

Solution of Exam 2

Problem 1 Answer: E

Problem 2 Answer: B

Details ① note that $x^* = 0$ is a global minimizer of a function $\phi: \mathbb{R} \rightarrow \mathbb{R}$ of the form $\phi(x) = f(x) + x_+$ (where $f: \mathbb{R} \rightarrow \mathbb{R}$ is a convex, continuously differentiable function) only if

$$\dot{\phi}(0^-) = \lim_{x \rightarrow 0^-} \dot{\phi}(x) \leq 0 \quad \text{and} \quad \dot{\phi}(0^+) = \lim_{x \rightarrow 0^+} \dot{\phi}(x) \geq 0$$

To see why, suppose, for example, that $\dot{\phi}(0^-) > 0$, then ϕ would be increasing when approaching $x^* = 0$ from the left — that invalidates $x^* = 0$ being a minimum. Similarly, suppose $\dot{\phi}(0^+) < 0$, then ϕ would be decreasing when departing from $x^* = 0$ to the right — that invalidates $x^* = 0$ being a minimum.

$$\textcircled{2} \text{ In our case, } \phi(x) = \underbrace{e^{x-a} + e^{-x} + x^2 - 2x}_{f(x)} + x_+.$$

Thus, $x^* = 0$ minimizes ϕ when

$$\dot{\phi}(0^-) \leq 0 \quad \text{and} \quad \dot{\phi}(0^+) \geq 0 \iff f'(0) \leq 0 \quad \text{and} \quad f'(0) + 1 \geq 0$$

$$\iff e^{-a} - 3 \leq 0 \quad \text{and} \quad e^{-a} - 2 \geq 0$$

$$\iff 2 \leq e^{-a} \leq 3$$

$$\iff \underbrace{-\log 3}_{\substack{1.2 \\ -1.1}} \leq a \leq \underbrace{-\log 2}_{\substack{1.2 \\ -0.7}}$$

The only number a in $\{-2, -1, 0, 1, 2, 3\}$ that satisfies the inequalities above is $a = -1$

Problem 3 Answer: C

Details ① The gradient descent algorithm is $x_{k+1} = x_k + \alpha_k d_k$, where $\alpha_k > 0$ is the step size and $d_k = -\nabla f(x_k)$

② For $x_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, we have $\nabla f(x_0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$. Thus, for the step size $\alpha_0 = 1$, we have $x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} + (1) \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

Problem 4

First, note that $f(r) = r^T D r = \|D^{1/2} r\|_2^2$, where $D^{1/2} = \begin{bmatrix} d_1^{1/2} & & \\ & d_2^{1/2} & \\ & & \ddots \\ & & & d_n^{1/2} \end{bmatrix}$

Now: $\min_{s, v} \|s - \bar{s}\|_2^2 + f(v)$ \Leftrightarrow $\min_s \|s - \bar{s}\|_2^2 + f(y - As)$
 s.t. $y = As + v$
 use the constraint to eliminate the variable v : $v = y - As$

$$\Leftrightarrow \min_s \|s - \bar{s}\|_2^2 + \|D^{1/2} (As - y)\|_2^2$$

use the identity: $\|A_1 s - b_1\|_2^2 + \|A_2 s - b_2\|_2^2 = \left\| \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} s - \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \right\|_2^2$

$$\min_s \left\| \underbrace{\begin{bmatrix} I \\ D^{1/2} A \end{bmatrix}}_{\mathcal{A}} s - \underbrace{\begin{bmatrix} \bar{s} \\ D^{1/2} y \end{bmatrix}}_{\beta} \right\|_2^2$$

Problem 5

$$\begin{array}{ll} \max_{x_1, x_2} & f(x_1, x_2) \\ \text{s.t.} & x_1 + x_2 = 1 \end{array} \quad \Leftrightarrow \quad \begin{array}{ll} \max_{x_1} & f(x_1, 1-x_1) \end{array}$$

use the constraint to eliminate the variable x_2 : $x_2 = 1 - x_1$

$$\Leftrightarrow \max_{x_1} \underbrace{\frac{1}{2} a x_1^2 + b x_1 (1-x_1) + \frac{1}{2} a (1-x_1)^2}_{g(x_1)}$$

$$g(x_1) = (a-b)x_1^2 + (b-a)x_1 + \frac{1}{2}a$$

↓
because $b > a$, this is a parabola that looks like this



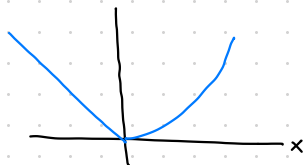
thus, the global maximizer occurs at the stationary point: $g'(x_1^*) = 0 \Leftrightarrow x_1^* = 1/2$

Because $x_2^* = 1 - x_1^* = 1/2$, the global maximizer of f (under the constraint $x_1 + x_2 = 1$) is

$$\begin{bmatrix} x_1^* \\ x_2^* \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$$

Problem 6

- ① First, note that $g: \mathbb{R} \rightarrow \mathbb{R}$ is convex! this can be obtained directly from its graph:



② The given problem is

$$\begin{aligned} \min_x \quad & \underbrace{g(x_1 - c_1) + \dots + g_n(x_n - c_n)}_{f(x)} \\ \text{s.t.} \quad & Ax = b, \end{aligned}$$

where

$$A = \begin{bmatrix} a_1 & a_2 & \dots & a_n \end{bmatrix}$$

③ The constraints are linear. Thus, the problem is convex if f is convex

④ $f = f_1 + f_2 + \dots + f_n$ where $f_i: \mathbb{R}^n \rightarrow \mathbb{R}$, $f_i(x) = g(x_i - c_i)$, for $1 \leq i \leq n$

f_i is convex because $f_i = g \circ h_i$, where $h_i(x) = \begin{bmatrix} 0 & \dots & 1 & \dots & 0 \end{bmatrix} x - c_i$ is an affine map, and g is convex

f is convex because it is the sum of convex functions

Problem 7

① We start by obtaining a closed-form expression for $f(x)$, for fixed $x \in \mathbb{R}$:

$$\begin{aligned} f(x) &= \max \{ \| (a+u)x - b \|_2 : \|u\|_2 = r \} \\ &= \max \{ (\|ax - b + ux\|_2^2)^{1/2} : \|u\|_2 = r \} \\ &= \max \{ (\|ax - b\|_2^2 + \|u\|_2^2 x^2 + 2u^T (ax - b)x)^{1/2} : \|u\|_2 = r \} \\ &= \max \{ (\|ax - b\|_2^2 + r^2 x^2 + 2u^T (ax - b)x)^{1/2} : \|u\|_2 = r \} \\ &= (\|ax - b\|_2^2 + r^2 x^2 + 2 \max \{ u^T (ax - b)x : \|u\|_2 = r \})^{1/2} \\ &= (\|ax - b\|_2^2 + r^2 x^2 + 2r|x| \|ax - b\|_2)^{1/2} \\ &= ((\|ax - b\|_2 + r|x|)^2)^{1/2} \end{aligned}$$

$$= \underbrace{\|ax-b\|_2}_{f_1(x)} + \underbrace{r|x|}_{f_2(x)}$$

② f_1 is convex because $f_1 = g \circ h$, where $h(x) = ax - b$ is an affine map and $g = \|\cdot\|_2$ is convex.

f_2 is convex because $f_2 = |\cdot|$

f is convex because $f = f_1 + r f_2$ is a nonnegative combination of convex functions.