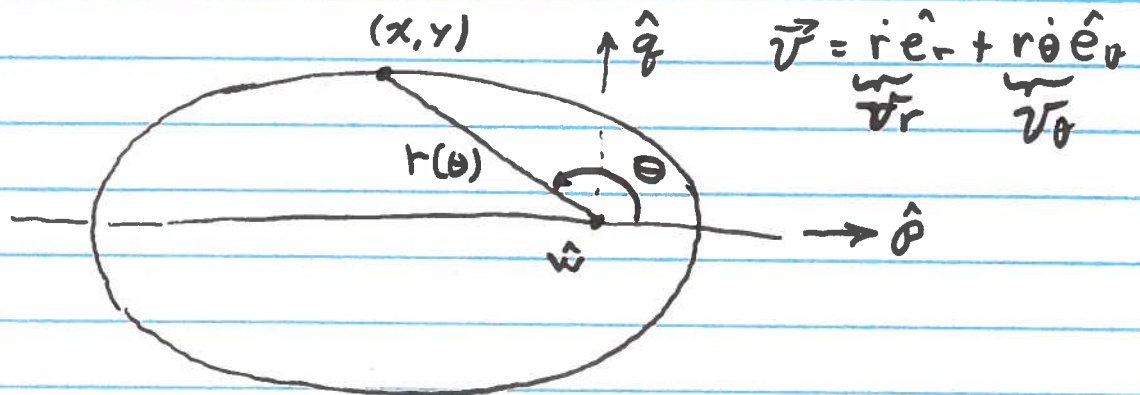


# 1) Lagrange - Gibbs Coefficients

- 2) A) Restricted 3-Body Problem  
B) "Lagrange Points"



$$r(\theta) = \frac{h^2}{\mu(1 + e \cos \theta)}$$

$$\begin{aligned}\vec{r} &= x\hat{p} + y\hat{q} \\ &= r \cos \theta \hat{p} + \underbrace{r \sin \theta}_{y} \hat{q}\end{aligned}$$

$$\begin{aligned}\vec{v} &= \frac{d}{dt} \vec{r} = \dot{x}\hat{p} + x\dot{\hat{p}} + \dot{y}\hat{q} + y\dot{\hat{q}} \\ &= \dot{x}\hat{p} + \dot{y}\hat{q}\end{aligned}$$

$$= (\dot{r} \cos \theta - r \dot{\theta} \sin \theta) \hat{p} + (\dot{r} \sin \theta + r \dot{\theta} \cos \theta) \hat{q}$$

$$\vec{v} = v_r \hat{e}_r + v_\theta \hat{e}_\theta$$

$$\dot{r} = v_r = \frac{\mu}{h} e \sin \theta, \quad v_\theta = \frac{\mu}{h} (1 + e \cos \theta)$$

$$\dot{x} = \underbrace{\dot{r} \cos \theta}_{v_r} - \underbrace{r \dot{\theta} \sin \theta}_{v_\theta}$$

$$\begin{aligned}\dot{x} &= \frac{\mu}{h} e \sin \theta \cos \theta - \frac{\mu}{h} (1 + e \cos \theta) \sin \theta \\ &= -\frac{\mu}{h} \sin \theta\end{aligned}$$

$$\dot{\gamma} = \underbrace{\dot{r}}_{\vec{v}_r} \sin\theta + r \underbrace{\dot{\theta}}_{\vec{v}_\theta} \cos\theta = \frac{u}{h} (r \sin\theta + e)$$

$$\vec{r}_0 = x_0 \hat{p} + y_0 \hat{q} \Rightarrow$$

$$\vec{v}_0 = \dot{x}_0 \hat{p} + \dot{y}_0 \hat{q}$$

$$\begin{aligned} \vec{h} = \vec{h} &\triangleq \vec{r}_0 \times \vec{v}_0 = (x_0 \hat{p} + y_0 \hat{q}) \times (\dot{x}_0 \hat{p} + \dot{y}_0 \hat{q}) \\ &= \underbrace{(x_0 \dot{y}_0 - y_0 \dot{x}_0)}_{h = h_0} \hat{w} \end{aligned}$$

