## STA 314: Statistical Methods for Machine Learning I

Lecture 5 - More on regularized linear regression and gradient descent

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#### Review: why consider alternatives to the OLS estimator?

Recall the linear model is

$$Y = \beta_0 + \beta_1 X_1 + \dots + \beta_p X_p + \epsilon.$$

Alternative fitting procedures to OLS could yield **better prediction accuracy** and **model interpretability**.

- Prediction: OLS estimator has large variance when p is large. Especially, if p > n, then OLS estimator is not unique and its variance is very large.
- Interpretability: By removing irrelevant features that is, by setting some coefficient estimates to zero – we can obtain a model that is more parsimonious hence more interpretable.

#### Review

- Best subset selection
  - Great! But computationally unaffordable (choose from  $2^{\rho}$  models)!
- Stepwise subset selection
  - Forward stepwise selection
  - Backward stepwise selection
  - Computationally affordable, but greedy approaches
- Are there better alternatives?
  - Shrinkage Methods! In particular, the Lasso.

#### Magic of the Lasso

Why does the lasso, unlike ridge regression, yield coefficient estimates that have exact zero?

#### Another Formulation for Ridge Regression and Lasso

The lasso and ridge regression coefficient estimates solve the problems

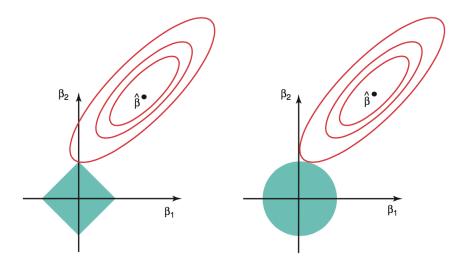
$$\underset{\beta}{\text{minimize}} \sum_{i=1}^{n} \left( y_i - \beta_0 - \sum_{j=1}^{p} \beta_j x_{ij} \right)^2 \quad \text{subject to} \quad \sum_{j=1}^{p} |\beta_j| \le s$$

and

minimize 
$$\sum_{i=1}^{n} \left( y_i - \beta_0 - \sum_{j=1}^{p} \beta_j x_{ij} \right)^2$$
 subject to  $\sum_{j=1}^{p} \beta_j^2 \le s$ ,

Here  $s \ge 0$  is some regularization parameter (connected with the original  $\lambda$ ).

# Understand why the Lasso yields zero estimates

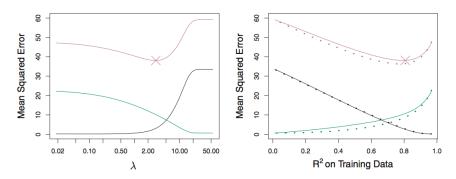


The solid areas are the constraint regions,  $|\beta_1| + |\beta_2| \le s$  and  $\beta_1^2 + \beta_2^2 \le s$ , while the red ellipses are the contours of the RSS.

#### Lasso vs Ridge

- The ability of yielding a sparse model is a huge advantage of Lasso comparing to Ridge.
- A more sparse model means more interpretability!
- What about their prediction performance?

# Comparing the MSE of Lasso and Ridge

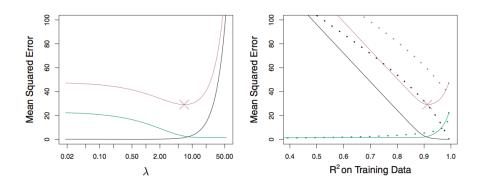


Left: Plots of squared bias (black), variance (green), and test MSE (purple) for the lasso on a simulated data set.

Right: Comparison of squared bias, variance and test MSE between lasso (solid) and ridge (dotted). Both are plotted against their  $R^2$  on the training data, as a common form of indexing. The crosses in both plots indicate the lasso model for which the MSE is smallest.

When the true coefficients are non-sparse, ridge and lasso have the same bias but ridge
has a smaller variance hence a smaller MSE.

