
Interpolation

Computer Oriented Numerical and Statistical Methods

Minal Shah

Outline

- Polynomial Interpolation
 - Difference Tables
 - Netwon's Forward and Backward Interpolation Formula
 - Lagrange's Formula
 - Divided Difference Formula
 - Inverse Interpolation
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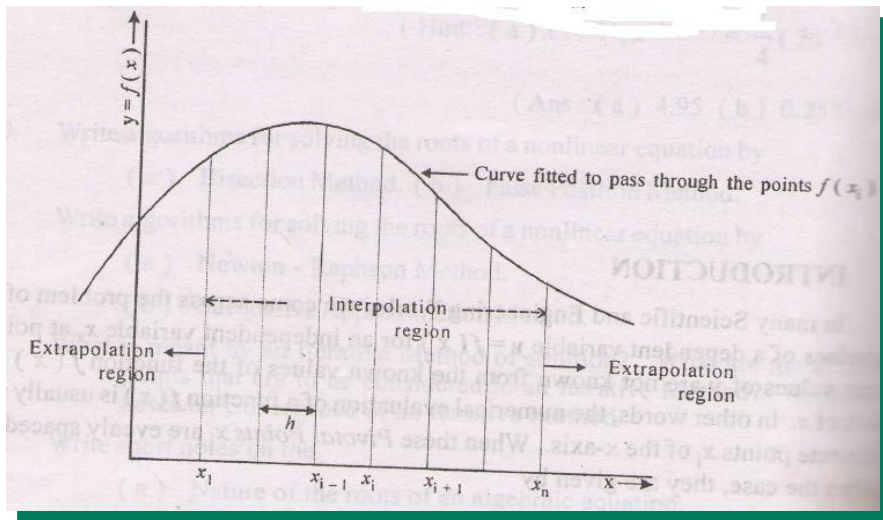
Introduction

- Suppose x and y are two variables and their relation can be expressed as $y = f(x)$; $x_1 \leq x \leq x_n$. Then we say that x is an independent variable and y is a dependent variable.
 - When the form of $f(x)$ is known, then the value of y can be computed directly corresponding to any value of x in the range $x_1 \leq x \leq x_n$.
 - However, if the form of $f(x)$ is not known, and only a set of values $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ satisfying the relation $y = f(x)$ are known, then the process of estimating the value of independent variable y for a given value of x in the range $x_1 \leq x \leq x_n$ is known as **interpolation**.
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Introduction

- However, if we move in opposite direction i.e. estimate the value of dependent variable x for a given value of independent variable y , the process is known as **inverse interpolation**.
 - The process of estimating the value of independent variable y for a given value of x outside the range $x_1 \leq x \leq x_n$ is known as **extrapolation**.
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Methods Of Interpolation

- The decision of using a particular method depends in tabulation of the functions.
- The tabulated points (x_i, y_i) $i = 1, 2, \dots, n$ of function $y = f(x)$, can be equally spaced or unequal spaced.
- Methods for equally spaced functions
 - Netwon's forward interpolation formula
 - Netwon's backward interpolation formula

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Methods Of Interpolation

- Methods for unequally spaced functions
 - Newton's divided difference interpolation formula
 - Lagrangian interpolation (Lagrange's)
 - These methods also work well for equally spaced function.

Finite Differences

- The finite differences are either difference between the values of the function or the differences between the past differences.
- There are 3 types of differences
 - Forward Differences
 - Backward Differences
 - Divided Differences

Forward Differences

- If $y_1, y_2, y_3, \dots, y_n$ denotes the values of the function of type $y = f(x)$ at $x = x_1, x_2, \dots, x_n$ then $y_2 - y_1, y_3 - y_2, y_4 - y_3, \dots, y_n - y_{n-1}$ are called the forward differences of y
- These differences are denoted as $\Delta y_1, \Delta y_2, \Delta y_3, \dots, \Delta y_{n-1}$
- ✓ $\therefore \Delta y_1 = y_2 - y_1, \Delta y_2 = y_3 - y_2, \dots, \Delta y_{n-1} = y_n - y_{n-1}$
where Δ is called **forward difference operator** and $\Delta y_1, \Delta y_2, \Delta y_3, \dots, \Delta y_{n-1}$ are called first order forward differences.

