PCB;  
2x 1-pole ON-ON switch;  
1x 1-pole ON-OFF-ON switch;  
1x power connector;

2x 4-bit data connector;  
2x single digit 0.56" 7-segment display;  
1x Arduino nano;  
12x 1K2 resistor for the 7-segment display;  
4x 10K pull down resistor;  
1x 20 x 8-hole experiment PCB.

## Specifications

Two 7-segment displays and an Arduino Nano are used to implement the necessary logic. Six display modes are available: 1. binary, 2. hexadecimal, 3. decimal, 4. signed, 5. 1-complement and 6. 2-complement. These modes are shown in Figure 1.

	byte	1	2	3	4	5	6
0	0000		0	0	0	0	0
1	0001	.	1	1	1	1	1
2	0010	.	2	2	2	2	2
3	0011	..	3	3	3	3	3
4	0100	.	4	4	4	4	4
5	0101	.	5	5	5	5	5
6	0110	.	6	6	6	6	6
7	0111	..	7	7	7	7	7
8	1000	.	8	8	- 0	- 1	- 8
9	1001	.	9	9	- 1	- 6	- 7
10	1010	.	A	1 0	- 2	- 5	- 6
11	1011	..	b	1 1	- 3	- 4	- 5
12	1100	..	c	1 2	- 4	- 3	- 4
13	1101	..	d	1 3	- 5	- 2	- 3
14	1110	..	e	1 4	- 6	- 1	- 2
15	1111	..	F	1 5	- 7	0	- 1
••						•	• •

Figure 1 – Display mode

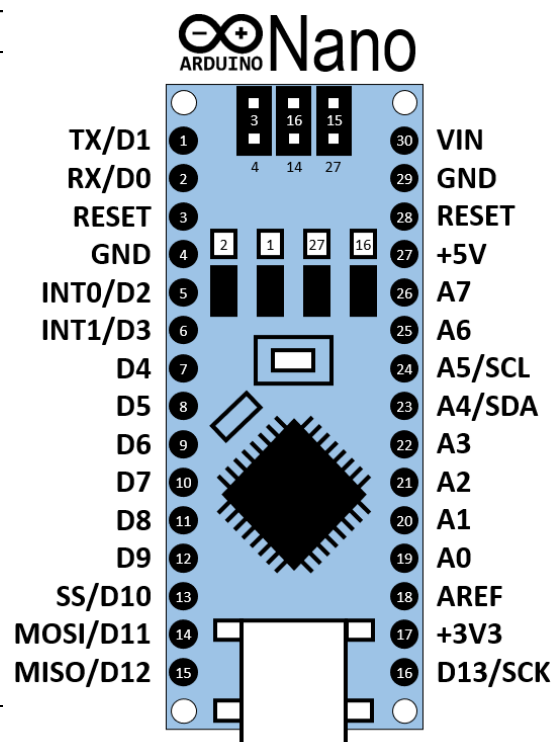
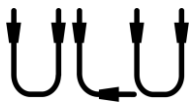


