# CNN 분류기 개발 프로젝트

전자정보공학부 IT융합전공 박준혁 (20170590) AI융합학부 김혜빈 (20192897) AI융합학부 이찬도 (20160391)

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## \*Team Introduction

# **Role Sharing**

#### [ 역할 분담 ]←

- 팀장 박준혁 : 데이터 불러오기 코드 작성 / 데이터셋 통합 코드 작성 / 데이터 전처리 코드 작↔ 성 / CNN 구조 설계 / 평가보고서 작성 / 발표 자료 작성 / 발표 및 시연↔
- 팀원 김혜빈 : 데이터 전처리 코드 작성 (데이터 증강, Shuffle) / CNN 구조 설계 /←

  CNN 구조 파라미터 조정 / 모델 학습 및 검정 / 과대적합 문제 해결←
- 팀원 이찬도: NVIDIA AGX Xavier Developer Kit 활용 방법 조사 및 예제 실행 /←

  CheckPointAndSaveModel 방법 조사 / Helper 코드 활용 방법 조사←







**Programmer** 



**Engineer** 

# Team Introduction

# **Meeting Progress**

#### [ 회의 진행 ]←

"2021.11.22" 1차 회의 : 전체 프로젝트 계획 수립 및 To Do List 작성↔

"2021.11.25" 2차 회의 : 데이터 불러오기, 데이터셋 통합 코드 작성 및 점검 ↔

"2021.11.28" 3차 회의 : CNN 구조 설계 1차 시도↔

"2021.12.01" 4차 회의 : CNN 구조 설계 2차 시도↔

"2021.12.05" 5차 회의 : 평가 보고서, 발표 자료 작성 및 시연 준비↔





#### 이름

🗐 211122 1차회의.txt

📄 211125\_2차회의.txt

📄 211128\_3차회의.txt

P CNN 개발 프로젝트 발표자료.pptx

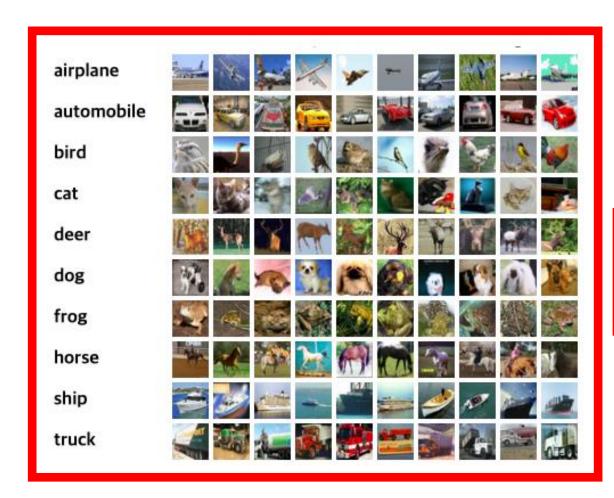
🧰 결과보고서.docx

📴 발표자료.pptx

📄 프로젝트 공지.txt

# → Data Preparation

### **CIFAR-10 Dataset**



 데이터 수집 / 준비
 CIFAR-10 dataset은 32x32 픽셀의
 60,000개 컬러 이미지가 10개의 클 래스로 레이블링 되어 있음.

각 카테고리별 6,000개의 데이터 중 앞에 5,000개는 훈련 데이터, 뒤에 1,000개는 시험 데이터로 사용함.

이렇게 해서 총 60,000개의 이미지를 통해 CNN 분류기를 설계함.

