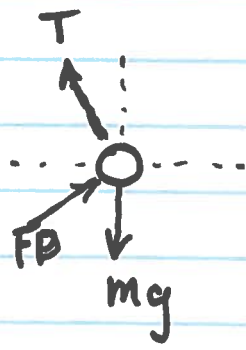


$$\begin{aligned}\Sigma \vec{F}^P &= T \hat{a}_2 + F_D \hat{a}_1 - m_p g \hat{n}_2 \\ &= m_p \ddot{\vec{a}}^P \\ &= m_p (L \ddot{\theta} \hat{a}_1 + L \dot{\theta}^2 \hat{a}_2)\end{aligned}$$



$$\begin{aligned}\hat{n}_2 &= \cos \theta \hat{a}_2 + \sin \theta \hat{a}_1\end{aligned}$$

$$\begin{aligned}\hat{a}_1: m_p L \ddot{\theta} &= F_D - m_p g \sin \theta \\ \hat{a}_2: m_p L \dot{\theta}^2 &= T - m_p g \cos \theta\end{aligned}$$

$$F_D = -\text{sgn}(\dot{\theta}) \frac{1}{2} \rho C_D \underbrace{L \dot{\theta}}_{v} \underbrace{L \dot{\theta}}_{v} A$$

$$\begin{aligned}v &= L \dot{\theta} \\ \vec{v} &= \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta\end{aligned}$$

$$m_p L \ddot{\theta} + \text{sgn}(\dot{\theta}) \frac{1}{2} \rho C_D (L^2 \dot{\theta}^2) A + m_p g \sin \theta = 0$$

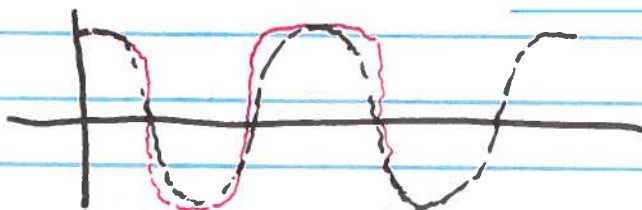
↑
sign()

$$\ddot{\theta} + \text{sgn}(\dot{\theta}) \left(\frac{1}{2} \rho \right) C_D L \dot{\theta}^2 A + \frac{g}{L} \sin \theta = 0$$

$$C_D \sim 0 \Rightarrow \ddot{\theta} + \frac{g}{L} \sin \theta = 0$$

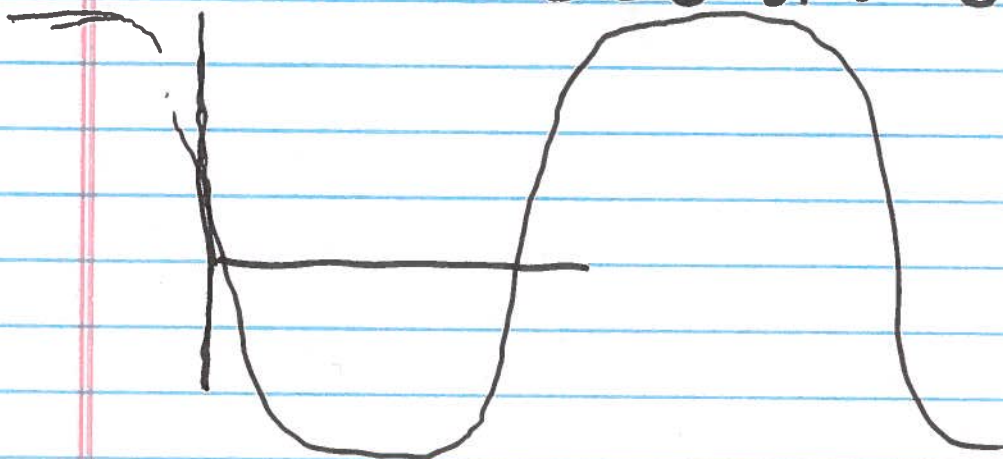
$$\theta \ll 1 \Rightarrow \ddot{\theta} + \left(\frac{g}{L} \right) \theta = 0$$

$$\Rightarrow \theta(t) = A \sin \sqrt{\frac{g}{L}} t + B \cos \sqrt{\frac{g}{L}} t$$



$$\Theta(t) = \Theta_0 \cos \sqrt{\frac{g}{L}} t$$

~~SIN~~ $\sin \Theta \sim \Theta - \frac{\Theta^3}{3!} + \frac{\Theta^5}{5!} + \dots$



