

In this chapter we will introduce some key concepts that will be used in later chapters.

Note 0.1 In case you are already familiar with the topics

It is recommended for readers who are familiar with the topics to at least gloss! over this chapter and make sure they know and understand all the concept presented here.

0.1 MATHEMATICAL SYMBOLS AND SETS

LOGICAL STATEMENTS AND THEIR TRUTH VALUE

We start our discussion with the simplest mathematical concept: a **proposition**. A proposition is simply a statement that might be either **true** or **false**.

Example 0.1 Truth of propositions

- 3 > 1 (true)
- -2 = 5 7 (true)
- 7 < 5 (**false**)
- The radius of the earth is bigger than that of the moon. (true)
- The word 'House' starts with the letter 'G'. (false)



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The AND operator returns a true statement only if **both** the statements it groups are themselves true, otherwise it returns **false**.

Example 0.2 The AND operator

logical operators are AND and OR.

- 2+4=6 is true, 4-2=2 is true. (2+4=6 AND 4-2=2) is therefore true.
- 2+4=6 is true, 2>6 is false. (2+4=6 AND 2>6) is therefore false.
- $\frac{10}{2} = 1$ is **false**, $2^4 = 16$ is **true**. $(\frac{10}{2} = 1 \text{ AND } 2^4 = 16)$ is therefore **false**.
- 7 < 5 is false, 10 + 2 = 13 is false. (7 < 5 AND 10 + 2 = 13) is therefore false.

The **OR** operator returns **true** if **at least** one of the statements it groups is true.

Example 0.3 The OR operator

- 2+4=6 is true, 4-2=2 is true. (2+4=6 OR 4-2=2) is therefore true.
- 2 + 4 = 6 is true, 2 > 6 is false. (2 + 4 = 6 OR 2 > 6) is therefore true.
- $\frac{10}{2} = 1$ is false, $2^4 = 16$ is true. $(\frac{10}{2} = 1 \text{ OR } 2^4 = 16)$ is therefore true.
- 7 < 5 is false, 10 + 2 = 13 is false. (7 < 5 OR 10 + 2 = 13) is therefore false.

The behaviour of both operators can be summarized using a truth table (see Table 0.1 below).

Table 0.1 The truth table for the operators **AND** and **OR**.

A	В	A AND B	A OR B
true	true	true	true
true	false	false	true
false	true	false	true
false	false	false	false

When writing, it is convinient to use **notations** to represent operators: the **AND** operator is denoted by \land , while the **OR** operator is denoted by \lor .

Example 0.4 Using the notations for AND and OR

$$(2+2=5) \land (1-1=0) \Rightarrow \text{false}$$

$$(2+2=5) \lor (1-1=0) \Rightarrow \text{true}$$

$$\text{false}$$

$$(2+2=5) \lor (1-1=0) \Rightarrow \text{true}$$

COMMON MATHEMATICAL NOTATIONS

Several more common mathematical notations are given in Table 0.2.

Table 0.2 Common Mathematical NotationsUsed in this Book.

Symbol	In words
$\neg a$	not a
$a \wedge b$	a and b
$a \lor b$	a or b
$a \Rightarrow b$	a implies b
$a \Leftrightarrow b$	a is equivalent to b
$\forall x$	For all x ()
$\exists x$	There exists x such that $()$
a := b	a is defined to be b

The notation \Rightarrow need a bit of clarification: implication means that we can directly derive a proposition from another proposition. For example, if x = 3 then x > 2. The opposite implication can be a **false** statemt, i.e. for the example above x > 2 does not imply x = 3 (denoted as $x > 2 \Rightarrow x = 3$). Sometimes implication is expressed by using the word if: in the above example x > 2 if x = 3, but the other way around is not **true**.

We say that two propositions are **equivalent** when they imply each other. For example: x = 2 implies that $\frac{x}{2} = 1$, while $\frac{x}{2} = 1$ implies that x = 2. We can write this as

$$\frac{x}{2} = 1 \Leftrightarrow x = 2.$$

Instead of the word *equivalent*, the phrase *if and only if* (sometimes shortened to **iff**) is commonly used, e.g.

$$x = 2 \text{ iff } \frac{x}{2} = 1.$$

SETS AND SUBSETS

The concept of sets is perhaps one of the most basic ideas in modern mathematics. Much of the material convered in this book will be built upon sets and their properties. However, as with the rest of the material presented here - our description of sets will not be thorough nor percise.

For our purposes, a set is a collection of elements. These elements can be any concept - be it physical (a chair, a bicycle, a tapir) or abstract (a number, an idea). However, we will consider only sets comprised of numbers. Sets can have finite of infinite number of elements in them.

We denote sets by using curly brackets, and if the number of elements in them is not too big - we display the elements, separated by commas, inside the brackets. In other cases we can express the sets as a sentence or a mathematical proposition.

Example 0.5 Simple sets

 $\{1, 2, 3, 4\}$ $\left\{-4, \frac{3}{7}, 0, \pi, 0.13, -2.5, \frac{e}{3}, 2^{-\pi}\right\}$ {all even numbers}

Sets have two important properties:

- 1. Elements in a set do not repeat.
- 2. The order of elements in a set does not matter.

Example 0.6 Important set properties

Examples demonstrating the two afforementioned important properties of sets:

1. The following is not a proper set:

$$\{1, 1, 0, 1, 0, 0, -1, 0, 0, -1, -1, 1\}$$

2. The following sets are all identical:



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 $\{1,2,3,4\}$ $\{1,3,2,4\}$ $\{3,4,1,2\}$ $\{1,3,2,4\}$

 $\{4, 3, 2, 1\}$

Sets can be denoted using conditions, with the symbol | representing the phrase "such that".

Example 0.7 Defining a set using a condition

he following set contains all the odd whole numbers between 0 and 10, including both:

$$\{0 < x < 10 \mid x \text{ is an odd number}\}.$$

The definition of this set can be read as

all numbers x that are bigger than 0 and are smaller than 10, such that x is odd.

(note that the requirement of *x* to be an odd number means that it is neccessarily a whole number as well)

This set can be written explicitly as



$$\{1,3,5,7,9\}.$$

Sets are usually denoted with an uppercase latin letter (A, B, C, ...), while their elements are denoted as lowercase letters $(a, b, \alpha, \phi, ...)$. When we want to denote that an element belongs to a set we use the following symbol: \in . Conversly, \notin is used to denote that an element *does not* belong to a set.

