



Link Length, mm.	Twist Angle, deg.	Joint Offset, mm.	Joint Angle, deg.
$a_{12} = 0$	$\alpha_{12} = 90$		$\phi_1 = \text{variable}$
$a_{23} = 650$	$\alpha_{23} = 0$	$S_2 = 190$	$\theta_2 = \text{variable}$
$a_{34} = 0$	$\alpha_{34} = 270$	$S_3 = 0$	$\theta_3 = \text{variable}$
$a_{45} = 0$	$\alpha_{45} = 90$	$S_4 = 600$	$\theta_4 = \text{variable}$
$a_{56} = 0$	$\alpha_{56} = 90$	$S_5 = 0$	$\theta_5 = \text{variable}$
		S_6 is a free of choice (125) in picture	$\theta_6 = \text{variable}$