Forward Differences

- The differences of the first order forward differences are called second order forward differences and are denoted as $\Delta^2 y_1, \Delta^2 y_2, \Delta^2 y_3, \dots, \Delta^2 y_{n-1}$
- ✓ $\therefore \Delta^2 y_1 = \Delta y_2 - \Delta y_1 = y_3 - 2y_2 + y_1$
- $\Delta^2 y_2 = \Delta y_3 - \Delta y_2 = y_4 - 2y_3 + y_2$
- In the similar manner, the third order forward differences are
- ✓ $\Delta^3 y_1 = \Delta^2 y_2 - \Delta^2 y_1 = y_4 - 3y_3 + 3y_2 - y_1$
- ✓ $\Delta^3 y_2 = \Delta^2 y_3 - \Delta^2 y_2 = y_5 - 3y_4 + 3y_3 - y_2$
- In general, the first order forward differences at the i^{th} point is $\Delta y_i = y_{i+1} - y_i$ and the j^{th} order forward differences at the i^{th} point is $\Delta^j y_i = \Delta^{j-1} y_{i+1} - \Delta^{j-1} y_i$

Backward Differences

- If $y_1, y_2, y_3, \dots, y_n$ denotes the values of the function of type $y = f(x)$ at $x = x_1, x_2, \dots, x_n$ then $y_2 - y_1, y_3 - y_2, y_4 - y_3, \dots, y_n - y_{n-1}$ are called the backward differences of y
 - These differences are denoted as $\nabla y_2, \nabla y_3, \dots, \nabla y_n$
- ∇ ∴ $\nabla y_2 = y_2 - y_1, \nabla y_3 = y_3 - y_2, \dots, \nabla y_n = y_n - y_{n-1}$ where ∇ is called **backward difference operator** and $\nabla y_2, \nabla y_3, \dots, \nabla y_n$ are called first order backward differences.

Backward Differences

- The differences of the first order backward differences are called second order backward differences and are denoted as $\nabla^2 y_3, \nabla^2 y_4, \dots$ etc.
- ∇ ∴ $\nabla^2 y_3 = \nabla y_3 - \nabla y_2 = y_3 - 2y_2 + y_1$
- $\nabla^2 y_4 = \nabla y_4 - \nabla y_3 = y_4 - 2y_3 + y_2$
 - In the similar manner, the third order backward differences are
- ∇ $\nabla^3 y_4 = y_4 - 3y_3 + 3y_2 - y_1$
- ∇ $\nabla^3 y_5 = y_5 - 3y_4 + 3y_3 - y_2$
- In general, the first order backward differences at the i^{th} point is $\nabla y_i = y_i - y_{i-1}$ and the j^{th} order backward differences at the i^{th} point is $\nabla^j y_i = \nabla^{j-1} y_i - \nabla^{j-1} y_{i-1}$

Divided Differences

- If $y_1, y_2, y_3, \dots, y_n$ denotes the values of the function of type $y = f(x)$ at $x = x_1, x_2, \dots, x_n$ then

$$\frac{y_2 - y_1}{x_2 - x_1}, \quad \frac{y_3 - y_2}{x_3 - x_2}, \quad \frac{y_4 - y_3}{x_4 - x_3}, \dots, \quad \frac{y_n - y_{n-1}}{x_n - x_{n-1}}$$

- are called the divided differences of y and are denoted as $\Delta_d y_1, \Delta_d y_2, \Delta_d y_3, \dots, \Delta_d y_{n-1}$

$$\nabla \therefore \Delta_d y_1 = (y_2 - y_1) / (x_2 - x_1) = [x_1, x_2]$$

$$\nabla \Delta_d y_2 = (y_3 - y_2) / (x_3 - x_2) = [x_2, x_3]$$

$$\nabla \Delta_d y_{n-1} = (y_n - y_{n-1}) / (x_n - x_{n-1}) = [x_{n-1}, x_n]$$

- Where Δ_d is called **divide difference operator** and $\Delta_d y_1, \Delta_d y_2, \dots, \Delta_d y_n$ are called first order divided differences.

