

EXERCISE SET 9

Numerical Methods for Hyperbolic Partial Differential Equations

IMATH, FS-2020

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Problem 9.1 E-schemes (2pts)

Consider a consistent monotone 3-point numerical flux $f^{num}(u, v)$. The scheme given by this flux is said to be an *E-scheme* if it satisfies

$$(u_{j+1} - u_j)(f^{num}(u_j, u_{j+1}) - f(u)) \leq 0 \quad \forall u \in [u_j, u_{j+1}] \text{ or } \forall u \in [u_{j+1}, u_j], \quad (1)$$

according to the sign of $(u_{j+1} - u_j)$.

1. Prove that a 3-point monotone scheme is an E-scheme.

Solution

Let us rewrite the definition of E-scheme more explicitly. A numerical flux generates an E-scheme if

$$\begin{cases} f^{num}(u_j, u_{j+1}) \leq f(u) & \forall u_j \leq u \leq u_{j+1}, \\ f^{num}(u_j, u_{j+1}) \geq f(u) & \forall u_{j+1} \leq u \leq u_j. \end{cases} \quad (2)$$

Consider a monotone scheme $f^{num}(u, v)$, i.e., $u \mapsto f^{num}(u, v)$ is monotone non decreasing and $v \mapsto f^{num}(u, v)$ is monotone non increasing. We have

$$\begin{cases} f^{num}(u_j, u_{j+1}) \leq f^{num}(u, u_{j+1}) \leq f^{num}(u, u) = f(u) & \text{if } u_j \leq u \leq u_{j+1} \\ f^{num}(u_j, u_{j+1}) \geq f^{num}(u, u_{j+1}) \geq f^{num}(u, u) = f(u) & \text{if } u_{j+1} \leq u \leq u_j. \end{cases} \quad (3)$$

Hence, the scheme is an E-scheme.

2. Consider the Godunov flux

$$f_G^{num}(u, v) := \begin{cases} \min_{u_j \leq u \leq u_{j+1}} f(u) & u_j \leq u_{j+1}, \\ \max_{u_{j+1} \leq u \leq u_j} f(u) & u_{j+1} \leq u_j. \end{cases} \quad (4)$$

Prove that every monotone 3-point scheme with numerical flux f^{num} under $\text{CFL} \leq 1$ verifies

$$\begin{cases} f^{num}(u_j, u_{j+1}) \leq f_G^{num}(u_j, u_{j+1}) & \text{if } u_j \leq u_{j+1}, \\ f^{num}(u_j, u_{j+1}) \geq f_G^{num}(u_j, u_{j+1}) & \text{if } u_{j+1} \leq u_j. \end{cases} \quad (5)$$

Solution

In case $u_j \leq u_{j+1}$, we know for any $u \in [u_j, u_{j+1}]$ that $f^{num}(u_j, u_{j+1}) \leq f(u)$ so, it is also true that

$$f^{num}(u_j, u_{j+1}) \leq \min_{u_j \leq u \leq u_{j+1}} f(u) = f_G^{num}(u_j, u_{j+1}). \quad (6)$$

In case $u_j \geq u_{j+1}$, we know for any $u \in [u_{j+1}, u_j]$ that $f^{num}(u_j, u_{j+1}) \geq f(u)$ so, it is also true that

$$f^{num}(u_j, u_{j+1}) \geq \max_{u_{j+1} \leq u \leq u_j} f(u) = f_G^{num}(u_j, u_{j+1}). \quad (7)$$

Problem 9.2 Lax Wendroff (3 pts)

Code the two step Lax Wendroff scheme, where

$$\begin{cases} u_j^{n+1} = u_j^n - \lambda \left(f(u_{j+1/2}^{n+1/2}) - f(u_{j-1/2}^{n+1/2}) \right), \\ u_{j+1/2}^{n+1/2} = \frac{u_j + u_{j+1}}{2} - \frac{\lambda}{2} \left(f(u_{j+1}^n) - f(u_j^n) \right). \end{cases} \quad (8)$$

1. Write it in the conservation formulation.

Solution

We can write the scheme as

$$u_j^{n+1} = u_j^n - \lambda (F_{j+1/2}^n - F_{j-1/2}^n) \quad (9)$$

with

$$F_{j+1/2}^n = f \left(\frac{u_j + u_{j+1}}{2} - \frac{\lambda}{2} (f(u_{j+1}^n) - f(u_j^n)) \right). \quad (10)$$

2. Code it in the usual code (check solution of Exercise Set 8).
3. Compare it with the classical Lax Wendroff scheme: check the accuracy order and the computational times:

For $N \in \{2^k : k = 1, \dots, 10\}$ number of cells solve the advection equation $u_t + u_x = 0$ with $u_0(x) = \cos(\pi x)$ on $[-2, 2]$ with periodic boundary conditions. Compute the \mathbb{L}^2 error with respect the exact solution for both schemes and all N and the time needed to solve the scheme (see `tic`, `toc` in Matlab and package `time` in Python). Plot the error wrt N in an appropriate scale and the time and N in an appropriate scale. What can you say on the error? And on the time?

