

# Krylov Subspace Methods

## Fast Iterative Solvers, Project 1

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## 1 Remarks on used architecture and compiler options

The code was compiled using Clang-compiler and ran on an Apple Silicon M1 Pro Chip with ARM64 architecture. All timings were conducted with the a CPU-timer object of the Boost timer library,

which was specifically compiled for the previously mentioned CPU architecture. If not stated otherwise, no optimization using -O0 flag was used. For timings, the output was disabled at specific regions of the code, using a specific preprocessor directive "DISABLEIO" which can be passed to the compiler using -D option.

## 2 Generalized Minimal Residual Method - GMRES

### 2.1 Relative residuals for GMRES with and without preconditioning

For the full GMRES method, the relative residuals are plotted against the iterations index of the top loop in the full GMRES algorithm in Fig. 1. The iterations index in this case corresponds to the Krylov vectors. The number of necessary Krylov vectors to reduce the 2-norm of the initial residual by 8 orders of magnitude ( $\|\mathbf{r}_k\|/\|\mathbf{r}_0\| = 10^{-8}$ ) is given by  $\tilde{m}$  in the plot's legend. All iterations were started with parameter  $m = 600$  in case the convergence criterion was fulfilled before reaching the prescribed max number of Krylov vectors, the loop was exited prematurely with  $\tilde{m}$ . Compared to the full GMRES method without preconditioning ( $\tilde{m} = 479$ ) the Gauss-Seidel preconditioning performed best with just  $\tilde{m} = 143$  Krylov vectors that are required to established convergence (according to the aforementioned convergence criterion). I obtained  $\tilde{m} = 256$  required Krylov vectors for Jacobi preconditioning and  $\tilde{m} = 465$  Krylov vectors for Incomplete LU Factorization (ILU(0)) to reach convergence.