Example 0.8 Elements in sets

For the two sets

$$A = \{1, 2, 5, 7\}, B = \{\text{even numbers}\},\$$

all the following propostions are true:

$$1 \in A$$
, $2 \in A$, $5 \in A$, $7 \in A$, $2 \in B$, $1 \notin B$, $5 \notin B$, $7 \notin B$.



The number of elements in a set, also called its **cardinality** is denoted using two vertical bars (similar to the way absolute values are denoted).

Example 0.9 Cardinality



For
$$S = \{-3, 0, -2, 7, 1, \frac{1}{2}, 5\}, |S| = 7.$$

An important special set is the **empty set**, which is the set containing no elements. It is denoted by \emptyset , and has the unique property that $|\emptyset| = 0$.

INTERSECTION, UNION, DIFFERENCE AND COMPLEMENT SETS

Two sets are equal if they both contain the exact same elements and only these elements, i.e.

$$A = B \Longleftrightarrow x \in A \Leftrightarrow x \in B. \tag{0.1}$$

This proposition reads 'The sets A and B are equal $\underbrace{if\ and\ only\ if}$ any element x in A is also in B, and any element x in B is also in A'. When all the elements of a set B are also elements of another set A, we say that B is a **subset** of A, and we denote that as $B \subset A$. In mathematical notation, we write

$$B \subset A \Leftrightarrow \forall x \in B, x \in A. \tag{0.2}$$

i.e. B is a subset of A iff the following is true: any element in B is also an element in A.

Note 0.2 (not so) Surprising properties of subsets

The definion of a subset (Equation 0.2) gives rise to two interesting properties:

- The empty set ∅ is a subset of any set.
- Any set is a subset of itself.

Note 0.3 The uniqueness of ∅

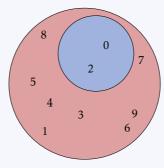
There is only a single empty set, as any set that has no elements is equivalent to any other set with no elements (i.e. they have the same elements). Due to the way subsets are defined, the empty set is a subset of any set (including itself!).

Of course, since we have a definition for a subset, the opposite concept also exists: if *B* is a subset of *A*, then we say that *A* is a **superset** of *B*.

A very useful way of illustrating the relationship between two or more sets is by using **Venn diagrams**, where sets are represented by circles (or other 2D shapes).

Example 0.10 Subsets and Venn diagrams

A Venn diagram depicting the set $B = \{0, 2\}$ as a subset of $A = \{0, 1, 2, 3, 4, \dots, 9\}$:





!

If for two sets A, B both $A \subset B$ and $B \subset A$, then A = B. We can write this fact as a methematical proposition:

$$(A \subset B) \land (B \subset A) \Leftrightarrow A = B. \tag{0.3}$$

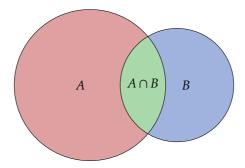
The **intersection** of two sets *A* and *B*, denoted $A \cup B$, is the set of all elements *x* such that $x \in A$ **AND** $x \in B$:

$$A \cup B = \{x \mid x \in A \land x \in B\}. \tag{0.4}$$

Example 0.11 Intersection of sets

The intersection of the sets $A = \{1, 2, 3, 4\}$ and $B = \{3, 4, 5, 6\}$ is the set $A \cup B = \{3, 4\}$. \bigcirc The intersection of the sets $C = \{0, 1, 2, 6, 7\}$ and $D = \{3, 9, -4, 5\}$ is the empty set \emptyset , since no element is in both sets.

The following Venn diagram depicts the intersection of two sets (the green area):



Note 0.4 Disjoint sets

When the intersection of two sets is the empty set, we say that the set is disjoint.

The union of two sets (denoted using the symbol \cup) is the set composed of all the elements that belong to any of the sets, including elements that are in both sets:

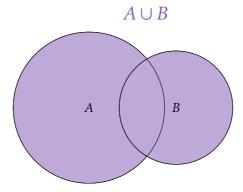
$$A \cup B = \{x \mid x \in A \lor x \in B\}. \tag{0.5}$$

Example 0.12 Union of sets

The union of the sets $A = \{1, 2, 3, 4\}$ and $B = \{3, 4, 5, 6\}$ is the set $A \cup B = \{1, 2, 3, 4, 5, 6\}$.

The union of the sets $C = \{0,1,2,6,7\}$ and $D = \{3,9,-4,5\}$ is the set $C \cup D = \{0,1,2,3,-4,5,6,7,9\}$.

The following Venn diagram depicts the union of two sets (the purple area):



Naively, the number of elements of a union $A \cup B$ is simply the sum of the number of elements in A and the number of elements in B. However, this naive approach might count the elements in both sets twice: once for A and once for B (see Figure 0.1) - this is exactly the set $A \cap B$. We therefore subtract the number of elements in $A \cap B$ and get

$$|A \cup B| = |A| + |B| - |A \cap B|.$$
 (0.6)

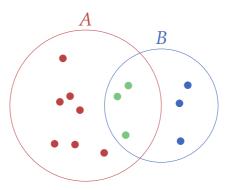


Figure 0.1 Counting the number of elements in the union of two sets: *A* has 10 elements (red + green dots), while *B* has 6 elements (blue + green dots). If we count both we get 16 elements, but this counts the joint elements (green dots) twice. Therefore we should subtract the number of joint points, and get that there are only 13 elements in the union.

When two sets A, B are disjoint, then $|A \cap B| = 0$, and so $|A \cup B| = |A| + |B|$.

The definitions of intersections and unions can be easily extended to any whole number of sets.

Example 0.13 Intersection and union of 3 sets

The intersection of 3 sets $A = \{1, 2, 3, 4, 5\}$, $B = \{-2, -1, 0, 1, 2\}$ and $C = \{2, 3, 4, 5, 6\}$ is the set of all elements that are in A and in B and in C, i.e. the set $A \cap B \cap C = \{2\}$. The union of these sets is the set of all elements that are in either of the sets, i.e. $A \cup B \cup C = \{-2, -1, 0, 1, 2, 3, 4, 5, 6\}$.