#### **Another Case**



• When the true coefficients are sparse, Lasso outperforms ridge regression of having both a smaller bias and a smaller variance.

## Conclusions on Lasso relative to Ridge

- These two examples illustrate that neither ridge regression nor the lasso will universally dominate the other.
- In general, one might expect the lasso to perform better when the response is only related with a relatively small number of predictors.
- As the ridge regression, when the OLS estimates have excessively high variance, the lasso solution can yield a reduction in variance at the expense of a small increase in bias, and consequently can lead to more accurate predictions.
- Unlike ridge regression, the lasso performs variable selection, and hence yields models that are easier to interpret.

# A simple example of the shrinkage effects of ridge and lasso

- Assume that n = p and  $\mathbf{X} = \mathbf{I}_n$ . We force the intercept term  $\beta_0 = 0$ .
- ullet The OLS approach is to find  $eta_1,\ldots,eta_p$  that minimize

$$\sum_{j=1}^{p} (y_j - \beta_j)^2.$$

This gives the OLS estimator

$$\hat{\beta}_j = y_j, \quad \forall j \in \{1, \dots, p\}.$$

#### The ridge estimator

• The ridge regression is to find  $\beta_1, \ldots, \beta_p$  that minimize

$$\sum_{j=1}^{p} (y_j - \beta_j)^2 + \lambda \sum_{j=1}^{p} \beta_j^2.$$

This leads to the ridge estimator

$$\hat{\beta}_j^R = \frac{y_j}{1+\lambda}, \quad \forall j \in \{1, \dots, p\}.$$

Since  $\lambda \ge 0$ , the magnitude of each estimated coefficient is shrinked toward 0.

#### The lasso estimator

• The lasso is to find  $\beta_1, \ldots, \beta_p$  that minimize

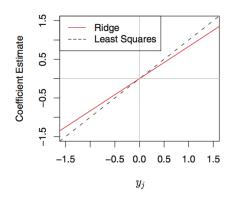
$$\sum_{j=1}^p (y_j-\beta_j)^2 + \lambda \sum_{j=1}^p |\beta_j|.$$

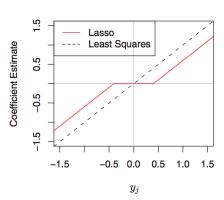
This gives estimator

$$\hat{\beta}_j^L = \begin{cases} y_j - \lambda/2 & \text{if } y_j > \lambda/2; \\ y_j + \lambda/2 & \text{if } y_j < -\lambda/2; \\ 0 & \text{if } |y_j| \le \lambda/2. \end{cases}$$

The estimated coefficients from Lasso are also shrinked. The above shrinkage is known as the **soft-thresholding**.

# An illustrative figure

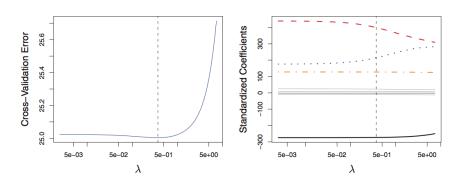




## Selecting the Tuning Parameter

- Similar as the subset selection, for ridge and lasso, we require a systematic way of choosing the best model under a sequence of fitted models (from different choices of  $\lambda$ )
- Equivalently, we require a method to select the optimal value of the tuning parameter  $\lambda$  or equivalently, the value of the constraint s.
- Cross-validation provides a simple way to tackle this problem. We choose a grid of  $\lambda$ , and compute the cross-validation error rate for each value of  $\lambda$ .
- We then select the value of tuning parameter for which the cross-validation error is smallest.
- Finally, the model is re-fitted by using all of the available observations and the selected value of the tuning parameter.

# Credit Card Data Example



Cross-validation errors that result from applying ridge regression to the Credit data set for various choices of  $\lambda$ .

