

[Marks]

(8) 1. Let  $A = \begin{bmatrix} 0 & 1 & 2 & 2 & -2 \\ 1 & 0 & 3 & 0 & 4 \\ -1 & 3 & 3 & 0 & -10 \end{bmatrix}$ . Its row reduced echelon form  $R = \begin{bmatrix} 1 & 0 & 3 & 0 & 4 \\ 0 & 1 & 2 & 0 & -2 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$ .

- (a) Solve the linear system  $A\mathbf{x} = \mathbf{0}$ . Write the solution in parametric vector form.  
 (b) Find a basis of  $\text{Row}(A)$ .  
 (c) Find a basis of  $\text{Col}(A)$ .  
 (d) Write the last column of  $A$  as a linear combination of the other columns of  $A$ .

(6) 2. Use linear algebra to balance the chemical equation:  $\text{C}_3\text{H}_8 + \text{O}_2 \rightarrow \text{CO}_2 + \text{H}_2\text{O}$ .

(7) 3. Let the matrix  $A = \begin{bmatrix} 1 & -2 & -1 & -2 \\ 2 & -1 & 4 & 5 \\ 4 & 1 & 2 & 1 \\ 1 & -1 & 1 & 1 \end{bmatrix}$ .

- (a) Use row operations to find  $A^{-1}$  or to show that  $A^{-1}$  does not exist.

(b) Find two elementary matrices  $E_1$  and  $E_2$  such that  $E_2E_1A = \begin{bmatrix} 1 & -2 & -1 & -2 \\ 2 & -1 & 4 & 5 \\ \frac{1}{3} & -\frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ 4 & 1 & 2 & 1 \end{bmatrix}$

(6) 4. Let  $A = \begin{bmatrix} 4 & 0 & 1 \\ -2 & 3 & -1 \\ 0 & 1 & 2 \end{bmatrix}$ .

- (a) Find  $\text{adj}(A)$ . (b) Compute  $\det(A)$ . (c) Find  $A^{-1}$  using  $\text{adj}(A)$ .

(5) 5. Solve for the matrix  $X$  where

$$\left( \begin{bmatrix} 2 & 5 \\ 2 & 6 \end{bmatrix} X^T \right)^{-1} = \begin{bmatrix} 3 & 4 \\ 4 & 5 \end{bmatrix}$$

(9) 6. Let  $A$  be a symmetric  $4 \times 4$  matrix with  $\det(A) = -3$ . Let  $B$  be a  $4 \times 4$  matrix with  $\det(B) = 2$ .

- (a) Find  $\det((A^{-1})^3)$ . (b) Find  $\det(\text{adj}(A^{-1}B))$ . (c) Find  $\det(A + A^T)$ .

(8) 7. Let  $S: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a linear transformation such that  $S\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$  and  $S\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$ .

Let  $R: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the rotation of  $-\frac{\pi}{4}$  about the origin.

- (a) Find the standard matrix of  $S$ .  
 (b) Find the standard matrix of  $R \circ S$ .

(6) 8. We are given the lines  $\mathcal{L}_1: \mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 5 \end{bmatrix} + t \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$  and  $\mathcal{L}_2: \mathbf{x} = \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$ . Find an equation of the plane (in the form  $ax + by + cz = d$ ) that contains  $\mathcal{L}_2$  and is parallel to  $\mathcal{L}_1$ .

(6) 9. Find an equation of the plane (in the form  $ax + by + cz = d$ ) that contains the point  $M(1, -1, 2)$  and is perpendicular to both planes  $x + 2y - z = 2$  and  $x - y - z = 4$ .

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(8) 10. Define  $H = \left\{ \begin{bmatrix} x & y \\ z & w \end{bmatrix} \in M_{2 \times 2} : xy = zw \right\}$ .

(a) Show that  $H$  is not closed under vector addition.

(b) Show that  $H$  is closed under scalar multiplication.

(5) 11. Find a basis for the subspace  $V = \{p(x) \in \mathbb{P}_2 : p(2) = p'(1)\}$ .

(5) 12. Let  $\mathbf{u}$  and  $\mathbf{v}$  be two vectors in  $\mathbb{R}^n$ . Suppose that  $\mathbf{u}$  is a unit vector,  $\|\mathbf{v}\| = 5$  and  $\mathbf{u} \cdot \mathbf{v} = -3$ . Find all values of  $k$ , if any, for which the vectors  $\mathbf{u} + k\mathbf{v}$  and  $\mathbf{v} + 2\mathbf{u}$  are orthogonal.

(9) 13. Given a point  $P(8, 5, 0)$  and a line  $\mathcal{L} : \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$ ,

(a) find the point  $Q$  on  $\mathcal{L}$  closest to  $P$ ;

(b) find the distance from  $P$  to  $\mathcal{L}$ .