The most general definition of an intersection of n sets (where n is a whole number), which we will call $A_1, A_2, A_3, \dots, A_n$ is

$$A_1 \cap A_2 \cap A_3 \cap \dots \cap A_n = \{x \mid (x \in A_1) \land (x \in A_2) \land (x \in A_3) \land \dots \land (x \in A_n)\}. \tag{0.7}$$

the left hand side of Equation 0.7 can be written as

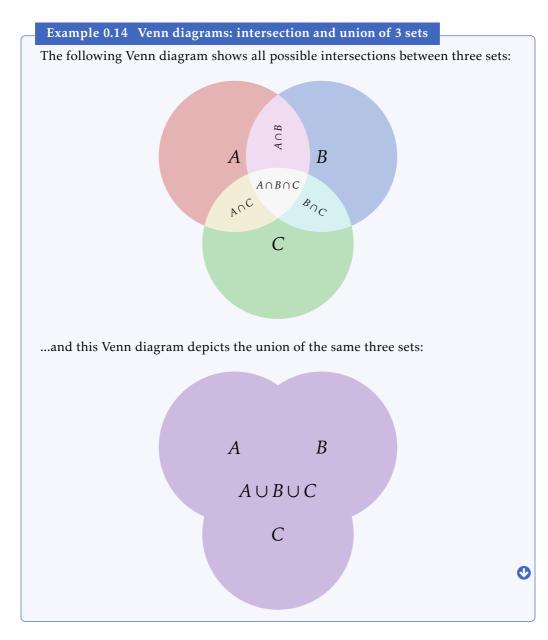
$$A_1 \cap A_2 \cap A_3 \cap \dots \cap A_n = \bigcap_{i=1}^n A_i. \tag{0.8}$$

(clarifying the notation? i.e. indexing, etc.)

Similarly, the union of n different sets is defined as

$$\bigcup_{i=1}^{n} A_{i} = A_{1} \cup A_{2} \cup A_{3} \cup \dots \cup A_{n}$$

$$= \{x \mid (x \in A_{1}) \lor (x \in A_{2}) \lor (x \in A_{3}) \lor \dots \lor (x \in A_{n})\}. \tag{0.9}$$



TBW: difference, complement.

Given a set A with |A| elements - how many different subsets does it have? We'll start by looking at a practical example: $A = \{1, 2, 3\}$. We can immidetly see that any set which contains just one of the elements of A is a subset of A, i.e. $\{1\},\{2\},\{3\}$ are all subsets of A. In addition, any set which contains only two elements from A is a subset of A, i.e. $\{1,2\},\{1,3\},\{2,3\}$. Of course, we must not forget the empty set and A itself - both subsets of A (see Note 0.2). Thus altogether A has 8 subsets:

Generaly, any set A with |A| elements has $2^{|A|}$ different subsets. The set of all these subsets is called the **power set** of A, and is denoted as P(A).

Example 0.15 Power set

The power set of $A = \{1, 2, 3\}$ is



$$P(A) = \{\emptyset, \{1\}, \{2\}, \{3\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, \{1, 2, 3\}\}.$$

IMPORTANT NUMBER SETS

It is now time to introduce some important number sets. We begin with the simplest of these sets: the **natural numbers**, denoted by \mathbb{N} . These are the numbers 1, 2, 3, 4, Adding the opposites to the natural numbers and adding 0 to the set yields the **integers**, denoted by \mathbb{Z} . Loosley speaking, we can define the integers as

$$\mathbb{Z} = \{0, \pm 1, \pm 2, \pm 3, \pm 4, \dots\}. \tag{0.10}$$

This makes the integers a superset of the natual numbers, i.e.

$$\mathbb{N} \subset \mathbb{Z}.\tag{0.11}$$

One can think of the integers as all the number needed for solving an equation of the form a + x = b, where a and b are integers themselves, and x is an unknown. No matter which integer values we put in a and b, the unknown x will always be an integer as well (whether it be positive, negative or zero depends on the values of a and b). However, when one wishes to solve an equation fo the sort ax = b, the integers are not longer sufficient: for example, if a = 2 and b = 1, then x is not an integer.

To solve ax = b (where $a, b \in \mathbb{Z}$) we must introduce the **rational numbers**: numbers with values that are ratios of two integers. We denote the set of rational numbers with the symbol \mathbb{Q} , and write

$$\mathbb{Q} = \left\{ \frac{a}{b} \mid a, b \in \mathbb{Z} \land b \neq 0 \right\}. \tag{0.12}$$

(TBW: discuss briefly why $b \neq 0$)

For some combinations of a and b the ratio $\frac{a}{b}$ is an integer. For example: $\frac{3}{1}$, $\frac{8}{4}$, $\frac{-2}{2}$. This makes the integers a subset of the rational numbers, i.e.

$$\mathbb{Z} \subset \mathbb{Q}. \tag{0.13}$$

About 2500 years ago it was discovered that some numbers are not rational (and thus also not integers). The most famous example is the number $\sqrt{2}$ - there are not two integers a, b such that $\frac{a}{b} = \sqrt{2}$. We call some of these numbers algebraic numbers (denoted by \mathbb{A}), and what makes them special is that they are solutions to **polynomial equations**, which we will not define yet (see section xxx). Instead, here is an example for a 2nd order polynomial equation (called a **quadratic equation**):

$$x^2 - 2x - 1 = 0. (0.14)$$

Similar to what we saw before, the rational numbers are a subset of the algebraic numbers, i.e.

$$\mathbb{Q} \subset \mathbb{A}. \tag{0.15}$$

The algebraic numbers together with other non-rational numbers, such as π and e, form the set of **real numbers**, denoted as \mathbb{R} . The definition of real numbers is way beyond the scope of this book, but it is important to understand that the progression we used so far still holds, i.e.

$$\mathbb{A} \subset \mathbb{R}. \tag{0.16}$$

The final set of numbers we will touch upon here is the set of **complex numbers**, denoted \mathbb{C} , which we can define as

$$\mathbb{C} = \left\{ a + ib \mid a, b \in \mathbb{R}, \ i = \sqrt{-1} \right\}. \tag{0.17}$$

When b = 0, Equation 0.17 becomes just a single real number - and so

$$\mathbb{R} \subset \mathbb{C}.\tag{0.18}$$

(chapter xxx is dedicated to complex numbers)

Equations 0.11-0.18 can be merged together to the following single equation:

$$\mathbb{N} \subset \mathbb{Z} \subset \mathbb{Q} \subset \mathbb{A} \subset \mathbb{R} \subset \mathbb{C}. \tag{0.19}$$

There are more advanced constructions that generalize the complex numbers (i.e. create supersets of the complex number set). These include **quaternions** and **Clifford algebras**. However, as stated before, we will not consider them in this book.