## More choices of penalties

- There are many other penalties in addition to the  $\ell_2$  and  $\ell_1$  norms used by ridge and lasso.
  - the elastic net:

$$\underset{\beta}{\operatorname{argmin}} \ \|\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\|_{2}^{2} + \lambda \left[ (1 - \alpha) \|\boldsymbol{\beta}\|_{1} + \alpha \|\boldsymbol{\beta}\|_{2} \right]$$

for some tuning parameters  $\lambda \ge 0$  and  $\alpha \in [0,1]$ . Ridge corresponds to  $\alpha = 1$  while lasso corresponds to  $\alpha = 0$ .

#### The group lasso

▶ If we suspect the model is nonlinear in  $X_1$  or  $X_2$ , we can add quadratic terms, say

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_1^2 + \beta_3 X_2 + \beta_4 X_2^2 + \epsilon.$$

The group lasso estimator minimizes

$$RSS + \lambda \left( \sqrt{\beta_1^2 + \beta_2^2} + \sqrt{\beta_3^2 + \beta_4^2} \right).$$

In this penalty, we view  $\beta_1$  and  $\beta_2$  (coefficient of  $X_1$  and  $X_1^2$ ) as if they belong to the same group. The group Lasso can shrink the parameters in the same group (both  $\beta_1$  and  $\beta_2$ ) exactly to 0 simultaneously.

▶ There are a lot more penalties out there ......

#### Regularization in more general settings

- The ridge and lasso regressions are not restricted to the linear models.
- The idea of penalization is generally applicable to almost all parametric models.

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \ \underline{L(\boldsymbol{\beta}, \boldsymbol{\mathcal{D}}^{train}) + Pen(\boldsymbol{\beta})}_{g(\boldsymbol{\beta}; \boldsymbol{\mathcal{D}}^{train})}.$$

- ▶ OLS:  $L(\beta, \mathcal{D}^{train}) = ||\mathbf{y} \mathbf{X}\beta||_2^2$ ,  $Pen(\beta) = 0$ .
- Ridge:  $L(\beta, \mathcal{D}^{train}) = \|\mathbf{y} \mathbf{X}\beta\|_2^2$ ,  $Pen(\beta) = \|\beta\|_2^2$ .

  Lasso:  $L(\beta, \mathcal{D}^{train}) = \|\mathbf{y} \mathbf{X}\beta\|_2^2$ ,  $Pen(\beta) = \|\beta\|_1$ .
- ▶ In general,
  - L can be any loss function, i.e. negative likelihood, 0-1 loss.
  - Pen could be any penalty function.

# Moving Beyond Linearity

The linearity assumption in the feature space is almost always an approximation, and sometimes a poor one.

We consider the following extensions to relax the linearity assumption.

- Univariate case (p = 1):
  - Polynomial regression
  - Step functions
  - Regression splines
- Multivariate case (p > 1):
  - Local regression
  - Generalized additive models

#### Polynomial Regression

• The polynomial regression

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \dots + \beta_d x_i^d + \epsilon_i,$$

where  $\epsilon_i$  is the error term and  $x_i \in \mathbb{R}$ .

- Can be fitted by the OLS approach.
- Coefficients themselves are not interpretable; we are more interested in the trend of the fitted function

$$\hat{f}(x_0) = \hat{\beta}_0 + \hat{\beta}_1 x_0 + \hat{\beta}_2 x_0^2 + \dots + \hat{\beta}_d x_0^d.$$

• The degree *d* in practice is typically no greater than 4, and can be chosen via cross-validation.

#### Polynomial Regression

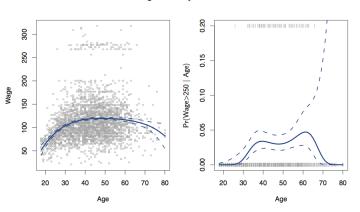
- The polynomial regression can be used for classification as well.
  - ▶ For instance, in the logistic regression,

logit (
$$\mathbb{P}(Y_i = 1 \mid X_i = x_i)$$
) =  $\beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \dots + \beta_d x_i^d$ .

