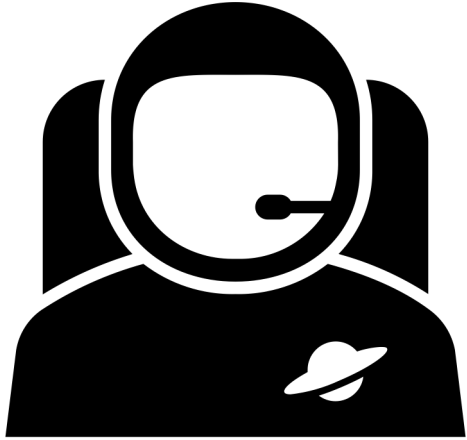




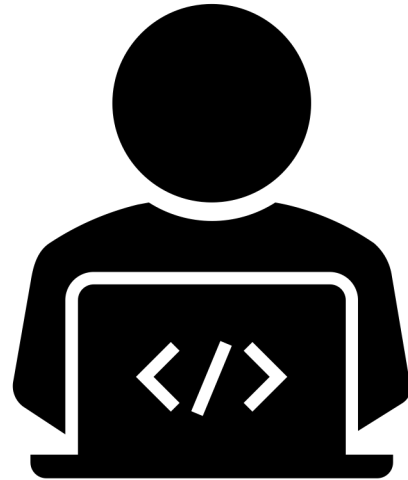
Flood Measurement from a Photo

By

Shaffer, Hoke, Pander & Kuehl Partners



Clint Hoke



Jamie Shaffer



Jonna Pander



Josh Kuehl

Partners

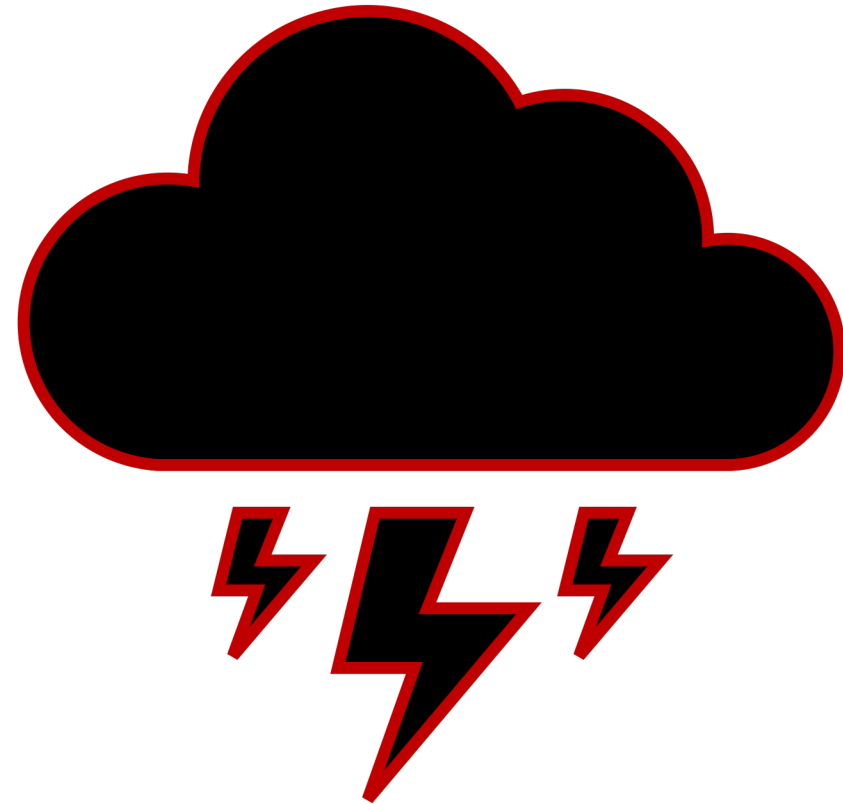


Agenda

- Problem Statement
- Research
- Solution
- Issues



Problem: Create a machine model that can detect flood depth from a photo.