INTERVALS ON THE REAL NUMBER LINE

An important concept that is easily defined over the set \mathbb{R} is an **interval**. A **closed interval** [a, b] is a subset of \mathbb{R} which is defined as

$$[a,b] = \{x \in \mathbb{R} \mid a \le x \le b\}.$$
 (0.20)

An open interval (a, b) is a subset of \mathbb{R} which is defined as

$$(a,b) = \{ x \in \mathbb{R} \mid a < x < b \}. \tag{0.21}$$

The difference between closed and open intervals is the inclusion and exclusion, respectively, of the edge point: in a closed interval the points *a*, *b* are included, while they are not included in an open interval. Of course, we can also create half open intervals, i.e.

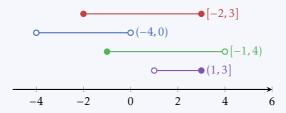
$$[a,b) = \{x \in \mathbb{R} \mid a \le x < b\},\$$

$$(a,b] = \{x \in \mathbb{R} \mid a < x \le b\},\$$
(0.22)

where the first interval includes a but not b, and the second interval includes b but not a.

Example 0.16 Intervals

Intervals can be drawn as colored line segments on top of the real number line:



Note how a full point denotes a closed edge, while an empty point denotes an open edge.

In some cases, it is necessary to use intervals that are infinite in one side, i.e. the left or the right edge are at infinity. In these cases, we use the symbol ∞ to denote infinity, and always keep the interval open at that end:

$$(-\infty, b) = \{x \mid x < b\},\$$

$$(-\infty, b] = \{x \mid x \le b\},\$$

$$(a, \infty) = \{x \mid x > a\},\$$

$$[a, \infty) = \{x \mid x \ge a\}.$$
(0.23)

CARTESIAN PRODUCTS

The **Cartesian product** of two sets A, B (denoted $A \times B$) is the set of all possible **ordered** pairs, where the first component is an element of A and the second component is an element of B:

$$A \times B = \{(a, b) \mid a \in A, b \in B\}.$$
 (0.24)

Example 0.17 Cartesian products

Consider $A = \{1, 2, 3\}, B = \{x, y\}.$ Then



$$A \times B = \{(1, x), (1, y), (2, x), (2, y), (3, x), (3, y)\}$$

The concept of 'ordered pairs' is paramount: if we reverse the order of the elements in a pair the result might not be in the Cartesian product. We therefore say that the Cartesian product is **not commutative**.

Example 0.18 Non-commutivity of the Cartesian product

The elements (x, 1), (y, 1), (x, 2) and so on **are not** in the Cartesian product $A \times B \heartsuit$ as defined in the previous example, since in each one of the pairs the first element is from B and the second element is from A.

The number of elements in a Cartesian product is the product of the number of elements in each of the sets it is composed of, i.e.

$$|A \times B| = |A| \cdot |B|. \tag{0.25}$$

Example 0.19 Number of elements in a Cartesian product



The Cartesian product described in the previous two examples has in total $3 \cdot 2 = 6$ elements, as seen in **Example 0.17**.

As with intersections and unions, the definition of a Cartesian product can be expanded into any natural number of sets:

$$A_1 \times A_2 \times \dots \times A_n = \{(x_1, x_2, \dots, x_n) \mid x_1 \in A_1, x_2 \in A_2, \dots, x_n \in A_n\}. \tag{0.26}$$

Example 0.20 Cartesian product of three sets

The Cartesian product of the sets $A = \{1, 2, 3\}$, $B = \{x, y\}$, $C = \{\alpha, \beta\}$ is

$$A \times B \times C = \{(1, x, \alpha), (1, x, \beta), (1, y, \alpha), (1, y, \beta)$$

$$(2, x, \alpha), (2, x, \beta), (2, y, \alpha), (2, y, \beta)$$

$$(3, x, \alpha), (3, x, \beta), (3, y, \alpha), (3, y, \beta)\}.$$

A special case of Cartesian products are those products for which all the sets composing them are the same set. We denote these as the respective integer power, for example the Cartesian product $\mathbb{R} \times \mathbb{R}$ is denoted as \mathbb{R}^3 , etc.

Specifically, the Cartesian product \mathbb{R}^2 can be interpreted as the two-dimensional Euclidean space, which is the space used to draw graphs in one-dimensional calculus and shapes in two-dimensional analytican geometry. We will explore this idea (and higher dimensional spaces) in more details in upcoming chapters.

0.2 RELATIONS AND FUNCTIONS

BASICS

Cartesian products of two sets can be viewed as describing all possible connections between the elements of the first set to the elements of the second set, and thus any subset of a Cartesian product forms a specific **relation** between the sets.

Example 0.21 Relations as subsets of Cartesian products

Given the following two sets:

$$A = \{1, 2, 3, 4\}, B = \{\alpha, \beta, \gamma\},\$$

then

$$A \times B = \{(1, \alpha), (1, \beta), (1, \gamma),$$

$$(2, \alpha), (2, \beta), (2, \gamma),$$

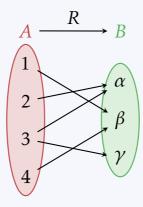
$$(3, \alpha), (3, \beta), (3, \gamma),$$

$$(4, \alpha), (4, \beta), (4, \gamma)\}.$$

We can choose the following pairs to form a subset of $A \times B$:

$$R = \{(1, \beta), (2, \alpha), (3, \alpha), (3, \beta), (4, \gamma)\}.$$

R is thus a relation between *A* and *B*. We can graphically illustrate *R* as follows:



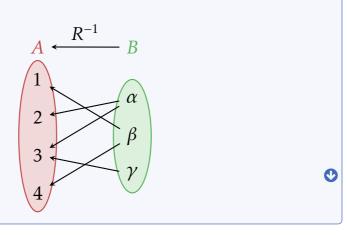
Relations can be inversed by reversing the order of each of its pairs.

