

Student Name: Jorge Andrés Esquivel Estrada

Assignment: robotic6

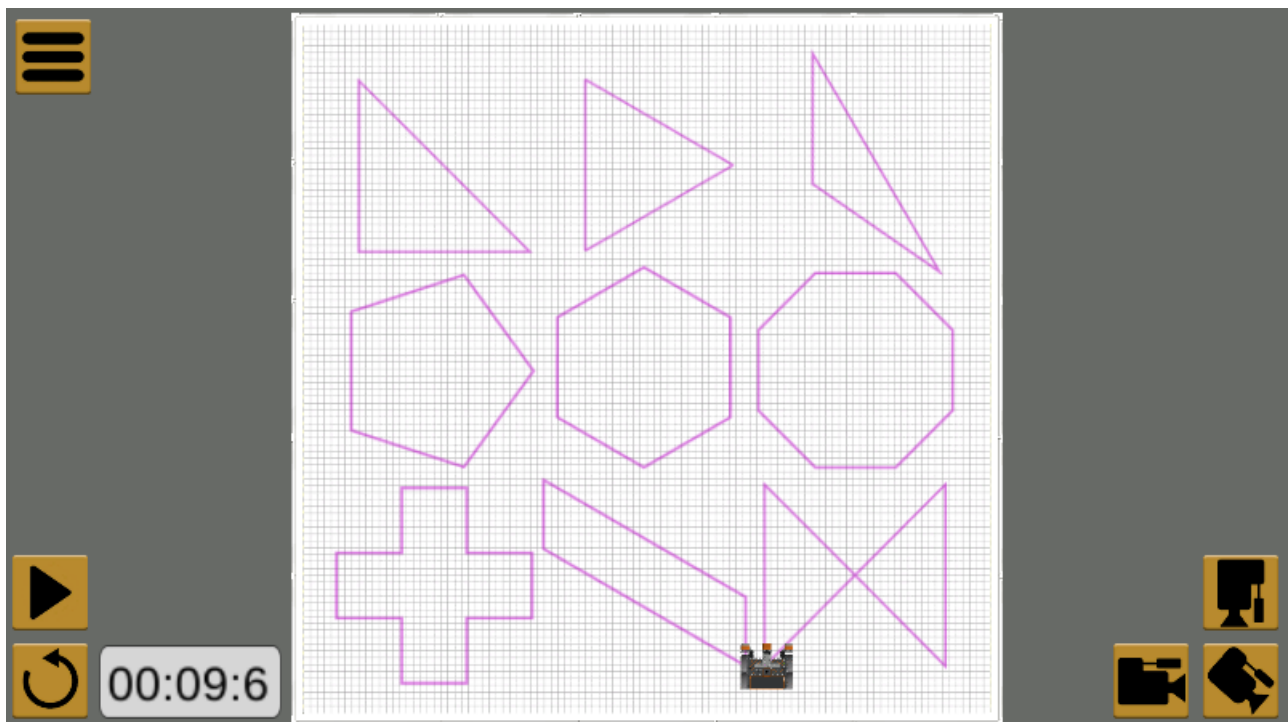
Notes: rastrea formas

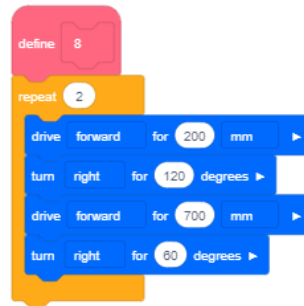