Figure 2 – Arduino Nano pinout



Binary		Hexadecimal								Decimal								Signed								1-complement								2-complement													
c	e	a	b	c	d	e	f	g		b	c	a	b	c	d	e	f	g	•	g	a	b	c	d	e	f	g	•	g	a	b	c	d	e	f	g	•	g	a	b	c	d	e	f	g	•	
0				1	1	1	1	1	1				1	1	1	1	1	1	1			1	1	1	1	1	1			1	1	1	1	1	1	1			1	1	1	1	1	1	1		
1		1			1	1							1	1								1	1							1		1	1					1	1					1			
2			1		1	1		1	1			1	1		1	1		1				1	1		1	1		1		1	1		1	1		1	1		1	1		1	1		1		
3			1	1		1	1		1			1	1	1	1			1				1	1	1	1		1		1	1	1	1		1	1		1	1	1	1		1	1		1		
4	1				1	1			1	1				1	1			1	1				1	1			1	1			1		1	1		1	1		1	1		1	1		1		
5	1		1			1	1	1	1	1			1		1	1		1	1			1		1	1	1	1			1		1	1	1	1	1		1	1		1	1		1			
6	1			1		1	1	1	1	1	1			1		1	1	1	1	1			1		1	1	1	1	1			1		1	1	1	1	1		1	1		1	1		1	
7	1		1	1		1	1	1				1	1	1								1	1	1				1			1	1	1		1	1		1	1		1	1		1			
8		1			1	1	1	1	1	1	1			1	1	1	1	1	1	1	1	1		1	1	1	1	1	1		1	1	1	1	1	1	1		1	1	1	1	1	1	1		
9		1	1			1	1	1	1		1	1			1	1	1	1		1	1		1		1	1	1	1	1		1	1	1	1		1	1		1	1		1	1		1		
10		1		1		1	1	1		1	1	1	1	1	1	1	1	1	1			1	1	1		1	1		1		1		1	1	1	1	1		1	1		1	1		1		
11		1	1	1			1	1	1	1	1		1	1		1	1					1	1	1	1	1		1		1		1		1	1	1	1		1	1		1	1		1		
12	1	1			1		1	1	1		1	1	1	1		1	1	1	1			1		1	1		1	1			1		1	1		1	1		1	1		1	1		1		
13	1	1	1			1	1	1	1	1		1	1	1	1	1	1	1	1			1	1		1	1	1	1	1			1		1	1	1	1		1	1		1	1		1		
14	1	1		1			1	1	1	1	1	1		1	1		1		1	1		1		1	1	1	1	1			1		1	1		1	1		1	1		1	1		1		
15	1	1	1	1		1		1	1	1	1	1	1	1	1	1	1	1	1			1	1	1	1			1			1	1	1		1	1		1	1		1	1		1			

Figure 3 – 7-segment specification for the left and right display

## Construction

The standard ULU specifications are applicable as specified in the datasheet *ULU.00 – Common specifications*. The switches need to be mounted as close to the front of the enclosure as possible, otherwise they will not fit.