Example 0.22 Inverse relation

The inverse relation to the relation in Example 0.21 is

$$R^{-1} = \{(\beta, 1), (\alpha, 2), (\alpha, 3), (\beta, 3), (\gamma, 4)\}.$$

Graphically:

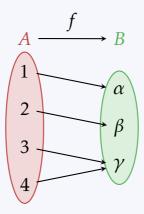


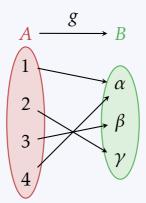
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A **function** f from a set A to a set B is a relation for which any element in A is connected to a single element in B.

Example 0.23 Functions

The following are two functions from the set *A* to the set *B* defined in **Example** 0.21:





The pairs making up f are $(1, \alpha)$, $(2, \beta)$, $(3, \gamma)$ and $(4, \gamma)$, and the pairs making up g are $(1, \alpha)$, $(2, \gamma)$, $(3, \beta)$ and $(4, \alpha)$.

Note 0.5 Relations which are not functions

Note that the relation in **Example 0.21** is **not** a function, since the element $3 \in A$ is connected to more than one element in B, namely α and γ .

Different names are used in some branches of mathematics to describe functions, such as maps and transformations. Baring context, they all mean the same thing.

A common way to denote that a function f is connecting elements in A to elements in B is

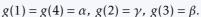
$$f: A \to B. \tag{0.27}$$

A is called the **domain** of f, and B its **image**. In this book and many other sources, the following notation is used: f(x) = y, which means that when we apply the function f to an element $x \in A$, the result is the element it is connected to, i.e. $y \in B$. We write this as $x \mapsto y$ (the special symbol \mapsto is called a **mapping notation**).

Example 0.24 Value \mapsto value notation for functions

For the functions f, g as defined in Example 0.23:

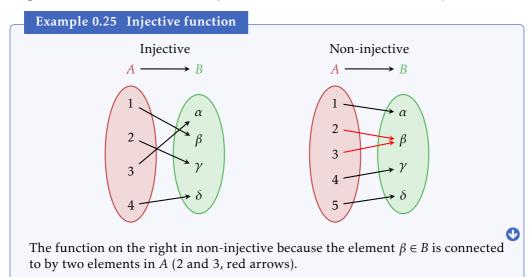
$$f(1) = \alpha$$
, $f(2) = \beta$, $f(3) = f(4) = \gamma$.





INJECTIVE, SURJECTIVE AND BIJECTIVE FUNCTIONS

A function is **injective** if each of the elements in its **image** is connected to by at most a single element in its **domain**. An injective function is also known as an **injection**.



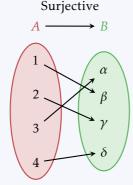
A function is **surjective** if every element in its image is connected to by at least a single element in its domain (see **Example 0.26**). As with injective functions, a surjective function is also known as a **surjection**. A non surjective function can be made into surjective function by excluding from its image any element that is not connected to by any element from its domain (see **Example 0.27**).

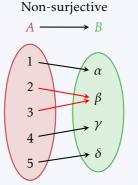
A function $f: A \to B$ that is both surjective and bijective is called a **bijective function** (also a **bijection**). All elements in the image of a bijection are connected to by exactly a single element in its domain. This means that the direction of the connections can be flipped, yielding the **inverse** of the original function (denoted f^{-1}).

The reason only bijective functions have inverses is as follows: Given a function $f: A \rightarrow B$,

- if f is non-injective, then there is at least one element $y_1 \in B$ which is connected to by at least two elements from A. We can name these elements x_1 and x_2 . When inverted, $f^{-1}: B \to A$ has an element $y_1 \in B$ (note that for f^{-1} , B is its domain), which is connected to two or more elements in A, the image of f^{-1} . These are of course x_1, x_2 . This fact disqualifies f^{-1} from being a function.
- If f is non-surgetive, then there exists at least one element $y_2 \in B$ that is not connected to by any element from A. When inverted, y_2 in the domain B of f^{-1} is not connected to any element in its image A. This fact disqualifies f^{-1} from being a function.

Example 0.26 Surjective function





•

Example 0.27 Making a non-surjective function into a surjection

Given the two sets $A = \{1, 2, 3, 4\}$ and $B = \{\alpha, \beta, \gamma, \delta\}$, the following non-surjective function $f : A \to B$ is defined:

$$f = \{(1,\alpha), \ (2,\beta), \ (3,\gamma), \ (4,\gamma)\}.$$



By removing δ from B, the function f becomes surjective (though it remains non-injective).

TBW: an example of all four possible combinations (injective non-surjective, surjective non-injective, bijective, non-injective non-surjective) and their inverses.

Note 0.6 Other names for bijections

Bijections are also called one-to-one correspondences and invertible functions.

REAL FUNCTIONS

In suitable cases, a function is defined via a general mapping rule. This should be very familiar to anyone who learned mathematics in highschool, where many times functions are defined this way, e.g.

$$f(x) = x^2 + 3x - 4. (0.28)$$

In mapping notation we can write Equation 0.28 as $f: x \mapsto x^2 + 3x - 4$. In highschool mathematics, both the domain and image of such functions is \mathbb{R} , although it is almost never specified explicitly. Such functions are commonly referred to as **real functions**, a convention used in this book as well.

Example 0.28 Functions defined using a mapping rule

The following are real functions:

$$f_1(x) = 2x^2 - 5$$
, $f_2(x) = \sin\left(\frac{x}{3}\right)$, $f_3(x) = \frac{1}{\sqrt{2\pi}}e^{-\frac{(x-\mu)^2}{\sigma^2}}$.

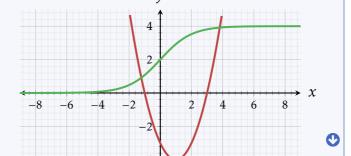
Note that these functions can also be defined using different sets, for example $f_1: \mathbb{N} \to \mathbb{Z}$, $f_2: \mathbb{N} \to [-1,1]$, etc.

Real functions can be easily plotted in a Cartesian coordinate system by drawing all the points (x, f(x)) (i.e. all the points (x, y), where $x, y \in \mathbb{R}$ and $x \mapsto y$). We call these points the graph of f over \mathbb{R} .