Divided Differences

- The differences of the first order divided differences are called second order divided differences and are denoted as $\Delta_d^2 y_1, \Delta_d^2 y_2, \dots, \Delta_d^2 y_n$ etc.

$$\nabla \therefore \Delta_d^2 y_1 = (\Delta_d y_2 - \Delta_d y_1) / (x_3 - x_1)$$

$$\nabla \Delta_d^2 y_2 = (\Delta_d y_3 - \Delta_d y_2) / (x_4 - x_2)$$

- In the similar manner, the third order forward differences are

$$\nabla \Delta_d^3 y_1 = (\Delta_d^2 y_2 - \Delta_d^2 y_1) / (x_4 - x_1)$$

$$\nabla \Delta_d^3 y_2 = (\Delta_d^2 y_3 - \Delta_d^2 y_2) / (x_5 - x_2)$$

- In general, the first order divided differences at the i^{th} point is $\Delta_d y_i = (y_{i+1} - y_i) / (x_{i+1} - x_i)$ and the j^{th} order forward differences at the i^{th} point is $\Delta_d^j y_i = (\Delta_d^{j-1} y_{i+1} - \Delta_d^{j-1} y_i) / (x_{i+1} - x_i)$

Differences Tables

- A difference table is a table that lists the differences of the function values and the differences of differences in succession.

Forward Difference Table

- Let us consider the values y_1, y_2, y_3, y_4 of the function type $y = f(x)$ tabulated at equally spaced points x_1, x_2, x_3, x_4 . The forward difference table along with tabulated points will look like

Forward Difference Table					
i	x_i	y_i	Δy_i	$\Delta^2 y_i$	$\Delta^3 y_i$
1	x_1	y_1	$\Delta y_1 = y_2 - y_1$	$\Delta^2 y_1 = \Delta y_2 - \Delta y_1$	$\Delta^3 y_1 = \Delta^2 y_2 - \Delta^2 y_1$
2	x_2	y_2	$\Delta y_2 = y_3 - y_2$	$\Delta^2 y_2 = \Delta y_3 - \Delta y_2$	
3	x_3	y_3	$\Delta y_3 = y_4 - y_3$		
4	x_4	y_4			

Forward Difference Table

- The forward difference table for function tabulated at n equally spaced points can be represented by a matrix of size $(n-1) \times (n-1)$ where j^{th} order frequency at the i^{th} point ($\Delta^j y_i$) is represented by the element d_{ij} of matrix D .
- Note that only the elements in the column 1 to $(n - i)$, for rows $i = 1, 2, \dots, n-1$ are of interest.

Backward Difference Table

- Let us consider the values y_1, y_2, y_3, y_4 of the function type $y = f(x)$ tabulated at equally spaced points x_1, x_2, x_3, x_4 . The Backward difference table along with tabulated points will look like

Backward Difference Table					
i	x_i	y_i	∇y_i	$\nabla^2 y_i$	$\nabla^3 y_i$
1	x_1	y_1			
2	x_2	y_2	$\nabla y_2 = y_2 - y_1$		
3	x_3	y_3	$\nabla y_3 = y_3 - y_2$	$\nabla^2 y_3 = \nabla y_3 - \nabla y_2$	
4	x_4	y_4	$\nabla y_4 = y_4 - y_3$	$\nabla^2 y_4 = \nabla y_4 - \nabla y_3$	$\nabla^3 y_4 = \nabla^2 y_4 - \nabla^2 y_3$

Divided Difference Table

- Let us consider the values y_1, y_2, y_3, y_4 of the function type $y = f(x)$ tabulated at points x_1, x_2, x_3, x_4 not necessarily equally spaced . The divide difference table along with tabulated points will look like

Divided Difference Table

Divided Difference Table					
i	x_i	y_i	$\Delta_d y_i$	$\Delta_d^2 y_i$	$\Delta_d^3 y_i$
1	x_1	y_1	$\Delta_d y_1 = (y_2 - y_1) / (x_2 - x_1)$	$\Delta_d^2 y_1 = (\Delta_d y_2 - \Delta_d y_1) / (x_3 - x_1)$	$\Delta_d^3 y_1 = (\Delta_d^2 y_2 - \Delta_d^2 y_1) / (x_4 - x_1)$
2	x_2	y_2	$\Delta_d y_2 = (y_3 - y_2) / (x_3 - x_2)$	$\Delta_d y_2 = (\Delta_d y_3 - \Delta_d y_2) / (x_4 - x_2)$	
3	x_3	y_3	$\Delta_d y_3 = (y_4 - y_3) / (x_4 - x_3)$		
4	x_4	y_4			

Netwon's Methods Of Interpolation

- It is divided into following methods depending on the type of differences being used.
- 1. Netwon's Forward Difference Interpolation Formula
- 2. Netwon's Backward Difference Interpolation Formula
- 3. Netwon's Divided Difference Interpolation Formula
- If the function is tabulated at equal intervals, then we can use either Netwon's Forward Difference Interpolation Formula or Netwon's Backward Difference Interpolation Formula.