# → Data Preparation

#### CIFAR-10 Dataset

아래 그림은 CIFAR 10 데이터 중 무작위로 40개의 이미지를 추출하여 출력한 결과와 함께 한 이미지의 픽셀 값을 나타낸 것이다. CIFAR 10 데이터셋 내 모든 인스턴스들은 (32, 32, 3)의 구조를 가지고 있는데, 이는 가로 세로 픽셀 값이 모두 '32'이며, 3개의 RGB 채널을 가지고 있는 것을 의미한다. 또한, 각 픽셀 값은 Resize로 이미지 사이즈가 조정되는 과정에서 0 ~ 1 사이의 값으로 변화되기 때문에 입력 단계에서 추가적인 정규화 처리는 필요하지 않다.



```
array([[0.78431373, 0.79215686, 0.77254902],
[0.79215686, 0.8 , 0.78039216],
[0.79607843, 0.80392157, 0.78431373],
[0.81176471, 0.81960784, 0.8 ],
[0.83137255, 0.83921569, 0.81960784],
[0.83529412, 0.84313725, 0.82352941],
[0.82352941, 0.83137255, 0.81176471],
[0.79215686, 0.8 , 0.78039216],
[0.8666667, 0.8745098 , 0.85490196],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.87058824, 0.87843137, 0.85882353],
[0.8705882451, 0.89411765, 0.8745098],
```

### **Data Load**

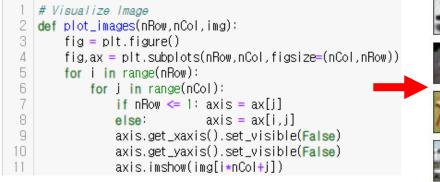
### **Definition**

#### 기본 변수 정의

```
5
   # 상수 사용을 위함
  class Default:
                                  10
3
       imgR
                = 32
                                  15
                = 32
       imgC
4
                = 3
       channel
                                  20
       imgCount = 6000
                                  25
       split
                = 5000
                                  30
                                            10
```

```
array([[0.78431373, 0.79215686, 0.77254902],
       [0.79215686, 0.8]
                              . 0.78039216].
       [0.79607843, 0.80392157, 0.78431373],
       [0.79607843, 0.80392157, 0.78431373],
       [0.81176471, 0.81960784, 0.8
       [0.83137255, 0.83921569, 0.81960784],
       [0.83529412, 0.84313725, 0.82352941],
       [0.82352941, 0.83137255, 0.81176471],
       [0.79215686, 0.8
                              , 0.78039216],
       [0.8666667. 0.8745098 . 0.85490196].
       [0.87058824. 0.87843137. 0.85882353].
       [0.80784314, 0.81568627, 0.79607843],
```

