- 1. What things should you consider while implementing messaging in a model?
  - Message Levels: Implement message verbosity (e.g., error, warning, info, debug) to control the amount of information displayed.
  - Message Consistency: Ensure uniform message formatting for readability.
  - Message Filtering: Allow filtering based on severity levels.
  - Time Stamping: Include time stamps for debugging and tracking.
  - Performance: Ensure messages don't cause performance bottlenecks.
- 2. How are message levels implemented in a BFM?

BFM uses different levels of messaging, such as:

- Errors: Critical issues that stop the simulation.
- Warnings: Non-fatal issues that may affect functionality.
- Info: General information about operations.
- Debug: Detailed messages for debugging.
- 3. What is a BUS Functional Model (BFM)?

A BFM is a simulation model that mimics the behaviour of a bus or protocol without internal logic. It generates stimuli or responds to transactions based on bus operations and helps in testing design interfaces.

- 4. What are a few considerations that go into designing a BFM?
  - Protocol Compliance: Ensure the BFM accurately follows the bus protocol.
  - Transaction Speed: Balance between timing accuracy and performance.
  - Configurability: Design for flexible transaction generation (address, data, delays).
  - Error Injection: Support for testing corner cases and error conditions.
- 5. What is a typical flow in designing a BFM?
  - Specification Study: Understand the protocol or bus thoroughly.
  - Basic Transaction Design: Implement basic read/write and handshaking logic.
  - Timing Modeling: Introduce accurate timing for transaction events.
  - Error Handling: Implement error injection and handling scenarios.
  - Testing: Verify with various test cases and protocols.
- 6. How can BFMs be used to inject intentional errors in the stimulus?

BFMs can inject errors by:

- Sending incorrect addresses or data.
- Violating timing constraints like setup or hold times.
- Misaligning handshake signals.
- 7. What are the main responsibilities of a bus monitor?
  - Transaction Monitoring: Capture all bus transactions.
  - Error Detection: Detect protocol violations or incorrect data/addresses.
  - Logging: Log transactions and errors for debugging.
  - Coverage Collection: Monitor transactions to assess test coverage
- 8. Design of bus monitor and explain it's working.
  - Signal Capture: Monitor bus signals (e.g., data, address, control).
  - State Machine: Use a state machine to track the bus states and transactions.
  - Error Detection Logic: Compare observed transactions against protocol rules to identify errors.
  - Log Transactions: Capture all valid transactions with relevant details (address, data, timestamps).
- 9. What are the considerations in designing a Monitor?
  - Protocol Adherence: Must accurately reflect bus protocol timing and rules.
  - Latency: Ensure minimal delay in monitoring to avoid affecting performance.
  - Configurability: This should be adaptable to different test environments and buses.
  - Error Reporting: Efficiently report errors without overwhelming the user.

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10. A 1-bit full subtractor has 3 inputs x,y and z(previous borrow) and 2 outputs D(difference) and B(borrow).
The logic equations for D and B are as follows:
D = x'y'z+x'yz'+xy'z'+xyz
B=x'y+x'z+yz
    a. Write the Verilog RTL description for the full subtractor.
         module full subtractor (
                           // Inputs: x, y, z (previous borrow)
           input x, y, z,
           output D, B
                              // Outputs: D (difference), B (borrow)
         );
           assign D = (\sim x \& \sim y \& z) | (\sim x \& y \& \sim z) | (x \& \sim y \& \sim z) | (x \& y \& z);
           assign B = (\sim x \& y) | (\sim x \& z) | (y \& z);
         endmodule
    b. Optimize for fastest timing.
         module full subtractor optimized (
           input x, y, z, // Inputs: x, y, z (previous borrow)
                            // Outputs: D (difference), B (borrow)
           output D, B
        );
           // Optimized equations for Difference (D) and Borrow (B)
           assign D = x ^ y ^ z;
                                            // XOR gates are fast
           assign B = (\sim x \& (y \mid z)) \mid (y \& z); // Optimized borrow logic with minimal depth
         endmodule
    c. Apply stimulus to verify that the design function properly.
         module test full subtractor;
           reg x, y, z;
           wire D, B;
           full subtractor uut (.x(x), .y(y), .z(z), .D(D), .B(B));
           initial begin
              // Test all input combinations
              \frac{display("x y z | D B")}{display("x y z | D B")};
              $monitor("%b %b %b | %b %b", x, y, z, D, B);
              // Apply test cases
              x = 0; y = 0; z = 0; #10;
              x = 0; y = 0; z = 1; #10;
              x = 0; y = 1; z = 0; #10;
              x = 0; y = 1; z = 1; #10;
              x = 1; y = 0; z = 0; #10;
              x = 1; y = 0; z = 1; #10;
              x = 1; y = 1; z = 0; #10;
              x = 1; y = 1; z = 1; #10;
              // Finish simulation
              $finish;
           end
         endmodule
```

d. Print error messages whenever necessary.

```
initial begin
```

```
// Apply test cases x=0; y=0; z=0; \#10; \text{ if } (D !== 0 \parallel B !== 0) \text{ $display("Error: } x=0, y=0, z=0"); $$$$$$$$x=0; y=0; z=1; \#10; \text{ if } (D !== 1 \parallel B !== 1) \text{ $display("Error: } x=0, y=0, z=1"); end
```