Solution

```
1 function [fNum] = numericalFlux(scheme, f, u, v, extra)
% encode in this function different numerical fluxes
3 switch scheme
    case "Lax Friedrichs"
5         % extra should be lambda=dt/dx
        lam=extra{1};
7         fNum=(f(u)+f(v))/2-(v-u)/lam/2;
    case "Lax Wendroff"
```

```

9      % extra should be lambda=dt/dx
      lam=extra{1};
11     df=extra{2};
      idxn= u==v;
13     idx=logical(1-idxn);
      a=zeros(size(u));
15     a(idx)=(f(u(idx))-f(v(idx)))/(u(idx)-v(idx));
      fNum=(f(u)+f(v))/2-lam/2*a.*(f(v)-f(u));
17     case "2stepLxW"
      % extra should be lambda=dt/dx
19     lam=extra{1};
      fNum=f(0.5*(u+v) -lam/2*(f(v)-f(u)));
21     case "Rusanov"
      % extra should be f'
23     df=extra{1};
      fNum=(f(u)+f(v))/2-max(abs(df(u)),abs(df(v)))*(v-u)/2;
25     case "Godunov"
      % extra should be omega the unique local minimum of f
27     omega=extra{1}*ones(size(u));
      fNum=max(f(max(u,omega)),f(min(v,omega)));
29     case "Roe"
      % extra should be empty
31     idxs=u==v;
      idx=logical(1-idxs);
33     fNum=f(u);
      A=(f(u(idx))-f(v(idx)))/(u(idx)-v(idx));
35     fNum(idx)=f(u(idx)).*(A>=0)+f(v(idx)).*(A<0);
      case "EO" %Engquist—Osher
37     % extra should be omega the unique local minimum of f
      omega=extra{1}*ones(size(u));
39     fNum=f(max(u,omega))+ f(min(v,omega));
end
41
43 end

```

Listing 1: NumericalFlux.m

```

%% Convergence
2 model.f=@(u) u;
  model.df=@(u) ones(size(u));
4 model.T=1;
  model.a=-2;
6 model.b=2;
  model.u0=@(x) 1+ 0.2*cos(pi*x);% (x<1).*(x>0); % (x<1).*(x>0);%0.2*cos(pi*x);% uL*(x<0)+
  uR*(x>=0); %cos(pi*x);%cos(pi*x);
8 model.BC="periodic";%"dirichlet";%"periodic";
  model.exact=@(x,t) model.u0(x-t);
10
  model.entropy=@(x) abs(x);
12
  solver.Nx = 100;
14 solver.CFL = 0.7;
16
18 schemes=["Lax Friedrichs";"Rusanov";"Godunov";"Roe";"EO";"Lax Wendroff";"2stepLxW"];