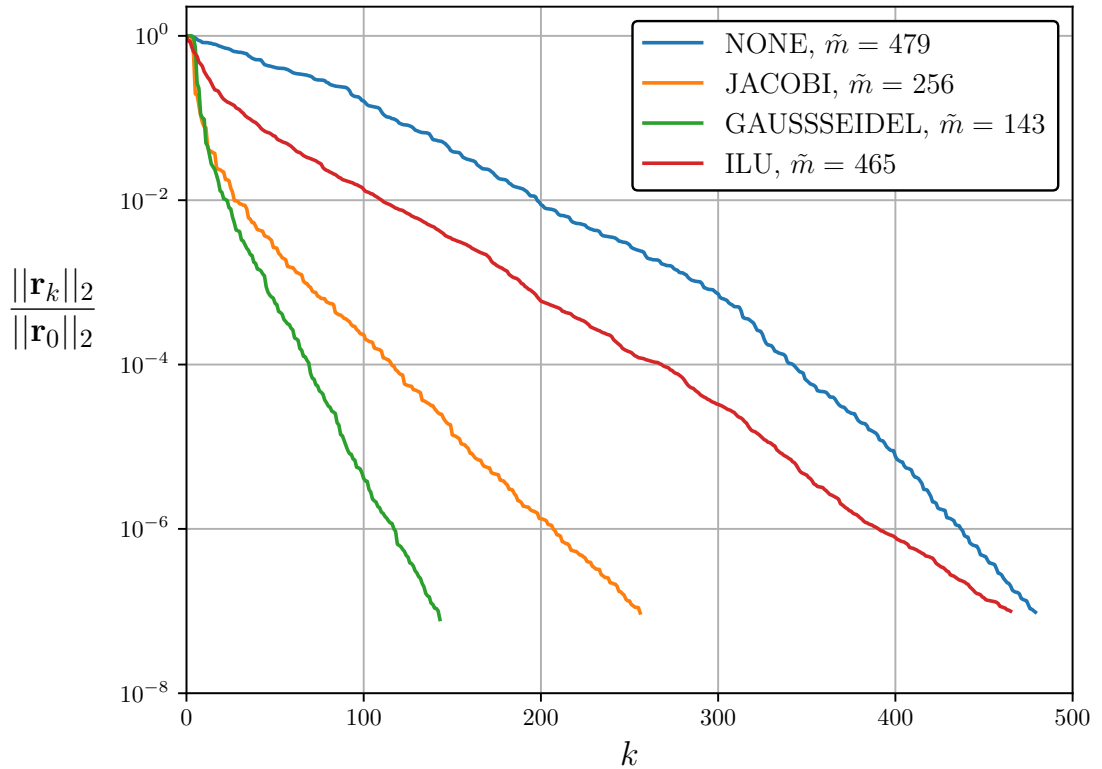


Figure 1: Comparison of the different preconditioning options for the GMRES procedure to the full GMRES Method without preconditioning using  $m = 600$  Krylov vectors as an input.

## 2.2 Optimization of restart parameter for restarted GMRES

In an effort to find a "good" restart parameter the parameters  $m = 30$ ,  $m = 50$  and  $m = 100$  are compared to the runtime of full GMRES in table Tab. 1 for no optimization and in table Tab. 2 for moderate optimization level. Restart parameters of  $m = 50$  and  $m = 100$  showed a decrease in

$m$	Iterations	User [s]	System [s]	CPU-Time [s]
479 (full)	1	5.04	0.11	5.15
30	144	7.25	0.08	7.33
50	43	4.43	0.06	4.49
100	14	4.23	0.09	4.32

Table 1: Comparison of timings for different restart parameters using clang compiler with no optimization (-O0 flag) + disabled Output (-DDISABLEIO) and without preconditioning

$m$	Iterations	User [s]	System [s]	CPU-Time [s]
479 (full)	1	0.29	0.1	0.39
30	143	0.46	0.06	0.52
50	43	0.29	0.07	0.36
100	14	0.27	0.07	0.34

Table 2: Comparison of timings for different restart parameters using clang compiler with optimization (-O2 flag) + disabled Output (-DDISABLEIO) and without preconditioning

CPU-Time of 12.8% and 16.1% for restarted GMRES compared to full GMRES<sup>1</sup> respectively, where as a restart parameter of  $m = 30$  showed an increase of 43%, if compiler optimization is disabled. Activating a moderate optimization level (-O2) restart parameters of  $m = 50$  and  $m = 100$  decreased the CPU-Time only by 7.7% and 12.82%, compared to full GMRES. Furthermore, I conducted an investigation to find the globally "best" restart parameter, which is presented in Fig. 2. The globally best restart parameter was found to be  $m = 63$ , requiring 25 iterations to converge in 3.73 seconds, which is a decrease by 27.6% opposed to the full GMRES method. The red line in Fig. 2 denotes the CPU-time of the full GMRES method ( $m = 479$ ). For all restart parameter  $m$  for which the blue line is below the CPU time for full GMRES (indicated by the red line), the restarted formulation of the GMRES method is faster than full GMRES. The paragraphs in the course of CPU time can be attributed to the reduction of the required loop iterations.

<sup>1</sup>in the following context "full" GMRES refers to a restarted GMRES method where only one loop iteration of the restarted GMRES method is necessary to establish convergence according to the given convergence criterion.