The following two functions are plotted on the domain [-9, 9]:

- $f(x) = x^2 2x 3$,
- $g(x) = 4e^x/(e^x+1)$.



In **Example 0.29**, the function g(x) always increases in value from left to right. Let's give this notion a more formal tone: a function f is said to be **increasing** on an interval I if for any $x_1, x_2 \in I$, if $x_2 > x_1$ then $f(x_2) > f(x_1)$. We can similarly define the idea of **decreasing** on an interval.

TBW: injections and surjections in real functions.

COMPOSITION OF FUNCTIONS

Functions can be **composed** together, generating new functions. Given two functions $f: A \to B$ and $g: B \to C$, their composition is denoted as $f \circ g$. For the composition to work, the **domain** of the g must be the same as the **image** of f, i.e. $f \circ g: A \to C$.

Example 0.30 Composition of functions

Consider the functions

$$f(x) = x^2$$
, $g(x) = \sin(x)$.

Using these functions, the two possible compositions are

•
$$f \circ g = f(g(x)) = [\sin(x)]^2$$
, and

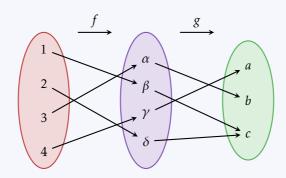


•
$$g \circ f = g(f(x)) = \sin(x^2)$$
.

Example 0.31 Graphical representation of function composition

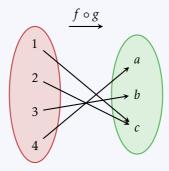
A graphical representation of composing two functions:

$$f: \{1, 2, 3, 4\} \rightarrow \{\alpha, \beta, \gamma, \delta\}, \quad g: \{\alpha, \beta, \gamma, \delta\} \rightarrow \{a, b, c\}.$$



The composition results in the following function

$$f \circ g : \{1, 2, 3, 4\} \rightarrow \{a, b, c, \}.$$





0.3 POLYNOMIAL FUNCTIONS

A very useful family of real functions can be derived using only three fundamental operations: addition, multiplication and exponentiation: the (real) **polynomial functions**. These are functions of the form

$$P_n(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots + a_n x^n, \tag{0.29}$$

where $a_0, a_1, ..., a_n$ are real numbers called the **coefficients** of the polynomial function. Note that $a_n \neq 0$, i.e. the **degree** of the polynomial function is the index of the highest non-zero coefficient (and thus the highest power in the expression). We also call this the **order** of the polynomial function.

Example 0.32 Polynomial

The following is a polynomial function of degree n = 6:

$$P(x) = 4 + 2x - 3x^2 + 7x^4 - x^5 + 3x^6.$$

Breaking down this polynomial to its constituent terms:

Note that a_3 is missing from the polynomial function (i.e. there is no x^3 term). This means that $a_3 = 0$.

A shorthand way to write the general form of a polynomial function is by using the summation notation:

$$P(x) = \sum_{k=0}^{n} a_k x^k. {(0.30)}$$

This notation, called the **Capital-sigma notation**, essentially represents addition of n elements (in the case shown here), each with its own **index of summation**, in this case i. The most general form of the summation notation is

$$\sum_{i=k}^{n} a_i = a_k + a_{k+1} + a_{k+2} + \dots + a_{n-1} + a_n,$$
(0.31)

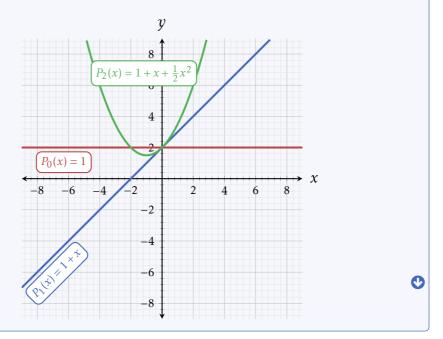
i.e. the notation tells us to add those elements a_i for which $k \ge i \ge n$. Note that in the case of Equation 0.30, when k = 0, $x^k = x^0 = 1$ and the first term of the polynomial function has no x power (i.e. it is simply a_0), and when k = 1, $x^k = x^1 = x$ and thus the second term is a_1x . We will encounter the summation notation in more details later in the book.

In the special case n = 0, i.e. when $P(x) = a_0$, the function is constant. When n = 1 the

function $P(x) = a_0 + a_1 x$ is a line, and when n = 2, $P(x) = a_0 + a_1 x + a_2 x^2$ is a quadratic function.

Example 0.33 Polynomial functions for n = 0, 1, 2

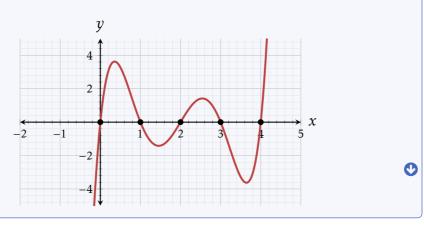
The following graphs represent the polynomial functions of degrees n = 0, 1, 2 with coefficients $a_0 = 2$, $a_1 = 1$, $a_2 = \frac{1}{2}$:



The values $x \in \mathbb{R}$ for which P(x) = 0 are called the **roots** (also: **zeros**) of the polynomial function.

Example 0.34 Roots of a polynomial function

The polynomial function $P(x) = 24x - 50x^2 + 35x^3 - 10x^4 + x^5$ has the following 5 roots: $x_0 = 0$, $x_1 = 1$, $x_2 = 2$, $x_3 = 3$, $x_4 = 4$. In the following graph of P(x) the roots are shown as black dots.



