

DSCI 551 Review

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Lecture 1

Basic probability concepts:

In general, the probability of an event A occurring is denoted as $P(A)$ and is defined as

$$P(A) = \frac{\text{Number of times event } A \text{ is observed}}{\text{Total number of events observed}}$$

as the number of events goes to infinity.

- We heavily rely on the “frequency of events” to make estimations of specific parameters of interest in a population or system.
- This is basically the foundation of a frequentist approach: relying on the frequency (or “number”!) of events to estimate your parameters of interest.

Law of total probability: When partitioning the sample space (the set of all possible events), the sum of the probabilities of each event should be one.

$$\sum_{E \in \Omega} P(E) = 1.$$

- In general, for a given event A , the law implies that

$$1 = P(A) + P(A^c).$$

Inclusion-exclusion principle:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B),$$

$$P(A \cup B \cup C) = P(A) + P(B) + P(C) - P(A \cap B) - P(B \cap C) - P(A \cap C) + P(A \cap B \cap C),$$

etc.

Odds: are quite helpful in comparing the probability of two events.

$$o = \frac{p}{1-p},$$

where p is the probability of an event.

- This implies

$$p = \frac{o}{o+1}.$$

Measures of central tendency and uncertainty:

Central tendency: a measure denoting a “typical” value in a random variable.

Uncertainty: a measure of how “spread” a random variable is

- Called **parameters** when it comes to a population
- Are estimated via **sample statistics**

Mode: the outcome having the highest probability.

Entropy: a measure of uncertainty defined by

$$H(X) = \sum_x P(X = x) \ln \left(\frac{1}{P(X = x)} \right)$$

or

$$H(X) = \int_x f_X(x) \ln \left(\frac{1}{f_X(x)} \right) dx.$$

- Always non-negative in the discrete case
- $H(X) = 0 \iff X$ is constant in the discrete case.

Expectation:

$$\mathbb{E}(X) = \sum_x x \cdot P(X = x).$$

or

$$\mathbb{E}(X) = \int_x x \cdot f_X(x)$$

- Can usually be estimated via the **sample mean**

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

Variance:

$$\text{Var}(X) = \mathbb{E}\{[X - \mathbb{E}(X)]^2\}.$$

$$\implies \text{Var}(X) = \mathbb{E}(X^2) - [\mathbb{E}(X)]^2.$$

- the variance is an expectation (specifically, the squared deviation from the mean)
- can usually be estimated via the **sample variance**

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$$

- Always non-negative, and $\text{Var}(X) = 0 \iff X$ is constant

Standard deviation: The square root of the variance,

$$\sigma_x = \sqrt{\text{Var}(X)}.$$

Lecture 2

- To maximize entropy, you need equal probabilities for all the outcomes in the sample space. This indicates we have a uniform uncertainty over the whole range of possible outcomes.
- Helpful univariate distribution guide: <http://www.math.wm.edu/~leemis/chart/UDR/UDR.html>

Binomial distribution:

$$X \sim \text{Binomial}(n, \pi)$$

- X is the number of successes in n trials in which each trial has probability π of success, independent of all other trials.
- PMF:

$$P(X = x \mid n, \pi) = \binom{n}{x} \pi^x (1 - \pi)^{n-x} \quad \text{for } x = 0, 1, \dots, n.$$

- Expected value:

$$\mathbb{E}(X) = n\pi$$

- Variance:

$$\text{Var}(X) = n\pi(1 - \pi)$$

Families and Parameters:

- We refer to the entire set of Binomial probability distributions as the **Binomial family of distributions**.
- Specifying a value for both π and n results in a unique Binomial distribution.
- Since π and n fully specify a Binomial distribution, we call them **parameters** of the Binomial family, and we call the Binomial family a **parametric family** of distributions.
- There are other ways we can specify the distribution. For instance, specifying the mean and variance is enough to identify a Binomial distribution.
- Exactly which variables we decide to use to identify a distribution within a family is called the family's parameterization.
- The parameterization you use in practice will depend on the information you can more easily obtain

Geometric distribution:

$$X \sim \text{Geometric}(\pi)$$

X is the number of trials **before** experiencing a success, where each trial has probability π of success, independent of all other trials.

- PMF:

$$P(X = x \mid \pi) = \pi(1 - \pi)^x \quad \text{for } x = 0, 1, \dots$$

- Since there is only one parameter, this means that if you know the mean, you also know the variance!
- Expected value:

$$\mathbb{E}(X) = \frac{1 - \pi}{\pi}$$

- Variance:

$$\text{Var}(X) = \frac{1 - \pi}{\pi^2}$$

Negative Binomial Distribution:

$$X \sim \text{Negative Binomial}(k, \pi)$$

- X is the number of failed trials before experiencing k successes, where each trial has probability π of success, independent of all other trials. - PMF:

$$P(X = x | k, \pi) = \binom{k-1+x}{x} \pi^k (1-\pi)^x \quad \text{for } x = 0, 1, \dots$$