#### 사용자 함수 정의

























































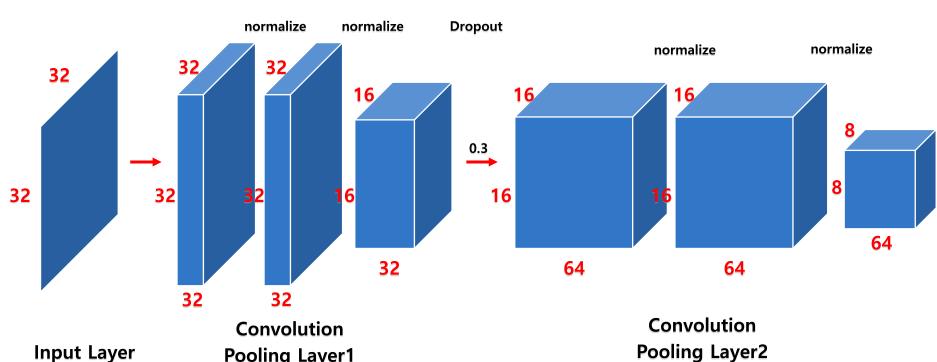
## → Data Load

### **Dataset Create & Train Test Split**

```
# 데이터셋 로드
      (train_images, train_labels), (test_images, test_labels) = data_load(path, class_labels)
       print(f'train data: {train_images.shape} {train_labels.shape}')
       print(f'test_data: {test_images.shape} {test_labels.shape}')
                                train 0: (5000, 32, 32, 3) (5000,)
                                test 0: (1000, 32, 32, 3) (1000,)
                                train 1: (5000, 32, 32, 3) (5000,)
0: (6000, 32, 32, 3) (6000,)
                                test 1: (1000, 32, 32, 3) (1000,)
                                train 2: (5000, 32, 32, 3) (5000.)
1: (6000, 32, 32, 3) (6000,)
                                test 2: (1000, 32, 32, 3) (1000,)
2: (6000, 32, 32, 3) (6000,)
                                train 3: (5000, 32, 32, 3) (5000.)
                                test 3: (1000, 32, 32, 3) (1000,)
                                                                           Done: set x, y data
3: (6000, 32, 32, 3) (6000,)
                                train 4: (5000, 32, 32, 3) (5000,)
                                                                           Successfully load data
4: (6000, 32, 32, 3) (6000,)
                                test 4: (1000, 32, 32, 3) (1000,)
                                                                           train data: (50000, 32, 32, 3) (50000,)
                                train 5: (5000, 32, 32, 3) (5000,
5: (6000, 32, 32, 3) (6000,
                                                                          test data: (10000, 32, 32, 3) (10000,)
                                test 5: (1000, 32, 32, 3) (1000,)
6: (6000, 32, 32, 3) (6000,)
                                train 6: (5000, 32, 32, 3) (5000,)
7: (6000, 32, 32, 3) (6000,)
                                test 6: (1000, 32, 32, 3) (1000,)
                                train 7: (5000, 32, 32, 3) (5000,)
8: (6000, 32, 32, 3) (6000,)
                                test 7: (1000, 32, 32, 3) (1000,)
9: (6000, 32, 32, 3) (6000,)
                                train 8: (5000, 32, 32, 3) (5000,)
                                test 8: (1000, 32, 32, 3) (1000,)
Done: set x, y dictionary
                                train 9: (5000, 32, 32, 3) (5000,)
```

test 9: (1000, 32, 32, 3) (1000,)
Done: split x,y dict --> train/test

# CNN Structure Block Diagram (1)

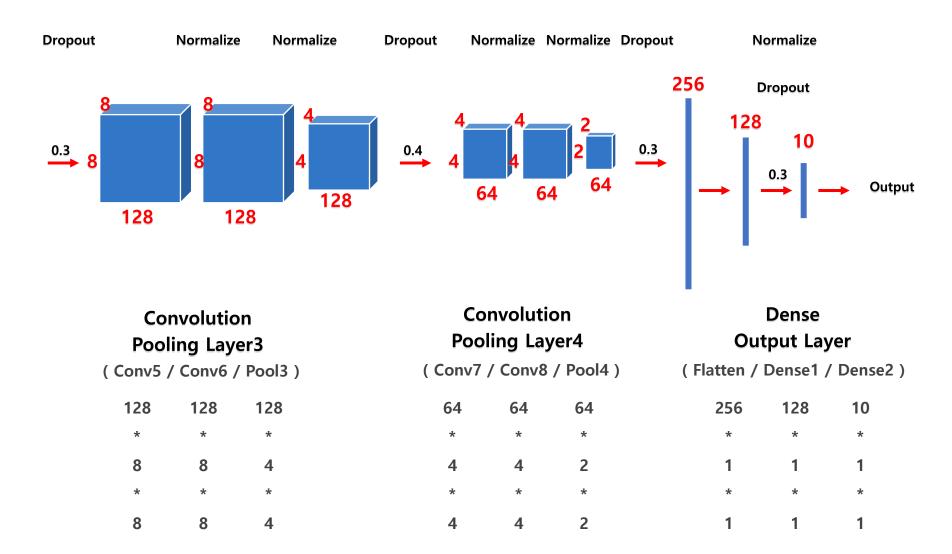


out Layer	Convolution Pooling Layer1 ( Conv1 / Conv2 / Pool1 )				
3	32	32	32		
*	*	*	*		
32	32	32	16		
*	*	*	*		
32	32	32	16		

# **Pooling Layer2**

(Conv3 / Conv4 / Pool2) 

