

# Stats

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```
-- Attaching packages ----- tidyverse 1.3.2 --
v ggplot2 3.3.6      v dplyr    1.0.10
v tibble   3.1.8      v stringr  1.4.1
v readr    2.1.3      vforcats  0.5.2
v purrr   0.3.4

-- Conflicts ----- tidyverse_conflicts() --
x dplyr::filter() masks stats::filter()
x dplyr::lag()   masks stats::lag()

Registered S3 method overwritten by 'GGally':
  method from
  +.gg   ggplot2

Rows: 111 Columns: 4
-- Column specification -----
Delimiter: ","
dbl (4): radiation, temperature, wind, ozone

i Use `spec()` to retrieve the full column specification for this data.
i Specify the column types or set `show_col_types = FALSE` to quiet this message.
```

## 0.1 Question 1 a)

Ex 1 a) Knowing Aaron's parent have brown eyes and an offspring with blue eyes we can determine that each of the parents have a brown eye gene and a blue eye gene, since if one of them had 2 dominant brown eye genes the outcome of 2 blue genes that got inherited by Aaron's sister would be impossible.

We can also conclude that Aaron has one brown gene, since it has been displayed by Aaron brown eyes. Leaving Aaron with 3 other outcomes,  $\{AA, Aa, aA\}$  since we don't know the order of Aaron's brown eye gene, we only know he has it.

Defining the event of Aaron inheriting a blue gene as F  
Let E be the event of inheriting a brown gene.

Since Aaron has already a brown eye gene we need to know what is the probability of Aaron inheriting a blue eye gene that has been conditioned by Aaron inheriting a brown gene.

$$P(E|F) = \frac{P(\text{having a blue and brown gene})}{P(\text{brown gene})} \quad (\approx)$$
$$(\approx) P(E|F) = \frac{P(F \cap F)}{P(F)} \quad (\approx) P(E|F) = \frac{\frac{1}{2}}{\frac{3}{4}} = \frac{2}{3} \quad //$$

Figure 1: Exercise 1 a)

## 0.2 Question 1 b)

## 0.3 Question 1 c)

Part 1 of exercise 1 c)

Part 2 of exercise 1 c)

## 0.4 Question 2 a)

Part 1 of exercise 2 a)

Part 2 of exercise 2 a)

1 b) In the previous exercise we have proven that a  $\frac{2}{3}$  chance of blue eyes which is the 2 outcomes  $\{aA, Aa\}$  out of possible  $^3$  sample of  $\{AA, aA, aA\}$ . Since Aaron's wife has blue eyes she can only have 1 gene combination  $\{a a\}$ . Notice that out of the 3 possible Aaron genes, they are all equally likely.

Aaron's genes			
Aaron's wife genes	A A	A a	a A
a Aa at	A a	a a	Aa
a aA Aa	aA	aa	aA

Again since the gene is chosen randomly with equal probability each of 12 possible combination listed above  $\{Aa, aA, aA\}$  each of these have a equal probability of  $\frac{1}{12}$ .

Knowing all the outcomes and their respective probability we can sum up the number of blue eye combinations defined by the  $\{a a\}$  gene combination.

As observed from the listed outcomes 4 outcomes lead to a probability for blue eyes of

$$P(\text{blue eyes}) = \frac{1}{12} + \frac{1}{12} + \frac{1}{12} + \frac{1}{12} = \frac{4}{12} = \frac{1}{3} //$$

Figure 2: Exercise 1 b)

1(c) The information of the birth of Aaron's first child changes the probability that Aaron has the blue eye gene by updating the prior probability that Aaron received probability as in accordance to Bayesian inference.

Aaron still has 3 possible gene combinations  $\{AA, Aa, aA\}$  while Aaron's wife has blue eyes and therefore has the 2 blue eye gene combination.

Knowing this we can determine that Aaron's wife will always provide a blue eye gene and so the eye gene inherited from Aaron's wife is the determining factor of the children eye colour.

The previous information help us determine that the odds of Aaron giving us updated by how likely it is for a child to inherit a brown eye gene from Aaron as it can be demonstrated by the following:

knowing the 3 combinations,

		Aaron eye gene		
		A	a	A
(already) received a blue eye gene from mom)	Aaron	AA (A, A)	Aa (A, a)	aA (a, A)
	child	Brown Brown	Brown Blue	Blue Blue

has observed the double brown eye gene her the same likelihood of having either a brown eye gene than the blue eye and brown eye combinations since the genes chosen to be passed down is randomly selected with equal probability that means that each of the brown and blue eye combinations have 50% of not having a brown eye gene while the 2 brown eye will always pass down each other.

In (in Clarke, O. M. and Cooke, P. (2005) A basic course in statistics. London: Arnold) tree diagram

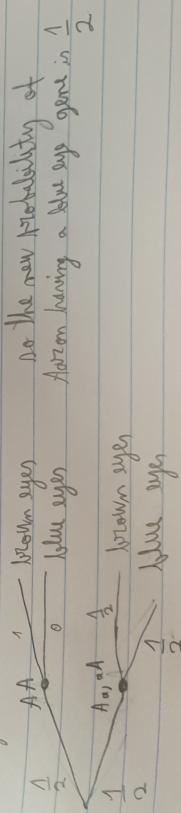


Figure 3: Exercise 1 c) part 1

has observed in the previous table and tree diagram the {AA} combination will always pass down the needed brown gene to ensure the kid has brown eyes

Using the newly adjusted probability, the probability of the 2nd child having brown eyes is

$$P(\text{2nd child brown}) = 1 \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} = \frac{3}{4} //$$

Figure 4: Exercise 1 c) part 2

2 a) There are 361 MPs, 2 are candidates B and M and the remaining 359 MPs will be casting votes on their supporting candidate.

At the start of the Conservative Party leadership election candidate M had the support of 184 MPs and candidate B had the remaining 175 MPs support which is defined by  $X_i^{(1)} = 0$

We also know that each of the candidate M supporters have a fixed chance of 0,005 of changing their support to per day which is defined by  $X_i^{(2)} = 1$  and each of the B supporters have a fixed chance of changing their support of 0,001 per day which is defined by  $X_i^{(1)} = 0$

$$X_i^{(1)} = \begin{cases} 1, & \text{B supporter;} \\ 0, & \text{M supporter;} \end{cases} \text{ at the end of day } i : [1, 185]$$

$$X_i^{(2)} = \begin{cases} 1, & \text{M supporter that will change their support to candidate B at the end of day } i : [1, 184] \\ 0, & \text{M supporter that will not change their support to candidate M at the end of day } i \end{cases}$$

Both variables for the variables  $X_i^{(1)}$  and  $X_i^{(2)}$  are disjoint since a MP can only support one candidate and are independent.

Let us determine that since we want the expected number of B supporters at the end of day 1 we should derive the probability distributions of  $X_i^{(1)}$  and  $X_i^{(2)}$

$$\begin{aligned} P(X_i^{(1)} = 1) &= 1 - P(X_i^{(1)} = 0) \\ \Leftrightarrow P(X_i^{(1)} = 1) &= 1 - 0,004 \\ \Leftrightarrow P(X_i^{(1)} = 1) &= 0,996 \end{aligned}$$

$$\begin{aligned} P(X_i^{(2)} = 0) &= 1 - P(X_i^{(2)} = 1) \\ \Leftrightarrow P(X_i^{(2)} = 0) &= 1 - 0,001 \\ \Leftrightarrow P(X_i^{(2)} = 0) &= 0,999 \end{aligned}$$

Now that we have all the probabilities of  $X_i^{(1)}$  and  $X_i^{(2)}$  we can calculate the theoretical number of supporters that remained by summing up the number of MPs that continued to support candidate B at the end of day 1 plus the number of MPs that supported candidate M but changed their support to candidate B at the end of the day.

Let  $\theta$  be the number of MB supporting candidate  $\theta$

$$\theta = \sum_{i=1}^{175} (X_i^{(1)} = 1) + \sum_{i=1}^{184} (X_i^{(2)} = 1) \quad (=)$$

$$(\Rightarrow) \theta = 175 \times 0,996 + 184 \times 0,005 \quad (=)$$

$$(\Rightarrow) \theta = 174,3 + 0,92$$

$$(\Rightarrow) \theta = 175,22 //$$

Figure 6: Exercise 2 a) part 2

## 0.5 Question 2 C)