- The Geometric family results with $k = 1$.
- Expected value:

$$\mathbb{E}(X) = \frac{k(1-\pi)}{\pi}.$$

- Variance:

$$\text{Var}(X) = \frac{k(1-\pi)}{\pi^2}.$$

Poisson Distribution:

$$X \sim \text{Poisson}(\lambda)$$

- X is number of events occurring in a fixed interval of time or space, assuming that these events occur with a known constant mean rate (e.g. 3 events per minute or 5 events per meter) and independently of the time since the last event
- PMF

$$P(X = x | \lambda) = \frac{\lambda^x \exp(-\lambda)}{x!} \quad \text{for } x = 0, 1, \dots$$

- Expected value:

$$\mathbb{E}(X) = \lambda.$$

- Variance:

$$\text{Var}(X) = \lambda.$$

Bernoulli Distribution:

$$X \sim \text{Bernoulli}(\pi)$$

- X is equal to one with probability π and equal to zero with probability $1 - \pi$.
- Basically a weighted coin-flip
- A special case of the Binomial family ($n = 1$)
- PMF:

$$P(X = x | \pi) = \pi^x (1-\pi)^{1-x} \quad \text{for } x = 0, 1.$$

- Expected value:

$$\mathbb{E}(X) = \pi.$$

- Variance:

$$\text{Var}(X) = \pi(1-\pi).$$

Lecture 3

Joint distributions and marginal distributions:

- A **joint distribution** is the distribution of n -tuples of random variables, where $n \geq 2$.
- The distribution of an individual variable is called the **marginal distribution** (sometimes just “marginal” or “margin”).
- The word “marginal” is not really needed when we are talking about a standalone random variable – there is no difference between the “marginal distribution of X ” and the “distribution of X .” Therefore, we just use the word “marginal” to emphasize that the distribution is being considered in isolation from other related variables in the same process or system.
- Going from the initial marginal distributions to the joint distribution is not a straightforward procedure.
- It requires us to understand the dependency structure among the random variables
- If we assume that all the RVs are independent, then we can just multiply the probabilities from the marginal distributions to find the joint distribution
- If you have a joint distribution, then the marginal distribution of each individual variable follows as a consequence
- Just sum up (discrete) or integrate (continuous), and apply the law of total probability:

$$P(A) = \sum_n P(A \cap B_n),$$

or

$$P(A) = \int_y P(A \cap Y = y).$$

Independence:

- X and Y are **independent** if

$$P(X = x \cap Y = y) = P(X = x) \cdot P(Y = y) \quad \forall_{x,y}$$

- Equivalently:

$$P(X = x \mid Y = y) = P(X = x) \quad \forall_{x,y}$$

- In other words: X and Y are independent if knowing something about one of them tells us nothing about the other.

Dependence Measures:

Covariance:

$$\text{Cov}(X, Y) = \mathbb{E}[(X - \mu_X)(Y - \mu_Y)],$$

where $\mu_X = \mathbb{E}(X)$ and $\mu_Y = \mathbb{E}(Y)$.

$$\implies \text{Cov}(X, Y) = \mathbb{E}(XY) - \mathbb{E}(X)\mathbb{E}(Y).$$

- Note that

$$\mathbb{E}(XY) = \mathbb{E}(X)\mathbb{E}(Y) \iff \text{Cov}(X, Y) = 0,$$

- Also if X and Y are independent then $\text{Cov}(X, Y) = 0$.
- But the reverse implication does **not** hold in general!
- Zero covariance simply indicates that there is no **linear** trend

Pearson's correlation:

- $\text{Cov}(X, Y)$ is dependent on the scale of X and Y .
- e.g. $\text{Cov}(10X, Y) = 10 \text{Cov}(X, Y)$.
- Pearson's Correlation standardizes the scale according to the standard deviations of X and Y :

$$\begin{aligned}\text{Corr}(X, Y) &= \mathbb{E} \left[\left(\frac{X - \mu_X}{\sigma_X} \right) \left(\frac{Y - \mu_Y}{\sigma_Y} \right) \right] \\ &= \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X) \text{Var}(Y)}}.\end{aligned}$$

- Can show that $-1 \leq \text{Corr}(X, Y) \leq 1$ using the Cauchy-Schwarz inequality
- a value of -1 implies a perfect negative linear relationship
- a value of 0 implies no linear relationship (not necessarily independent tho)
- a value of 1 implies a perfect linear relationship

Kendall's τ_K :

- Another measure of correlation
- Measures **monotonic** dependence instead of linear dependence
- Used on samples of observations, not on entire known distributions
- Measures concordance between each pair of observation (x_i, y_i) and (x_j, y_j) with $i \neq j$.
- Concordant means

$$\begin{aligned}x_i < x_j \quad \text{and} \quad y_i < y_j, \\ \text{or} \\ x_i > x_j \quad \text{and} \quad y_i > y_j;\end{aligned}$$

- Discordant means

$$\begin{aligned}x_i < x_j \quad \text{and} \quad y_i > y_j, \\ \text{or} \\ x_i > x_j \quad \text{and} \quad y_i < y_j;\end{aligned}$$

- The formal definition is then

$$\tau_K = \frac{\text{Number of concordant pairs} - \text{Number of discordant pairs}}{\binom{n}{2}},$$

where n is the sample size.