$$\Theta \Leftrightarrow x_1$$

$$\dot{\Theta} \Leftrightarrow x_2$$

$$\Theta \Rightarrow \dot{x}(1)$$

$$\dot{\Theta} \Rightarrow \dot{x}(2)$$

$$\ddot{\Theta} =$$

1) TAKE INVENTOR

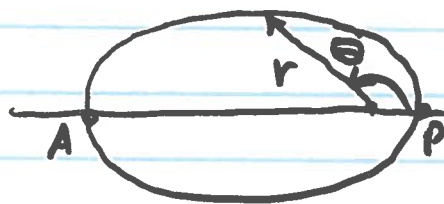
$$\vec{h} = \vec{r} \times \vec{v} = \text{const}$$

$$\frac{v^2}{2} - \frac{\mu}{r} = E = -\frac{\mu}{2a}^*$$

$$\vec{e} = \frac{\vec{v} \times \vec{h}}{\mu} - \frac{\vec{r}}{r}$$

$$e = |\vec{e}|$$

$$r(\theta) = \frac{h^2}{\mu(1 + e \cos \theta)}$$



$$v_r = \frac{\mu}{h} e \sin \theta$$

$$v_\theta = \frac{\mu}{h} (1 + e \cos \theta)$$

$$e = \frac{r_a - r_p}{r_a + r_p}$$

$$r_p = a(1 - e)^*$$

$$r_a = a(1 + e)^*$$

$$h^2 = a\mu(1 - e^2)^*$$

$$r(\theta) = \frac{a(1 - e^2)}{1 + e \cos \theta}^*$$

$$t=t_0 \Rightarrow \vec{r}_0 = 8182 \hat{i} - 6865.9 \hat{j} \text{ [Km]}$$

$$\vec{v}_0 = 0.47572 \hat{i} + 8.8116 \hat{j} \text{ [Km/s]}$$

$$\epsilon = ? , e = ? , \Theta_0 = ?$$

$$v @ \Theta_0 + 120^\circ , r(\Theta_0 + 120^\circ)$$

$$\vec{h} = \vec{h}_0 = \vec{r}_0 \times \vec{v}_0 = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 8182 & -6865.9 & 0 \\ 0.475 & 8.81 & 0 \end{vmatrix} = 75366 \hat{k}$$

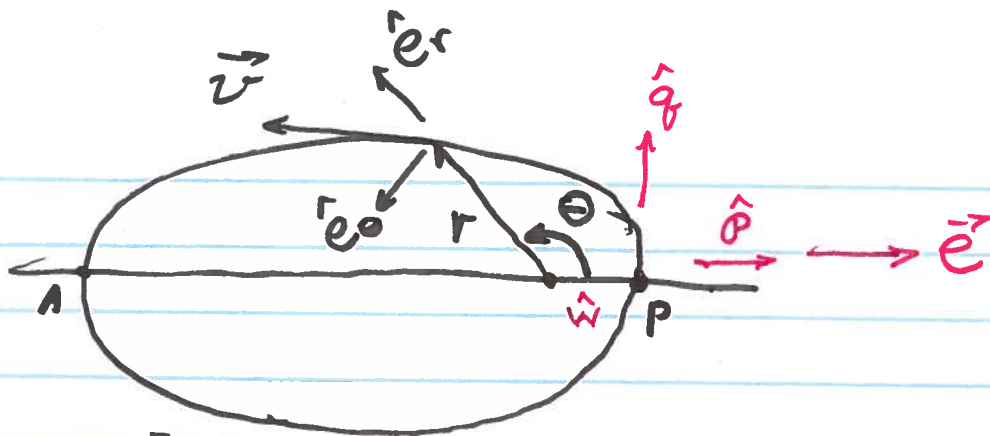
$$r_0 = |\vec{r}_0| = \sqrt{(8182)^2 + (-6865.9)^2} = 10681 \text{ Km}$$

$$\epsilon = \frac{v^2}{2} - \frac{\mu}{r} = \frac{\vec{v}_0 \cdot \vec{v}_0}{2} - \frac{398600}{10681} = \text{hyp.}$$

$$\vec{e} = \frac{\vec{v} \times \vec{h}}{\mu} - \frac{\vec{r}}{r} = 0.900 \hat{i} + 0.553 \hat{j}$$

$$e = |\vec{e}| = 1.0562$$

$$\begin{Bmatrix} v_1 \\ v_2 \\ v_3 \end{Bmatrix}_{ijk} = \begin{bmatrix} ijk \text{ orb} \\ C \end{bmatrix} \begin{Bmatrix} v_r \\ v_\theta \\ 0 \end{Bmatrix}_{orb}$$