```

```

styles=["-","*-","+-","x-",".:",".-","+"]
20 nn=6;
Ns=2.^[1:nn];
22
clear u x t ent errors times
24
for k=1:length(schemes)
26     solver.scheme=schemes(k);
    for n=1:nn
28         solver.Nx=Ns(n);
        tic
30         [u,x,t,ent]= runScheme(model, solver);
        times(k,n)=toc;
32         errors(k,n)=computeError(u,x,t,model);
    end
34 end

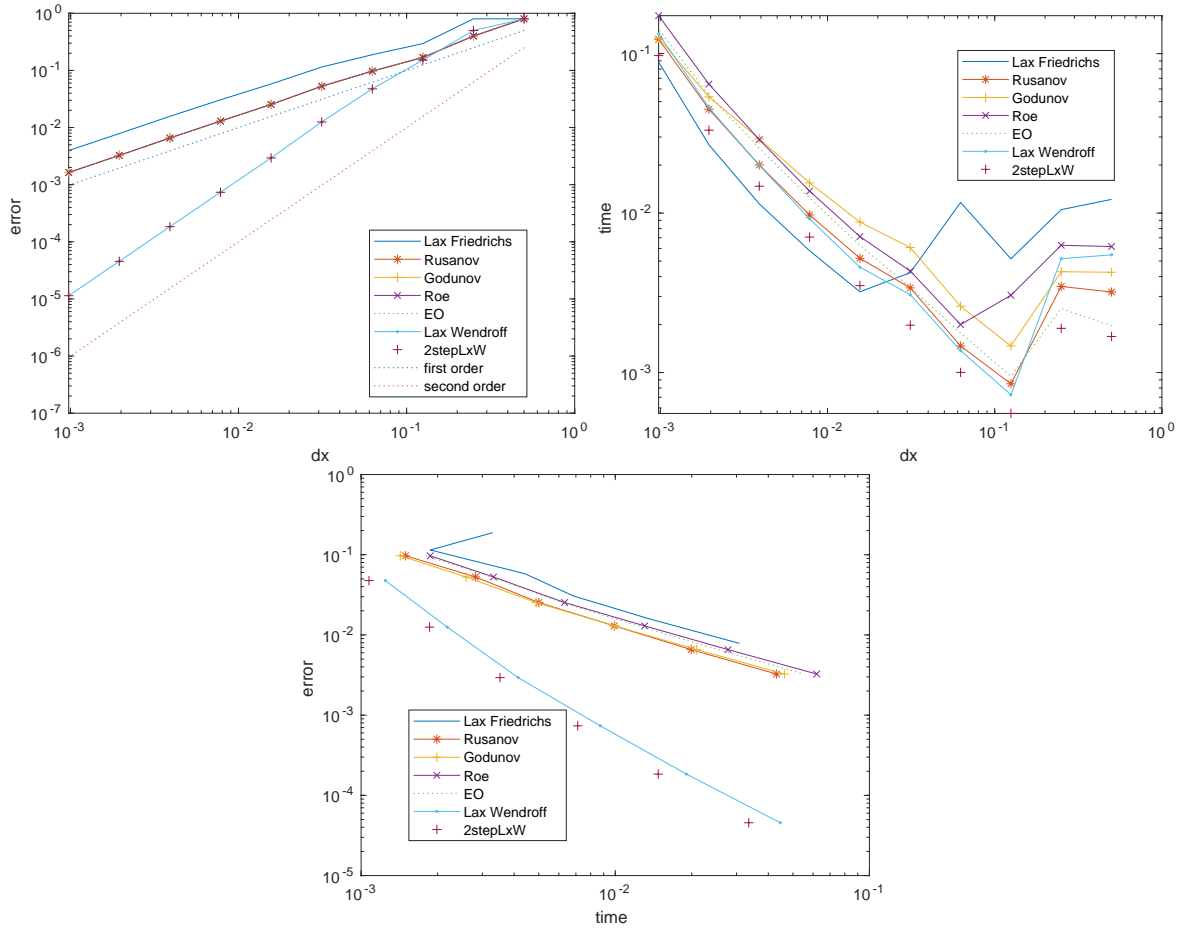
36 fig=figure()
for k=1:length(schemes)
38     scheme=schemes(k);
    loglog(1./Ns,errors(k,:),styles(k),'DisplayName',scheme)
40     hold on
end
42 loglog(1./Ns,1./Ns,':','DisplayName','first order')
loglog(1./Ns,1./Ns.^2,':','DisplayName','second order')
44 legend('Location','best')
xlabel('dx')
46 ylabel('error')
saveas(fig,'errorLxW.pdf')
48

fig=figure()
50 for k=1:length(schemes)
    scheme=schemes(k);
52     loglog(1./Ns,times(k,:),styles(k),'DisplayName',scheme)
    hold on
54 end
legend('Location','best')
56 xlabel('dx')
ylabel('time')
58 saveas(fig,'computationalTimeLxW.pdf')

60 fig=figure()
for k=1:length(schemes)
62     scheme=schemes(k);
    loglog(times(k,:),errors(k,:),styles(k),'DisplayName',scheme)
64     hold on
end
66 legend('Location','best')
ylabel('error')
68 xlabel('time')
saveas(fig,'errorTimeLxW.pdf')
70

72
function err=computeError(u,x,t,model)
74     err=norm(u(end,:)-model.exact(x,t(end)))*sqrt(x(2)-x(1));
end

```



Listing 2: testOrderSpeedLxW.m

We can see that the scheme, being always second order accurate, is also faster than the previous Lax Wendroff scheme.

Problem 9.3 MUSCL (5 pts + 1 extra)

In this problem we code the MUSCL scheme with different choices of *switching function*. The scheme can be summarized in the following steps.

1. Given the solution u_j^n , reconstruct the solution inside the cell $[x_{j-1/2}, x_{j+1/2}]$ as linear function

$$u_j^n(x) = u_j^n + \sigma_j^n(x - x_j), \quad x \in [x_{j-1/2}, x_{j+1/2}]. \quad (11)$$

Define $u_{j,\pm}^n := u_j^n(x_{j\pm 1/2})$.