```
# set.seed(26041999)

candidateBWins = 0

## Here we set the number of times we will estimate
largeNumberOfEstimations = 1e+06

for (i in 1:largeNumberOfEstimations) {

  candidateB = 175 ## candidate B initial votes/support
  candidateM = 184 ## candidate M initial votes/support

  ## increment for each day from the initial day to the final day,
  ## the 14th
  for (i in 1:14) {

    ## will be used to hold the new value of votes that continue to
    ## support the same candidate
    candidateBAuxCalc = 0
    candidateMAuxCalc = 0

    ## here we will estimate how many candidates still support the
    ## same candidate by generating a vector where 1 means they
    ## still support the same candidate after the end of each day
    ## the 0 represent them changing the support and vote from one
    ## candidate to another
    candidateBAuxCalc = sum(sample(c(1, 0), candidateB, replace = TRUE,
      prob = c(0.996, 0.004)))
    candidateMAuxCalc = sum(sample(c(1, 0), candidateM, replace = TRUE,
      prob = c(0.995, 0.005)))

    ## here we calculate the number of votes that will be exchanged
    ## by the candidates, so the votes that are subtracted from
    ## what they had previously
    votesMovedFromCandidateBToCandidateM = candidateB - candidateBAuxCalc
    votesMovedFromCandidateMToCandidateB = candidateM - candidateMAuxCalc

    ## here calculate that the new current votes for each candidate
    ## by adding the current votes from the mps that still support
    ## the same candidate plus the number of votes of the mps that
    ## exchanged support for their candidate
    candidateB = candidateBAuxCalc + votesMovedFromCandidateMToCandidateB
    candidateM = candidateMAuxCalc + votesMovedFromCandidateBToCandidateM

  }
}
```

```

## check if the candidate B did win the election by holding the
## majority of the votes
if (candidateB > candidateM) {
  candidateBWins = candidateBWins + 1
}

## probability estimation of candidate B winning after 14 days of
## campaign by holding the majority of the votes

probabilityB = candidateBWins/largeNumberOfExtimations

probabilityB

```

[1] 0.359058

As we can see the probability of candidate B winning after 14 days is approximately 0.35

## 0.6 Question 2 d)

```

# set.seed(26041999)

candidateBWins = 0

## Here we set the number of times we will estimate
largeNumberOfExtimations = 1e+06

for (i in 1:largeNumberOfExtimations) {

  candidateB = 175 ## candidate B initial votes/support
  candidateM = 184 ## candidate M initial votes/support

  ## increment for each day from the initial day to the final day,
  ## the 60th
  for (i in 1:60) {

    ## will be used to hold the new value of votes that continue to
    ## support the same candidate
    candidateBAuxCalc = 0
    candidateMAuxCalc = 0

    ## here we will estimate how many candidates still support the
    ## same candidate by generating a vector where 1 means they
    ## still support the same candidate after the end of each day
    ## the 0 represent them changing the support and vote from one
  }
}

```

```

## candidate to another
candidateBAuxCalc = sum(sample(c(1, 0), candidateB, replace = TRUE,
    prob = c(0.996, 0.004)))
candidateMAuxCalc = sum(sample(c(1, 0), candidateM, replace = TRUE,
    prob = c(0.995, 0.005)))

## here we calculate the number of votes that will be exchanged
## by the candidates, so the votes that are subtracted from
## what they had previously
votesMovedFromCandidateBToCandidateM = candidateB - candidateBAuxCalc
votesMovedFromCandidateMToCandidateB = candidateM - candidateMAuxCalc

## here calculate that the new current votes for each candidate
## by adding the current votes from the mps that still support
## the same candidate plus the number of votes of the mps that
## exchanged support for their candidate
candidateB = candidateBAuxCalc + votesMovedFromCandidateMToCandidateB
candidateM = candidateMAuxCalc + votesMovedFromCandidateBToCandidateM

}

## check if the candidate B did win the election by holding the
## majority of the votes
if (candidateB > candidateM) {
    candidateBWins = candidateBWins + 1
}