Netwon's Forward Difference Interpolation Formula

- Let us assume that the function $y(x)$ is tabulated at $(n+1)$ equally spaced (interval size h) points.
- To derive the formula for netwon's forward difference interpolation assume a polynomial of type

$$y(x) = a_1 + a_2(x-x_1) + a_3(x-x_1)(x-x_2) + \dots + a_{n+1}(x-x_1)(x-x_2) \dots (x-x_n) \dots [a]$$
- It is the n^{th} order polynomial in x .
- It is an interpolation polynomial for the table values x_i and y_i then the polynomial must pass through all points.
- ✓ \therefore we can obtain y_i by substituting the corresponding x_i for x

Newton's Forward Difference Interpolation Formula

- At $x = x_1$ $y_1 = a_1$
- $x = x_2$ $y_2 = a_1 + a_2(x_2 - x_1)$
- $x = x_3$ $y_3 = a_1 + a_2(x_3 - x_1) + a_3(x_3 - x_1)(x_3 - x_2)$
- And so on.
- Since x_i 's are equally spaced therefore we can write $x_{i+1} - x_i = h$ and $x_{i+m} - x_i = mh$ then we can express the function values y_i 's in terms of intervals values as

$$y_1 = a_1$$

$$y_2 = a_1 + a_2h$$

$$y_3 = a_1 + a_2(2h) + a_3(2h)(h)$$

.....

$$y_{n+1} = a_1 + a_2(nh) + a_3(nh)((n-1)h) + \dots + a_{n+1}(nh)((n-1)h)\dots(h)$$

Newton's Forward Difference Interpolation Formula

- Now for a_1, a_2, a_3, a_{n+1} we get

$$a_1 = y_1$$

$$a_2 = \frac{y_2 - a_1}{h} = \frac{y_2 - y_1}{h}$$

$$a_3 = \frac{y_3 - 2y_2 + y_1}{2!h^2}$$

$$a_{n+1} = \frac{y_{n+1} - ny_n + \dots + y_1}{n!h^n}$$

Newton's Forward Difference Interpolation Formula

- Using forward difference table we get

$$a_1 = y_1$$

$$a_2 = \frac{\Delta y_1}{h}$$

$$a_3 = \frac{\Delta^2 y_1}{2! h^2}$$

.

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$$a_{n+1} = \frac{\Delta^n y_1}{n! h^n}$$

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Newton's Forward Difference Interpolation Formula

- Substituting these values of a_1, a_2, a_3, a_{n+1} in equation [a] we get

$$y(x) = y_1 + \frac{\Delta y_1}{h} (x - x_1) +$$

$$\frac{\Delta^2 y_1}{2! h^2} (x - x_1) (x - x_2) +$$

$$\dots + \frac{\Delta^n y_1}{n! h^n} (x - x_1) (x - x_2) \dots (x - x_n)$$

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Newton's Forward Difference Interpolation Formula

- If we use the relation $(x-x_1)/h = u$ then $x - x_1 = hu$
 $x - x_2 = x - (x_1 + h) = h(u-1)$
 $x - x_3 = x - (x_2 + h) = h(u-2) \dots\dots$
 $x - x_n = h(u-(n-1))$
- Substituting these values $(x-x_1)$, $(x-x_2)$, $\dots\dots$, $(x - x_n)$ in equation [b] we get

Newton's Forward Difference Interpolation Formula

$$\begin{aligned}
 y(x) = & y_1 + \frac{\Delta y_1}{h} hu + \\
 & \frac{\Delta^2 y_1}{2!h^2} h^2 u(u-1) + \\
 & \dots\dots + \frac{\Delta^n y_1}{n!h^n} h^n u(u-1) \dots\dots (u-(n-1)) \\
 & \dots\dots\dots c] [
 \end{aligned}$$

Netwon's Forward Difference Interpolation Formula

- Simplifying we get

$$y(x) = y_1 + \Delta y_1 u + \frac{\Delta^2 y_1}{2} u(u-1) + \dots + \frac{\Delta^n y_1}{n!} u(u-1) \dots (u-(n-1))$$

- The above derivation assumes that $x_1 < x < x_2$
- This polynomial is called Netwon's Forward Difference Interpolation Formula

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Netwon's Backward Difference Interpolation Formula