Playground: Shape Tracer

Project Name: VEXcode Project

Project Type: Blocks

Date: Fri Mar 10 2023







when started



9

define

1

drive

forward

for

500

mm



turn

right

for

135

degrees



drive

forward

for

700

mm



turn

right

for

135

degrees



drive

forward

for

500

mm



turn

right

for

90

degrees



define

3

drive

forward

for

400

mm



turn

right

for

150

degrees



drive

forward

for

700

mm



turn

right

for

150

degrees



drive

forward

for

400

mm



turn

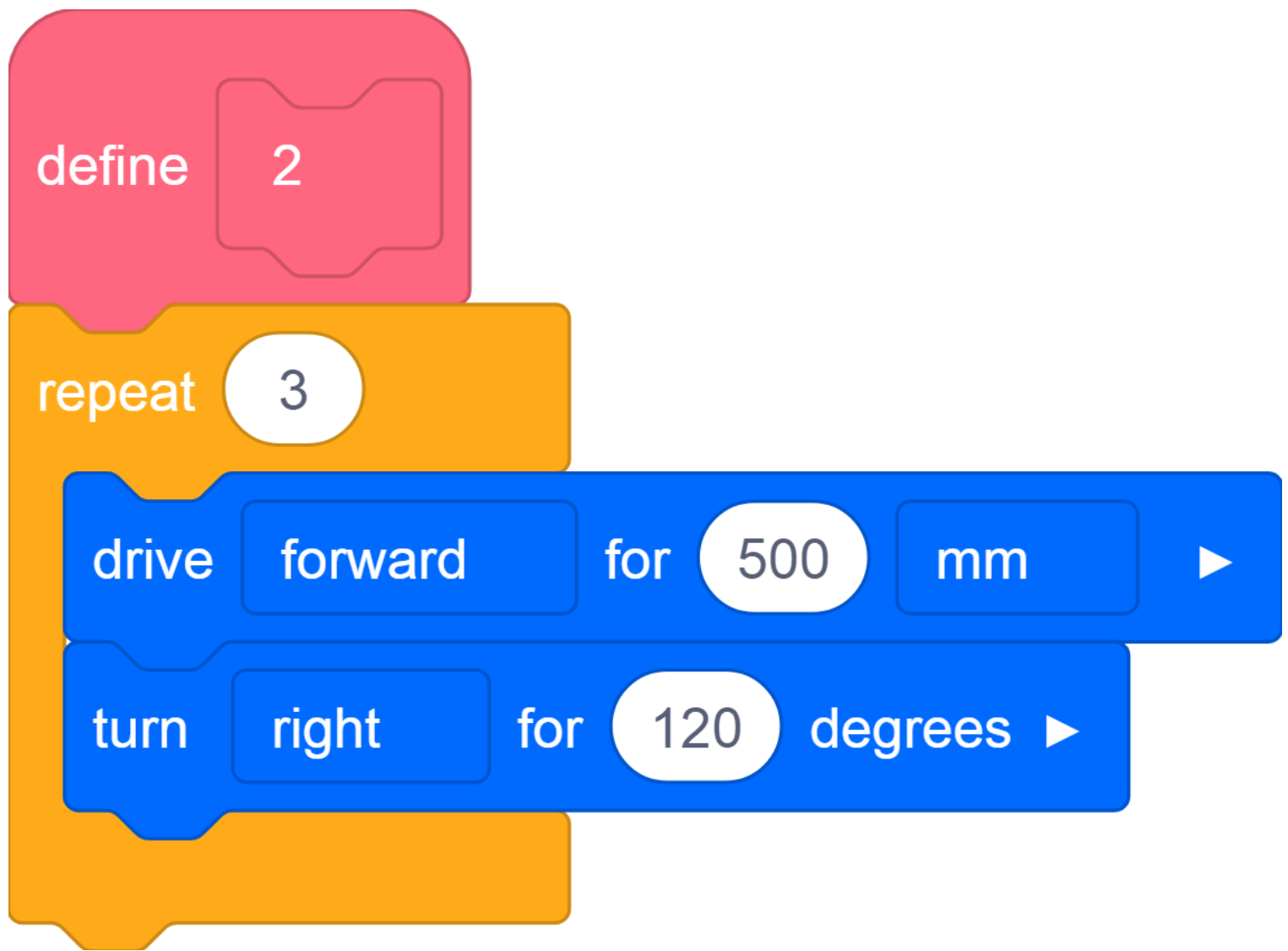