The maximum number of **real** roots of a polynomial function with degree $n \ge 1$ is n, e.g. a polynomial of degree n = 4 has at most 4 real roots. This statement is a consequence of a very important theorem called **the fundamental theorem of algebra**, which due to its importance we will mention here without proof:

Theorem 0.1 The fundamental theorem of algebra

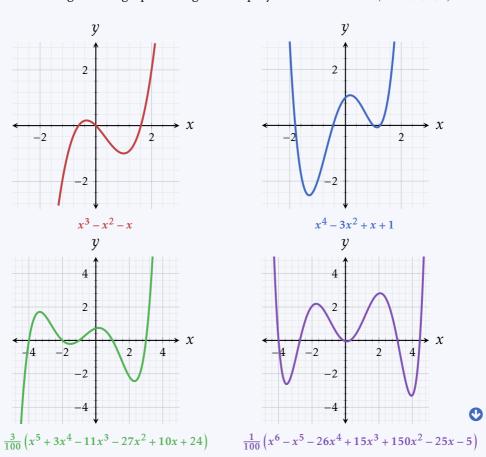
For any $n \ge 1$, the polynomial function $P(z) = a_0 + a_1 z + a_2 z^2 + \dots + a_n z^n$, where $a_0, a_1, a_2, \dots, a_n$ are all **complex numbers** and $a_n \ne 0$, has n complex roots.

Given a polynomial function P(x) with n roots r_1 , r_2 , \cdots , r_n , the function can be written as a product of terms of the form $x - r_i$ (up to a constant), e.g. the polynomial function of degree n = 3 with roots -1, 1, 2 can be written as

$$P(x) = (x+1)(x-1)(x-2) = x^3 - 2x^2 - x + 2.$$
(0.32)

Example 0.35 Higher order polynomial functions

The following are the graphs of high-order polynomial functions (n = 3, 4, 5, 6):



As can be seen in Example 0.35, the maximal number of 'bends' in a polynomial func-

tion of order n is n-1 (i.e. one less than the order of the function).

We will continue to explore polynomial functions in more details in future chapters.

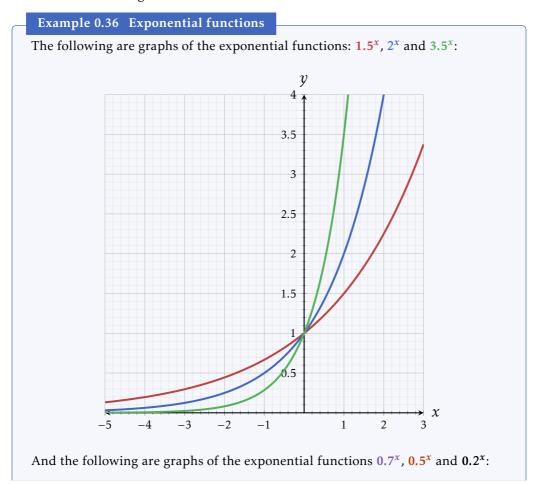
0.4 EXPONENTIAL AND LOGARITHMIC FUNCTIONS

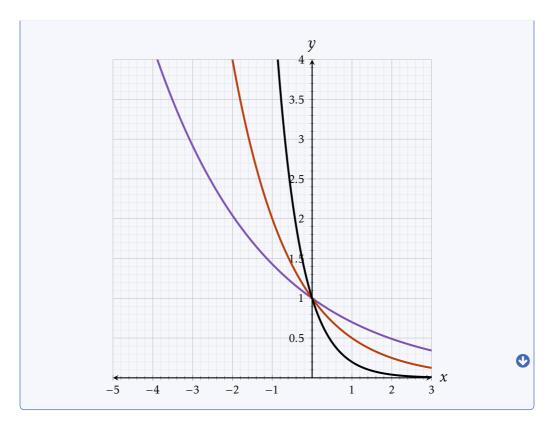
In the previous section we dealt with functions composed of integer powers of *x*. We will now shortly focus on functions where *x* is in the power itself and their inverse functions.

An exponential function is a real function of the type

$$f(x) = b^x, (0.33)$$

where b > 0 is called the **base** of the exponentiation, and x the exponent. All exponential functions, regardless of base, are always positive. In addition, all exponential functions pass through the point (0,1) since $b^0 = 1$ for any real positive number, and through the point (1,b) since $b^1 = b$. When b > 1 the function is increasing on \mathbb{R} , while for b < 1 the function is descending on \mathbb{R} .





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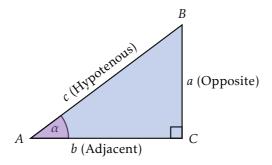
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0.5 TRIGONOMETRIC FUNCTIONS

BASIC DEFINITIONS

Consider a **right triangle** $\triangle ABC$ with sides a, b, and Hypotenous c, where the angle $\angle ACB$ is 90°, and the angle $\angle BAC$ is denoted as α :



We use the ratios between the three sides of the triangle to define three functions of α :

Definition 0.1 The basic triginometric functions

- 1. The **sine** of the angle α is $\sin(\alpha) = \frac{a}{c}$,
- 2. the **cosine** of the angle α is $\cos(\alpha) = \frac{b}{c}$, and
- 3. the **tangent** of the angle α is $\tan(\alpha) = \frac{a}{b}$, which in turn is equal to $\frac{\sin(\alpha)}{\cos(\alpha)}$.

 π

We can rearrange the above definitions to yield

$$a = c\sin(\alpha),$$

$$b = c\cos(\alpha).$$
 (0.34)

Normaly, the Hypotenous is the longest side of a right triangle. We will consider here the two edge cases where one of the sides *a*, *b* is equal to the Hypotenous (and the other side is thus 0):

- if a = c then $\alpha = 90^{\circ}$,
- if b = c then $\alpha = 0$.

The posssible length of a is therefore in the range $0 \le a \le c$, which means that $0 \le \frac{a}{c} \le 1$, or since $\sin(\alpha) = \frac{a}{c}$,

$$0 \le \sin(\alpha) \le 1. \tag{0.35}$$

The same is of course true for b, and thus

$$0 \le \cos(\alpha) \le 1 \tag{0.36}$$

as well.

As a reminder, the **Pythagorean theorem**¹ states that for a right triangle like the one here,

$$a^2 + b^2 = c^2. (0.37)$$

By substituting **Equation** 0.34 into the above we get

$$c^2 = a^2 + b^2 = (c\sin(\alpha))^2 + (c\cos(\alpha))^2 = c^2\sin^2(\alpha) + c^2\cos^2(\alpha) = c^2\left[\sin^2(\alpha) + \cos^2(\alpha)\right],$$

and cancelling c^2 on both sides simply yields

$$\sin^2(\alpha) + \cos^2(\alpha) = 1. \tag{0.38}$$

¹It's worth mentioning that no three positive integers a, b, and c satisfy the equation $a^n + b^n = c^n$ for any integer value of n > 2. This can be proven, however the proof is too large to fit in the footnotes.