# **CNN Structure Block Diagram (2)**



# **CNN Structure Summary**

Model: "sequential_1	0
----------------------	---

Layer (type)	Output Shape	Param #
	(None, 32, 32, 32)	896
batch_normalization_164 (Ba tchNormalization)	(None, 32, 32, 32)	128
conv2d_147 (Conv2D)	(None, 32, 32, 32)	9248
batch_normalization_165 (Ba tchNormalization)	(None, 32, 32, 32)	128
max_pooling2d_73 (MaxPooling2D)	(None, 16, 16, 32)	0
dropout_108 (Dropout)	(None, 16, 16, 32)	0
conv2d_148 (Conv2D)	(None, 16, 16, 64)	18496
batch_normalization_166 (Ba tchNormalization)	(None, 16, 16, 64)	256
conv2d_149 (Conv2D)	(None, 16, 16, 64)	36928
batch_normalization_167 (Ba tchNormalization)	(None, 16, 16, 64)	256
max_pooling2d_74 (MaxPooling2D)	(None, 8, 8, 64)	0
dropout_109 (Dropout)	(None, 8, 8, 64)	0
conv2d_150 (Conv2D)	(None, 8, 8, 128)	73856
batch_normalization_168 (Ba tchNormalization)	(None, 8, 8, 128)	512
dropout_110 (Dropout)	(None, 8, 8, 128)	0
conv2d_151 (Conv2D)	(None, 8, 8, 128)	147584
batch_normalization_169 (Ba tchNormalization)	(None, 8, 8, 128)	512
max_pooling2d_75 (MaxPooling2D)	(None, 4, 4, 128)	0
dropout_111 (Dropout)	(None, 4, 4, 128)	0

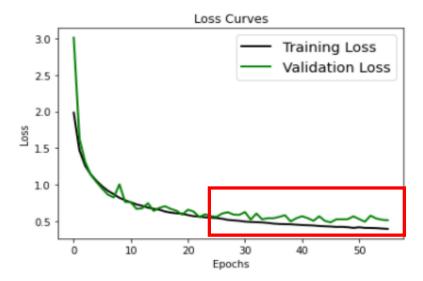
conv2d_152 (Conv2D) (None, 4, 4, 64)	73792
batch_normalization_170 (Ba (None, 4, 4, 64) tchNormalization)	256
dropout_112 (Dropout) (None, 4, 4, 64)	0
conv2d_153 (Conv2D) (None, 4, 4, 64)	36928
batch_normalization_171 (Ba (None, 4, 4, 64) tchNormalization)	256
max_pooling2d_76 (MaxPoolin (None, 2, 2, 64) g2D)	0
dropout_113 (Dropout) (None, 2, 2, 64)	0
flatten_18 (Flatten) (None, 256)	0
dense_36 (Dense) (None, 128)	32896
batch_normalization_172 (Ba (None, 128) tchNormalization)	512
dropout_114 (Dropout) (None, 128)	0

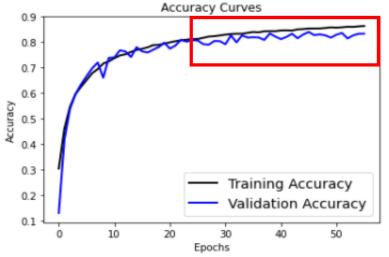
Total params: 434,730 Trainable params: 433,322 Non-trainable params: 1,408

### **CNN Model Learning**

Learning Parameter: Epochs = 500 / Early Stopping.Patience = 10

Epoch 00044: val\_loss did not improve from 0.49674 Epoch 00045: val\_loss did not improve from 0.49674 Epoch 00046: val\_loss improved from 0.49674 to 0.48407, 000\_training/cp-0046-0.48.ckpt Epoch 00047: val\_loss did not improve from 0.48407 Epoch 00048: val\_loss did not improve from 0.48407 Epoch 00049: val\_loss did not improve from 0.48407 Epoch 00050: val\_loss did not improve from 0.48407 Epoch 00051: val\_loss did not improve from 0.48407 Epoch 00052: val\_loss did not improve from 0.48407 Epoch 00053: val\_loss did not improve from 0.48407 Epoch 00054: val\_loss did not improve from 0.48407 Epoch 00055: val\_loss did not improve from 0.48407 Epoch 00056: val\_loss did not improve from 0.48407