(8) 14. Given points  $A(0, 0, 1)$ ,  $B(1, 1, 2)$ ,  $C(4, 6, 5)$ , and  $D(-1, 4, k)$ ,

(a) find the area of triangle  $ABC$ ;

(b) find an equation of the plane (in the form  $ax + by + cz = d$ ) that contains  $A$ ,  $B$  and  $C$ ;

(c) find  $k$  such that  $\overrightarrow{AD}$  is orthogonal to  $\overrightarrow{AC}$ .

(4) 15. Fill in the blank with the word *must*, *might*, or *cannot*, as appropriate.

(a) If two vectors  $\mathbf{u}$  and  $\mathbf{v}$  are linearly independent, then  $\text{Span}\{\mathbf{u} + \mathbf{v}, \mathbf{u} - \mathbf{v}\}$  \_\_\_\_\_ be equal to  $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ .

(b) If  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear transformation such that  $T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ , then  $T$  \_\_\_\_\_ be a rotation.

(c) If  $A$  is a  $3 \times 3$  matrix, then  $\text{Col}(A)$  and  $\text{Nul}(A)$  \_\_\_\_\_ both be planes in  $\mathbb{R}^3$ .

(d) Let  $\mathbf{u}$ ,  $\mathbf{v}$  and  $\mathbf{w}$  be vectors. If  $\{\mathbf{u}, \mathbf{v}\}$  is linearly dependent and  $\{\mathbf{u}, \mathbf{w}\}$  is linearly dependent, then  $\{\mathbf{v}, \mathbf{w}\}$  \_\_\_\_\_ be linearly dependent.

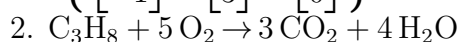
## ANSWERS

1. (a)  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = s \begin{bmatrix} -3 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -4 \\ 2 \\ 0 \\ 0 \\ 1 \end{bmatrix}$

(b)  $\{(1 \ 0 \ 3 \ 0 \ 4), (0 \ 1 \ 2 \ 0 \ -2), (0 \ 0 \ 0 \ 1 \ 0)\}$

(c)  $\left\{ \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} \right\}$

(d)  $\begin{bmatrix} -2 \\ 4 \\ -10 \end{bmatrix} = 4 \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$



3. (a)  $A^{-1}$  does not exist

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$$(b) E_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \text{ OR } E_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \frac{1}{3} \end{bmatrix}, E_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$4. (a) \operatorname{adj}(A) = \begin{bmatrix} 7 & 1 & -3 \\ 4 & 8 & 2 \\ -2 & -4 & 12 \end{bmatrix} \quad (b) 26 \quad (c) A^{-1} = \frac{1}{26} \begin{bmatrix} 7 & 1 & -3 \\ 4 & 8 & 2 \\ -2 & -4 & 12 \end{bmatrix}$$

$$5. X = \begin{bmatrix} -25 & 9 \\ \frac{39}{2} & -7 \end{bmatrix}$$

$$6. (a) \frac{-1}{27} \quad (b) \frac{-8}{27} \quad (c) -48$$

$$7. (a) \begin{bmatrix} -2 & 2 \\ -1 & 0 \end{bmatrix} \quad (b) \begin{bmatrix} -\frac{3\sqrt{2}}{2} & \sqrt{2} \\ \frac{\sqrt{2}}{2} & -\sqrt{2} \end{bmatrix}$$

$$8. 3x - 5y + z = 7$$

$$9. x + z = 3$$

$$10. (a) A_1 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \in H \text{ and } A_2 = \begin{bmatrix} -1 & -1 \\ 1 & 1 \end{bmatrix} \in H, \text{ but } A_1 + A_2 \notin H \text{ (for example)}$$

$$(b) \text{ For any } A = \begin{bmatrix} x & y \\ z & w \end{bmatrix} \in H \text{ (so } xy = zw) \text{ and any scalar } \lambda, \lambda A = \begin{bmatrix} \lambda x & \lambda y \\ \lambda z & \lambda w \end{bmatrix}, \lambda A \in H \text{ since}$$

$$(\lambda x)(\lambda y) = \lambda^2(xy) = \lambda^2(zw) = (\lambda z)(\lambda w).$$

$$11. \left\{ -\frac{1}{2}x^2 + x, -\frac{1}{2}x^2 + 1 \right\} \text{ (other answers possible)}$$

$$12. k = \frac{1}{19}$$

$$13. (a) Q(0, 5, 4) \quad (b) 4\sqrt{5}$$

$$14. (a) \sqrt{2} \quad (b) -x + z = 1 \quad (c) k = -4$$

$$15. (a) \text{ MUST} \quad (b) \text{ MIGHT} \quad (c) \text{ CANNOT} \quad (d) \text{ MIGHT}$$