}

## probability estimation of candidate B winning after 14 days of
## campaign by holding the majority of the votes

probabilityB = candidateBWins/largeNumberOfEstimations

probabilityB

```

[1] 0.771314

As we can see the probability of candidate B winning after 60 days is approximately 0.77

$$3a) f(y; \theta) = \frac{y_1 - y^2/\alpha\theta}{\theta} \quad \text{for } \theta > 0 \quad \text{and } 0 < y < \infty$$

$$\mu = \sqrt{\frac{\pi\theta}{2}}$$

$$\sigma^2 = \theta(4 - \pi)$$

the first theoretical moment in the  $E(X)$ .

Since we already have the mean of the distribution  $\mu$  and the first moment is equal to  $\mu$  we can use it to derive the estimator.

$$\bar{Y} = \sqrt{\frac{\pi\theta}{2}} (\approx)$$

$$(\approx) \quad \bar{V} = \sqrt{\frac{\pi\theta}{2}} (\approx)$$

$$(\approx) \quad 2\bar{Y}^2 = \pi\theta (\approx)$$

$$(\approx) \quad \theta = \frac{2\bar{Y}^2}{\pi} //$$

Figure 7: Exercise 3 a)

3 b) is often for an estimator to be unbiased if the expected value of the estimator is equal to what it is trying to estimate

$$\text{Unbiased estimator } E(\hat{\theta}) = \theta$$

$$\text{If } \hat{\theta} \text{ is unbiased } E(\hat{\theta}) = E\left(\frac{2Y^2}{\pi}\right)$$

Using the linearity of expectation.

$$\begin{aligned} E\left(\frac{2Y^2}{\pi}\right) &= \frac{2}{\pi} \sum_{i=1}^{\infty} E(Y^2) \quad \text{using } V_{\theta}(Y) = E(Y^2) - E(Y)^2 \\ &= \frac{2}{\pi} \times \int_{-\pi}^{\pi} V_{\theta}(Y) \quad E(Y^2) = V_{\theta}(Y) + E(Y)^2 \\ &= \frac{2}{\pi} \times \left[ \frac{\theta(4-\pi)}{2} - \left(\frac{\pi\theta}{2}\right)^2 \right] \quad (\because) \\ &= \frac{2}{\pi} \times \left( \frac{\theta(4-\pi)}{2} - \frac{\pi^2\theta^2}{4} \right) \quad (\because) \\ &= E(\hat{\theta}) = \frac{2}{\pi} \times \left( \frac{\theta(4-\pi)}{2} - \frac{\pi^2\theta}{2} \right) \quad (\because) \\ &= E(\hat{\theta}) = \frac{2}{\pi} \times \left( \frac{4\theta}{2} - \frac{\pi^2\theta}{2} \right) \quad (\because) \\ &= E(\hat{\theta}) = \frac{2}{\pi} \times \left( 2\theta - \frac{\pi^2\theta}{2} \right) \quad (\because) \\ &= E(\hat{\theta}) = \frac{4\theta}{\pi} - 2\theta \quad (\because) \end{aligned}$$

Since  $E(\hat{\theta}) \neq \theta$  this estimator is biased

Sina

Figure 8: Exercise 3 b)

$$3(c) \hat{\theta} = \frac{1}{2m} \sum_{i=1}^m Y_i^2 \quad (\text{minimization})$$

as seen in the previous solution to check for bias in an estimator we need to check if  $E(\hat{\theta}) = \theta$

$$\begin{aligned} E(\hat{\theta}) &= E\left(\frac{1}{2m} \sum_{i=1}^m Y_i^2\right) \\ (\Rightarrow) E(\hat{\theta}) &= \frac{1}{2m} \sum_{i=1}^m E(Y_i^2) \quad (\Rightarrow) \begin{array}{l} \text{Calc Aux:} \\ \text{Var}(Y) = E(Y^2) - E(Y)^2 \end{array} \\ (\Rightarrow) E(\hat{\theta}) &= \frac{1}{2m} \left( \text{Var}(Y) + E(Y)^2 \right) \\ (\Rightarrow) E(\hat{\theta}) &= \frac{1}{2m} \left[ \theta \left( \frac{4\theta - \pi}{2} \right) - \left( \sqrt{\frac{\pi\theta}{2}} \right)^2 \right] \\ (\Rightarrow) E(\hat{\theta}) &= \frac{1}{2m} \left( \frac{4\theta - \theta\pi}{2} - \frac{\pi\theta}{2} \right) \\ (\Rightarrow) E(\hat{\theta}) &= \frac{1}{2m} \left( 2\theta - \frac{\pi\theta}{2} \right) \\ (\Rightarrow) E(\hat{\theta}) &= \frac{2\theta}{2m} - \frac{\pi\theta}{2m} \\ (\Rightarrow) E(\hat{\theta}) &= \theta - \frac{\pi}{2m} \end{aligned}$$

since  $E(\hat{\theta}) \neq \theta$  this is biased estimator however this bias is very simple to compensate.

$$\hat{\theta} - \frac{\pi}{2m}$$

bias in an unbiased estimator  
since we already know that  $E(\hat{\theta}) = \theta - \frac{\pi}{2m}$

using the linearity of the expectation

$$E(\hat{\theta} + \frac{\pi}{2m}) = E(\hat{\theta}) - \frac{\pi}{2m}$$

so if we plug it back on the desired estimator then

$$E(\hat{\theta}) - \frac{\pi}{2m} = \theta - \frac{\pi}{2m} \quad (\Rightarrow) E(\hat{\theta}) = \theta - \frac{\pi}{2m} + \frac{\pi}{2m}$$

$(\Rightarrow) E(\hat{\theta}) = \theta$  // making  $\hat{\theta} - \frac{\pi}{2m}$  an unbiased estimator.

## 0.7 Question 3 a)

## 0.8 Question 3 b)

## 0.9 Question 3 c)

## 0.10 Question 3 d)

3d) an estimator can be considered consistent if  $MSE \rightarrow 0$  as  $m \rightarrow \infty$

Since  $\hat{\theta} - \frac{\pi}{2m}$  is unbiased we have that  $MSE(\hat{\theta} - \frac{\pi}{2m}) = \text{Var}(\hat{\theta} - \frac{\pi}{2m})$

$$\text{Var}(\hat{\theta} - \frac{\pi}{2m}) = \text{Var}\left(\frac{1}{2m} \sum_{i=1}^m Y_i^2 - \frac{\pi}{2m}\right) = \text{Var}\left(\frac{1}{2m} \sum_{i=1}^m X - \frac{\pi}{2m}\right)$$

Since the Variance is invariant when it comes to constants added to all the values of the Variable. Variance (2022) Wikipedia. Wikimedie Foundation. Available at: <https://en.wikipedia.org/wiki/Variance> (Accessed: December 2, 2022).

$$\begin{aligned} & \text{Var}\left(\frac{1}{2m} \sum_{i=1}^m X - \frac{\pi}{2m}\right) = \quad \text{using that variance rules we can remove the } - \frac{\pi}{2m} \\ & = \text{Var}\left(\frac{1}{2m} \sum_{i=1}^m X\right) = \quad \text{for independent random variables, since they are always uncorrelated } \text{Var}\left(\sum_{i=1}^m X\right) = \sum_{i=1}^m \text{Var}(X) \\ & = \sum_{i=1}^{20} \text{Var}\left(\frac{1}{2m} X\right) \\ & = \sum_{i=1}^m \left[\frac{1}{2m}\right]^2 \text{Var}(X) \quad \text{since all values are scaled by a constant, the variance is scaled by the square of the constant.} \\ & = \sum_{i=1}^m \frac{1}{4m^2} \text{Var}(X) \end{aligned}$$

Figure 10: Exercise 3 d)

## 0.11 Question 4 c)