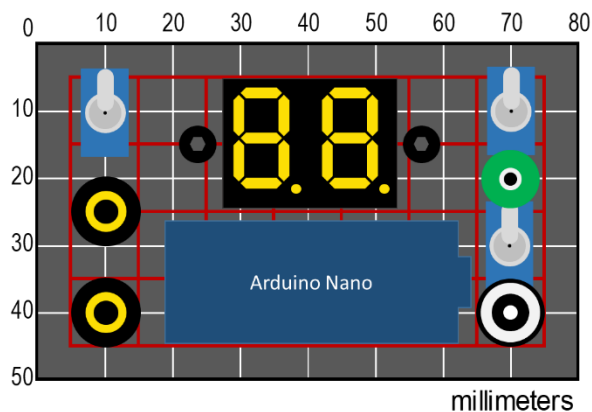


Figure 4 – Drill guide

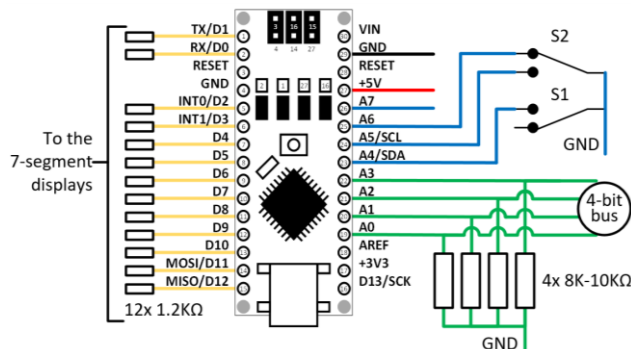


Figure 5 – Circuit diagram

Port	Con.	Rest.	Func.	Interface	Function
1. D1	8		L	5	Right b segment
2. D0	8		L	5	Right a segment
3. D2	8		L	5	Right dp segment
4. D3	8		L	5	Right c segment
5. D4	8		L	5	Right f segment
6. D5	8		L	5	Right d segment
7. D6	8		L	5	Right e segment
8. D7	8		L	5	Left dp segment
9. D8	8		L	5	Left c segment
10. D9	8		L	5	Right g segment
11. D10	8		L	5	Left b segment
12. D11	8		L	5	Left e segment
13. D12	8		L	5	Left g segment
14. D13		O	L		Heartbeat
15. A0	4		I	4	Bit 3 (MSB)
16. A1	4		I	4	Bit 2
17. A2	4		I	4	Bit 1
18. A3	4		I	4	Bit 0 (LSB)
19. A4	4		T	2	Switch 1 down
20. A5	4		T	2	Switch 2 up
21. A6	4		T	2	Switch 2 down
22. A7	4		I	3	Display on
23. +5V	4		I	0	DC +5V
24. GND	4		I	0	Ground (-)

Input, Output, Led, SPI, Toggle switch, Rotary switch

Figure 6 – Arduino pinout

Only one wire is used to connect the 4-bit connectors to each other and to the Arduino. In order to do this, a small segment in the middle of the wire is stripped. The input marked with pull up (pu) is directly connected to the Arduino, because the internal pull up resistor is used. As result of that, the witches must be fed with the ground (-). When both A5 and A6 of the Arduino Nano are connected to the ground, a test program will run. Then the display will first show `rl.8.` and then start counting from 0 to F repeatedly.

Also, a solder check program and test mode is available to check the soldering and find possible solder or connection errors. This program contains two parts. First it will turn the left display on, followed by the right display. Segment by segment, in a clockwise manner. Then it will show the inputs on the right display, as shown in Figure 8, left part.