Table 0.3 Common angles in radians.

Degrees	Radians	
0°	0	
45°	$\frac{\pi}{4}$	
90°	$\frac{\frac{\pi}{4}}{\frac{\pi}{2}}$	
180°	π	
270°	$\frac{3\pi}{2}$	
360°	2π	

Table 0.4 Text

Quadrant	$\cos(\theta) = x$	$\sin(\theta) = y$
1	[0,1]	[0,1]
2	[-1, 0]	[0,1]
3	[-1, 0]	[-1,0]
4	[0,1]	[-1,0]

THE UNIT CIRCLE

The range of the trigonometric functions can be extended by using the **unit circle**: a circle of radius R = 1 is placed such that its center lies at the origin of a 2-dimensional axis system, i.e. at the point O = (0,0). A radius to a point O = (x,y) on the circle's circumference is the drawn. This radius has an angle O = (x,y) to the O = (x,y) on the circle's perpendicular to the O = (x,y) on the circle's circumference is the drawn. This radius has an angle O = (x,y) on the circle's circumference is the drawn. This radius has an angle O = (x,y) on the circle's circumference is the drawn.

The triangle $\triangle OPD$ is a right triangle. Therefore, we can use the trigonometic functions to calculate the coordinates of the point P = (x, y):

$$x = R\cos(\theta) = \cos(\theta),$$

$$y = R\sin(\theta) = \sin(\theta).$$
 (0.39)

We can now define $cos(\theta)$ and $sin(\theta)$ as the values of x and y, respectively, as a function of θ .

We will switch to measuring angles in **Radians** instead of degrees: θ radians are equal to the length of an arc on a unit circle, which corresponds to the angle θ (**Figure** 0.4). This allows us to use the same units as x and y: for example, when length is measured in [meter], an angle in radians is measured in [meter] as well. The full circumference of a circle equals 2π radians, and therefore a single radian is equivalent to $\frac{180}{\pi} \approx 57.3^{\circ}$. **Table** 0.3 shows some common angles in radians.

Another advantage which we gain by defining the trigonometric functions using the unit circle is the extension of their domain to all of \mathbb{R} : an angle of size $2\frac{1}{2}\pi$ (equivalent to 450°), for example is the same as an angle of size $\frac{1}{2}\pi$ (90°), and an angle of $-\frac{1}{6}\pi$ (-30°) is the same as $\frac{5}{6}\pi$ (330°).

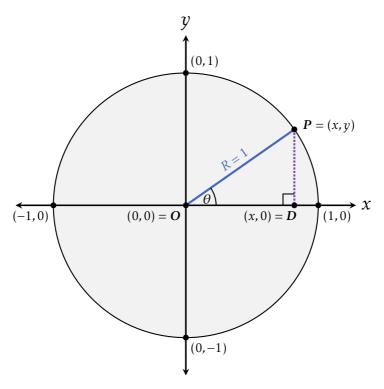


Figure 0.3 A unit circle with (...)

0.6 COMPLEX NUMBERS

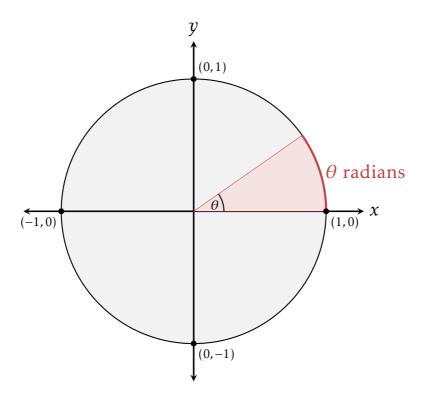


Figure 0.4 Radians

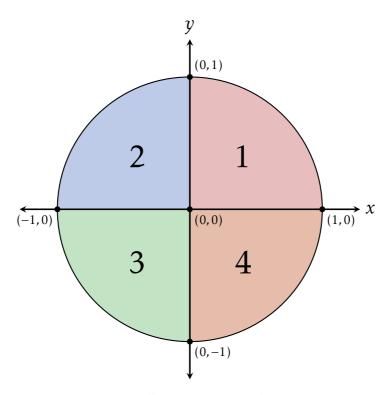
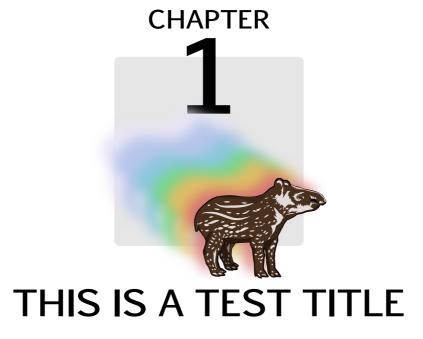


Figure 0.5 The different quadrants of the unit circle.



1.1 THE FOO AND THE BAR

THE FOO; OR: WHY DOES A FISH?

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Definition 1.1 The Foo

A Foo is simply a thing, i.e.
$$e^{i\pi} = -e^{i\tau} = -1. \tag{1.1}$$

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Example 1.1 A Bla which is not a Foo

Is there even such a thing? Consider



$$f(x) = \sin(x) + 5x^2.$$

THE BAR, THE ONE AND ONLY

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Note 1.1 Something to Consider

Bla bla bla, yada yada yada.

More lines.

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In the middle of this random Lorem Ipsum, there are some other words! This is refreshing, isn't it? Any way, this is used to test some **highlighting** and **indexing** of words. I hope it works. Well, it doesn't. I need to check how to make the marginnotes to go to the left side in odd pages.

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Challange 1.1 Generalize this thing

In 2D, the distance between two points $\mathbf{A} = (A_x, A_y)$ and $\mathbf{B} = (B_x, B_y)$ is

$$|AB| = \sqrt{(A_x - B_x)^2 + (A_y - B_y)^2}.$$
 (1.2)

Generalize this to 3D and to ND, where $N \in \mathbb{N}$.

?

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As you probably learned in school, a **triangle** is a shape with three sides. An example of a triangle can be seen in **Figure** 1.1 .

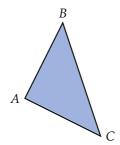


Figure 1.1 This is a triangle.

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