- ▶ Can be fit by maximizing the likelihood.
- However, polynomials have notorious tail behavior very bad for extrapolation.

## The Wage Data

#### Degree-4 Polynomial



Left: The solid blue curve is a degree-4 polynomial of wage as a function of age, fit by the OLS. The dotted curves are estimated 95 % confidence intervals. Right: We model the binary event  $1\{wage > 250\}$  using logistic regression, with a

degree-4 polynomial.

#### Step Functions

- The polynomial regression imposes a global structure on the non-linearity of X.
- The **step function** approach avoids such a global structure by breaking the range of *X* into bins.
- For pre-specified K cut points  $c_1, \ldots, c_K$ , define

$$C_0(X) = 1\{X < c_1\},$$

$$C_1(X) = 1\{c_1 \le X < c_2\},$$

$$\vdots$$

$$C_K(X) = 1\{c_K \le X\}.$$

 $C_0(X), \ldots, C_K(X)$  are in fact (K+1) dummy variables, and they sum up to 1.

#### Step Functions

• Step function approach assumes

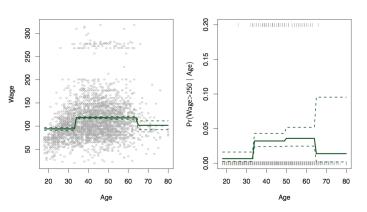
$$y_i = \beta_0 + \beta_1 C_1(x_i) + \beta_2 C_2(x_i) + ... + \beta_K C_K(x_i) + \epsilon_i$$

where  $\epsilon_i$  is the error term. (Note we don't need  $C_0(x_i)$  in the model when we also have the intercept term  $\beta_0$ .)

- Can be fitted by the OLS.
- $\beta_j$  represents the average change in the response Y for  $c_j \le X < c_{j+1}$  relative to  $X < c_1$ .

#### The Wage Data

#### Piecewise Constant



Left: The solid blue curve is a step function of wage as a function of age, fit by least squares. The dotted curves indicate an estimated 95 % confidence interval. Right: We model the binary event wage>250 using logistic regression, with the step function.

#### Pros and Cons of Step Function

- The step function approach is widely used in biostatistics and epidemiology among other areas, because the model is easy to fit and the regression coefficient has a natural interpretation.
- However, piecewise-constant functions can miss the trend of the true relationship between Y and X. The choice of cut points can be difficult to specify.
- How about combining polynomial and step function?

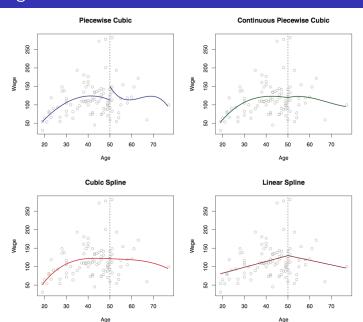
#### Piecewise Polynomials

• Instead of a single polynomial in *X* over its whole domain, we can use different polynomials in different regions:

$$y_i = \begin{cases} \beta_{01} + \beta_{11} x_i + \beta_{21} x_i^2 + \beta_{31} x_i^3 + \epsilon_i & \text{if } x_i < c; \\ \beta_{02} + \beta_{12} x_i + \beta_{22} x_i^2 + \beta_{32} x_i^3 + \epsilon_i & \text{if } x_i \ge c. \end{cases}$$

- The cut point c is called knot. Using more knots leads to a more flexible piecewise polynomial.
- In general, if we place K different knots throughout the range of X, then we will end up fitting (K+1) different cubic polynomials.

#### The Wage Data



#### Regression splines

- Better to add constraints to polynomials at the knots for:
  - continuity: equal function values
  - smoothness: equal first and second order derivatives
  - higher order derivatives
- The constrained polynomials are called **splines**. A degree-d spline contains piecewise degree-d polynomials, with continuity in derivatives up to degree (d-1) at each knot.
- How can we construct the degree-d spline?