```
vectorY = c(0.573, 0.77, 0.652, 0.827, 0.821, 0.789, 0.898, 0.718, 0.382,
0.668, 0.647, 0.477, 0.661, 0.38, 0.87, 0.794, 0.783, 0.732, 0.629, 0.777,
0.6, 0.724, 0.553, 0.693, 0.687, 0.935, 0.494, 0.411, 0.53, 0.478)

# rt <- polyroot(t)
```

## 0.12 Question 5 a)

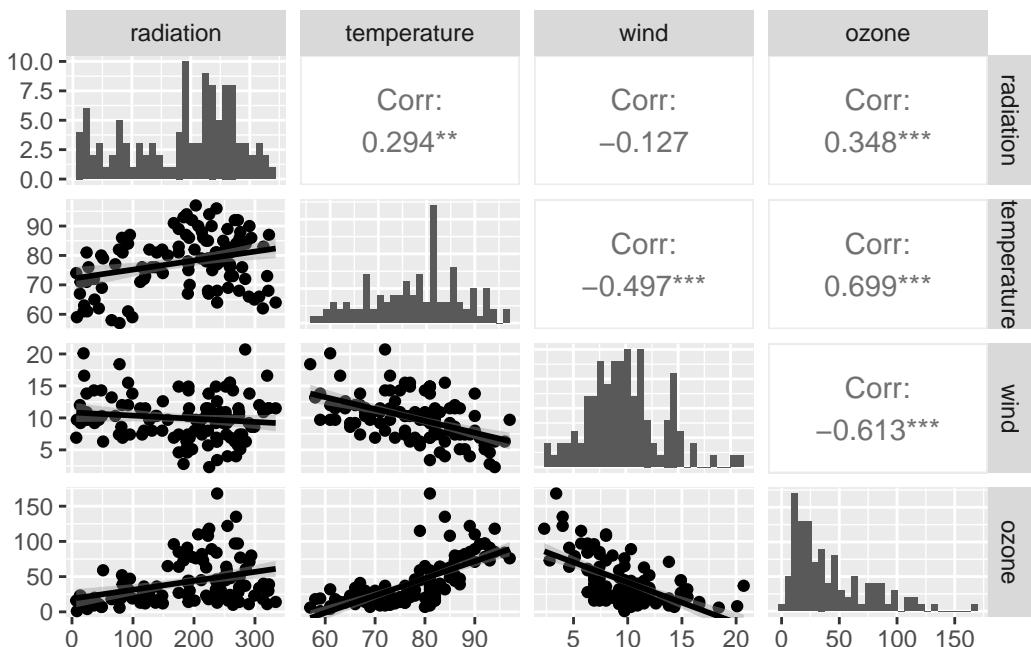
```
summary(ozone)
```

	radiation	temperature	wind	ozone
Min.	: 7.0	Min. :57.00	Min. : 2.300	Min. : 1.0
1st Qu.	:113.5	1st Qu.:71.00	1st Qu.: 7.400	1st Qu.: 18.0
Median	:207.0	Median :79.00	Median : 9.700	Median : 31.0
Mean	:184.8	Mean :77.79	Mean : 9.939	Mean : 42.1
3rd Qu.	:255.5	3rd Qu.:84.50	3rd Qu.:11.500	3rd Qu.: 62.0
Max.	:334.0	Max. :97.00	Max. :20.700	Max. :168.0

Here we can see that wind and ozone have some pretty extremely high max values compared to both the median