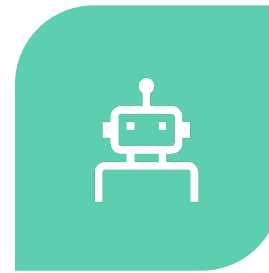
Research



SCHOLARLY
ARTICLES



RESOURCES

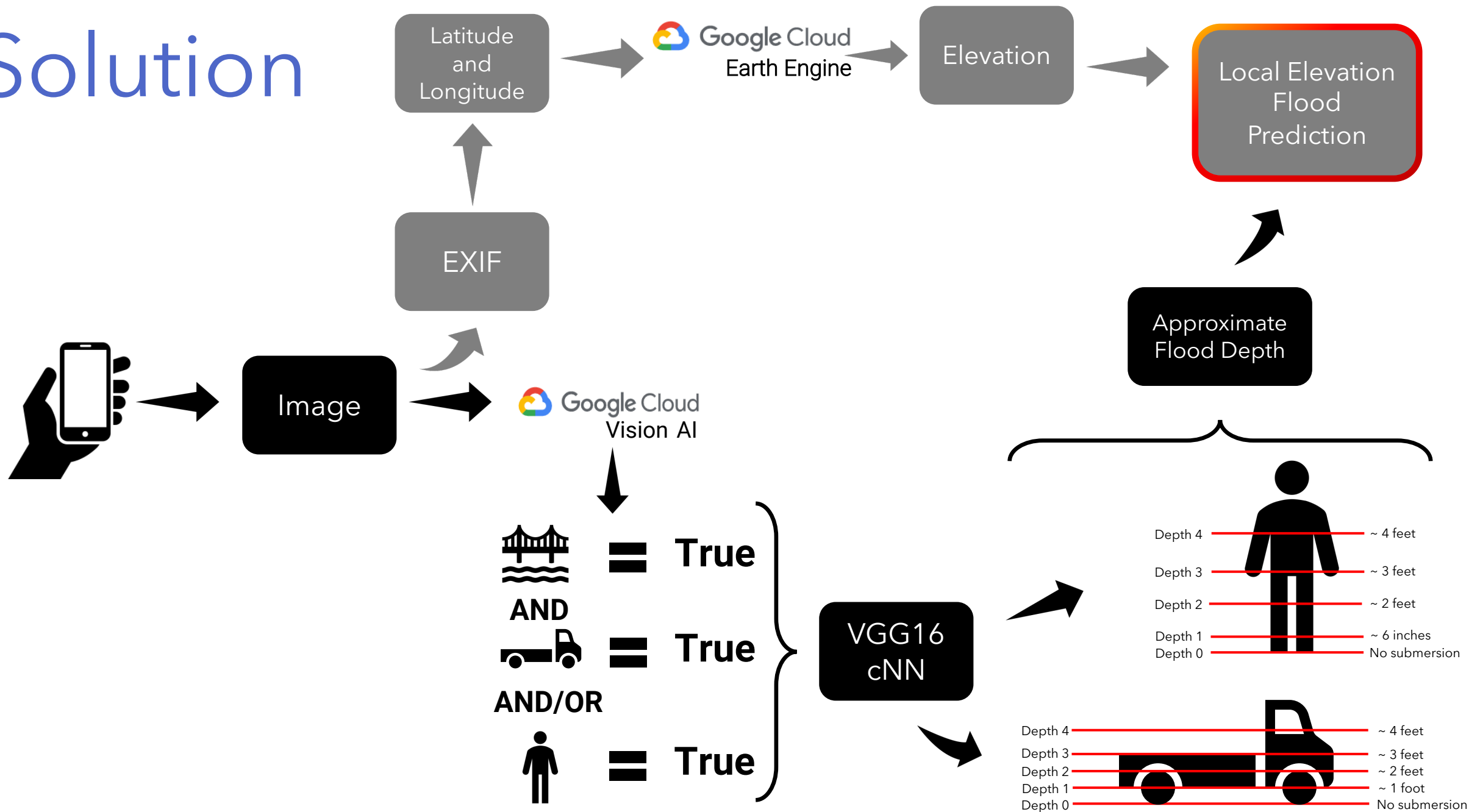


APIS



LIBRARIES

Solution



Google Vision AI

- Paid Service
- Detect objects automatically
- Data labeling service
- Image pre-processor
- API was used to run batches of images