### ightharpoonup Evaluation

### **Performance Test**

True: deer

Predict: deer

True: automobile

Predict- automobile

True: ship

Predict: ship

True: truck

Predict truck

True: ship

Predict: ship

Thue cat

Predict: cat

True: cat

Predict: cat

True: bird

Predict: bird

True: deer

Predict deer

True: bird

Predict: bird

True: airplane

Predict: airplane

Predict, deer

True: deer

Predict: deer

True-truck

Predict: truck

True-bird

Predict: bird

True: deer

Predict deer

True: automobile

Predict: truck

True: deer

Predict: deer

Predict: horse

Predict. ship

True cat

Predict: cat

True horse



True: airplane Predict: airplane















True: deer









True: frog







True: frog

Predict: frog

True: automobile

Predict: automobile

Predict, ship

True: dog

Predict: dog

True shin

Predict: ship

True-deer

Predict: deer

True: frog

Predict: froa

True: ship

Predict: airplane



True: airplane

Predict airplane



True: ship

Predict. ship

True: airplane

Predict: deer

Thue shin

Predict: ship

True: airplane

Predict airplane

True: frag

Predict: deer

True: ship

Predict-ship

True: deer

Predict: deer





True: frog

Predict: frog

True: cat

Predict: cat





Thue hird

Predict: bird

True: bird

Predict bird

True: automobile

True: airplane

Predict: airplane

True: bird

Predict: bird

Predict, truck





True: truck

Predict: truck

True: dog

Predict dog

Predict: ship

Predict. deer



True: horse

Predict: horse

True: bird

Predict: bird

True: horse

Predict: horse

















True: deer

Predict: deer

Predict: dog







































True: dog Predict: dog



**Prediction** 

print(pred)

print(pred.shape)

pred = model.predict(test\_images)

```
# Converting the predictions into label index
    pred_labels = np.argmax(pred, axis=1)
 7 print(pred labels)
[[8.1475837e-06 1.6372454e-07 1.2896578e-04 ... 1.7792576e-04
  1.1053589e-05 3.8428734e-061
[1.6674405e-03 3.7332320e-05 4.9921684e-03 ... 1.0810441e-04
 8.9227957e-05 2.7710406e-041
[5.5045797e-04 1.1152675e-05 3.3990669e-01 ... 5.2811165e-04
 4.9362170e-05 1.2164089e-041
[3.6471534e-05 1.6703419e-06 6.3088536e-04 ... 7.7230132e-01
 2.8163120e-06 2.7078061e-061
[3.7712550e-03 5.0671010e-06 9.8829460e-01 ... 3.9528991e-04
 5.2363132e-05 2.0366554e-041
```

[6.8038549e-05 1.2875648e-05 9.7700185e-01 ... 6.9528673e-05

#### Result

(10000, 10) [3 3 4 ... 7 2 2]

4.6684770e-05 1.1698684e-0511

```
1 | test_loss, test_acc = model.evaluate(test_images, test_labels, verbose=2)
2 print('테스트 정확도:',test_acc)
```

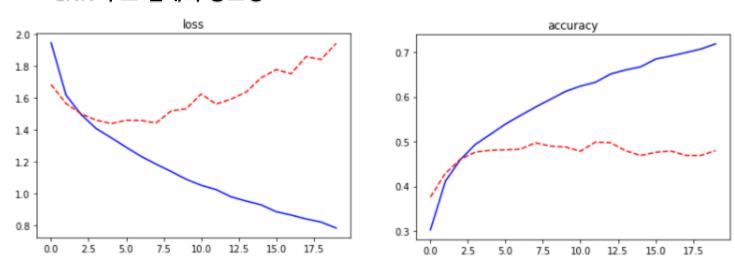
313/313 - 20s - Toss: 0.2993 - accuracy: 0.9041 - 20s/epoch - 63ms/step 테스트 정확도: 0.9041000008583069

테스트 정확도: 0.904

# ⁺Evaluation

### **Conclusion**

#### · CNN 구조 설계의 중요성



하이퍼 파라미터 조정 없이 Convolution Pooling Layer를 두 개 층만 쌓아 만들었던 초기 모델은 좋은 분류 성능을 보이지 못하였음. 정확도가 0.4 ~ 0.7 사이에서 형성되며, loss 값 역시 튀는 현상이 목격되었음.

따라서 보다 복잡한 CNN 구조를 설계하여 조금씩 파라미터를 조정해가는 방식의 접근이 필요함을 깨달음.

Convolution Pooling Layer를 4개 층까지 확장하고, BatchNormalization, DropOut 기법을 사용하여, 오차 값을 보정하고 과대적합 문제를 해결함.

그 결과, 테스트 데이터 정확도 : 0.904의 높은 분류 성능을 얻음.

# Thank you