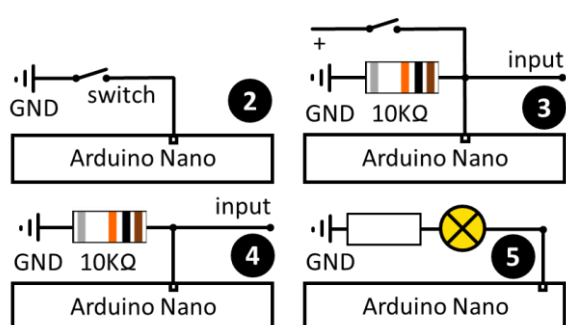


Figure 7 – Arduino interfaces

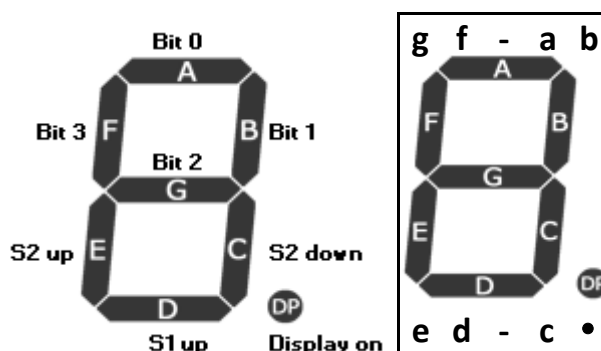


Figure 8 – Solder check display & 7-segment pinout

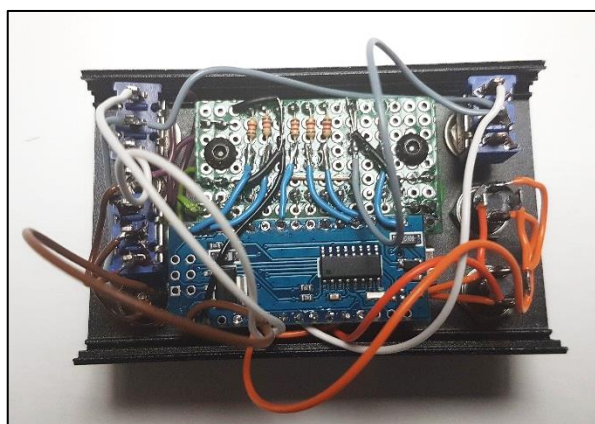


Figure 9 – ULU inside

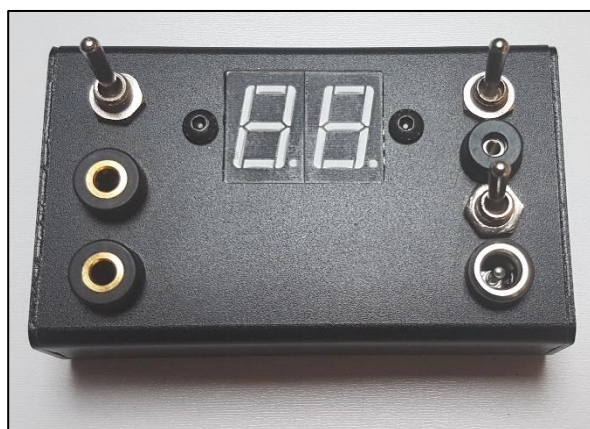


Figure 10 – Finished ULU

## Usage

The two top switches are used to select one of the six different display modes:

**Left switch is set to top**

1. Binary
2. Hexadecimal
3. Decimal

**Left switch is set to bottom**

4. Signed
5. 1-complement
6. 2-complement

**Right top switch is set to top position**

**Right top switch is set to neutral position**

**Right top switch is set to bottom position**

When the 1- complement code is used the right decimal point is switched on, when the 2-complement code is used both decimal points are switched on. In binary mode the top right segment is switched on, so it is clear the input equals zero and the display is still on.

The display can be turned on by both a switch and a signal connector. The right bottom switch is used to switch the display on (top position) or off (bottom position). The enable connector has the same function: if a logical 1 is offered, the display is switched on. There is an OR relation between switch and

connector: either of them can switch the display on. That makes it possible to use the display as a controlled output device, connected to a data bus. It can also be used to for zero suppression: the zero is only shown when the keyboard is pressed or the data is entered.

Both the data bus connectors are interconnected. That offers the possibility to 'tap' a data-line and put the display between both ULUs connected to each other. When the enable switch is set up, the corresponding socket can be used to obtain a logical 1 for use in the circuit.