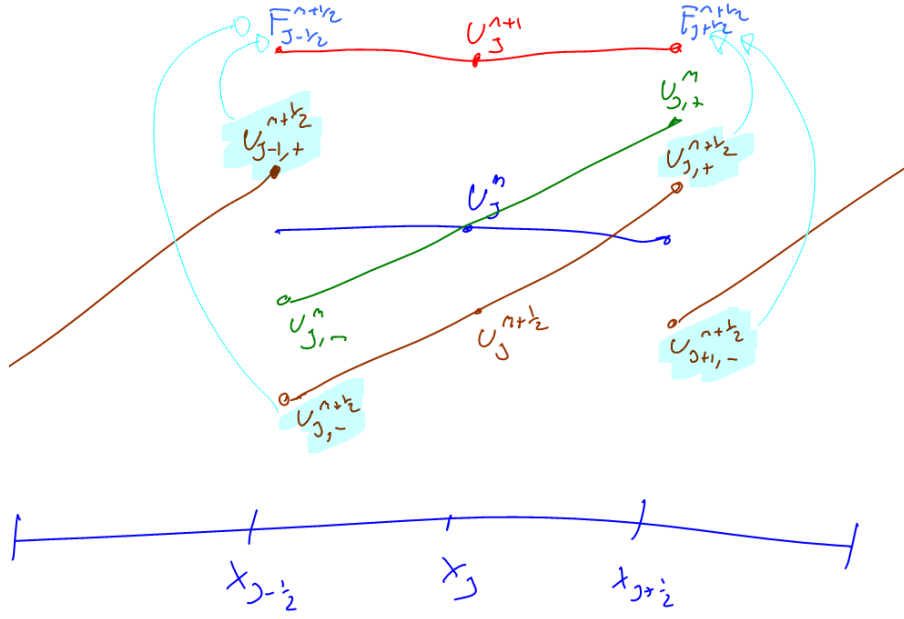


Figure 1: An amazing sketch of the MUSCL scheme. In order blue, green, brown, lightblue, red.

- Using this reconstruction compute an intermediate step at time $t^{n+1/2}$ for the interface values

$$u_{j,\pm}^{n+1/2} = u_{j,\pm}^n - \frac{\lambda}{2} (f(u_{j,+}^n) - f(u_{j,-}^n)). \quad (12)$$

- Apply the numerical flux on the intermediate states

$$u_j^{n+1} = u_j^n - \lambda (F_{j+1/2}^{n+1/2} - F_{j-1/2}^{n+1/2}) \quad (13)$$

where the numerical fluxes are defined as

$$F_{j+1/2}^{n+1/2} = f^{num}(u_{j,+}^{n+1/2}, u_{j+1,-}^{n+1/2}). \quad (14)$$

Check figure 1 for an idea of the steps of the scheme.

The left choice to define this scheme are the way we define the slope σ_j^n , and it will depend on u_{j-1}, u_j, u_{j+1} and the numerical fluxes f^{num} .

The slope can be defined in a general way as

$$\sigma_j^n(u_{j-1}^n, u_j^n, u_{j+1}^n) = \frac{u_{j+1}^n - u_j^n}{\Delta x} \phi(r_j^n), \quad r_j^n := \frac{u_j^n - u_{j-1}^n}{u_{j+1}^n - u_j^n}. \quad (15)$$

Here, follows some possible choices for the *switching* function.

Name	Switching function $\phi(r)$
Upwind	0
Lax-Wendroff	1
Beam-Warming	r
Minmod	$\minmod(1, r)$
Superbee	$\max(0, \min(1, 2r), \min(2, r))$
MC	$\max(0, \min(\frac{1+r}{2}, 2, 2r))$
van Leer	$\frac{r+ r }{1+ r }$

Table 1: The most popular flux limiters.

Note that

$$\minmod(a, b) = \begin{cases} \text{sign}(a) \min(|a|, |b|) & \text{if } ab \geq 0, \\ 0 & \text{else.} \end{cases} \quad (16)$$

1. Which condition should the switching function and the numerical flux f^{num} verify in order to have a TVD and second order scheme on linear advection problems?

Solution

On linear advection problems if we use a monotone numerical flux and the switching function is such that

$$0 \leq \frac{\phi(r)}{r}, \phi(r) \leq 2,$$

then the scheme is TVD, and it if also fulfills

$$\phi(r) = \alpha + (1 - \alpha)r, \quad \alpha \in [0, 1]$$

then the scheme is second order.

2. Code a function **switchingFunctions**, which code all the functions contained in Table 1 (inputs: a string with the name of the function and r , output the value of the function evaluated in r). In another script, plot all the functions in one figure on the interval $[0, 5]$. Which of the functions does not verify the TVD conditions and which one does not verify the second order condition?

Solution

```

1 function sigma=switchingFunction(r, solver)
2 switch solver.limiter
3     case "vanLeer"
4         sigma= (r+abs(r))./(1+abs(r));
5     case "upwind"
6         sigma=zeros(size(r));
7     case "Lax Wendroff"
8         sigma=ones(size(r));
9     case "Beam Warming"
10        sigma=r;
11    case "minmod"
```

```

13     sigma=minmod(ones(size(r)),r);
14     case "Superbee"
15         sigma=max(zeros(size(r)),min(ones(size(r)),2*r));
16         sigma=max(sigma,min(2*ones(size(r)),r));
17     case "MC"
18         sigma=min((1+r)/2,2*ones(size(r)));
19         sigma=min(sigma,2*r);
20         sigma=max(sigma,zeros(size(r)));
21 end
22 end
23 function c=minmod(x,y)
24     c= (sign(x)+sign(y))/2.*min(abs(x),abs(y));
25 end