#### Linear Splines

• A linear spline has piecewise linear functions continuous at each knot. That is, with knots at  $\xi_1 < \xi_2 < \cdots < \xi_K$ ,

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 (x_i - \xi_1)_+ \cdots + \beta_{K+1} (x_i - \xi_K)_+ + \epsilon_i$$

where

$$(x_i - \xi_k)_+ = \begin{cases} x_i - \xi_k & \text{if } x_i > \xi_k \\ 0 & \text{otherwise} \end{cases}.$$

A basis representation:

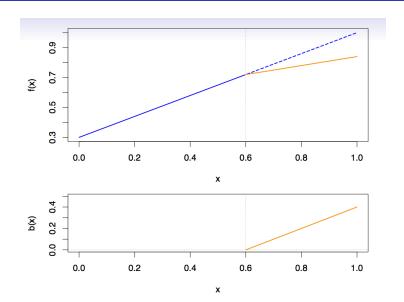
$$y_i = \beta_0 + \beta_1 b_1(x_i) + \beta_2 b_2(x_i) + \dots + \beta_{K+1} b_{K+1}(x_i) + \epsilon_i,$$

where  $b_k$  are basis functions

$$b_1(x_i) = x_i, \quad b_{k+1}(x_i) = (x_i - \xi_k)_+, \quad k = 1, \dots, K,$$

• Interpretation of  $\beta_1$ : the averaged increase of Y associated with one unit of X for  $X < \xi_1$ .

# Linear Splines



## **Cubic Splines**

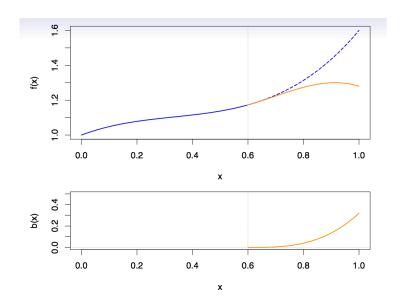
• A cubic spline has piecewise cubic polynomials with continuous derivatives up to order 2 at each knot. That is, with K knots at  $\xi_1 < \xi_2 < \cdots < \xi_K$ ,

$$y_i = \beta_0 + \beta_1 b_1(x_i) + \beta_2 b_2(x_i) + \dots + \beta_{K+3} b_{K+3}(x_i) + \epsilon_i,$$

where  $b_k$  are basis functions

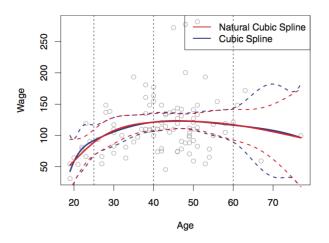
$$b_1(x_i) = x_i,$$
  $b_2(x_i) = x_i^2,$   $b_3(x_i) = x_i^3,$   
 $b_{k+3}(x_i) = (x_i - \xi_k)_+^3,$   $k = 1, ..., K.$ 

# **Cubic Splines**



#### Natural Splines

A natural spline is a regression spline with additional boundary constraints: the function is required to be linear at the boundary.



#### More on splines

- Choosing the number and locations of the knots
  - ▶ Typically, we place K knots at certain quantiles of the data or place on the range of X with equal space. Oftentimes, the placement of knots is not very crucial.
  - We use cross-validation to choose K.
- Polynomial regressions and step functions are special cases of splines.
- Another variant: smoothing spline (ISLR 7.5).