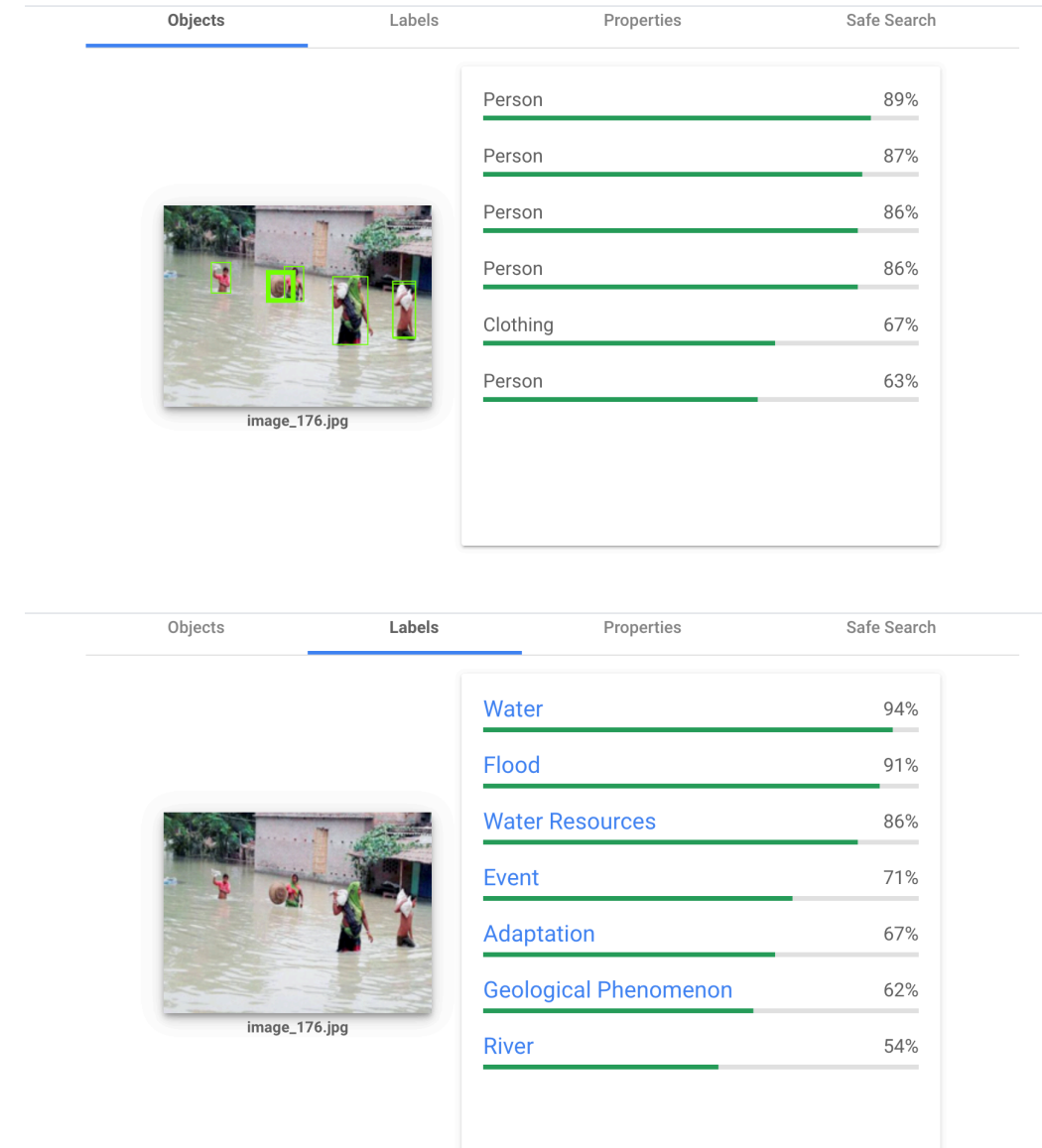


Image Augmentation

Image: rot-4.5_img_0144.jpg

Actual: depth_3

Predicted: depth_2

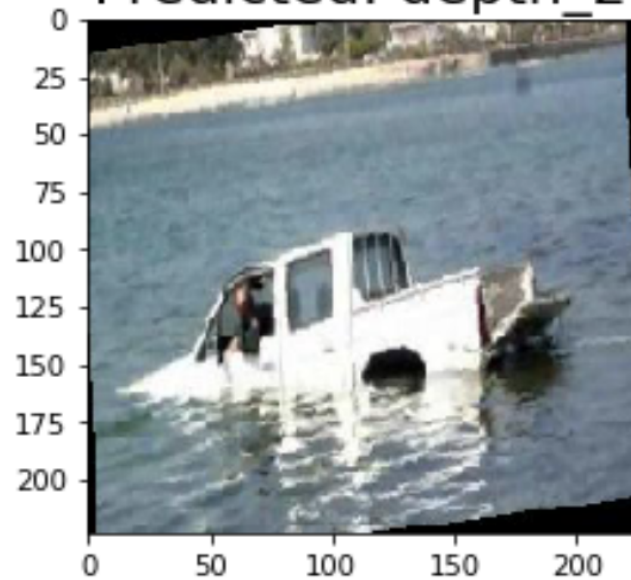
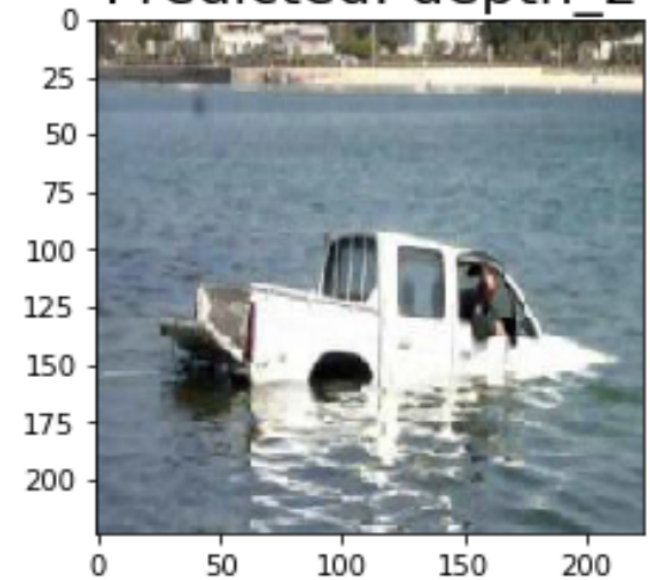


Image: hflip_img_0144.jpg

Actual: depth_3

Predicted: depth_2




Results

Truck Model

- Exact Accuracy: 32%
- Tolerance(+/-1) Accuracy: 80%
- Most accurate at depths 0 - 2

People Model

- Exact Accuracy: 25%
- Tolerance(+/-1) Accuracy: 60%
- Most accurate at depths 0 and 4

- 
1. People can swim
 2. Shortage of training data
 3. Bow wake
 4. Personal computer processing power
 5. Complex images
 6. Micro terrain
 7. Time constraint
 8. Definition of levels

Issues





Questions