right

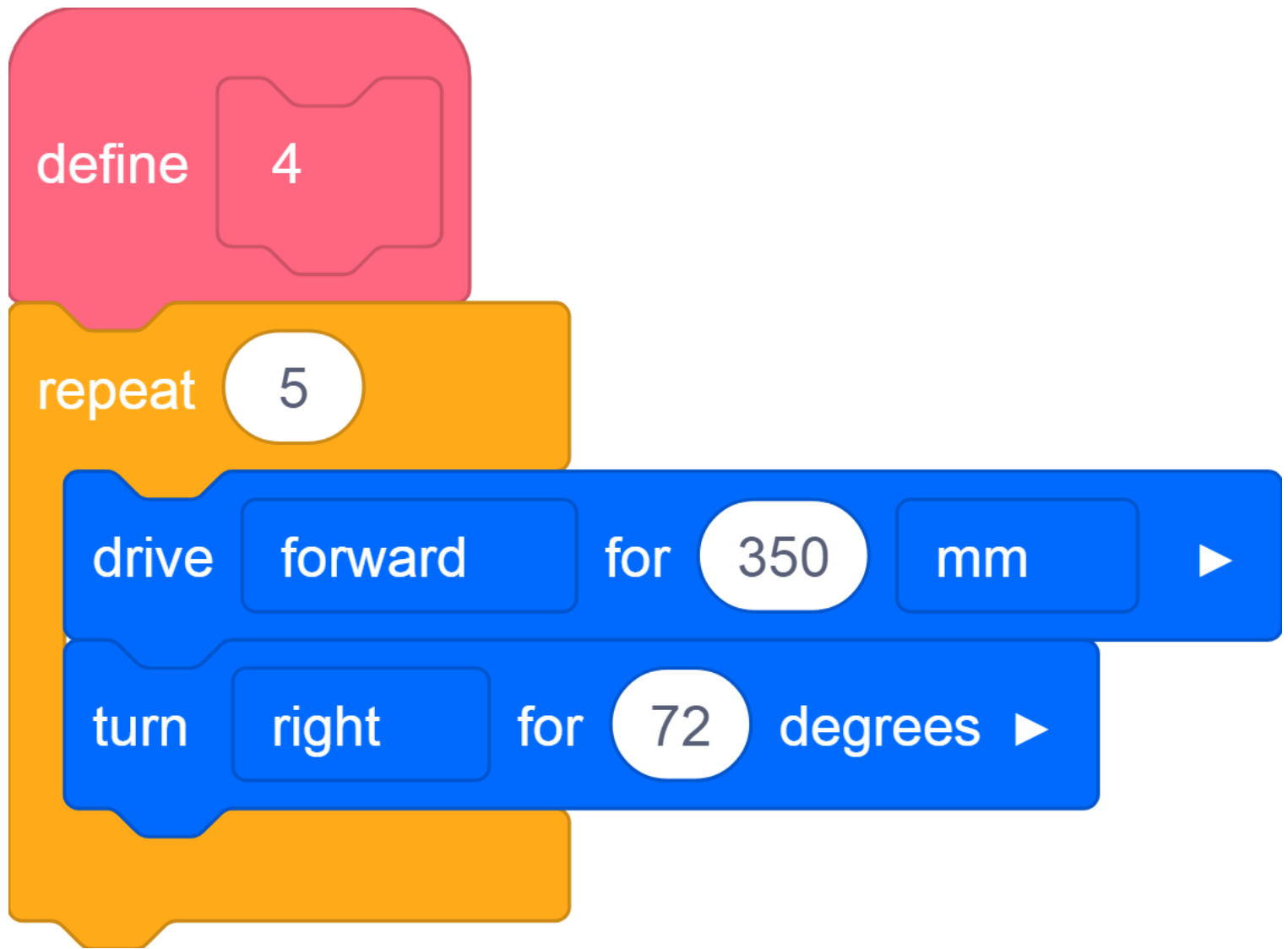
for

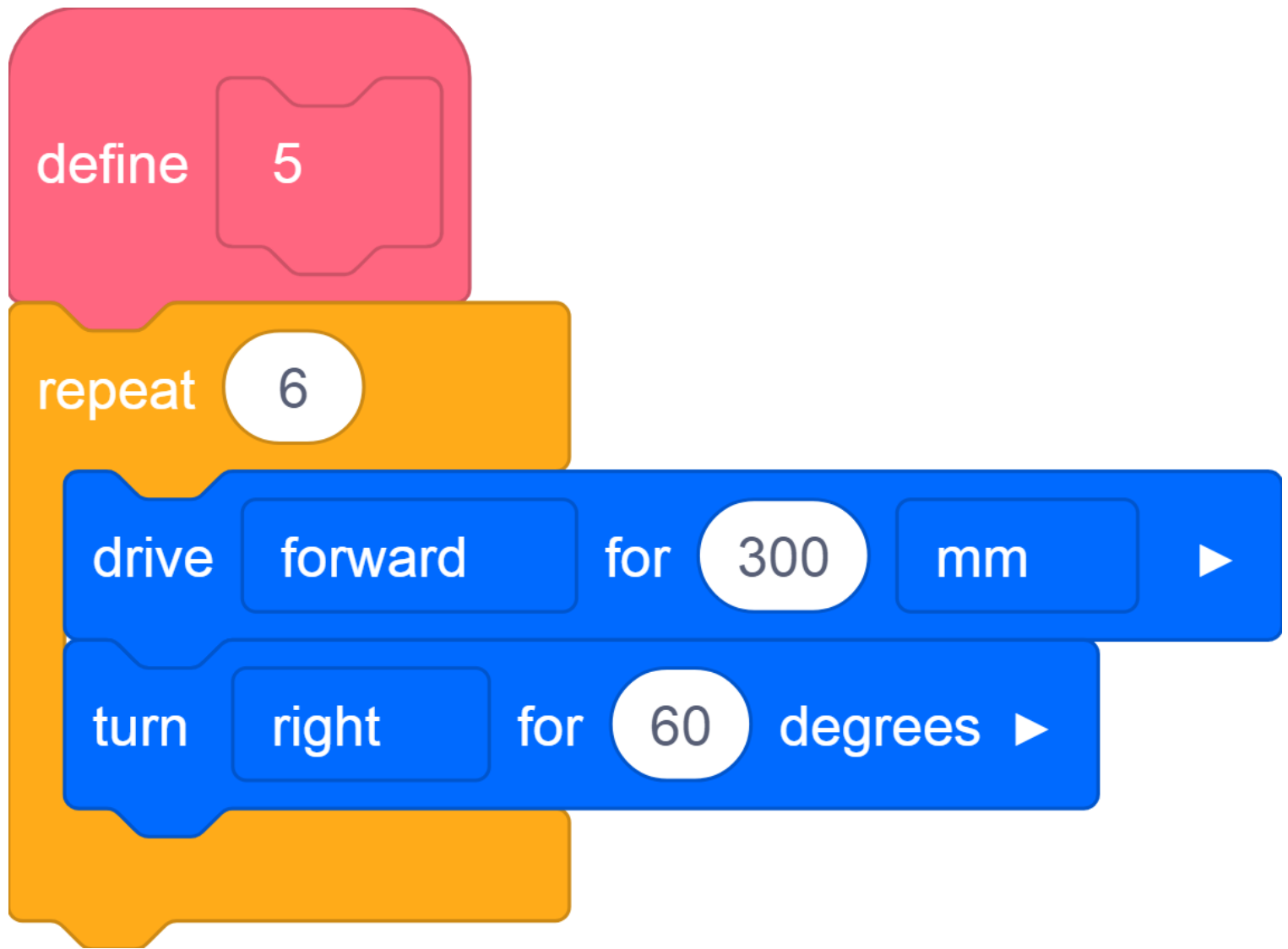
60

degrees

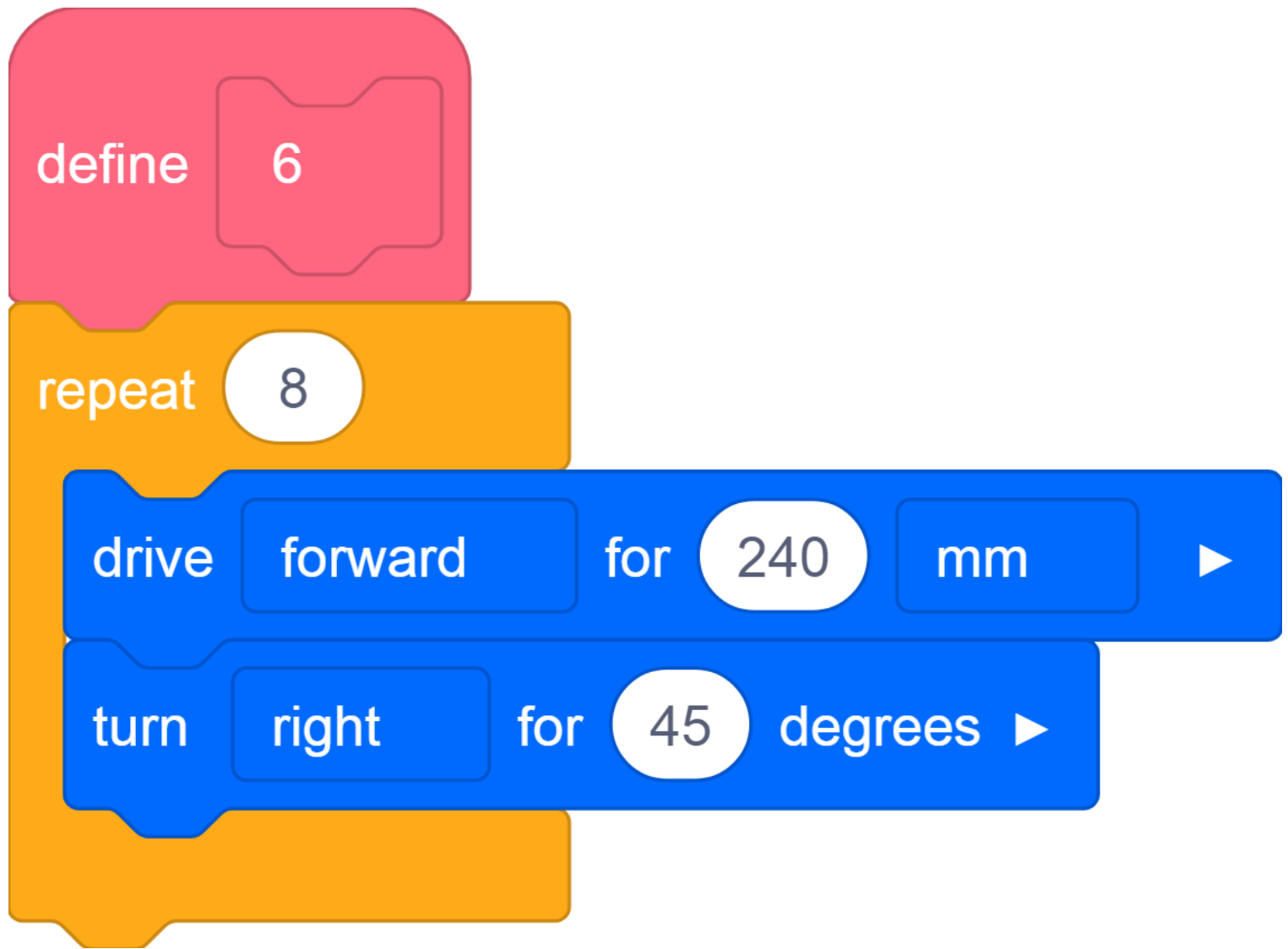