```

Listing 3: switchingFunction.m

```

1  limiters=[ "minmod", "vanLeer","upwind","Lax Wendroff", "Beam Warming","Superbee","MC"];
2  xx=linspace(0,5,101);
3  fig=figure();
4  styles=["*-","+-","x-","-",":",".-","+"];
5  for k=1:length(limiters)
6      solver.limiter=limiters(k);
7      yy=switchingFunction(xx,solver);
8      plot(xx,yy,styles(k),'DisplayName',limiters(k))
9      hold on
10 end
11 title('Switching functions')
12 legend('Location','best')
13 saveas(fig,'switchingFunctions.pdf')
14 system('pdfcrop switchingFunctions.pdf')

```

Listing 4: testSwitchingFunctions.m

We clearly see in figure 2 that the upwind function does not verify the second order condition and the Beam Warming and Lax Wendroff do not verify the TVD condition, while the other functions verify all the properties.

3. Code the MUSCL scheme as presented above, making use of the old function for numerical fluxes and of the `switchingFunctions`.

Hint: build a function `computeSlope`, which compute the slopes of the intervals, check that the reconstruction that you obtain is TVD (a simple linear advection problem with few Ns is enough to check it).

Solution

```

1 function [u,x,t,ent] = runMUSCL(model, solver, varargin)
2 if nargin<3
3     withplot=0;
4 else
5     withplot=varargin{1};
6 end
7 N=solver.Nx;

```

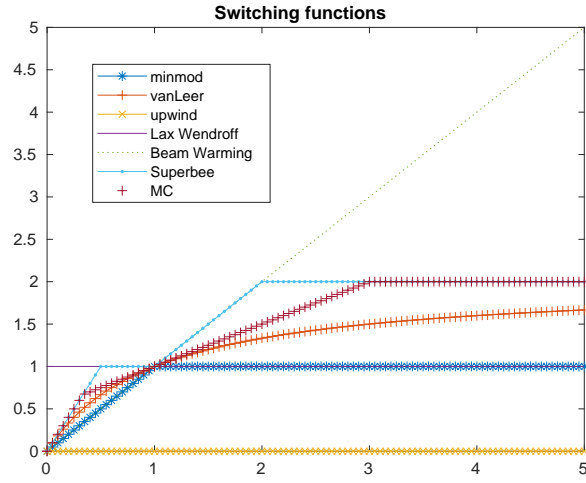



Figure 2: Switching Functions

```

x=linspace(model.a,model.b,solver.Nx+1);
9 dx=x(2)-x(1);
maxdfu=max(abs(model.df(model.u0(x))));
11 dt=dx*solver.CFL/maxdfu;
Nt=ceil(model.T/dt);
13 dt=model.T/Nt;
t=linspace(0,model.T,Nt+1);
15 %u(j,n+1)=H(u(j-1,n),u(j,n),u(j+1,n))
if model.BC=="periodic"
17     j=1:N;
    jR=[2:N,1];
19     jL=[N,1:N-1];
    u=zeros(Nt+1,N);
21     ent=zeros(Nt+1,N);
    x=x(j);
23 elseif model.BC=="dirichlet"
    j=[2:N];
25     jL=[1:N-1];
    jR=[3:N+1];
27     x=x(1:N+1);
    u=zeros(Nt+1,N+1);
29     ent=zeros(Nt+1,N+1);
    u(:,1)=model.u0(x(1));
31     u(:,N+1)=model.u0(x(N+1));
elseif model.BC=="neumann"
33     j=[1:N+1];
    jL=[1,1:N];
35     jR=[2:N+1,N+1];
    x=x(1:N+1);
37     u=zeros(Nt+1,N+1);
    ent=zeros(Nt+1,N+1);
39 end
41 u(1,:)=model.u0(x);