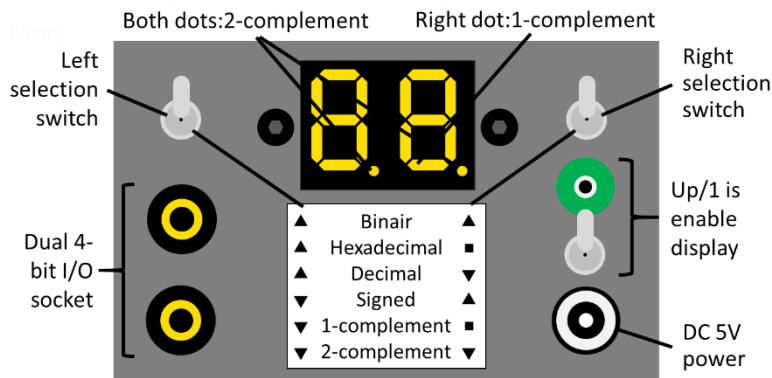


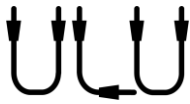
Figure 11 – Connectors & controls

## Solder check program

```
/* ULU.05 Universal 4-bit 7-segment display - solder check */
/* CC BY-NC-SA Jeroen Brinkman */
int v0, v1, v2, v3, s1, s2u, s2d, s3u;

#define LB 10
#define LC 8
#define LE 11
#define LG 12
#define LP 7
#define RA 0
#define RB 1
#define RC 3
#define RD 5
#define RE 6
#define RF 4
#define RG 9
#define RP 2
#define RP 2
#define B0 A3
#define B1 A2
#define B2 A1
#define B3 A0
#define SW1D A4
#define SW2U A5
#define SW2D A6
#define SW3U A7

void setup() {
  /* Define I/O pins */
  pinMode(LB, OUTPUT); // left display, segment b
  pinMode(LC, OUTPUT); // left display, segment c
  pinMode(LE, OUTPUT); // left display, segment e
  pinMode(LG, OUTPUT); // left display, segment g
  pinMode(LP, OUTPUT); // left display, segment dp
  pinMode(RA, OUTPUT); // right display, segment a
  pinMode(RB, OUTPUT); // right display, segment b
  pinMode(RC, OUTPUT); // right display, segment c
  pinMode(RD, OUTPUT); // right display, segment d
  pinMode(RE, OUTPUT); // right display, segment e
  pinMode(RF, OUTPUT); // right display, segment f
  pinMode(RG, OUTPUT); // right display, segment g
  pinMode(RP, OUTPUT); // right display, segment dp
  pinMode(13, OUTPUT); // blinking led showing the programma's heartbeat
  pinMode(B3, INPUT); // Bit 3
  pinMode(B2, INPUT); // Bit 2
  pinMode(B1, INPUT); // Bit 1
  pinMode(B0, INPUT); // Bit 0
  pinMode(SW1D, INPUT_PULLUP);
  pinMode(SW2U, INPUT_PULLUP);
  pinMode(SW2D, INPUT_PULLUP);
  pinMode(SW3U, INPUT);
  /* test display */
  digitalWrite(LB, LOW);
  digitalWrite(LC, LOW);
  digitalWrite(LE, LOW);
  digitalWrite(LG, LOW);
}
```



```
digitalWrite(LP, LOW);
digitalWrite(RA, LOW);
digitalWrite(RB, LOW);
digitalWrite(RC, LOW);
digitalWrite(RD, LOW);
digitalWrite(RE, LOW);
digitalWrite(RF, LOW);
digitalWrite(RG, LOW);
digitalWrite(RP, LOW); delay(1000);
digitalWrite(LB, HIGH); delay(500);
digitalWrite(LC, HIGH); delay(500);
digitalWrite(LE, HIGH); delay(500);
digitalWrite(LG, HIGH); delay(500);
digitalWrite(LP, HIGH); delay(500);
digitalWrite(RA, HIGH); delay(500);
digitalWrite(RB, HIGH); delay(500);
digitalWrite(RC, HIGH); delay(500);
digitalWrite(RD, HIGH); delay(500);
digitalWrite(RE, HIGH); delay(500);
digitalWrite(RF, HIGH); delay(500);
digitalWrite(RG, HIGH); delay(500);
digitalWrite(RP, HIGH); delay(500);
digitalWrite(LB, LOW);
digitalWrite(LC, LOW);
digitalWrite(LE, LOW);
digitalWrite(LG, LOW);
digitalWrite(LP, LOW);
digitalWrite(RA, LOW);
digitalWrite(RB, LOW);
digitalWrite(RC, LOW);
digitalWrite(RD, LOW);
digitalWrite(RE, LOW);
digitalWrite(RF, LOW);
digitalWrite(RG, LOW);
digitalWrite(RP, LOW);
};

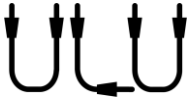
void loop(){
  digitalWrite(13, (millis() / 1000) % 2); //1s heartbeat for the onboard led
  /* Read switches & inputs */
  v0 = analogRead(B0) > 500 ? 1 : 0;
  v1 = analogRead(B1) > 500 ? 1 : 0;
  v2 = analogRead(B2) > 500 ? 1 : 0;
  v3 = analogRead(B3) > 500 ? 1 : 0;
  s1 = analogRead(SW1D) < 300 ? 1 : 0; // Switch 1 is on, switch uses pull down resistor so equals 0 when on
  s2u = analogRead(SW2U) < 300 ? 1 : 0; // Switch 2 is up, switch uses pull down resistor so equals 0 when on
  s2d = analogRead(SW2D) < 300 ? 1 : 0; // switch 2 is down, switch uses pull down resistor so equals 0 when on
  s3u = analogRead(SW3U) < 300 ? 0 : 1; // display is on, switch puts +5V to connector

  /* Display all inputs on right display */
  digitalWrite(RA, (v0 == 1) ? HIGH : LOW); // LSB
  digitalWrite(RB, (v1 == 1) ? HIGH : LOW); // bit 1
  digitalWrite(RC, (v2 == 1) ? HIGH : LOW); // bit 2
  digitalWrite(RF, (v3 == 1) ? HIGH : LOW); // MSB
  digitalWrite(RC, (s2d == 1) ? HIGH : LOW); // Switch 2 down
  digitalWrite(RE, (s2u == 1) ? HIGH : LOW); // Switch 2 up
  digitalWrite(RD, (s1 == 1) ? HIGH : LOW); // Switch 1 down
  digitalWrite(RP, (s3u == 1) ? HIGH : LOW); // DP display on
}
```