- Let us assume that the function $y(x)$ is tabulated at $(n+1)$ equally spaced (interval size h) points.
- To derive the formula for netwon's backward difference interpolation assume a polynomial of type $y(x) = a_1 + a_2(x-x_n) + a_3(x-x_n)(x-x_{n-1}) + \dots + a_{n+1}(x-x_n)(x-x_{n-1}) \dots (x-x_1) \dots [a]$
- It is the n^{th} order polynomial in x .
- It is an interpolation polynomial for the table values x_i and y_i then the polynomial must pass through all points.
- ✓ \therefore we can obtain y_i by substituting the corresponding x_i for x

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Newton's Backward Difference Interpolation Formula

- At $x = x_n$ $y_n = a_1$
- $x = x_{n-1}$ $y_{n-1} = a_1 + a_2(x_{n-1} - x_n)$
- $x = x_{n-2}$ $y_{n-2} = a_1 + a_2(x_{n-2} - x_n) + a_3(x_{n-2} - x_n)(x_{n-2} - x_{n-1})$
- And so on.
- Since x_i 's are equally spaced therefore we can write $x_i - x_{i-1} = h$ and $x_{i-1} - x_i = -h$ and $x_{i-m} - x_i = -mh$ then we can express the function values y_i 's in terms of intervals values as

$$y_n = a_1$$

$$y_{n-1} = a_1 + a_2(-h)$$

$$y_{n-2} = a_1 + a_2(-2h) + a_3(-2h)(-h)$$

.....

$$y_1 = a_1 + a_2(-nh) + a_3(-nh)(-(n-1)h) + \dots + a_{n+1}(-nh)(-(n-1)h)\dots(-h)$$

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Newton's Backward Difference Interpolation Formula

- Now for a_1, a_2, a_3, a_{n+1} we get

$$a_1 = y_n$$

$$a_2 = \frac{y_{n-1} - a_1}{h} = \frac{y_n - y_{n-1}}{h}$$

$$a_3 = \frac{y_n - 2y_{n-1} + y_{n-2}}{2!h^2}$$

$$a_{n+1} = \frac{y_1 - ny_2 + \dots + y_n}{n!h^n}$$

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Newton's Backward Difference Interpolation Formula

- Using backward difference table we get

$$a_1 = y_n$$

$$a_2 = \frac{\nabla y_n}{h}$$

$$a_3 = \frac{\nabla^2 y_n}{2! h^2}$$

.

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$$a_{n+1} = \frac{\nabla^n y_n}{n! h^n}$$

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Newton's Backward Difference Interpolation Formula

- Substituting these values of a_1, a_2, a_3, a_{n+1} in equation [a] we get

$$y(x) = y_n + \frac{\nabla y_n}{h} (x - x_n) +$$

$$\frac{\nabla^2 y_n}{2! h^2} (x - x_n) (x - x_{n-1}) +$$

$$\dots + \frac{\nabla^n y_n}{n! h^n} (x - x_n) (x - x_{n-1}) \dots (x - x_1) \dots$$

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Newton's Backward Difference Interpolation Formula

- If we use the relation $(x - x_n) / h = u$ then $x - x_n = hu$
 $x - x_{n-1} = x - (x_n - h) = h(u+1)$
 $x - x_{n-2} = x - (x_{n-1} - h) = h(u+2) \dots$
 $x - x_1 = h(u+(n-1))$
- Substituting these values $(x - x_n)$, $(x - x_{n-1})$, ..., $(x - x_1)$ in equation [b] we get

Newton's Backward Difference Interpolation Formula

$$\begin{aligned}
 y(x) = & y_n + \frac{\nabla y_n}{h} hu + \frac{\nabla^2 y_n}{2h^2} h^2 u(u+1) + \\
 & \dots + \frac{\nabla^n y_n}{n! h^n} h^n u(u+1) \dots (u+n-1)
 \end{aligned}$$

Netwon's Backward Difference Interpolation Formula

- Simplifying we get

$$y(x) = y_n + \nabla y_n u + \frac{\nabla^2 y_n}{2} u(u+1) + \dots + \frac{\nabla^n y_n}{n!} u(u+1) \dots (u+(n-1))$$

- The above derivation assumes that $x_{n-1} < x < x_n$
- This polynomial is called Netwon's Backward Difference Interpolation Formula

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Netwon's Divided Difference Interpolation Formula

- Let us assume that the function $y(x)$ is tabulated at $(n+1)$ equally spaced (interval size h) points.
- To derive the formula for netwon's divided difference interpolation assume a polynomial of type

$$y(x) = a_1 + a_2(x-x_1) + a_3(x-x_1)(x-x_2) + \dots + a_{n+1}(x-x_1)(x-x_2) \dots (x-x_n)$$