solve  $\vec{r}_0$  for  $\hat{q}$

$$\hat{q} = \frac{\vec{r}_0 - x_0 \hat{p}}{y_0}$$

$$\vec{r}_0 = \dot{x}_0 \hat{p} + \dot{y}_0 \hat{q}$$

$$= \dot{x}_0 \hat{p} + \dot{y}_0 \left( \frac{\vec{r}_0 - x_0 \hat{p}}{y_0} \right)$$

$$= \frac{(y_0 \dot{x}_0 - x_0 \dot{y}_0)}{y_0} \hat{p} + \frac{\dot{y}_0}{y_0} \vec{r}_0 = \frac{-h}{y_0} \hat{p} + \frac{\dot{y}_0}{y_0} \vec{r}_0$$

$$\text{solve this for } \hat{p} = \frac{\dot{y}_0}{h} \vec{r}_0 - \frac{y_0}{h} \vec{v}_0$$

$$\vec{r} = x \hat{p} + y \hat{q}$$

$$= \underbrace{\left( \frac{x \dot{y}_0 - y \dot{x}_0}{h} \right)}_f \vec{r}_0 + \underbrace{\left( \frac{y x_0 - x y_0}{h} \right)}_g \vec{v}_0$$

$$\vec{v} = \dot{x} \hat{p} + \dot{y} \hat{q}$$

$$= \underbrace{\left( \frac{\dot{x}\dot{y}_0 - \dot{y}\dot{x}_0}{n} \right)}_f \vec{r}_0 + \underbrace{\left( \frac{\dot{y}x_0 - \dot{x}y_0}{n} \right)}_g \vec{v}_0$$

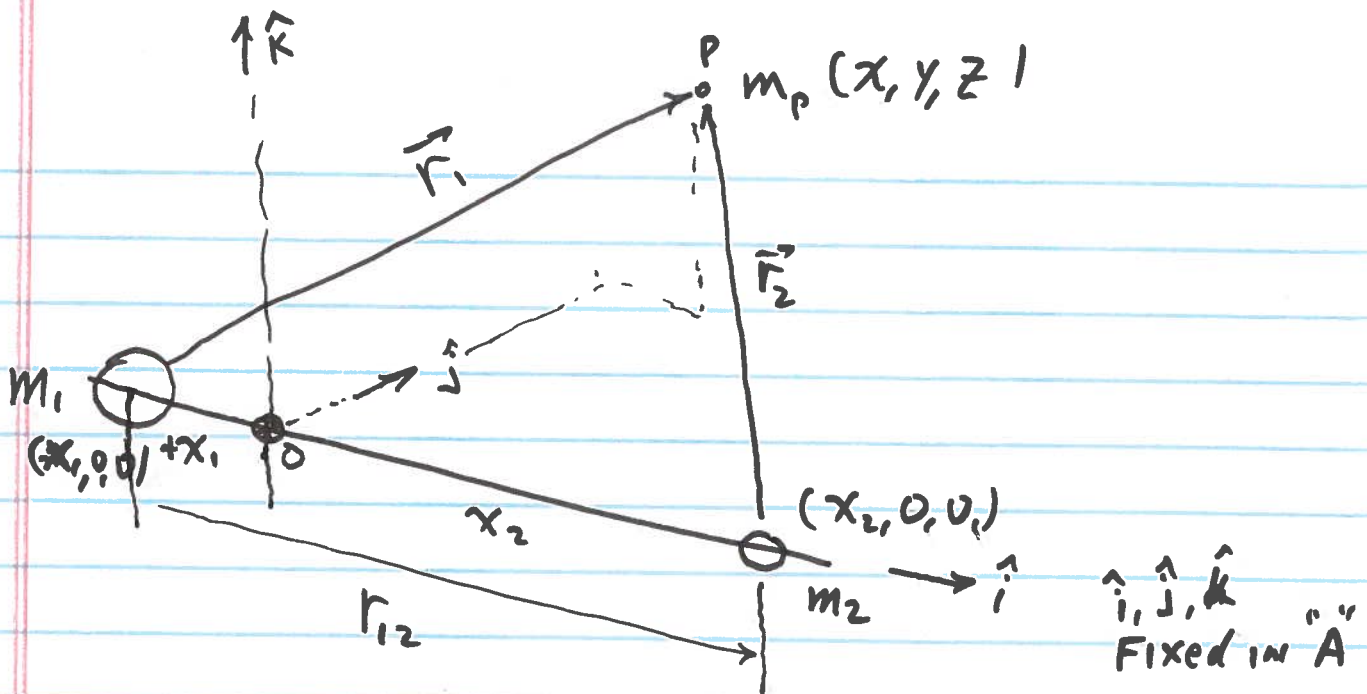
$$\Rightarrow \vec{r} = f \vec{r}_0 + g \vec{v}_0$$