## Program

```
/* ULU.07 Universal 4-bit 7-segment display - program code */
/* CC-BY-NC-SA Jeroen Brinkman */

int value, setting, pointer, look, todo;
int r, s1d, s2u, s2d, s3u;
int v0, v1, v2, v3;
int show1[16][4] =
{{0,0,0,0},{0,0,0,1},{0,0,1,0},{0,0,1,1},{0,1,0,0},{0,1,0,1},{0,1,1,0},{0,1,1,1},{1,0,0,0},{1,0,0,1},{1,0,1,0},{1,0,1,1},{1,1,0,0},{1,1,0,1},{1,1,1,0},{1,1,1,1}};
int show2[8][7] =
{{1,1,1,1,1,1,0},{0,1,1,0,0,0,0},{1,1,0,1,1,0,1},{1,1,1,1,0,0,1},{0,1,1,0,0,1,1},{1,0,1,1,0,1,1},{1,0,1,1,1,1,1},{1,1,1,0,0,0,0}};
int show3[8][5][11] = { // values for Lb, Lc, Le, Lg, Ra, Rb, Rc, Rd, Re, Rf, Rg
{{0,0,0,0,1,1,1,1,1,1,1}, {0,0,0,0,1,1,1,1,1,1,1}, {0,0,0,1,1,1,1,1,1,0,0}, {0,0,0,1,1,1,1,1,0,0,0}, {0,0,0,1,1,1,1,1,1,1,1}},
{{0,0,0,0,1,1,1,1,0,1,1}, {0,0,0,0,1,1,1,1,0,1,1}, {0,0,0,1,0,1,1,1,0,0,0}, {0,0,0,1,0,1,1,1,1,1,1}, {0,0,0,1,1,1,1,0,0,0,0}},
{{0,0,0,0,1,1,1,0,1,1,1}, {1,1,0,0,1,1,1,1,1,0,1}, {0,0,0,1,1,1,0,1,0,1,1}, {0,0,0,1,1,0,1,1,0,1,1}, {0,0,0,1,1,0,1,1,1,1,1}},
{{0,0,0,0,0,0,1,1,1,1,1}, {1,1,0,0,0,1,1,0,0,0,0}, {0,0,0,1,1,1,1,1,0,0,1}, {0,0,0,1,0,1,1,1,0,0,1}, {0,0,0,1,0,1,1,0,1,1,1}},
{{0,0,0,0,1,0,0,1,1,1,0}, {1,1,0,0,1,1,0,1,0,1,1}, {0,0,0,1,0,1,1,0,0,1,1}, {0,0,0,1,1,1,1,1,0,0,1}, {0,0,0,1,0,1,1,0,0,1,1}},
{{0,0,0,0,0,0,1,1,1,0,1}, {1,1,0,0,1,1,1,1,0,0,1}, {0,0,0,1,1,0,1,1,0,1,1}, {0,0,0,1,1,0,1,1,0,1,1}, {0,0,0,1,1,1,1,1,0,0,1}},
{{0,0,0,0,1,0,0,1,1,1,1}, {1,1,0,0,0,1,1,0,0,1,1}, {0,0,0,1,1,0,1,1,1,1,1}, {0,0,0,1,0,1,1,0,0,0,0}, {0,0,0,1,1,1,0,1,1,0,1}},
{{0,0,0,0,0,1,0,0,1,1,1}, {1,1,0,0,1,0,1,1,0,1,1}, {0,0,0,1,1,1,1,0,0,0,0}, {0,0,0,0,1,1,1,1,1,1,0}, {0,0,0,1,0,1,1,0,0,0,0}}
};
#define LB 10
#define LC 8
#define LE 11
#define LG 12
#define LP 7
#define RA 0
#define RB 1
#define RC 3
#define RD 5
#define RE 6
#define RF 4
#define RG 9
#define RP 2
```



```
#define B0 A3
#define B1 A2
#define B2 A1
#define B3 A0
#define SW1D A4
#define SW2U A5
#define SW2D A6
#define SW3U A7

void setup() {
  // declare the ledPins as an OUTPUT:
  pinMode(LB, OUTPUT); // left display, segment b
  pinMode(LC, OUTPUT); // left display, segment c
  pinMode(LE, OUTPUT); // left display, segment e
  pinMode(LG, OUTPUT); // left display, segment g
  pinMode(LP, OUTPUT); // left display, segment dp
  pinMode(RA, OUTPUT); // right display, segment a
  pinMode(RB, OUTPUT); // right display, segment b
  pinMode(RC, OUTPUT); // right display, segment c
  pinMode(RD, OUTPUT); // right display, segment d
  pinMode(RE, OUTPUT); // right display, segment e
  pinMode(RF, OUTPUT); // right display, segment f
