

o) Problem 4.26 Type Problems

1) Transfer trajectories

A) Impulsive (high Thrust - short duration)

B) Low Thrust (Long duration)

$$\vec{r}_0 = r_{01} \hat{n}_1 + r_{02} \hat{n}_2 + r_{03} \hat{n}_3$$

$$\vec{v}_0 = v_{01} \hat{n}_1 + v_{02} \hat{n}_2 + v_{03} \hat{n}_3$$

$$\vec{h} = \vec{h}_0 = \vec{r}_0 \times \vec{v}_0$$

$$\vec{e} = \frac{\vec{v} \times \vec{h}}{\mu} - \frac{\vec{r}}{r}$$

$$E = \frac{\vec{v} \cdot \vec{v}}{2} - \frac{\mu}{r} = -\frac{\mu}{2a}$$

Kepler $\Rightarrow \theta$, if given Δt

$$r(\theta) = \frac{h^2}{\mu(1 + e \cos \theta)}$$

$$\vec{r}(\theta) = r_{11} \hat{n}_1 + r_{12} \hat{n}_2 + r_{13} \hat{n}_3$$

$$\hat{p} \triangleq \frac{\vec{p}}{p}, \quad \hat{\omega} \triangleq \frac{\vec{h}}{h}, \quad \hat{q} \triangleq \hat{\omega} \times \hat{p}$$

$$\begin{bmatrix} {}^{PF} C_o^N \end{bmatrix} = \begin{bmatrix} p_1 & p_2 & p_3 \\ q_1 & q_2 & q_3 \\ w_1 & w_2 & w_3 \end{bmatrix} = \text{Body } \begin{matrix} Z \\ 3 \\ 13 \end{matrix} \times \begin{matrix} Z \\ 3 \\ 13 \end{matrix}$$

Ω_0, i, ω_0

$$\Omega(t_1) = \Omega_0 + \dot{\Omega} t_1$$

$$\Omega_0 = \text{ATAN2} \left(\overset{w_1}{\underset{Y}{C_{31}}} - \overset{w_2}{\underset{X}{C_{32}}} \right), \quad i = \cos^{-1}(C_{33})$$

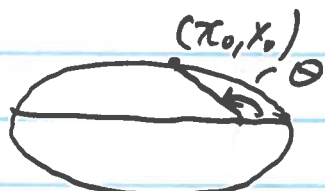
$$\omega_0 = \text{ATAN2} \left(\overset{p_3}{\underset{Y}{C_{13}}}, \overset{q_3}{\underset{X}{C_{23}}} \right) \quad \omega = \omega_0 + \dot{\omega} t_1$$

$$\dot{\Omega} = - \left[\frac{3\sqrt{\mu} R^2 J_2}{2(1-e^2)^2 a^{7/2}} \right] \cos i$$

$$\dot{\omega} = - \left[\frac{3\sqrt{\mu} R^2 J_2}{2(1-e^2)^2 a^{7/2}} \right] \left(\frac{5}{2} \sin^2 i - 2 \right)$$

$$\begin{Bmatrix} x_0 \\ y_0 \\ z_0 \end{Bmatrix}_{PF} = \begin{bmatrix} {}^{PF} C_o^N \end{bmatrix} \begin{Bmatrix} r_{01} \\ r_{02} \\ r_{03} \end{Bmatrix}_N$$

$\Theta_0 = \text{ATAN2}(y_0, x_0)$



Θ_0

Kepler $\xrightarrow{\text{Elliptic traj.}}$

$$\sqrt{\frac{\mu}{a^3}} (\overbrace{t - T_0}^{T_0}) = E_0 - e \sin E_0$$

$$\tan\left(\frac{\Theta}{2}\right) = \sqrt{\frac{1+e}{1-e}} \tan\left(\frac{E}{2}\right)$$

\hookrightarrow solve for E_0

Solve Keplers for time T_0

$$T_1 = T_0 + 96(3600)$$

$$\sqrt{\frac{\mu}{a^3}} (T_1) = E_1 - e \sin E_1$$

\hookrightarrow solve Numerically for E_1

$$E_1 \quad \tan\left(\frac{\Theta_1}{2}\right) = \sqrt{\frac{1+e}{1-e}} \tan\left(\frac{E_1}{2}\right)$$