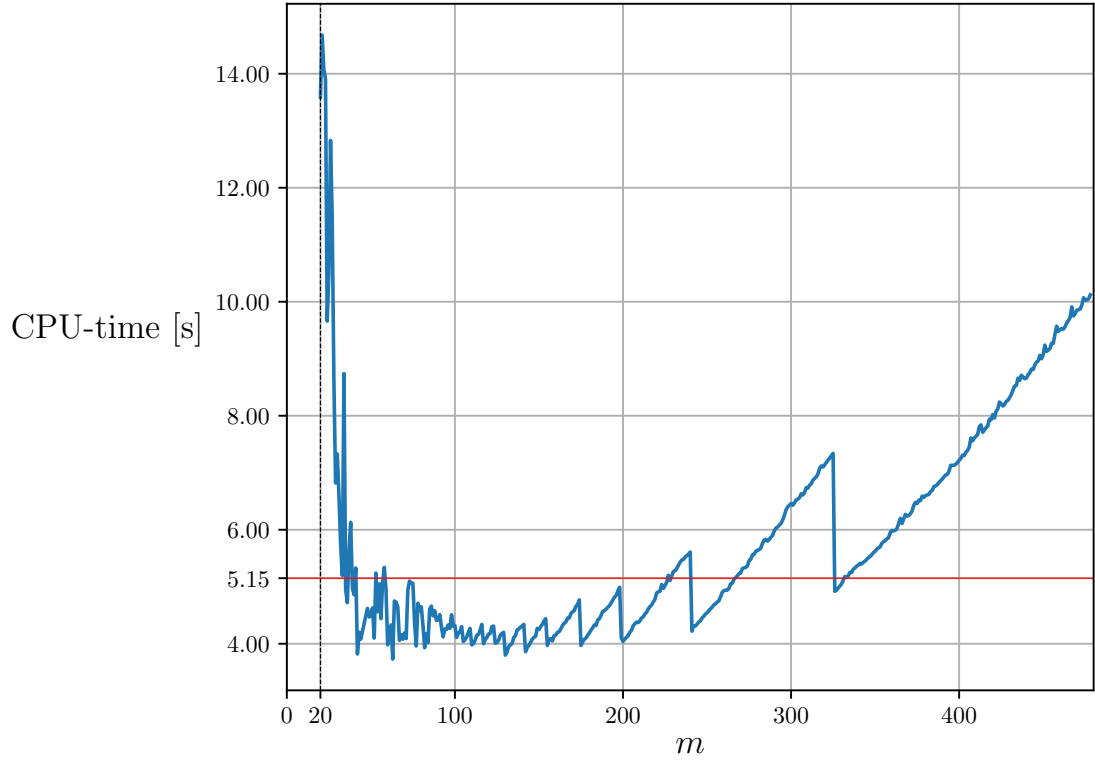


Figure 2: CPU-timings of restarted GMRES for different restart parameters  $m = 20 \dots 478$  with global minimum at  $m = 63$  with  $3.73s$ , using clang compiler with no optimization (-O0 flag) + disabled Output (-DDISABLEIO) and without preconditioning