  pinMode(RG, OUTPUT); // right display, segment g
  pinMode(RP, OUTPUT); // right display, segment dp
  pinMode(13, OUTPUT); // blinking led showing the program heartbeat
  pinMode(B3, INPUT); // Bit 3
  pinMode(B2, INPUT); // Bit 2
  pinMode(B1, INPUT); // Bit 1
  pinMode(B0, INPUT); // Bit 0
  pinMode(SW1D, INPUT_PULLUP);
  pinMode(SW2U, INPUT_PULLUP);
  pinMode(SW2D, INPUT_PULLUP);
  pinMode(SW3U, INPUT);
  /* Every ULU with an Arduino introduces itself. This one uses the 7-segment display */
  digitalWrite(RA, HIGH); digitalWrite(RB, HIGH); digitalWrite(RC, HIGH); delay(800);
  digitalWrite(RA, LOW); digitalWrite(RB, LOW); digitalWrite(RC, LOW); delay(800);
};

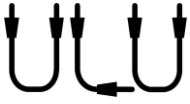
void loop(){
  digitalWrite(13, (millis() / 1000) % 2); //1s heartbeat for the onboard led

  /* Read settings */
  s1d = analogRead(SW1D) < 500 ? 1 : 0; // Switch 1 is down, switch uses pull down resistor so equals 0 when on
  s2u = analogRead(SW2U) < 500 ? 1 : 0; // Switch 2 is up, switch uses pull down resistor so equals 0 when on
  s2d = analogRead(SW2D) < 500 ? 1 : 0; // switch 2 is down, switch uses pull down resistor so equals 0 when on
  s3u = analogRead(SW3U) < 500 ? 0 : 1; // display is on, switch puts +5V to connector
  setting = 2;
  if (s2u == 1) {
    setting = 1;
  } else {
    if (s2d == 1) setting = 3;
  }
  if (s1d == 1) setting += 3;
  if (s3u == 0) setting = 0; // if display needs to be off, result = 0
  // 0. Display off
  // 1. Binary
  // 2. Hexdecimal
  // 3. Decimal
  // 4. Signed
  // 5. 1-complement
  // 6. 2-complement
  // 7. System test

  /* Read value */
  v0 = analogRead(B0) > 500 ? 1 : 0;
  v1 = analogRead(B1) > 500 ? 1 : 0;
  v2 = analogRead(B2) > 500 ? 1 : 0;
  v3 = analogRead(B3) > 500 ? 1 : 0;
  value = v0 + (v1 * 2) + (v2 * 4) + (v3 * 8);

  /* Process input */
  todo = 4;
  if (value < 8) todo = 2;
  if (value == 16) todo = 3; // all segments on
  if (setting == 0) todo = 0; // dimming the display
  if (setting == 1) todo = 1; // show binary
  // todo = 0 -> display off
  // todo = 1 -> binary display
  // todo = 2 -> value less than 8, so only write data to right display
  // todo = 3 -> all segments on
  // todo = 3 -> value > 7 display two segments
  digitalWrite(LP, (setting == 6) ? HIGH : LOW); // write the left dot if 2-complement
  digitalWrite(RP, setting > 4 ? HIGH : LOW); // write the right dot if 1-complement or 2-complement

  /* Write output */
  switch (todo) {
  case 0: // dim display
    digitalWrite(LB, LOW);
    digitalWrite(LC, LOW);
    digitalWrite(LE, LOW);