```
ggpairs(ozone, lower = list(continuous = "smooth"), diag = list(continuous = "barDiag"),
axisLabels = "show")
```

```
`stat_bin()` using `bins = 30`. Pick better value with `binwidth`.
`stat_bin()` using `bins = 30`. Pick better value with `binwidth`.
`stat_bin()` using `bins = 30`. Pick better value with `binwidth`.
`stat_bin()` using `bins = 30`. Pick better value with `binwidth`.
```



Firstly, as it can be observed in the graph that ozone has a very significant positive skewness and is possibly normally distributed. It also noticeable from the ozone histogram that it resembles a normal distribution with positive skewness.

We can also observe that temperature have a positive and strong linear correlation with ozone with only a small amount of variance overall with the exception of a few points between the 3rd quartile and the maximum, we can also see that there is a positive slope meaning that as temperature increases the amount of ozone detected increases as well.

Furthermore, radiation has a positive correlation with ozone so radiation has a positive effect on ozone. The variance is more extreme between the 2nd quartile and maximum but maintaining a relatively low variance between the minimum and the 2nd quartile.

Lastly, Wind's has a negative correlation with ozone, meaning that as wind increases the less ozone is detected. Most of the variance below the line of best fit, is between the first and third quartile while the values that are more on the extreme, between the the minimum and 1st quartile and the 3rd quartile and the maximum are almost all above the line of best fit. The wind histogram also displays what looks to be a normal distribution with close to zero skewness with some irregularities near the 15 bin.

##question 5 b)

```
model = lm(ozone ~ radiation + temperature + wind, data = ozone)
```

```
summary(model)
```

Call:

```
lm(formula = ozone ~ radiation + temperature + wind, data = ozone)
```

Residuals:

Min	1Q	Median	3Q	Max
-40.485	-14.210	-3.556	10.124	95.600

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	-64.23208	23.04204	-2.788	0.00628 **
radiation	0.05980	0.02318	2.580	0.01124 *
temperature	1.65121	0.25341	6.516	2.43e-09 ***
wind	-3.33760	0.65384	-5.105	1.45e-06 ***
---				
Signif. codes:	0 ***	0.001 **	0.01 *	0.05 .
	'	'	'	'

Residual standard error: 21.17 on 107 degrees of freedom

Multiple R-squared: 0.6062, Adjusted R-squared: 0.5952

F-statistic: 54.91 on 3 and 107 DF, p-value: < 2.2e-16

```
## we can observe that the intercept so when \t
```

```
## residuals are the values of the differences between the line we made
## and the observations
```