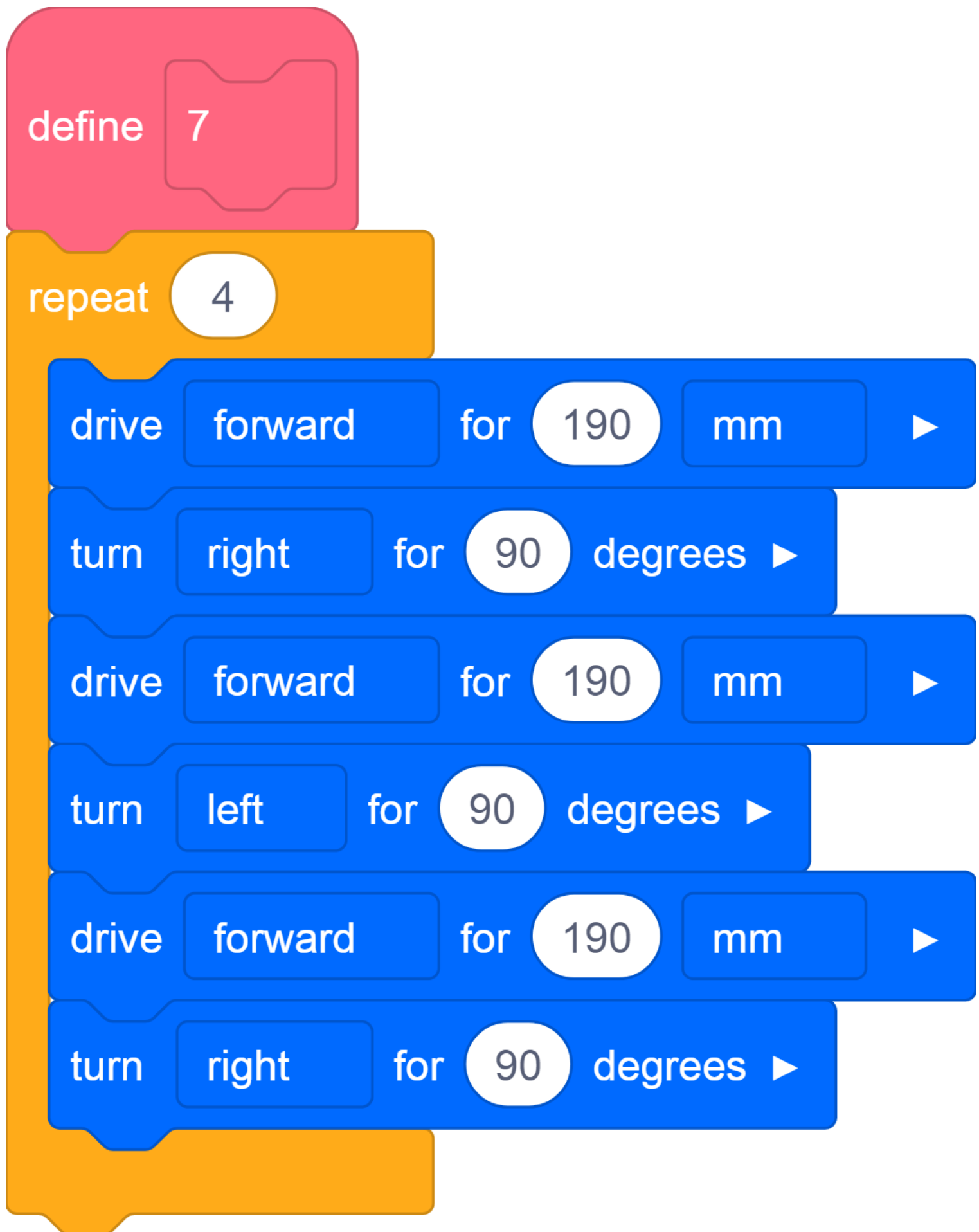


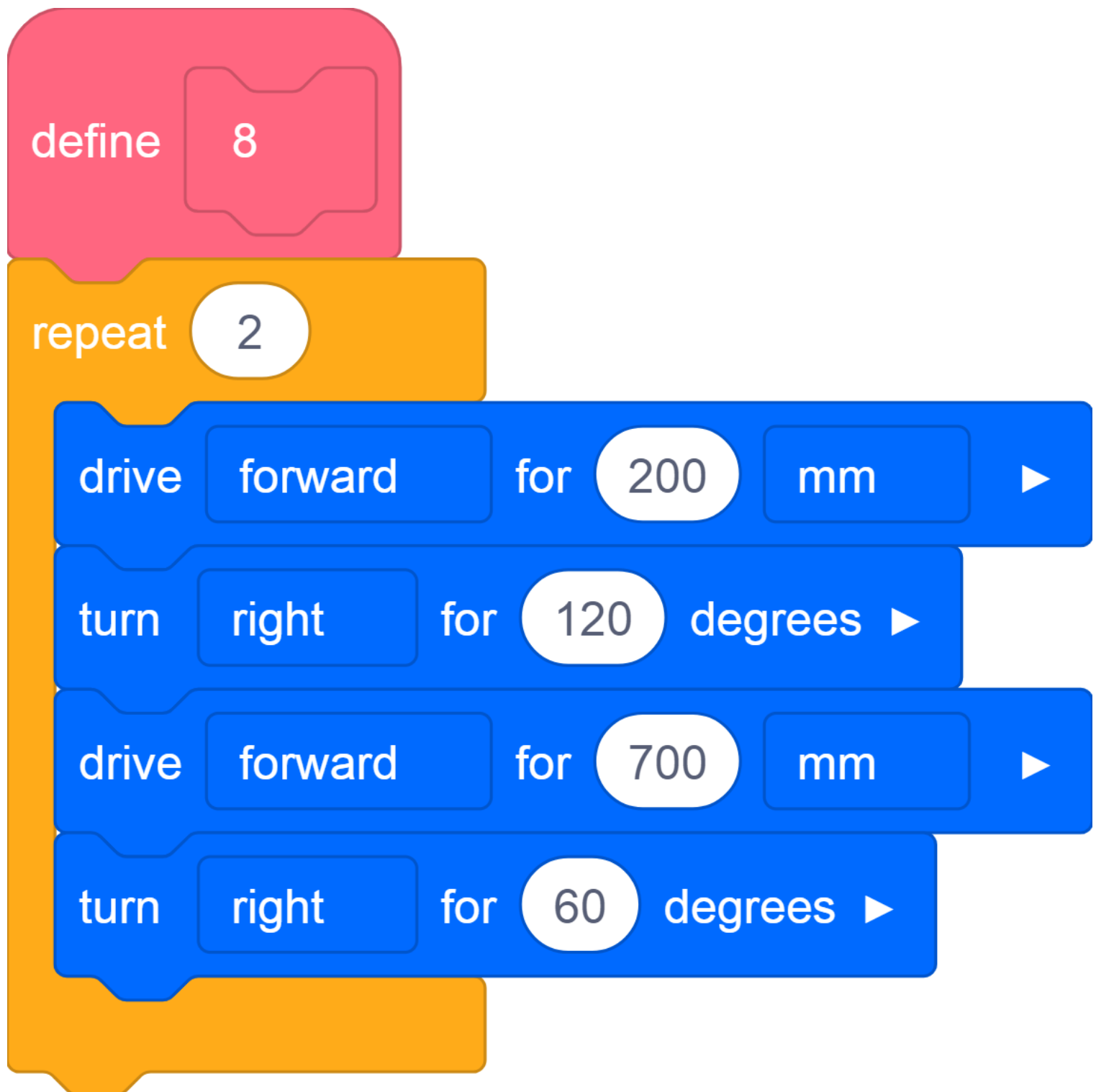












define

9

drive

forward

for

545

mm



turn

right

for

135

degrees



drive

forward

for

760

mm



turn

left

for

135

degrees



drive

forward

for

500

mm



turn

left

for

135

degrees



drive

forward

for

750

mm



turn

right

for

135

degrees