```

```

ent(1,:)=model.entropy(u(1,:));
43 extra=defineExtraScheme(solver.scheme,dt/dx,model.df);
for kt=2:Nt+1
45     un=u(kt-1,:);
        slopes=slope(un(jL),un(j),un(jR), solver);
47     um=un; up=un; ulm=un; ulp=un;
        um(j)=un(j)-slopes/2;
49     up(j)=un(j)+slopes/2;
        plotReconstruction(j,dx,x,un,um,up,withplot);
51     ulp(j)=up(j) - dt/dx/2 *( model.f(up(j)) -model.f(um(j)) );
        ulm(j)=um(j) - dt/dx/2 *( model.f(up(j)) -model.f(um(j)) );
53     plotReconstruction(j,dx,x,un,ulm,ulp,withplot);
        % u2star=u(kt-1,:);
55     %ustar(j)=u(kt-1,j)-evolutionOperator(u(kt-1,:), j, jL, jR, solver, dt, dx,x, model,
        extra,withplot);
        % u2star(j)=ustar-evolutionOperator(ustar, j, jL, jR, solver, dt, dx,x, model,extra,
        withplot);
57     % u(kt,j)=0.5*(u2star(j)+u(kt-1,j));%u(kt-1,j)-evolutionOperator(ustar, j, jL, jR,
        solver, dt, dx,x, model,extra,withplot);
        u(kt,j)=un(j)- dt/dx*(...
59         numericalFlux(solver.scheme,model.f,ulp(j),ulm(jR),extra)...
        -numericalFlux(solver.scheme,model.f,ulp(jL),ulm(j),extra));
61     if withplot
        for k=1:length(j)
63         plot(x(j(k))+[-dx/2,dx/2],[u(kt,j(k)),u(kt,j(k))],'r')
        end
65         drawnow
        pause(1)
67     end
        ent(kt,:)=model.entropy(u(kt,:));
69 end
71 end

73 function plotReconstruction(j,dx,x,u,um,up,withplot)
    if withplot
75         figure(4)
            clf()
77         plot(x(j),u(j),'x')
            hold on
79         for k=1:length(j)
            plot(x(j(k))+[-dx/2,dx/2],[um(j(k)),up(j(k))],'--')
81         end
            drawnow
83         pause(0.5)
        end
85 end

87
89 function extra=defineExtraScheme(scheme,lam,df)
switch scheme
    case {"Lax Friedrichs","2stepLxW"}
        extra={lam};
91     case "Lax Wendroff"
        extra={lam, df};
93     case "Rusanov"
        extra={df};
95

```

```

107     case {"Godunov","EO"}
        extra={0}; %only Burgers
109     case "Roe"
        extra={};
101 end
103 end
105 function sigma=slope(uL,u,uR,solver)
107 idx=logical(1-(uR==u));
109 r=zeros(size(u));
107 r(idx)=(u(idx)-uL(idx))./(uR(idx)-u(idx));
109 sigma=(uR-u).*switchingFunction(r,solver);
107 end

```

Listing 5: runMUSCL.m

4. Test the accuracy of the method on $\partial_t u + \partial_x u = 0$ with $u_0(x) = 1 + 0.2 \cos(\pi x)$ on $[-2, 2]$ for all switching functions and Rusanov as numerical flux. Which limiter performs better? Which one does not reach second order of accuracy?
5. Test the TVD property of the scheme. For $\partial_t u + \partial_x u = 0$ with

$$u_0(x) = \begin{cases} 1 & \text{if } 0 \leq x \leq 1 \\ 0 & \text{else} \end{cases}$$

on $[-2, 2]$ with all the limiters and Rusanov numerical flux compute the TV of the solution as a function of time on a simulation with $N = 100$ cells, $T = 1$ and $\text{CFL}=0.9$. Which limiter does not fulfill the TVD conditions?

Solution

```

%% Test MUSCL SCHEME on LINEAR ADVECTION equation
2 model.f=@(u) u; %u.^2;
model.df=@(u) ones(size(u));
4 model.T=1;
model.a=-2;
6 model.b=2;
model.u0=@(x) (x<1).*(x>0); %1+ 0.2* cos(pi*x); % 0.2* cos(pi*x); % uL*(x<0)+uR*(x>=0); %cos
(pi*x); %cos(pi*x);
8 model.BC="periodic"; %"dirichlet"; %"periodic";
model.exact=@(x,t) model.u0(x-t);
10
model.entropy = @(u) abs(u); %u.^2; %abs(u); %u.^2/2; %@(u)
12 model.eFlux = @(u) sign(u).*f(u); % @(u) u.^3/3;

14 %% One example
solver.Nx = 40;
16 solver.CFL=0.8; %0.7;
solver.limiter="minmod"; %"Beam Warming";
18 solver.scheme="Rusanov";

20 runMUSCL(model, solver);