$$\vec{v} = \dot{f} \vec{r}_0 + \dot{g} \vec{v}_0$$

$f, g \Rightarrow$  Lagrange Coefficient

$$\frac{\mu}{r^2} = r \dot{\theta}^2$$

$$\dot{\theta} = \sqrt{\frac{\mu}{r^3}}$$



$$m_1 x_1 \neq m x_2 \Rightarrow$$

$$x_2 - x_1 = r_{12}$$

$$x_2 = r_{12} + x_1$$

$$x_1 = \underbrace{\left( \frac{-m_2}{m_1 + m_2} \right)}_{\pi_2} r_{12} \quad x_2 = \underbrace{\left( \frac{m_1}{m_1 + m_2} \right)}_{\pi_1} r_{12}$$

$$\pi_1 + \pi_2 = 1$$

$$\vec{r}_1 = (x - x_1) \hat{i} + y \hat{j} + z \hat{k}$$

$$\vec{r}_2 = (x - x_2) \hat{i} + y \hat{j} + z \hat{k}$$

$$\vec{\omega}^A = \Omega \hat{k}$$

$$\Omega = \sqrt{\frac{\mu}{r_{12}^3}}$$

$$\Sigma F_g^P = m_P \ddot{\vec{a}}^P = m_P \left[ \underbrace{\ddot{x} \hat{i} + \ddot{y} \hat{j} + \ddot{z} \hat{k}}_{\text{acceleration in } A} + \underbrace{2 \vec{\omega}^A \times \dot{\vec{r}}^P}_{\text{Coriolis acceleration}} + \underbrace{\vec{\omega}^A \times (\vec{\omega}^A \times \vec{r}^{OP})}_{\text{centrifugal acceleration}} \right]$$

$$\mu = G(M_1 + m_2)$$

$$\mu_1 = \pi_1 \mu$$

$$\mu_2 = \pi_2 \mu$$

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$$\sum F_g^p = \frac{-\mu_1 \vec{r}_1}{r_1^3} - \frac{\mu_2 \vec{r}_2}{r_2^3}$$

specific gravity

$$= \frac{-\mu_1 [(x-x_1)\hat{i} + y\hat{j} + z\hat{k}]}{[(x-x_1)^2 + (y^2) + (z^2)]^{3/2}}$$

$$- \frac{\mu_2 [(x-x_2)\hat{i} + y\hat{j} + z\hat{k}]}{[(x-x_2)^2 + y^2 + z^2]^{3/2}}$$

$$\hat{i}: \ddot{x} - \Omega^2 x - 2\Omega \dot{y} = \frac{-\mu_1 (x-x_1)}{r_1^3} - \frac{\mu_2 (x-x_2)}{r_2^3}$$

$$\hat{j}: \ddot{y} + \Omega^2 y + 2\Omega \dot{x} = - \left\{ \frac{\mu_1}{r_1^3} + \frac{\mu_2}{r_2^3} \right\} y$$

$$\hat{k}: \ddot{z} = - \left\{ \frac{\mu_1}{r_1^3} + \frac{\mu_2}{r_2^3} \right\} z$$