```
## the coefficients are the point estimations intercept is the beta0
## and the wt is the beta1
```

First thing we can observe is the confidence intervals of the 3 variables, both the temperature and wind have confidence intervals of 99,9% as it can be see by the 3 stars next to their respective p-values, radiation is in the 95% confidence interval but is close to the 99% confidence interval, meaning all 3 variables have a significant association and are a meaningful addition to our model. Significance being p-values < 0.05.

We can also see by the value of the R-squared and adjusted R-squared that this model around 60% of the variation in ozone levels.

From the estimates we can than wind is the variable with the biggest impact per unit however when comparing it is also important to compare using the minimum and maximum values so we can determine how much each of the independent variables have been recorded to affect the ozone readings so we will be using the minimum and maximum to determine the maximum and minimum variance.

About the Coefficients, we can observe that radiation is the least impactful of the 3 independent variables, the changes in ozone radiation detected vary between [0.4186,19.9732] from the minimum and maximum values, which compared to the [94.11897,160.16737] minimum and maximum variance from the temperature readings which is by far the most impactful variable or the [-7.67648,-66.752] variance from the minimum and maximum values from the wind readings.

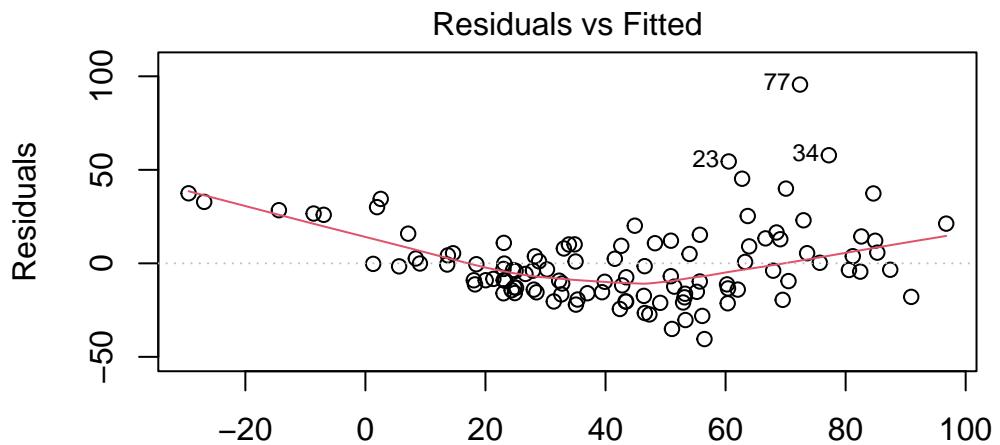
Are these findings consistent with your earlier descriptive plots? Also include suitable residual plots, commenting as appropriate.

## **0.13 the intercept value is impossible so lets grpah what we have and have a look**

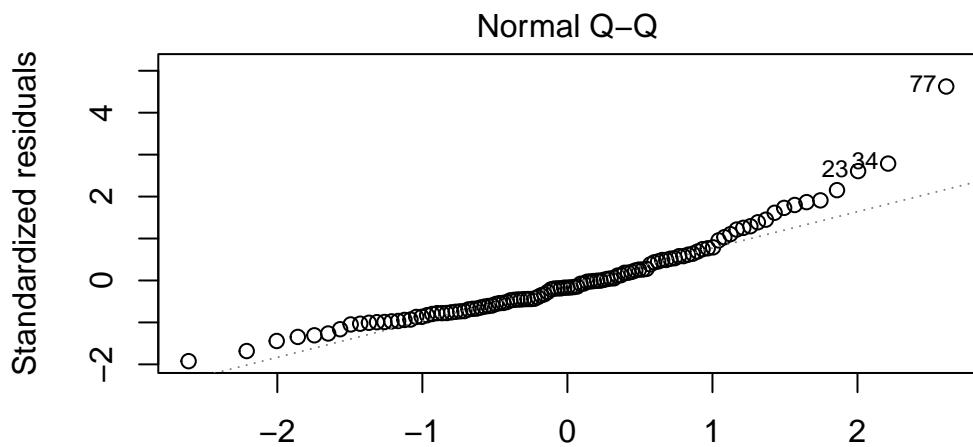
```
Coefficients: Estimate Std. Error t value Pr(>|t|)
(Intercept) -64.23208 23.04204 -2.788 0.00628 ** radiation 0.05980 0.02318 2.580 0.01124 *
temperature 1.65121 0.25341 6.516 2.43e-09 wind -3.33760 0.65384 -5.105 1.45e-06
radiation temperature wind ozone
Min. : 7.0 Min. :57.00 Min. : 2.300 Min. : 1.0
1st Qu.:113.5 1st Qu.:71.00 1st Qu.: 7.400 1st Qu.: 18.0
Median :207.0 Median :79.00 Median : 9.700 Median : 31.0
Mean :184.8 Mean :77.79 Mean : 9.939 Mean : 42.1
3rd Qu.:255.5 3rd Qu.:84.50 3rd Qu.:11.500 3rd Qu.: 62.0
Max. :334.0 Max. :97.00 Max. :20.700 Max. :168.0
```

$$\beta_0 = \beta_1$$

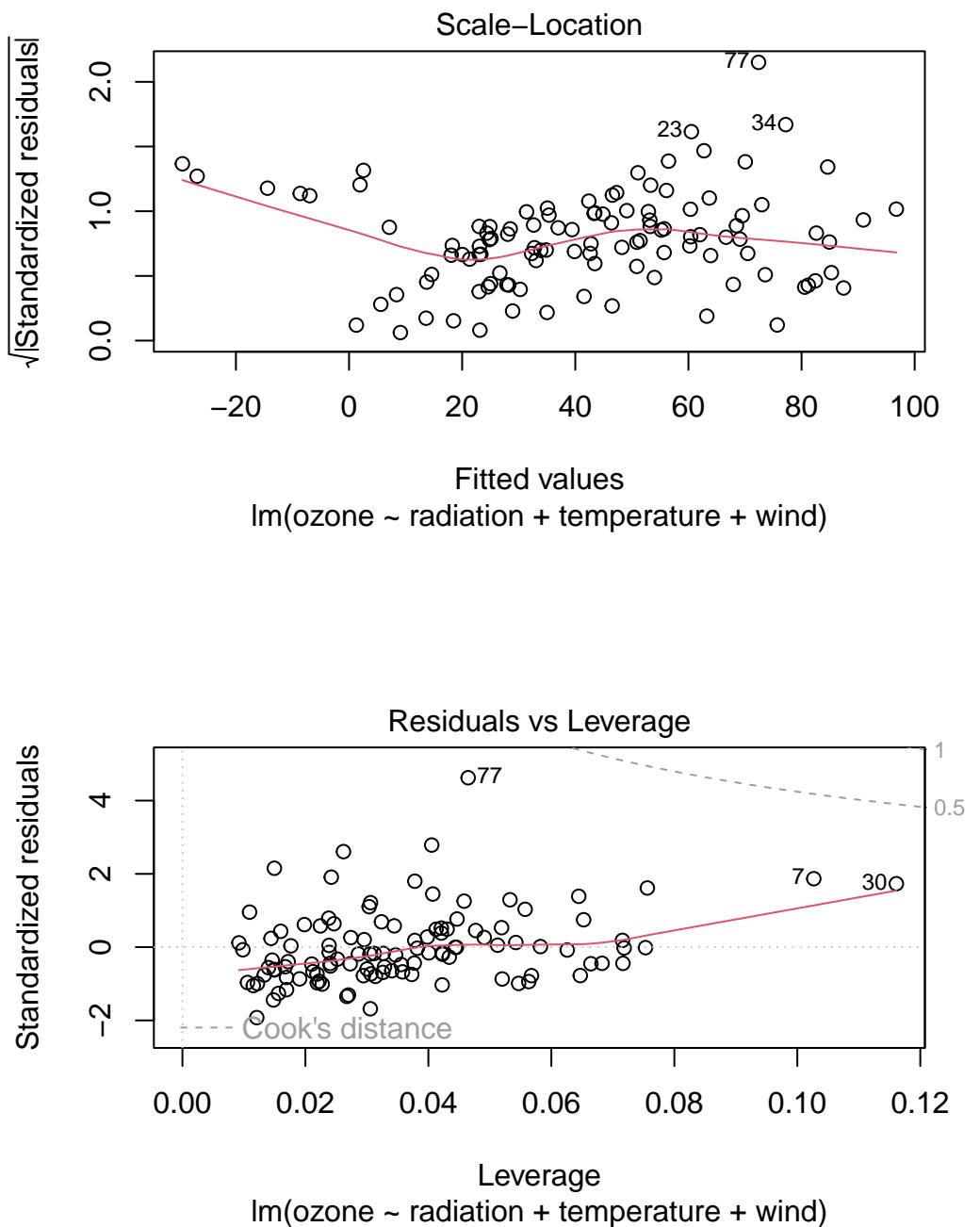
```
plot(model)
```



Fitted values  
 $\text{Im}(\text{ozone} \sim \text{radiation} + \text{temperature} + \text{wind})$



Theoretical Quantiles  
 $\text{Im}(\text{ozone} \sim \text{radiation} + \text{temperature} + \text{wind})$