```

```

22 %% Convergence
model.u0=@(x) 1+ 0.2* cos(pi*x);% 0.2* cos(pi*x);% uL*(x<0)+uR*(x>=0); %cos(pi*x);%cos(pi
*x);
24 model.exact=@(x,t) model.u0(x-t);

26
28 solver.Nx = 100;
28 solver.CFL = 0.9;
28 solver.limiter="MC";

30
32 schemes=["Lax Friedrichs";"Rusanov";"Godunov";"Roe";"EO";"Lax Wendroff";"2stepLxW"];
32 styles=["-","*-","+-","x-",".",",","-","+"];
32 nn=10;
34 Ns=2.^[1:nn];

36 clear u x t ent errors times

38 for k=1:length(schemes)
    solver.scheme=schemes(k);
40     for n=1:length(Ns)
        solver.Nx=Ns(n);
42         tic
        [u,x,t,ent]= runMUSCL(model, solver);
44         times(k,n)=toc;
        errors(k,n)=computeError(u,x,t,model);
46     end
48 end

48 figure()
50 for k=1:length(schemes)
    scheme=schemes(k);
52     loglog(1./Ns,errors(k,:),styles(k),'DisplayName',scheme)
    hold on
54 end
54 loglog(1./Ns,1./Ns,':','DisplayName','first order')
56 loglog(1./Ns,100*1./Ns.^2,':','DisplayName','second order')
56 legend('Location','best')
58 xlabel('dx')
58 ylabel('error')

60
62 %% Different limiters
62 model.u0=@(x) 1+ 0.2* cos(pi*x);% 0.2* cos(pi*x);% uL*(x<0)+uR*(x>=0); %cos(pi*x);%cos(pi
*x);
64 model.exact=@(x,t) model.u0(x-t);

66
66 solver.Nx = 100;
66 solver.CFL = 0.9;

68
68 solver.scheme="Rusanov";%"Godunov";%"Rusanov";
70 limiters=["minmod", "vanLeer","upwind","Lax Wendroff", "Beam Warming","Superbee","MC"];
70 styles=["-","*-","+-","x-",".",",","-","+"];
72 nn=10;
72 Ns=2.^[2:nn];

74
74 clear u x t ent errors times

```

```

76 for k=1:length(limiters)
77     solver.limiter=limiters(k);
78     for n=1:nn-1
79         solver.Nx=Ns(n);
80         tic
81         [u,x,t,ent]= runMUSCL(model, solver);
82         times(k,n)=toc;
83         errors(k,n)=computeError(u,x,t,model);
84     end
85 end
86
87 fig=figure()
88 for k=1:length(limiters)
89     scheme=limiters(k);
90     loglog(1./Ns, errors(k,:), styles(k), 'DisplayName', scheme)
91     hold on
92 end
93 title(sprintf('Convergence with numerical flux %s', solver.scheme))
94 loglog(1./Ns, 1./Ns, ':', 'DisplayName', 'first order')
95 loglog(1./Ns, 10*1./Ns.^2, ':', 'DisplayName', 'second order')
96 legend('Location', 'best')
97 xlabel('dx')
98 ylabel('error')
99 saveas(fig, sprintf('convergence-%s.pdf', solver.scheme))
100
101 %% plot TV instability
102
103 model.f=@(u) u; % u.^2;
104 model.df=@(u) ones(size(u));
105 model.T=1;
106 model.a=-2;
107 model.b=2;
108 model.u0=@(x) (x<1).*(x>0); % 1+ 0.2* cos(pi*x); % (x<1).*(x>0); % 0.2* cos(pi*x); % uL*(x
109 <0)+uR*(x>0); % cos(pi*x); % cos(pi*x);
110 model.BC="periodic"; % "dirichlet"; % "periodic";
111 model.exact=@(x,t) model.u0(x-t);
112
113 model.entropy = @(u) abs(u); % u.^2; % abs(u); % u.^2/2; % @(u)
114 model.eFlux = @(u) sign(u).*f(u); % @(u) u.^3/3;
115
116 solver.scheme="Rusanov";
117 solver.Nx=100;
118 solver.CFL=0.8;
119
120
121 limiters=[ "minmod", "vanLeer", "upwind", "Lax-Wendroff", "Beam-Warming", "Superbee", "MC"];
122 styles=["-", "*-", "+-", "x-", ".", "-.", "+"];
123 clear TV
124 fig=figure()
125 k=0;
126 for limiter=limiters
127     k=k+1;
128     solver.limiter=limiter;
129     [u,x,t,ent]= runMUSCL(model, solver);
130     for n=1: numel(t)

```

```

132         TV(k,n) = sum(abs( diff(u(n,:)) ))+abs(u(n,end)-u(n,1));
133     end
134     plot(t,TV(k,:), styles(k), 'DisplayName', limiter)
135     hold on
136 end
137 legend('Location', 'best')
138 title(sprintf('Total variation %s', solver.scheme))
139 saveas(fig, sprintf('TV_MUSCL%s.pdf', solver.scheme))
140
141 %% plot TV instability for Burger
142
143 model.f=@(u) u.^2;
144 model.df=@(u) u;%ones(size(u));
145 model.T=1;
146 model.a=-2;
147 model.b=2;
148 model.u0=@(x) (x<1).*(x>0);%1+ 0.2* cos(pi*x);% 0.2* cos(pi*x);% uL*(x<0)+uR*(x>=0); %
149     cos(pi*x);%cos(pi*x);
150 model.BC="periodic";%"dirichlet";%"periodic";
151 model.exact=@(x,t) model.u0(x-t);
152
153 model.entropy = @(u) abs(u);%u.^2;%abs(u); %u.^2/2; %(u)
154 model.eFlux = @(u) sign(u).*f(u); % @(u) u.^3/3;
155
156 solver.scheme="Lax Friedrichs";
157 solver.Nx=100;
158 solver.CFL=0.5;
159
160 %runMUSCL(model, solver,1);
161
162
163 limiters=[ "minmod"];%, "vanLeer", "upwind", "Lax Wendroff", "Beam Warming", "Superbee", "MC
164     "];
165 styles=["-", "*-", "+-", "x-", ":", ":", "-.", "+"];
166 clear TV
167 fig=figure()
168 k=0;
169 for limiter=limiters
170     k=k+1;
171     solver.limiter=limiter;
172     [u,x,t,ent]= runMUSCL(model, solver);
173     for n=1:numel(t)
174         TV(k,n) = sum(abs( diff(u(n,:)) ))+abs(u(n,end)-u(n,1));
175     end
176     semilogy(t,TV(k,:), styles(k), 'DisplayName', limiter)
177     hold on
178 end
179 legend('Location', 'best')
180 title(sprintf('Total variation %s CFL %g', solver.scheme, solver.CFL))
181 saveas(fig, 'TV_Burgers.pdf')
182 system('pdfcrop TV_Burgers.pdf TV_Burgers.pdf')
183
184
185 function err=computeError(u,x,t,model)