#### **Local Regression**

**Local regression** predicts at a target point  $x_0$  using only the nearby training observations.

#### **Algorithm 7.1** Local Regression At $X = x_0$

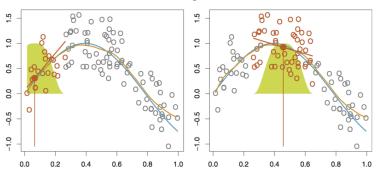
- 1. Gather the fraction s = k/n of training points whose  $x_i$  are closest to  $x_0$ .
- 2. Assign a weight  $K_{i0} = K(x_i, x_0)$  to each point in this neighborhood, so that the point furthest from  $x_0$  has weight zero, and the closest has the highest weight. All but these k nearest neighbors get weight zero.
- 3. Fit a weighted least squares regression of the  $y_i$  on the  $x_i$  using the aforementioned weights, by finding  $\hat{\beta}_0$  and  $\hat{\beta}_1$  that minimize

$$\sum_{i=1}^{n} K_{i0} (y_i - \beta_0 - \beta_1 x_i)^2.$$
 (7.14)

4. The fitted value at  $x_0$  is given by  $\hat{f}(x_0) = \hat{\beta}_0 + \hat{\beta}_1 x_0$ .

#### Simulated Example

#### **Local Regression**



The blue curve is true f(x), and the light orange curve is the local regression  $\hat{f}(x)$ . The orange points are local to the target point  $x_0$ , represented by the orange vertical line. The yellow bell-shape indicates weights assigned to each point. The fit  $\hat{f}(x_0)$  at  $x_0$  is obtained by fitting a weighted linear regression (orange line segment), and using the fitted value at  $x_0$  (orange solid dot) as the estimate  $\hat{f}(x_0)$ .

#### **Local Regression**

- The size of the neighborhood (fraction s of training data) is a tuning parameter, which can be chosen by cross-validation.
- The weight of each point in the neighborhood needs to be specified.
- When we have two dimensional predictors  $X_1$  and  $X_2$ , we can simply use 2-dimensional neighborhoods, and fit bivariate linear regression models using the observations that are near each target point in 2-dimensional space.
- However, local regression can perform poorly if *p* is much larger than about 3 or 4 (the curse of dimensionality).
- k-Nearest Neighbour is one of the most common local regression approaches. It corresponds to  $K(x_i, x_0) = \frac{1}{k}$  and  $\beta_1 = 0$ .

#### Generalized Additive Models

 Generalized additive models (GAMs) provide a general framework for extending a standard linear model by allowing non-linear functions of each of the variables, while maintaining additivity,

$$y_i = \beta_0 + f_1(x_{i1}) + f_2(x_{i2}) + \dots + f_p(x_{ip}) + \epsilon_i.$$

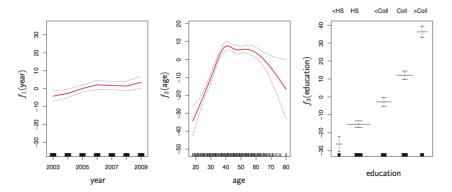
- Each  $f_k$  can be linear, polynomials, step function, splines and local regression.
- Can be applied to classification problems.
  - Logistic regression:

logit (
$$\mathbb{P}(Y_i = 1 \mid X_i = x_i)$$
) =  $\beta_0 + f_1(x_{i1}) + f_2(x_{i2}) + \cdots + f_p(x_{ip})$ .

## Wage Data

#### Consider the wage data

wage = 
$$\beta_0 + f_1(\text{year}) + f_2(\text{age}) + f_3(\text{education}) + \epsilon$$
.



The first two functions are natural splines in year and age. The third function is a step function, fit to the qualitative variable education.

#### Pros and Cons of GAMs

- GAMs allow us to fit a non-linear  $f_j$  to each  $X_j$ , so that we can automatically model non-linear relationships that standard linear regression won't be able to capture.
- The non-linear fit can potentially improve prediction accuracy.
- Because the model is additive, we can still examine the effect of each  $X_i$  on Y individually while holding all of the other variables fixed.
- It avoids the curse of dimensionality by assuming additivity.
- However, GAMs fail to incorporate the interaction of variables.