    digitalWrite(LG, LOW);
    digitalWrite(LP, LOW);
    digitalWrite(RA, LOW);
    digitalWrite(RB, LOW);
    digitalWrite(RC, LOW);
    digitalWrite(RD, LOW);
    digitalWrite(RE, LOW);
    digitalWrite(RF, LOW);
    digitalWrite(RG, LOW);
    digitalWrite(RP, LOW);
```



```
break;
case 1: // binary
    digitalWrite(LB, LOW);
    digitalWrite(LG, LOW);
    digitalWrite(LE, (show1[value][0] == 1) ? HIGH : LOW);
    digitalWrite(LC, (show1[value][1] == 1) ? HIGH : LOW);
    digitalWrite(RA, HIGH);
    digitalWrite(RB, LOW);
    digitalWrite(RD, LOW);
    digitalWrite(RF, LOW);
    digitalWrite(RG, LOW);
    digitalWrite(RE, (show1[value][2] == 1) ? HIGH : LOW);
    digitalWrite(RC, (show1[value][3] == 1) ? HIGH : LOW);
    break;
case 2: // value < 8 // only write data to right display
    digitalWrite(LB, LOW);
    digitalWrite(LG, LOW);
    digitalWrite(LE, LOW);
    digitalWrite(LC, LOW);
    digitalWrite(RA, (show2[value][0] == 1) ? HIGH : LOW);
    digitalWrite(RB, (show2[value][1] == 1) ? HIGH : LOW);
    digitalWrite(RC, (show2[value][2] == 1) ? HIGH : LOW);
    digitalWrite(RD, (show2[value][3] == 1) ? HIGH : LOW);
    digitalWrite(RE, (show2[value][4] == 1) ? HIGH : LOW);
    digitalWrite(RF, (show2[value][5] == 1) ? HIGH : LOW);
    digitalWrite(RG, (show2[value][6] == 1) ? HIGH : LOW);
    break;
case 3: // all segments on
    digitalWrite(LB, HIGH);
    digitalWrite(LC, HIGH);
    digitalWrite(LE, HIGH);
    digitalWrite(LG, HIGH);
    digitalWrite(LF, HIGH);
    digitalWrite(RA, HIGH);
    digitalWrite(RB, HIGH);
    digitalWrite(RC, HIGH);
    digitalWrite(RD, HIGH);
    digitalWrite(RE, HIGH);
    digitalWrite(RF, HIGH);
    digitalWrite(RG, HIGH);
    digitalWrite(RP, HIGH);
    break;
case 4: // write data on both displays
    look = value - 8; pointer = setting - 2;
    digitalWrite(LB, (show3[look][pointer][0] == 1) ? HIGH : LOW);
    digitalWrite(LC, (show3[look][pointer][1] == 1) ? HIGH : LOW);
    digitalWrite(LE, (show3[look][pointer][2] == 1) ? HIGH : LOW);
    digitalWrite(LG, (show3[look][pointer][3] == 1) ? HIGH : LOW);
    digitalWrite(RA, (show3[look][pointer][4] == 1) ? HIGH : LOW);
    digitalWrite(RB, (show3[look][pointer][5] == 1) ? HIGH : LOW);
    digitalWrite(RC, (show3[look][pointer][6] == 1) ? HIGH : LOW);
    digitalWrite(RD, (show3[look][pointer][7] == 1) ? HIGH : LOW);
    digitalWrite(RE, (show3[look][pointer][8] == 1) ? HIGH : LOW);
    digitalWrite(RF, (show3[look][pointer][9] == 1) ? HIGH : LOW);
    digitalWrite(RG, (show3[look][pointer][10] == 1) ? HIGH : LOW);
}
}
```