$$\hat{p} \triangleq \frac{\vec{r}}{r} = 0.852 \hat{i} + 0.523 \hat{j}$$

$$\hat{w} \triangleq \frac{\vec{h}}{h} = \hat{k}$$

$$\hat{q} \triangleq \hat{w} \times \hat{p} = -0.523 \hat{i} + 0.852 \hat{j}$$

$$\begin{array}{c} \hat{p} \\ \hat{q} \\ \hat{w} \end{array} \begin{array}{c} \hat{i} \quad \hat{j} \quad \hat{k} \\ \left| \begin{array}{ccc} 0.852 & 0.523 & 0 \\ -0.523 & 0.852 & 0 \\ 0 & 0 & 1 \end{array} \right| \end{array}$$

⇓

$${}^{PF}C^{ijk} = \begin{bmatrix} 0.852 & 0.523 & 0 \\ -0.523 & 0.852 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{Bmatrix} x \\ y \\ z \end{Bmatrix}_{PF} = \begin{Bmatrix} 3379 \\ -10132 \\ 0 \end{Bmatrix}_{PF} = [{}^{PF}C^{ijk}] \begin{Bmatrix} 8182 \\ -6865 \\ 0 \end{Bmatrix}_{ijk}$$

$$\Theta_0 = \text{ATAN2}(y_0, x_0) = -1.249 \text{ rad.}$$

$$v_r(\theta = \Theta_0 + 120^\circ) = \frac{\mu}{h} e \sin \theta = 4.180 \text{ km/s}$$

$$v_\theta = \frac{\mu}{h} (1 + e \cos \theta) = 8.995 \text{ km/s}$$

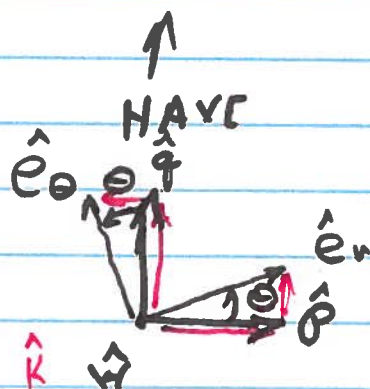
$$r(\theta) = \frac{h^2}{\mu (1 + e \cos \theta)} = 8379 \text{ km}$$

want

$$\left\{ \begin{matrix} v_1 \\ v_2 \\ v_3 \end{matrix} \right\}_{ijk} = \left[\begin{matrix} ijk \\ \text{orb} \end{matrix} \right] \left\{ \begin{matrix} v_r \\ v_\theta \\ v_\phi \end{matrix} \right\}_{\text{orb}}$$

Have

$$\left[\begin{matrix} \text{PF} & ijk \\ C \end{matrix} \right] \Rightarrow \left[\begin{matrix} ijk & \text{PF} \\ C \end{matrix} \right] = \left[\begin{matrix} \text{PF} & ijk \\ C \end{matrix} \right]^T$$



$$\begin{aligned} \hat{e}_r &= c_\theta \hat{p} + s_\theta \hat{q} \\ \hat{e}_\theta &= -s_\theta \hat{p} + c_\theta \hat{q} \\ \hat{k} &= \hat{w} \end{aligned}$$

	\hat{p}	\hat{q}	\hat{w}
\hat{e}_r	c_θ	s_θ	0
\hat{e}_θ	$-s_\theta$	c_θ	0
\hat{k}	0	0	1

$$\Rightarrow \left[\begin{matrix} \text{pol} & \text{PF} \\ C \end{matrix} \right] = \left[\begin{matrix} c_\theta & s_\theta & 0 \\ -s_\theta & c_\theta & 0 \\ 0 & 0 & 1 \end{matrix} \right]$$

orb \triangleq polar

$$\left[\begin{matrix} ijk & \text{pol} \\ C \end{matrix} \right] = \left[\begin{matrix} ijk & \text{PF} \\ C \end{matrix} \right] \left[\begin{matrix} \text{PF} & \text{pol} \\ C \end{matrix} \right]$$

$$\left\{ \begin{matrix} \Gamma_1 \\ \Gamma_2 \\ \Gamma_3 \end{matrix} \right\}_{ijk} = [C]_{ijk}^{pol} \left\{ \begin{matrix} r \\ 0 \\ 0 \end{matrix} \right\}_{pol}$$

8379 = r(\theta_0 + 120^\circ)

@ $\theta = \theta_0 + 120^\circ$

$$\vec{r} = r \hat{e}_r$$