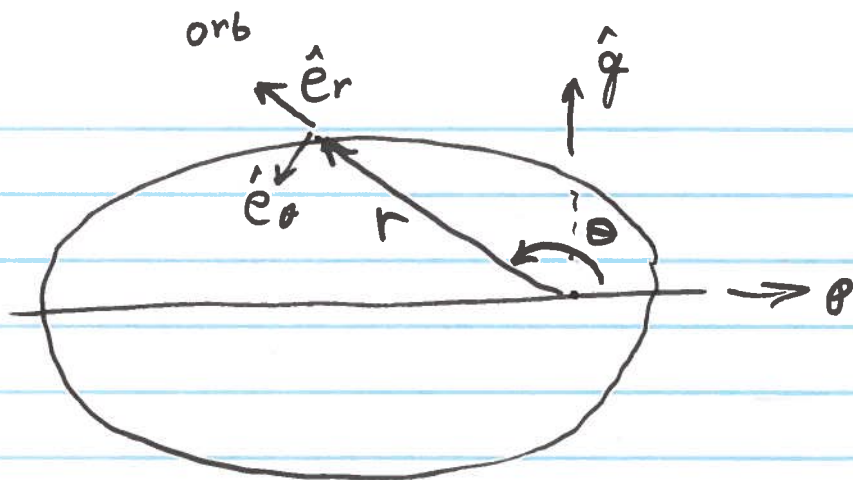
solve for Θ_1

$$r_1 = r(\Theta_1) = \frac{h^2}{\mu(1 + e \cos \Theta_1)}$$

$$\begin{Bmatrix} r_{i1} \\ r_{i2} \\ r_{i3} \end{Bmatrix}_N = \begin{bmatrix} N_{\text{orb}} \\ C \end{bmatrix} \begin{Bmatrix} r_i \\ 0 \\ 0 \end{Bmatrix}_{\text{orb}}$$

\uparrow want

$$\begin{bmatrix} N_{\text{orb}} \\ C \end{bmatrix} = \begin{bmatrix} N_{\text{PF}} \\ C^{\text{PF}} \end{bmatrix} \begin{bmatrix} \text{PF}_{\text{orb}} \\ C^{\text{orb}} \end{bmatrix}$$



$$\begin{bmatrix} {}^{orb}PF \\ C \end{bmatrix} = \begin{bmatrix} C_\theta & S_\theta & 0 \\ -S_\theta & C_\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} {}^{PF}N \\ C \end{bmatrix} = \begin{bmatrix} {}^{PF}B \\ C \end{bmatrix} \begin{bmatrix} B \\ C \end{bmatrix} \begin{bmatrix} A \\ C \end{bmatrix} \begin{bmatrix} N \\ C \end{bmatrix}$$

$$\begin{bmatrix} A \\ C \end{bmatrix} = \begin{bmatrix} C_n & S_n & 0 \\ -S_n & C_n & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad n = n_0 + \dot{n}t$$

$$\begin{bmatrix} B \\ C \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & C_i & S_i \\ 0 & -S_i & C_i \end{bmatrix}$$

$$\begin{bmatrix} {}^{PF}B \\ C \end{bmatrix} = \begin{bmatrix} C_\omega & S_\omega & 0 \\ -S_\omega & C_\omega & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \omega = \omega_0 + \dot{\omega}t$$

Low Thrust Transfer

$$\epsilon = \frac{v^2}{2} - \frac{\mu}{r} = -\frac{\mu}{2a}$$

$$\epsilon = -\frac{\mu}{2a}$$

$$\frac{d\epsilon}{dt} = \frac{d}{dt} \left(-\frac{\mu}{2a} \right) = \frac{\mu}{2a^2} \frac{da}{dt}$$

$$\begin{aligned} \frac{d\epsilon}{dt} &= P = \vec{F} \cdot \vec{v} = \vec{F} \cdot (v \hat{e}) \\ &= \cancel{\left(\frac{\mu}{r^2} \right)} \vec{a}_p \cdot v \hat{e} \\ &= \left(\dot{v} \hat{e} + \frac{v^2}{\rho} \hat{n} \right) \cdot v \hat{e} \end{aligned}$$

$$= \underbrace{\dot{v}}_{A_t} v$$

$$\frac{v^2}{2} - \frac{\mu}{r} = -\frac{\mu}{2a} \Rightarrow v = \sqrt{\mu} \left[\frac{2}{r} - \frac{1}{a} \right]^{1/2}$$

$$\frac{d\epsilon}{dt} = \frac{\mu}{2a^2} \frac{da}{dt} = A_t \left[\sqrt{\mu} \left(\frac{2}{r} - \frac{1}{a} \right)^{1/2} \right]$$

$$r = \frac{a(1-e^2)}{1+e \cos \theta}$$

$$\frac{\sqrt{\mu}}{2a^2} \frac{da}{dt} = A_t \left[\frac{1+2e \cos \theta + e^2}{a(1-e^2)} \right]^{1/2} \quad e \sim 0$$

$$\frac{\sqrt{\mu}}{2a^2} \frac{da}{dt} = (A_t) \left[\frac{1}{a} \right]^{1/2}$$

$$\frac{da}{a^{3/2}} = \frac{2}{\sqrt{\mu}} dt (A_t) \quad \text{const?}$$

$$\Rightarrow \int_{a_0}^{a_t} \frac{da}{a^{3/2}} = \frac{2A_t}{\sqrt{\mu}} (t - t_0)$$

$A_t = \text{const}$
 $\text{Mass} = \text{const}$

$$A_t = \frac{F_{\text{thrust}}}{m}$$

$$a_0 \sim r_0$$

$$a \sim r$$

$$\int_{a_0}^a \frac{da}{a^{3/2}} = \frac{2}{\sqrt{\mu}} \int_{t_0}^t \frac{\text{Thrust}}{(m_0 - \dot{m}t)} dt$$

$m = m_0 - \dot{m}t$

$$\Rightarrow \left[\frac{1}{\sqrt{r_0}} - \frac{1}{\sqrt{r}} = \left(\frac{\text{Thrust}}{\sqrt{\mu} \dot{m}} \right) \ln \left[\frac{m_0}{m_0 - \dot{m}t} \right] \right]$$