```

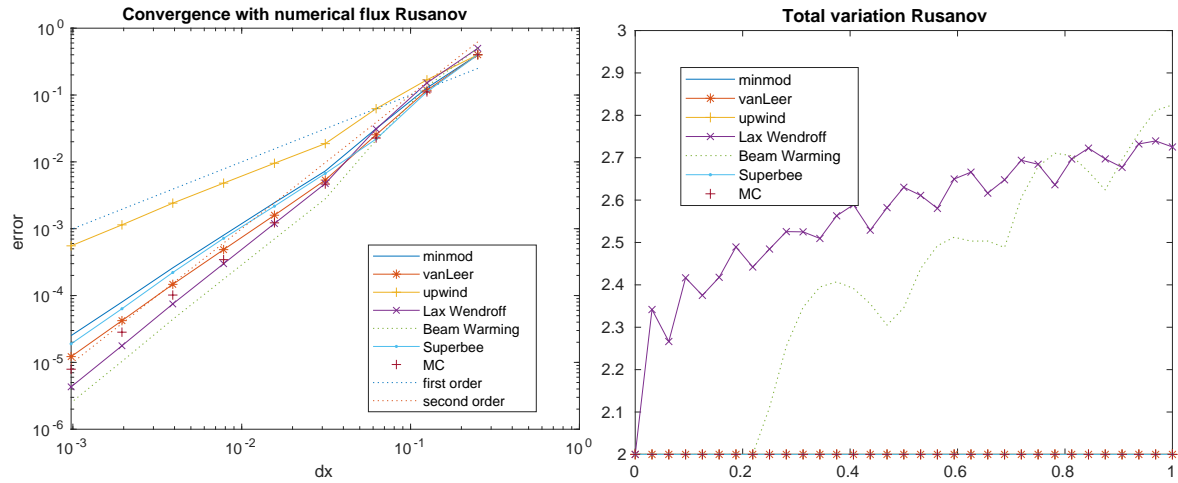


Figure 3: Convergence error and TV of MUSCL schemes

```
err=norm(u(end,:)-model.exact(x,t(end)))*sqrt(x(2)-x(1));
end
```

Listing 6: testConvergenceMUSCL.m

We see that all the methods respect the conditions we theoretically found: upwind is 1st order, Lax-Wendroff and Beam Warming are not TVD, the rest is second order and TVD.

6. Test the scheme with Burgers' equation. What is happening? Why? Can you find a switching function and a numerical flux that, under some conditions, give a TVD scheme?

Solution

The conditions are not valid also for the Burgers' equation. What we can observe is that if we lower the CFL conditions and we choose a very diffusive numerical flux as the Lax Friedrichs, we can obtain TVD for the minmod limiter.

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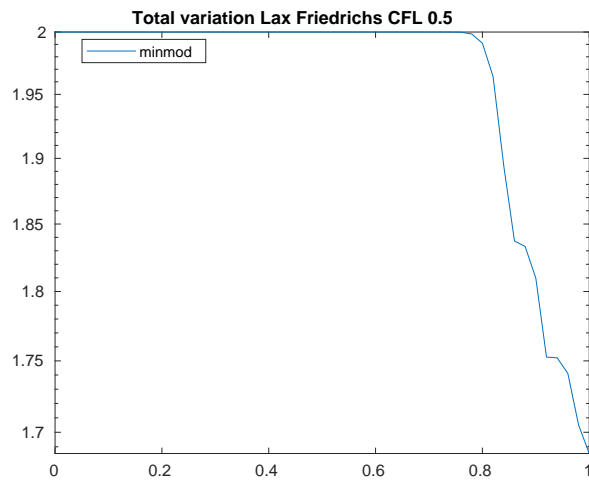


Figure 4: Convergence error and TV of MUSCL schemes on Burgers equation