.....[a]
- It is the n^{th} order polynomial in x .
- It is an interpolation polynomial for the table values x_i and y_i then the polynomial must pass through all points.
- ✓ \therefore we can obtain y_i by substituting the corresponding x_i for x

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Newton's Divided Difference Interpolation Formula

- At $x = x_1$ $y_1 = a_1$
- $x = x_2$ $y_2 = a_1 + a_2(x_2 - x_1)$
- $x = x_3$ $y_3 = a_1 + a_2(x_3 - x_1) + a_3(x_3 - x_1)(x_3 - x_2)$
- And so on.
- Solving for a_1, a_2, a_3, a_{n+1} we get

Newton's Divided Difference Interpolation Formula

$$a_1 = y_1$$

$$a_2 = \frac{y_2 - a_1}{x_2 - x_1} = \frac{y_2 - y_1}{x_2 - x_1}$$

$$a_3 = \frac{1}{(x_3 - x_2)} \left[\frac{(y_3 - y_1)}{(x_3 - x_1)} - \frac{(y_2 - y_1)}{(x_2 - x_1)} \right]$$

and on

Newton's Divided Difference Interpolation Formula

- Using divided difference table we get

$$a_1 = y_1$$

$$a_2 = \Delta_d y_1$$

$$a_3 = \Delta_d^2 y_1$$

.

.

.

$$a_{n+1} = \Delta_d^n y_1$$

Newton's Divided Difference Interpolation Formula

- Substituting these values of a_1, a_2, a_3, a_{n+1} in equation [a] we get

$$\begin{aligned}
 p(x) = & y_1 + \Delta_d y_1 (x - x_1) + \\
 & \Delta_d^2 y_1 (x - x_1)(x - x_2) + \\
 & \dots + \Delta_d^n y_1 (x - x_1)(x - x_2) \dots (x - x_n)
 \end{aligned}$$

- This polynomial is called Newton's Divided Difference Interpolation Formula

Lagrangian / Lagranges Interpolation Formula

- In order to derive a general formula for lagrangian interpolation, we consider a second order polynomial of type.

$$y(x) = a_1(x-x_2)(x-x_3) + a_2(x-x_1)(x-x_3) + a_3(x-x_1)(x-x_2) \dots\dots\dots[a]$$

passing through the points (x_1, y_1) , (x_2, y_2) , and (x_3, y_3) where a_1 , a_2 , and a_3 are unknown constants whose values are determined as follows.

- At $x = x_1$ $y(x_1) = a_1(x_1 - x_2)(x_1 - x_3)$

Lagrangian / Lagranges Interpolation Formula

$$\text{At } x = x_1 \quad y(x_1) = a_1(x_1 - x_2)(x_1 - x_3)$$

$$\Rightarrow a_1 = \frac{y_1}{(x_1 - x_2)(x_1 - x_3)}$$

$$\text{At } x = x_2 \quad y(x_2) = a_2(x_2 - x_1)(x_2 - x_3)$$

$$\Rightarrow a_2 = \frac{y_2}{(x_2 - x_1)(x_2 - x_3)}$$

$$\text{At } x = x_3 \quad y(x_3) = a_3(x_3 - x_1)(x_3 - x_2)$$

$$\Rightarrow a_3 = \frac{y_3}{(x_3 - x_1)(x_3 - x_2)}$$

Lagrangian / Lagranges Interpolation Formula

- Substituting these values of a_1, a_2, a_3 in equation [a] we get

$$y(x) = y_1 * \frac{(x-x_2)(x-x_3)}{(x_1-x_2)(x_1-x_3)} +$$

$$y_2 * \frac{(x-x_1)(x-x_3)}{(x_2-x_1)(x_2-x_3)} +$$

$$y_3 * \frac{(x-x_1)(x-x_2)}{(x_3-x_1)(x_3-x_2)}$$

Lagrangian / Lagranges Interpolation Formula

$$f(x) = f(x_0) * \frac{(x-x_1)(x-x_2) \dots (x-x_n)}{(x_0-x_1)(x_0-x_2) \dots (x_0-x_n)} +$$

$$f(x_1) * \frac{(x-x_0)(x-x_2) \dots (x-x_n)}{(x_1-x_0)(x_1-x_2) \dots (x_1-x_n)} + \dots +$$

$$f(x_n) * \frac{(x-x_0)(x-x_1) \dots (x-x_{n-1})}{(x_n-x_0)(x_n-x_1) \dots (x_n-x_{n-1})} +$$

- This polynomial is known as the Lagrange's polynomial