```
## a residual is the distance between our data points and our
## regression line
```

As observed here on Residuals vs Fitted graph

# # question 5 c)

```

## log(ozone) = 0 + 1 log(radiation) + 2 log(temperature) + 3
## log(wind) + i where i ~ N(0, 2) 0 = intercept

modelLogFriend = lm(log(ozone) ~ log(radiation) + log(temperature) + log(wind),
                     data = ozone)

summary(modelLogFriend)

```

Call:

```
lm(formula = log(ozone) ~ log(radiation) + log(temperature) +
   log(wind), data = ozone)
```

Residuals:

Min	1Q	Median	3Q	Max
-1.63961	-0.30073	-0.00097	0.34414	1.11545

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	-10.55570	2.08818	-5.055	1.79e-06 ***
log(radiation)	0.30500	0.05868	5.198	9.73e-07 ***
log(temperature)	3.20478	0.46019	6.964	2.79e-10 ***
log(wind)	-0.66305	0.13751	-4.822	4.74e-06 ***

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 0.4907 on 107 degrees of freedom

Multiple R-squared: 0.6876, Adjusted R-squared: 0.6788

F-statistic: 78.49 on 3 and 107 DF, p-value: < 2.2e-16

```
summary(model)
```

Call:

```
lm(formula = ozone ~ radiation + temperature + wind, data = ozone)
```

Residuals:

Min	1Q	Median	3Q	Max
-40.485	-14.210	-3.556	10.124	95.600

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	-64.23208	23.04204	-2.788	0.00628 **
radiation	0.05980	0.02318	2.580	0.01124 *
temperature	1.65121	0.25341	6.516	2.43e-09 ***
wind	-3.33760	0.65384	-5.105	1.45e-06 ***

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 21.17 on 107 degrees of freedom

Multiple R-squared: 0.6062, Adjusted R-squared: 0.5952

F-statistic: 54.91 on 3 and 107 DF, p-value: < 2.2e-16