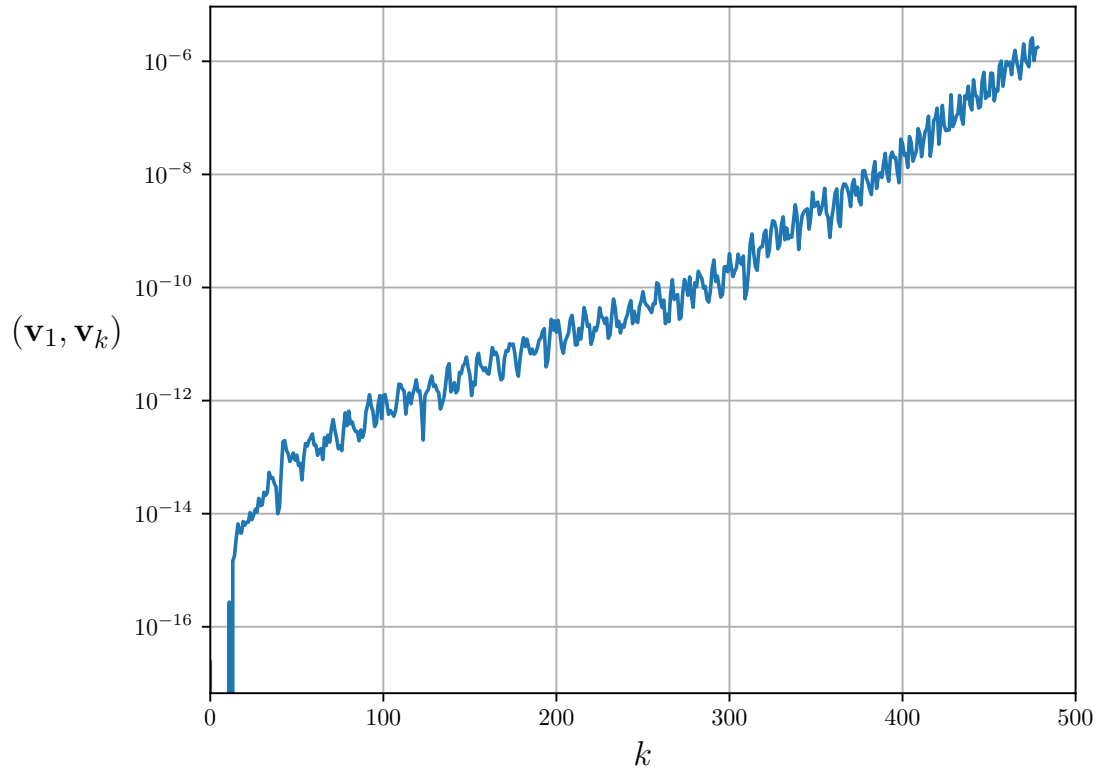


Figure 3: Orthogonality of the Krylov vectors. Plot of the dot product  $(\mathbf{v}_1, \mathbf{v}_k)$  against the iteration index  $k$  of the top loop in the GMRES method

### 3 Conjugate Gradient Method - CG

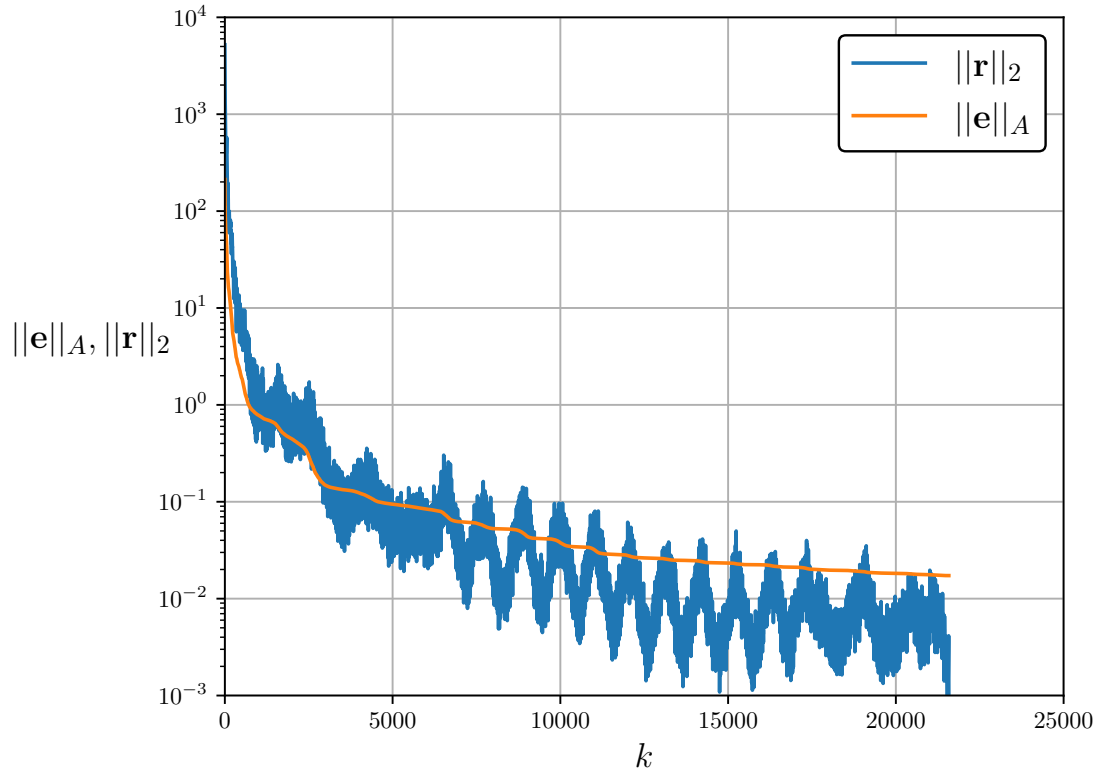


Figure 4: Error  $\mathbf{e}_k = \mathbf{x}_k - \mathbf{x}$  in A-Norm  $\|\mathbf{e}\|_A = \sqrt{(\mathbf{A}\mathbf{e}, \mathbf{e})}$  and the residual in 2-Norm  $\|\mathbf{e}\|_2 = \sqrt{(\mathbf{r}, \mathbf{r})}$  against the iteration index  $k$  for CG-method